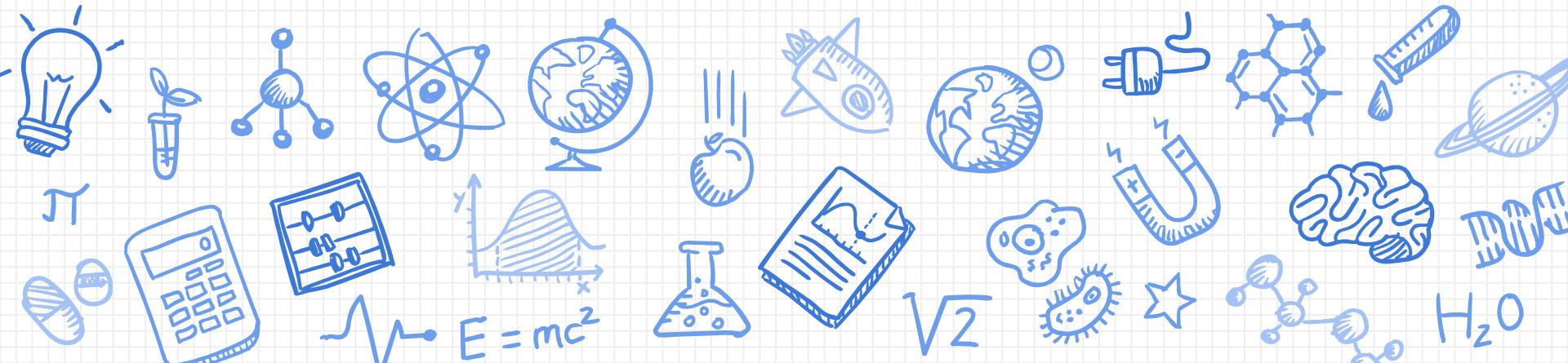
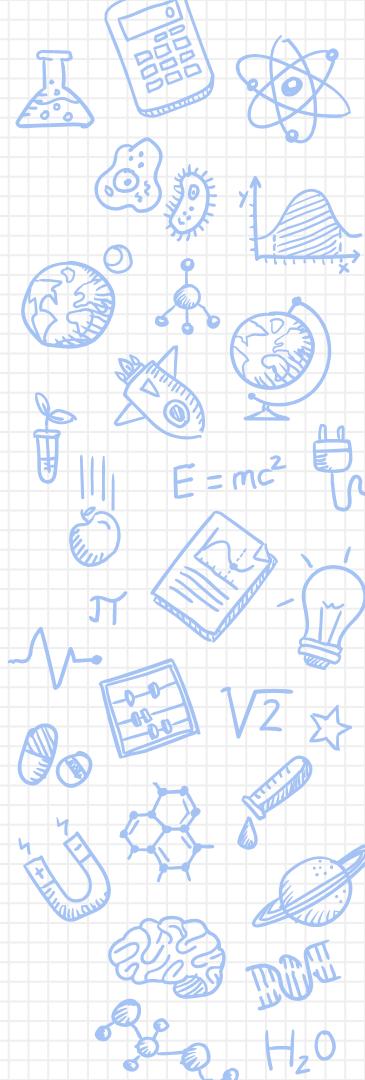


EE16A Imaging 2



Why?

- ✗ Imaging 1:
 - ✗ Finding a link between physical quantities and voltage is powerful
 - ✗ If you can digitize it, you can do anything (IOT devices, internet, code, processing)
- ✗ Imaging 2:
 - ✗ What measurements are good measurements?
 - Remember Kody and Nara?



Kody and Nara

2. Finding The Bright Cave

Nara the one-handed druid and Kody the one-handed ranger find themselves in dire straits. Before them is a cliff with four cave entrances arranged in a square: two upper caves and two lower caves. Each entrance emits a certain amount of light, and the two wish to find exactly the amount of light coming from each cave. Here's the catch: after contracting a particularly potent strain of ghoul fever, our intrepid heroes are only able to see the total intensity of light before them (so their eyes operate like a single-pixel camera). Kody and Nara are capable adventurers, but they don't know any linear algebra – and they need your help.

Kody proposes an imaging strategy where he uses his hand to completely block the light from two caves at a time. He is able to take measurements using the following four masks (black means the light is blocked from that cave):

Cave Labels

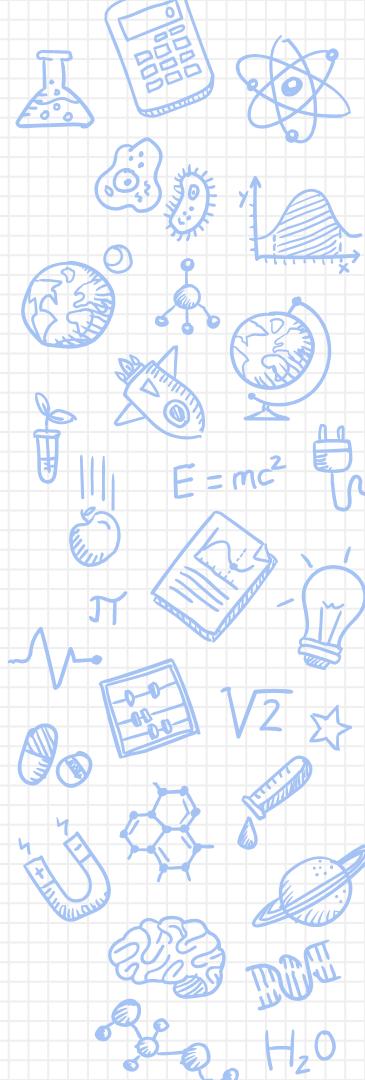
x_1	x_2
x_3	x_4

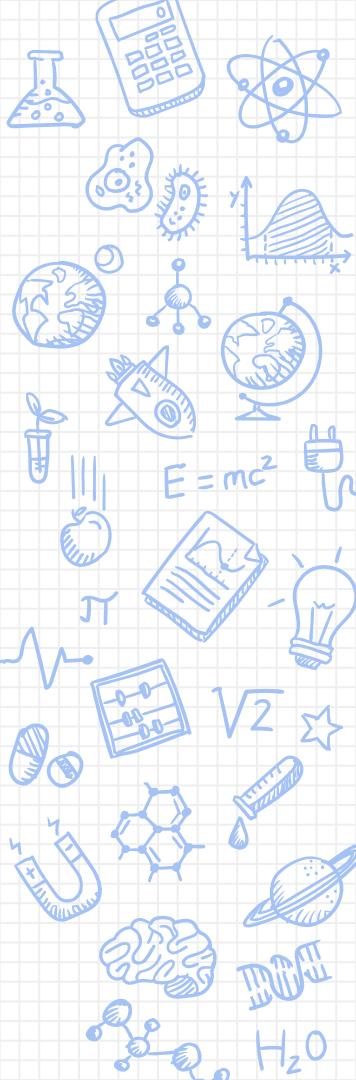


Measurement 1 Measurement 2 Measurement 3 Measurement 4

Figure 1: Four image masks.

- Let \vec{x} be the four-element vector that represents the magnitude of light emanating from the four cave entrances. Write a matrix \mathbf{K} that performs the masking process in Figure 1 on the vector \vec{x} , such that $\mathbf{K}\vec{x}$ is the result of the four measurements.
- Does Kody's set of masks give us a unique solution for all four caves' light intensities? Why or why not?
- Nara, in her infinite wisdom, places her one hand diagonally across the entrances, covering two of the cave entrances. However, her hand is not wide enough, letting in 50% of the light from the caves covered and 100% of the light from the caves not covered. The following diagram shows the percentage of light let through from each cave:



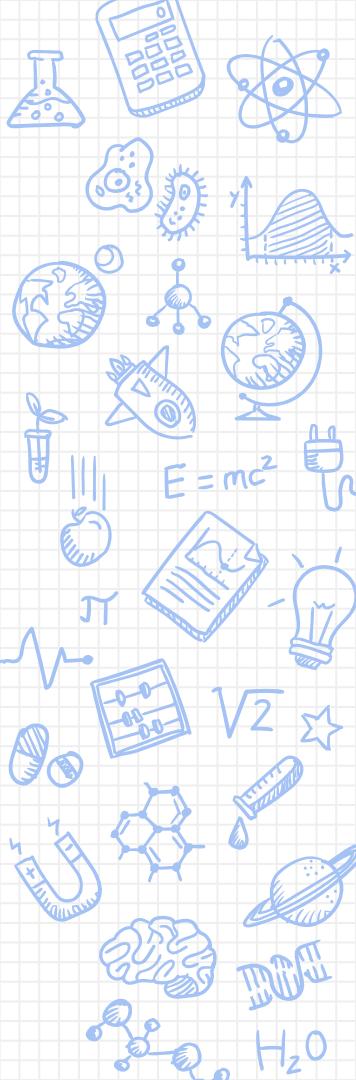


Illuminating the Big Picture

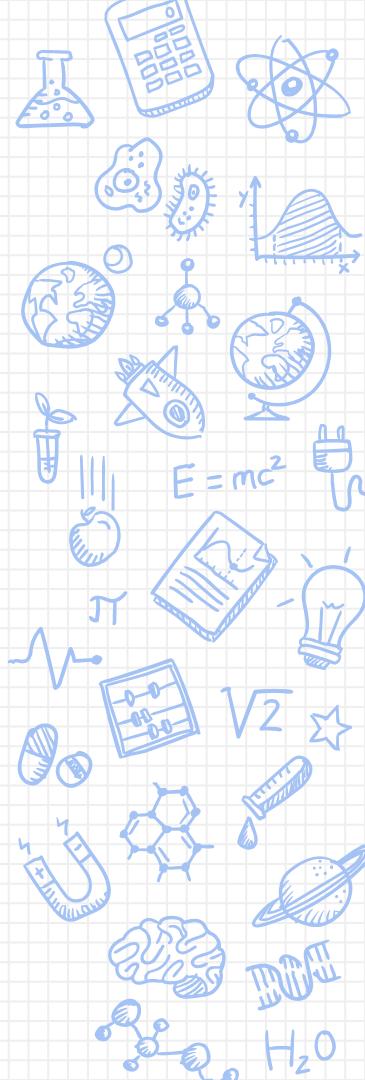
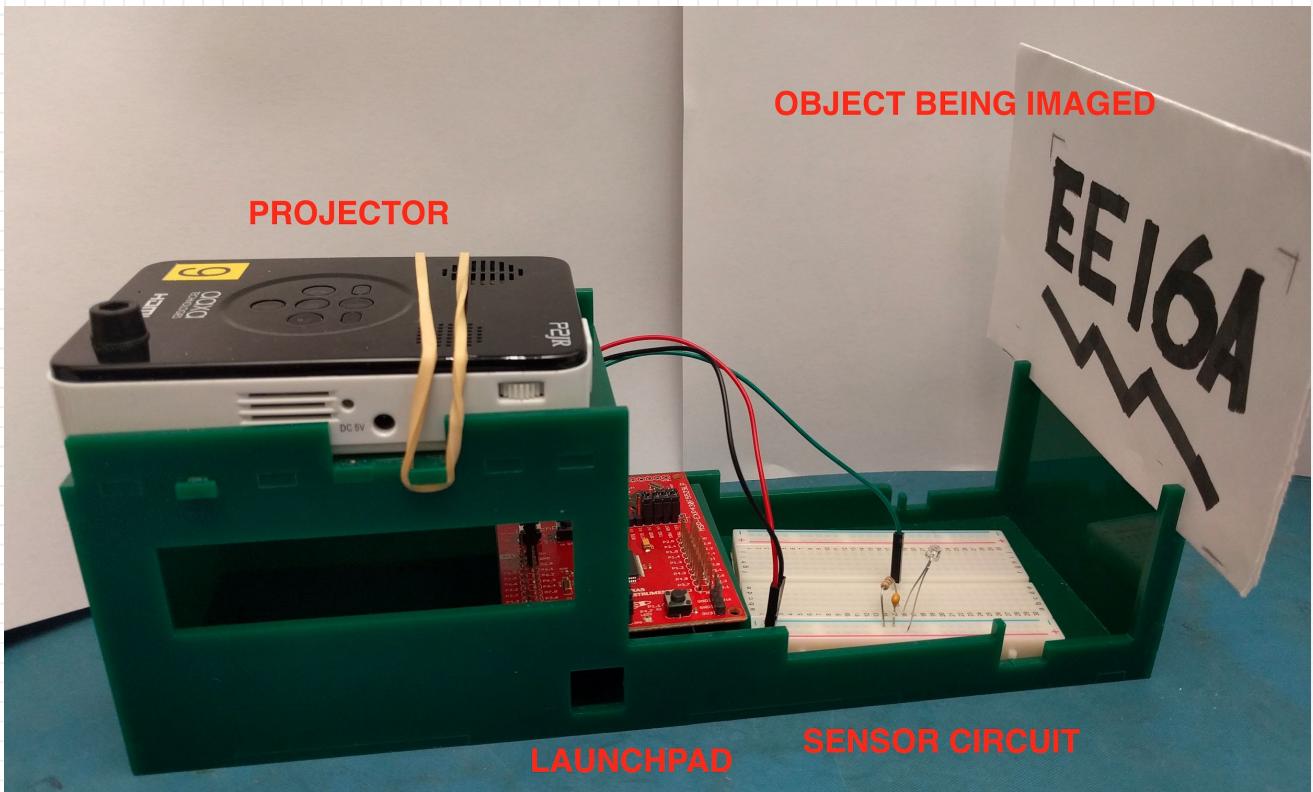
- ✗ Linear dependance
 - ✗ When can you even recover your image?
 - ✗ Does it matter what mask matrix you pick?
 - ✗ Does it matter how you cover the pixels?
 - ✗ Invertibility
 - ✗ When can you solve $Ax = b$
 - ✗ Why do we care? How does this affect the way we pick our imaging matrix?

