Chapter 3: Asymptotic Statistics

Jonathan Roth

Mathematical Econometrics I Brown University Fall 2023

Outline

- 1. Overview
- 2. LLN, CLT, and CMT
- 3. Putting Asymptotics into Practice

Motivation

- We've seen how we can test hypotheses about population means using information from the sample mean $\hat{\mu}$ when it is **normally distributed** with a known variance
- ullet This situation arises when we know that $Y_i \sim \mathrm{N}(\mu,\sigma^2)$ with known σ
- But this situation is rare... how do we "do inference" more generally?

Motivation

- We've seen how we can test hypotheses about population means using information from the sample mean $\hat{\mu}$ when it is **normally distributed** with a known variance
- ullet This situation arises when we know that $Y_i \sim N(\mu,\sigma^2)$ with known σ
- But this situation is rare... how do we "do inference" more generally?
- Fortunately, the assumption of normally distributed sample means turns out to be a good approximation when samples are large

Motivation

- We've seen how we can test hypotheses about population means using information from the sample mean $\hat{\mu}$ when it is **normally distributed** with a known variance
- ullet This situation arises when we know that $Y_i \sim N(\mu,\sigma^2)$ with known σ
- But this situation is rare... how do we "do inference" more generally?
- Fortunately, the assumption of normally distributed sample means turns out to be a good **approximation** when samples are large
- What we mean by a "good approximation" is formalized by asymptotic statistics, which considers the distribution of $\hat{\mu}$ in the limit as $N \to \infty$

Overview of Important Results

• The Law of Large Numbers (LLN) says that when N is large, $\hat{\mu}$ is close to μ with very high probability

Overview of Important Results

- The Law of Large Numbers (LLN) says that when N is large, $\hat{\mu}$ is close to μ with very high probability
- The **Central Limit Theorem** (CLT) says that when N is large, the distribution of $\hat{\mu}$ is approximately normally distributed with mean μ and variance σ^2/n

Overview of Important Results

- The Law of Large Numbers (LLN) says that when N is large, $\hat{\mu}$ is close to μ with very high probability
- The **Central Limit Theorem** (CLT) says that when N is large, the distribution of $\hat{\mu}$ is approximately normally distributed with mean μ and variance σ^2/n
- The Continuous Mapping Theorem says that when N is large, continuous functions of $\hat{\mu}$, say $g(\hat{\mu})$, are also close to $g(\mu)$

Outline

- 1. Overview ✓
- 2. LLN, CLT, and CMT
- 3. Putting Asymptotics into Practice

• Intuitively, a random variable X_N converges in probability to x if the probability that X_N is "close to" x is almost 1 when N is large

- Intuitively, a random variable X_N converges in probability to x if the probability that X_N is "close to" x is almost 1 when N is large
- Formally, we say X_N converges in probability to x, $X_n \to_p x$ or $plim X_n = x$, if for all $\varepsilon > 0$,

$$P(|X_N-x|>\varepsilon)\to 0$$

- Intuitively, a random variable X_N converges in probability to x if the probability that X_N is "close to" x is almost 1 when N is large
- Formally, we say X_N converges in probability to x, $X_n \rightarrow_p x$ or $plim X_n = x$, if for all $\varepsilon > 0$,

$$P(|X_N-x|>\varepsilon)\to 0$$

• If $X_n \rightarrow_p x$ for a constant x, we say X_n is *consistent* for x

- Intuitively, a random variable X_N converges in probability to x if the probability that X_N is "close to" x is almost 1 when N is large
- Formally, we say X_N converges in probability to x, $X_n \to_p x$ or $plim X_n = x$, if for all $\varepsilon > 0$,

$$P(|X_N-x|>\varepsilon)\to 0$$

- If $X_n \rightarrow_p x$ for a constant x, we say X_n is *consistent* for x
- Typically x is a constant, although we will sometimes also say $X_N \to X$ for X a random variable (using the same definition as above)

• Useful fact: if $E[(X_N - x)^2] \to 0$, then $X_N \to_p x$

- Useful fact: if $E[(X_N x)^2] \to 0$, then $X_N \to_p x$
- Proof (you won't be responsible for this):
 By the law of iterated expectations,

$$E[(X_N - x)^2] = P(|X_n - x| > \varepsilon)E[(X_N - x)^2 | |X_n - x| > \varepsilon] + P(|X_n - x| \le \varepsilon)E[(X_N - x)^2 | |X_n - x| \le \varepsilon]$$

- Useful fact: if $E[(X_N x)^2] \to 0$, then $X_N \to_p x$
- Proof (you won't be responsible for this):
 By the law of iterated expectations,

$$E[(X_N - x)^2] = P(|X_n - x| > \varepsilon)E[(X_N - x)^2 | |X_n - x| > \varepsilon] + P(|X_n - x| \le \varepsilon)E[(X_N - x)^2 | |X_n - x| \le \varepsilon]$$
$$\ge P(|X_n - x| > \varepsilon)\varepsilon^2 + 0$$

- Useful fact: if $E[(X_N x)^2] \to 0$, then $X_N \to_p x$
- Proof (you won't be responsible for this):
 By the law of iterated expectations,

$$E[(X_N - x)^2] = P(|X_n - x| > \varepsilon)E[(X_N - x)^2 | |X_n - x| > \varepsilon] + P(|X_n - x| \le \varepsilon)E[(X_N - x)^2 | |X_n - x| \le \varepsilon]$$
$$\ge P(|X_n - x| > \varepsilon)\varepsilon^2 + 0$$

This implies that

$$P(|X_N - x| > \varepsilon) \le E[(X_N - x)^2]/\varepsilon^2$$
 (Chebychev's Inequality)

- Useful fact: if $E[(X_N x)^2] \to 0$, then $X_N \to_p x$
- Proof (you won't be responsible for this):
 By the law of iterated expectations,

$$E[(X_N - x)^2] = P(|X_n - x| > \varepsilon)E[(X_N - x)^2 | |X_n - x| > \varepsilon] + P(|X_n - x| \le \varepsilon)E[(X_N - x)^2 | |X_n - x| \le \varepsilon]$$
$$\ge P(|X_n - x| > \varepsilon)\varepsilon^2 + 0$$

This implies that

$$P(|X_N-x|>\varepsilon) \le E[(X_N-x)^2]/\varepsilon^2$$
 (Chebychev's Inequality)
Hence, $E[(X_N-x)^2] \to 0$ implies $P(|X_N-x|>\varepsilon) \to 0$

Law of Large Numbers

• Law of Large Numbers. Suppose that $Y_1,...,Y_N$ are drawn *iid* from a distribution with $Var(Y_i) = \sigma^2 < \infty$. Then

$$\hat{\mu}_N = \frac{1}{N} \sum_{i=1}^N Y_i \to_p \mu = E[Y_i]$$

 In words: as the sample gets large, the sample mean will be close to the population mean with high probability.

Law of Large Numbers

• Law of Large Numbers. Suppose that $Y_1,...,Y_N$ are drawn *iid* from a distribution with $Var(Y_i) = \sigma^2 < \infty$. Then

$$\hat{\mu}_N = \frac{1}{N} \sum_{i=1}^N Y_i \to_P \mu = E[Y_i]$$

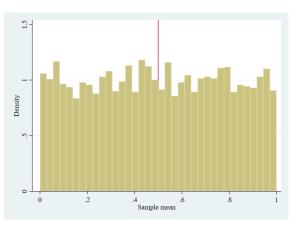
- In words: as the sample gets large, the sample mean will be close to the population mean with high probability.
- **Proof:** We saw last chapter that $E[\hat{\mu}_N] = \mu$ and $Var(\hat{\mu}_N) = \sigma^2/N$. Thus,

$$Var(\hat{\mu}_N) = E[(\hat{\mu}_N - \mu)^2] = \sigma^2/N \rightarrow 0$$

Hence, $\hat{\mu}_N \rightarrow_p \mu$ by our "useful fact".

