

# Prediction and Analysis of Thermal Errors for Efficient CNC Machining

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Thermal error and temperature data extracted from graphs of the paper:

# Thermal error optimization modeling and real-time compensation on a CNC turning center



## Thermal error optimization modeling and real-time compensation on a CNC turning center

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### ABSTRACT

Thermal errors are the largest contributor to the dimensional errors of a workpiece in precision machining. The error compensation technique is an effective way of reducing thermal errors. Accurate modeling of errors is a key part of error compensation. The thermal errors of a machine tool can be treated as the superposition of a series of thermal error modes. In this paper, five key temperature points of a turning center were obtained based on the thermal error mode analysis. A thermal error model based on the five key temperature points was proposed by using genetic algorithm-based back propagation neural network (GA-BPN). The GA-BPN method improves the accuracy and reduces computational cost for the prediction of thermal deformation in the turning center. A thermal error real-time compensation system was developed based on the proposed model. An experiment was carried out to verify the performance of the compensation system. The experimental results show that the diameter error of the workpiece reduced from about 27–10  $\mu\text{m}$  after implementation of the compensation.

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### 1. Introduction

The inherent inaccuracy of machine tools is a major contributor to workpiece errors. Among many various sources of machine tool errors, thermal errors are the largest contributor, accounting for as much as 70% of workpiece errors in precision machining (Weck et al., 1995). Researchers have considered many ways of reducing thermal errors, including the thermally symmetric design of a structure, separation of the heat sources from the main body of a machine tool, installation of a cooling unit, and so on. However, the manufacturing costs associated with the above-mentioned approaches are usually very high. In addition, there are many physical limitations in implementing process, which cannot be overcome solely by design techniques. As a result, error compensation technique used to improve machine accuracy cost-effectively has received significant attention in recent years (Yang et al., 1996a).

Accurate modeling of errors is a key part of error compensation. The thermal errors of a machine tool origin from the non-linear and time-varying thermal deformations caused by the non-uniform temperature variations in the machine structure. The temperature variations are related to the heat source location, heat source intensity, thermal resistance coefficient and the machine system configuration. Therefore, the thermal error model is usually achieved by non-linear empirical modeling approaches which correlate machine thermal errors to temperature measurements of a machine. In recent years, it has been shown that thermal error map of a machine tool can be successfully approximated by empirical modeling approaches such as multiple regression analysis techniques (Yang et al., 1996b, 1999, 2002; Lee and Yang, 2002), types of artificial neural networks (Yang et al., 1996c; Yang and Lee, 1998; Mize and Ziegert, 2000; Lee et al., 2003; Yang and Ni, 2005), grey system theory (Wang et al., 1998), genetic algorithm (Choi and Lee, 2002), rigid body kinematics (Okafor

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What are we  
going to  
Discuss in next  
8-9 minutes?

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The Motive

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Different sensor positions

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The Code: Different  
Models Proposed

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Comparisons & Results

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Uses & Applications





Minimizing Errors

Data visualization

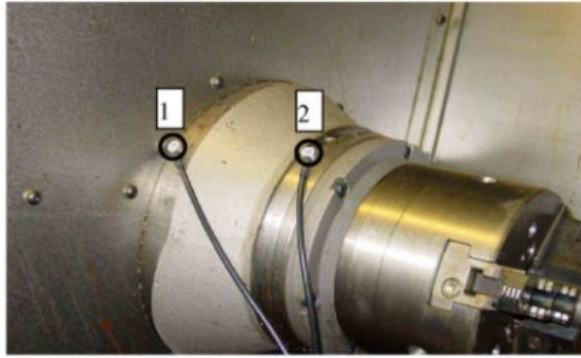
Parameters and sensors

Machine Learning Model  
Analysis

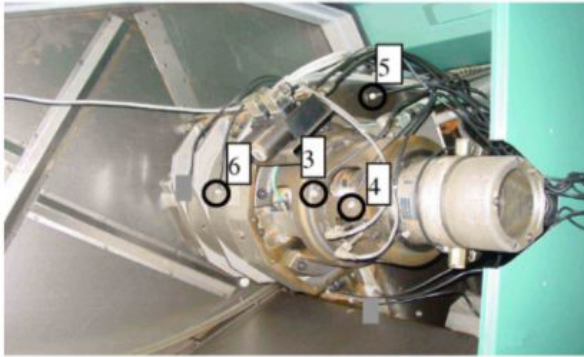
The Motive



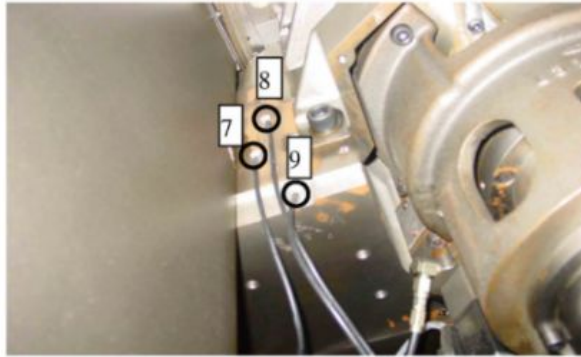
(a) The tested turning center



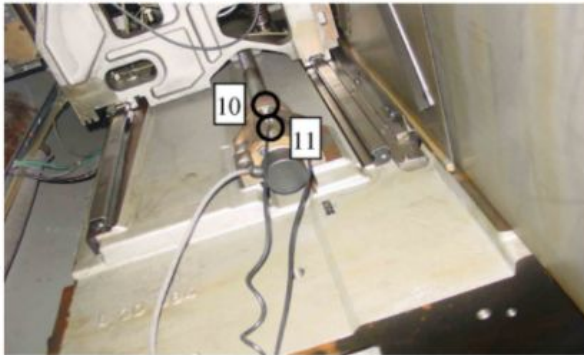
(b) Thermistors on the spindle fore-end



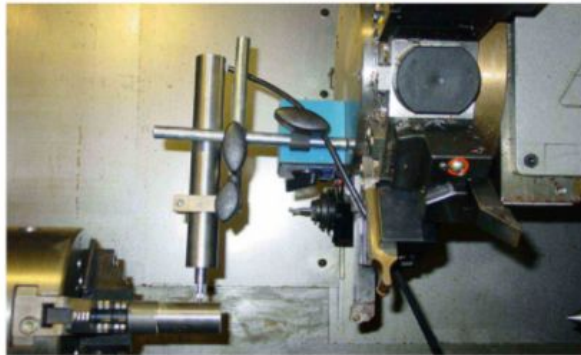
(c) Thermistors on the spindle rear-end



(d) Thermistors on the headstock



(e) Thermistors on the X-axis lead screw



(f) Displacement sensor

# Temperature Sensor Positions & Effects of Temp. Rise

- Friction- Cause of temperature Rise
- Bearing Expansion
- Ball Screw Expansion
- Wrapping Effect of Base