Today's Lab: Single Pixel Scanning

- ✗ Circuit from last week measures **light** intensity
- ✗ Projector illuminates index card in a controlled way
- ✗ Python programming to reconstruct image

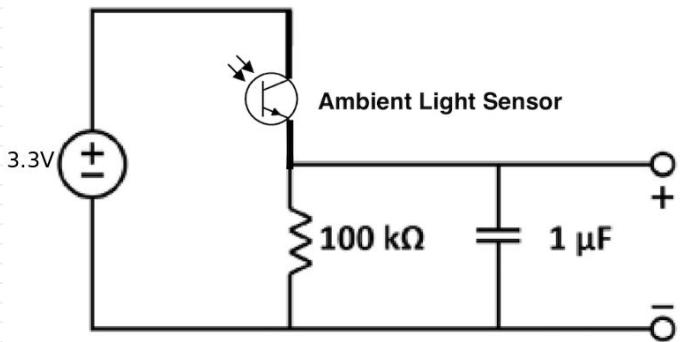


Setup:

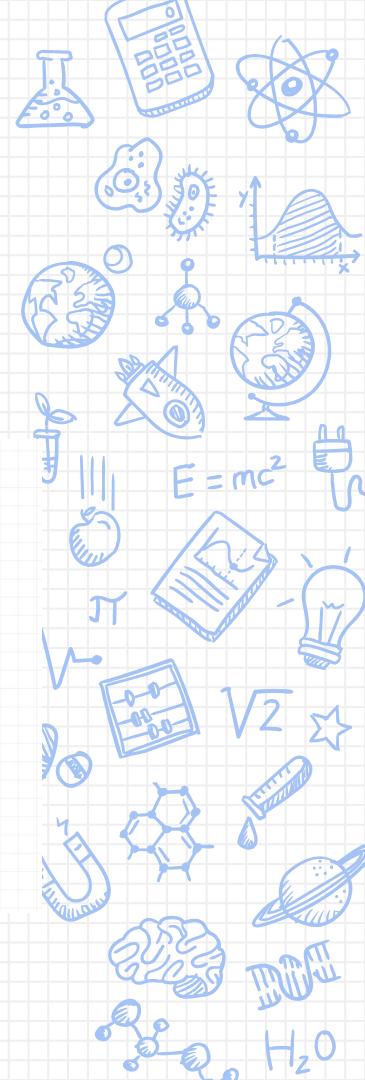
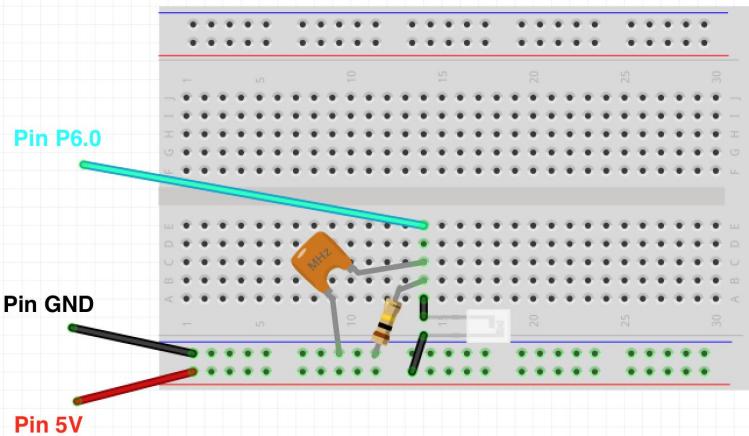


Circuit From Last Week

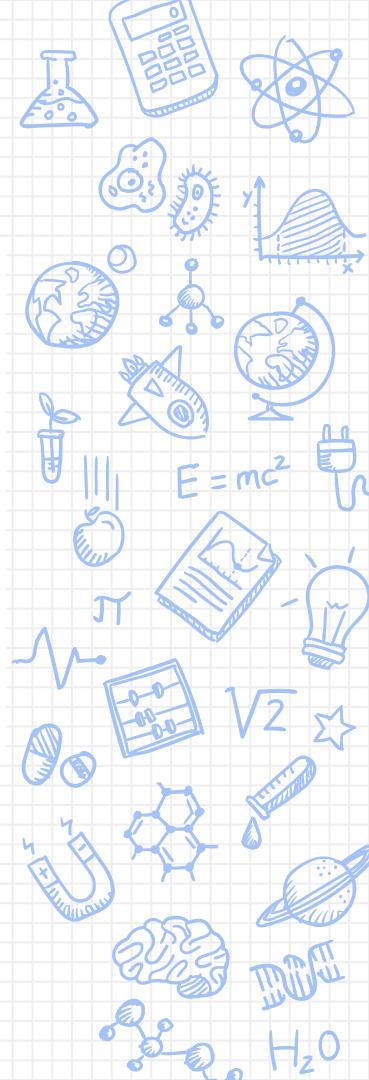
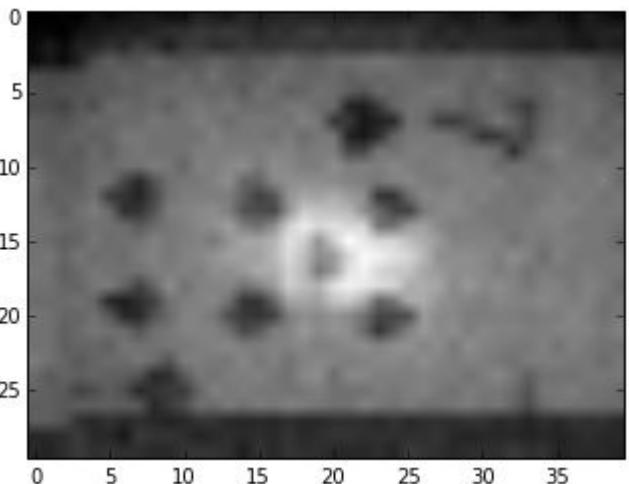
Circuit Diagram



Breadboard Diagram

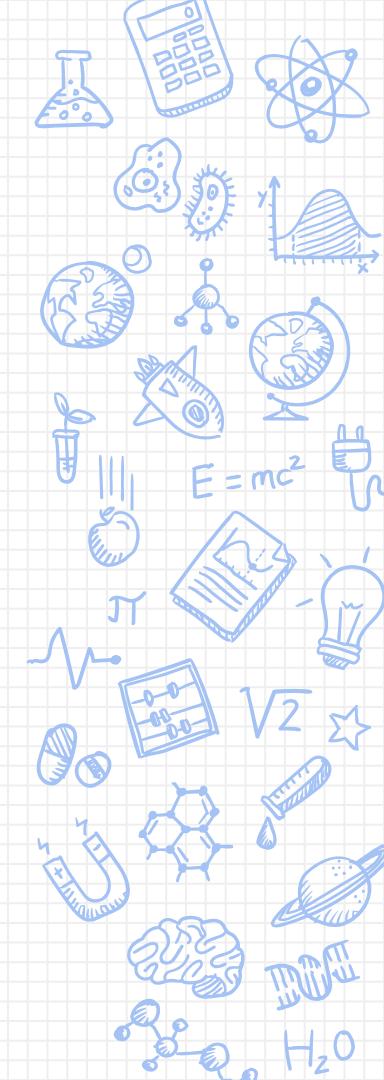
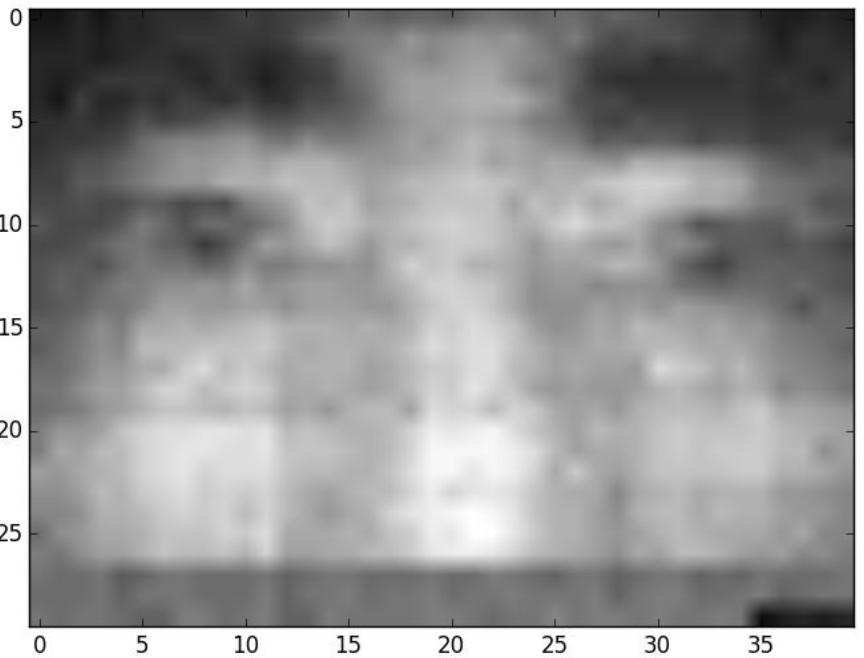


Sample Images



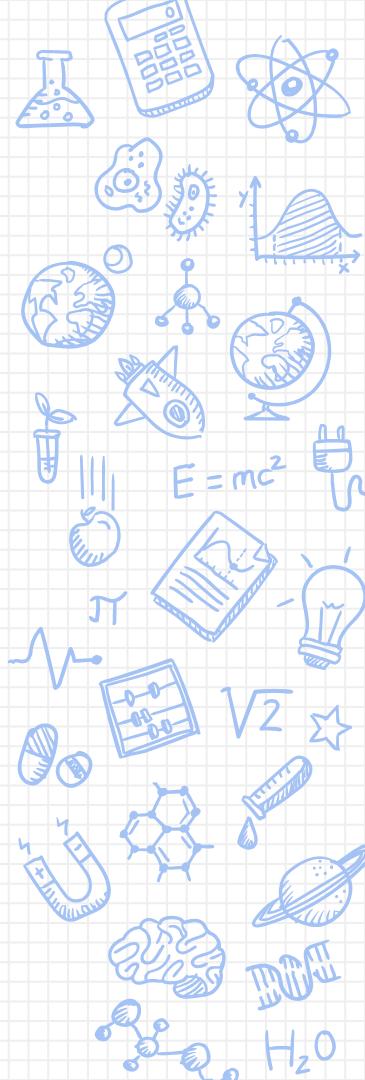
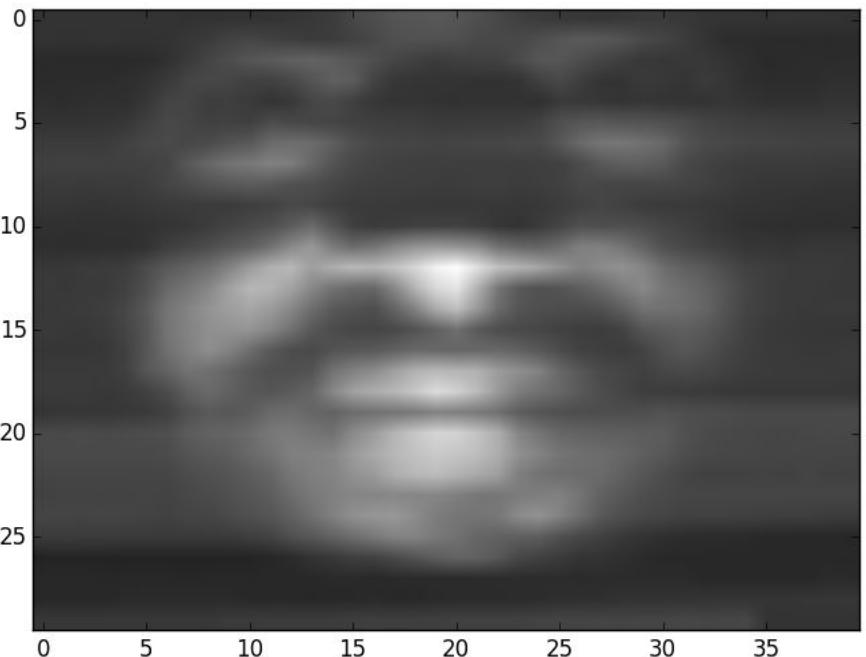
Sample Images

