

MA102

Linear Algebra

## Ordinary differential Equations (ODE).

- Linear Operators.  $T(ax+by) = aT(x) + bT(y)$

- Physical Phenomenon  $\xrightarrow[\text{Modelling}]{\text{Mathematical}}$  Differential equations.

e.g. Newton's Second Law.

$$\boxed{\frac{d^2y}{dx^2} = \frac{f}{m}}$$

↓ Solution

behaviour of variables involved  
in physical model.

- \* Differential equation :- An equation involving derivatives of one or more dependent variables w.r.t. one or more independent variables is called a diff. eqn. (DE).

$$(1) \frac{dy}{dx} = ay; (1) \frac{dy}{dx} = k(a-y), (2) \frac{d^2y}{dx^2} = \frac{f}{m}.$$

$$(4) \frac{d^2y}{dx^2} + a \cdot \frac{dy}{dx} + by = \sin x,$$

(x), where

$$(2) \frac{\partial u}{\partial t} = k \frac{\partial^2 u}{\partial x^2}$$

$x$  is order of DE.

\* Types

ODE (ordinary) { Only one independent variable

PDE (Partial)

Linear ODE

Non-linear ODE

\* Mathematical form  $f(x, y, y', y'', \dots) = 0$ .

Maharaza of ODE :- where,  $x$  is independent variable.

★ Order of DE :-

It is the highest order of derivative involved in the DE.

★ First Order ODE (DE) :-

Mathematical form of 1st order ODE :-  $f(x, y, y') = 0$

Standard form of 1st order ODE :-

$$\textcircled{I} \quad \frac{dy}{dx} = f(x, y) \quad (\text{Derivative form})$$

$$\textcircled{II} \quad M(x, y) dx + N(x, y) dy = 0. \quad (\text{Differential form})$$

Unless specified;  $y$  is treated dependent &  $x$  as independent

★ S. L. Ross: Differential Equations. (Textbook)

e.g. Population Model. Convert into DE.

$x(t) \Rightarrow$  Population size at  $t$

$b \Rightarrow$  birth rate

$d \Rightarrow$  death rate / individual / time.

$$\Delta x = x(t+\Delta t) - x(t) = (bx(t) - dx(t))\Delta t$$

$$\Rightarrow \frac{\Delta x}{\Delta t} = (b-d)x(t)$$

$a = \text{const.}$

(if rates are considered constant throughout)

\* Newton's Law of Cooling.

$$\boxed{T_0} \quad \frac{dT}{dt} = -k(T_e - T)$$

\* Method I to solve Ist order DE (Exact DEs):

Given:-  $Mdx + Ndy = 0. \quad \text{--- } \textcircled{1}$

$M, N$  are functions of  $x$  and  $y$  both,

{ DE  $\textcircled{1}$  is called exact DE if  $\exists f(x,y)$  st.

$$df \equiv \left( \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy \right)$$

$$Mdx + Ndy$$

$$\Rightarrow df = 0, \text{ Solution } \boxed{f(x,y) = c}$$

Solution of DE is family of curves (not unique) which depends on a parameter which is nothing but constant of integration.

\* e.g.  $x^2 dx + y^2 dy = 0$

$$\Rightarrow d\left(\frac{x^2}{2} + \frac{y^2}{2}\right) = 0$$

Soln :-

$$\frac{x^2}{2} + \frac{y^2}{2} = C$$

$$\Rightarrow \boxed{x^2 + y^2 = C}$$

Discussion → To determine exactness of given DE, and corresponding solutions.

If ① is exact  $\Rightarrow \frac{\partial f}{\partial x} = M$  and  $\frac{\partial f}{\partial y} = N$  — (i)

$$\Rightarrow \frac{\partial^2 f}{\partial y \partial x} = \frac{\partial M}{\partial y} \quad \text{&} \quad \frac{\partial^2 f}{\partial x \partial y} = \frac{\partial N}{\partial x}$$

(I)  $\Rightarrow \boxed{\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}}$  { condition :-  
partial derivatives of M & N are continuous }

So, ① is exact  $\Leftrightarrow \frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$  { & continuous }

↑

Test to check exactness of DE

from (i) ;  $f(x,y) = \int M(x,y)dx + \phi(y)$

$$\frac{\partial f}{\partial y} = \frac{\partial}{\partial y} \int M(x,y)dx + \frac{d\phi}{dy}$$

from (i) ;  $N(x,y) = \frac{\partial}{\partial y} \int M(x,y)dx + \frac{d\phi}{dy}$

\* Algorithm.

① Write equation as  $Mdx + Ndy = 0$ .

② Check if equation is exact — (I).

③ If exact, find  $f$

④ Sol  $f(x,y) = c$

$$Q. (3x^2 + 4xy) \cdot dx + (2x^2 + 2y) dy = 0.$$

→ Check for exactness.

$$M = 3x^2 + 4xy ; N = 2x^2 + 2y$$

$$\frac{\partial M}{\partial y} = 4x ; \frac{\partial N}{\partial x} = 4x$$

$$\Rightarrow \frac{\partial M}{\partial y} = \frac{\partial N}{\partial x} \rightarrow \text{D.eqn is exact.}$$

Since, equation is exact,  $\exists f(x,y)$  s.t.

$$\left\{ \frac{\partial f}{\partial x} = 3x^2 + 4xy ; \frac{\partial f}{\partial y} = 2x^2 + 2y \right\}$$

$$\Rightarrow f(x,y) = \frac{3x^3}{3} + 4y \cdot \frac{x^2}{2} + \phi(y)$$

$$\Rightarrow f(x,y) = x^3 + 2x^2y + \phi(y).$$

$$\Rightarrow \frac{\partial f}{\partial y} = 2x^2 + \frac{d\phi}{dy}$$

$$\Rightarrow 2x^2 + 2y = 2x^2 + \frac{d\phi}{dy}$$

$$\Rightarrow \frac{d\phi}{dy} - 2y \Rightarrow \phi = y^2$$

$$\Rightarrow f(x,y) = x^3 + 2x^2y + y^2$$

Hence, solution is  $x^3 + 2x^2y + y^2 = C$

\* Method II :- Separation of Variable

Form -  $f(x)dx + g(y)dy = 0$

$$\frac{df}{dx} = f(x) \quad \frac{\partial F}{\partial y} = g(y)$$

$$F = \int f(x)dx + \phi(y) = \int f(x)dx + \int g(y)dy$$

$$\frac{df}{dy} = \frac{d\phi}{dy} = g(y)$$

Its solution is

$$\boxed{\int f(x)dx + \int g(y)dy = c}$$

Generalized form for separation of Variables

$$f(x) \cdot F(y)dx + g(y)G(x)dy = 0 \quad \text{--- (1)}$$

By  $\frac{1}{F(y) \cdot G(x)} \times (1)$  we obtain,

$$\frac{f(x)}{G(x)}dx + \frac{g(y)}{F(y)}dy = 0$$

Soln:-  $\boxed{\int \frac{f(x)}{G(x)}dx + \int \frac{g(y)}{F(y)}dy = c}$

\* solve.  $(x-4)y^4 dx - x^3(y^2-3)dy = 0 \quad \text{--- (1)}$

By  $\frac{1}{y^4 \times (-x^3)} \times (1)$  we obtain.

$$(-1) \left( \frac{x-4}{x^3} \right) dx + \left( \frac{y^3-3}{y^4} \right) dy = 0.$$

$$(-1) \left( \frac{1}{x^2} dx - \frac{4}{x^3} dx \right) + \left( \frac{1}{y} dy - \frac{3}{y^4} dy \right) = 0$$

Integrating ;

$$(-1) \left[ \int \frac{1}{x^2} dx - \int \frac{4}{x^3} dx \right] + \int \frac{1}{y} dy - \int \frac{3}{y^4} dy = 0.$$

$$\Rightarrow (-1) \left[ \frac{-1}{x} - \frac{4}{(-2)x^2} \right] + \left( \ln y - \frac{3}{-3y^3} \right) = 0$$

$$\Rightarrow \left[ \frac{1}{x} - \frac{2}{x^2} + \ln y + \frac{1}{y^3} = C \right]$$

\* Tutorial-5 Linear Algebra

1.

3.  $V$  is inner product space then

$$|\langle x, y \rangle| = \|x\| \cdot \|y\| \text{ iff } x = cy \text{ or } y = cx$$

$\Rightarrow$

4.  $T$  is linear operator on  $V$ ,  $\|T(x)\| = \|x\|$  for all  $x$ . Prove that  $T$  is one-one.

$\Rightarrow$

Let  $x_1, x_2 \in V$

$$\Rightarrow T(x_1) = T(x_2)$$

$$\Rightarrow T(x_1) - T(x_2) = 0$$

$$\Rightarrow T(x_1 - x_2) = 0$$

$$\Rightarrow \|T(x_1 - x_2)\| = \|0\| = 0.$$

$$\Rightarrow \|x_1 - x_2\| = 0.$$

$$\Rightarrow x_1 - x_2 = 0$$

$$\Rightarrow x_1 = x_2$$

$\therefore T$  is one-one.

\* Gram-Schmidt process to obtain orthonormal set.

\* If  $v_i$  is given vector then  $w_i = \frac{v_i}{\|v_i\|}$  is called orthonormal to  $v_i$  vector.

Let  $\{v_1, \dots, v_n\}$  is basis of  $V$ .

We can construct orthogonal basis of  $V$   $\{w_1, \dots, w_n\}$  as follows.

Take  $\bar{w}_1 = v_1 / \cancel{\|v_1\|}$

$$\bar{w}_2 = v_2 - \frac{\langle v_2, \bar{w}_1 \rangle}{\langle \bar{w}_1, \bar{w}_1 \rangle} \bar{w}_1 \quad (\because \langle \bar{w}_1, \bar{w}_2 \rangle = 0)$$

$$\bar{w}_3 = v_3 - \frac{\langle v_3, \bar{w}_1 \rangle}{\langle \bar{w}_1, \bar{w}_1 \rangle} \bar{w}_1 - \frac{\langle v_3, \bar{w}_2 \rangle}{\langle \bar{w}_2, \bar{w}_2 \rangle} \bar{w}_2$$

Q.5) (b)  $\left[ \begin{array}{c} v_1 \\ \vdots \\ v_n \end{array}; p_1(t) = t; p_2(t) = t^2 \right]$  of  $P_2$  with the inner product  $\langle p, q \rangle = \int_0^1 p(t)q(t)dt$ .