Inside the  
Code

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Data Visualization

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Choosing the Right Sensors

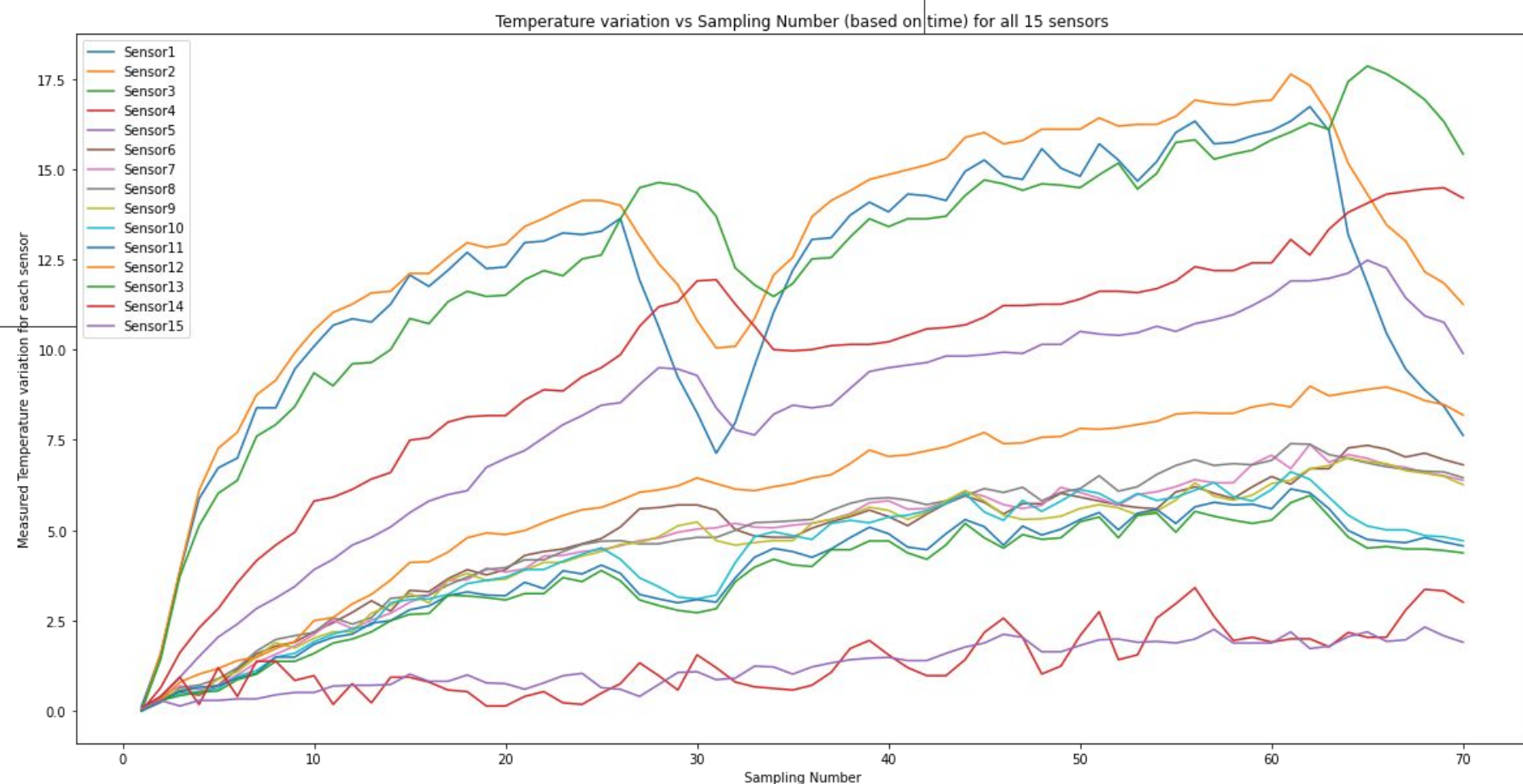
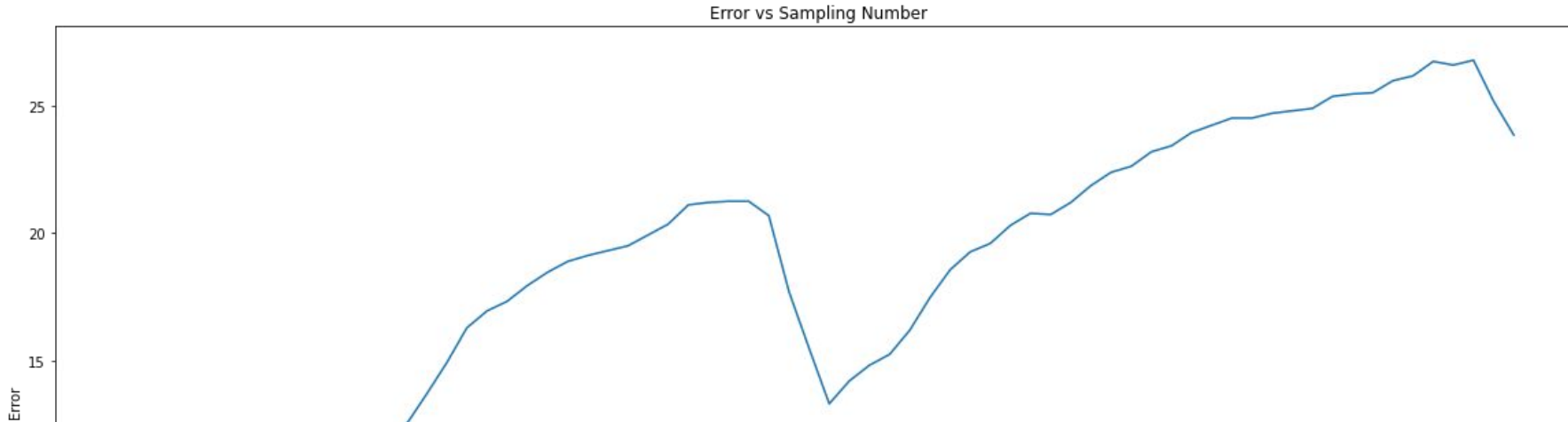
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Regression Using Different  
Approaches

