

# Module 6

## Formal Definition of TM and its types

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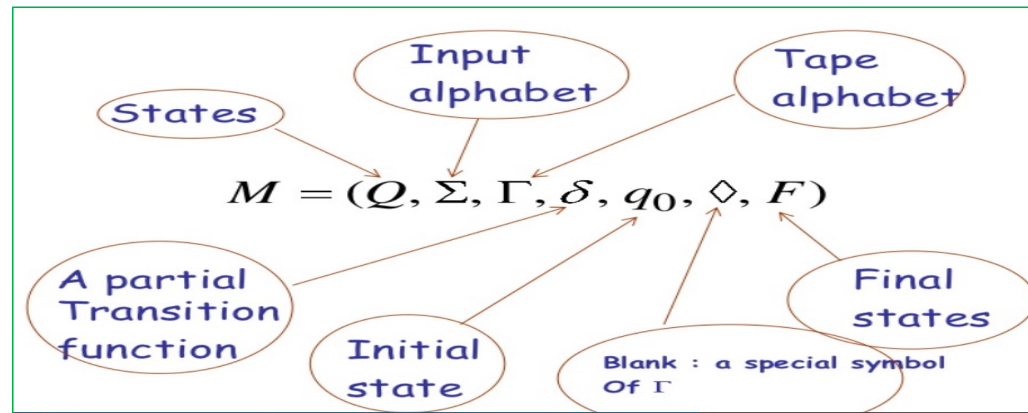


# Formal Definition of TM

A TM can be formally described as a 7-tuple

$(Q, \Gamma, \Sigma, \delta, q_0, B, F)$

where –



$\delta : Q \times \Sigma \rightarrow Q \times X \times \{ \text{Direction} \}.$

Direction:

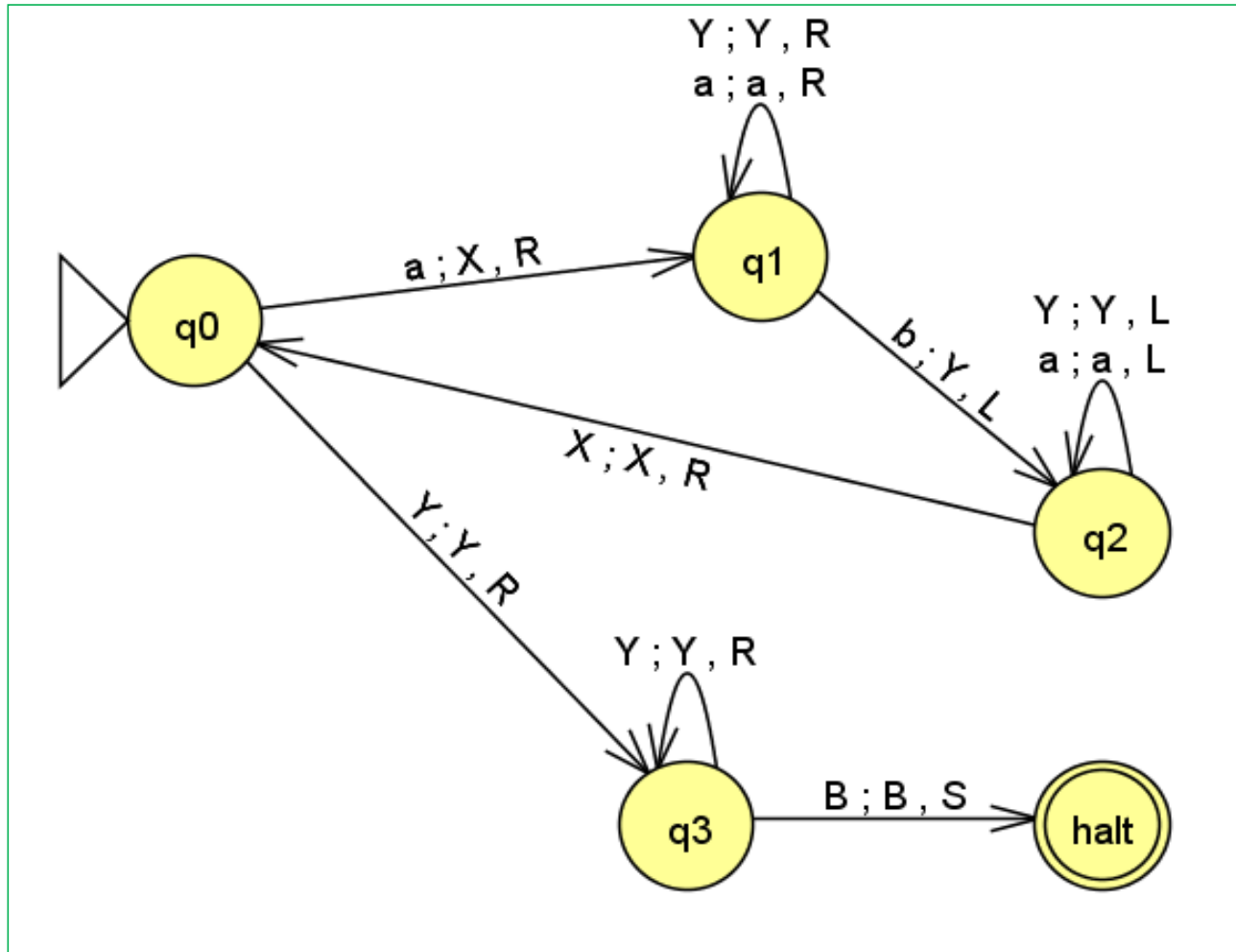
Left (L)