Let, orthogonal set is  $\{w_1, w_2, w_3\}$ .

$$\checkmark w_1 = \pm$$

$$\checkmark w_3 = \pm \frac{1}{6} + \frac{1}{2} - \frac{1}{2}$$

$$w_2 = v_2 - \frac{\langle v_2, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1$$

$$\langle v_2, w_1 \rangle = \int_0^1 t \cdot 1 dt = \frac{1}{2}$$

$$w_2 = t - \frac{\frac{1}{2} \times 1}{1} \rightarrow w_2 = t - \frac{1}{2}$$

$$w_3 = t^2 - \int_0^1 t^2 dt - \int_0^1 t^2 \left( t - \frac{1}{2} \right) dt \times \left( t - \frac{1}{2} \right)$$

$$w_3 = t^2 - \frac{1}{3} + \left( \frac{1}{4} + \frac{1}{6} \right) \times \left( t - \frac{1}{2} \right)$$

# Assignment - I. Sem.II (Differential Equations)



Q.1)

		Linear	Nonlinear	Ordinary	Partial	Order
(i)	$y'' + 3y' + 2y = e^x$	✓	✗	✓	✗	2
(ii)	$\sqrt{1+y'^3} = x^2$ $\Rightarrow 1+y'^3 = x^4$	✗	✓	✓	✗	1
(iii)	$y'' + y^2 = \cos x$	✗	✗	✓	✗	2
(iv)	$y' + xy = \cos y$	✗	✓	✓	✗	1
(v)	$(xy')' = xy$ $\Rightarrow y' + xy'' = xy$	✓	✗	✓	✗	2
(vi)	$u_x + u_y = 0$	✓	✗	✗	✓	1
	$u(x,y)$		$u(x,y,t)$			
	$\Rightarrow u_x = \frac{\partial u}{\partial x}$		$u_{xx} = \frac{\partial^2 u}{\partial x^2}$		$u_t = \frac{\partial u}{\partial t}$	
	& $u_y = \frac{\partial u}{\partial y}$		$u_{yy} = \frac{\partial^2 u}{\partial y^2}$			
(vii)	$u_{xx} + u_{yy} = u_t$	✓	✗	✗	✓	2

Q.8) Show that following eqns are exact and hence find their general solution.

$$M(x,y) \cdot dx + N(x,y) \cdot dy = 0$$

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x} \quad (\text{for exactness})$$

Maharaja

$$(i) (\cos x \cos y - \cot x) dx - (\sin x \sin y) dy = 0.$$

$$\frac{\partial M}{\partial y} = -\cos x \sin y; \quad \frac{\partial N}{\partial x} = -\cos x \cdot \sin y.$$

$$\Rightarrow \int M dx = C_1$$

$$\Rightarrow \int \{ \cos x \cdot \cos y - \cot x \} dx = C_1$$

$$\Rightarrow \int \cos x \cdot \cos y dx - \int \cot x dx = C_1$$

$$\Rightarrow \sin x \cos y - \int \frac{\cos x}{\sin x} dx = C_1$$

$$\Rightarrow \sin x \cos y - \ln(t) = C_1 \quad (t = \sin x)$$

$$\Rightarrow \sin x \cos y - \log_e(\sin x) + \phi(y) = C_1$$

$$\Rightarrow \frac{\partial f}{\partial y} = N,$$

$$\Rightarrow \sin x \sin y - \frac{d\phi}{dy} = 0.$$

$$\Rightarrow d\phi = \sin x \sin y dy$$

$$\Rightarrow \phi(y) = \int \sin x \sin y dy \\ = -\sin x \cos y.$$

$$\rightarrow \boxed{\sin x \cos y - \log_e(\sin x) - \sin x \cos y = C_1}.$$

## Linear Algebra continued.

★

Diagonalization  $PAP^{-1} = D$ .

Let  $A$  be a square matrix of order  $n$  over the field  $F$  then if there exists an (non-singular) invertible matrix  $P$  such that  $PAP^{-1} = D$  then we call matrix  $P$  diagonalize the matrix  $A$ , where  $D$  is a diagonal matrix.

e.g.  $A_{3 \times 3}$ .

$$\lambda_1 \quad x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \quad \lambda_2 \quad y = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} \quad \lambda_3 \quad z = \begin{bmatrix} z_1 \\ z_2 \\ z_3 \end{bmatrix}$$

$$P = [x \ y \ z].$$

$$PAP^{-1} = D = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix}.$$

\* If eigen vectors are linearly independent then only the given matrix can be diagonalized.

\* fixed point of function :-

$f: A \rightarrow A \quad x \in A, f(x) = x;$   
then  $x$  is called fixed point of  $f$

\* Banach fixed point Theorem :-

$$\langle \alpha x + \beta y, z \rangle = \alpha \langle x, z \rangle + \beta \langle y, z \rangle \quad (\text{The left side})$$

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## \* Bilinear form :- / Bilinear functional.

Def'n :- Let  $U$  and  $V$  be two vector spaces over the same field  $F$ . Let  $W = U \times V$  (or  $U \oplus V$ )  $(W, +, \cdot)$  is a vector space where addition and scalar multiplication  $W$  is defined as usual i.e.

$$(x_1, x_2) (y_1, y_2) \in W$$

$$\Rightarrow (x_1, x_2) + (y_1, y_2) = (x_1 + y_1, x_2 + y_2),$$

$$\alpha(x_1, x_2) = (\alpha x_1, \alpha x_2).$$

A map  $f: W \times W \rightarrow F$  is said to be a bilinear form if (i)  $f(\alpha x + \beta y, z) = \alpha f(x, z) + \beta f(y, z)$  and (ii)  $f(x, \gamma y + \delta z) = \gamma f(x, y) + \delta f(x, z)$  where,  $x, y, z \in W$ ;  $\alpha, \beta, \gamma, \delta \in F$ .

(i) linearity from left (ii) linearity from right.

Here,  $f$  is bilinear form from  $U$  to  $V$ .  
If  $U = V$ ;  $f$  is bilinear form on  $U$ .

$$\text{eg. } V = \mathbb{R}^2 = \{(x, y) | x, y \in \mathbb{R}\}$$

$f: V \times V \rightarrow F$  defined by.

$$f(\alpha, \beta) = x_1 y_2 - x_2 y_1$$

where  $\alpha = (x_1, x_2); \beta = (y_1, y_2)$ .

whether  $f$  is bilinear form or not?

$$\begin{aligned} \text{Ans} \Rightarrow f(a\alpha + b\beta, \gamma) &= f(a(x_1, x_2) + b(y_1, y_2), (z_1, z_2)) \\ &= f((ax_1 + by_1, ax_2 + by_2), (z_1, z_2)) \\ &= (ax_1 + by_1)z_2 - (ax_2 + by_2)(z_1). \quad \text{---(1)} \\ f(x, c\beta + d\gamma) &= f((x_1, x_2), c(y_1, y_2) + d(z_1, z_2)) \\ &= f((x_1, x_2), (cy_1 + dz_1, cy_2 + dz_2)) \end{aligned}$$

$$\text{Maharashtra } a, b, c, d \in \mathbb{R}; \alpha = (x_1, x_2)$$

$$\gamma = (z_1, z_2); \beta = (y_1, y_2)$$

$$= x_1(cy_2 + dz_2) - x_2(cy_1 + dz_1) \quad \text{---(2)}$$

Also check for  $f_2(\alpha, \beta) = (x_1 - y_1)^2 + 2x_2y_2$ .

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$$af(\alpha, \gamma) + bf(\beta, \gamma)$$

$$= a(x_1z_2 - x_2z_1) + b(y_1z_2 - y_2z_1) \\ = (ax_1 + by_1)z_2 - (ax_2 + by_2)z_1 \quad \text{--- (3)}$$

$$cf(\alpha, \beta) + df(\alpha, \gamma)$$

$$= c(x_1y_2 - x_2y_1) + d(x_1z_2 - x_2z_1) \\ = x_1(cy_2 + dz_2) - x_2(cy_1 + dz_1) \quad \text{--- (4)}$$

$\therefore$  from & from  $\Rightarrow f$  is bilinear  
① & ③ & ② & ④

\*  $f_2(\alpha, \beta) = (x_1 - y_1)^2 + 2x_2y_2$

\* Hermitian Matrix  $A = (\bar{A})^T$

Skew Hermitian Matrix.  $A = -(\bar{A})^T$ .

\* Jordan Decomposition Theorem.

\* Any Linear transformation  $T$  is said to be symmetric / skew-symmetric if its matrix representation is symmetric / skew-symmetric.

\* A bilinear form  $f$  on vector space  $V(F)$  is said to be symmetric if  $f(x,y) = f(y,x)$ ;  $x,y \in V$ .

- skew symmetric if  $f(x,y) = -f(y,x)$ ;  $x,y \in V$ .

-  $f: V \times V \rightarrow F$ ;  $B = \{x_1, x_2, \dots, x_n\}$  is basis of  $V$

$$f(x_i, y_j) = f\left(\sum_{i=1}^n a_i x_i, \sum_{j=1}^n b_j x_j\right).$$

$$= \sum_{j=1}^n \sum_{i=1}^n a_i b_j f(x_i, x_j).$$

$$f(x_i, x_j) = a_{ij}, 1 \leq i, j \leq n$$

Matrix representation of bilinear form

$$[f]_B = (a_{ij})_{n \times n}$$

\* Quadratic form:

Let  $f$  be a bilinear form on a vector space  $V(F)$ . Then a map  $q: V \rightarrow F$  as

$$q(x) = f(x, x); \forall x \in V$$

is called quadratic form. ( $\because f(x, y) = f(y, x)$ )

- It is symmetric bilinear form as  $f(x, x) = f(x, x)$

## Quadratic form

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Def'n using Inner product space.

Let  $T$  be a symmetric linear operator on a vector space  $V(F)$ . Then a map  $q : V \rightarrow F$  is called a quadratic form if

$$q(x) = \langle T(x), x \rangle ; \quad \forall x \in V.$$

Standard Inner Product

$$x = (x_1, \dots, x_n); \quad y = (y_1, \dots, y_n).$$

$$\langle x, y \rangle = x_1 y_1 + \dots + x_n y_n$$

$$f(x, y) = ax^2 + 2hxy + by^2$$

$$= \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} a & h \\ h & b \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$= \begin{bmatrix} ax+hy & hx+by \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$= [ax^2 + hxy + hxy + by^2]_{1 \times 1}$$

$$= ax^2 + 2hxy + by^2$$

Let,  $u = [x, y]$ ;  $q(u) = \langle T(u), u \rangle$ .

$$g(x, y, z) = ax^2 + by^2 + cz^2 + 2hxy + 2fyz + 2gz$$

$$\begin{bmatrix} x & y & z \end{bmatrix}_{1 \times 3} \begin{bmatrix} a & h & f \\ h & b & g \\ f & g & c \end{bmatrix}_{3 \times 3} \begin{bmatrix} x \\ y \\ z \end{bmatrix}_{3 \times 1}$$

$$ds^2 = dx^2 + dy^2 + dz^2$$

$$ds^2 = dr^2 + r^2 d\theta^2 + dz^2$$

Not in  
syndicate for now  
(IV sem)

positive definite

negative definite

indefinite

All principal

All principal

Random

minors > 0

minors < 0

principal minor  $\Rightarrow$  determinants (all possible)

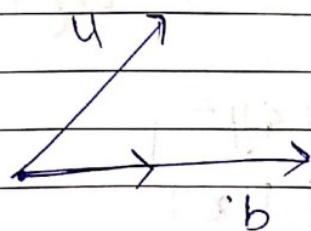
for  $3 \times 3 \Rightarrow 1 \times 1 ; 2 \times 2 ; 3 \times 3$

Orthogonal  $\langle x, y \rangle = 0$

Orthonormal.  $\langle x, y \rangle = 0 ; \langle x, x \rangle = 1 \& \langle y, y \rangle = 1$

Tut-5.

Q.6)



$$P_b(u) = \frac{\langle u, b \rangle}{\|b\|^2} \vec{b}$$

(a)  $V = \mathbb{R}^2$ ;  $u = (2, 6)$  and  $W = \{(mx, y) \mid y = 4x\}$

$$u = (2, 6); b = (1, 4)$$

$$P_b(u) = \frac{26}{17} (1, 4)$$

$$\text{Orthogonal projection} = \vec{e}_2 \Leftrightarrow P_b(u) = \frac{26}{17} (1, 4)$$

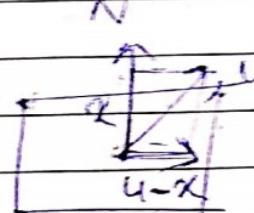
(b)

$$V = \mathbb{R}^3, u = (2, 1, 3) \text{ and } W = \{(x, y, z) \mid x + 3y - 2z = 0\}$$

$$\Rightarrow u = (2, 1, 3); b = (1, 3, -2).$$

$$\Rightarrow u - \left[ \frac{\langle u \cdot b \rangle}{\|b\|^2} b \right] (x)$$

$$(2, 1, 3) - \frac{(-1)}{14} (1, 3, -2)$$



$$= \left( \frac{29}{14}, \frac{17}{14}, \frac{40}{14} \right).$$

$$(c) V = P(\mathbb{R}) \quad \langle f, g \rangle = \int_0^1 f(t)g(t) dt.$$

Q.9) Associated matrix of  $f(x) = x^2 - 3xy + 4y^2$ .

$$f(x) = x^T A x = x^2 - 3xy + 4y^2$$

$$= (x, y) \begin{bmatrix} 1 & -3/2 \\ -3/2 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

(d) bilinear form from quadratic form.