Seiya:



Sample Images

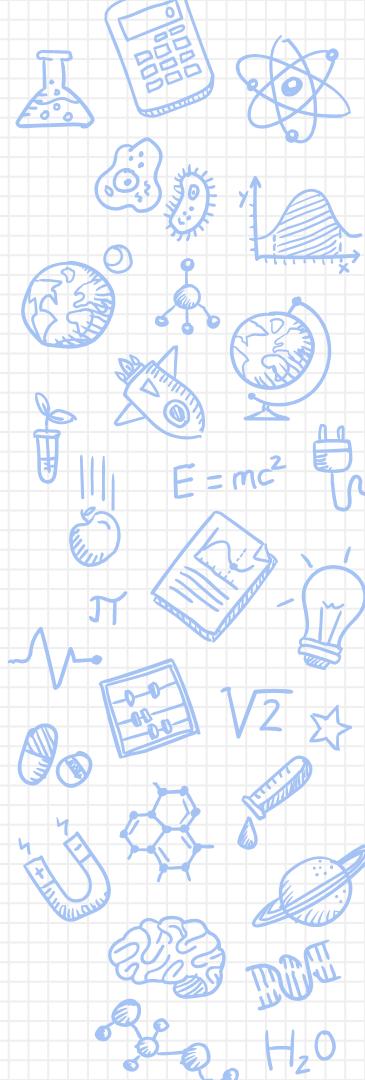
Nick:



Images, Matrices, Vectors



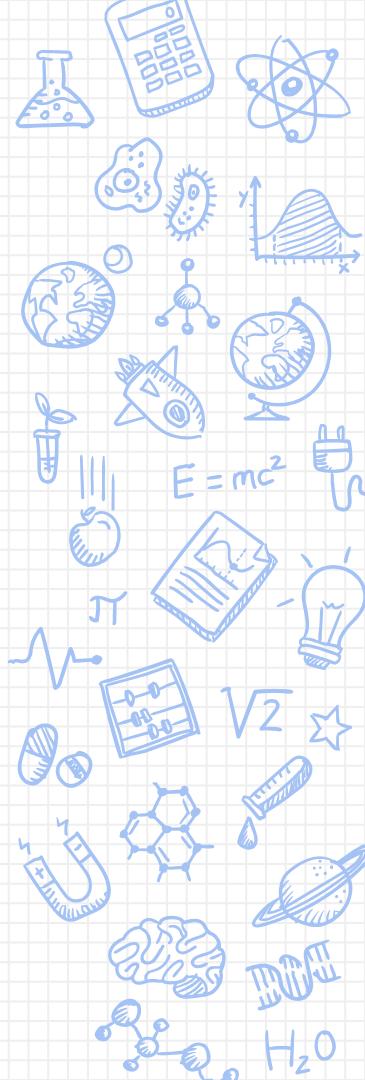
- ✗ What are the unknowns in our system?
 - ✗ Want to do an experiment to get information about these unknowns.
 - ✗ We can do a lot of interesting processing on vectors, but we need to convert the image into one first
 - ✗ In lecture and discussion, you have seen how to turn an image into a vector. How?



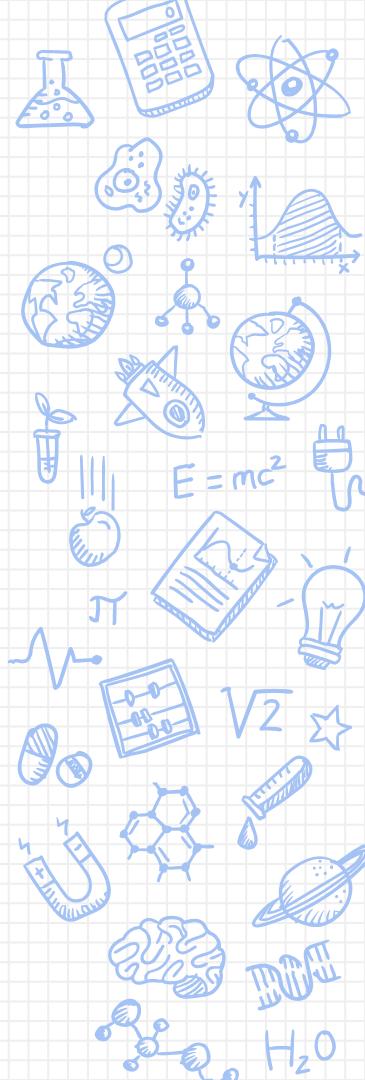
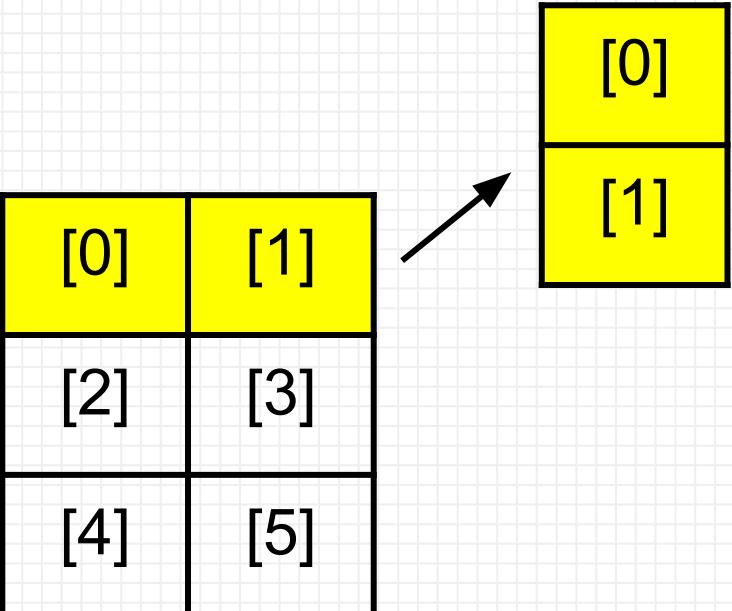
Images, Matrices, Vectors



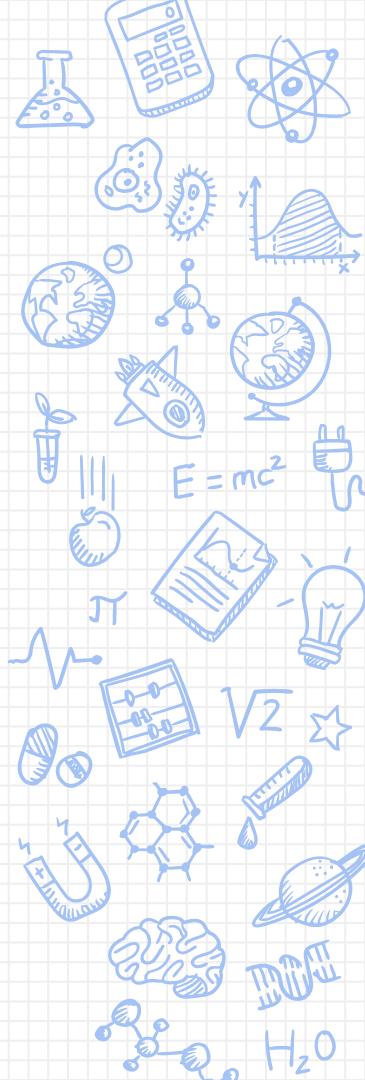
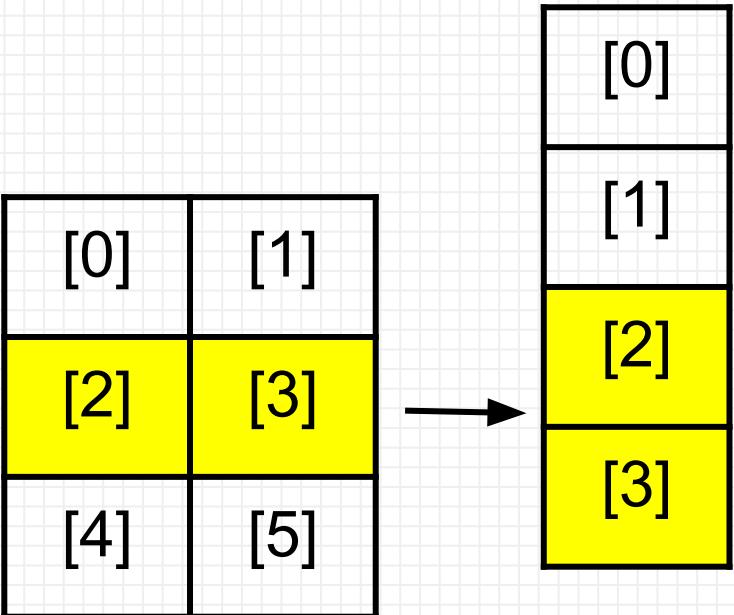
[0]	[1]
[2]	[3]
[4]	[5]



Images, Matrices, Vectors



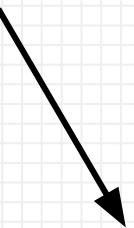
Images, Matrices, Vectors



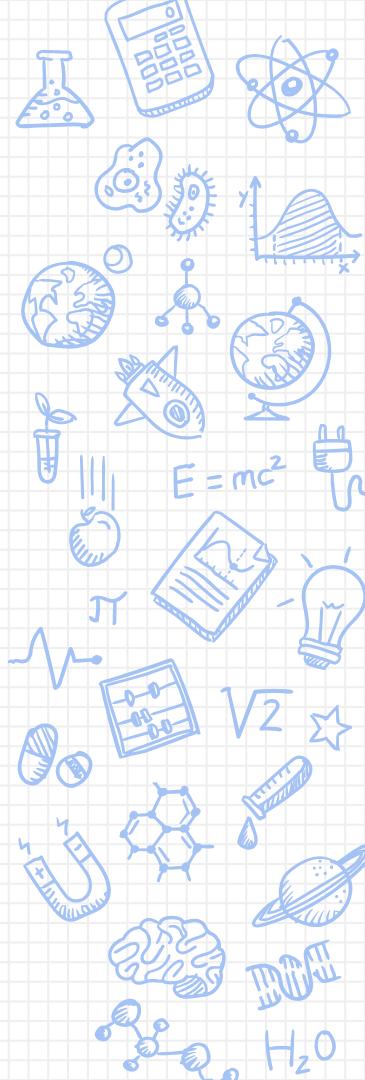
Images, Matrices, Vectors



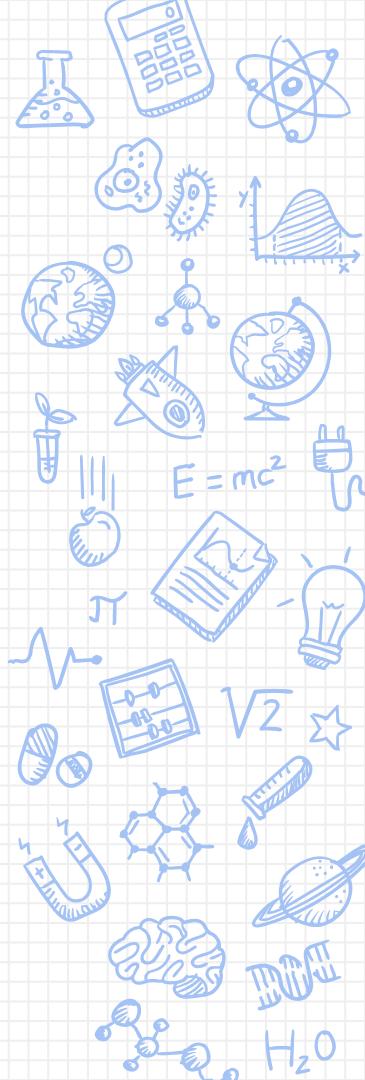
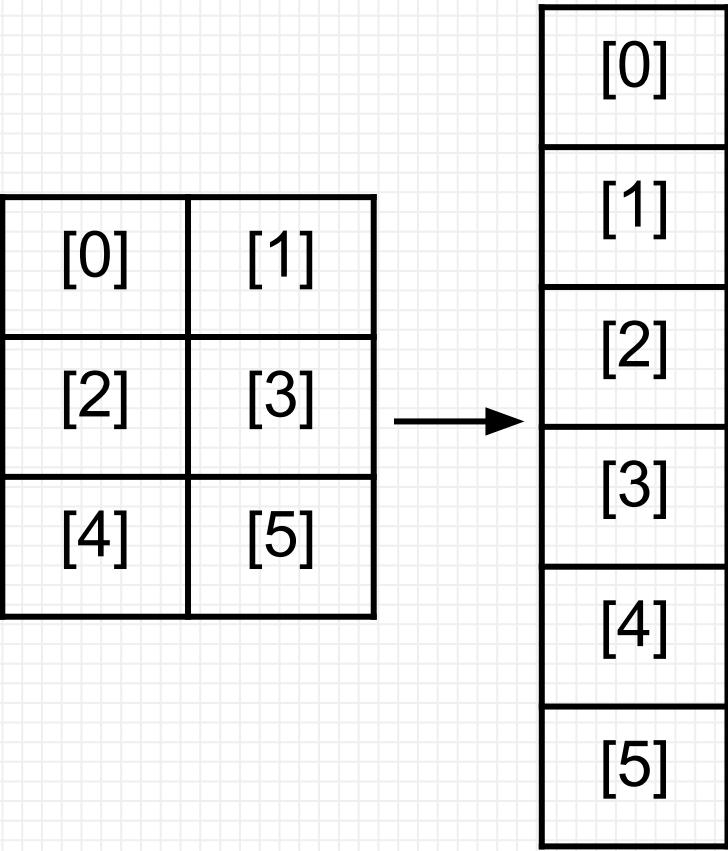
[0]	[1]
[2]	[3]
[4]	[5]



