A Deep-Learning-Based Seismic Hazard Assessment System from Geodetic Big Data

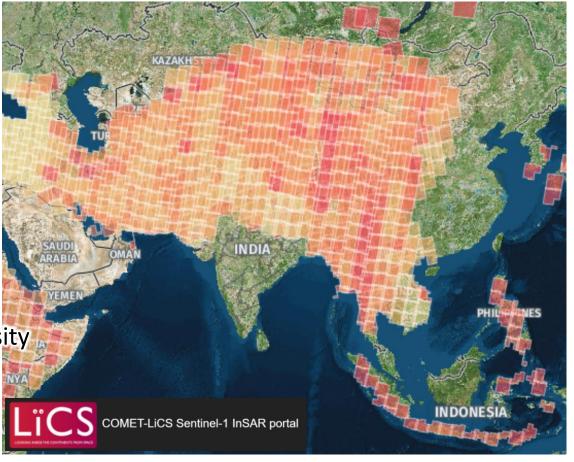
2018 MOST (Talwan) - DST (India) Joint Research

González, PJ; Walters, RJ; Hatton, EL; Spaans, K; McDougall, A; Hooper, AJ; Wright, TJ LiCSAR: Tools for automated generation of Sentinel-1 frame interferograms AGU Fall Meeting, 2016

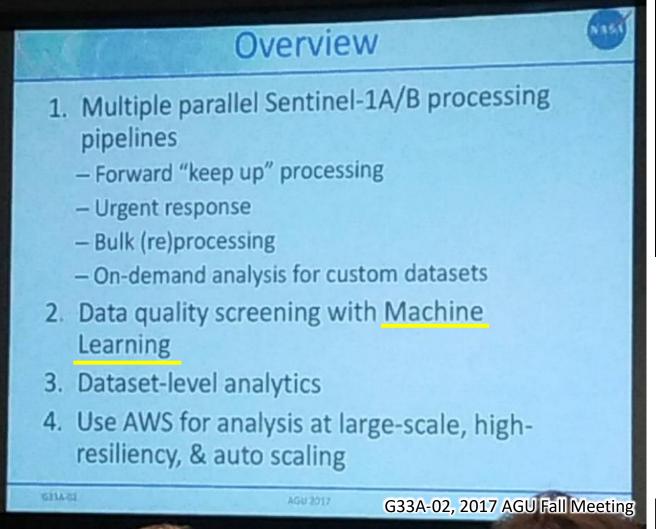
Kuo-En Ching (景國恩)

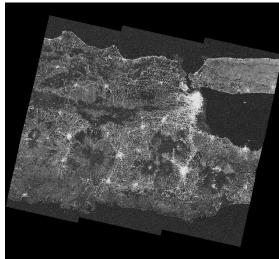
Department of Geomatics

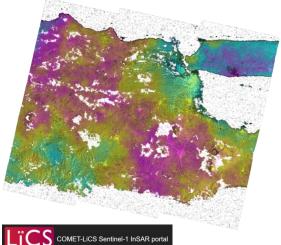
National Cheng Kung University



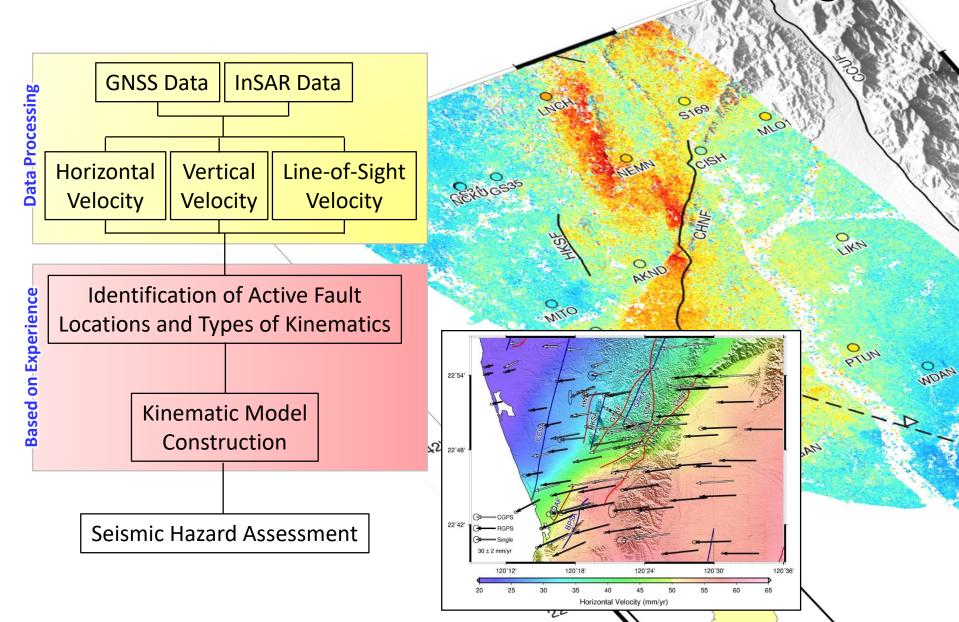
Recent Advances in InSAR Processing and Cloud Computing