(e)  $x_1, x_2$

Bilinear form

$$f(x, y) = x^T A y.$$

$$A = \begin{bmatrix} 1/2 & 0 & 0 & 0 \\ 0 & 1/2 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Quadratic form

$$f(x) = x^T A x$$

$$x = (x_1, x_2, x_3, x_4)$$

$$y = (y_1, y_2, y_3, y_4)$$

$$f(x, y) = x^T A y$$

$$= (x_1 \ x_2 \ x_3 \ x_4) \begin{bmatrix} 0 & \frac{1}{2} & 0 & 0 \\ \frac{1}{2} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix}$$

$$f(x, y) = \left[ \frac{x_2}{2} \quad \frac{x_1}{2} \quad 0 \quad 0 \right] \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix} \Rightarrow \begin{bmatrix} y_1 \\ \frac{x_2 y_1 + x_1 y_2}{2} \\ \frac{x_2 y_3 + x_1 y_4}{2} \\ y_4 \end{bmatrix}$$

$$f(x, y) = (x_2 y_1 + x_1 y_2)/2$$

(b)  $x_1 x_3 + x_4^2 = f(x) = x^T A x$

$$f(x, y) = x^T A y$$

$$\rightarrow A = \begin{bmatrix} 0 & 0 & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 0 \\ \frac{1}{2} & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = (x_1 \ x_2 \ x_3 \ x_4) \begin{bmatrix} 0 & 0 & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 0 \\ \frac{1}{2} & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix}$$

$$f(x, y) = \begin{bmatrix} x_3 \\ \frac{x_2}{2} \\ 0 \\ \frac{x_1}{2} \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix}$$

$$= \frac{x_3 y_1 + x_2 y_3}{2} + x_1 y_4.$$

P.T.)  $V(F) ; w \leq v$   
 $W^+ = \{ v \in V \mid \langle v, w \rangle = 0 \ \forall w \in W \}.$

P.T.  $z \in W^+ \Leftrightarrow \langle z, v \rangle = 0 \ \forall v \in F$

the basis of  $W$ .

# Differential Equations (Continued)

(Revision).

Mathematical form of ODE  $f(x, y, y', y'', \dots) = 0$ .

Order of DE  $\Rightarrow$  highest order of derivative involved.

Mathematical form of 1<sup>st</sup> order ODE  $f(x, y, y') = 0$

Standard form of 1<sup>st</sup> order ODE

$$\frac{dy}{dx} = f(x, y) \quad M(x, y) dx + N(x, y) dy = 0 \quad (1)$$

(derivative form)

(differential form)

Exact ODE of first order  $\text{②}$  is called exact if  $\exists$   $F(x, y)$  s.t.  $dF = M dx + N dy$ , moreover solution in the case is  $F(x, y) = c$ .

$$\left. \frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \text{ condition to determine exactness}$$

Separation of variables  $\Rightarrow f(x).dx + g(y).dy = 0$ .  
Solt :-  $\int f(x).dx + \int g(y).dy = C$ .

General form for separable method.

$$f(x) F(y).dx + g(y).G(x).dy = 0 \quad (3)$$

By  $\frac{1}{f(y) G(x)}$   $\times$  ③ we obtain

$$\frac{f(x)}{G(x)}.dx + \frac{g(y)}{F(y)}.dy = 0. \quad (3)$$

$$\text{Solt:- } \left[ \int \frac{f(x)}{G(x)}.dx + \int \frac{g(y)}{F(y)}.dy \right] = C.$$

The solution is not exactly the solution for eq<sup>n</sup> (3) as there may be some more or less solutions for the eq<sup>n</sup> (3).

Eq<sup>n</sup> (3) need not be exact always but (3) is always exact.

So, to make the eq<sup>n</sup> (3) exact we have multiplied it with a certain function. This function is called as Integrating factor (IF)

IF is not unique. It can be also completely different along with constant multiples of the same IF.

### \* Linear first Order ODE's :-

\* linear ODE :- An ODE is linear if dependent variable and its derivatives appear to the power 1. (Product of dependent variable and its derivatives are not allowed) otherwise ODE is non-linear.

e.g.  $\frac{dy}{dx} = ay$ ;  $m \frac{d^2y}{dt^2} = f$ ;  $\frac{d^4y}{dx^4} + a \frac{d^2y}{dx^2} + by = \sin x$ .

Some Non-linear e.g.  $\frac{d^4y}{dx^4} + a \frac{d^2y}{dx^2} + by - \sin y$ ;

$$\frac{d^4y}{dx^4} + \left(\frac{dy}{dx}\right)^2 \frac{d^2y}{dx^2} + by = \sin x.$$

\* Mathematical form of nth order of linear ODE;

$$a_0 \cdot \frac{d^n y}{dx^n} + a_1 \cdot \frac{d^{n-1} y}{dx^{n-1}} + a_2 \cdot \frac{d^{n-2} y}{dx^{n-2}} + \dots + a_{n-1} \frac{dy}{dx} + by = b$$

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where,  $a_i$  and  $b$  are either constants or functions of  $x$  m/w.

\* Linear First order ODE's :-

$$\boxed{a_0 \cdot \frac{dy}{dx} + a_1 y = b}$$

general

Mathematical form,

\* Standard form of 1st order linear ODE :-

$$\boxed{\frac{dy}{dx} + p(x) \cdot y = q(x)} \quad \text{--- (4)}$$

Let  $u$  be a function s.t.  $u \times \text{L.H.S. of (4)}$  is complete derivative of a function

(i.e. Given ODE becomes exact). such  $u$  is called Integrating factor (IF) for (4).

$$u \cdot \frac{dy}{dx} + u \cdot p(x) \cdot y = u \cdot q(x)$$

$$\text{gives. } \frac{d}{dx}(uy) = u \cdot q(x) \quad \text{--- (5)}$$

Thus for solution (4) integrate (5) w.r.t.  $x$ ;

$$\text{for } u; \quad u' = u \cdot p(x)$$

$$\frac{du}{dx} = u \cdot p(x)$$

$$\Rightarrow \frac{du}{u} = p(x) \cdot dx$$

$$\Rightarrow \ln u = \int p(x) \cdot dx$$

$$\Rightarrow u = e^{\int p(x) \cdot dx}$$

$$\Rightarrow \boxed{u(x) = e^{\int p(x) \cdot dx}}$$

\* Algorithm to solve 1<sup>st</sup> order linear ODE :-

(1) Write the equation in following form

$$\frac{dy}{dx} + p(x)y = q(x) \quad \text{--- (1)}$$

(2) Find IF ;  $u(x) = e^{\int p(x) \cdot dx}$ .

(3) Multiply u in expression (1) and obtain

$$(uy)' = uq(x)$$

(4) Solution of (1) is  $uy = \int uq(x) \cdot dx + c$

e.g. (I)  $x \cdot \frac{dy}{dx} - y = x^3$ .

$$\rightarrow \frac{dy}{dx} - \frac{1}{x}y = x^2$$

$$\text{IF ; } u(x) = e^{\int \frac{1}{x} dx} = \frac{1}{x}$$

$$\frac{1}{x} \frac{dy}{dx} - \frac{1}{x^2}y = x$$

$$\frac{d}{dx}\left(\frac{1}{x}y\right) = x$$

$$\Rightarrow \frac{1}{x}y = \frac{x^2}{2} + C$$

$$\Rightarrow \boxed{\frac{y}{x} = \frac{x^2}{2} + C} \rightarrow \text{solution}$$

$$\text{II} \quad (1 + \cos x)y' - (\sin x) \cdot y = 2x .$$

$$\Rightarrow y' - \left( \frac{\sin x}{1 + \cos x} \right) \cdot y = \frac{2x}{1 + \cos x}$$

$$\text{IF. } u(x) = e^{\int \frac{\sin x}{1 + \cos x} dx}$$

$$= e^{\ln(1 + \cos x)}$$

$$u(x) = 1 + \cos x$$

$$(1 + \cos x)y' - (\sin x)y = 2x .$$

$$\frac{d}{dx}((1 + \cos x)y) = 2x .$$

$$(1 + \cos x)y = 2 \cdot \frac{x^2}{2} + c$$

$$\Rightarrow [y(1 + \cos x) = x^2 + c] \text{ is the solution.}$$

\* First order ODE's :-

① Exact method  $Mdx + Ndy = 0$  is exact iff  $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$ .

② Separation method  $f(x).dx + g(y).dy = 0$ .  
Soln:-  $\int f(x).dx + \int g(y).dy = C$ .

③ Linear ODE's method  $\frac{dy}{dx} + P(x)y = q(x)$ .

Soln:-  $(uy)' = uq$ ,  $u = e^{\int P(x) dx}$

④ Make exact, if possible

⑤ Substitution.

\* Bernoulli's Equation :-

$$\frac{dy}{dx} + p(x) \cdot y = q(x) \cdot y^a \quad (\text{a constant})$$

$$\Rightarrow y^a \cdot \frac{dy}{dx} + p(x) \cdot y^{1-a} = q(x)$$

Substitution  $u = y^{1-a}$   $\frac{du}{dx} = (1-a) \cdot y^{-a} \cdot \frac{dy}{dx}$

$\Rightarrow$  By subs.  $u = y^{1-a}$ ; we obtain

$$\frac{1}{1-a} \cdot \frac{du}{dx} + p(x) \cdot u = q(x).$$

$$\boxed{\frac{du}{dx} + (1-a)p(x)u = (1-a)q(x)}.$$

Linear; first find  $u$  and then  $y$ .

e.g.  $\frac{dy}{dx} - Ay = -By^2$  ( $A$  &  $B$  are constant).

$$\Rightarrow y^{-2} \cdot \frac{dy}{dx} - A y^{-1} = -B.$$

Let,  $u = y^{-1}$ ;  $\frac{du}{dx} = -\frac{1}{y^2} \cdot \frac{dy}{dx}$ .

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$$-\frac{du}{dx} - Au = -B \Rightarrow \frac{du}{dx} + Au = B.$$

$$\frac{du}{dx} + Au = B.$$

This solution

$$I.F. = e^{\int A \cdot dx} = e^{Ax}.$$

$$e^{Ax} \cdot \frac{du}{dx} + e^{Ax} \cdot Au = Be^{Ax}$$

$$\Rightarrow \frac{d}{dx}(u \cdot e^{Ax}) = Be^{Ax}$$

$$\Rightarrow \int (u \cdot e^{Ax})' dx = \int Be^{Ax} \cdot dx$$

$$\Rightarrow u \cdot e^{Ax} = \frac{B \cdot e^{Ax}}{A} + c.$$

$$u = y^{-1}$$

$$\Rightarrow \frac{e^{Ax}}{y} = \frac{B}{A} \cdot e^{Ax} + C'$$

$$\Rightarrow y = \frac{Ae^{Ax}}{Be^{Ax} + C}$$

$$* \frac{dy}{dx} = \frac{y}{x} \Rightarrow \frac{dy}{dx} - \frac{1}{x} \cdot y = 0.$$

$$I.F. = e^{-\int \frac{1}{x} \cdot dx} = \frac{1}{x}.$$

$$\Rightarrow \frac{1}{x} \cdot \frac{dy}{dx} - \frac{1}{x^2} \cdot y = 0$$

$$\Rightarrow \left( \frac{1}{x} \cdot y \right)' = 0$$

$$\Rightarrow \boxed{\frac{y}{x} = \text{Const.}}$$

$$\text{Notation: } M_y = \frac{\partial M}{\partial y}; N_x = \frac{\partial N}{\partial x}$$

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$$\Rightarrow xdy - ydx = 0 \Rightarrow ydx - xdy = 0 \quad \text{.....(1)}$$

$$M_y = \frac{\partial M}{\partial y} = 1; N_x = \frac{\partial N}{\partial x} = -1 \text{ not exact.}$$

