
```
function [b1,b2]= polynomial_no_intercept(x,y)
    % XA = Y
    n = length(x);
    X = zeros(n,2);

    X(:,1)= x;
    X(:,2)= x.^2;

    Y= y';

    % X'XA = X'Y
    X_trans= X';

    % A = inv(X'X)X'Y
    A = inv(X_trans*X)*X_trans*Y;
    b1 = A(1);
    b2 = A(2);
end
```

Published with MATLAB® R2021a