Right (R)

Same( S ) | Halt (H)



## State Diagram



# Construct TM for the language $L = \{a^n b^n\}$ where $n \geq 1$

## Logic:

Read out each 'a' mark it by X and then move ahead along with the input tape and find out b convert it to Y. Now, repeat this process for all a's and b's.

How this Turing machine work for aabb:

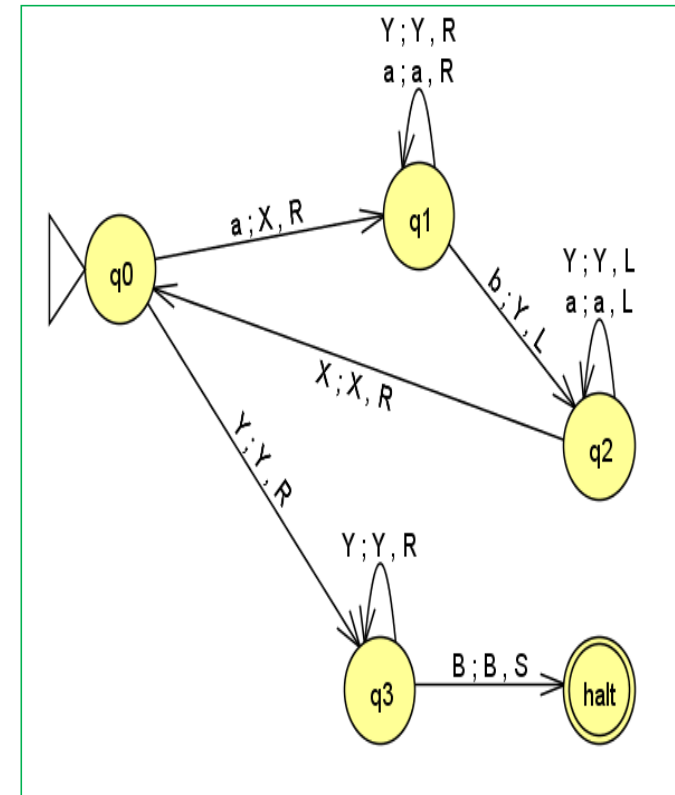


1. <u>B</u> a a b b B	6. B <u>X</u> a Y b B	11. B X <u>X</u> Y Y B
2. B <u>a</u> a b b B	7. B X <u>a</u> Y b B	12. B X X <u>Y</u> Y B
3. B X <u>a</u> b b B	8. B X X <u>Y</u> b B	13. B X X Y <u>Y</u> B
4. B X a <u>b</u> b B	9. B X X Y <u>b</u> B	14. B X X Y Y <u>B</u>
5. B X <u>a</u> Y b B	10. B X X <u>Y</u> Y B	15. B X X Y Y <u>B</u>