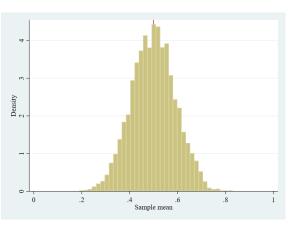
Distribution and mean of $\frac{1}{N}\sum_i Z_i$ when $Z_i \sim \mathrm{U}(0,1)$, $\mathbf{N} = \mathbf{1}$

```
matrix sims=J(5000,1,.)
    foreach N in 1 10 100 1000 (
30
           forval 1=1/5000 {
31
32
33
                   set obs 'N'
34
                   gen X = runiform()
36
                   matrix sims['j',1]=r(mean)
37
38
39
          clear
41
           local mean = r(mean)
          hist sims, xlabel(0(0.2)1) xline('mean')
           graph export sims'N'_2.png, replace
```



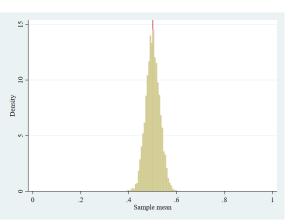
Distribution and mean of $\frac{1}{N}\sum_{i}Z_{i}$ when $Z_{i}\sim \mathrm{U}(0,1)$, $\mathbf{N}=\mathbf{10}$

```
foreach N in 1 10 100 1000 (
           forval i=1/5000 {
31
32
33
                   set obs 'N'
34
                   gen X = runiform()
36
                   matrix sims['j',1]=r(mean)
37
38
39
          clear
41
           summ sims
42
          local mean = r(mean)
          hist sims, xlabel(0(0.2)1) xline('mean')
           graph export sims'N'_2.png, replace
```



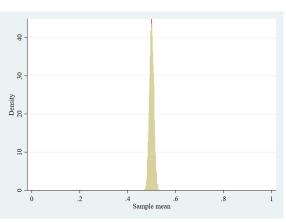
Distribution and mean of $\frac{1}{N}\sum_i Z_i$ when $Z_i \sim \mathrm{U}(0,1)$, $\mathbf{N} = \mathbf{100}$

```
foreach N in 1 10 100 1000 (
30
           forval i=1/5000 {
31
32
                   clear
33
                   set obs 'N'
34
                   gen X = runiform()
36
                   matrix sims['j',1]=r(mean)
37
38
39
          clear
           symat sims
41
           summ sims
42
          local mean = r(mean)
          hist sims, xlabel(0(0.2)1) xline('mean')
           graph export sims'N'_2.png, replace
```



Distribution and mean of $\frac{1}{N}\sum_i Z_i$ when $Z_i \sim \mathrm{U}(0,1)$, $\mathbf{N} = \mathbf{1000}$

```
matrix sims=J(5000,1,.)
    foreach N in 1 10 100 1000
30
           forval i=1/5000 (
31
32
                   clear
33
                   set obs 'N'
34
                   gen X = runiform()
35
36
                   matrix sims['j',1]=r(mean)
37
38
39
          clear
           symat sims
41
           summ sims
42
          local mean = r(mean)
          hist sims, xlabel(0(0.2)1) xline('mean')
           graph export sims'N'_2.png, replace
```



Convergence in Distribution

- ullet You might have noticed that the distribution of $\hat{\mu}$ in the simulations looks close to a normal distribution as N gets large
- The notion of **convergence in distribution** formalizes what it means for one distribution to be close to another distribution

Convergence in Distribution

- ullet You might have noticed that the distribution of $\hat{\mu}$ in the simulations looks close to a normal distribution as N gets large
- The notion of convergence in distribution formalizes what it means for one distribution to be close to another distribution
- Definition: We say that X_N converges in distribution to a continuously distributed variable X, denoted $X_n \rightarrow_d X$ or $X_n \Rightarrow X$, if the CDF of X_N converges (pointwise) to the CDF of X,

$$F_{X_N}(x) \to F_X(x)$$
 for all x

Central Limit Theorem

 The Central Limit Theorem (CLT) formalizes the sense in which sample means are approximately normally distributed in large samples

Central Limit Theorem

- The Central Limit Theorem (CLT) formalizes the sense in which sample means are approximately normally distributed in large samples
- Theorem: Suppose that $Y_1,...,Y_N$ are drawn *iid* from a distribution with mean $\mu=E[Y_i]$ and variance $Var(Y_i)=\sigma^2<\infty$. Then the sample mean $\hat{\mu}=\frac{1}{N}\sum_{i=1}^N Y_i$ satisfies

$$\sqrt{N}(\hat{\mu}-\mu) \to_{d} N(0,\sigma^2)$$

Central Limit Theorem

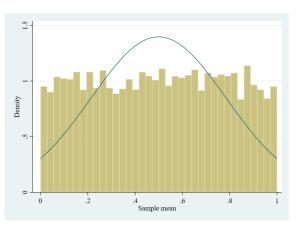
- The Central Limit Theorem (CLT) formalizes the sense in which sample means are approximately normally distributed in large samples
- Theorem: Suppose that $Y_1,...,Y_N$ are drawn *iid* from a distribution with mean $\mu=E[Y_i]$ and variance $Var(Y_i)=\sigma^2<\infty$. Then the sample mean $\hat{\mu}=\frac{1}{N}\sum_{i=1}^N Y_i$ satisfies

$$\sqrt{N}(\hat{\mu}-\mu) \rightarrow_d N(0,\sigma^2)$$

- In words, the theorem says the following:
 - **1** We can start with any distribution Y_i , possibly non-normal
 - ② If we take the average of the $Y_1,...,Y_N$ in a sample sufficiently large, the distribution of $\hat{\mu} = \frac{1}{N} \sum_i Y_i$ is (approximately) normal!

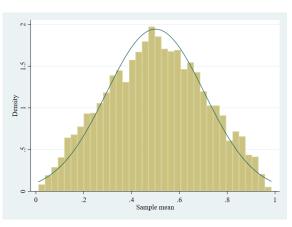
Distributions of $\hat{\mu} = \frac{1}{N} \sum_i X_i$ vs. $N(E[\hat{\mu}], Var(\hat{\mu}))$: $X_i \sim U(0,1)$, N = 1

```
clear all
      set seed 42
      set matsize 5000
      matrix sims=J(5000,1,.)
    ☐ foreach N in 1 2 5 10 (
          forval 1=1/5000 (
                   clear
                   set obs 'N'
                   gen X = runiform()
                   summ X
19
                   matrix sims['j',1]=r(mean)
20
21
22
          clear
          hist sims, normal xtitle("Sample mean")
          graph export sims'N'.png. replace
```



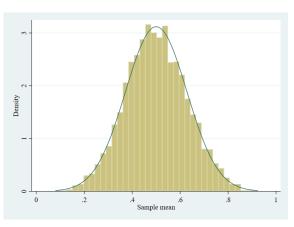
Distributions of $\hat{\mu} = \frac{1}{N} \sum_i X_i$ vs. $N(E[\hat{\mu}], Var(\hat{\mu}))$: $X_i \sim U(0,1)$, N = 2

```
clear all
      set seed 42
      set matsize 5000
      matrix sims=J(5000,1,.)
    foreach N in 1 2 5 10 (
          forval i=1/5000 (
                   clear
                   set obs 'N'
                   gen X = runiform()
                   summ X
19
                   matrix sims['j',1]=r(mean)
20
21
22
          clear
          hist sims, normal xtitle("Sample mean")
          graph export sims'N'.png. replace
```