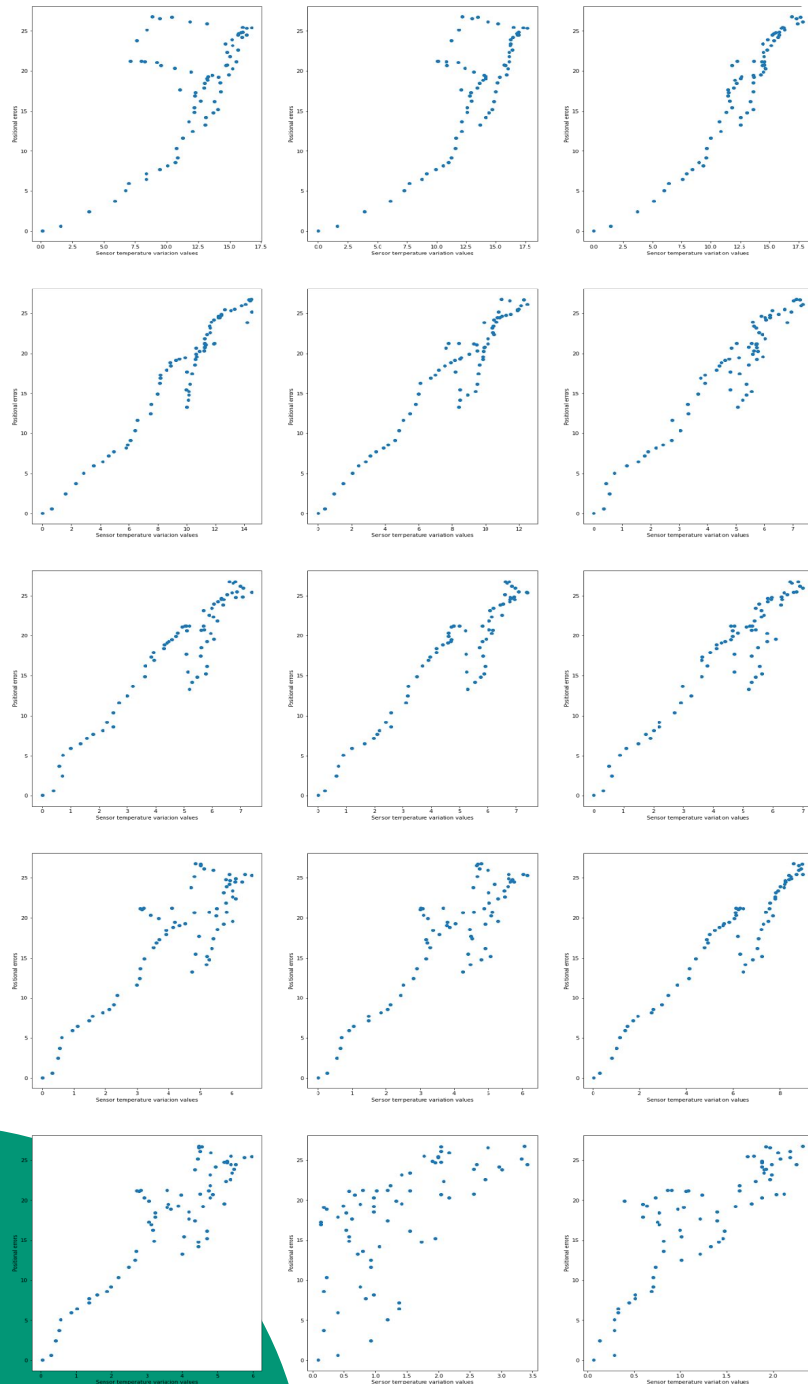
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Comparison of Results

# DATA VISUALIZATION



Click to add text



# Sensor temperature variation values vs Positional errors

## 3 key learnings:

- For Sensors 3-8 it is almost linear and is uniformly spread out
- For other sensors, there is some non-uniformity and variations are more complex than Linear
- Last 2 sensors almost convey no major information