# Transition Table

STATE	INPUT-a	INPUT-b	B	X	Y
q0	(q1,X,R)	-	-	-	(q3,Y,R)
q1	(q1,a,R)	(q2,Y,L)	-	-	(q1,Y,R)
q2	(q2,a,L)	-	-	(q0,X,R)	(q2,Y,L)
q3	-	-	(q4,B,B)	-	(q3,Y,R)
q4 Accept  Halt					



# ID

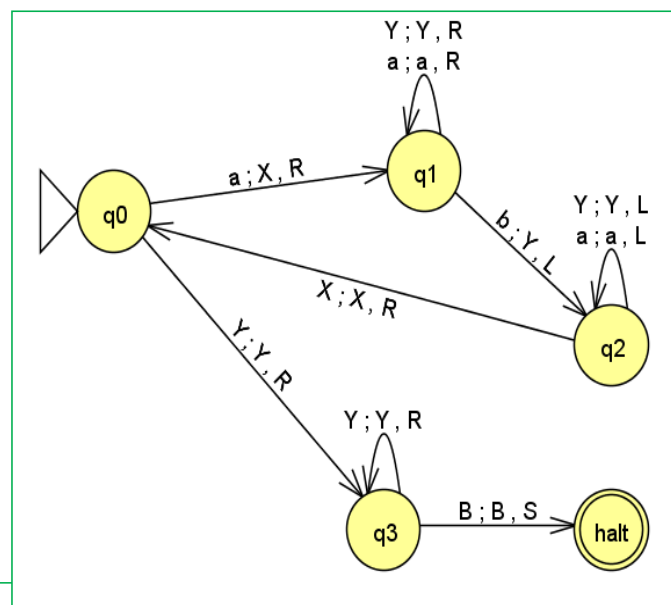
- ID's for TM's are strings of the form:

$\alpha - q - \beta$ ,

where  $\alpha, \beta \in \Gamma^*$  and  $q \in Q$

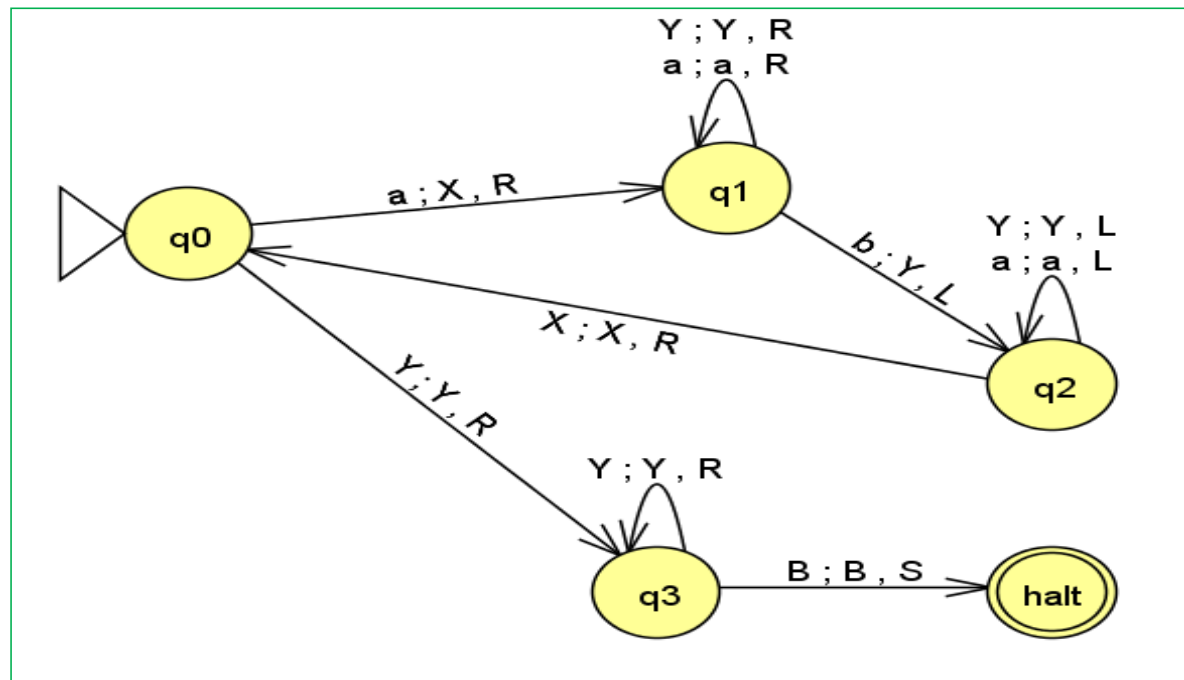
Example: Trace the string aabb:

