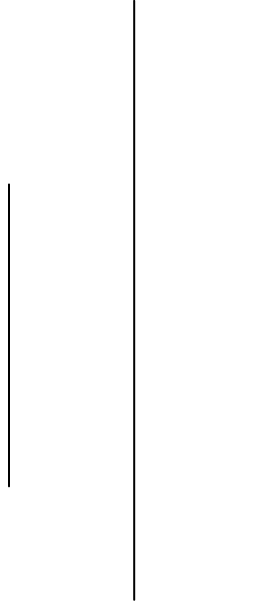


KATHMANDU UNIVERSITY

DHULIKHEL KAVRE



COEG-304: Instrumentation and Control

Lab Sheet No. 1

SUBMITTED BY

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Level: UNG

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Date of Submission:

....../....../2018



KATHMANDU UNIVERSITY
School of Engineering
Department of Electrical and Electronics Engineering

Instrumentation and Control Lab I

Introduction to MATLAB

1.1 Matrix operation

Example-1

For the matrix equation below, $AX = B$, determine the vector X .

$$\begin{bmatrix} 4 & -2 & -10 \\ 2 & 10 & -12 \\ -4 & -6 & 16 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -10 \\ 32 \\ -16 \end{bmatrix}$$

Ans:

```
>>B=[-10;32;-16];  
>> A=[4 -2 -10; 2 10 -12; -4 -6 16];  
>> X=A\B
```

X =

```
2.0000  
4.0000  
1.0000
```

1.2 Inverse of a matrix

Example-2

Use the **inv** function to determine the inverse of matrix A in Example 1.1 and then determine X . The following statements

Ans:

```
>> Y=inv(A)
```

Y =

```
2.2000  2.3000  3.1000  
0.4000  0.6000  0.7000  
0.7000  0.8000  1.1000
```

```
>> X=Y*B
```

X =

2
4
1

1.3 Roots of polynomial

Example-3

Find the roots of the following polynomial.

$$s^6 + 9s^5 + 31.25s^4 + 61.25s^3 + 67.75s^2 + 14.75s + 15$$

Ans:

P=[1 9 31.25 61.25 67.75 14.75 15]

P =

1.0000 9.0000 31.2500 61.2500 67.7500 14.7500 15.0000

>> r=roots(P)

r =

-4.0000 + 0.0000i
-3.0000 + 0.0000i
-1.0000 + 2.0000i
-1.0000 - 2.0000i
-0.0000 + 0.5000i
-0.0000 - 0.5000i

Example-4

The roots of a polynomial are -1 , -2 , $-3 \pm j4$. Determine the polynomial equation.

Ans:

>> Q=[-1 -2 -3+j*4 -3-j*4]

Q =

-1.0000 + 0.0000i -2.0000 + 0.0000i -3.0000 + 4.0000i -3.0000 - 4.0000i

>> p=poly(Q)

p =

1 9 45 87 50

1.4 X-Y Plot

Example-5

Create a linear X - Y plot for the following variables.

