

# Eigen Decomposition & PCA

An introduction to Linear Algebra (Part 2)

# Contents

- Special Matrices and Vectors
- Linear Transformation
- Eigenvectors and eigenvalues
- Eigendecomposition
- Introduction to PCA
- Steps for PCA
- Example

# Special Kinds of Matrices and Vectors

Diagonal matrix

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 8 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

Symmetric matrix

$$\begin{bmatrix} 1 & 2 & 6 \\ 2 & 8 & 4 \\ 6 & 4 & 5 \end{bmatrix}$$

- A matrix  $A_{i,j}$  is diagonal if its entries are all zeros except on the diagonal (when  $i=j$ )
- The diagonal matrix can be denoted  $\text{diag}(\mathbf{v})$  where  $\mathbf{v}$  is the vector containing the diagonal values.
- The matrix  $\mathbf{A}$  is symmetric if it is equal to its transpose. This concerns only square matrices

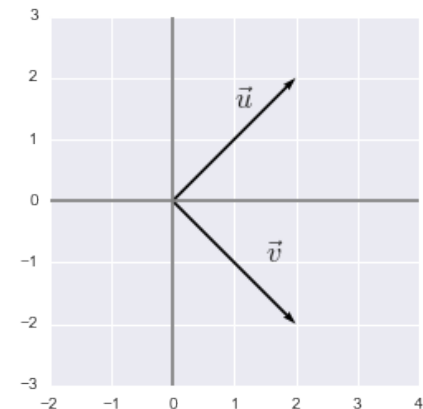
$$\mathbf{A} = \mathbf{A}^T$$

# Special Kinds of Matrices and Vectors

- Unit vectors
  - A unit vector is a vector of length equal to 1. It can be denoted by a letter with a hat:  $\hat{u}$
- Orthogonal vectors
  - Two orthogonal vectors are separated by a 90° angle. The dot product of two orthogonal vectors gives 0.

- Example:  $\mathbf{x} = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$        $\mathbf{y} = \begin{bmatrix} 2 \\ -2 \end{bmatrix}$

$$\mathbf{x}^T \mathbf{y} = [2 \quad 2] \begin{bmatrix} 2 \\ -2 \end{bmatrix} = [2 \times 2 + 2 \times -2] = 0$$



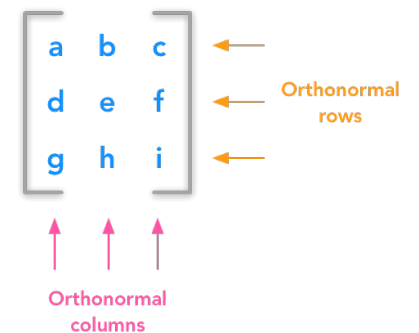
# Special Kinds of Matrices and Vectors: Orthogonal matrices

- A matrix is orthogonal if columns are mutually orthogonal and have a unit norm (norm means length or magnitude of the vector) and rows are mutually orthonormal and have unit norm.

**Property 1:**  $\mathbf{A}^T \mathbf{A} = \mathbf{I}$

**Property 2:**  $\mathbf{A}^T = \mathbf{A}^{-1}$

Orthogonal matrix



# Special Kinds of Matrices and Vectors: Proof

$$\mathbf{A} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$\mathbf{A}^T = \begin{bmatrix} a & c \\ b & d \end{bmatrix}$$

$$\begin{aligned} \mathbf{A}^T \mathbf{A} &= \begin{bmatrix} a & c \\ b & d \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} aa + cc & ab + cd \\ ab + cd & bb + dd \end{bmatrix} \\ &= \begin{bmatrix} a^2 + c^2 & ab + cd \\ ab + cd & b^2 + d^2 \end{bmatrix} \end{aligned}$$

$a^2 + c^2 = 1$  and  $b^2 + d^2 = 1$ . So we now have:

$$\mathbf{A}^T \mathbf{A} = \begin{bmatrix} 1 & ab + cd \\ ab + cd & 1 \end{bmatrix}$$