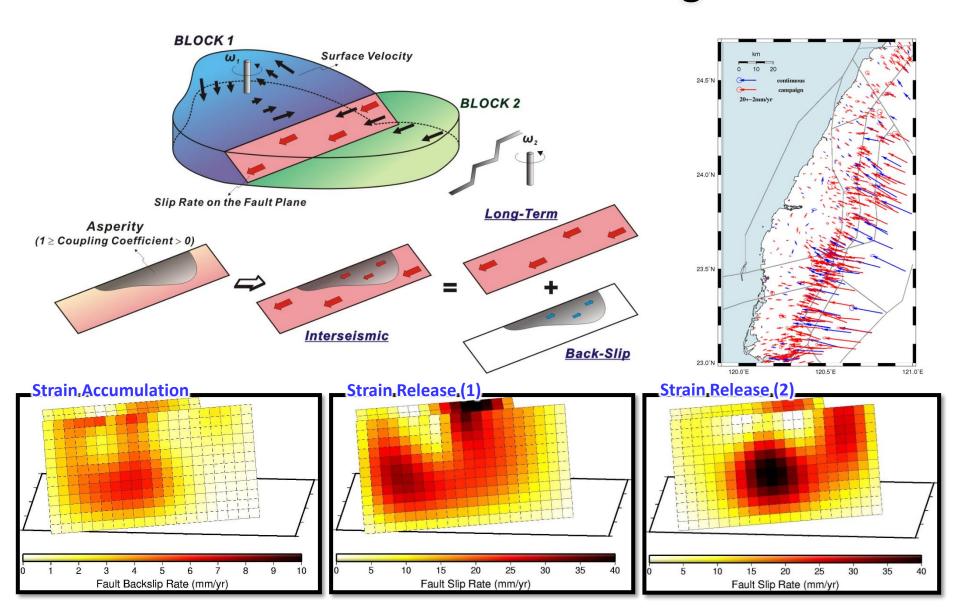




Seismic Hazard Assessment from Geodetic Big Data

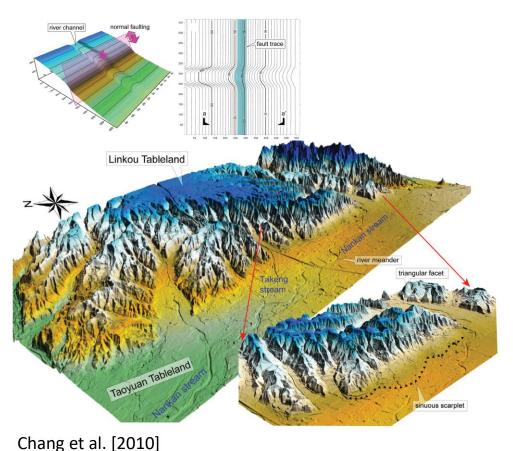


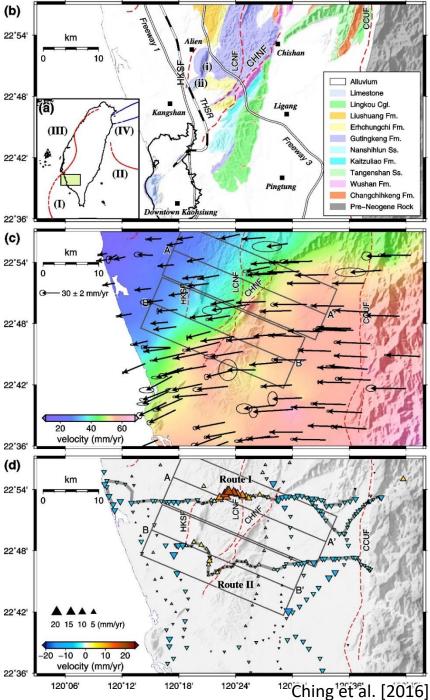
Kinematic Model Construction and Seismic Hazard Assessment from Geodetic Big Data



