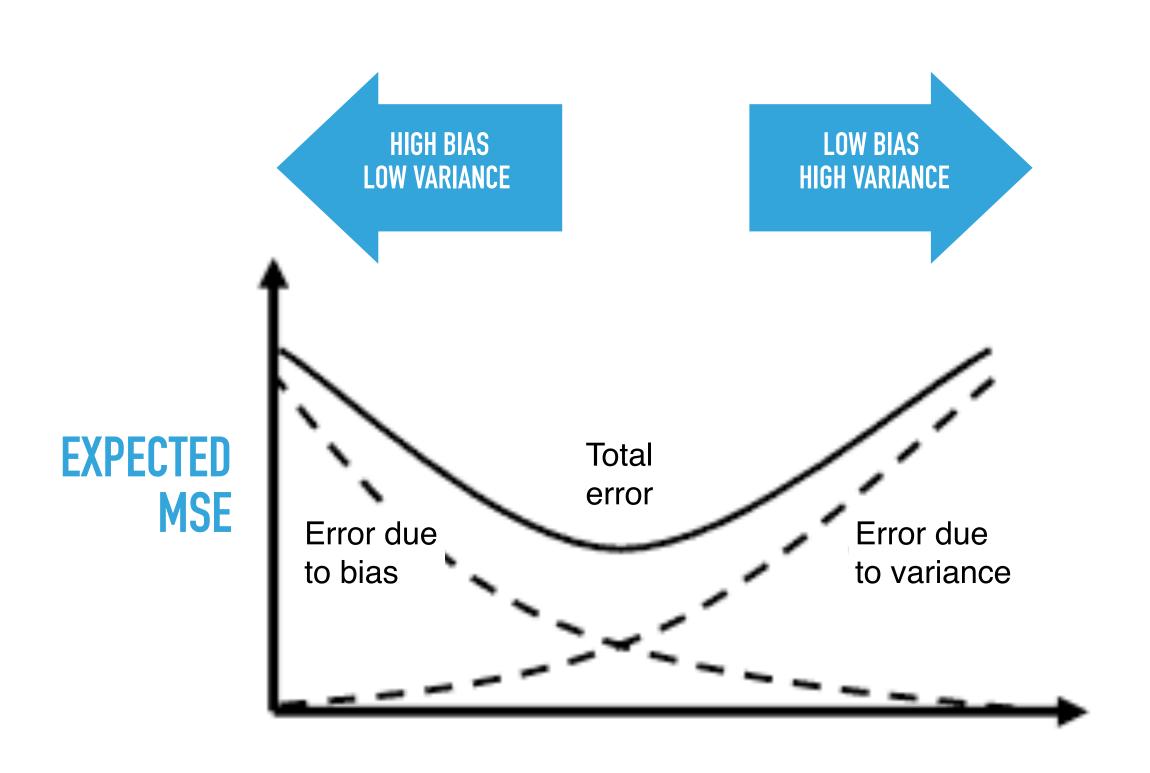
CS57300 PURDUE UNIVERSITY NOVEMBER 1, 2021

DATA MINING

ANNOUNCEMENTS

- Assignment 4 will be out today!
 - Due on November 14
 - > Start early! It's going to be more time consuming to train the models!

BIAS/VARIANCE TRADEOFF FOR LEARNING A SINGLE MODEL



Bias-variance tradeoff:

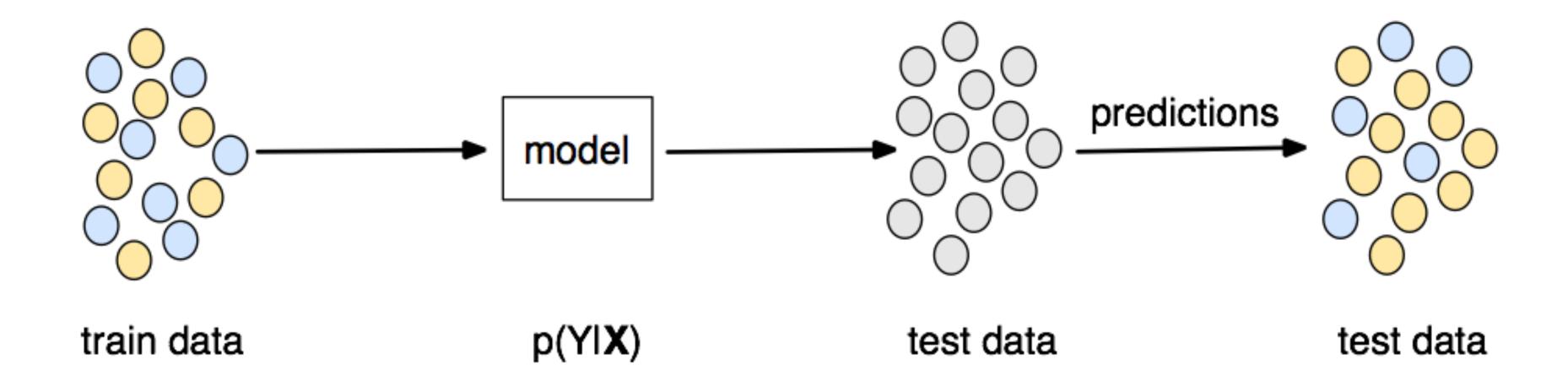
increasing the size of the model space can reduce bias of the learned model, but that also tends to increase variance...