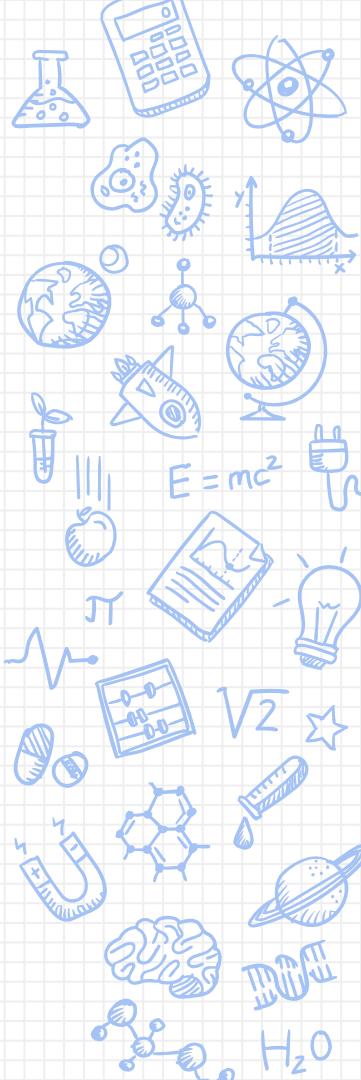
[0]
[1]
[2]
[3]
[4]
[5]



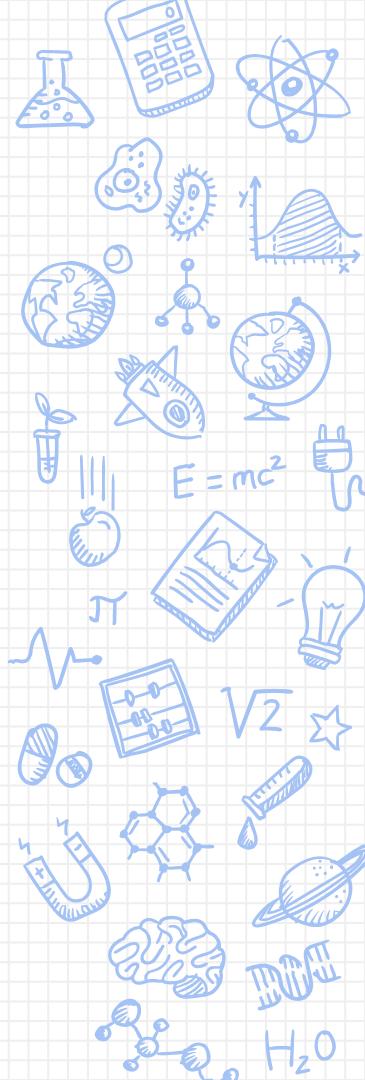
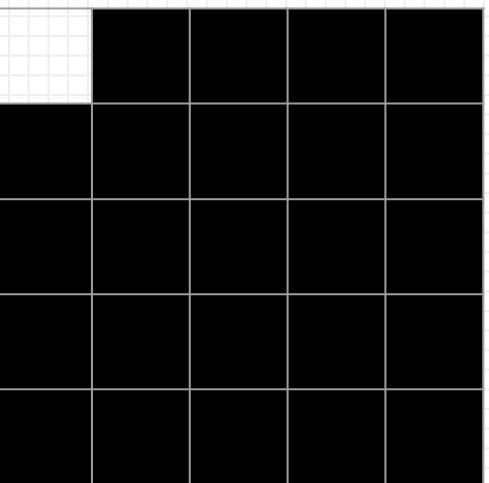
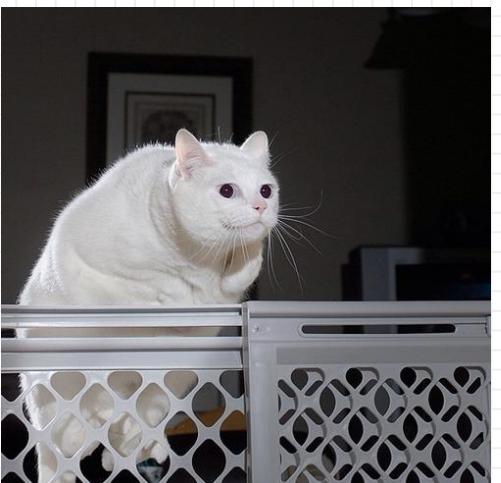
Images, Matrices, Vectors