**q0 a a b b B**



|-Xq1a b b B  
 |- X a q1b b B  
 |-X q2a Y b B  
 |- q2X a Y b B  
 |-X q0a Y b B  
 |-X X q1Y b B  
 |-X X Y q1b B  
 |-X X q2 Y Y B  
 |-X q2X Y Y B

|-X X q0Y Y B  
 |-XXYq3YB  
 |- XXYq3B  
 |-Halt (Accept | halt)





# Universal Turing Machine

- A Universal Computing Machine
- It is a TM, whose input consists of 2 parts
  - A string specifying some other (special purpose) TM-  $T_1$
  - A string  $Z$ ( input to the TM-  $T_1$ )
  - The TM,  $T_u$  then simulates the processing of  $Z$  by  $T_1$



# Construction of Tu

- **Step 1: Formulate a notational system**
  - For each tape symbol ( including Blank)
  - For each state ( including halt state)
  - Three directions

## For Input Symbols:

**$\Delta$ - 0**

**a-00**

**b-000**

## For each State:

**Halt- 0**

**q0-00**

**q1-000**

**q2-0000**



For Directions:

S-0

L-00

R-000

For beginning of string and ending of string – 11

For comma encoding is- 1

Tu- represents the universal TM

T1 – represents the name of special TM

$$Tu = e(T1) . e(Z)$$



# Construct a Tu for the TM

Transition Function:

$\delta(q_0, \Delta) = (q_1, \Delta, R)$

00 1 0 1 000 1 0 1 000

$\delta(q_1, b) = (q_1, b, R)$

000 1 000 1 000 1 000 1 000

$\delta(q_1, \Delta) = (q_2, \Delta, L)$

000 1 0 1 0000 1 0 1 00

$\delta(q_1, a) = (q_2, b, L)$

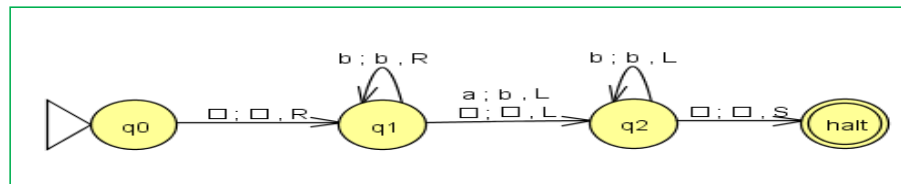
000 1 00 1 0000 1 000 1 00

$\delta(q_2, b) = (q_2, b, L)$

0000 1 000 1 0000 1 000 1 00

$\delta(q_2, \Delta) = (\text{Halt}, \Delta, S)$

0000 1 0 1 0 1 0 1 0



Input	State	Direction
Δ-0	Halt-0	S-0
a-00	q0-00	L-00
b-000	P-000	R-000
	R-0000	



$e(T) = \delta(q_0, \Delta) = (q_1, \Delta, R) \ 11 \ \delta(q_1, b) = (q_1, b, R) \ 11 \ \delta(q_1, \Delta) = (q_2, \Delta, L) \ 11$   
 $\delta(q_1, a) = (q_2, b, L) \ 11 \ \delta(q_2, b) = (q_2, b, L) \ 11 \ \delta(q_2, \Delta) = (\text{Halt}, \Delta, S)$

$e(T) =$  00 1 0 1 000 1 0 1 000 11 000 1 000 1 000 1 000 1 000 11 000 1 0  
 1 0000 1 0 1 00 11 000 1 00 1 0000 1 000 1 00 11 0000 1 000 1 0000 1  
 000 1 00 11 0000 1 0 1 0 1 0 1 0