\* Result I :- If  $\frac{M_y - N_x}{N} = R(x)$ ; function of  $x$  alone

$$\text{then I.F.} = e^{\int R(x) dx}$$

\* Result II :- If  $\frac{N_x - M_y}{M} = R(y)$ ; function of  $y$  alone.

$$\text{then I.F.} = e^{\int R(y) dy}$$

$$\text{Applying Result (I); } \frac{M_y - N_x}{N} = \frac{1+1}{-x} = \frac{-2}{x}.$$

$$\text{thus I.F.} = e^{-\int \frac{2}{x} dx} = \frac{1}{x^2}$$

By  $\frac{1}{x} \times (1)$ ; we obtain

$$\frac{y}{x^2} dx - \frac{1}{x} dy = 0$$

$$\Rightarrow d\left(\frac{-y}{x}\right) = 0 \Rightarrow \text{soln: } \frac{-y}{x} = \text{const.}$$

$$\Rightarrow \boxed{\frac{y}{x} = \text{const.}}$$

Applying Result (II);  $N_x - M_y = \frac{-1 - 1}{y} = \frac{-2}{y}$

$$\text{IF} = e^{\int \frac{2}{y} dy} = \frac{1}{y^2}$$

$\frac{1}{y^2} \times ①$ ; we obtain.

$$\Rightarrow \frac{1}{y^2} \times y dx - \frac{1}{y^2} x dy = 0$$

$$\Rightarrow \frac{1}{y} dx - \frac{1}{y^2} x dy = 0$$

$$\Rightarrow d\left(x \cdot \frac{1}{y}\right) = 0 \Rightarrow \frac{x}{y} = \text{const}$$

$$\boxed{\frac{y}{x} = \text{const}}$$

Take IF =  $\frac{1}{xy}$ ; Then by  $\frac{1}{xy} \times ①$ ; we obtain

$$\frac{1}{x} dx - \frac{1}{y} dy = 0$$

$$\Rightarrow \ln x - \ln y = C \Rightarrow \frac{x}{y} = \text{const. A.}$$

Take IF =  $\frac{1}{x^2 + y^2}$ ;  $y dm - x dy = 0$

## \* More About Substitution Method :-

Type of Given ODE	Substitution	Given ODE reduces to
$\frac{dy}{dx} + p(x)y = q(x), y^a (a \neq 0, 1)$	$z = y^{1-a}$	Linear form.
$f(y)\frac{dy}{dx} + p(x).f(y) = q(x)$	$z = f(y)$	Linear form.

e.g.  $\frac{dy}{dx} = e^{2x}e^{-y} - e^x$

$$\Rightarrow e^y \cdot \frac{dy}{dx} + e^x e^y = e^{2x} \quad \text{Sub } z = e^y.$$

$$\Rightarrow \frac{dz}{dx} + e^x z = e^{2x}$$

$$IF = e^{\int e^x dx} = e^{e^x}$$

$$\Rightarrow e^{e^x} \cdot \frac{dz}{dx} + e^{e^x} \cdot e^x \cdot z = e^{2x} \cdot e^{e^x}$$

$$\Rightarrow (e^{e^x} \cdot z)^{\frac{1}{e^x}} = \int e^{2x} \cdot e^{e^x} \cdot dx + C.$$

$$\begin{aligned} \text{Take } t = e^x, & \quad = \int t^2 \cdot e^t \cdot dt + C. \\ dt = e^x dx. & \end{aligned}$$

$$= \int t \cdot e^t dt + C$$

$$= t \cdot e^t - \int e^t dt + C$$

$$= t \cdot e^t - e^t + C$$

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$$e^{e^x} \cdot z = e^x \cdot e^{e^x} - e^{e^x} + C.$$

$$\Rightarrow e^y = e^x - 1 + C e^{-e^x}.$$

Type of given ODE	substitution	Given ODE reduced to
$\frac{dy}{dx} = f\left(\frac{y}{x}\right)$	$y = zx \quad (\cancel{\frac{y}{x}})$	separable form.

Homogeneous equation

$$\text{of first order. } y = zx \Rightarrow \frac{dy}{dx} = z + x \cdot \frac{dz}{dx} = f(z).$$

$$\Rightarrow x \cdot \frac{dz}{dx} = f(z) - z$$

$$\Rightarrow \frac{dz}{f(z) - z} = \frac{dx}{x}$$

$$\text{eg. } xy \cdot \frac{dy}{dx} + 4x^2 + y^2 = 0.$$

$$\Rightarrow \frac{dy}{dx} = -\frac{(4x^2 + y^2)}{xy} = -\frac{4 + \left(\frac{y}{x}\right)^2}{\left(\frac{y}{x}\right)}.$$

$$\text{sub : } y = zx.$$

$$\Rightarrow z + x \cdot \frac{dz}{dx} = -\left(\frac{4+z^2}{z}\right)$$

$$\Rightarrow x \cdot \frac{dz}{dx} = -\left[\frac{4+z^2}{z} + z\right]$$

$$\Rightarrow x \frac{dz}{dx} = -\frac{4+2z^2}{z} = -2 \left(\frac{2+z^2}{z}\right)$$

$$\Rightarrow \frac{1}{(-2)} \frac{z \cdot dz}{2+z^2} = \frac{2 \cdot dz}{x}.$$

$$\text{Soln :- } -\frac{1}{4} \ln(2+z^2) = 2 \ln x + C.$$

Type of Given ODE	Substitution	Given ODE reduces to.
$\frac{dy}{dx} = f(ax+by+c)$ ; a, b, c are const.	$z = ax+by+c$	separable form.

eg.  $\frac{dy}{dx} = e^{qy-x}$  Sub.  $z = qy-x$   
 $\frac{dz}{dx} = q \cdot \frac{dy}{dx} - 1$ .

$$\Rightarrow \frac{1}{q} \left( \frac{dz}{dx} + 1 \right) = e^z \Rightarrow \frac{dz}{dx} = q e^z - 1.$$

$$\Rightarrow \frac{dz}{q e^z - 1} = dx.$$

$$\Rightarrow \frac{e^{-z} \cdot dz}{q - e^{-z}} = dx.$$

$$\Rightarrow \ln(q - e^{-z}) = x + C.$$

$$\Rightarrow [q - e^{-z} = C e^x]$$

$$(a_1 x + b_1 y + c_1) \cdot dx + (a_2 x + b_2 y + q) dy = 0$$

$a_1, a_2, b_1, b_2, c_1, c_2$  are consts.

$$+ \frac{a_1}{q_2} = \frac{b_1}{b_2}$$

$z = a_1x + b_1y$  Separable form .

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e.g.  $(x+2y+3)dx + (2x+4y-1)dy = 0$

Sol :-  $z = x+2y \Rightarrow dz = dx+2dy$

$$(z+3)dx + \frac{1}{2}(z-1)(dz-dx) = 0$$

$$\Rightarrow zdx + 3dx + zdz - \frac{zdx}{2} - dz + \frac{dx}{2} = 0$$

$$\Rightarrow \left(3 + \frac{1}{2}\right)dx + \left(z - \frac{1}{2}\right)dz = 0.$$

$$\Rightarrow 7dx + (2z-1)dz = 0$$

$$\Rightarrow \int 7dx = \int (1-2z)dz$$

$$\Rightarrow 7x = z - z^2 + C$$

$$\Rightarrow 7x = x+2y - (x^2 + 4y^2 + 4xy)$$

$$\Rightarrow 6x - 2y = -x - 4y^2 + 4xy$$

$$\Rightarrow x^2 + 4y^2 + 4xy + 6x - 2y = C$$

\*

$$(a_1x + b_1y + c_1).dx + (a_2x + b_2y + c_2)dy = 0$$

$a_1, b_1, c_1, a_2, b_2, c_2$  are constants

But  $\frac{a_1}{a_2} \neq \frac{b_1}{b_2}$  homogeneous eq<sup>n</sup>

$$z_1 = x-h \quad \text{in variables } z_1$$

$$\& z_2$$

$$z_2 = y-k$$

where  $h, k$  are solution of

$$a_1h + b_1k + c_1 = 0$$

$$a_2h + b_2k + c_2 = 0$$

$$\text{eg. } (-2y+1) \cdot dx + (4x-3y-6) \cdot dy = 0.$$

$$\Rightarrow \frac{1}{4} \neq \frac{-2}{3} \quad z_1 = x-h; \quad z_2 = y-k;$$

$$\begin{aligned} h-2k+1 &= 0 \\ 4h-3k-6 &= 0 \end{aligned} \quad \begin{aligned} h &= 3 \\ k &= 2 \end{aligned} \quad \begin{aligned} z_1 &= x-3 \Rightarrow x = z_1+3 \\ z_2 &= y-2 \Rightarrow y = z_2+2 \end{aligned}$$

$$((z_1+3) - 2(z_2+2)+1) \cdot dz_1 + (4(z_1+3)-3(z_2+2)-6) dz_2 = 0$$

$$\Rightarrow (z_1 - 2z_2) \cdot dz_1 + (4z_1 - 3z_2) dz_2 = 0.$$

$$\Rightarrow \frac{dz_2}{dz_1} = \frac{2z_2 - z_1}{4z_1 - 3z_2}$$

$$\frac{dz_2}{dz_1} = \frac{2 - (z_1/z_2)}{4(z_1/z_2) - 3} = \frac{2(z_2/z_1) - 1}{4 - 3(z_2/z_1)}$$

Homogeneous form in  $z_1$  &  $z_2$

$$\text{Sub :- } z_2 = z z_1$$

+

## More about IF :-

let  $M(x,y)dx + N(x,y)dy$  be not exact.

Assignment-1 ; Sem II ; MA102.

Q.6) A. Reduce  $y' = f\left(\frac{ax+by+c}{dx+ey+f}\right)$ ,  $ae-bd \neq 0$  to a separable variable form. What if  $ae=bd$ ?

→ Put  $X = x-h$ ;  $Y = y-k$ .  
 $\Rightarrow dx = dX$ ;  $dy = dY$ .

$h$  &  $k$  are the solution of  $ax+by+c=0$   
 $dx+ey+f=0$ .

$$\frac{dY}{dX} = \frac{ax+by}{dx+ey} = \frac{a+b(Y/X)}{b+e(Y/X)}$$

Now; Put  $\frac{Y}{X} = v \Rightarrow Y = vX$ ;  $Y' = v + XV'$

$$v + XV' = f\left(\frac{a+bv}{b+ev}\right) \rightarrow XV' = \frac{a+bv - bv^2 - ev^2}{b+ev}$$

$$\Rightarrow XV' = f() - v$$

$$\Rightarrow \int \frac{dv}{f() - v} = \int \frac{dx}{x} + C.$$

$$\Rightarrow \int \frac{dv}{G(v)} = \int \frac{dx}{x} + C.$$

$$\text{If } ae=bd \Rightarrow \frac{a}{d} = \frac{b}{e} = \lambda.$$

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$$\Rightarrow a = d\lambda; b = e\lambda.$$

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$$\rightarrow \frac{dy}{dx} - \frac{dx + ey + c}{dx + ey + f} = \frac{\lambda(dx + ey) + C}{dx + ey + f}$$

$$\text{Put; } dx + ey = u \Rightarrow d + ey' = u'.$$

$$\Rightarrow dy = \frac{d + ey'}{u'} du + C$$

$$\rightarrow \int \frac{dy}{d + e \left( \frac{du + C}{u + C} \right)} = \int du + C$$

$$= u'$$

$$(B) (i) (x+2y+1)dx - (2x+y-1).dy = 0.$$

$$\rightarrow z_1 = x-h; z_2 = y-k. \quad h+2k+1=0 \\ -(2h+k-1)=0$$

$$z_1 = x-1; z_2 = y+1. \quad h=1; k=-1.$$

$$dz_1 = dx; dz_2 = dy.$$

$$x = z_1 + 1; y = z_2 - 1.$$

$$(z_1+1) + 2(z_2-1)+1).dx - (2(z_1+1) + (z_2-1)-1).dy = 0$$

$$\rightarrow \frac{dz_2}{dz_1} = \frac{z_1 + 2z_2}{2z_1 + z_2}.$$

$$\frac{dz_2}{dz_1} = \frac{1 + 2\left(\frac{z_2}{z_1}\right)}{2 + \left(\frac{z_2}{z_1}\right)}$$

Q.3) Let  $V$  be linear space of all twice differentiable functions with usual operations. Show that sol<sup>n</sup> of diff. eqn  $y'' + \alpha y' + \beta y = 0$  form a linear space. — (1)

$\rightarrow S$  be Solution set.