and decreasing the model space tends to reduce variance but also increase bias

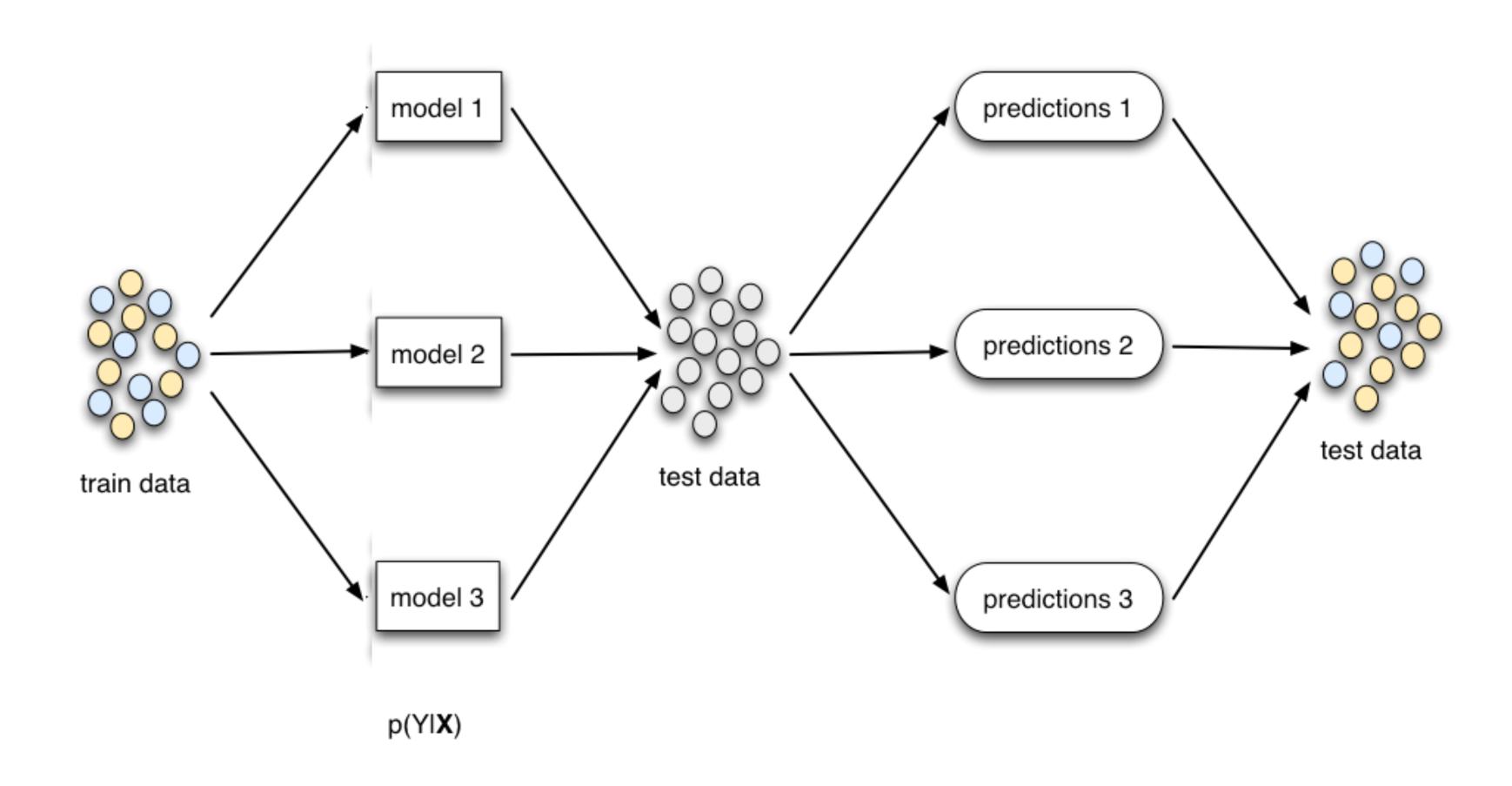
- Suppose there are N independent predictors $f_1(x;D), f_2(x;D), \dots, f_N(x;D)$
- The "blended" predictor is $f(x; D) = \frac{1}{N} \sum_{i=1}^{N} f_i(x; D)$
- At data point (x*, y*), say all individual prediction has a bias of b and a variance of σ², and we have f(x*) = E_D[f(x*,D)] = 1/N ∑_{i=1}^N f_i(x*)
 Bias of f(x*,D): f(x*) y* = 1/N ∑_{i=1}^N (f_i(x*) y*) = b
 Variance of f(x*,D): 1/N² ∑_{i=1}^N Var(f_i(x*,D)) = σ²/N

Variance decreases!

CONVENTIONAL CLASSIFICATION



ENSEMBLE CLASSIFICATION



BAGGING

- Is it possible to have multiple models of the same type?
- There is only one training data set, where do multiple models of the same type come from?
- ▶ Bagging: Bootstrap aggregating

BAGGING

- Given a training data set $D=\{(x_1,y_1),...,(x_N,y_N)\}$
- ▶ For m=1:M
 - Obtain a bootstrap sample D_m by drawing N instances
 with replacement from D