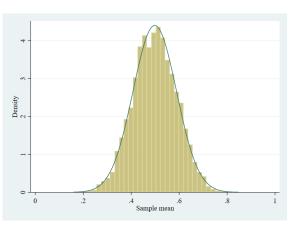
Distributions of $\hat{\mu} = \frac{1}{N} \sum_{i} X_{i}$ vs. $N(E[\hat{\mu}], Var(\hat{\mu}))$: $X_{i} \sim U(0,1)$, N = 5

```
clear all
      set seed 42
      set matsize 5000
      matrix sims=J(5000,1,.)
    □ foreach N in 1 2 5 10 (
          forval i=1/5000 (
                   clear
                   set obs 'N'
                   gen X = runiform()
                   summ X
19
                   matrix sims['j',1]=r(mean)
20
21
22
          clear
          hist sims, normal xtitle("Sample mean")
          graph export sims'N'.png. replace
```



Distributions of $\hat{\mu} = \frac{1}{N} \sum_i X_i$ vs. $N(E[\hat{\mu}], Var(\hat{\mu}))$: $X_i \sim U(0,1)$, N = 10

```
clear all
      set seed 42
      set matsize 5000
      matrix sims=J(5000,1,.)
    foreach N in 1 2 5 10 (
          forval i=1/5000 {
                   clear
                   set obs 'N'
                   gen X = runiform()
                   summ X
19
                   matrix sims['j',1]=r(mean)
20
21
22
          clear
          hist sims, normal xtitle("Sample mean")
          graph export sims'N'.png. replace
```





https://www.youtube.com/watch?v=EvHiee7gs9Y



Multivariate Versions

• The results we've discussed extend naturally to the multivariate case

Multivariate Versions

- The results we've discussed extend naturally to the multivariate case
- For a vector $\mathbf{X}_{\mathbf{N}} \in \mathbb{R}^k$, we say $\mathbf{X}_{\mathbf{N}} \to_p \mathbf{x}$ if each component of $\mathbf{X}_{\mathbf{N}}$ converges in probability to each component of \mathbf{x} .

Multivariate Versions

- The results we've discussed extend naturally to the multivariate case
- For a vector $\mathbf{X}_{\mathbf{N}} \in \mathbb{R}^k$, we say $\mathbf{X}_{\mathbf{N}} \to_p \mathbf{x}$ if each component of $\mathbf{X}_{\mathbf{N}}$ converges in probability to each component of \mathbf{x} .
- LLN: For $\hat{\mu}_N$, the sample mean of iid vectors $\mathbf{Y_1},...\mathbf{Y_N}$ with mean $\boldsymbol{\mu}$ and finite variance, $\hat{\boldsymbol{\mu}}_N \to_p \boldsymbol{\mu}$

Multivariate Versions

- The results we've discussed extend naturally to the multivariate case
- For a vector $\mathbf{X}_{\mathbf{N}} \in \mathbb{R}^k$, we say $\mathbf{X}_{\mathbf{N}} \to_p \mathbf{x}$ if each component of $\mathbf{X}_{\mathbf{N}}$ converges in probability to each component of \mathbf{x} .
- LLN: For $\hat{\mu}_N$, the sample mean of *iid* vectors $\mathbf{Y_1},...\mathbf{Y_N}$ with mean $\boldsymbol{\mu}$ and finite variance, $\hat{\boldsymbol{\mu}}_N \to_P \boldsymbol{\mu}$
- For a vector $\mathbf{X}_{\mathbf{N}} \in \mathbb{R}^k$, we say $\mathbf{X}_{\mathbf{N}} \to_d \mathbf{X}$ for \mathbf{X} continuously distributed if $F_{\mathbf{X}_{\mathbf{N}}}(\mathbf{x}) \to F_{\mathbf{X}}(\mathbf{x})$ for all $\mathbf{x} \in \mathbb{R}^k$.
- CLT: For $\hat{\mu}_N$, the sample mean of iid vectors $\mathbf{Y_1},...\mathbf{Y_N}$ with mean $\boldsymbol{\mu}$ and finite variance $\boldsymbol{\Sigma},\ \sqrt{N}(\hat{\mu}_N-\boldsymbol{\mu})\to_d \mathrm{N}(\mathbf{0},\boldsymbol{\Sigma})$

• Sometimes we are interested in functions of sample means (e.g., the *t*-statistic is a function of $\hat{\mu}$ and σ).

- Sometimes we are interested in functions of sample means (e.g., the t-statistic is a function of $\hat{\mu}$ and σ).
- The continuous mapping theorem (CMT) tells us about continuous functions of random variables that converge in distribution/probability

- Sometimes we are interested in functions of sample means (e.g., the t-statistic is a function of $\hat{\mu}$ and σ).
- The continuous mapping theorem (CMT) tells us about continuous functions of random variables that converge in distribution/probability
- Theorem: suppose $g(\cdot)$ is a continuous function If $X_N \to_p X$, then $g(X_N) \to_p g(X)$

- Sometimes we are interested in functions of sample means (e.g., the t-statistic is a function of $\hat{\mu}$ and σ).
- The continuous mapping theorem (CMT) tells us about continuous functions of random variables that converge in distribution/probability
- Theorem: suppose $g(\cdot)$ is a continuous function If $X_N \to_p X$, then $g(X_N) \to_p g(X)$ If $X_N \to_d X$, then $g(X_N) \to_d g(X)$

- Sometimes we are interested in functions of sample means (e.g., the t-statistic is a function of $\hat{\mu}$ and σ).
- The continuous mapping theorem (CMT) tells us about continuous functions of random variables that converge in distribution/probability
- Theorem: suppose $g(\cdot)$ is a continuous function

If
$$X_N \to_p X$$
, then $g(X_N) \to_p g(X)$

If
$$X_N \to_d X$$
, then $g(X_N) \to_d g(X)$

Multivariate versions here too: If $X_N \to_p X$, then $g(X_N) \to_p g(X)$ and if $X_N \to_d X$, then $g(X_N) \to_d g(X)$

 One useful application of the CMT is to show convergence in probability of the sample variance

- One useful application of the CMT is to show convergence in probability of the sample variance
- Let $\hat{\sigma}^2 = \frac{1}{N} \sum_{i=1}^{N} (Y_i \hat{\mu})^2$ be the sample variance of Y_i .

- One useful application of the CMT is to show convergence in probability of the sample variance
- Let $\hat{\sigma}^2 = \frac{1}{N} \sum_{i=1}^{N} (Y_i \hat{\mu})^2$ be the sample variance of Y_i .
- Claim: if $Y_1,...,Y_N$ are *iid* and $Var(Y_i^2)$ is finite, then $\hat{\sigma}^2 \rightarrow_p \sigma^2 = Var(Y_i)$.

- One useful application of the CMT is to show convergence in probability of the sample variance
- Let $\hat{\sigma}^2 = \frac{1}{N} \sum_{i=1}^{N} (Y_i \hat{\mu})^2$ be the sample variance of Y_i .
- Claim: if $Y_1,...,Y_N$ are *iid* and $Var(Y_i^2)$ is finite, then $\hat{\sigma}^2 \rightarrow_p \sigma^2 = Var(Y_i)$.
- Proof: We can write the sample variance as $\hat{\sigma}^2 = \frac{1}{N} \sum_{i=1}^N Y_i^2 \hat{\mu}^2$.