Assume  $Z = baa$

$e(Z) = 000 \ 1 \ 00 \ 1 \ 00$

$T_u = e(T1) \cdot e(Z)$



$$T_u = e(T1) \cdot e(Z)$$

**Tu=** 11 00 1 0 1 000 1 0 1 000 11 000 1 000 1 000 1 000 1 000 11 000 1 0 1  
 0000 1 0 1 00 11 000 1 00 1 0000 1 000 1 00 11 0000 1 000 1 0000 1 000  
 1 00 11 0000 1 0 1 0 1 0 1 0 11 000 1 00 1 00 11

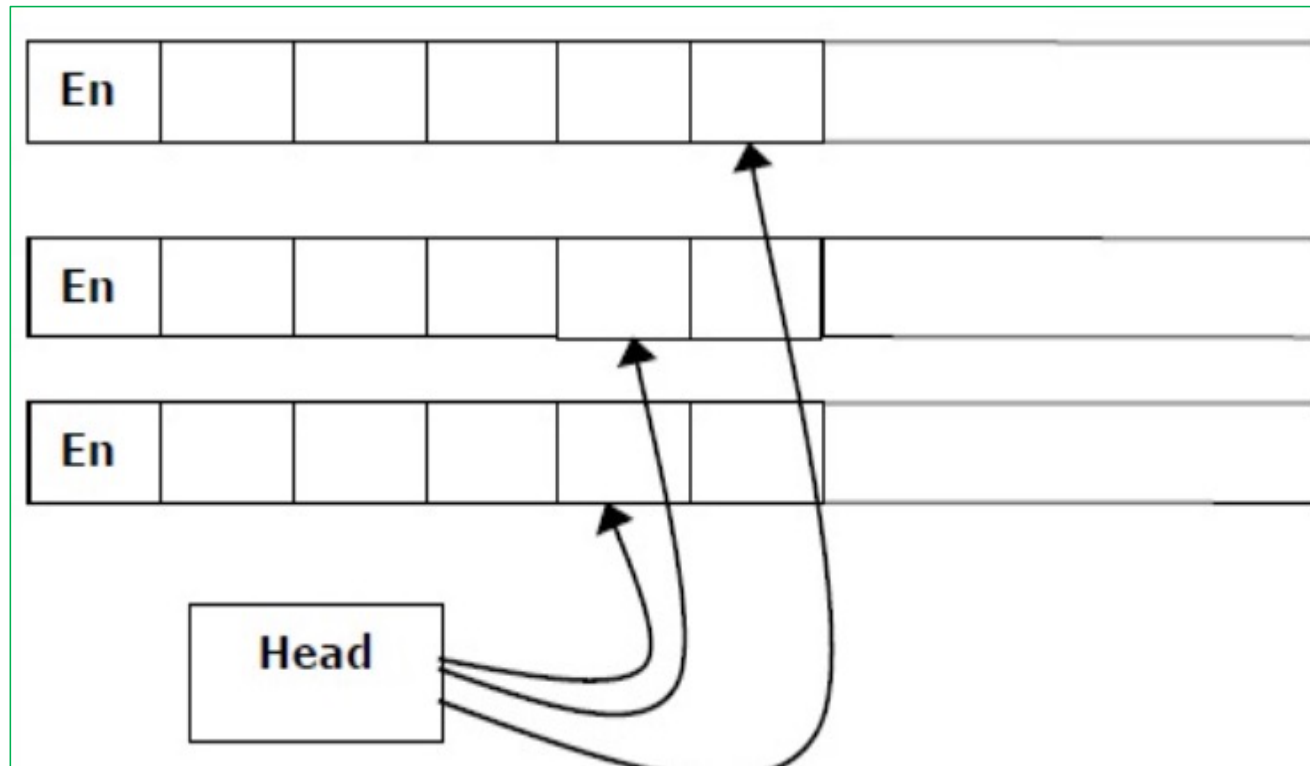


# Turing Machine Types

- Multi-Head Turing Machine
- 2-way infinite tape TM
- Multi-tape Turing machine
- Offline Turing Machine



# Multi-Tape Turing Machine





# Multi-Tape Turing Machine

- It has multiple tapes and controlled by a single head.
- The Multi-tape Turing machine is different from k-track Turing machine but expressive power is same.
- Multi-tape Turing machine can be simulated by single-tape Turing machine.