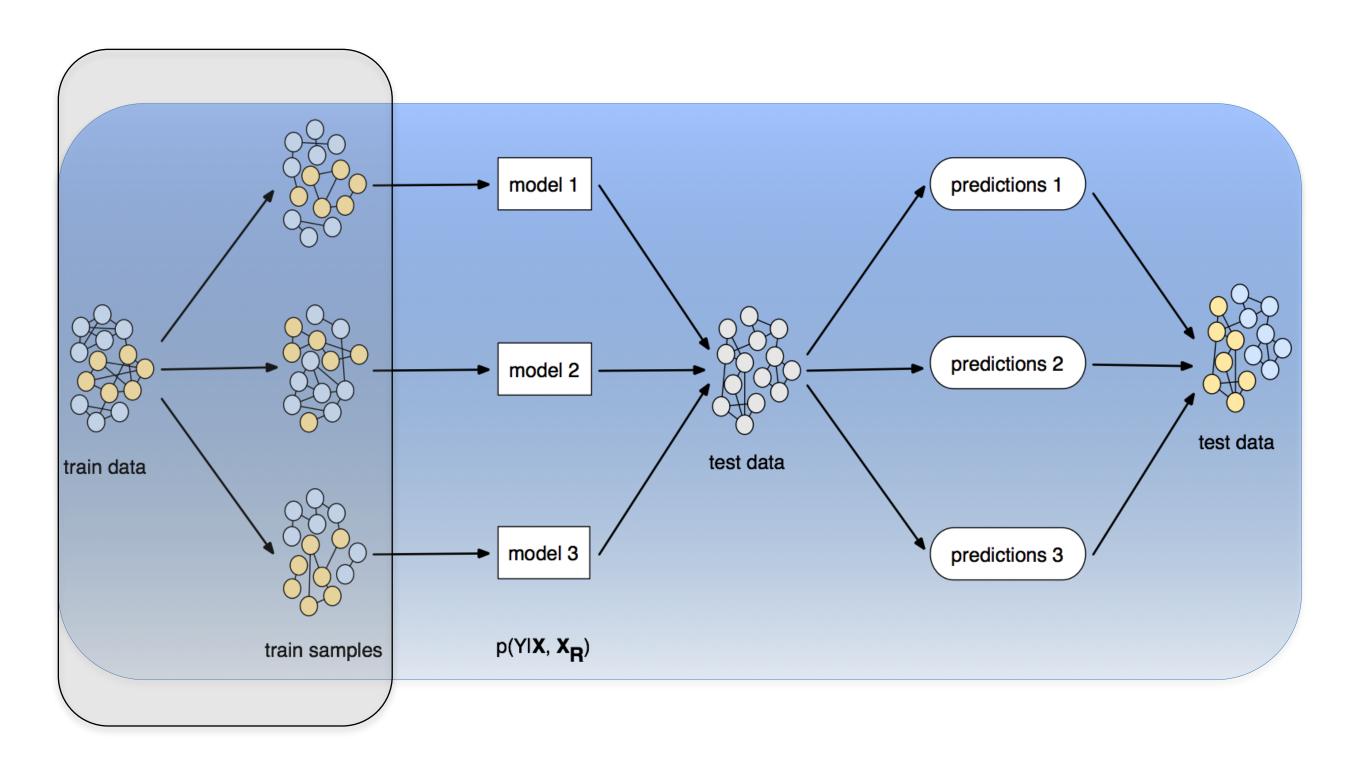


- Learn model M_m from D_m
- To classify test instance t, apply each model M_m to t and use majority predication or average prediction

BAGGING

- Main assumption
 - Combining many *unstable* predictors in an ensemble produces a *stable* predictor (i.e., reduces variance)
 - Unstable predictor: small changes in training data produces large changes in the model (e.g., fully-grown trees)
- Models have somewhat uncorrelated errors due to difference in training sets (each bootstrap sample has ~63% of D)
- Model space: non-parametric, can model any function if an appropriate base model is used