x	0	0.5	1.0	1.5	2.0	2.5	3.0	3.5	4.0	4.5	5.0
y	10	10	16	24	30	38	52	68	82	96	123

Ans:

```
>> X=[0:0.5:5]
```

X =

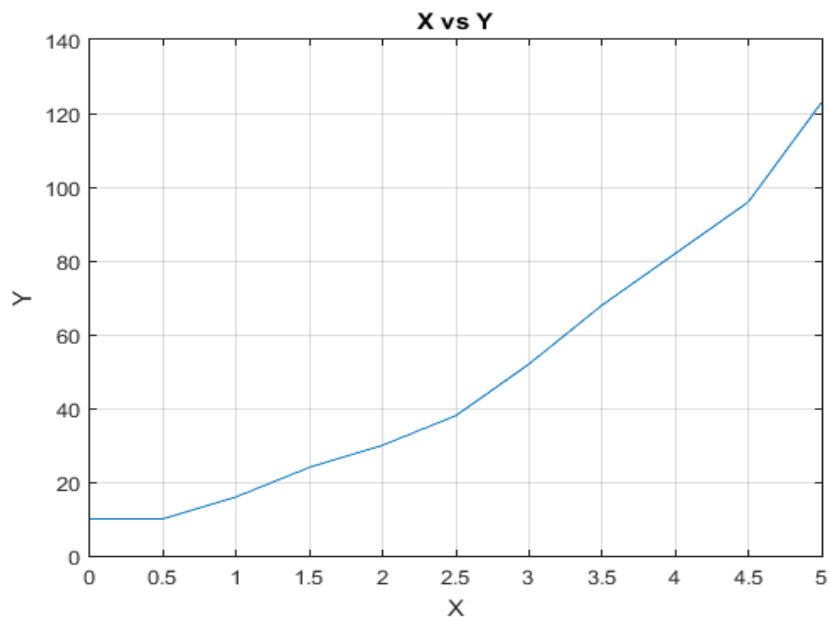
```
    0    0.5000    1.0000    1.5000    2.0000    2.5000    3.0000    3.5000    4.0000    4.5000  
5.0000
```

```
>> Y=[10 10 16 24 30 38 52 68 82 96 123]
```

Y =

```
    10    10    16    24    30    38    52    68    82    96   123
```

```
>> plot(X,Y), grid, xlabel('X'), ylabel('Y'), title('X vs Y')
```



Example-6

Plot function $y = 1 + e^{-2t} \sin(8t - \pi/2)$ from 0 to 3 seconds. Find the time corresponding to the peak value of the function and the peak value. The graph is to be labeled, titled, and have grid lines displayed.

Remember to use `.` for the element-by-element multiplication of the two terms in the given equation. The command `[cp, k] = max(c)` returns the peak value and the index `k` corresponding to the peak time. We use the following commands.

Ans:

```
>> t=0:0.005:3;  
>> c=1+exp(-2*t).*sin(8*t-pi/2);  
>> [cp,k]=max(c)
```

cp =

1.4702

k =

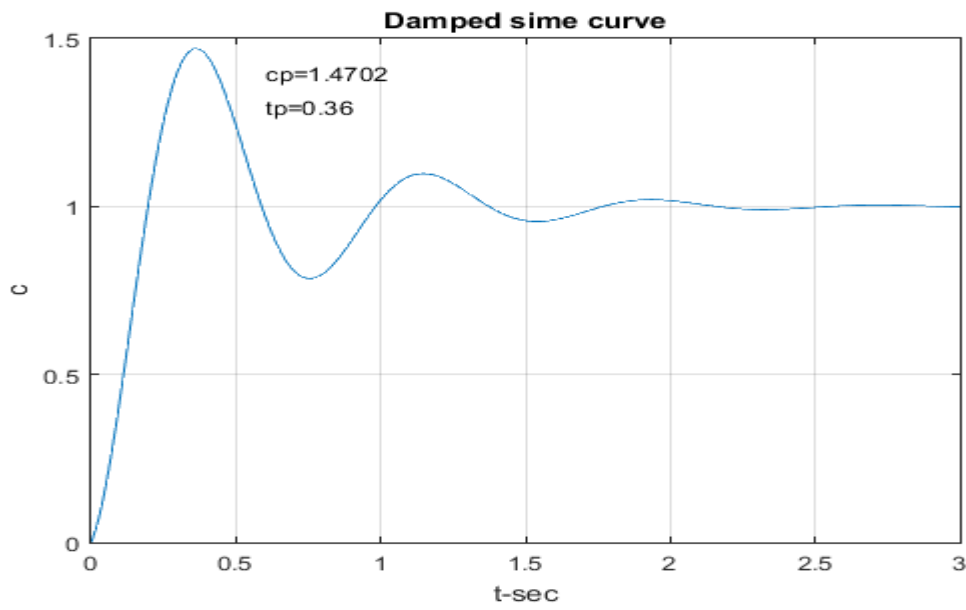
73

```
>> tp=t(k)
```

tp =

0.3600

```
>> plot(t,c), xlabel('t-sec'),ylabel('c'),grid;  
title('Damped sine curve');  
text(0.6,1.4,['cp=', num2str(cp),  
tp=0.36])
```