## Choosing the Right Sensors

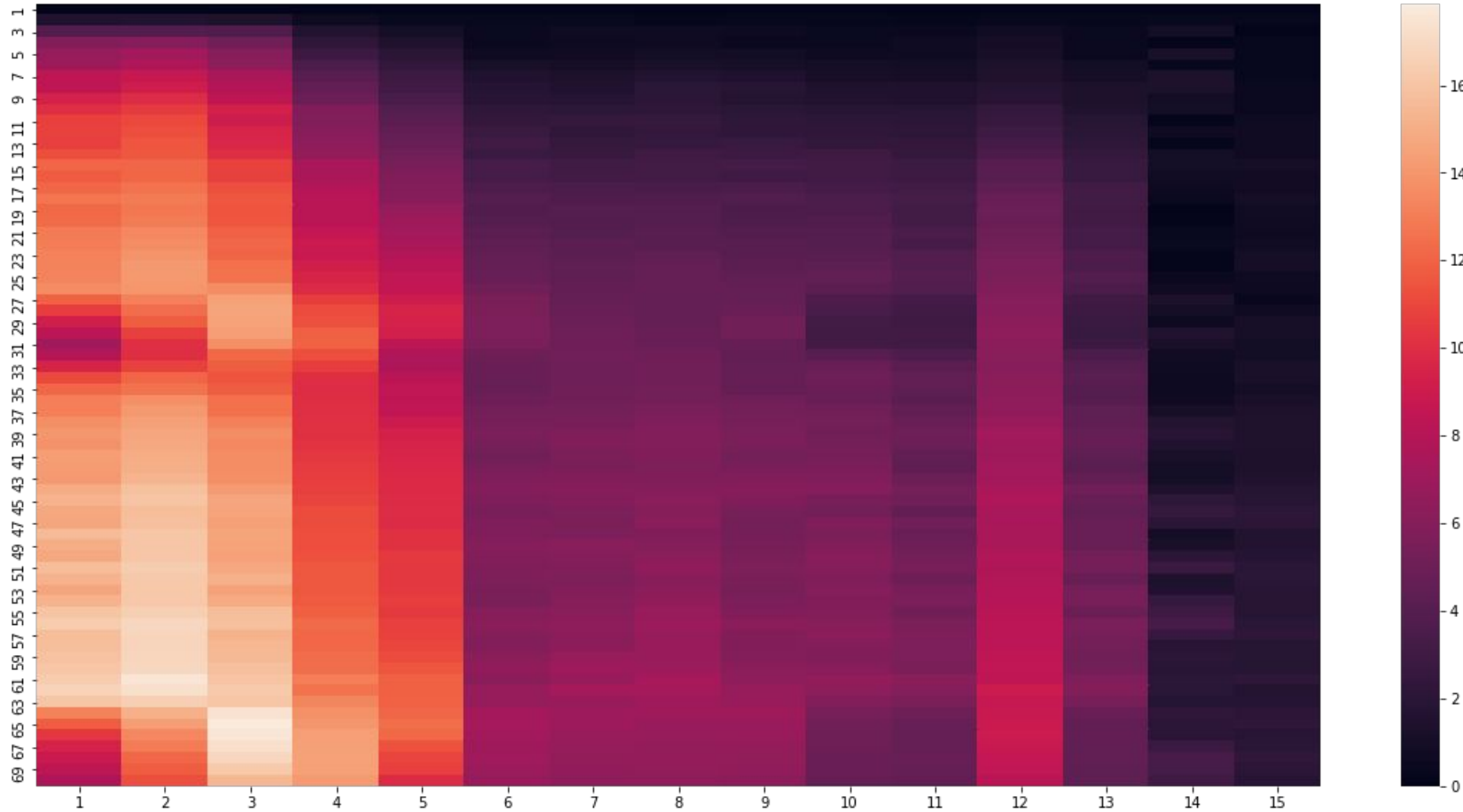
1

Insights from Heatmap

2

Clustering based on correlation

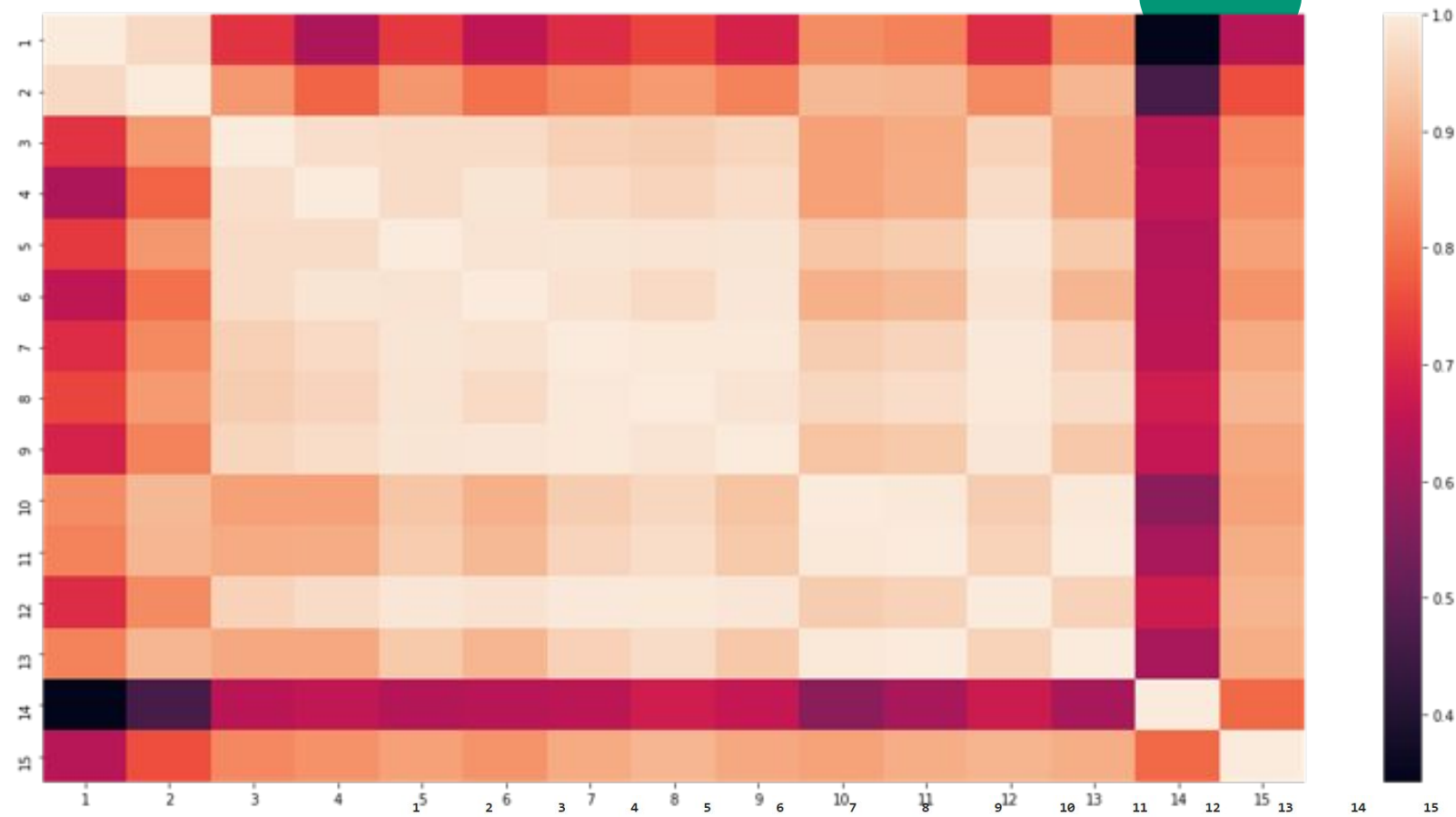
# 1. Insights from Heatmap and sensor positions



- **1 to 5:** High Variance (More Information)
- Others do not vary much- they have low temperature variations
- Sensor positions from 1 to 5 along with high variance, are also directly responsible for holding the work.

## 2. Clustering Based on Correlation

**Correlation Matrix + Code + Heatmap** confirm our results



```
[131] import scipy.cluster.hierarchy as sci
```

```
corr = df1.corr().values
```

```
pd = sci.distance.pdist(corr)
```

```
linkage = sci.linkage(pd, method='complete')
```

```
id = sci.fcluster(linkage, 0.2 * pd.max(), 'distance')
```

```
id
```

```
array([4, 5, 2, 2, 2, 2, 2, 2, 2, 1, 1, 2, 1, 6, 3], dtype=int32)
```