# Multi-Head Turing Machine

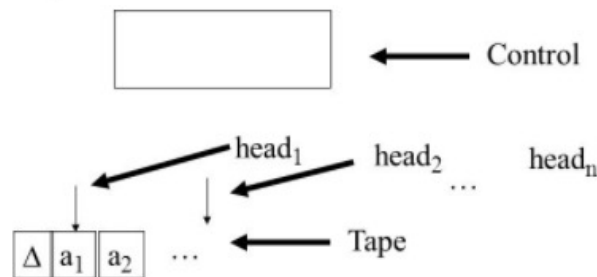
- A multi-head Turing machine contains two or more heads to read the symbols on the same tape.
- In one step all the heads sense the scanned symbols and move or write independently.
- Multi-head Turing machine can be simulated by single head Turing machine.



# MULTIHEAD TURING MACHINE

Clip slide

- Multihead TM has a number of heads instead of one.
- Each head independently read/ write symbols and move left / right or keep stationary.



We add a finite number of heads for the same tape



# 2-way infinite tape TM

Both ends are infinite



# 2-way infinite tape TM

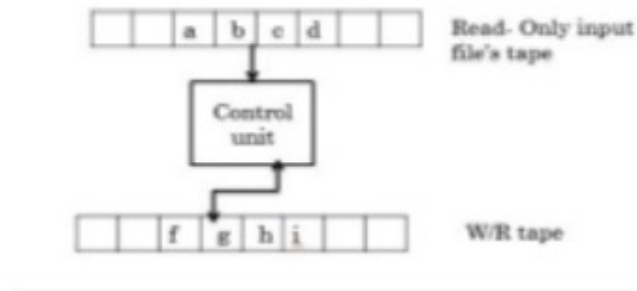
- Infinite tape of two-way infinite tape Turing machine is unbounded in both directions left and right.
- Two-way infinite tape Turing machine can be simulated by one-way infinite Turing machine(standard Turing machine).



# OFF- LINE TURING MACHINE

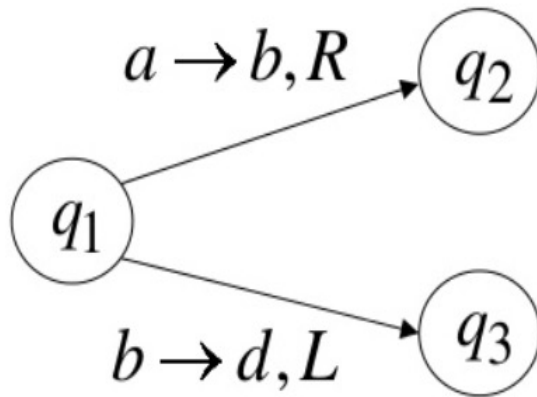
➤ An *Offline Turing Machine* has two tapes

1. One tape is *read-only* and contains the input
2. The other is *read-write* and is initially blank.

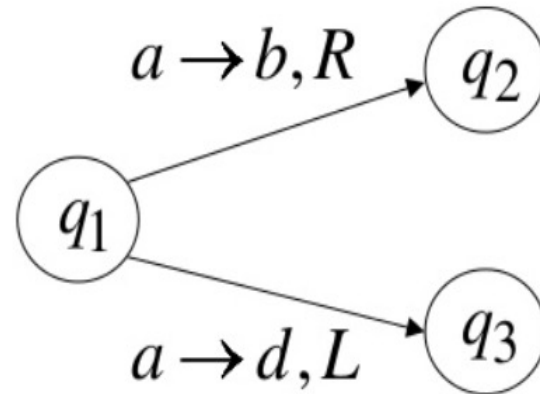


# Deterministic TM

Allowed



Not Allowed



# Non-Deterministic Turing Machine

- For every state and symbol, there are a group of actions the TM have.
- The computation of a non-deterministic Turing Machine is a tree
- If all branches of the computational tree halt on all inputs, the non-deterministic Turing Machine is called a **Decider**
- If for some input, all branches are rejected, the input is also rejected.