And we know that the columns are orthogonal which means that:

$$\begin{bmatrix} a & c \end{bmatrix} \begin{bmatrix} b \\ d \end{bmatrix} = 0$$

$$\mathbf{A}^T \mathbf{A} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

# Matrices as linear transformations

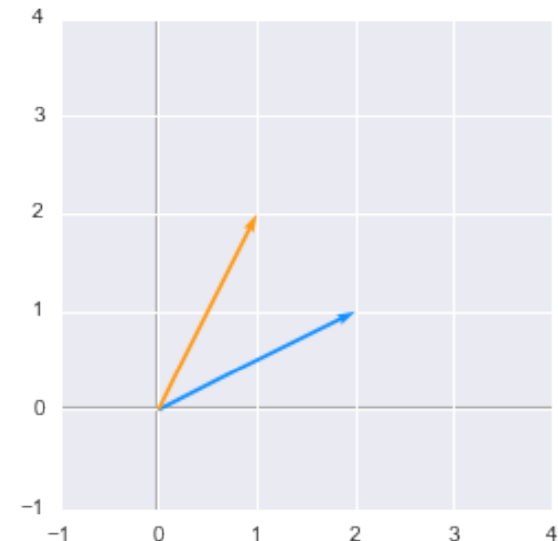
- Some matrices will rotate your space, others will rescale it.
- When we apply a matrix to a vector, we end up with a transformed version of the vector.
- When we say that we *apply* the matrix to the vector, it means that we calculate the dot product of the matrix with the vector

## Example: Transformation using matrix

- Let  $\mathbf{A} = \begin{pmatrix} -1 & 3 \\ 2 & -2 \end{pmatrix}$

and  $\mathbf{v} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$

So applying  $\mathbf{A}$  to  $\mathbf{v}$  gives us  $\begin{pmatrix} 1 \\ 2 \end{pmatrix}$



In figure the blue line shows the older vector and orange shows the new vector

- Hence, matrix  $\mathbf{A}$  transformed the vector with an angle.



# Using matrices to describe the system

- If the transformation of the initial vector gives us a new vector that has the exact same direction and the scale is different , this special vector is called an *eigenvector* of the matrix.
- Mathematically, we have the following equation:

$$Av = \lambda v$$

- $v$ - is the eigenvector and
- $\lambda$  - is the eigenvalue

# Example: Eigenvector and Eigenvalues

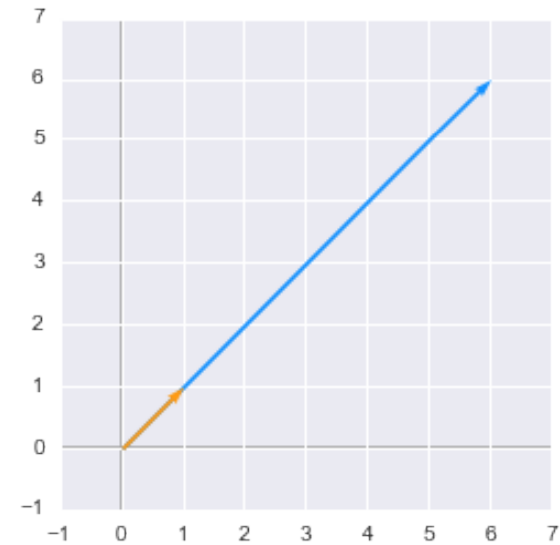
$$\mathbf{A} = \begin{bmatrix} 5 & 1 \\ 3 & 3 \end{bmatrix}$$

$$\mathbf{v} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

- Applying  $\mathbf{A}$  to  $\mathbf{v}$  gives us

$$\begin{bmatrix} 5 & 1 \\ 3 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ 6 \end{bmatrix}$$

- Hence  $\lambda$  is 6



# Find eigenvalues and eigenvectors in Python

- Numpy provides a function (`np.linalg.eig( )`) returning eigenvectors and eigenvalues.
- Two arrays are returned as a result from the function such that:
  - the first array corresponds to the eigenvalues and
  - the second to the eigenvectors concatenated in columns

# Eigendecomposition

- Let  $\mathbf{V}$  be a matrix such that all eigenvectors of a matrix  $\mathbf{A}$  can be concatenated in a matrix with each column corresponding to each eigenvector.
- The vector  $\boldsymbol{\lambda}$  can be created from all eigenvalues.
- Then the eigen decomposition is given by:

$$\mathbf{A} = \mathbf{V} \cdot \text{diag}(\boldsymbol{\lambda}) \cdot \mathbf{V}^{-1}$$

- For a symmetric matrix, the eigenvectors are orthogonal.