1	1.000000	0.968485	0.718261	0.622147	0.730066	0.651168	0.708134	0.744505	0.691249	0.844082	0.829502	0.708757	0.829957	0.341901	0.639990
2	0.968485	1.000000	0.861207	0.785907	0.860710	0.802997	0.838351	0.864254	0.828655	0.915146	0.909225	0.840624	0.908238	0.467531	0.758112
3	0.718261	0.861207	1.000000	0.978032	0.972938	0.973074	0.952374	0.947979	0.962769	0.876563	0.891771	0.957582	0.887613	0.643839	0.836836
4	0.622147	0.785907	0.978032	1.000000	0.973335	0.988922	0.970407	0.960432	0.975980	0.875695	0.893531	0.972351	0.888744	0.654988	0.851088
5	0.730066	0.860710	0.972938	0.973335	1.000000	0.985781	0.988133	0.984911	0.987551	0.934868	0.944721	0.990955	0.941331	0.634639	0.875725
6	0.651168	0.802997	0.973074	0.988922	0.985781	1.000000	0.983729	0.970820	0.990581	0.900009	0.912870	0.983701	0.909085	0.640455	0.854883
7	0.708134	0.838351	0.952374	0.970407	0.988133	0.983729	1.000000	0.993567	0.992391	0.947837	0.959015	0.995525	0.955843	0.649114	0.890956
8	0.744505	0.864254	0.947979	0.960432	0.984911	0.970820	0.993567	1.000000	0.986410	0.965113	0.975236	0.993409	0.972336	0.677402	0.909938
9	0.691249	0.828655	0.962769	0.975980	0.987551	0.990581	0.992391	0.986410	1.000000	0.931013	0.942613	0.991880	0.939764	0.658734	0.885860
10	0.844082	0.915146	0.876563	0.875695	0.934868	0.900009	0.947837	0.965113	0.931013	1.000000	0.992908	0.947909	0.993236	0.575221	0.877444
11	0.829502	0.909225	0.891771	0.893531	0.944721	0.912870	0.959015	0.975236	0.942613	0.992908	1.000000	0.958766	0.997821	0.615406	0.895089
12	0.708757	0.840624	0.957582	0.972351	0.990955	0.983701	0.995525	0.993409	0.991880	0.947909	0.958766	1.000000	0.956370	0.672977	0.906602
13	0.829957	0.908238	0.887613	0.888744	0.941331	0.909085	0.955843	0.972336	0.939764	0.993236	0.997821	0.956370	1.000000	0.616067	0.894744
14	0.341901	0.467531	0.643839	0.654988	0.634639	0.640455	0.649114	0.677402	0.658734	0.575221	0.615406	0.672977	0.616067	1.000000	0.792518
15	0.639990	0.758112	0.836836	0.851088	0.875725	0.854883	0.890956	0.909938	0.885860	0.877444	0.895089	0.906602	0.894744	0.792518	1.000000

# Thermal Error Prediction Approaches:



Linear  
Regression



PCA



Neural Networks



Polynomial  
Regression



# Linear Regression

```
[11] from sklearn import datasets, linear_model
      from sklearn.metrics import mean_squared_error, confusion_matrix

      from sklearn.linear_model import LinearRegression

      reg = linear_model.LinearRegression()

      # Train the model using the training sets
      reg.fit(X_train, y_train)

      # Make predictions using the testing set
      y_pred = reg.predict(X_test)
      y_pred
```

```
array([28.65677213, 17.47649304, 18.15863582, 28.98336201, 25.05728277,
        25.62511935, 27.37608329, 16.95618079, 25.92340552, 22.59560472,
        18.35944864, 23.13065671,  9.9362597 , 13.31207123, 18.3647796 ,
        19.16731123, 11.40686787, 26.57640344, 15.74711226, -1.68657532,
        22.87553239])
```

```
[12] y_test
```

```
array([26.149, 17.685, 20.664, 26.716, 25.345, 25.44 , 26.574, 14.8 ,
        25.156, 20.333, 19.292, 21.184,  8.606, 12.483, 16.172, 19.576,
        11.632, 25.96 , 17.306,  0.047, 22.602])
```

```
[13] print('Coefficients: \n', reg.coef_)
      # mean squared error
      print('Mean squared error: %.2f' % mean_squared_error(y_test, y_pred))
```

```
Coefficients:
[ 0.53692302 -1.48916046  1.77198791  0.73190075  1.86866492  0.05282001
 0.23555601 -0.8638938  -4.15419536 -0.52287336 -1.22174307  0.29677728
 4.00336151 -0.39301756  0.68355898]
Mean squared error: 2.23
```

- Minimum MSE through this approach- data has a linear setting
- Ran more than once on particular sensors

# PCA

```
[19] #PCA
      from sklearn.decomposition import PCA
```

```
      comp=100
      pca=PCA(n_components=5)
      pca.fit(X_train)
```

```
      X_train_pca=pca.transform(X_train)
      X_test_pca=pca.transform(X_test)
      #X_train_pca.shape
      X_train_pca.shape
```

```
(49, 5)
```

```
▶ eigenvalues = pca.explained_variance_
  eigenvalues
```

```
↳ array([80.5449243 ,  6.51457542,  0.99883578,  0.509529  ,  0.1246482 ])
```

```
[22] cov_matrix = pca
      cov_matrix.fit(X_train)
      variance = cov_matrix.explained_variance_ratio_
      vars=np.cumsum(np.round(cov_matrix.explained_variance_ratio_, decimals=3)*100)
      vars #cumulative sum of variance
      #Clearly first 5 features give almost 100% variance
      #SO WE CAN SAFELY TAKE ONLY FIRST 5 FEATURES(Sensors)
```

```
array([90.6, 97.9, 99. , 99.6, 99.7])
```

```
[23] #Now using Linear regrression on the PCA components
```

```
[24] reg = linear_model.LinearRegression()
```

```
      # Train the model using the training sets
      reg.fit(X_train_pca, y_train)
```

```
      # Make predictions using the testing set
      y_pred_pca = reg.predict(X_test_pca)
      y_pred_pca
```

```
▶ y_test
```

```
↳ array([26.149, 17.685, 20.664, 26.716, 25.345, 25.44 , 26.574, 14.8  ,
          25.156, 20.333, 19.292, 21.184,  8.606, 12.483, 16.172, 19.576,
          11.632, 25.96 , 17.306,  0.047, 22.602])
```

```
[26] print('Mean squared error: %.2f' % mean_squared_error(y_test, y_pred_pca))
```

```
Mean squared error: 3.07
```

- Found out new, more informative features (Number of components=5)
- Explained Variance- first 5 eigen vectors taken for maximum information
- These collectively express 99.8% variance