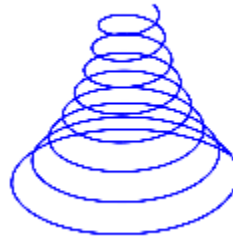
1.5 Three-Dimensional Plots

Example-7

Plot of a parametric space curve

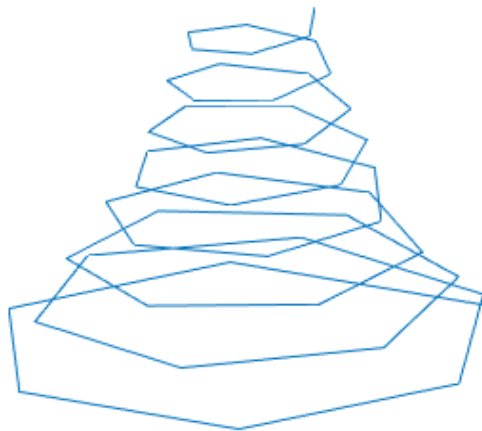
$$x(t) = e^{-0.03t} \cos t, \quad y(t) = e^{-0.03t} \sin t, \quad z(t) = t$$

```
t= 0:0.1:16*pi;  
x=exp(-0.03*t).*cos(t);  
y=exp(-0.03*t).*sin(t);  
z=t;  
plot3(x, y, z), axis off
```



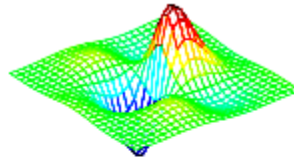
Ans:

```
t=0:0.1:16*pi;  
x=exp(-0.03*t).*cos(t);  
y=exp(-0.03*t).*sin(t);  
z=t;  
plot3(x,y,z),axis off
```



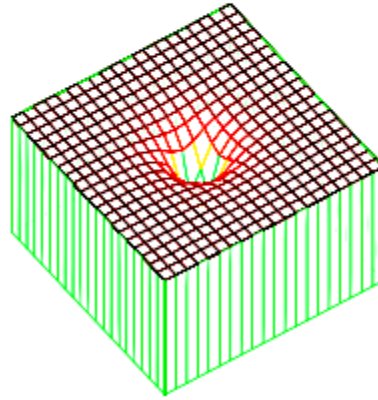
Plot of function $z = \sin x \cos y e^{-(x^2+y^2)^{0.5}}$
using mesh

```
t = -4:0.3:4;
[x,y] = meshgrid(t,t);
z = sin(x).*cos(y).*exp(-(x.^2+y.^2).^0.5);
mesh(x,y,z), axis off
```



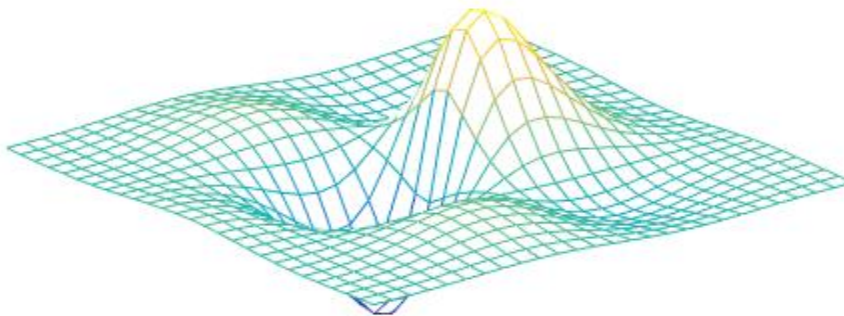
Plot of function $z = -0.1/(x^2+y^2+1)$
using meshz

```
x = -3:0.3:3; y=x;
[x,y] = meshgrid(x,y);
z = -0.1./(x.^2+y.^2+1);
meshz(z), axis off
view(-35, 60)
```