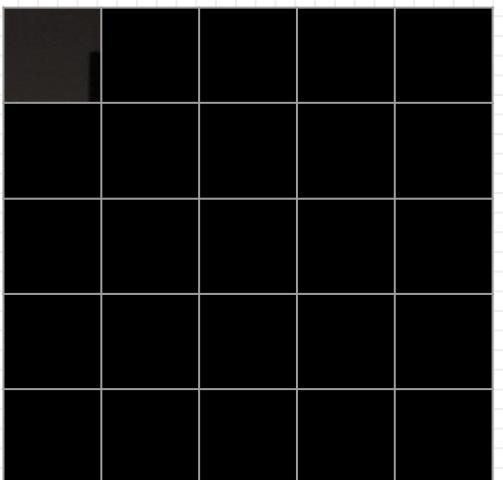
Pixel-by-Pixel Scan of an Image



Pixel-by-Pixel Scan of an Image



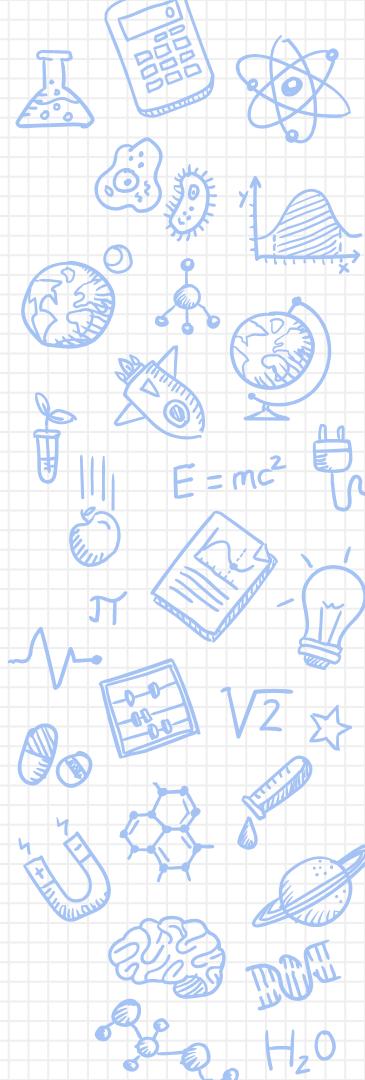
Pixel-by-Pixel Scan of an Image



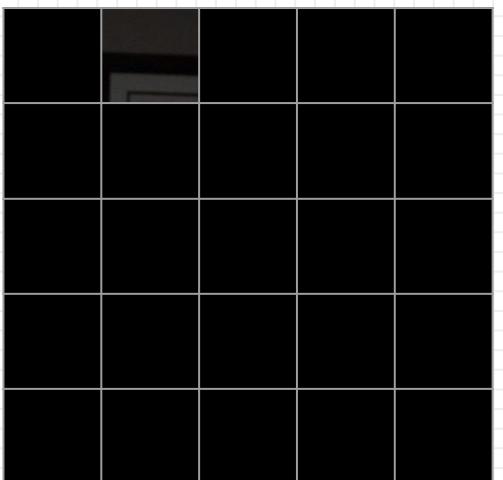
Masked image



Image



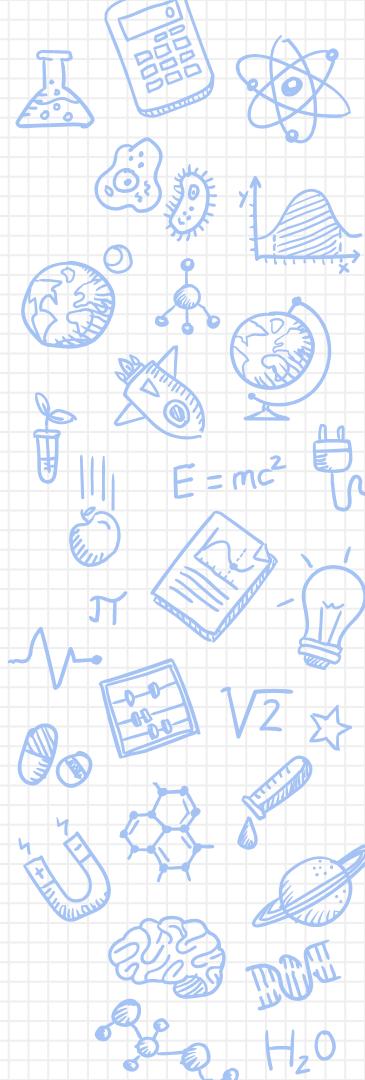
Pixel-by-Pixel Scan of an Image



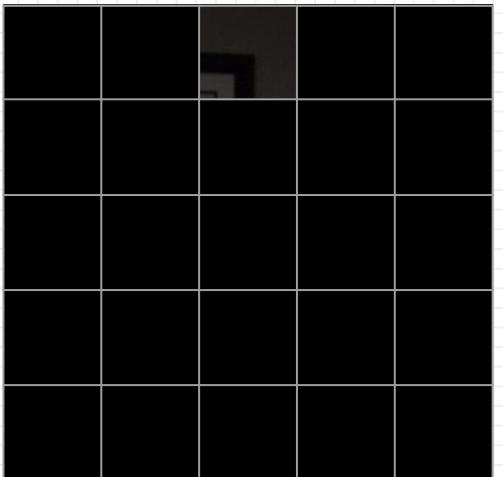
Masked image



Image



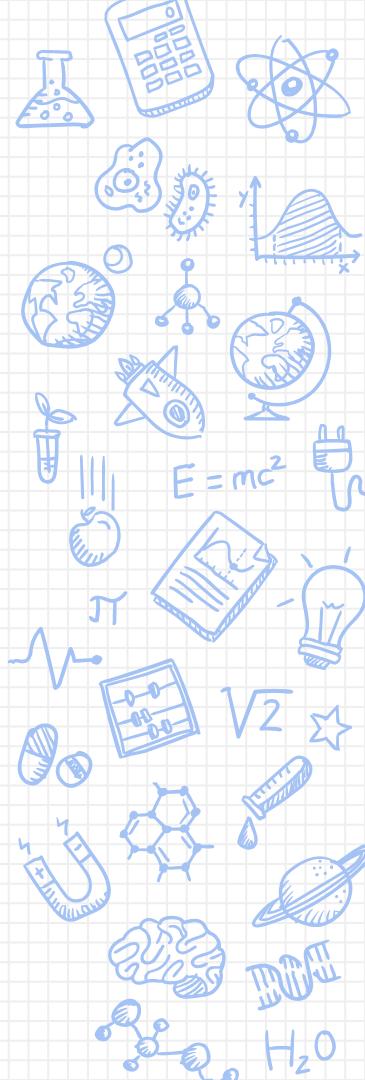
Pixel-by-Pixel Scan of an Image



Masked image

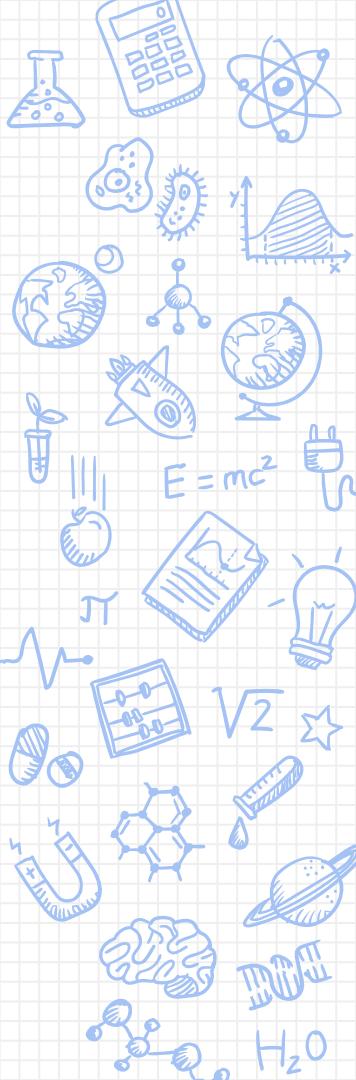


Image



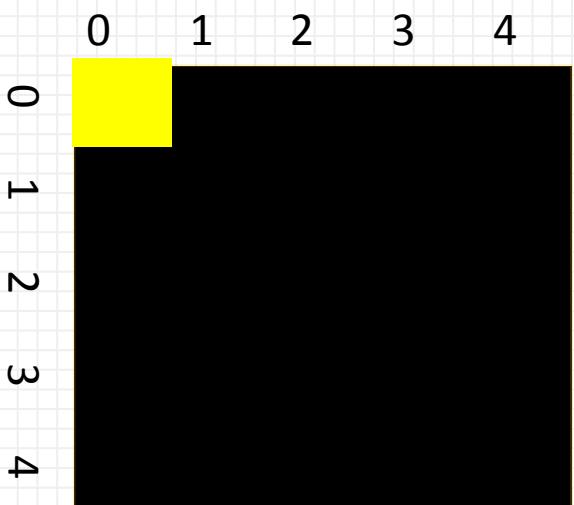
Question Time

- ✗ To read all the pixels of a 4x4 image, how many pixel-by-pixel scans do we need to do?



Representing our Masks in Python

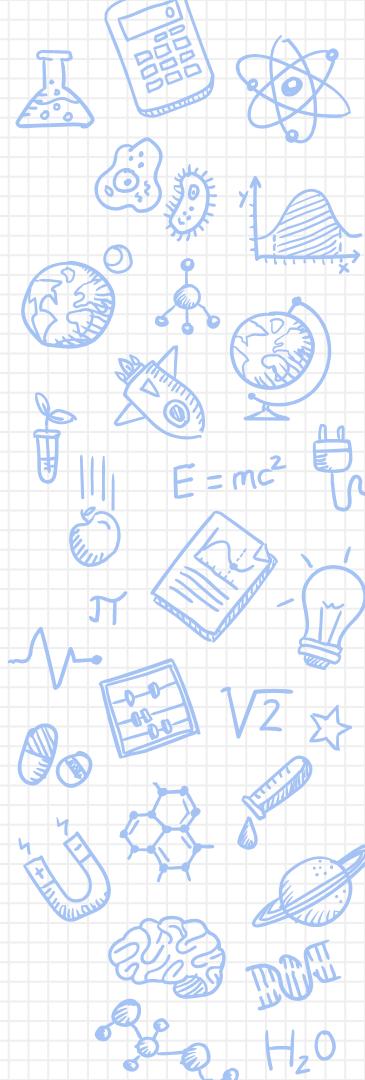
Imaging Mask 0



mask0 =

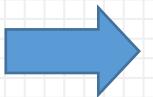
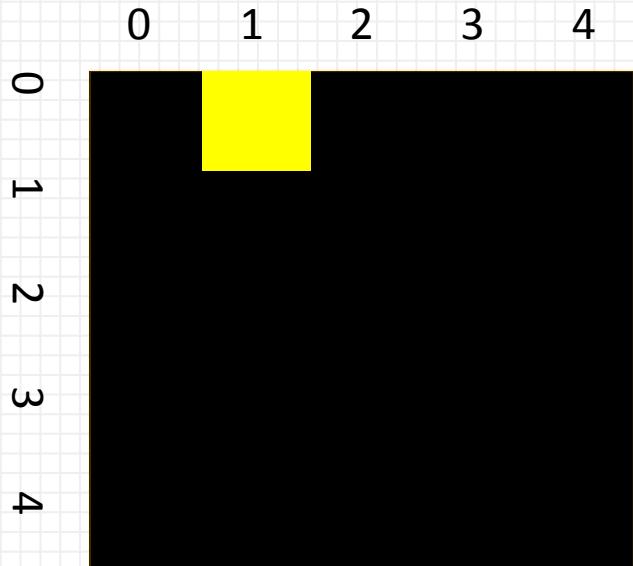
```
np.array([ [ 1, 0, 0, 0, 0 ]  
          [ 0, 0, 0, 0, 0 ]  
          [ 0, 0, 0, 0, 0 ]  
          [ 0, 0, 0, 0, 0 ]  
          [ 0, 0, 0, 0, 0 ] ])
```





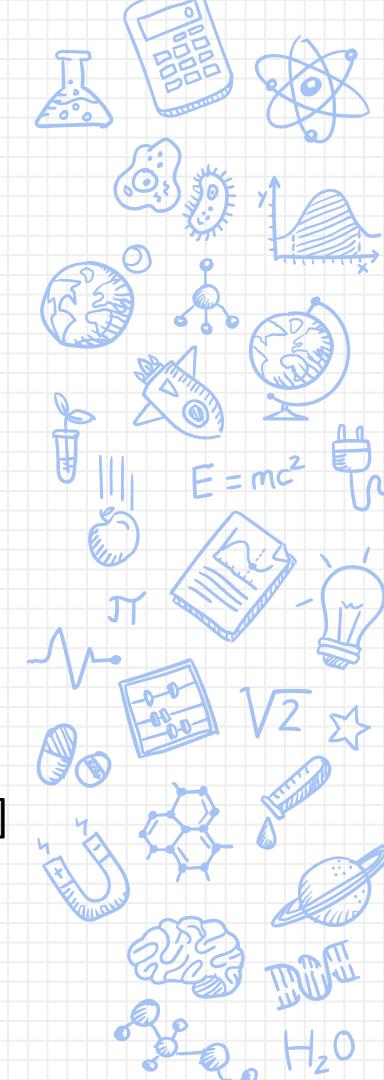
Representing our Masks in Python

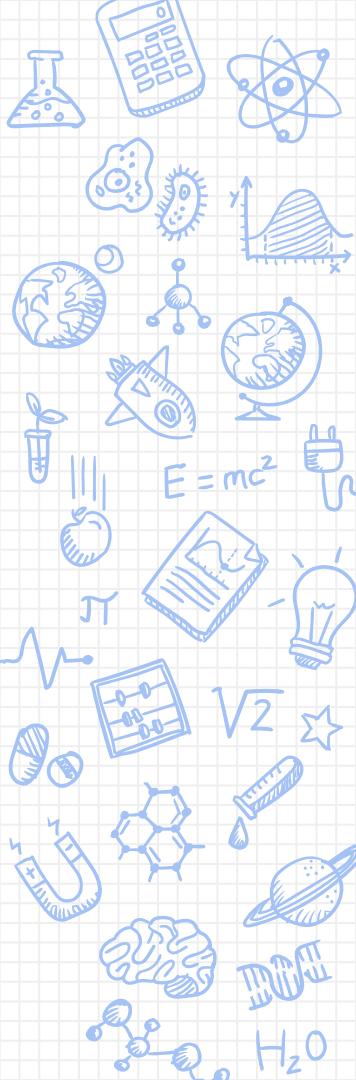
Imaging Mask 1



mask1 =

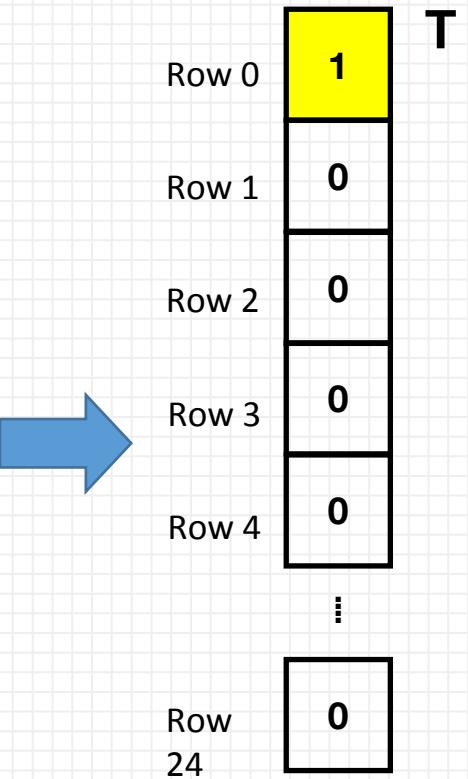
```
np.array([
    [ 0, 1, 0, 0, 0 ],
    [ 0, 0, 0, 0, 0 ],
    [ 0, 0, 0, 0, 0 ],
    [ 0, 0, 0, 0, 0 ],
    [ 0, 0, 0, 0, 0 ]])
```





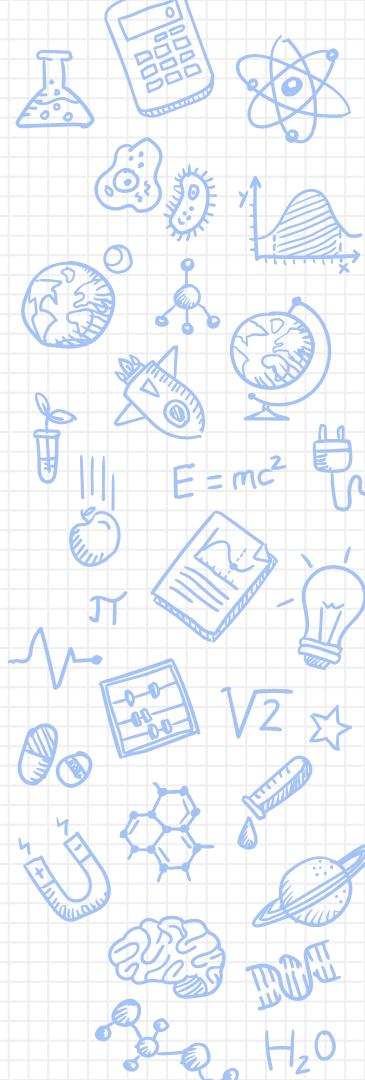
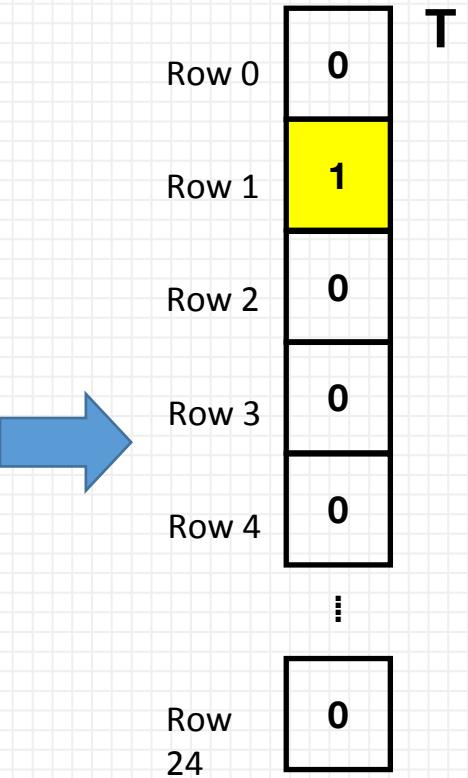
Turning the Masks Into Vectors

```
mask0 = [[ 1, 0, 0, 0, 0 ],  
          [ 0, 0, 0, 0, 0 ],  
          [ 0, 0, 0, 0, 0 ],  
          [ 0, 0, 0, 0, 0 ],  
          [ 0, 0, 0, 0, 0 ]]]
```



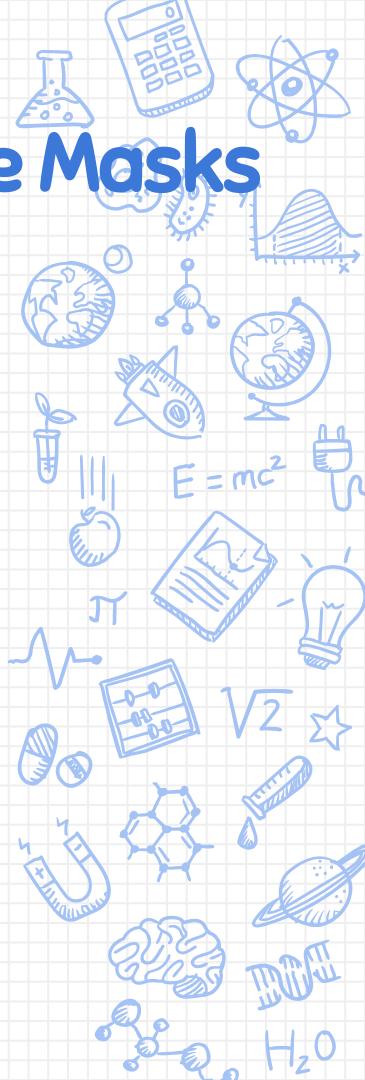
Turning the Masks Into Vectors

```
mask1 = [[0, 1, 0, 0, 0],  
         [0, 0, 0, 0, 0],  
         [0, 0, 0, 0, 0],  
         [0, 0, 0, 0, 0],  
         [0, 0, 0, 0, 0]]
```