- One useful application of the CMT is to show convergence in probability of the sample variance
- Let $\hat{\sigma}^2 = \frac{1}{N} \sum_{i=1}^{N} (Y_i \hat{\mu})^2$ be the sample variance of Y_i .
- Claim: if $Y_1,...,Y_N$ are *iid* and $Var(Y_i^2)$ is finite, then $\hat{\sigma}^2 \rightarrow_p \sigma^2 = Var(Y_i)$.
- Proof: We can write the sample variance as $\hat{\sigma}^2 = \frac{1}{N} \sum_{i=1}^N Y_i^2 \hat{\mu}^2$. First term: by the LLN, $\frac{1}{N} \sum_{i=1}^N Y_i^2 \rightarrow_p E[Y_i^2]$.

- One useful application of the CMT is to show convergence in probability of the sample variance
- Let $\hat{\sigma}^2 = \frac{1}{N} \sum_{i=1}^{N} (Y_i \hat{\mu})^2$ be the sample variance of Y_i .
- Claim: if $Y_1, ..., Y_N$ are *iid* and $Var(Y_i^2)$ is finite, then $\hat{\sigma}^2 \rightarrow_p \sigma^2 = Var(Y_i)$.
- Proof: We can write the sample variance as $\hat{\sigma}^2 = \frac{1}{N} \sum_{i=1}^N Y_i^2 \hat{\mu}^2$. First term: by the LLN, $\frac{1}{N} \sum_{i=1}^N Y_i^2 \to_p E[Y_i^2]$. Second term: by the LLN, $\hat{\mu} \to_p \mu = E[Y_i]$. Thus, by the CMT, $\hat{\mu}^2 \to_p E[Y_i]^2$.

- One useful application of the CMT is to show convergence in probability of the sample variance
- Let $\hat{\sigma}^2 = \frac{1}{N} \sum_{i=1}^{N} (Y_i \hat{\mu})^2$ be the sample variance of Y_i .
- Claim: if $Y_1,...,Y_N$ are *iid* and $Var(Y_i^2)$ is finite, then $\hat{\sigma}^2 \rightarrow_p \sigma^2 = Var(Y_i)$.
- Proof:

We can write the sample variance as $\hat{\sigma}^2 = \frac{1}{N} \sum_{i=1}^{N} Y_i^2 - \hat{\mu}^2$.

First term: by the LLN, $\frac{1}{N}\sum_{i=1}^{N}Y_i^2 \rightarrow_p E[Y_i^2]$.

Second term: by the LLN, $\hat{\mu} \to_p \mu = E[Y_i]$. Thus, by the CMT, $\hat{\mu}^2 \to_p E[Y_i]^2$.

Thus, by the CMT again, $\frac{1}{N}\sum_{i=1}^{N}Y_i^2 - \hat{\mu}^2 \rightarrow_p E[Y_i^2] - E[Y_i]^2 = \sigma^2$.

• **Slutsky's lemma** (sometimes Slutsky's theorem) summarizes a few special cases of the CMT that are very useful.

- Slutsky's lemma (sometimes Slutsky's theorem) summarizes a few special cases of the CMT that are very useful.
- Suppose that $X_N \to_p c$ for a constant c, and $Y_N \to_d Y$. Then:
- $\bullet \ X_N + Y_N \to_d c + Y.$

- Slutsky's lemma (sometimes Slutsky's theorem) summarizes a few special cases of the CMT that are very useful.
- Suppose that $X_N \to_p c$ for a constant c, and $Y_N \to_d Y$. Then:
- $X_N + Y_N \rightarrow_d c + Y$.
- $X_n Y_n \rightarrow_d cY$.

- Slutsky's lemma (sometimes Slutsky's theorem) summarizes a few special cases of the CMT that are very useful.
- Suppose that $X_N \to_p c$ for a constant c, and $Y_N \to_d Y$. Then:
- $X_N + Y_N \rightarrow_d c + Y$.
- $X_n Y_n \rightarrow_d cY$.
- If $c \neq 0$, then $Y_n/X_n \rightarrow_d Y/c$.

- Slutsky's lemma (sometimes Slutsky's theorem) summarizes a few special cases of the CMT that are very useful.
- Suppose that $X_N \to_p c$ for a constant c, and $Y_N \to_d Y$. Then:
- $X_N + Y_N \rightarrow_d c + Y$.
- $X_n Y_n \rightarrow_d cY$.
- If $c \neq 0$, then $Y_n/X_n \rightarrow_d Y/c$.
- Analogous versions apply for vector-valued random variables.

• Recall that when $Y_i \sim N(\mu, \sigma^2)$, we showed that the *t*-statistic $\hat{t} = \frac{\hat{\mu} - \mu_0}{\sigma_0 / \sqrt{n}} \sim N(0, 1)$ under $H_0: \mu = \mu_0$.

- Recall that when $Y_i \sim N(\mu, \sigma^2)$, we showed that the *t*-statistic $\hat{t} = \frac{\hat{\mu} \mu_0}{\sigma / \sqrt{n}} \sim N(0, 1)$ under $H_0 : \mu = \mu_0$.
- Thus, when $Y_i \sim N(\mu, \sigma^2)$, we had that $Pr(|\hat{t}| > 1.96) = 0.05$ under the null.

- Recall that when $Y_i \sim \mathrm{N}(\mu, \sigma^2)$, we showed that the t-statistic $\hat{t} = \frac{\hat{\mu} \mu_0}{\sigma/\sqrt{n}} \sim \mathrm{N}(0,1)$ under $H_0: \mu = \mu_0$.
- Thus, when $Y_i \sim N(\mu, \sigma^2)$, we had that $Pr(|\hat{t}| > 1.96) = 0.05$ under the null.
- Now, suppose that Y_i is not normally distributed and we don't know its variance.

- Recall that when $Y_i \sim \mathrm{N}(\mu, \sigma^2)$, we showed that the t-statistic $\hat{t} = \frac{\hat{\mu} \mu_0}{\sigma/\sqrt{n}} \sim \mathrm{N}(0,1)$ under $H_0: \mu = \mu_0$.
- Thus, when $Y_i \sim N(\mu, \sigma^2)$, we had that $Pr(|\hat{t}| > 1.96) = 0.05$ under the null.
- Now, suppose that Y_i is not normally distributed and we don't know its variance.
- By CLT, $\sqrt{N}(\hat{\mu} \mu_0) \rightarrow_d N(0, \sigma^2)$. By CMT and LLN (as shown above), $\hat{\sigma} \rightarrow_P \sigma$.

- Recall that when $Y_i \sim \mathrm{N}(\mu, \sigma^2)$, we showed that the t-statistic $\hat{t} = \frac{\hat{\mu} \mu_0}{\sigma/\sqrt{n}} \sim \mathrm{N}(0,1)$ under $H_0: \mu = \mu_0$.
- Thus, when $Y_i \sim \mathrm{N}(\mu, \sigma^2)$, we had that $Pr(|\hat{t}| > 1.96) = 0.05$ under the null.
- Now, suppose that Y_i is not normally distributed and we don't know its variance.
- By CLT, $\sqrt{N}(\hat{\mu} \mu_0) \rightarrow_d N(0, \sigma^2)$. By CMT and LLN (as shown above), $\hat{\sigma} \rightarrow_P \sigma$.
- Thus, by Slutsky's lemma, $\hat{t} = \frac{\hat{\mu} \mu_0}{\hat{\sigma}/\sqrt{n}} \rightarrow_d N(0,1)$.

