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1  library ieee;
2  use ieee.std_logic_1164.all;
3  use ieee.numeric_std.all;
4
5  Entity MOORE_SM IS Port
6  (
7      clk_input, rst_n, Extender_en, Extend_tog          : in std_logic;
8      leds                                              : in std_logic_vector(3
9  downto 0);
10     shift_reg_en, shift_reg_dir, Extender_out, Grappler_en : out std_logic
11 );
12 END ENTITY;
13
14 Architecture SM of MOORE_SM is
15
16     TYPE STATE_NAME IS (Start,Extending,Extender_hold, Extended, Retracting, Retracter_hold,
17 Retracted); -- All the STATE_NAME values which are start, extender extending, extender
18 hold, fully extended, retracting, retractor hold and fully retracted
19
20     SIGNAL current_state, next_state : STATE_NAME; -- signals of type STATE_NAME
21
22     BEGIN
23
24     -----
25     --State Machine:
26     -----
27
28     -- REGISTER LOGIC PROCESS:
29
30     Register_Section: PROCESS (clk_input, rst_n, next_state) -- this process synchronizes the
31 activity to a clock
32 BEGIN
33     IF (rst_n = '0') THEN
34         current_state <= Start;
35     ELSIF(rising_edge(clk_input)) THEN
36         current_state <= next_State;
37     END IF;
38 END PROCESS;
39
40     -- Here Extend_tog is the input from the push button pb(1)
41
42     -- TRANSITION LOGIC PROCESS
43
44     Transition_Section: PROCESS (Extender_en, Extend_tog, leds, current_state) -- Sensitivity
45 list
46 BEGIN
47     CASE current_state IS
48     WHEN Start =>
49         next_state <= Start;
50         IF(Extender_en = '1' AND Extend_tog='0') THEN
51             next_state <= Extending; -- If the push button is pressed and extender
52 enable is 1, then the next state should be extending
53         END IF;
54
55     WHEN Extending =>
56         next_state <= Extending;
57         IF(leds = "1111") THEN
58             next_state <= Extended; -- If the leds(7..4) are all lighted up, then that
59 means the extender is fully extended and we need to move to the extended state
60         ELSIF (Extend_tog = '1') THEN
61             next_state <= Extender_hold; -- If we release the push button midway, then
62 we should move to the hold state
63         END IF;
64
65     WHEN Extender_hold =>
66         next_state <= Extender_hold;
67         IF(Extend_tog='0') THEN
68             next_state <= Extending; -- If we again press the push button, it should
69 resume extending
70         END IF;
71
72     WHEN Extended =>

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68         next_state <= Extended;
69         IF(Extend_tog='0') THEN
70             next_state <= Retracting; -- Here when the push button is presses, it would
retract now
71         END IF;
72
73         WHEN Retracting =>
74             next_state <= Retracting;
75             IF(leds = "0000") THEN
76                 next_state <= Retracted; -- If all the leds are down, then that means the
extender has retracted so we move to that state
77             ELSIF (Extend_tog = '1') THEN
78                 next_state <= Retracter_hold; -- Similarly if we release the button midway,
it is now in hold state
79             END IF;
80
81             WHEN Retracter_hold =>
82                 next_state <= Retracter_hold;
83                 IF(Extend_tog='0') THEN
84                     next_state <= Retracting; -- If the button is pressed again, it should keep
on retracting
85                 END IF;
86
87                 WHEN Retracted =>
88                     next_state <= Retracted;
89                     IF(Extend_tog='0' AND Extender_en = '1') THEN
90                         next_state <= Extending; -- After it has been retracted and we press the
push button along with the enabler being 1, it should start extending again
91                     END IF;
92                 END CASE;
93             END PROCESS;
94
95 -- DECODER SECTION PROCESS
96 Decoder_Section: PROCESS (current_state)
97
98 BEGIN
99     CASE current_state IS
100     WHEN Start =>
101         shift_reg_en <= '0'; -- Everything should be 0 because we don't want to do anything
102         shift_reg_dir <= '0';
103         Extender_out <= '0';
104         Grappler_en <= '0';
105
106     WHEN Extending => -- Here since leds should increase to the right,
shift_reg_dir is 1 along with enable and the extender will be out
107         shift_reg_en <= '1';
108         shift_reg_dir <= '1';
109         Extender_out <= '1';
110         Grappler_en <= '0';
111
112     WHEN Extended => -- when it is extended, we can use the grappler, so
grappler_en is 1
113         shift_reg_en <= '0';
114         shift_reg_dir <= '0';
115         Extender_out <= '1';
116         Grappler_en <= '1';
117
118     WHEN Retracting => -- while retracting the leds will go down in the left
direction so shift_reg_dir is 0
119         shift_reg_en <= '1';
120         shift_reg_dir <= '0';
121         Extender_out <= '1';
122         Grappler_en <= '0';
123
124     WHEN Retracted => -- after the extender has been retracted, everything should
be 0 because we cannot do anything
125         shift_reg_en <= '0';
126         shift_reg_dir <= '0';
127         Extender_out <= '0';
128         Grappler_en <= '0';
129
130     WHEN others => -- In all other cases, the extender will be open so its value
is 1
131         shift_reg_en <= '0';
132         shift_reg_dir <= '0';
133         Extender_out <= '1';

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134         Grapp1er_en <= '0';
135     END CASE;
136 END PROCESS;
137
138 END ARCHITECTURE SM;
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