Let,  $y_1, y_2 \in S$

$$y_1'' + \alpha y_1' + \beta y_1 = 0. \quad \text{--- (2)}$$

$$y_2'' + \alpha y_2' + \beta y_2 = 0. \quad \text{--- (3)}$$

To show linearity, claim  $y_1 + y_2$  is sol<sup>n</sup> of eqn (1).

Proof :-

$$\text{eqn (2)} + \text{eqn (3)}$$

$$y_1'' + y_2'' + \alpha(y_1' + y_2') + \beta(y_1 + y_2) = 0$$

$$\Rightarrow (y_1 + y_2)'' + \alpha(y_1 + y_2)' + \beta(y_1 + y_2) = 0$$

$$\left( \because \frac{d}{dx}(y+z) = \frac{dy}{dx} + \frac{dz}{dx} \right)$$

Q.4)  $y' = \alpha y$ ,  $\alpha > 0$ ,  $\alpha$  is constant. Show.

(i) If  $\phi$  is any sol<sup>n</sup> and  $\psi(x) = \phi(x)e^{-\alpha x}$ , then  $\psi(x)$  is a constant.

$$\frac{dy}{y} = \alpha dx$$

$$\ln y = \frac{\alpha x^2}{2} + \beta.$$

$$\therefore y = e^{\frac{\alpha x^2}{2} + \beta}$$

$$\psi(x) = C e^{\frac{\alpha x^2}{2}}$$

$$= C e^{\frac{\alpha}{2}(x^2 - x^2 + 2x + 1)} = C e^{\frac{\alpha}{2}(x+1)^2}$$

## Theory Continued.

More about IF for  $M(x,y)dx + N(x,y)dy = 0$  — ①.

Suppose  $F \equiv F(x,y)$  is IF for ①;

$$\Rightarrow \left( \frac{\partial}{\partial y} (FM) = \frac{\partial}{\partial x} (FN) \right)$$

$$\left\{ FM dx + FN dy = 0 \right.$$

As this eqn is exact;

$$\left. \frac{\partial}{\partial y} (FM) = \frac{\partial}{\partial x} (FN) \right\}$$

$$\Rightarrow \boxed{\frac{\partial F}{\partial y} M + F \cdot \frac{\partial M}{\partial y} - \frac{\partial F}{\partial x} N + F \cdot \frac{\partial N}{\partial x}} = 0 \quad \text{--- ②}$$

$$\text{Assume; } F \equiv F(x) \text{ Then } \frac{\partial F}{\partial y} = 0 \text{ & } \frac{\partial F}{\partial x} = \frac{dF}{dx} \quad \text{--- ③}$$

From ② & ③, we now obtain

$$\frac{F \cdot \partial M}{\partial y} = \frac{dF}{dx} N + F \cdot \frac{\partial N}{\partial x}$$

$$\Rightarrow \frac{dF}{dx} = \frac{FM_y - FN_x}{N}$$

$$\Rightarrow \frac{dF}{F} = \frac{M_y - N_x}{N} dx$$

$$\Rightarrow F = e^{\int \frac{M_y - N_x}{N} dx}$$

→ If  $\frac{My - Nx}{N} = R(x)$  then.

$$\Rightarrow F = e^{\int R(x) dx}$$

Assume,  $F = F(y)$ ; Then  $\frac{\partial F}{\partial x} = 0$  &  $\frac{\partial F}{\partial y} = \frac{\partial F}{\partial y}$

from ② & ④.

$$\frac{dF \cdot M}{dy} + F \cdot \frac{\partial M}{\partial y} = F \cdot \frac{\partial N}{\partial x}$$

$$\frac{dF}{dy} = \frac{FN_x - FM_y}{M}$$

$$\Rightarrow \frac{dF}{F} = \frac{Nx - My}{M} dy$$

Result II :-

$$\Rightarrow F = e^{\int R(y) dy}$$

$$F R(y) = \left( \frac{Nx - My}{M} \right)^{-1}$$

\* Some More useful results.

(III) Eqn ①  $\Rightarrow (M_1 y) dx + (N_1 x) dy = 0$

$$\& M_2 - N_2 \neq 0 \quad M = M_1 y$$

then

$$IF = \pm$$

$$Mx - Ny$$

(IV) If M and N are homogeneous functions  $\Rightarrow \text{form} \left( \frac{y}{x} \right)$

in (1);  $Mx + Ny \neq 0$ . Then

$$\text{IF} = 1$$

$$Mx + Ny$$

$$(xy \sin xy + \cos xy) \cdot y dx + (xy \sin xy - \cos xy) x dy = 0$$

$$\Rightarrow Mx - Ny$$

$$= xy(xy \sin xy + \cos xy - xy \sin xy + \cos xy) \\ = 2xy \cos xy \neq 0.$$

$$\Rightarrow \text{IF} = 1$$

$$2xy \cos xy$$

$$\frac{(xy \sin xy + \cos xy)y \cdot dx}{2xy \cos xy} + \frac{(xy \sin xy - \cos xy)x dy}{2xy \cos xy} = 0$$

$$\Rightarrow \left( \frac{\tan xy + 1}{2} \right) dx + \left( \frac{x \cdot \tan xy}{2} - \frac{1}{2y} \right) dy = 0$$

$y = f(x)$ ;  $f(x, y) = c$ ;  $\boxed{f(x, y, c) = 0} \Rightarrow$  preferred form of soln.

D.E. from given curve.

e.g.  $x^2 + y^2 = 2cx \quad \text{--- (1)}$

where  $c$  is a parameter.

$$2x + 2y \cdot \frac{dy}{dx} = 2c \quad \text{--- (2)}$$

not required  $x \cdot 2x \cdot \frac{dx}{dy} + 2y = 2c \cdot \frac{dx}{dy} \quad \text{--- (3)}$

from (1)  $\Rightarrow$  we obtain  $c = \frac{x^2 + y^2}{2x}$  put it  
into (2);

$$2x + 2y \cdot \frac{dy}{dx} = \frac{x^2 + y^2}{x}$$

$$\Rightarrow 2y \cdot \frac{dy}{dx} = \frac{y^2 - x^2}{x}$$

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$$\Rightarrow \boxed{\frac{dy}{dx} = -\frac{y^2 - x^2}{2xy}}$$

E.g.  $x^2 + y^2 = c^2 \Leftrightarrow$  (1);  $c$  is parameter.

$$2x + 2y \cdot \frac{dy}{dx} = 0 \quad \text{--- (2)}$$

$$\Rightarrow \boxed{\frac{dy}{dx} = -\frac{x}{y}}$$

\* Algorithm :-

- ① Write eqn as it is
- ② Differentiate with independent variable (generally  $x$ )
- ③ Eliminate  $c$  from both of above equations.

\* Geometrical view of first order ODE :-

derivative of solution curve at  $(x, y)$

$$\frac{dy}{dx} = f(x)y \Rightarrow y = g(x)$$

\* Topic to learn :-

IVP / General soln of DE / Particular soln / Interval of validity.

$$\frac{dy}{dx} = 6y^2x \Rightarrow \text{differential equation}$$

Initial value

$$y(1) = \frac{1}{25} \Rightarrow \text{Initial value problem}$$

problem condition

$$\Rightarrow \frac{dy}{y^2} = 6x dx \Rightarrow -\frac{1}{y} = 3x^2 + C$$

put  $y(1) = 1/25$  in general solution of DE

$$C = -3 - \frac{1}{1/25} = -28$$

Thus, particular solution of IVP.

$$-\frac{1}{y} = 3x^2 - 28 \Rightarrow \boxed{y = \frac{1}{28 - 3x^2}}$$

$$y = \frac{1}{28 - 3x^2} \quad \text{Interval of Validity} \\ \downarrow \quad \begin{array}{c} I_1 \quad I_2 \quad I_3 \\ \sqrt{\frac{28}{3}} \quad \frac{28}{3} \quad \sqrt{\frac{28}{3}} \end{array}$$

$(-\sqrt{\frac{28}{3}}, \sqrt{\frac{28}{3}})$ .

The above function  $y$  is valid in  $I_2$  interval only. Because if we include  $I_1$  &  $I_3$  the function will be discontinuous at some points i.e. not differentiable.

\*  $(\cos x) \frac{dy}{dx} + (\sin x)y = 2\cos^3 x \sin x - 1$ ,

$$I_{\frac{\pi}{4}} = 3\sqrt{2}; \quad 0 \leq x < \frac{\pi}{2}$$

$$\Rightarrow \frac{dy}{dx} + y \cdot \tan x = \frac{2\cos^3 x \sin x - 1}{\cos x}$$

$$\text{IF } \Rightarrow e^{\int \tan x dx} = e^{\ln \sec x} = \sec x$$

$$\sec x \frac{dy}{dx} + y \cdot \sec x \cdot \tan x = 2\sin x \cos x - \sec^2 x$$

$$(\sec x y)' = 2\sin x \cos x - \sec^2 x$$

$$\Rightarrow y \sec x = \int \sin 2x dx - \int \sec^2 x dx$$

$$\Rightarrow y \sec x = -\frac{\cos 2x}{2} - \tan x + C$$

$$3\sqrt{2} \cdot (\sqrt{2}) = -1 + C$$

$$\Rightarrow C = 7$$

$$\Rightarrow \frac{dy}{dx} = -\frac{\cos 2x}{2} - \tan x + 7.$$

$$* \frac{dy}{dx} - y = 4 \sin(3x) ; y(0) = y_0.$$

$$\frac{dy}{dx} - y = 2 \sin(3x).$$

$$\Rightarrow \text{IF } \Rightarrow e^{\int -1/2 x dx} \Rightarrow y(x) =$$

$$\Rightarrow e^{-x/2} \cdot \frac{dy}{dx} - y \cdot e^{-x/2} = 2e^{-x/2} \sin(3x).$$

$$\Rightarrow \frac{d}{dx} (y \cdot e^{-x/2}) = 2e^{-x/2} \sin(3x)$$

$$\Rightarrow y \cdot e^{-x/2} = 2 \int e^{-x/2} \sin(3x) dx.$$

$$\begin{aligned} I &= \int e^{-x/2} \sin(3x) dx \\ &= \sin(3x) \left( -\frac{1}{2} \right) \cdot e^{-x/2} - \int \frac{1}{2} \cdot e^{-x/2} \cdot 3 \cos 3x dx \\ &= -2 \sin(3x) e^{-x/2} + \frac{6}{4} \left[ \cos 3x \left( -\frac{1}{2} \right) e^{-x/2} + 6 \left( \frac{1}{2} \right) e^{-x/2} \right] dx \\ &= -2e^{-x/2} \sin(3x) - \frac{12}{4} \cos 3x \cdot e^{-x/2} - 36 I. \end{aligned}$$

$$37I = -2 (\sin(3x) \cdot e^{-x/2} + 6 \cos 3x \cdot e^{-x/2})$$

$$\Rightarrow y \cdot e^{-x/2} = \frac{-4}{37} \sin(3x) \cdot e^{-x/2} - \frac{24}{37} \cos 3x \cdot e^{-x/2}$$

$$y(x) = \frac{-24}{37} \cos 3x - \frac{4}{37} \sin 3x + \left( y_0 + \frac{24}{37} \right) e^{3x/2}$$

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Now, consider if we were given

$$y_0 < -\frac{24}{37}, \quad x \rightarrow \infty \quad y \rightarrow \infty$$

$$y_0 > -\frac{24}{37}, \quad x \rightarrow \infty \quad y \rightarrow \infty$$

$$y_0 = -\frac{24}{37}, \quad x \rightarrow \infty \quad y(x) = \frac{-24}{37} \cos 3x - \frac{4}{37} \sin 3x$$

Existence Theorem :-

\* Consider  $\begin{cases} \frac{dy}{dx} = f(x, y) \\ y(x_0) = y_0 \end{cases}$  IVP +  $x \in [x_0 - \delta, x_0 + \delta] = I$

If  $f$  is continuous on  $I$  then

IVP has a solution in some interval  $[x_0 - \epsilon, x_0 + \epsilon]$

\* Uniqueness Theorem :-

Consider  $\begin{cases} \frac{dy}{dx} = f(x, y) \\ y(x_0) = y_0 \end{cases}$  IVP +  $x \in [x_0 - \delta, x_0 + \delta] = I$

If  $f$  is continuous on  $I + \frac{\partial f}{\partial y}$  is bounded on  $I$  then IVP has a solution  $y$  in some interval  $[x_0 - \epsilon, x_0 + \epsilon]$ .