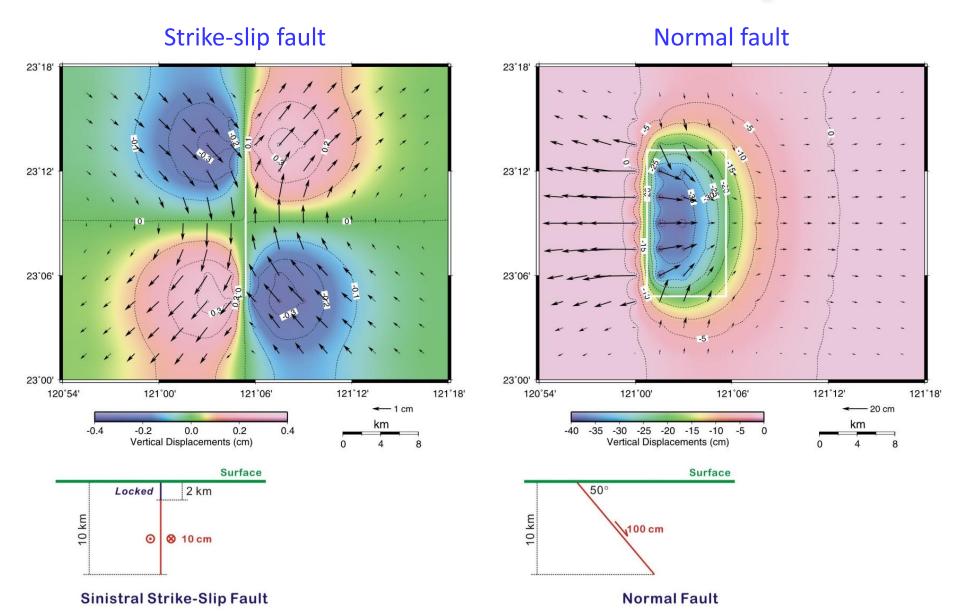
Identification of Active Fault Locations and Types of Kinematics

- 1. Geological Maps
- 2. Geomorphological Features
- 3. Patterns of Surface Deformation



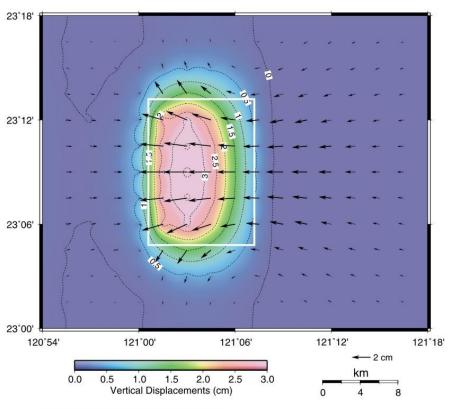


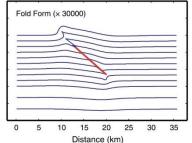
Surface Deformation Patterns Caused by Faults



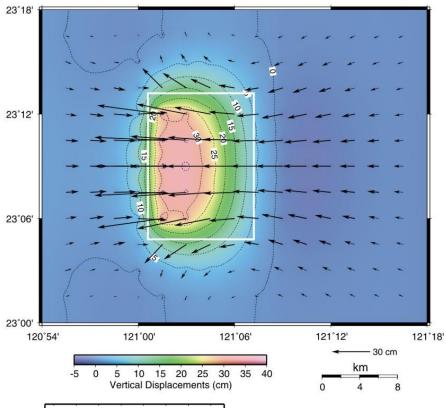
Surface Deformation Patterns Caused by Faults

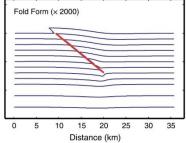
Reverse fault (no rupture to the surface)

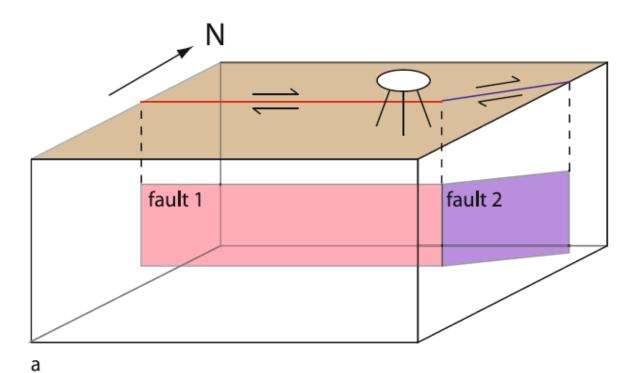


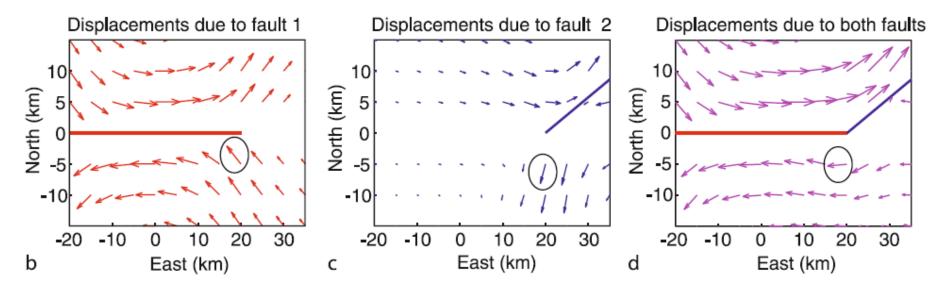


Reverse fault (rupture to the surface)