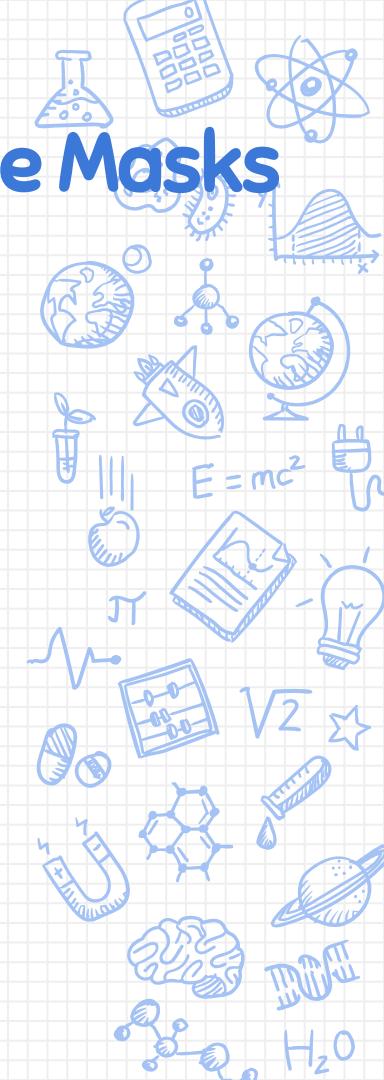
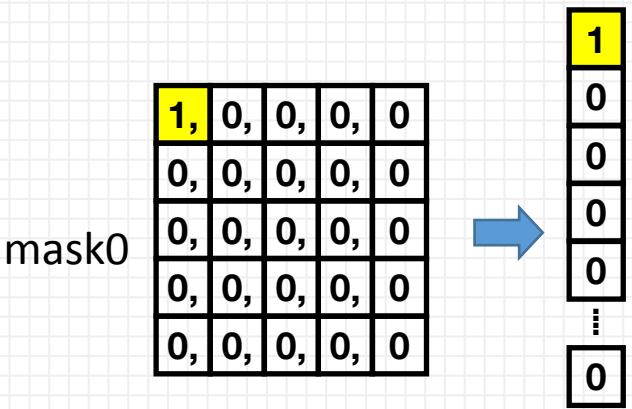


Generating the Masking Matrix from the Masks

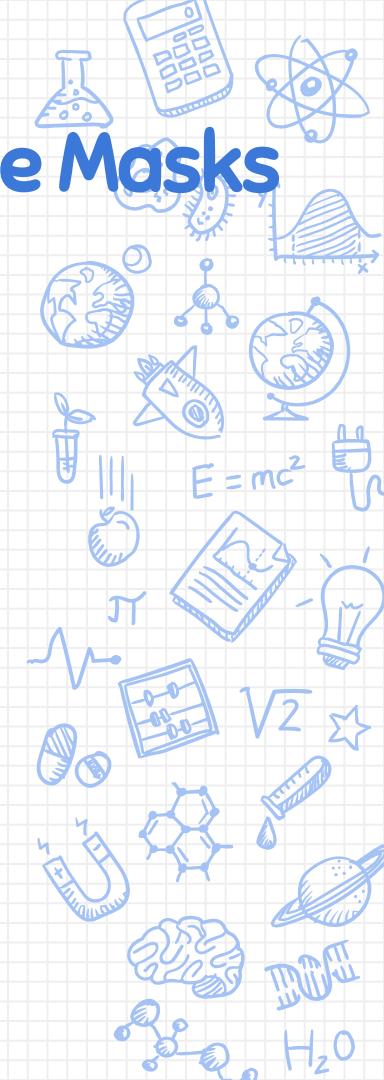
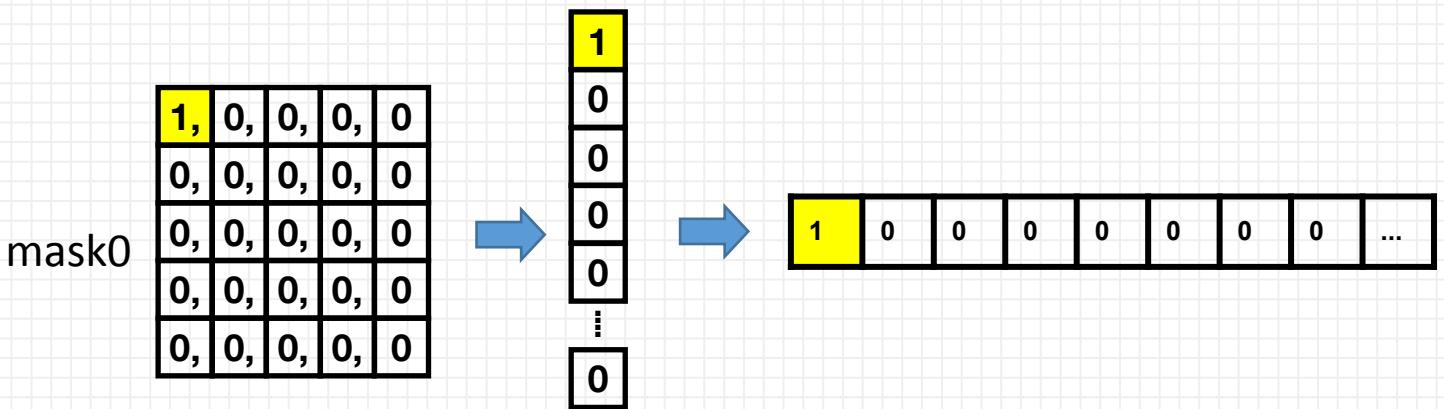
	1	0	0	0	0
mask0	0	0	0	0	0
	0	0	0	0	0
	0	0	0	0	0
	0	0	0	0	0



Generating the Masking Matrix from the Masks



Generating the Masking Matrix from the Masks

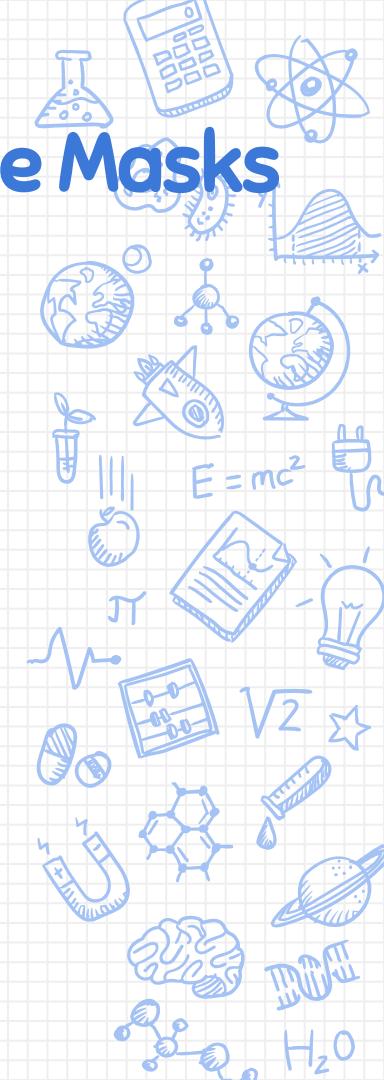


Generating the Masking Matrix from the Masks

mask1

0	1	0	0	0
0	0	0	0	0
0	0	0	0	0
0	0	0	0	0
0	0	0	0	0

1	0	0	0	0	0	0	0	...
---	---	---	---	---	---	---	---	-----



Generating the Masking Matrix from the Masks

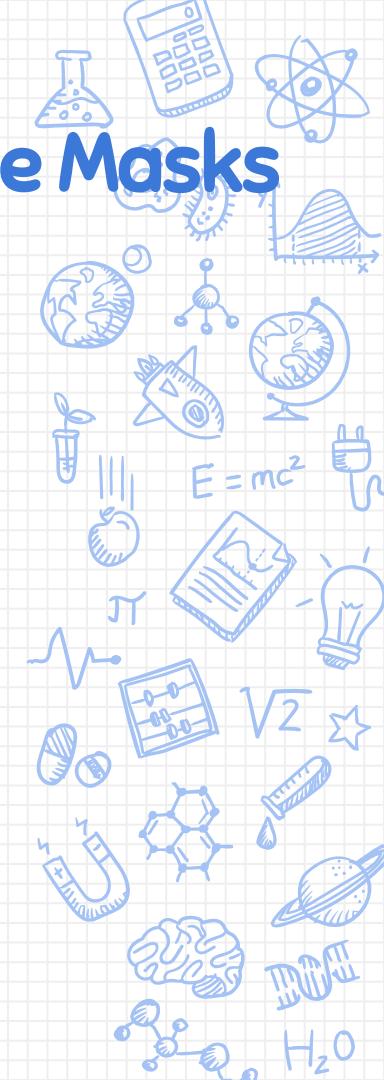
mask1

0	1	0	0	0
0	0	0	0	0
0	0	0	0	0
0	0	0	0	0
0	0	0	0	0

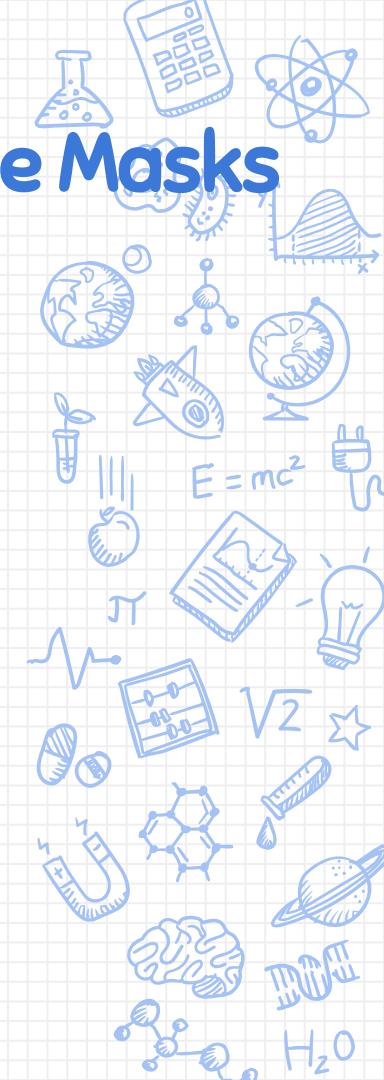
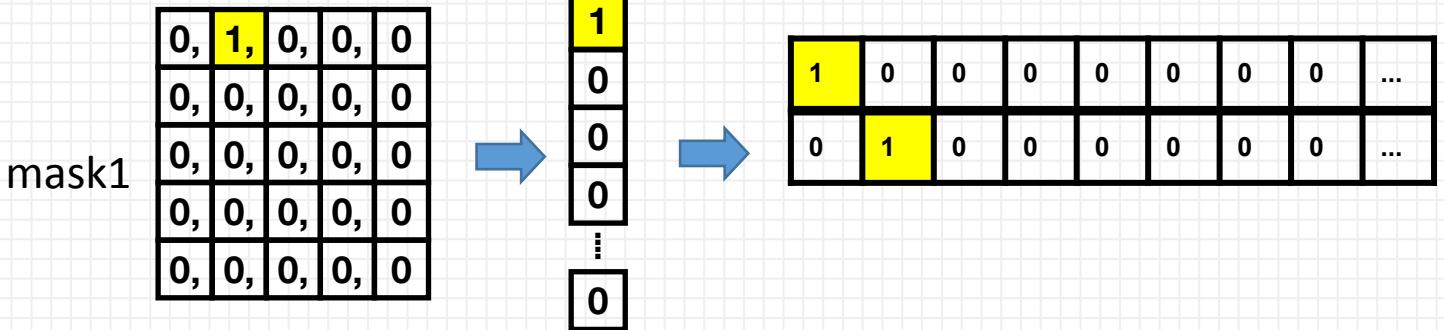


