## Assignment 5--5

Solution) Here there are two Casher given. One is the linear approximation of ni le second is non-linear approximation of xi.

Argument: > Second statement is true i.e. EL(V)>, EN(V) i.e. non-linear approximation of X; will give less or equal execut as compared to linear approximetion of Xi

Reason:

Case 1:> linear approximation of x will the always choose the first Kvalues of V corresponding to the first K eigenvalues for all points xi.

Case 2: 7 Non Great approximation of x doesn't make such ascumption of chasing first k values of v corresponding to the first k eigen values for all points vi. Infact from the equation,

di= argmin ||xi-Vcill2

We find Ci (with constraint that it can atmost have knon-zero elements), such that difference between xil VC; is minimum.

So non-approximation also to calculate xi gives us flexibility to Choose different set of k columns of V for different points. Hence di choosen in such fashion will give minimum reconstruction etror.

flend, we have proven our argument.

@ first Find the ai=VTxi. xi is the eigen cofficient it has d values. Value of a; i.e. a; denotes the projection value of x; on cxis(vector)i.

(b) We will find (: such that it has at most k largest value in

di and rest to O. (Greedy approch).

O For finding ci what we can do is create more heap with node having value (dij, j), where j de notes index of xij. This can be done

in o(d) 6m. 1 for l= 1 tok, we will find recondruction error te. ree= [|xi-Vce|| where Colas il largest absolute value or (use moxteap for this de

Operation ||xi-Xce||2 will take O(d2.7) for multiplication. O(d) for substaction & summition ... total is O(d2.71)

2. for k terms it is O(kd2.7)

Doing for every x; will take O(n. Kd2.7)

di; denotes the projection value on it axis. The smaller the value ire. tending to zero it means we can drop that axis because it will not Impact or introduce much error after reconstruction.

So its save to drop that axis.