

Minutes 06/02/13

Strategy

- Cristina had a meeting with some of last year's groups and they don't seem to think Michael's idea from the last meeting will work. They suggest that the robot should either have an attack strategy or a defend strategy and not both.
- A team last year had a successful defensive robot but we will look to have an attack strategy.
- Try to keep the strategy plans as simple as possible. More complicated strategies may not always be useful.
- Cristina will have the planning structure and a few percepts and actions done in around 10 days.

Vision

- Sean's Orientation class is not currently working correctly but will be soon.
- Need to set the RGB values for the main pitch on AT level 3.
- Need to work out the pixel ratio and then be able to convert from pixels to centimetres.
- Once the orientation and RGB thresholds are set, the vision side of things for milestone 2 should be done.
- From then on, the vision team will work towards optimising the system.

Robot

- The robot needs to be made sturdier. Introducing a frame around the body to protect it.

Simulator

- Andrei has a simulator working but needs to get it working within the project itself and adapt it to the classes there.

Communications

- Finn is going to work on the code for the Bluetooth caching this weekend. It will be very specific to our control code.