# Neural Network

```
[148] from keras import Sequential
      from keras.layers import Dense

      model = Sequential()
      model.add(Dense(20, activation='relu', kernel_initializer='normal', input_dim=15))
      model.add(Dense(5, activation='relu', kernel_initializer='normal'))
      model.add(Dense(1, kernel_initializer='normal'))

      model.compile(optimizer='adam', loss='mean_squared_error')

      #X_train = np.asarray(X_train)
      #y_train = np.asarray(y_train)
      #X_val = np.asarray(X_val)
      #y_val = np.asarray(y_val)

      model.fit(X_train, y_train, batch_size=10, epochs=100)
```

```
[150] y_test
```

```
array([25.345, 16.928,  6.478, 20.333, 25.487, 21.184, 22.366, 20.285,
        5.06 ,  8.606, 16.266, 21.089, 18.867,  2.459, 19.292, 23.17 ,
        20.664, 24.21 , 26.716, 25.44 , 14.895])
```

```
[151] print('Mean squared error: %.2f' % mean_squared_error(y_test, y_pred_nn))
```

```
Mean squared error: 3.86
```

- Neural Network for regression
  - Output layer has no activation function
  - Other layers use ReLU function
  - 2 hidden layers
  - Epochs 100
- Objective function: MSE
- NN ran thrice- for different variations

# Polynomial Regression

```
import timeit
start = timeit.default_timer()

from sklearn.preprocessing import PolynomialFeatures
poly_reg = PolynomialFeatures(degree=3)
X_poly = poly_reg.fit_transform(X_train)
pol_reg = LinearRegression()
pol_reg.fit(X_poly, y_train)

lin_reg = LinearRegression()
lin_reg.fit(X_train, y_train)

stop = timeit.default_timer()
print('Time: ', stop - start)
```

Time: 0.01660974299738882

```
[118] y_pred_lin=lin_reg.predict(X_test)
# Predicting a new result with Polynomial Regression
y_pred_poly=pol_reg.predict(poly_reg.fit_transform(X_test))
y_pred_poly
```

```
array([ 2.2834229 , 17.15119315, 23.20856834, 16.26975135, 16.45771219,
        12.07560442, 14.14706895, 20.26814796, 30.82674774, 15.85532802,
        23.61279125,  4.42657597, 26.68715072, 22.68009587, 30.06993318,
        20.42438251, 29.31923635, 15.89430274, 18.34042432, 16.49234431,
        23.37244115])
```

- On increasing the degree to 4 or more, it was overfitting
- Data points are limited, hence there's a high possibility of overfitting



A magnifying glass is positioned over a bar chart. The chart has blue and green bars for each quarter (Q1, Q2, Q3, Q4). A white circle with the word 'Comparisons' is centered over the chart. A green dashed line and a green dot are also present.

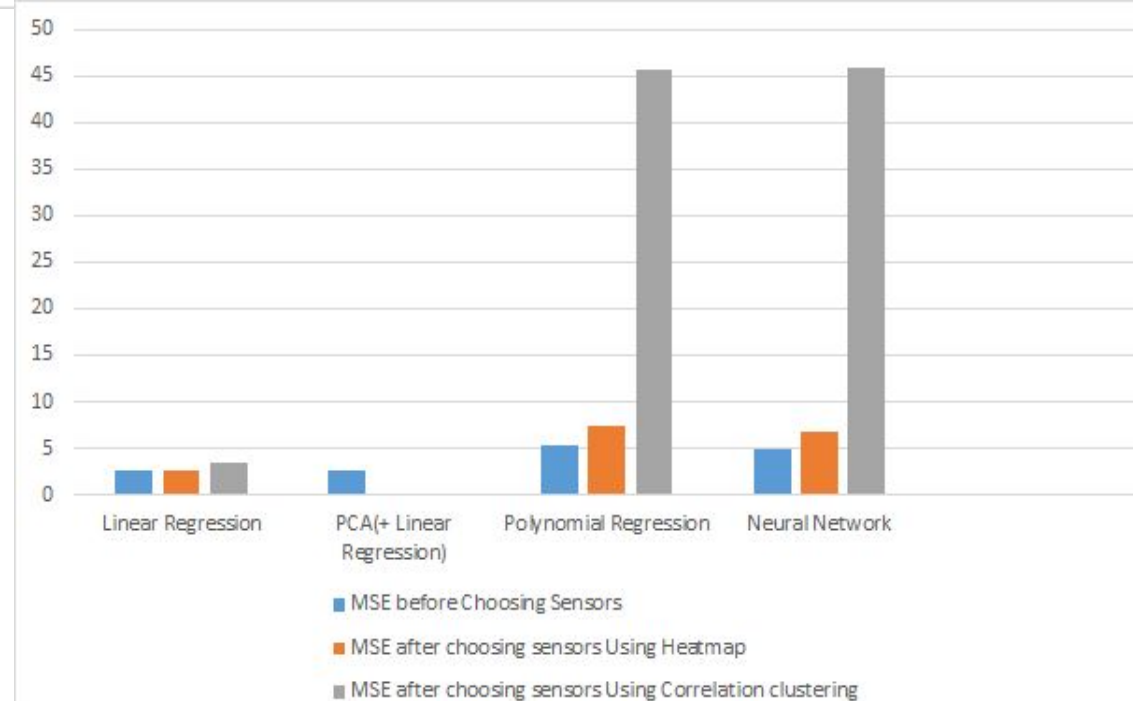
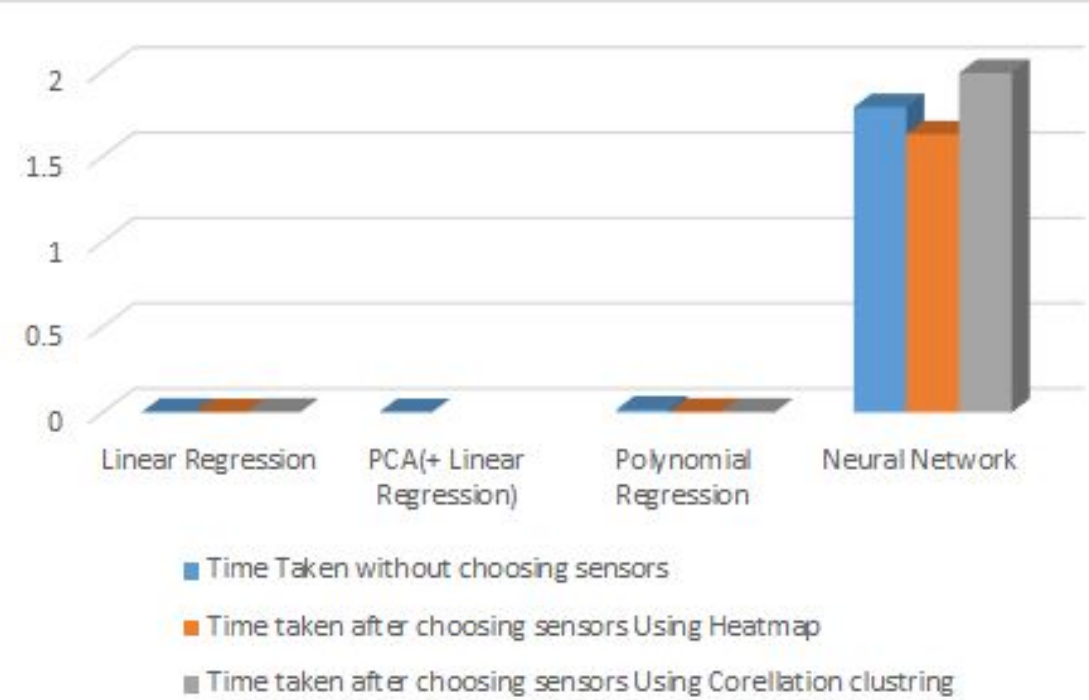
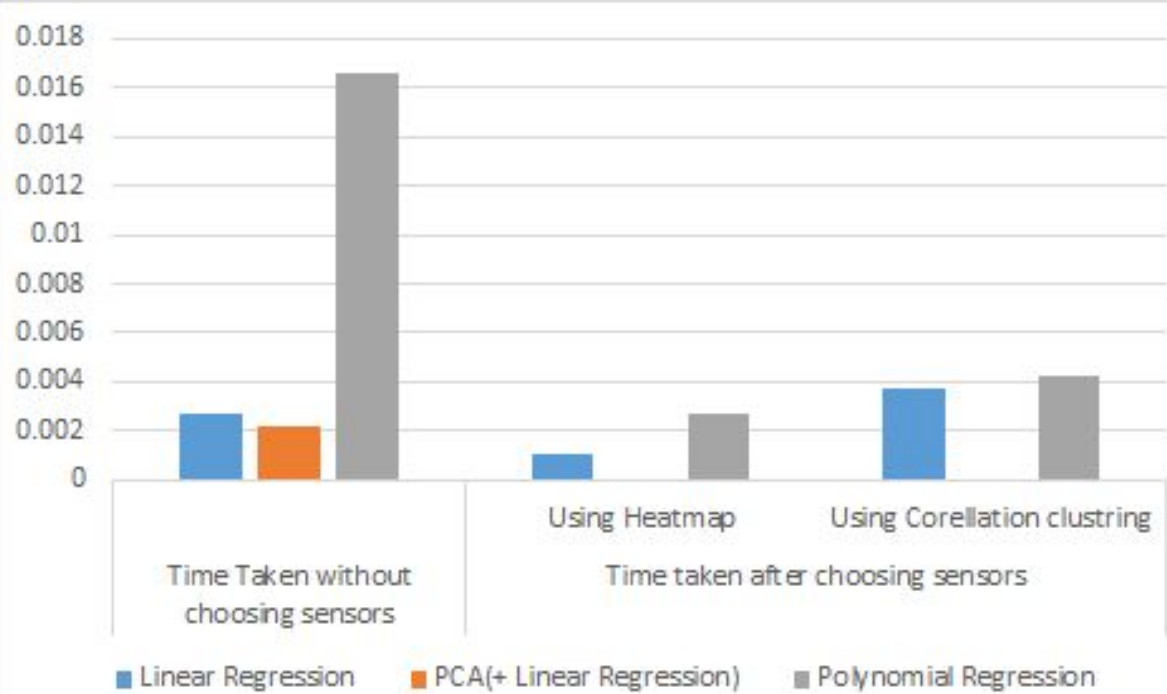
# Comparisons