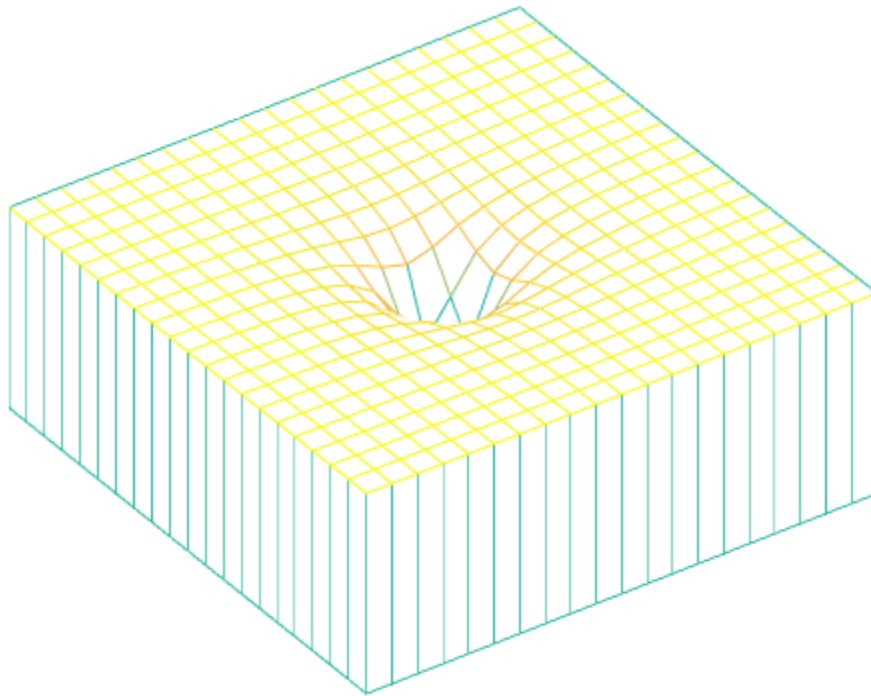
Ans:

```
t=-4:0.3:4;
[x,y]=meshgrid(t,t);
z=sin(x).*cos(y).*exp(-(x.^2+y.^2).^0.5);
mesh(x,y,z), axis off
```

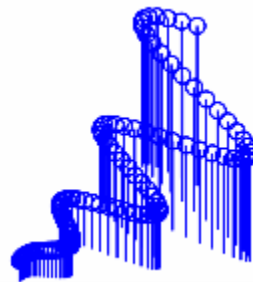


Ans:

```
x=-3:0.3:3;  
y=x;  
[x,y]=meshgrid(x,y);  
z=-0.1./(x.^2+y.^2+1);  
meshz(z), axis off, view(-35,60)
```

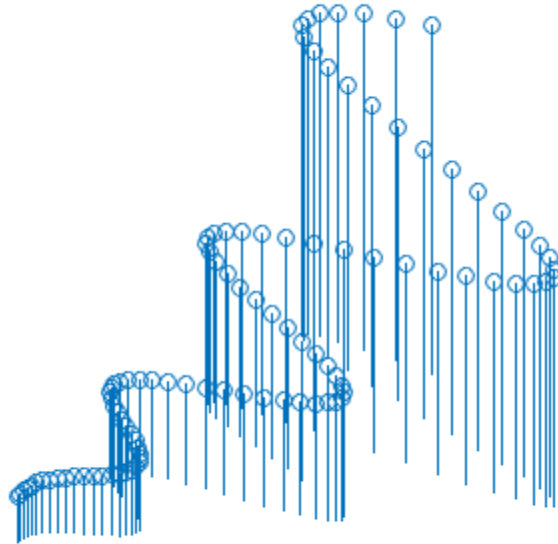


Discrete plot of
 $x=t, y=t \cos t, z=e^{0.1t}$
using stem3
t=0:.2:20;
x=t; y=t.*cos(t);
z=exp(0.1*t);
stem3(x,y,z), axis off



Ans:

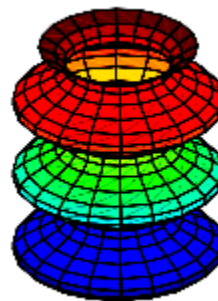
```
t=0:0.2:20;  
x=t;  
y=t.*cos(t);  
z=exp(0.1*t);  
stem3(x,y,z), axis off
```