Recall: Consider  $\frac{dy}{dx} = f(x, y); y(x_0) = y_0$

*only sufficient tests* existence

$f$  is continuous near  $(x_0, y_0)$

uniqueness.

$f$  is cont. +  $\frac{\partial f}{\partial y}$  is bounded } near  $(x_0, y_0)$

bounded  $\Rightarrow \left| \frac{\partial f}{\partial y} \right| \leq k$  (finite)

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Q.  $\frac{dy}{dx} = y^{1/3}; y(0) = 0$

$$\Rightarrow \frac{dy}{y^{1/3}} = dx$$

$$\Rightarrow \frac{3}{2} y^{-2/3} = x + C.$$

$$\Rightarrow y^{2/3} = \frac{2}{3}(x+C)$$

$$\Rightarrow y^{2/3} = \frac{2}{3}x$$

using  $y(0) = 0$ .

$$\Rightarrow y = \pm \left( \frac{2x}{3} \right)^{3/2}$$

$$+ y=0,$$

Now check

$$\frac{\partial f}{\partial y} = \frac{1}{3} y^{-2/3}$$

Not bounded.

(but this does not imply)  
non-unique solution.

On the other hand,  
existence of multiple solns

implies  $f$  is non-conts.

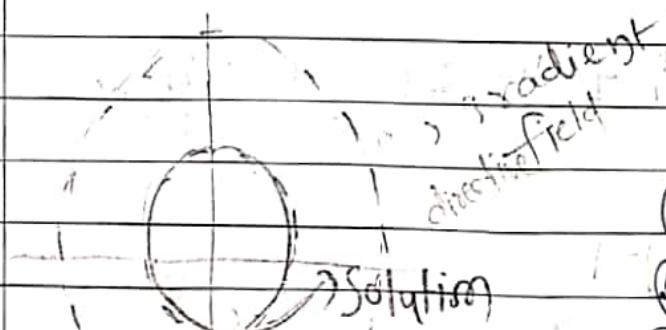
or  $\frac{\partial f}{\partial y}$  is not bounded.

\* Geometrical view :-

directive  
gradient/field

$$\longleftrightarrow \frac{dy}{dx} = f(x, y)$$

Solution  $\rightarrow$  Solution curve / Integral curve / Repres. curve



\* Algorithm:- (to draw).

- ① Take any slope  $c$ .
- ② Plot  $f(x, y) = c$  (isocline)
- ③ Draw line elements on above isocline with slope  $c$ .

$$\frac{dy}{dx} = 1 + x - y.$$

Solution curve

I Let,  $c = -1$ 

$$\text{II Plot } 1+x-y = -1 \\ \Rightarrow y-x = 2$$

III let  $c = 0$ 

$$\text{IV Plot } 1+x-y = 0 \\ \Rightarrow y-x = 1$$

V let  $c = 1$ 

$$\text{VI Plot } 1+x-y = 1 \\ \Rightarrow xy = 0$$

isodime

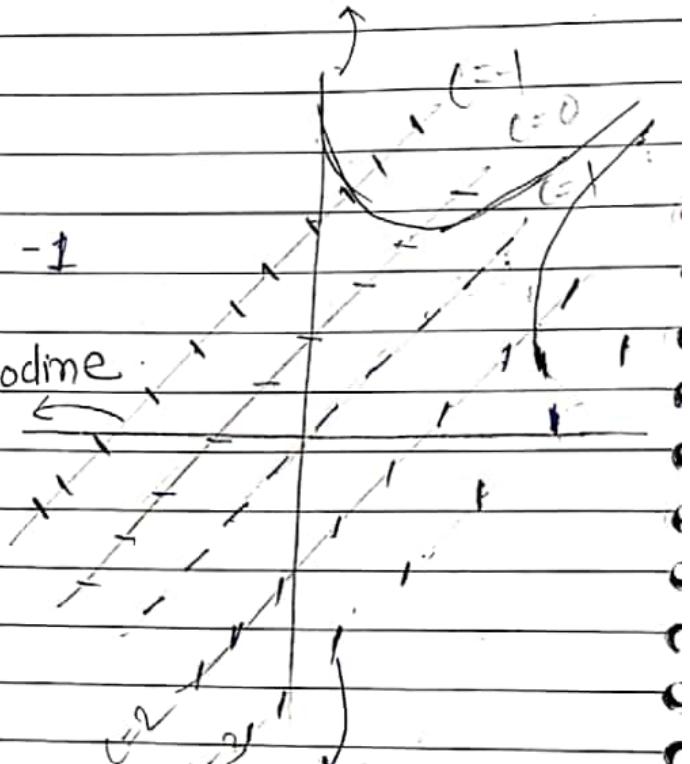


Fig. Gradient field corresponding  
to differential eqn.

Picard's Iterative Method

$$\frac{dy}{dx} = f(x, y) \rightarrow \int_{x_0}^x \frac{dy}{ds} ds = \int_{x_0}^x f(s, y) ds.$$

$$y(x_0) = y_0 \rightarrow y(x) = y(x_0) + \int_{x_0}^x f(s, y) ds$$

Start iteration

$$y_1(x) = y(x_0) + y(x_0) + \int_{x_0}^x f(s, y_0) ds$$

$$\text{Ex. } \frac{dy}{dx} = y ; y(0) = 1$$

$$y(x) = e^x.$$

$$y(x) = y(x_0) + \int_{x_0}^x y(s) ds$$

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$$y_1(x) = 1 + \int_{x_0}^x y_0(s) ds = 1 + \int_0^x ds = 1+x.$$

$$y_2(x) = y(x_0) + \int_{x_0}^x f(s, y_1) ds.$$

$$y_2(x) = 1 + \int_0^x (1+s) ds.$$

$$y_2(x) = 1 + x + \frac{x^2}{2}$$

$$y_3(x) = 1 + \int_0^x (1+s+\frac{s^2}{2}) ds.$$

$$y_3(x) = 1 + x + \frac{x^2}{2} + \frac{x^3}{6}$$

\* Tut. Ass. I . Sem II .

$$Q.7) \quad y' = \frac{1 - xy^2}{2x^2y}$$

$$y = vx^n$$

$$y' = nvx^{n-1} + x^n v'$$

$$nvx^{n-1} + x^n v' = \frac{1 - vx^{2n+1}}{2x \cdot vx^{n+2}}. \quad n = -\frac{1}{2},$$

Q.5) Ass. II.  $\Rightarrow$  Wronskian  $\left| \begin{array}{cc} y_1 & y_2 \\ y'_1 & y'_2 \end{array} \right| = W$

~~Given~~  $y'' + p(x)y' + q(x)y = 0$

$y_1$  &  $y_2$  are solution then

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$$\Rightarrow y_1'' + p(x)y_1' + q(x)y_1 = 0 \quad \text{--- (1)} \quad W = y_1y_2' - y_1'y_2$$

$$y_2'' + p(x)y_2' + q(x)y_2 = 0 \quad \text{--- (2)} \quad W' = y_1y_2'' - y_1''y_2$$

$$\text{Q.3) } \Rightarrow \quad \text{(1)} \times y_2 - \text{(2)} \times y_1 \Rightarrow (y_2y_1'' - y_1y_2'') + p(x)(y_2y_1' - y_1'y_2) = 0$$

$$\Rightarrow -W' + p(x)(-W) = 0$$

$$\Rightarrow \frac{dW}{W} = -p(x)dx$$

$$\Rightarrow W = c \cdot e^{-\int p(x)dx} \neq 0$$

Thus;  $W=0$  iff  $c=0$   
 $W \neq 0$  if  $c \neq 0$ . Hence, proved.

Q.6) (a)  $y'' + 3y' + 2y = 0$  . ( $y = e^{mx}$ ).

$\Rightarrow$  find  $m$ .

$$\Rightarrow m^2e^{mx} + 3me^{mx} + 2e^{mx} = 0$$

$$\Rightarrow e^{mx}(m^2 + 3m + 2) = 0$$

$$m = -1 ; -2$$

$$\therefore y = e^{-x} ; e^{-2x}$$

if  $y_1$  &  $y_2$  are L.D.  $y_2 = cy_1$

Q.7)  $\Rightarrow W = \left| \begin{array}{cc} y_1 & cy_1 \\ y'_1 & cy'_1 \end{array} \right| = 0 \Rightarrow \underline{\underline{W=0}}$

only if  $W=0$

$$\underline{y_1y_2' - y_2y_1'} = 0$$

$$\Rightarrow \underline{y_1^2 \left( \frac{y_2}{y_1} \right)' = 0} \Rightarrow \underline{\underline{y_2 = cy_1}}$$

$$Q.6) (b) \quad y = x^m$$

$$\begin{aligned} (i) \quad & x^2 y'' - 4xy' + 4y = 0 \\ \Rightarrow & x^2(m(m-1)x^{m-2}) - 4x(m(x^{m-1})) + 4x^m = 0 \\ \Rightarrow & x^m(m^2 - m - 4m + 4) = 0 \\ \Rightarrow & \text{As } x > 0 \Rightarrow x^m \neq 0 \\ \Rightarrow & m^2 - 5m + 4 = 0 \quad \Rightarrow m = 1, 4 \\ \Rightarrow & y = x^4, x. \end{aligned}$$

$$Q.4) \Rightarrow W(y_1, y_2) = y_1 y_2' - y_1' y_2 \quad (\text{Wronskian of } y'' + P(x)y' + Q(x)y = 0)$$

$$\frac{dW}{dx} = y_1 y_2'' + y_1'' y_2' - y_1' y_2'' - y_1'' y_2.$$

$$\begin{aligned} \frac{dW}{dx} &= y_1 y_2'' - y_1'' y_2 \\ y_1'' + P(x)y_1' + Q(x)y_1 &= 0 \\ y_2'' + P(x)y_2' + Q(x)y_2 &= 0. \end{aligned}$$

$$\begin{aligned} \Rightarrow y_1'' &= -P(x)y_1' - Q(x)y_1 \\ \Rightarrow y_2'' &= -P(x)y_2' - Q(x)y_2. \end{aligned}$$

$$\therefore \frac{dW}{dx} = P(x)(y_1'y_2 - y_1'y_2').$$

$$\therefore \frac{dW}{dx} = P(x) \cdot (-W(x)).$$

$$\Rightarrow W(x) = C e^{-\int P(x).dx} \neq 0.$$

If  $C = 0$ ;  $W = 0$

$C \neq 0$ ;  $W \neq 0$ .

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$$M(x, y) \cdot dx + N(x, y) \cdot dy = 0 \quad \text{--- (1)}$$

be a non-exact DE.

Let  $\phi(x, y)$  be IF of (1).

$\phi M dx + \phi N dy = 0 \quad \text{--- (2)}$  will be exact.