Regression Name	MSE Before choosing sensors	MSE after choosing sensors		Time taken without choosing sensors	Time taken after choosing sensors.	
		Using heatmap	Using correlation clustering		Using heatmap	Using correlation clustering
Linear Regression	2.62	2.57	3.47	0.00266	0.00107	0.00378
PCA(+ linear regression)	2.67	N/A	N/A	0.00220 (+0.00097=0.00317 )	N/A	N/A
Neural Network	4.81	6.69	45.96	1.78879	1.62970	1.98920
Polynomial Regression	5.32	7.37	45.70	0.01660	0.00270	0.00423

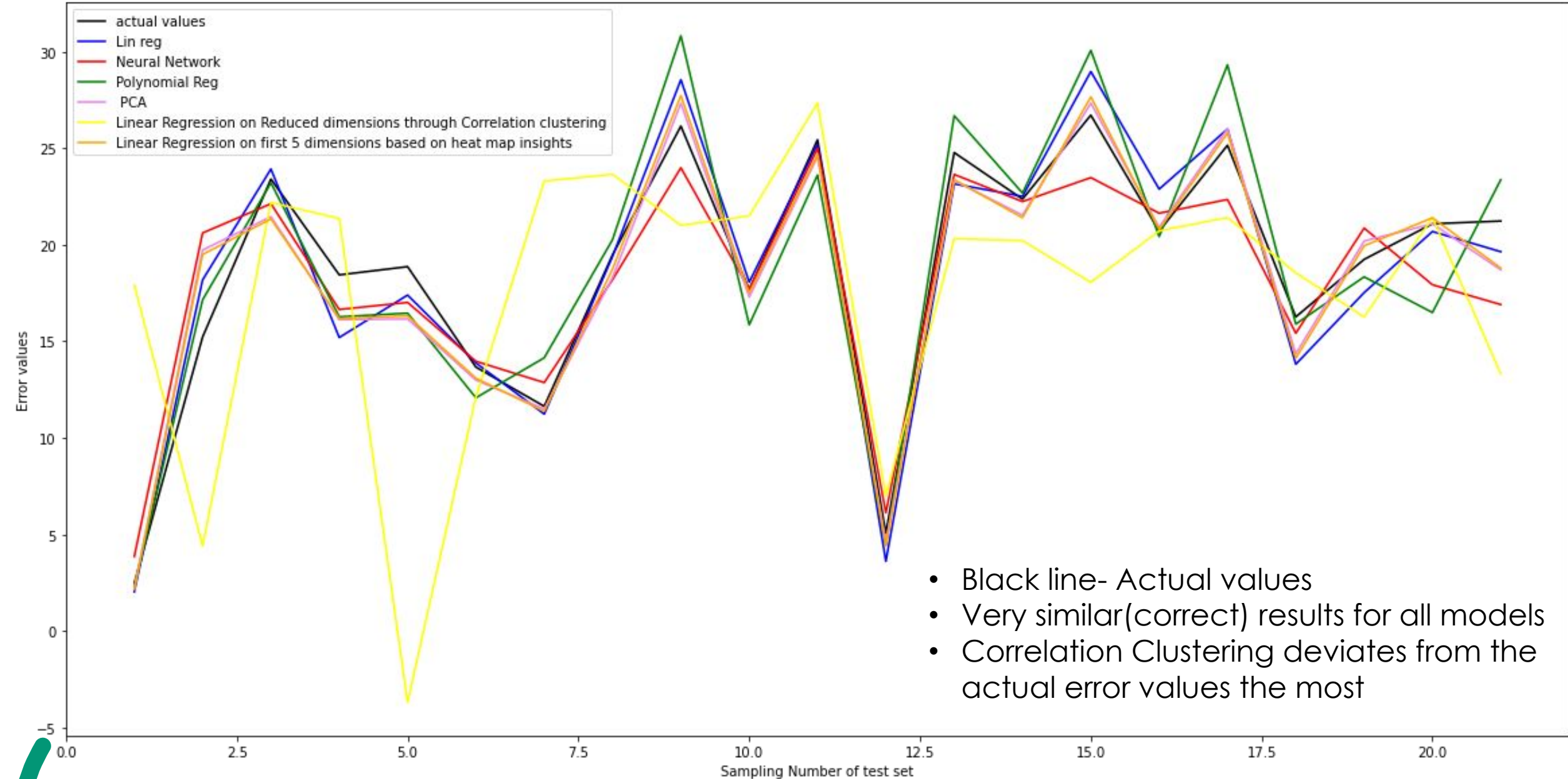
- The minimum time is for linear regression with sensors chosen
- With correlation clustering, the errors are getting increased. Mainly this could be because of non-relevance to the thermal error data. The correlation among the features does not exactly convey whether they carry similar information(temp variation) or not