0
1
0
0
0
⋮
0

1	0	0	0	0	0	0	0	...
---	---	---	---	---	---	---	---	-----

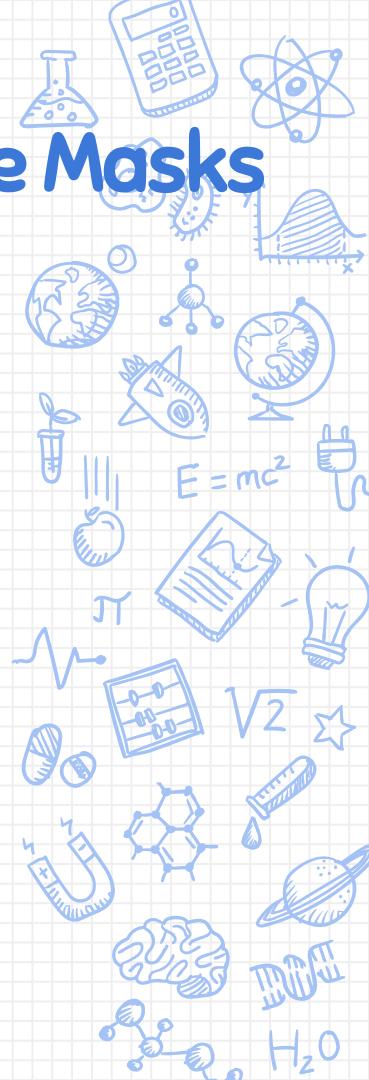


Generating the Masking Matrix from the Masks



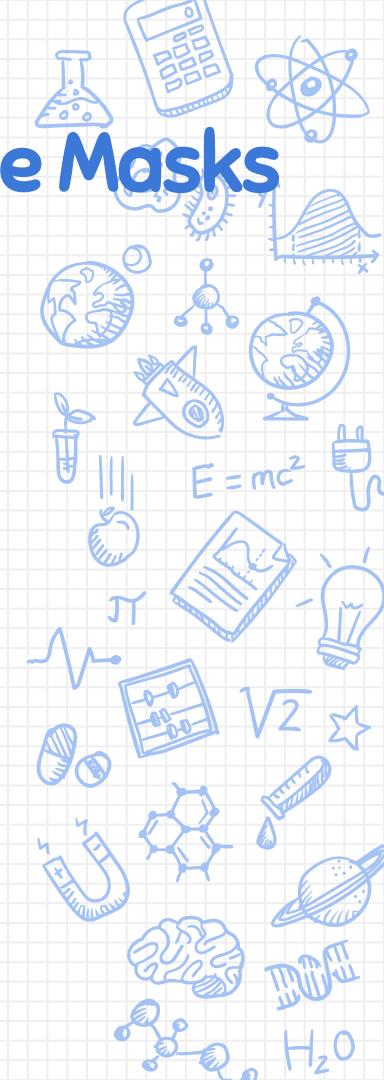
Generating the Masking Matrix from the Masks

1	0	0	0	0	0	0	0	...
0	1	0	0	0	0	0	0	...
0	0	1	0	0	0	0	0	...



Generating the Masking Matrix from the Masks

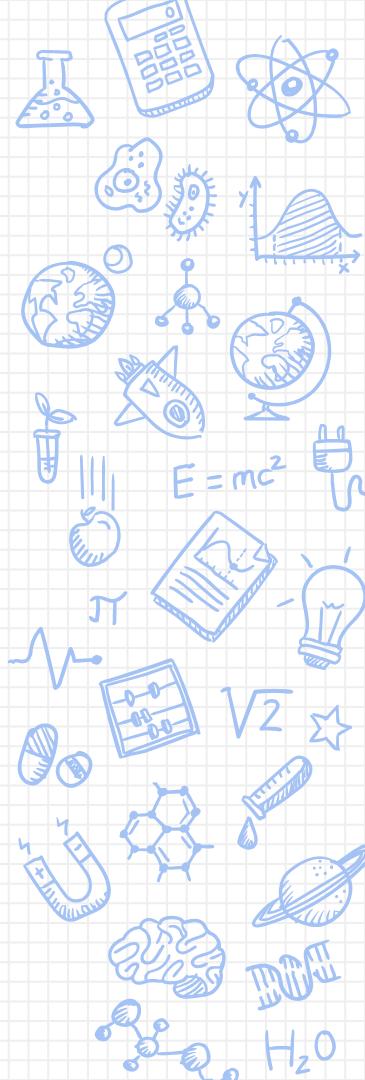
1	0	0	0	0	0	0	0	...
0	1	0	0	0	0	0	0	...
0	0	1	0	0	0	0	0	...
0	0	0	1	0	0	0	0	...



Each Row is a Different Experiment

$H =$

1	0	0	0	0	0	0	0	...
0	1	0	0	0	0	0	0	...
0	0	1	0	0	0	0	0	...
0	0	0	1	0	0	0	0	...
0	0	0	0	1	0	0	0	...
0	0	0	0	0	1	0	0	...
0	0	0	0	0	0	1	0	...
...								



Measuring a Pixel is Matrix–Vector Multiplication

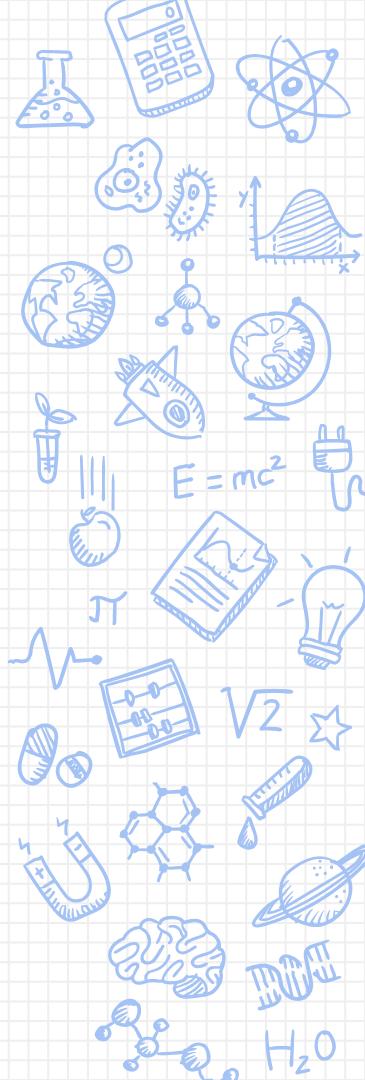
1	0	0	0	0	0	0	0	...
0	1	0	0	0	0	0	0	...
0	0	1	0	0	0	0	0	...
0	0	0	1	0	0	0	0	...
0	0	0	0	1	0	0	0	...
0	0	0	0	0	1	0	0	...
0	0	0	0	0	0	1	0	...
...								

Masking Matrix H

$$\begin{matrix} i_1 \\ i_2 \\ i_3 \\ \vdots \\ i_n \end{matrix} = \begin{matrix} s_1 \\ s_2 \\ s_3 \\ \vdots \\ s_n \end{matrix}$$

Unknown,
vectorized
image, \vec{i}

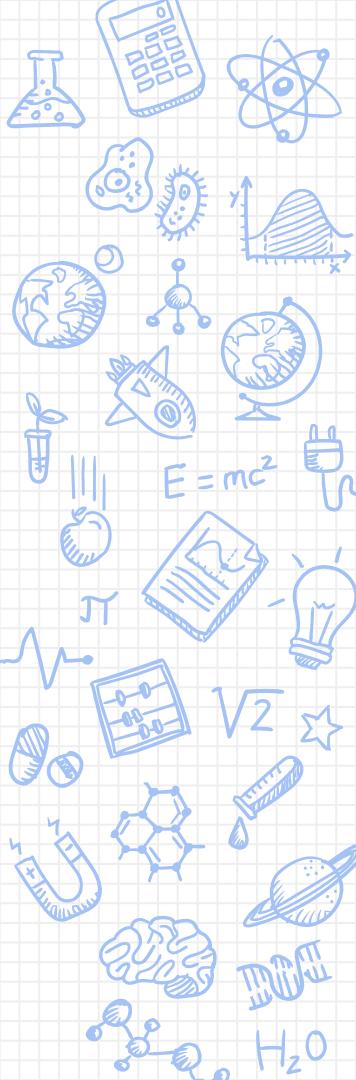
Recorded
Sensor
readings, \vec{s}



Measuring a Pixel is Matrix–Vector Multiplication

$$\vec{s} = H\vec{i}$$

- ✗ We know H and we have the sensor readings, how do we get the image?
 - ✗ How do we solve this?
 - ✗ When can we solve this?
 - ✗ Conditions on H

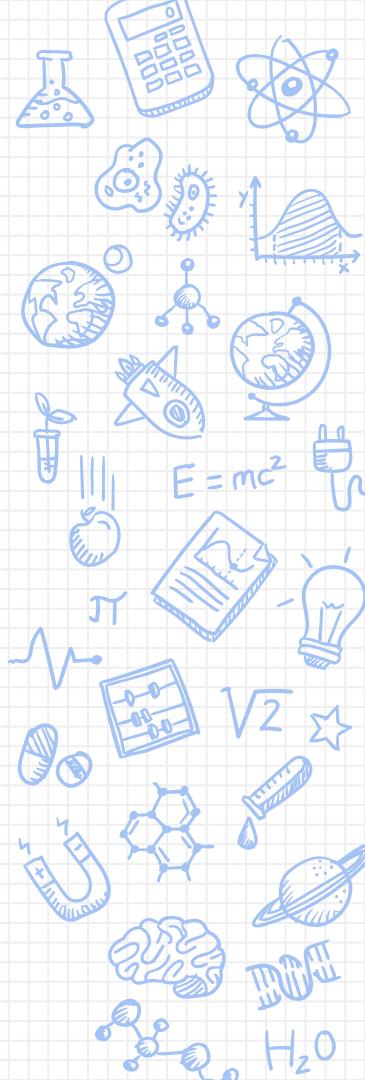


Example

1	0	0	0	0
0	0	0	0	0
0	0	0	0	0

What will the scanning matrix's dimensions be?

How many pixels?



Example

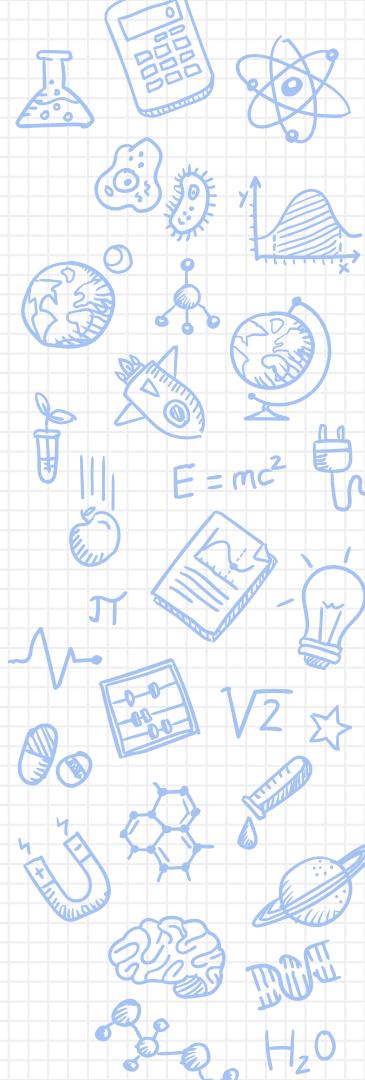
1	0	0	0	0
0	0	0	0	0
0	0	0	0	0

What will the scanning matrix's dimensions be?

15x15

How many pixels?

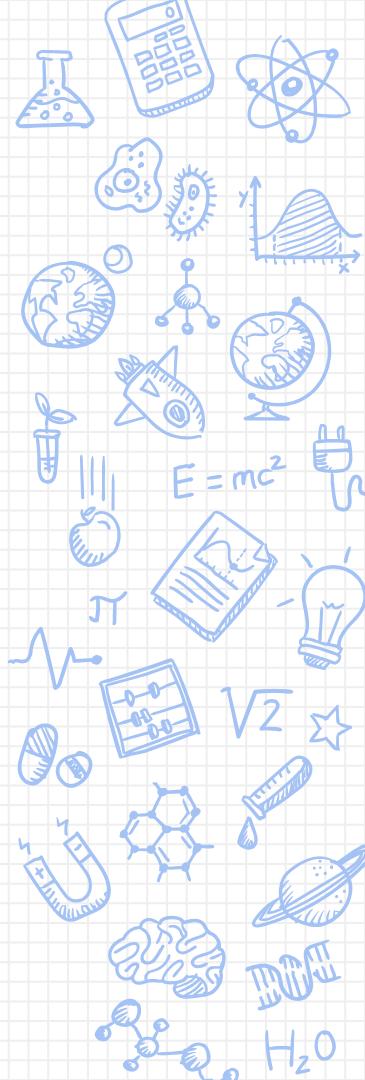
15



How Scanning Works: iPython

H =

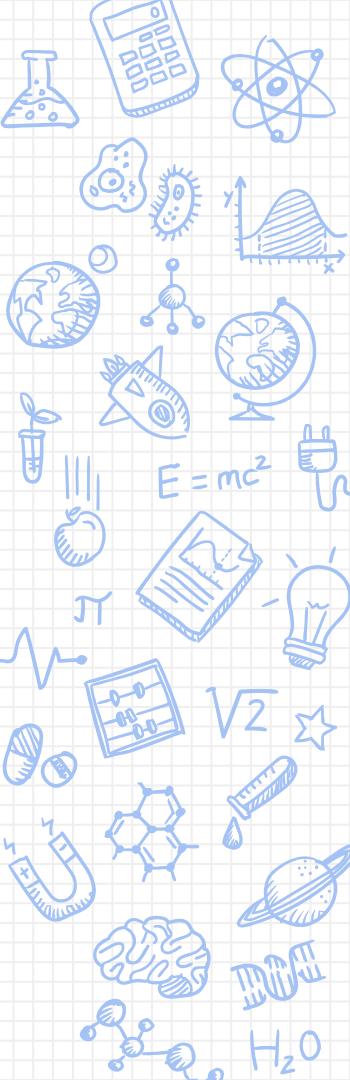
1	0	0	0	0	0	0	0	...
0	1	0	0	0	0	0	0	...
0	0	1	0	0	0	0	0	...
0	0	0	1	0	0	0	0	...
0	0	0	0	1	0	0	0	...
0	0	0	0	0	1	0	0	...
0	0	0	0	0	0	1	0	...
...								