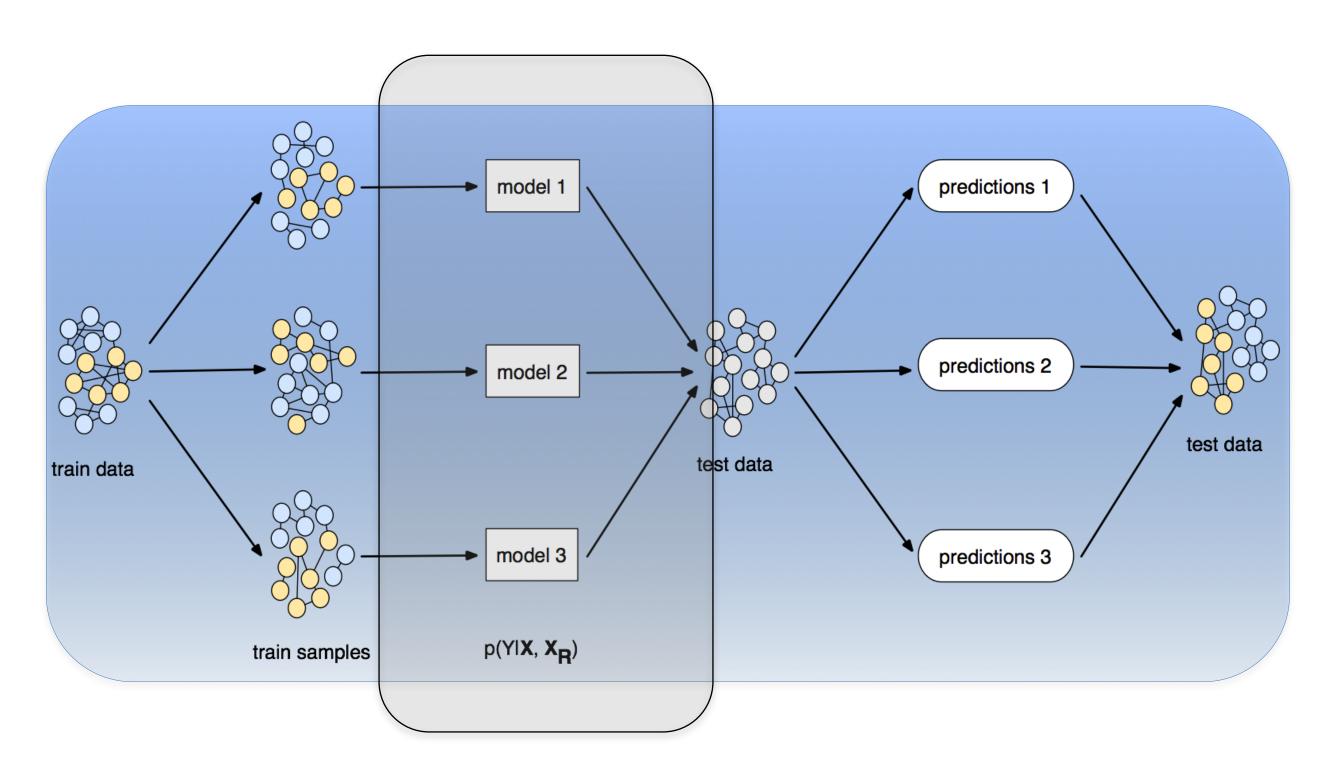
BAGGING



TREATMENT OF INPUT DATA

sample with replacement

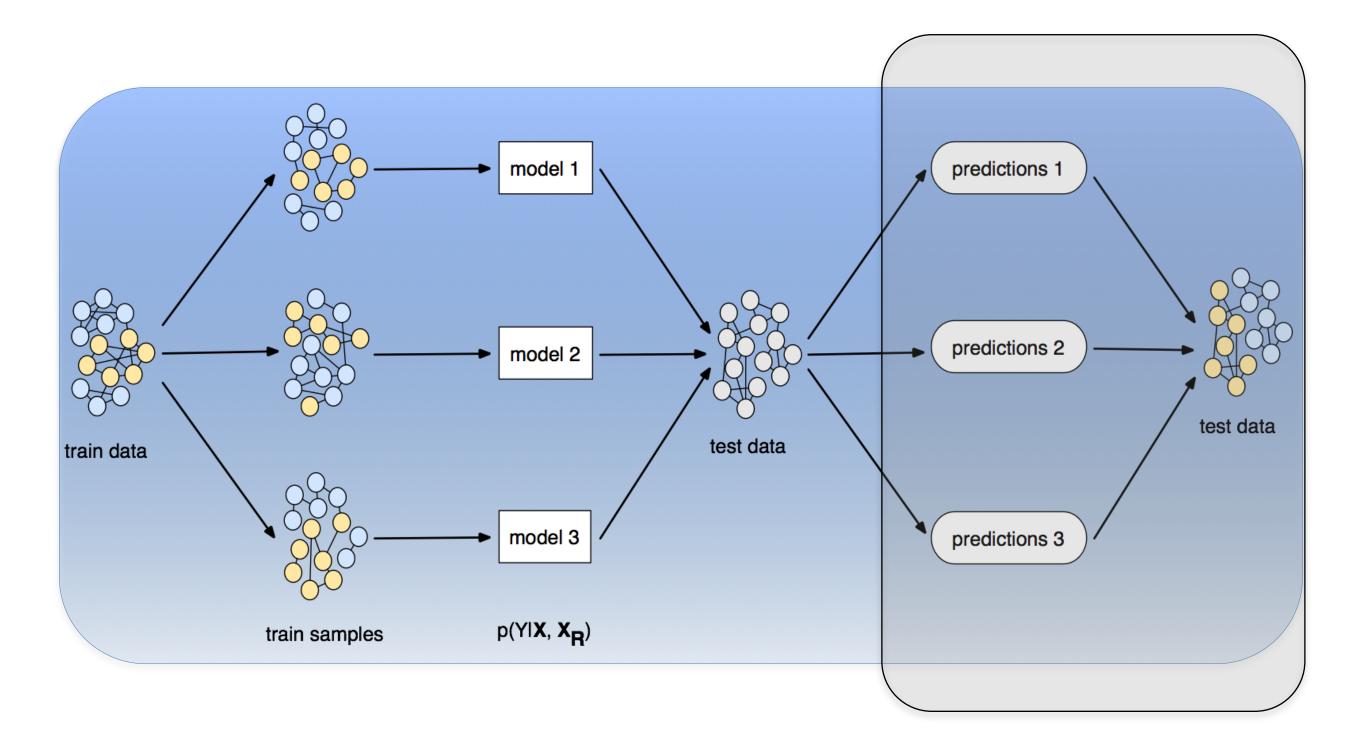
BAGGING



CHOICE OF BASE CLASSIFIER

 unstable predictor (e.g., decision tree)