Cylindrical surface created by
 $p=3+\sin t$

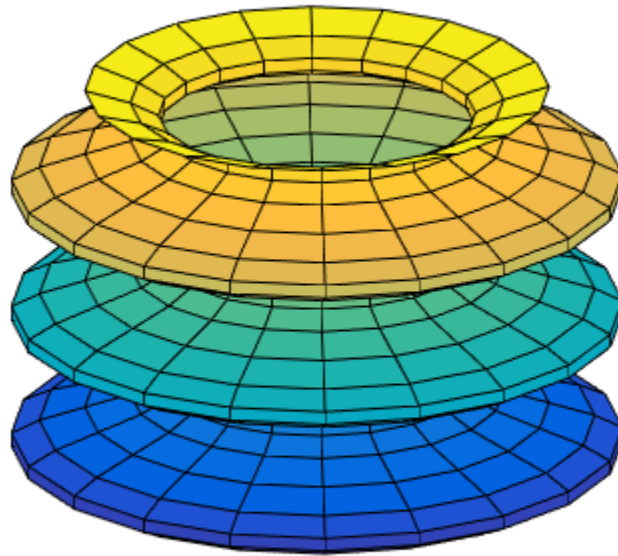
using cylinder function

```
t=0:pi/5:6*pi;  
p=3+sin(t);  
cylinder(p), axis off
```



Ans:

```
t=0:pi/5:6*pi;  
p=3+sin(t);  
cylinder(p), axis off
```

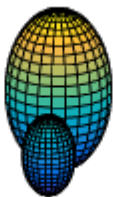


Plot of a unit sphere and a scaled sphere
using sphere function
`[x,y,z]=sphere(24);`
`subplot(2,2,2), surf(x-2, y-2, z-1);`
`hold on`
`surf(2*x, 2*y, 2*z);`
`axis off`



Ans:

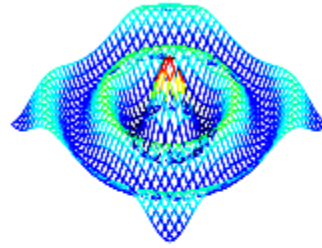
`[x,y,z]=sphere(24);`
`subplot(2,2,2), surf(x-2, y-2, z-1);`
`hold on`
`surf(2*x, 2*y, 2*z);`
`axis off`



Cartezian plot of Bessel function

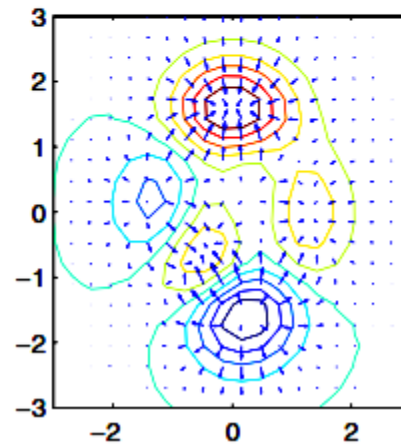
$$J_0 \sqrt{x^2 + y^2} \quad -12 < x < 12, \quad -12 < y < 12$$

```
[x,y]=meshgrid(-12:.7:12, -12:.7:12);
r=sqrt(x.^2+y.^2);z= bessel(0,r);
m=[-45 60]; mesh(z,m), axis off
```



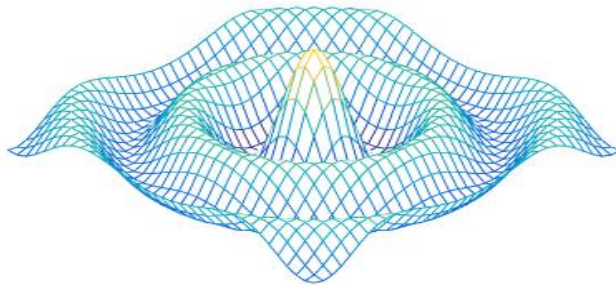
Contour lines and directional vectors
using contour and quiver functions

```
[x,y,z]=peaks(20);
[nx, ny]=gradient(z,1,1);
contour(x,y,z,10)
hold on
quiver(x,y,nx,ny)
```