- Recall that when $Y_i \sim N(\mu, \sigma^2)$, we showed that the t-statistic $\hat{t} = \frac{\hat{\mu} \mu_0}{\sigma/\sqrt{n}} \sim N(0, 1)$ under $H_0: \mu = \mu_0$.
- Thus, when $Y_i \sim \mathrm{N}(\mu, \sigma^2)$, we had that $Pr(|\hat{t}| > 1.96) = 0.05$ under the null.
- Now, suppose that Y_i is not normally distributed and we don't know its variance.
- By CLT, $\sqrt{N}(\hat{\mu} \mu_0) \rightarrow_d N(0, \sigma^2)$. By CMT and LLN (as shown above), $\hat{\sigma} \rightarrow_{P} \sigma$.
- Thus, by Slutsky's lemma, $\hat{t} = \frac{\hat{\mu} \mu_0}{\hat{\sigma}/\sqrt{n}} \rightarrow_d N(0,1)$.
- Hence, asymptotically $Pr(|\hat{t}| > 1.96) \rightarrow 0.05$, even though Y_i is not normal and $\hat{\sigma}$ is estimated! We can hypothesis test just like before.

Asymptotic Confidence Intervals

• Similarly, when Y_i was normal w/ σ known, we showed the confidence interval $\hat{\mu} \pm 1.96 \sigma/\sqrt{N}$ contained the true μ 95% of the time

Asymptotic Confidence Intervals

- Similarly, when Y_i was normal w/ σ known, we showed the confidence interval $\hat{\mu} \pm 1.96 \sigma/\sqrt{N}$ contained the true μ 95% of the time
- Analogously, when Y_i is non-normal with unknown variance, $\hat{\mu} \pm 1.96 \hat{\sigma}/\sqrt{N}$ contains the true μ with probability approaching 95% as N grows large.

Outline

- 1. Overview ✓
- 2. LLN, CLT, and CMT \checkmark
- 3. Putting Asymptotics into Practice

Example – Oregon Health Insurance Experiment

In 2008, a group of uninsured low-income adults in Oregon was selected by lottery to be given the chance to apply for Medicaid. This lottery provides an opportunity to gauge the effects of expanding access to public health insurance on the health care use, financial strain, and health of low-income adults using a randomized controlled design. In the year after random assignment, the treatment group selected by the lottery was about 25 percentage points more likely to have insurance than the control group that was not selected. We find that in this first year, the treatment group had substantively and statistically significantly higher health care utilization (including primary and preventive care as well as hospitalizations), lower out-of-pocket medical expenditures and medical debt (including fewer bills sent to collection), and better self-reported physical and mental health than the control group. *JEL* Codes: H51, H75, I1.

	Control Group	Treated Group
Mean	0.329	0.306
SD	0.470	0.461
N	10426	13315

	Control Group	Treated Group
Mean	0.329	0.306
SD	0.470	0.461
N	10426	13315

• Say we want a CI for the population mean in the control group

	Control Group	Treated Group
Mean	0.329	0.306
SD	0.470	0.461
N	10426	13315

- Say we want a CI for the population mean in the control group
- We have

$$\hat{\mu} \pm 1.96 \times \hat{\sigma}/\sqrt{\textit{N}} =$$

	Control Group	Treated Group
Mean	0.329	0.306
SD	0.470	0.461
N	10426	13315

- Say we want a CI for the population mean in the control group
- We have

$$\hat{\mu} \pm 1.96 \times \hat{\sigma}/\sqrt{N} = 0.329 \pm 1.96 \times 0.470/\sqrt{10426} =$$

	Control Group	Treated Group
Mean	0.329	0.306
SD	0.470	0.461
N	10426	13315

- Say we want a CI for the population mean in the control group
- We have

$$\hat{\mu} \pm 1.96 \times \hat{\sigma}/\sqrt{\textit{N}} = 0.329 \pm 1.96 \times 0.470/\sqrt{10426} = [0.319, 0.338]$$

	Control Group	Treated Group
Mean	0.329	0.306
SD	0.470	0.461
N	10426	13315

- Say we want a CI for the population mean in the control group
- We have

$$\hat{\mu} \pm 1.96 \times \hat{\sigma}/\sqrt{\textit{N}} = 0.329 \pm 1.96 \times 0.470/\sqrt{10426} = [0.319, 0.338]$$

• What about for the treated group?

Sample Means for Depression Outcome

	Control Group	Treated Group
Mean	0.329	0.306
SD	0.470	0.461
N	10426	13315

- Say we want a CI for the population mean in the control group
- We have

$$\hat{\mu} \pm 1.96 \times \hat{\sigma}/\sqrt{\textit{N}} = 0.329 \pm 1.96 \times 0.470/\sqrt{10426} = [0.319, 0.338]$$

• What about for the treated group?

$$\hat{\mu} \pm 1.96 \times \hat{\sigma}/\sqrt{N} =$$

Sample Means for Depression Outcome

	Control Group	Treated Group
Mean	0.329	0.306
SD	0.470	0.461
N	10426	13315

- Say we want a CI for the population mean in the control group
- We have

$$\hat{\mu} \pm 1.96 \times \hat{\sigma}/\sqrt{\textit{N}} = 0.329 \pm 1.96 \times 0.470/\sqrt{10426} = [0.319, 0.338]$$

• What about for the treated group?

$$\hat{\mu} \pm 1.96 \times \hat{\sigma}/\sqrt{N} = 0.306 \pm 1.96 \times 0.461/\sqrt{13315} =$$

Sample Means for Depression Outcome

	Control Group	Treated Group
Mean	0.329	0.306
SD	0.470	0.461
N	10426	13315

- Say we want a CI for the population mean in the control group
- We have

$$\hat{\mu} \pm 1.96 \times \hat{\sigma}/\sqrt{\textit{N}} = 0.329 \pm 1.96 \times 0.470/\sqrt{10426} = [0.319, 0.338]$$

• What about for the treated group?

$$\hat{\mu} \pm 1.96 \times \hat{\sigma}/\sqrt{N} = 0.306 \pm 1.96 \times 0.461/\sqrt{13315} = [0.298, 0.313]$$

Cls for Treatment Effects in Experiments

 We showed previously that in an experiment, the average treatment effect is given by

$$\tau = E[Y_i(1) - Y_i(0)] = E[Y_i|D_i = 1] - E[Y_i|D_i = 0].$$

i.e. the difference in population means between the treated and control groups.

Cls for Treatment Effects in Experiments

 We showed previously that in an experiment, the average treatment effect is given by

$$\tau = E[Y_i(1) - Y_i(0)] = E[Y_i|D_i = 1] - E[Y_i|D_i = 0].$$

i.e. the difference in population means between the treated and control groups.

How can we form confidence intervals (or test hypotheses) about the treatment effect?

• Let $\bar{Y}_1 = \frac{1}{N_1} \sum_{i:D_i=1} Y_i$ be the sample mean for the treated group. Let $\bar{Y}_0 = \frac{1}{N_0} \sum_{i:D_i=0} Y_i$ be the sample mean for the control group.