So,  $\exists$  a function s.t.

$$\phi[f(x, y)] = \phi M dx + \phi N dy.$$

Let;  $G$  be any arbitrary;  $G = G(f)$ .

Now,  $G(f) \cdot \phi(x, y)$  will be IF also.

e.g.  $x dy - y dx = 0$

$$M = -y, \quad N = x$$

$$My = -1, \quad Nx = 1$$

IF.  $\phi(x, y) = \frac{1}{y^2}$

$$\frac{1}{y^2} (x dy - y dx) = 0$$

$$\Rightarrow \frac{x \cdot dy}{y^2} - \frac{dx}{y} = 0 \quad \Rightarrow \text{Soln} \\ \Rightarrow \frac{x}{y} = c$$

$$M = \frac{-1}{y}, \quad N = \frac{x}{y^2}$$

$$\Rightarrow My = \frac{1}{y^2}, \quad Nx = \frac{1}{y^2}$$

then.  $G\left(\frac{x}{y}\right) \cdot \frac{1}{y^2}$  will be I.F.

e.g.  $\frac{x}{y} \left(\frac{1}{y^2}\right), \quad \left(\frac{1}{y^2}\right) \cdot \sin\left(\frac{x}{y}\right)$

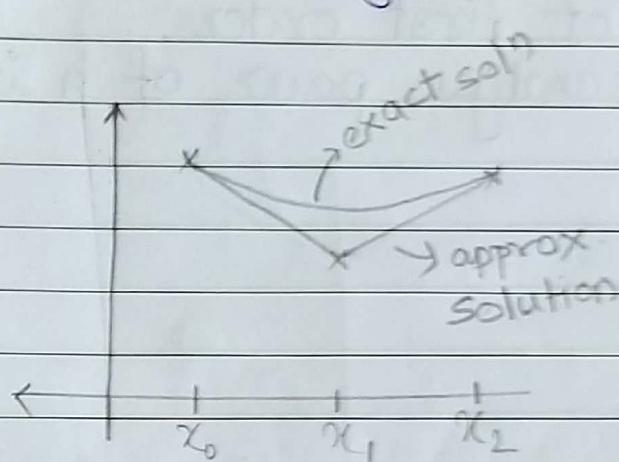
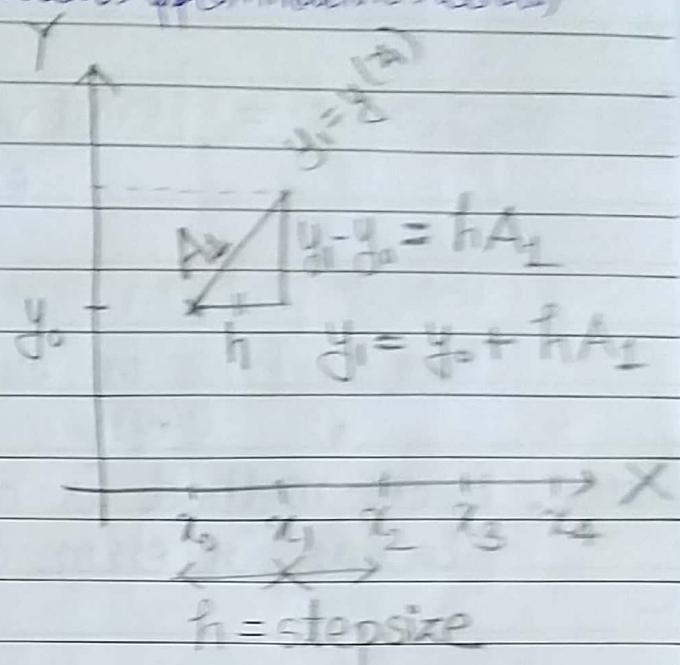
$$\frac{dy}{dx} = f(x, y) ; y(x_0) = y_0 \quad \frac{dy}{dx} = x^2 y^2 ; y(0) = 1$$

\* Euler's Method :- (Numerical Approximation Method)

$$x_{n+1} = x_n + h$$

$$y_{n+1} = y_n + h A_n$$

$$A_n = f(x_n, y_n)$$



$$\left\{ \frac{y_1 - y_0}{h} \approx f(x_0, y_0) \right.$$

\* We can find an approximate solution through this method.

$\frac{dy}{dx} = x^2 y^2$	$n$	$x_n$	$y_n$	$A_n = f(x_n, y_n)$	$h A_n$
	0	0	1	-1	-0.1
	1	0.1	0.9	$(0.1)^2 - (0.9)^2$	

$$y(0) = 1$$

$$h = 0.1$$

plot curve using values in above table

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$$* \frac{dy}{dx} + 2y = 2 - e^{-4x} \quad | \quad \text{Take step size } h = 0.1 \\ y(0) = 1 \quad | \quad y(0.1), y(0.2), y(0.3), \\ y(0.4), y(0.5)$$

↗  $y(x)$  (analytic)

Calculate.

$$\text{Absolute \% error} = \left| \frac{\text{exact value} - \text{approx. value}}{\text{exact value}} \right| \times 100$$

Repeat problem for  $h = 0.05$ 

Claim :- Error in euler's method is of order  $h$ .  
 i.e.  $E \sim h$ .

hence, euler's method is of first order.  
 (because in error analysis power of  $h$  is 1)

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$$x_{n+1} = x_n + h$$

$$k_1 = f(x_n, y_n)$$

$x_0 \quad x_1 \quad x_2$

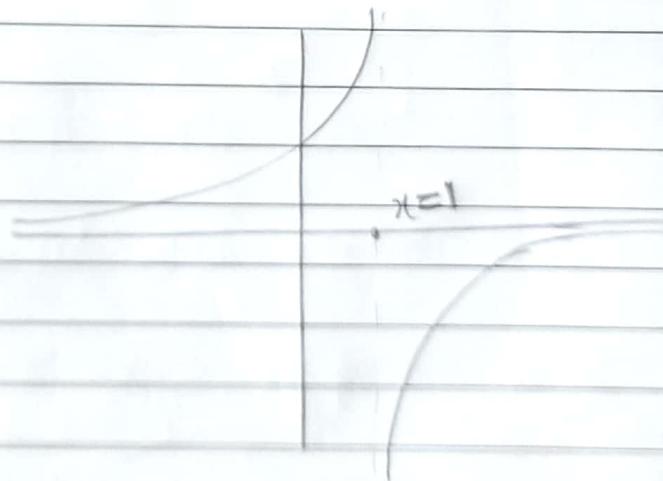
$$k_2 = f\left(x_n + \frac{h}{2}, y_n + \frac{k_1 h}{2}\right)$$

$$y_{n+1} = y_n + h k_2$$

$$\epsilon \sim h^2$$

\*  $\frac{dy}{dx} = y^2$ ,  $0 \leq x \leq 2$ ,  $y(0) = 1$

Ans.  $y = \frac{1}{1-x}$



Singularity in curve at  $x=1$ .

$$a_0(x) \frac{d^2y}{dx^2} + a_1(x) \frac{dy}{dx} + \dots + a_n(x) y = f(x)$$

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## \* Linear Differential Equations of second order :-

St. form 
$$\frac{d^2y}{dx^2} + p(x) \cdot \frac{dy}{dx} + q(x) \cdot y = r(x) \quad \text{--- } \circledast$$

If  $r(x) \equiv 0$ ; then  $\circledast$  is called homogeneous differential equation.

If  $p, q$  and  $r$  are constant then  $\circledast$  is called diff. equation of constant coefficients.

Consider 
$$\frac{d^2y}{dx^2} + p(x) \frac{dy}{dx} + q(x) \cdot y = 0 \quad \text{--- } \circledcirc$$

General solution 
$$y = c_1 y_1 + c_2 y_2$$

where  $y_1$  and  $y_2$  are two L.I solutions of  $\circledcirc$   
 $c_1$  &  $c_2$  are arb. constants

## Existence / Uniqueness :-

Equation  $\circledast$  with initial data  $y(x_0) = y_0$ ;  
 $y'(x_0) = y_1$  has unique solution if  $p, q, r$  are continuous functions in  $[a, b]$ . [Here  $x_0 \in [a, b]$ ]

Theorem :- If  $y_1$  and  $y_2$  are any two solutions of  $\circledcirc$  on  $[a, b]$ . Then their Wronskian  $W(y_1, y_2)$  is either identically zero or never zero. Further  $y_1$  &  $y_2$  are LD iff  $W(y_1, y_2)$  is identically zero.

Proof:

$$W(y_1, y_2) = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} = y_1 y_2' - y_2 y_1'$$

$$\Rightarrow W' = y_1 y_2'' + y_1' y_2' - y_2 y_1'' - y_2' y_1' \quad \text{--- (2)}$$

$$W' = y_1 y_2'' - y_2 y_1'' \quad \text{--- (2)}$$

Since  $y_1, y_2$  are sol' of (1) i.e.

$$y_1'' + p y_1' + q y_1 = 0 \quad \text{--- (3)}$$

$$y_2'' + p y_2' + q y_2 = 0 \quad \text{--- (4)}$$

from  $y_2 \times (3) - y_1 \times (4)$ , we obtain.

$$y_2 y_1'' + y_2' p y_1' + q y_1 = 0$$

$$- y_1 y_2'' - y_1' p y_2' - q y_2 = 0$$

$$(y_2 y_1'' - y_1 y_2'') + p [y_2 y_1' - y_1 y_2'] = 0$$

$$\Rightarrow \frac{dW}{dx} + pW = 0 \quad \text{--- (5)}$$

from (5), we obtain

$$W = C \cdot \underbrace{e^{-\int p(x) dx}}_{\neq 0}$$

Thus,

$W \equiv 0$  if  $C = 0$ .

OR  $W$  is never zero if  $C \neq 0$ .

$\Rightarrow$  if  $y_1$  &  $y_2$  are LD  $\Rightarrow y_2 = cy_1$ .

$$\text{Then, } W = \begin{vmatrix} y_1 & cy_1 \\ y_1' & c.y_1' \end{vmatrix} = 0 \rightarrow \boxed{W=0}$$

only if

$$W=0$$

$$\frac{y_1 y_2'' - y_2 y_1''}{y_1^2} = 0$$

$$\Rightarrow \left(\frac{y_2}{y_1}\right)' = 0 \rightarrow \boxed{y_2 = cy_1}$$

Consider  $y'' + py' + qy = 0$  (p & q are real constant functions)  $(p, q \in \mathbb{R})$ .

Theorem: If  $(u+iv)$  is a complex solution of ④. Then  $u$  and  $v$  are two solutions of ②.

Proof:  $(u+iv)'' + p(u+iv)' + q(u+iv) = 0$ .

$$\Rightarrow (u'' + pu' + qu) + i(v'' + pv' + qv) = 0.$$

$$\Rightarrow u'' + pu' + qu = 0$$

$$\& v'' + pv' + qv = 0.$$

Hence, proved.

Theorem: If  $y_1$  is a solution of ② then  $\exists u(x)$  s.t.  $y_2 = y_1 u$  is also a solution of ②.

Step 3: Put,  $y_2$  in ①.

$$y_1''u + 2y_1'u' + y_1u'' + p(y_1u + y_1u') + q(y_1u) = 0$$

$$\Rightarrow \underbrace{(y_1'' + py_1' + qy_1)}_{=0} u + (2y_1' + py_1)u' + y_1u'' = 0$$

as  $y_1$  is a solution.

$$\Rightarrow y_1 A' + (2y_1' + py_1)A = 0 \quad (A = u)$$

On solving,  $A = \frac{1}{y_1^2} \cdot e^{-\int p(x) dx}$

$$\Rightarrow \boxed{u = \int \frac{1}{y_1^2} \cdot e^{-\int p(x) dx} dx}$$

Assume  $y = e^{mx}$  is a solution of  $y'' + py' + qy = 0$ .

$$m^2 \cdot e^{mx} + pm \cdot e^{mx} + qe^{mx} = 0$$

$$\Rightarrow (m^2 + pm + q)e^{mx} = 0$$

$$\Rightarrow \boxed{m^2 + pm + q = 0} \quad m = \frac{-p \pm \sqrt{p^2 - 4q}}{2}$$

Step ④. Write Auxilliary equation wrt. DE  
 $m^2 + pm + q = 0$ .

