

Ayush Kumar

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EDUCATION

Manipal Institute of Technology, Manipal

Oct '20 - May '24

BTech Computer and Communication Engineering (minor in Computational Mathematics)

Cumulative GPA: **9.61**, won Achievers' Scholarship, ranked 1st out of 116 in branch by CGPA

EXPERIENCE

SAP Labs

June '23 - August '23

Summer Intern

- Built an interactive dashboard to streamline internal communications and event management workflows for SAP Labs India
- Utilized UI5 and NodeJS to integrate custom APIs, implementing features such as comments, status tracking and attachments on the application deployed on SAP's BTP platform
- Built an LLM-based context aware conversational agent to answer queries about employee benefits
- Implemented a pipeline to scrape SAP-internal sites to collect policy information and store vectorized data in Flask and Python backend

CiSTUP, Indian Institute of Science (IISc)

Dec '22 - Feb '23

Research Intern

- Studied and implemented mathematical models to predict and simulate congestion patterns on Bangalore's BMTTC bus network
- Parallelized a pipeline for route assignment algorithm using OpenMP, and achieved $\approx 68\times$ speedup, for 100,000+ queries
- Developed a logit-based choice model to simulate commuter behaviour for optimal route selection
- Co-authored paper 'A Scalable Framework for Public Transit Assignment with Explicit Capacity Constraints', which was accepted at the Dynamic Traffic Assignment Symposium '23, Evanston, USA and at AI Impact '23, IIT Bombay

Project MANAS

May '21 - Present

Artificial Intelligence Team Member

- MIT Manipal's official AI and Robotics Team, we build and research autonomous ground/aerial vehicles.
- Developed a surveillance area coverage path planning algorithm for an unmanned aerial vehicle (UAV), using a sweep line approach to solve the watchman route problem from computational geometry
- Represented India at AUVSI SUAS '22, team ranked 2nd in Flight Review, 10th in Technical Design

PROJECTS

FlockSim C++, OpenGL, GLMath

Built an interactive simulator to visualize bird flocking, using the Boids algorithm. Implemented spatio-temporal models for disease spread

Vacuum BotNav C++, ROS

A path planner for autonomous vacuum cleaners to navigate and clean a room with obstacles, given a map - generates an optimal heuristic-based path using A* search, after discretizing map into cells

Thumbs Up: Hand Gesture Recognition PyTorch, OpenCV, Python

Track hands in a video frame and identify gestures as defined by the HaGRID dataset - robust preprocessing pipeline implemented with OpenCV to extract regions-of-interest, reducing false positives

TECHNICAL STRENGTHS

Programming Languages

Python, C++/C, Java, NodeJS, SQL

Data Analysis

PyTorch, TensorFlow, OpenCV, Matplotlib

Software Tools

CMake, Bash, Git, OpenGL, L^AT_EX

Relevant Coursework

Analysis of Algorithms, Graph Theory, Computational Linear Algebra, Data Mining