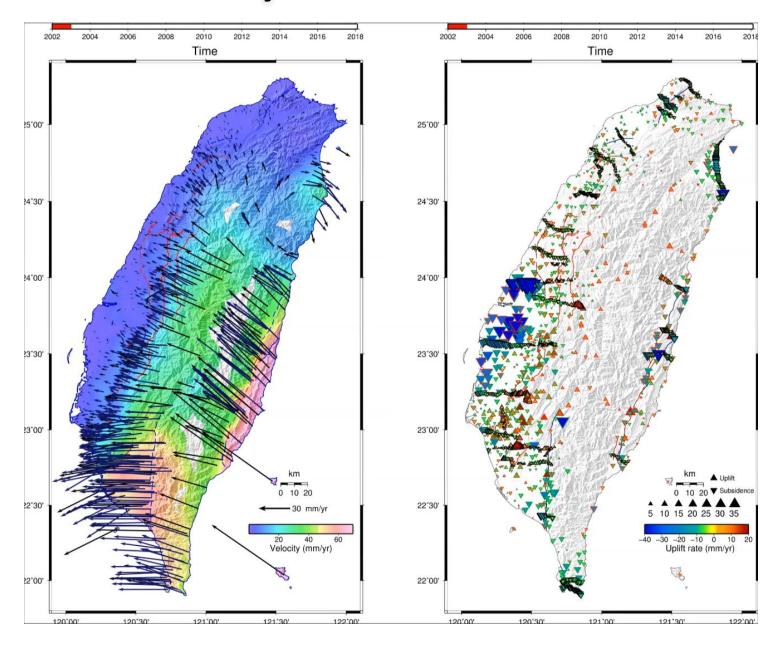




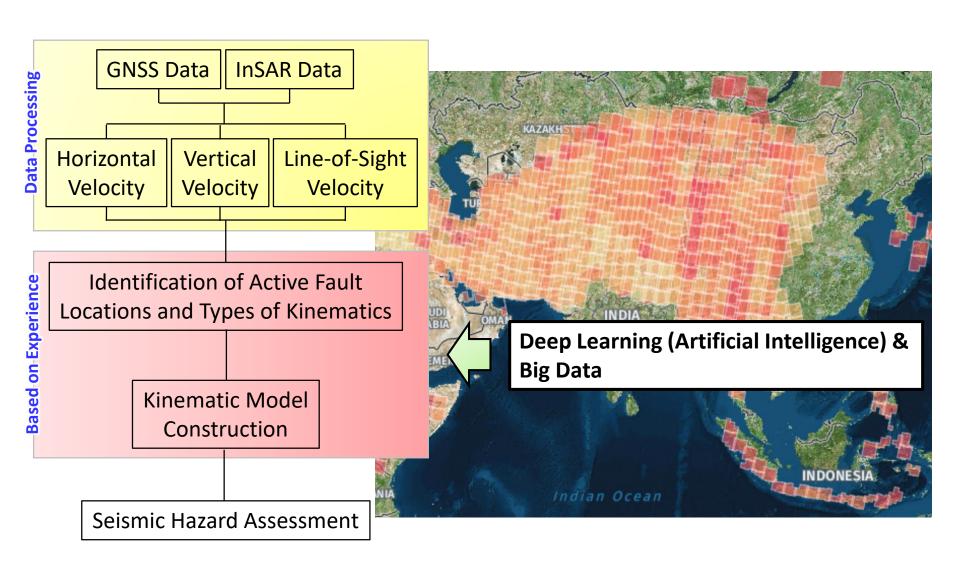




Surface Velocity Field in Taiwan 2002-2017



Seismic Hazard Assessment from Geodetic Big Data



Proposed Methods/Procedures

Learning: Synthetic Cases

Deformation pattern identification from InSAR and other geodetic observations

Caused by different types of single faults

Caused by the combination of different fault types

Including the deformation patterns caused by the deep-seated landslides

Linear pattern identification from DEM

Applications: Case Studies

Case Study in Taiwan – Test

Case Study in Indian Himalaya and other areas – Application

Future Works: Time-Dependent Studies

Advances of Engineering Geodesy and Artificial Intelligence in Monitoring of Movements and Deformations of Natural and Man-Made **Structures**

of Geodesy Symposia 139, DOI 10.1007/978-3-642-37222-3_64,