- Let $\bar{Y}_1 = \frac{1}{N_1} \sum_{i:D_i=1} Y_i$ be the sample mean for the treated group. Let $\bar{Y}_0 = \frac{1}{N_0} \sum_{i:D_i=0} Y_i$ be the sample mean for the control group.
- Since \bar{Y}_1, \bar{Y}_0 are each sample means, we have that

- Let $\bar{Y}_1 = \frac{1}{N_1} \sum_{i:D_i=1} Y_i$ be the sample mean for the treated group. Let $\bar{Y}_0 = \frac{1}{N_0} \sum_{i:D_i=0} Y_i$ be the sample mean for the control group.
- Since $\overline{Y}_1, \overline{Y}_0$ are each sample means, we have that

$$E[ar{Y}_1] = \mu_1, \qquad Var(ar{Y}_1) = \sigma_1^2/N_1$$

 $E[ar{Y}_0] = \mu_0, \qquad Var(ar{Y}_0) = \sigma_0^2/N_0$

where $\mu_d = E[Y_i \mid D_i = d]$ and $\sigma_d^2 = Var(Y_i \mid D_i = d)$.

• Let $\hat{ au} = ar{Y}_1 - ar{Y}_0$. It follows that $E[\hat{ au}] =$

- Let $\bar{Y}_1 = \frac{1}{N_1} \sum_{i:D_i=1} Y_i$ be the sample mean for the treated group. Let $\bar{Y}_0 = \frac{1}{N_0} \sum_{i:D_i=0} Y_i$ be the sample mean for the control group.
- Since $\overline{Y}_1, \overline{Y}_0$ are each sample means, we have that

$$E[\bar{Y}_1] = \mu_1, \qquad Var(\bar{Y}_1) = \sigma_1^2/N_1 \ E[\bar{Y}_0] = \mu_0, \qquad Var(\bar{Y}_0) = \sigma_0^2/N_0$$

where $\mu_d = E[Y_i \mid D_i = d]$ and $\sigma_d^2 = Var(Y_i \mid D_i = d)$.

• Let $\hat{ au}=ar{Y}_1-ar{Y}_0$. It follows that $E[\hat{ au}]=\mu_1-\mu_0= au$ and $Var(\hat{ au})=$

- Let $\bar{Y}_1 = \frac{1}{N_1} \sum_{i:D_i=1} Y_i$ be the sample mean for the treated group. Let $\bar{Y}_0 = \frac{1}{N_0} \sum_{i:D_i=0} Y_i$ be the sample mean for the control group.
- Since $\overline{Y}_1, \overline{Y}_0$ are each sample means, we have that

$$E[\bar{Y}_1] = \mu_1, \qquad Var(\bar{Y}_1) = \sigma_1^2/N_1 \ E[\bar{Y}_0] = \mu_0, \qquad Var(\bar{Y}_0) = \sigma_0^2/N_0$$

where $\mu_d = E[Y_i \mid D_i = d]$ and $\sigma_d^2 = Var(Y_i \mid D_i = d)$.

• Let $\hat{ au}=ar{Y}_1-ar{Y}_0$. It follows that $E[\hat{ au}]=\mu_1-\mu_0= au$ and $Var(\hat{ au})=\sigma_1^2/N_1+\sigma_0^2/N_0+2Cov(ar{Y}_1,ar{Y}_0)$

- Let $\bar{Y}_1 = \frac{1}{N_1} \sum_{i:D_i=1} Y_i$ be the sample mean for the treated group. Let $\bar{Y}_0 = \frac{1}{N_0} \sum_{i:D_i=0} Y_i$ be the sample mean for the control group.
- Since $\overline{Y}_1, \overline{Y}_0$ are each sample means, we have that

$$\begin{split} E[\bar{Y}_1] &= \mu_1, & \textit{Var}(\bar{Y}_1) = \sigma_1^2/\textit{N}_1 \\ E[\bar{Y}_0] &= \mu_0, & \textit{Var}(\bar{Y}_0) = \sigma_0^2/\textit{N}_0 \end{split}$$

where $\mu_d = E[Y_i \mid D_i = d]$ and $\sigma_d^2 = Var(Y_i \mid D_i = d)$.

• Let $\hat{\tau} = \bar{Y}_1 - \bar{Y}_0$. It follows that $E[\hat{\tau}] = \mu_1 - \mu_0 = \tau$ and

$$egin{aligned} extstyle extstyle Var(\hat{ au}) &= \sigma_1^2/N_1 + \sigma_0^2/N_0 + 2 extstyle Cov(ar{Y}_1, ar{Y}_0) \ &= \sigma_1^2/N_1 + \sigma_0^2/N_0 \end{aligned}$$

where the fact that the samples are independent implies that $Cov(\bar{Y}_1, \bar{Y}_0) = 0$.

• We just showed that in an experiment

$$E[\hat{ au}] = au$$
 and $Var(\hat{ au}) = \sigma_1^2/N_1 + \sigma_0^2/N_0$

where $\hat{\tau}$ is the difference in sample means btwn the treated/control groups

• If we knew that $\hat{\tau}$ was normally distributed (and we knew σ_1, σ_0), then we could construct CIs of the form

• We just showed that in an experiment

$$E[\hat{ au}] = au$$
 and $Var(\hat{ au}) = \sigma_1^2/N_1 + \sigma_0^2/N_0$

where $\hat{ au}$ is the difference in sample means between the treated/control groups

• If we knew that $\hat{\tau}$ was normally distributed (and we knew σ_1, σ_0), then we could construct CIs of the form

$$\hat{ au} \pm 1.96 \sqrt{\sigma_1^2/N_1 + \sigma_0^2/N_0}$$

• We just showed that in an experiment

$$E[\hat{ au}] = au$$
 and $Var(\hat{ au}) = \sigma_1^2/N_1 + \sigma_0^2/N_0$

where $\hat{ au}$ is the difference in sample means between the treated/control groups

• If we knew that $\hat{\tau}$ was normally distributed (and we knew σ_1, σ_0), then we could construct CIs of the form

$$\hat{\tau} \pm 1.96 \sqrt{\sigma_1^2/N_1 + \sigma_0^2/N_0}$$

• As with sample means, we do not know that $\hat{\tau}$ is normally distributed, but we can show that for N large, it is approximately normally distributed, which allows us to use CIs of the form

$$\hat{ au} \pm 1.96 \sqrt{\hat{\sigma}_1^2/N_1 + \hat{\sigma}_0^2/N_0},$$

for $\hat{\sigma}_d^2$ the estimated conditional variance.

ullet By the CLT, we have that $\sqrt{N_1}(ar{Y}_1-\mu_1)
ightarrow_d$

• By the CLT, we have that $\sqrt{N_1}(\bar{Y}_1 - \mu_1) \rightarrow_d N(0, \sigma_1^2)$.

- By the CLT, we have that $\sqrt{N_1}(\bar{Y}_1 \mu_1) \rightarrow_d N(0, \sigma_1^2)$.
- Note that $\frac{N_1}{N} = \frac{1}{N} \sum_i D_i \rightarrow_p$

- ullet By the CLT, we have that $\sqrt{N_1}(ar{Y}_1-\mu_1)
 ightarrow_d N(0,\sigma_1^2).$
- Note that $\frac{N_1}{N} = \frac{1}{N} \sum_i D_i \rightarrow_p E[D_i]$ by the LLN.