How Scanning Works: iPython

H =

1	0	0	0	0	0	0	0	...
0	1	0	0	0	0	0	0	...
0	0	1	0	0	0	0	0	...
0	0	0	1	0	0	0	0	...
0	0	0	0	1	0	0	0	...
0	0	0	0	0	1	0	0	...
0	0	0	0	0	0	1	0	...



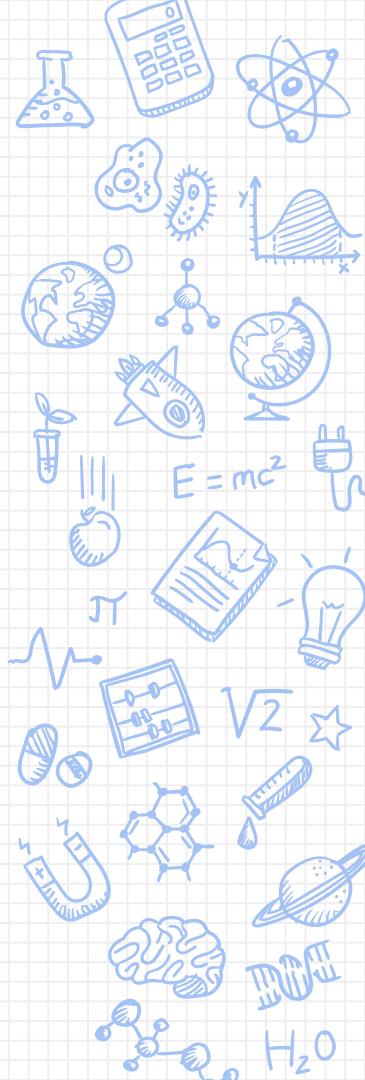
How Scanning Works: iPython

H =

1	0	0	0	0	0	0	0	0	...
0	1	0	0	0	0	0	0	0	...
0	0	1	0	0	0	0	0	0	...
0	0	0	1	0	0	0	0	0	...
0	0	0	0	1	0	0	0	0	...
0	0	0	0	0	1	0	0	0	...
0	0	0	0	0	0	1	0	0	...
...									



0
1
0
0
0
0
0
...



How Scanning Works: iPython

H =

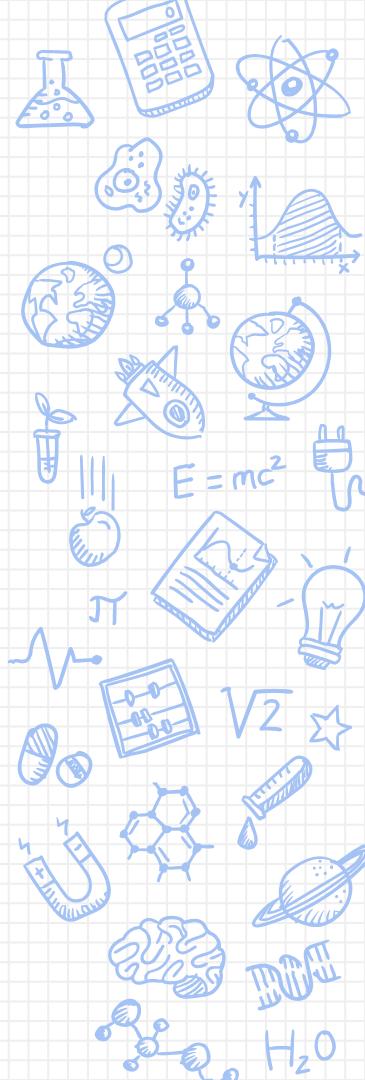
1	0	0	0	0	0	0	0	...
0	1	0	0	0	0	0	0	...
0	0	1	0	0	0	0	0	...
0	0	0	1	0	0	0	0	...
0	0	0	0	1	0	0	0	...
0	0	0	0	0	1	0	0	...
0	0	0	0	0	0	1	0	...
...								



0
1
0
0
0
0
...
0



0	1	0	0	0
0	0	0	0	0
0	0	0	0	0
0	0	0	0	0
0	0	0	0	0



How Scanning Works: iPython

H =

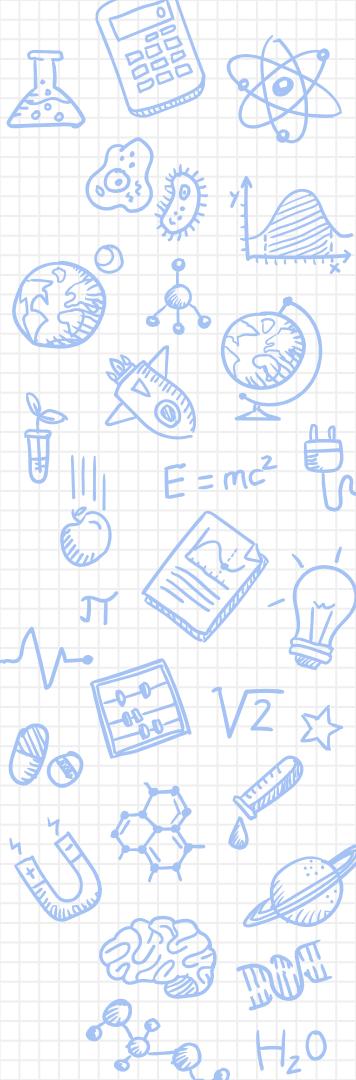
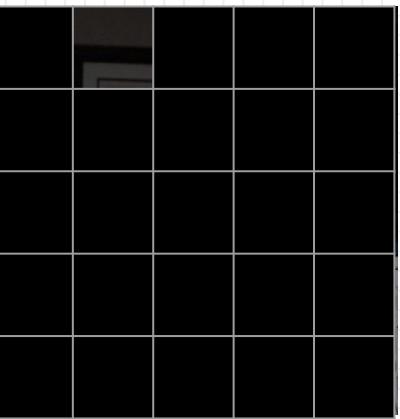
1	0	0	0	0	0	0	0	...
0	1	0	0	0	0	0	0	...
0	0	1	0	0	0	0	0	...
0	0	0	1	0	0	0	0	...
0	0	0	0	1	0	0	0	...
0	0	0	0	0	1	0	0	...
0	0	0	0	0	0	1	0	...
...								



0
1
0
0
0
0
...
0

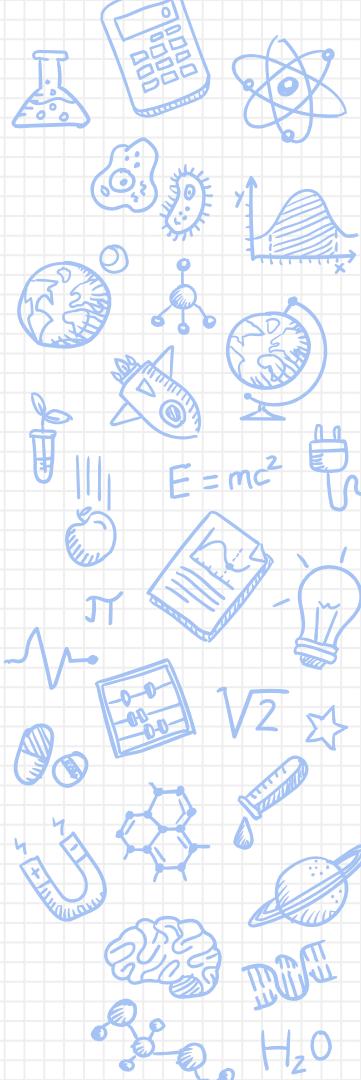


0	1	0	0	0
0	0	0	0	0
0	0	0	0	0
0	0	0	0	0
0	0	0	0	0



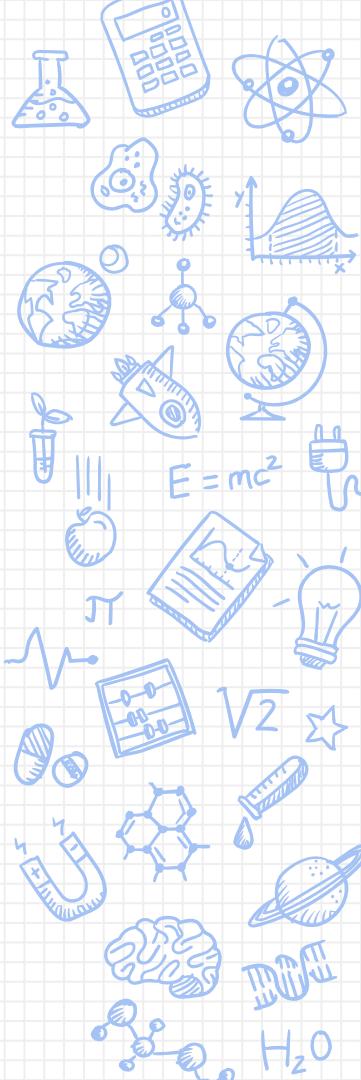
What Makes A Mask Good?

- ✗ Linearily independent columns -> Invertible
 - ✗ Can't get a solution without this
 - ✗ There is a unique solution
- ✗ What would be a bad mask?
- ✗ Food for thought: Are all invertible matrices equally as good?
 - ✗ Find out next week...



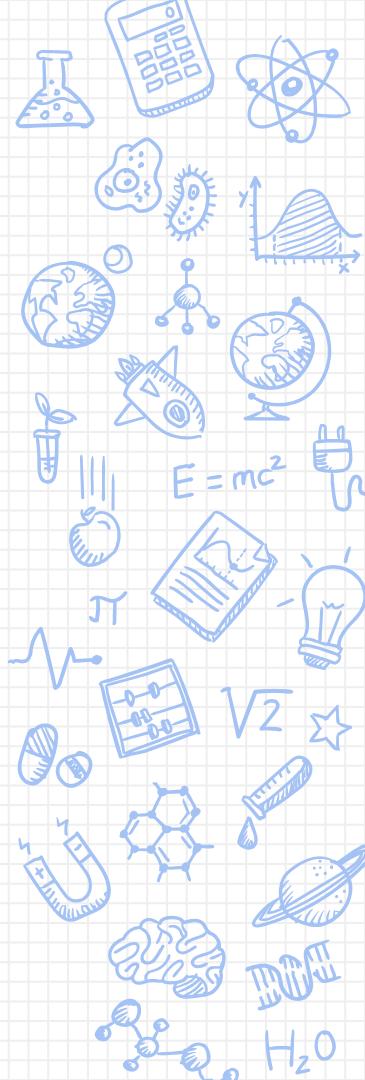
Tips for a Good Image

- ✗ READ CLOSELY. There are many small directions that help you get a good setup
- ✗ Focus projector using dial on the side
- ✗ Close the box firmly & scan under dark conditions

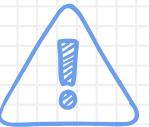


Notes

- ✗ No signal when testing the oscope on their previous circuit
 - ✗ **Unplug P6.0 from MSP and debug if necessary**
- ✗ UART Application Com Port not showing up as an option when scanning
 - ✗ **Close serial monitor!**
- ✗ Do not take sharpies and tape from the desk
- ✗ If something isn't working, close everything and turn it back on (works 9/10 times)



Important Notes



- ✗ You should have your kit from last week
- ✗ Equipment in cardboard box:
 - ✗ Don't break the plastic stand!
 - ✗ Put everything back before you leave!
 - Including Projector's Power
- ✗ Make sure you are using the right com port at all times
 - ✗ Not COM1, and not the debugger