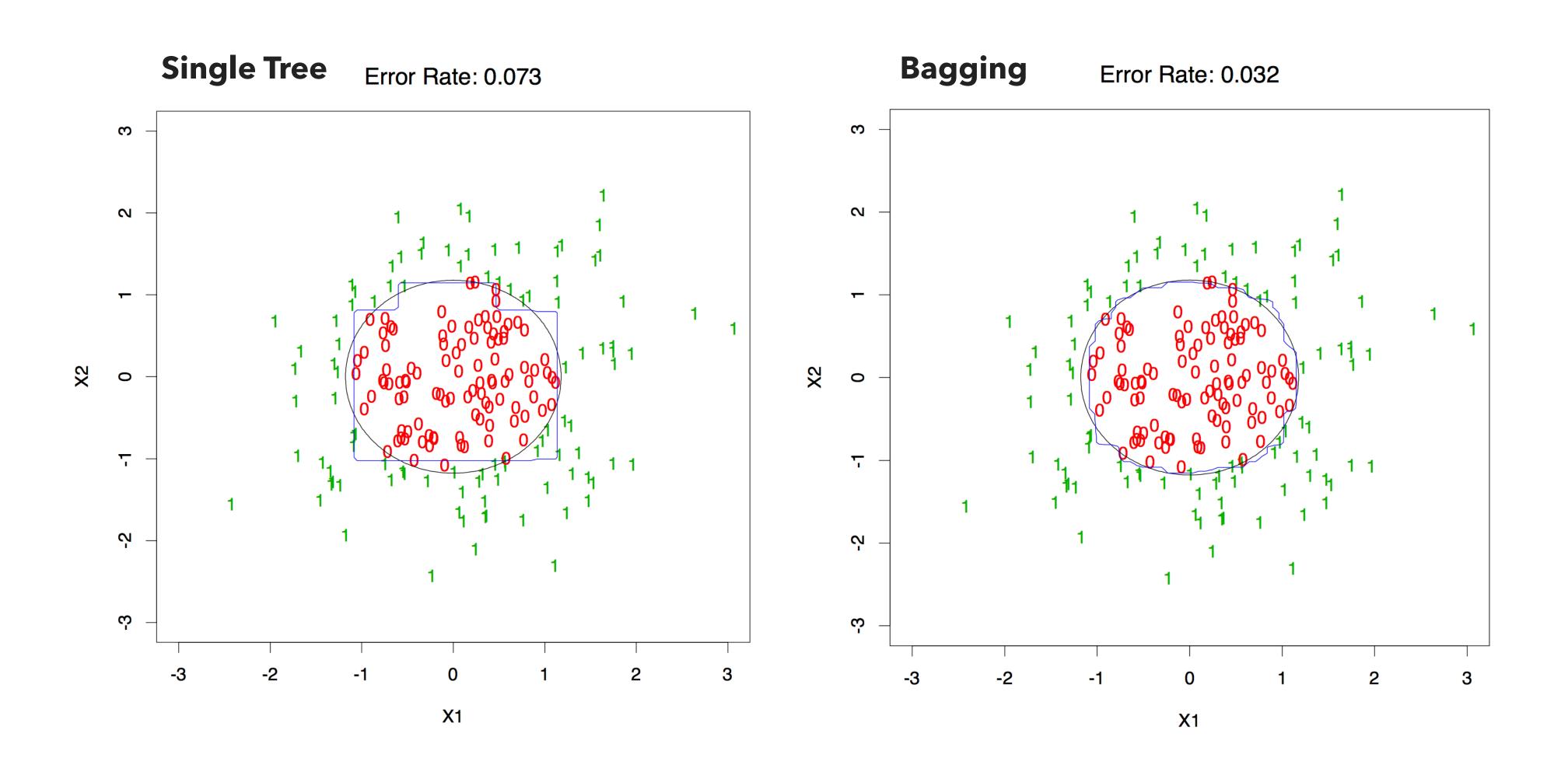
BAGGING



PREDICTION AGGREGATION

averaging / majority voting

DECISION BOUNDARY WITH SINGLE TREE VS. BAGGING



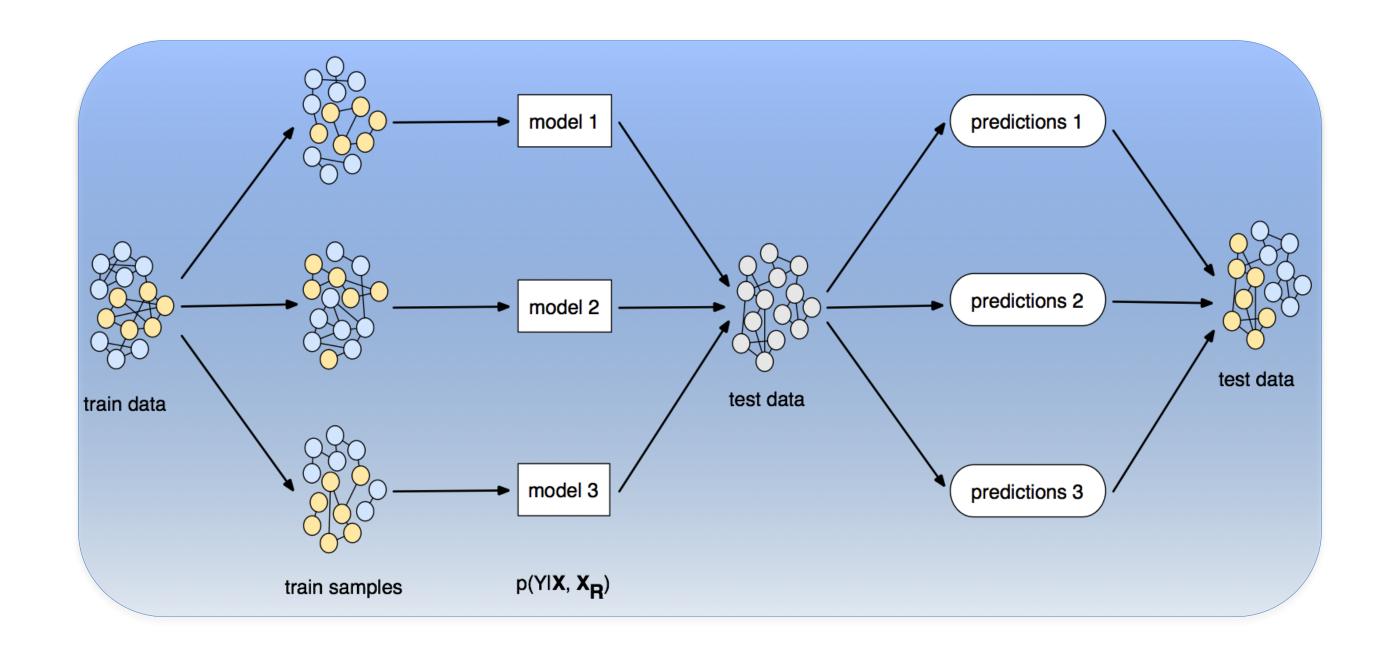
LIMITATIONS OF BAGGING

- A bag of M trees typically will lead to a reduction in variance that is smaller than 1/M
- ▶ Because the M models are correlated to some degree...
- Solution: further decrease the correlation between models...

RANDOM FORESTS

- Random forests are a variant that aims to improve on bagged decision trees by reducing the correlation between the models
 - Each tree is learned from a bootstrap sample (same as before)
 - For each tree split, a random sample of k features is drawn first, and **only** those features are considered when selecting the best feature to split on (typically $k=\sqrt{p}$ or $k=\log p$, p is the total number of features)

RANDOM FORESTS



TREATMENT OF INPUT DATA

sampling with replacement

CHOICE OF BASE CLASSIFIER

 decision tree (limited attributes are considered at each node)

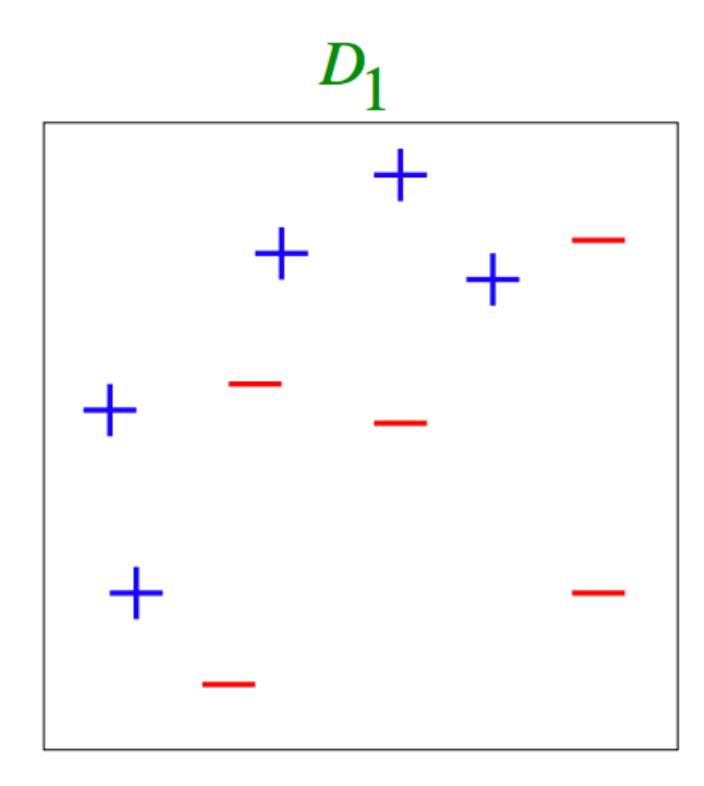
PREDICTION AGGREGATION

averaging/majority voting

BOOSTING

- Bagging and random forests share the same idea of combining multiple models that are trained on bootstrapped samples of the training data
 - Mimic learning the model from different training data
 - Each model has an equal amount of say (i.e., equal weights) in influencing the aggregated prediction
- Boosting
 - Combine multiple "complementary" models
 - Aggregate model predictions by considering how accurately each model can predict