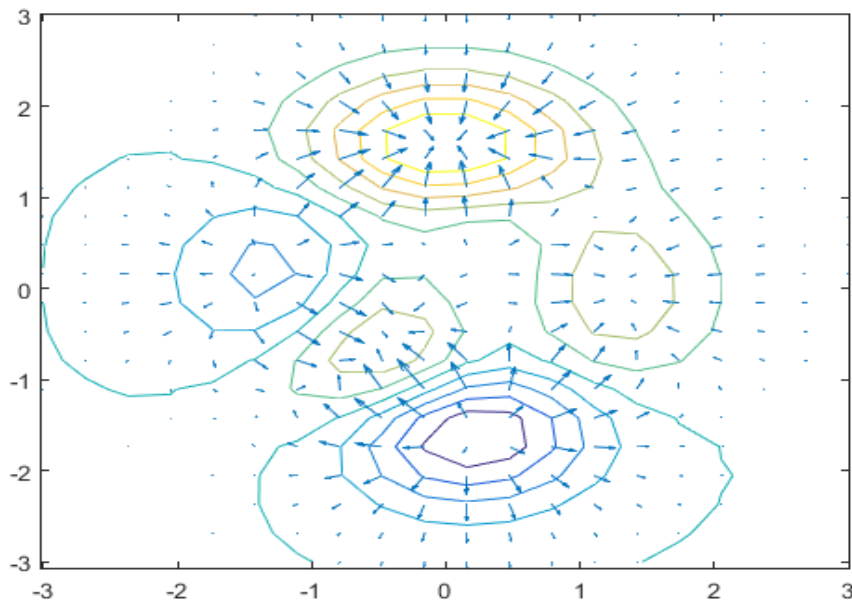
Ans:

```
[x,y]=meshgrid(-12:.7:12,-12:.7:12);
r=sqrt(x.^2+y.^2);
z=bessel(0,r);
z=besselj(0,r);
m=[-45 60];
mesh(z,m), axis off
```



Ans:

```
[x,y,z]=peaks(20);  
[nx,ny]=gradient(z,1,1);  
contour(x,y,z,10)  
hold on  
quiver(x,y,nx,ny)
```



1.6 Transfer Function

Example-8

Write a matlab code to obtain the following transfer function.

Transfer function:

$$\frac{s + 4}{s^2 + 2s + 10}$$

Ans:

```
>> num=[1 4]; den=[1 2 10];  
sys=tf(num,den)
```

sys =

$$\frac{s + 4}{s^2 + 2s + 10}$$

Continuous-time transfer function.

Example-9

Find the poles and zeros of the following transfer function:

$$H(s) = \frac{s^3 + 11s^2 + 30s}{s^4 + 9s^3 + 45s^2 + 87s + 50}$$

Ans:

```
>> num=[1 11 30 0];
den=[1 9 45 87 50];
[z,p,k]=tf2zp(num,den) %transfer function to zero and pole, k-gain. here k=1
```

z =

```
0
-6.0000
-5.0000
```

p =

```
-3.0000 + 4.0000i
-3.0000 - 4.0000i
-2.0000 + 0.0000i
-1.0000 + 0.0000i
```

k =

```
1
```

Example-10

A system has zeros at -6 , -5 , 0 , poles at $-3 \pm j4$, -2 , -1 , and a gain of 1 . Determine the system transfer function.

Ans:

```
>> z=[-6; -5; 0];
k=1;
i=sqrt(-1);
p=[-3+4*i;-3-4*i;-2;-1];
[num,den]=zp2tf(z,p,k)
```

num =

```
0 1 11 30 0
```

den =

1 9 45 87 50

Example-11

Find the Laplace transform.

$$te^{-4t}$$

Ans:

```
>> syms t s;  
laplace(t*exp(-4*t),t,s)
```

ans =

$$1/(s + 4)^2$$

Example-12

Find the inverse Laplace transform.

$$F(s) = \frac{s(s+6)}{(s+3)(s^2+6s+18)}$$

Ans:

```
>> syms s t;  
ilaplace(s*(s+6)/((s+3)*(s^2+6*s+18)))
```

ans =

$$2*\cos(3*t)*\exp(-3*t) - \exp(-3*t)$$