- By the CLT, we have that $\sqrt{N_1}(\bar{Y}_1 \mu_1) \rightarrow_d N(0, \sigma_1^2)$.
- Note that $\frac{N_1}{N} = \frac{1}{N} \sum_i D_i \rightarrow_p E[D_i]$ by the LLN.
- Hence, applying the continuous mapping theorem,

$$\sqrt{N}(\bar{Y}_1 - E[Y_i(1)]) =$$

- By the CLT, we have that $\sqrt{N_1}(\bar{Y}_1 \mu_1) \rightarrow_d N(0, \sigma_1^2)$.
- Note that $\frac{N_1}{N} = \frac{1}{N} \sum_i D_i \rightarrow_p E[D_i]$ by the LLN.
- Hence, applying the continuous mapping theorem,

$$\begin{split} \sqrt{N}(\bar{Y}_1 - E[Y_i(1)]) &= (1/\sqrt{N_1/N}) \cdot \sqrt{N_1}(\bar{Y}_1 - E[Y_i(1)]) \\ &\rightarrow_d (1/\sqrt{E[D_i]}) \cdot N(0, Var(Y_i(1))) \\ &= N\left(0, \frac{1}{E[D_i]} Var(Y_i(1))\right) \end{split}$$

- By the CLT, we have that $\sqrt{N_1}(\bar{Y}_1 \mu_1) \rightarrow_d N(0, \sigma_1^2)$.
- Note that $\frac{N_1}{N} = \frac{1}{N} \sum_i D_i \rightarrow_p E[D_i]$ by the LLN.
- Hence, applying the continuous mapping theorem,

$$\begin{split} \sqrt{N}(\bar{Y}_1 - E[Y_i(1)]) &= (1/\sqrt{N_1/N}) \cdot \sqrt{N_1}(\bar{Y}_1 - E[Y_i(1)]) \\ &\rightarrow_d (1/\sqrt{E[D_i]}) \cdot N(0, Var(Y_i(1))) \\ &= N\left(0, \frac{1}{E[D_i]} Var(Y_i(1))\right) \end{split}$$

• Applying similar steps for \bar{Y}_0 , we obtain that

- By the CLT, we have that $\sqrt{N_1}(\bar{Y}_1 \mu_1) \rightarrow_d N(0, \sigma_1^2)$.
- Note that $\frac{N_1}{N} = \frac{1}{N} \sum_i D_i \rightarrow_p E[D_i]$ by the LLN.
- Hence, applying the continuous mapping theorem,

$$\begin{split} \sqrt{N}(\bar{Y}_1 - E[Y_i(1)]) &= (1/\sqrt{N_1/N}) \cdot \sqrt{N_1}(\bar{Y}_1 - E[Y_i(1)]) \\ &\rightarrow_d (1/\sqrt{E[D_i]}) \cdot \mathrm{N}(0, Var(Y_i(1))) \\ &= \mathrm{N}\left(0, \frac{1}{E[D_i]} Var(Y_i(1))\right) \end{split}$$

• Applying similar steps for \overline{Y}_0 , we obtain that

$$\sqrt{N} \begin{pmatrix} \bar{Y}_1 - E[Y_i(1)] \\ \bar{Y}_0 - E[Y_i(0)] \end{pmatrix} \rightarrow_d$$

- By the CLT, we have that $\sqrt{N_1}(\bar{Y}_1 \mu_1) \rightarrow_d N(0, \sigma_1^2)$.
- Note that $\frac{N_1}{N} = \frac{1}{N} \sum_i D_i \rightarrow_p E[D_i]$ by the LLN.
- Hence, applying the continuous mapping theorem,

$$\sqrt{N}(\bar{Y}_1 - E[Y_i(1)]) = (1/\sqrt{N_1/N}) \cdot \sqrt{N_1}(\bar{Y}_1 - E[Y_i(1)])$$

$$\rightarrow_d (1/\sqrt{E[D_i]}) \cdot N(0, Var(Y_i(1)))$$

$$= N\left(0, \frac{1}{E[D_i]} Var(Y_i(1))\right)$$

• Applying similar steps for \overline{Y}_0 , we obtain that

$$\sqrt{N} \begin{pmatrix} \bar{Y}_1 - E[Y_i(1)] \\ \bar{Y}_0 - E[Y_i(0)] \end{pmatrix} \rightarrow_d N \begin{pmatrix} 0, \begin{pmatrix} \frac{1}{E[D_i]} Var(Y_i(1)) & 0 \\ 0 & \frac{1}{1 - E[D_i]} Var(Y_i(0)) \end{pmatrix} \end{pmatrix}$$

Hypothesis Testing for Experiments (continued)

We just showed that

$$\sqrt{N} \begin{pmatrix} \bar{Y}_1 - E[Y_i(1)] \\ \bar{Y}_0 - E[Y_i(0)] \end{pmatrix} \rightarrow_d N \begin{pmatrix} 0, \begin{pmatrix} \frac{1}{E[D_i]} Var(Y_i(1)) & 0 \\ 0 & \frac{1}{1 - E[D_i]} Var(Y_i(0)) \end{pmatrix} \end{pmatrix}$$

Hypothesis Testing for Experiments (continued)

We just showed that

$$\sqrt{N} \left(\begin{array}{c} \bar{Y}_1 - E[Y_i(1)] \\ \bar{Y}_0 - E[Y_i(0)] \end{array} \right) \rightarrow_d N \left(0, \left(\begin{array}{cc} \frac{1}{E[D_i]} Var(Y_i(1)) & 0 \\ 0 & \frac{1}{1 - E[D_i]} Var(Y_i(0)) \end{array} \right) \right)$$

Applying the CMT,

$$\begin{split} \sqrt{N}(\bar{Y}_1-\bar{Y}_0-E[Y_i(1)-Y_i(0)])\to_d N(0,\sigma^2), \end{split}$$
 where $\sigma^2=\frac{1}{E[D_i]}Var(Y_i(1))+\frac{1}{E[1-D_i]}Var(Y_i(0))$

Hypothesis Testing for Experiments (continued)

We just showed that

$$\sqrt{N} \begin{pmatrix} \bar{Y}_1 - E[Y_i(1)] \\ \bar{Y}_0 - E[Y_i(0)] \end{pmatrix} \rightarrow_d N \begin{pmatrix} 0, \begin{pmatrix} \frac{1}{E[D_i]} Var(Y_i(1)) & 0 \\ 0 & \frac{1}{1 - E[D_i]} Var(Y_i(0)) \end{pmatrix} \end{pmatrix}$$

Applying the CMT,

$$\sqrt{N}(\bar{Y}_1-\bar{Y}_0-E[Y_i(1)-Y_i(0)])\rightarrow_d N(0,\sigma^2),$$
 where $\sigma^2=\frac{1}{F[D_i]}Var(Y_i(1))+\frac{1}{F[1-D_i]}Var(Y_i(0))$

• We can thus form a 95% confidence interval for $\tau = E[Y_i(1) - Y_i(0)]$,

$$\bar{Y}_1 - \bar{Y}_0 \pm 1.96 \hat{\sigma} / \sqrt{N}$$

where $\hat{\sigma}^2 = \frac{N}{N_1} \hat{\sigma}_1^2 + \frac{N}{N_0} \hat{\sigma}_0^2$, where $\hat{\sigma}_d^2$ is the sample variance for treatment group $d \in \{0,1\}$

	Control Group	Treated Group
Mean	0.329	0.306
SD	0.470	0.461
N	10426	13315

	Control Group	Treated Group
Mean	0.329	0.306
SD	0.470	0.461
N	10426	13315

• Our point estimate of the treatment effect is

$$\hat{\tau} =$$

	Control Group	Treated Group
Mean	0.329	0.306
SD	0.470	0.461
N	10426	13315

• Our point estimate of the treatment effect is

$$\hat{\tau} = 0.306 - 0.329 = -0.023.$$

	Control Group	Treated Group
Mean	0.329	0.306
SD	0.470	0.461
N	10426	13315

- Our point estimate of the treatment effect is $\hat{\tau} = 0.306 0.329 = -0.023$.
- Our CI for the treatment effect is:

	Control Group	Treated Group
Mean	0.329	0.306
SD	0.470	0.461
N	10426	13315

- Our point estimate of the treatment effect is $\hat{\tau} = 0.306 0.329 = -0.023$.
- Our CI for the treatment effect is:

$$\hat{\tau} \pm 1.96 \times \sqrt{\frac{1}{N_1}\hat{\sigma}_1^2 + \frac{1}{N_0}\hat{\sigma}_0^2} =$$

	Control Group	Treated Group
Mean	0.329	0.306
SD	0.470	0.461
N	10426	13315

- Our point estimate of the treatment effect is $\hat{\tau} = 0.306 0.329 = -0.023$.
- Our CI for the treatment effect is:

$$\hat{\tau} \pm 1.96 \times \sqrt{\frac{1}{N_1}} \hat{\sigma}_1^2 + \frac{1}{N_0} \hat{\sigma}_0^2 =$$

$$-0.023 \pm 1.96 \times \sqrt{\frac{1}{13315}} 0.461^2 + \frac{1}{10426} 0.470^2$$
=

	Control Group	Treated Group
Mean	0.329	0.306
SD	0.470	0.461
N	10426	13315

- Our point estimate of the treatment effect is $\hat{\tau} = 0.306 0.329 = -0.023$.
- Our CI for the treatment effect is:

$$\hat{\tau} \pm 1.96 \times \sqrt{\frac{1}{N_1}} \hat{\sigma}_1^2 + \frac{1}{N_0} \hat{\sigma}_0^2 =$$

$$-0.023 \pm 1.96 \times \sqrt{\frac{1}{13315}} 0.461^2 + \frac{1}{10426} 0.470^2$$

$$= [-0.035, -0.001]$$

• Recall that under unconfoundedness, $D_i \perp \!\!\! \perp (Y_i(1), Y_i(0)) | X_i$, we have

$$\underbrace{E[Y_i(1) - Y_i(0)|X_i = x]}_{CATE(x)} = E[Y_i|D_i = 1, X_i = x] - E[Y_i|D_i = 0, X_i = x]$$

That is, within each value of X_i , it's as if we have an experiment.

• Recall that under unconfoundedness, $D_i \perp \!\!\! \perp (Y_i(1),Y_i(0))|X_i$, we have

$$\underbrace{E[Y_i(1) - Y_i(0)|X_i = x]}_{CATE(x)} = E[Y_i|D_i = 1, X_i = x] - E[Y_i|D_i = 0, X_i = x]$$

That is, within each value of X_i , it's as if we have an experiment.

By the same logic as for experiments, we have that

$$\sqrt{N_x(\bar{Y}_{1,x} - \bar{Y}_{0,x} - E[Y_i(1) - Y_i(0)|X_i = x])} \rightarrow_d N(0, \sigma_x^2),$$
 where $N_x = |i: X_i = x|$ and
$$\sigma_x^2 = \frac{1}{E[D_i|X_i = x]} Var(Y_i(1)|X_i = x) + \frac{1}{E[1 - D_i|X_i = x]} Var(Y_i(0)|X_i = x).$$

• Recall that under unconfoundedness, $D_i \perp \!\!\! \perp (Y_i(1),Y_i(0))|X_i$, we have

$$\underbrace{E[Y_i(1) - Y_i(0)|X_i = x]}_{CATE(x)} = E[Y_i|D_i = 1, X_i = x] - E[Y_i|D_i = 0, X_i = x]$$

That is, within each value of X_i , it's as if we have an experiment.

By the same logic as for experiments, we have that

$$\sqrt{N_x(\bar{Y}_{1,x} - \bar{Y}_{0,x} - E[Y_i(1) - Y_i(0)|X_i = x])} \rightarrow_d N(0, \sigma_x^2),$$
 where $N_x = |i: X_i = x|$ and
$$\sigma_x^2 = \frac{1}{E[D_i|X_i = x]} Var(Y_i(1)|X_i = x) + \frac{1}{E[1 - D_i|X_i = x]} Var(Y_i(0)|X_i = x).$$

• So we can also do hyptothesis testing on CATE(x) when N_x is large.

• Recall that under unconfoundedness, $D_i \perp \!\!\! \perp (Y_i(1), Y_i(0)) | X_i$, we have

$$\underbrace{E[Y_i(1) - Y_i(0)|X_i = x]}_{CATE(x)} = E[Y_i|D_i = 1, X_i = x] - E[Y_i|D_i = 0, X_i = x]$$

That is, within each value of X_i , it's as if we have an experiment.

By the same logic as for experiments, we have that

$$\sqrt{N_{x}(\bar{Y}_{1,x} - \bar{Y}_{0,x} - E[Y_{i}(1) - Y_{i}(0)|X_{i} = x])} \rightarrow_{d} N(0, \sigma_{x}^{2}),$$
where $N_{x} = |i: X_{i} = x|$ and
$$\sigma_{x}^{2} = \frac{1}{E[D_{i}|X_{i} = x]} Var(Y_{i}(1)|X_{i} = x) + \frac{1}{E[1 - D_{i}|X_{i} = x]} Var(Y_{i}(0)|X_{i} = x).$$

- So we can also do hyptothesis testing on CATE(x) when N_x is large.
- By averaging CATE(x), we can do hypothesis testing / form CIs for ATE.

- We've shown thus far how we can estimate CATE(x) when the number of observations with $X_i = x$ is large.
- This works great when X_i is binary (e.g. an indicator for college) or takes on a small number of discrete values (e.g. 50 states).

- We've shown thus far how we can estimate CATE(x) when the number of observations with $X_i = x$ is large.
- This works great when X_i is binary (e.g. an indicator for college) or takes on a small number of discrete values (e.g. 50 states).
- But what about when X_i is continuous?

- We've shown thus far how we can estimate CATE(x) when the number of observations with $X_i = x$ is large.
- This works great when X_i is binary (e.g. an indicator for college) or takes on a small number of discrete values (e.g. 50 states).
- But what about when X_i is continuous?
- For example, if X_i is income, then to estimate CATE(50,351), the theory we have says we need a large number of treated and control units both with income \$50,351. In most datasets, we won't have very many people with exactly this income.

- We've shown thus far how we can estimate CATE(x) when the number of observations with $X_i = x$ is large.
- This works great when X_i is binary (e.g. an indicator for college) or takes on a small number of discrete values (e.g. 50 states).
- But what about when X_i is continuous?
- For example, if X_i is income, then to estimate CATE(50,351), the theory we have says we need a large number of treated and control units both with income \$50,351. In most datasets, we won't have very many people with exactly this income.
- We thus need a different way of estimating conditional means when X_i is continuously distributed.

- We've shown thus far how we can estimate CATE(x) when the number of observations with $X_i = x$ is large.
- This works great when X_i is binary (e.g. an indicator for college) or takes on a small number of discrete values (e.g. 50 states).
- But what about when X_i is continuous?
- For example, if X_i is income, then to estimate CATE(50,351), the theory we have says we need a large number of treated and control units both with income \$50,351. In most datasets, we won't have very many people with exactly this income.
- We thus need a different way of estimating conditional means when X_i is continuously distributed.
- The next part of the course will focus on achieving this task using linear regression as an approximation to the CEF.