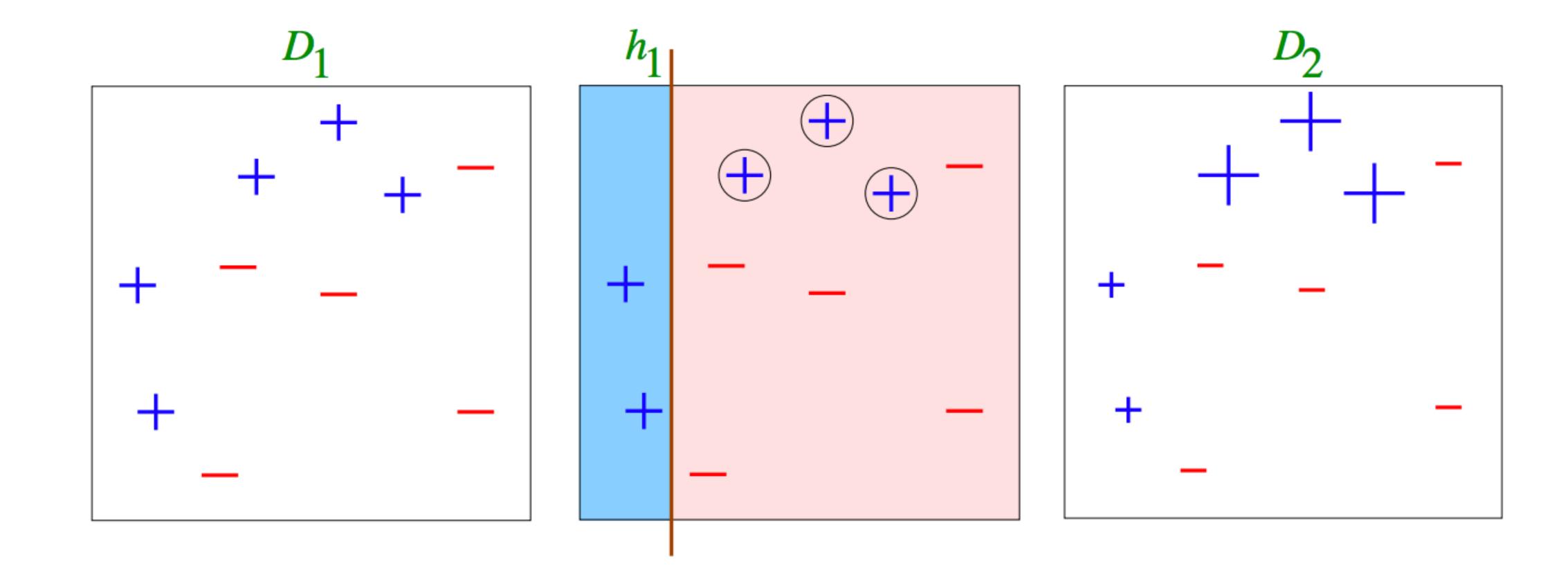
BOOSTING EXAMPLE



Model: Decision stump

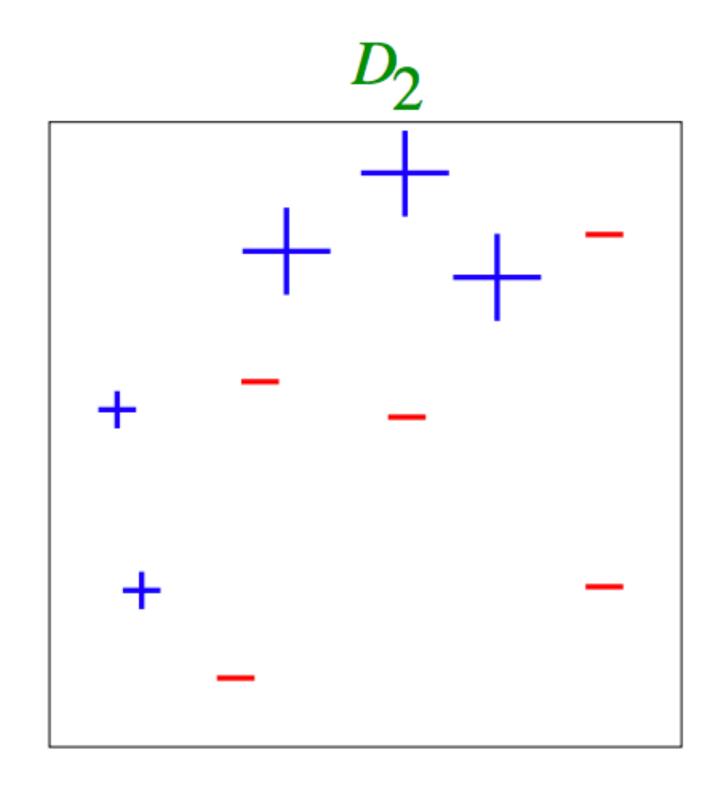
If $x_i > c$, then "+"; otherwise "-"