# Error visualization in different models

Error vs Sampling Number (based on time) for all models



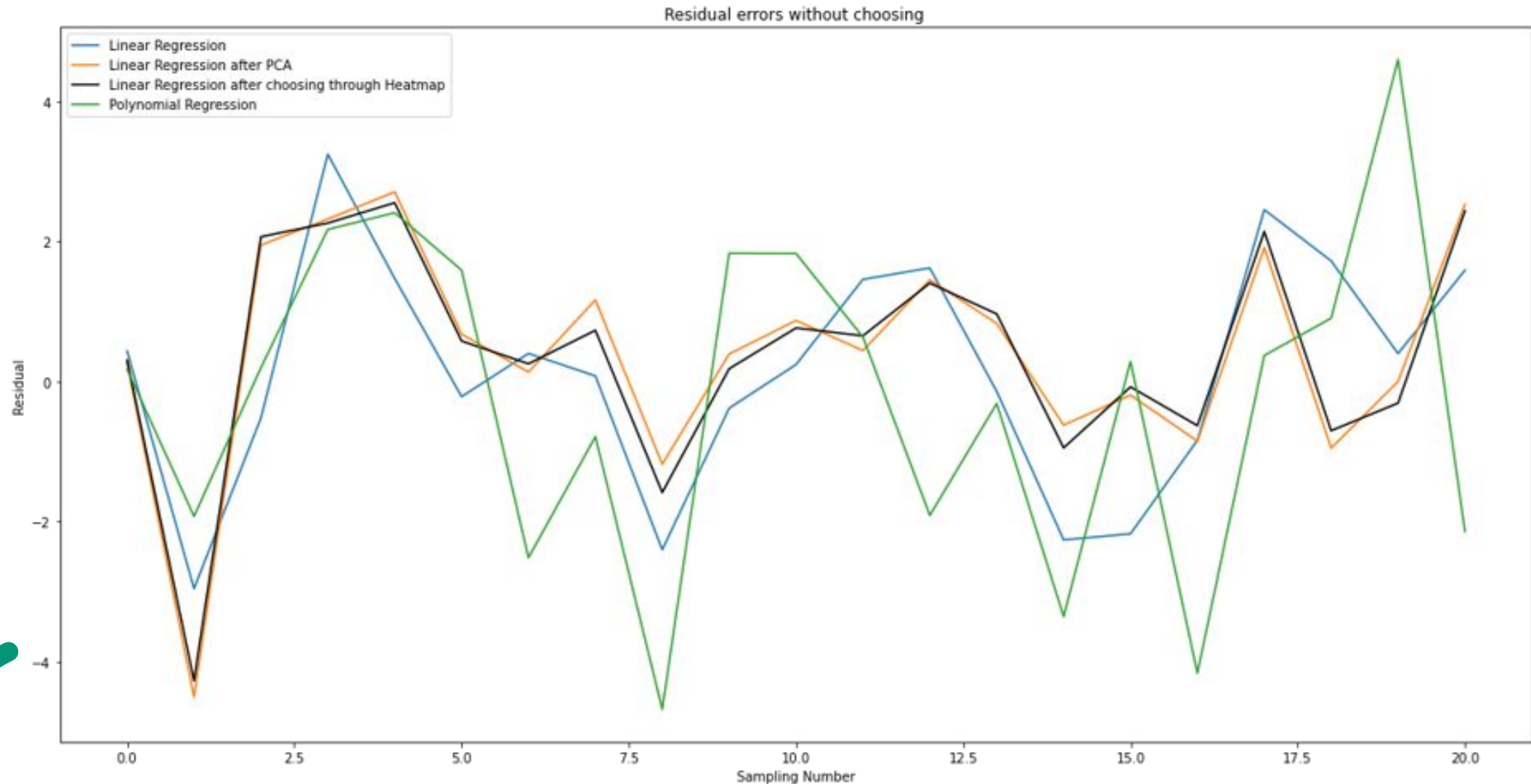



The image features a large white circle centered on a solid green background. A dashed green line, composed of several short segments, curves along the upper-left edge of the white circle. A solid green circle is positioned at the bottom-right edge of the white circle, partially overlapping it.

Application:

# Correction in Positioning during live operation

- Linear Regression with reduced sensors can be used for this



The background features several abstract geometric shapes. In the top left, there is a teal circle and a teal triangle. Below the triangle is a teal square. To the left of the square are two vertical teal dashes. In the center, there is a large green semi-circle and a teal circle. At the bottom, there is a large green circle and several teal dashes of varying lengths and orientations.

Thank You All for  
Listening!!  
We are open for  
Questions Now