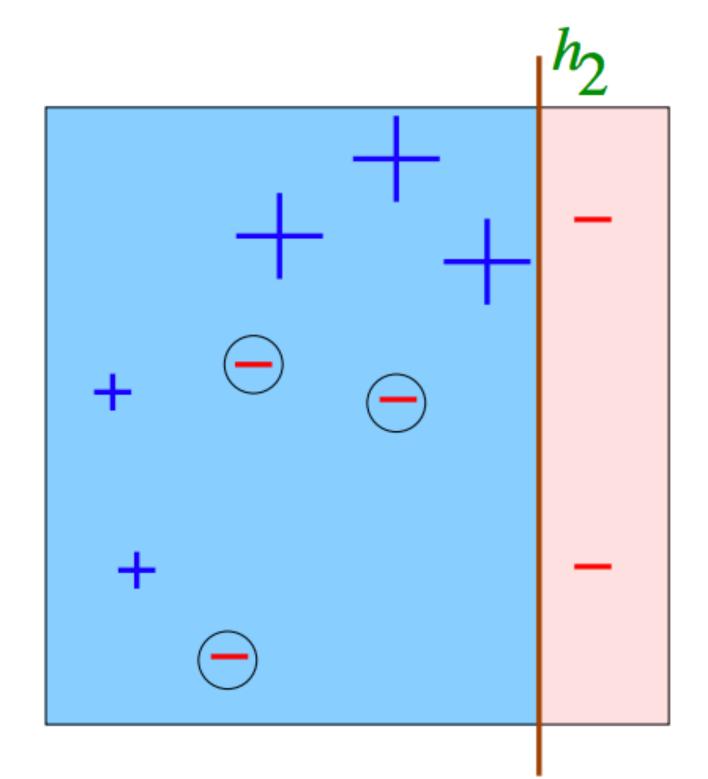
BOOSTING EXAMPLE: ROUND 1

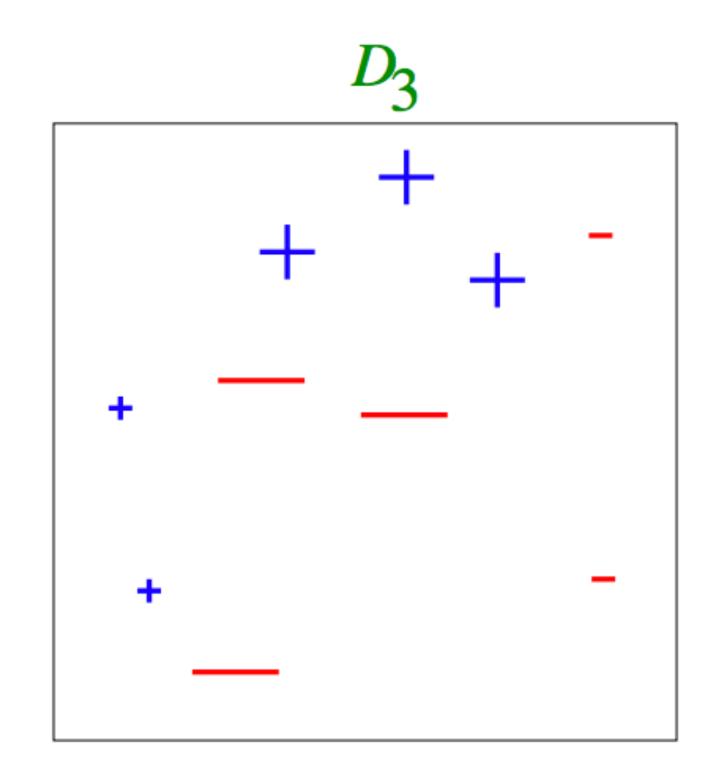


Construct "complementary" models? Re-weighting!

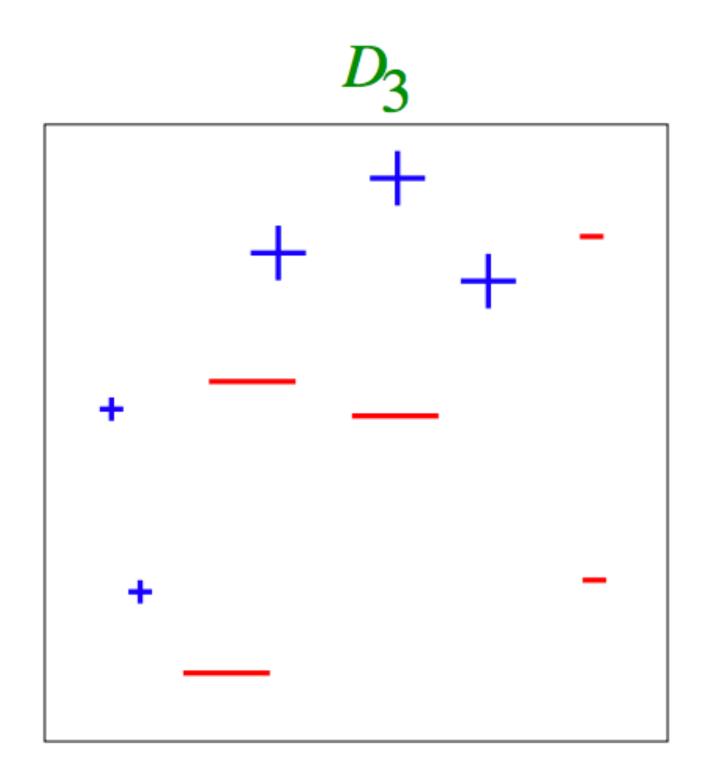
BOOSTING EXAMPLE: ROUND 2

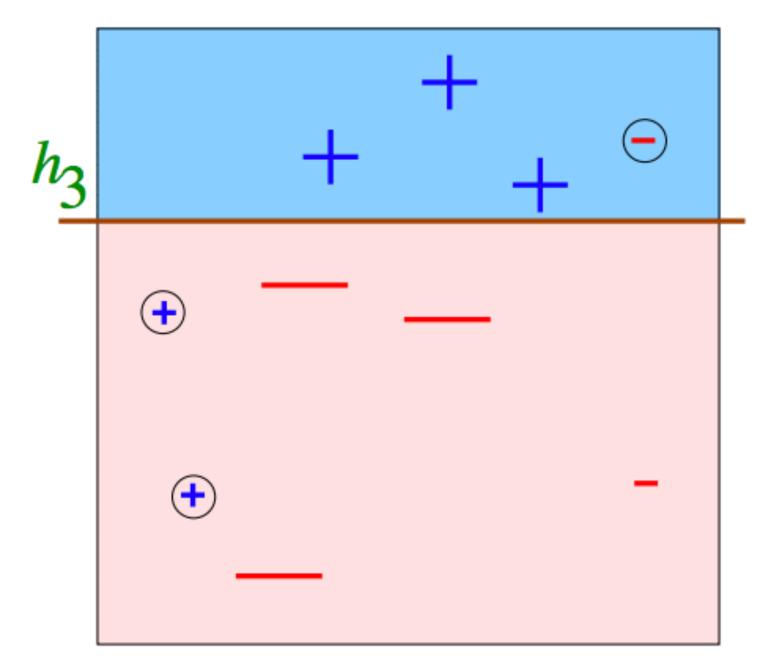




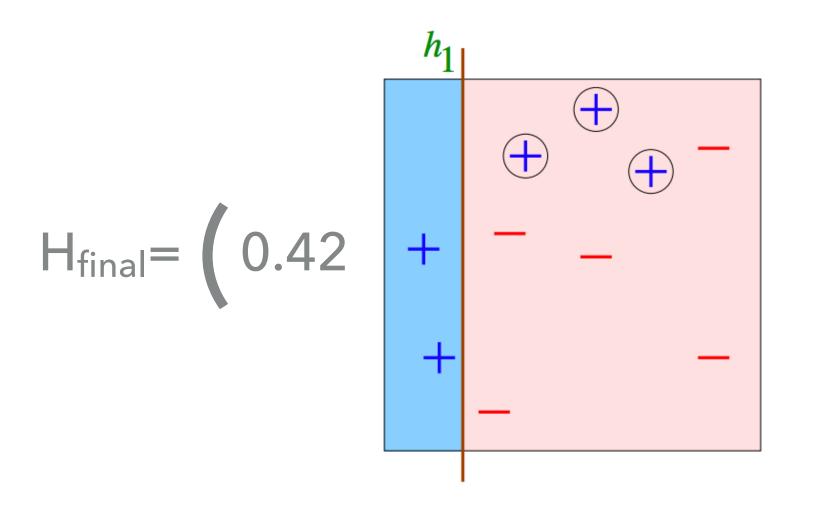


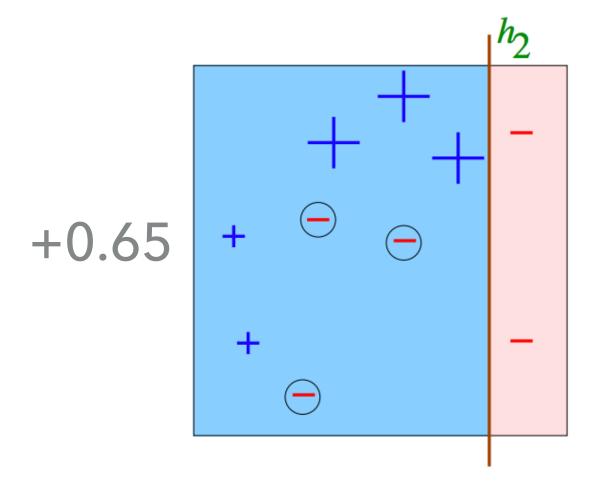
BOOSTING EXAMPLE: ROUND 3

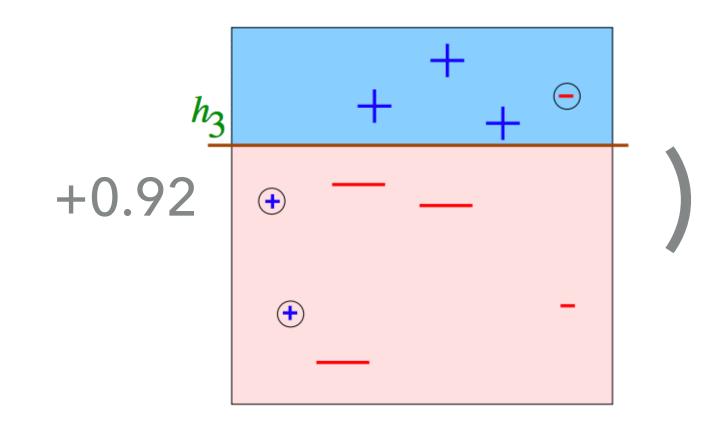


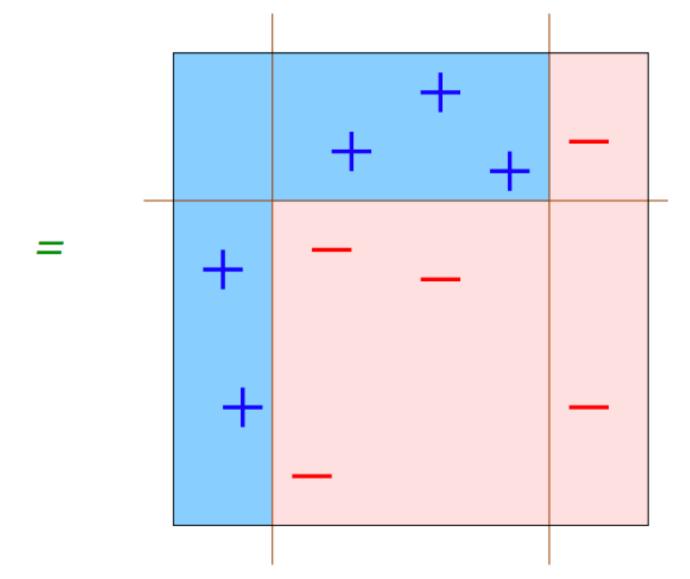


BOOSTING EXAMPLE: AGGREGATING









ADABOOST

- Given N training examples $(x_1, y_1), ..., (x_N, y_N)$, assign every example in with an equal weight $D_1(i)=1/N$
- For t=1:T
 - Learn model $h_t(x)$ to minimize the weighted error: $\epsilon_t = \Pr_{i \sim D_t}[h_t(x_i) \neq y_i] = \sum_{i=1}^N D_t(i) I(h_t(x_i) \neq y_i)$
 - Set the weight of this model: $\alpha_t = \frac{1}{2}ln(\frac{1-\epsilon_t}{\epsilon_t})$
 - Update training example weights: up-weight the examples that are incorrectly classified and downright examples that are correctly classified: $D_{t+1}(i) = \frac{D_t(i)exp(-\alpha_t y_i h_t(x_i))}{Z_t}$ where $Z_t = \sum_{t=0}^{N} D_t(i)exp(-\alpha_t y_i h_t(x_i))$ is a normalization factor
- To classify new test instance x', apply each model $h_t(x)$ to x' and take weighted vote of predictions

$$H(x') = \operatorname{sign}(\sum_{t=1}^{T} \alpha_t h_t(x'))$$