Case ① :  $p^2 > 4q$

we get two distinct real roots say  $m_1$  and  $m_2$ .

Case (II) :  $P^2 < 4q$ .

$$m = a \pm ib$$

$$y = e^{(a+ib)x} = e^{ax} e^{ibx} = e^{ax} (\cos bx + i \sin bx)$$

$y_1, y_2 = e^{ax} \cos bx, e^{ax} \sin bx$  are solutions

Case (III) :  $P^2 = 4q$

$$m = m_1, m_2$$

$$y_1 = e^{m_1 x} = e^{-P_1(x)}$$

$$y_2 = \left[ \int \frac{1}{y_1} e^{-\int P(x) dx} dx \right] y_1 \Leftrightarrow u y_1$$

$$\Rightarrow u = \int \frac{1}{e^{-Px}} e^{-Px} dx = x.$$

$$\Rightarrow y_2 = x y_1 = x e^{m_1 x}. \Rightarrow y_2 = x e^{m_1 x}$$

Step (II) Solve Aux. eqn - for  $m$

↓  
Case (I)

$$m = m_1, m_2 \text{ (real)}$$

$$m_1 \neq m_2$$

$$\text{G. soln. } y = c_1 e^{m_1 x} + c_2 e^{m_2 x}$$

↓  
Case (II)

$$m = a \pm ib$$

$$y = e^{ax} [c_1 \cos bx + c_2 \sin bx]$$

↓  
Case (III)

$$m = m_1, m_2$$

$$m_1 = m_2 = m$$

$$y = e^{mx} [c_1 + c_2 x]$$

\* Bank Account Model :-

$x(t)$  = money in account at time  $t$ .

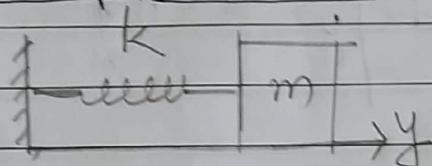
$I(t)$  = Interest rate / money time.

$q(t)$  = deposit rate / time.

$$x(t + \Delta t) - x(t) = I(t) \cdot x(t) \Delta t + q(t) \Delta t$$

$$\Rightarrow \frac{dx}{dt} - I(t) \cdot x(t) = q(t).$$

\* Undamped Oscillations :-



$$m \cdot \frac{d^2y}{dt^2} = -ky.$$

$$\Rightarrow y'' + \frac{k}{m} y = 0$$

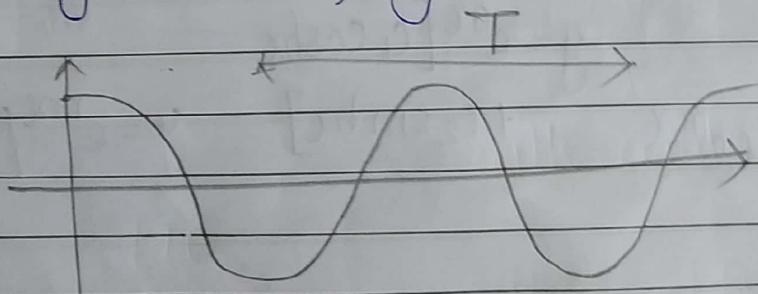
$$m^2 + \omega_0^2 = 0 \Rightarrow m = \pm i\omega_0.$$

$$a=0, b=\omega_0.$$

$$\therefore y = e^{(0)x} [c_1 \cos \omega_0 t + c_2 \sin \omega_0 t].$$

$$y(t) = c_1 \cos \omega_0 t + c_2 \sin \omega_0 t.$$

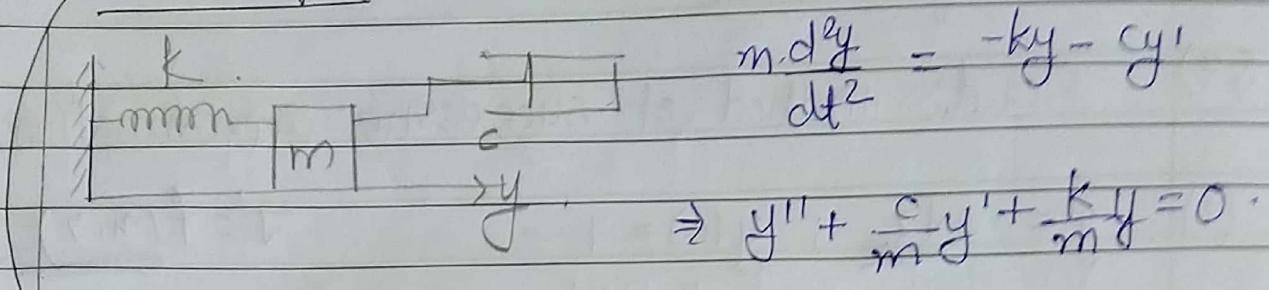
$$y(0) = 1; y'(0) = 0.$$



$$T = \frac{2\pi}{\omega_0}; \quad \text{freq.} = \frac{\omega_0}{2\pi} = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$$

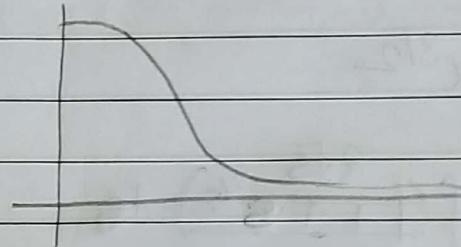
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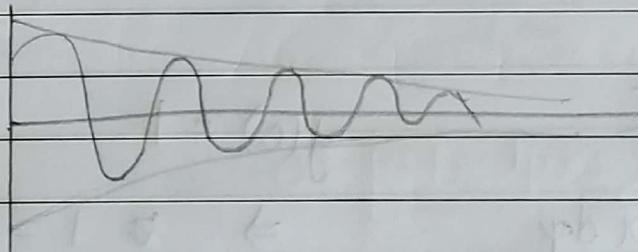
$$y'' + 4y' + 3y = 0$$

Auxiliary equation:  $m^2 + 4m + 3 = 0$        $y = c_1 e^{-t} + c_2 e^{-3t}$   
 $m = -1, -3$



$$y'' + 4y' + 5y = 0 \quad (\text{Underdamped})$$

$$m^2 + 4m + 5 = 0 \quad y = e^{-2t} [c_1 \cos t + c_2 \sin t]$$
$$m = -2 \pm i$$



$$y'' + 4y' + 4y = 0 \quad (\text{critically damped})$$

Q7). Ricard's method of successive approximation.

(i)  $y^1 = \underline{2\sqrt{x}}$ ;  $y(0) = 1$   $\bar{f} = f(x, y) = \underline{5x}$

$$\Rightarrow y_{n+1} = y_n + \int_0^x f(x, y_n) dx$$

$$y_1 = 1 + \int_0^x 2\sqrt{s} ds \quad f(x, y_1) = 5x$$

$$y_1 = 1 + \frac{4}{3}x^{3/2}$$

$$y_2 = 1 + \int_0^x \left(1 + \frac{4}{3}s^{3/2}\right) ds$$

$$= 1 + \frac{4}{3}x^{3/2}$$

$$\Rightarrow y_n = 1 + \frac{4}{3}x^{3/2}$$

$$\frac{dy}{dx} = 2\sqrt{x} \quad y(0) = 1$$

$$dy = 2\sqrt{x} dx \Rightarrow 1 = C$$

$$y = \frac{4}{3}x^{3/2} + C \Rightarrow y = 1 + \frac{4}{3}x^{3/2}$$

with constant coefficients

LDE

with variable coefficients.

Q.1) (i)  $y'' - 4y' + 3y = 0$

$$\Rightarrow m^2 - 4m + 3 = 0$$

$$m^2 - 3m - m + 3 = 0$$

$$m(m-1) - 3(m-1) = 0$$

$$m=1, 3$$

$\therefore y = C_1 e^x + C_2 e^{3x}$  is the solution

Q.2)

(ii)  $(1-x^2) \cdot y'' - 2xy' + 2y = 0, \quad y_1 = x$

$$\Rightarrow y'' - \left(\frac{2x}{1-x^2}\right)y' + \left(\frac{2}{1-x^2}\right)y = 0$$

$$\sqrt{y_2(x)} = u y_1(x) \quad y(x) = C_1 y_1(x) + C_2 y_2(x)$$

for  $y'' + p(x)y' + q(x)y = 0$

then  $u(x) = \int \frac{1}{y_1^2} e^{-\int p(x) dx} dx$

$$\Rightarrow u(x) = \int \frac{1}{x^2} e^{\int \frac{2x}{1-x^2} dx} dx$$

$$= \int \frac{1}{x^2} e^{-\log(1-x^2)} dx$$

$$u(x) = \int \frac{1}{x^2(1-x^2)} dx$$

$$\int \frac{1}{1-x^2} dx = \int \frac{1}{x^2} dx + \int \frac{1}{(1-x^2)} dx = \frac{-1}{x} + \frac{1}{2} \log\left(\frac{1+x}{1-x}\right)$$

$$= \int \frac{1}{2} \left( \frac{1}{1+x} + \frac{1}{1-x} \right) dx$$

$$y(x) = c_1 x + c_2 x \left\{ -\frac{1}{x} + \frac{1}{2} \log \left( \frac{1+x}{1-x} \right) \right\}$$

Q.3) (iv)  $y''' - 5y'' + 11y' - 6y = 0$

$$m^3 - 6m^2 + 11m - 6 = 0$$

$$m=1$$

$$\begin{array}{r|rrr} & 1 & -6 & 11 & -6 \\ & & 1 & -5 & 6 \\ \hline & 1 & -5 & 6 & 0 \end{array}$$

$$m^2 - 5m + 6 = 0 \quad m = 3, 2$$

$$m = 1, 2, 3$$

$\therefore y = c_1 e^x + c_2 e^{2x} + c_3 e^{3x}$  is the solution.

Q.4)

(ii)  $x^2 y'' + 2xy' - 12y = 0$

$\Rightarrow x^2 y'' + axy' + by = 0 \quad \dots \textcircled{1}$

Put  $x = e^z \Rightarrow z = \log x$

diff. w.r.t.  $x$ .

$$\Rightarrow \frac{dz}{dx} = \frac{1}{x}$$

Now,  $\frac{dy}{dx} = \frac{dy}{dz} \times \frac{dz}{dx} = \frac{1}{x} \cdot \frac{dy}{dz}$

$$\Rightarrow x \frac{dy}{dx} = \frac{dy}{dz} = xy$$

$$why n = D(D-1)(D-2)\dots(D-(n-1)).$$

$$xy^2 = D(D-1)\dots(D-(n-1))$$

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$$\frac{d}{dx} \left( \frac{dy}{dx} \right) = \frac{d}{dx} \left( \frac{1}{x} \cdot \frac{dy}{dz} \right) \quad xy = D.$$

$$= -\frac{1}{x^2} \cdot \frac{dy}{dz} + \frac{1}{x} \cdot \frac{d}{dx} \left( \frac{dy}{dz} \right)$$

$$\frac{d^2y}{dx^2} = -\frac{1}{x^2} \frac{dy}{dz} + \frac{1}{x} \cdot \frac{d^2y}{dz^2} \frac{dz}{dx}$$

$$\Rightarrow x^2 \cdot \frac{d^2y}{dx^2} = -\frac{dy}{dz} + x \cdot \frac{d^2y}{dz^2} \frac{dz}{dx}$$

$$= -\frac{dy}{dz} + x \cdot \frac{d^2y}{dz^2} \left( \frac{1}{x} \right).$$

$$\Rightarrow x^2 \cdot \frac{d^2y}{dx^2} = -\frac{dy}{dz} + \frac{d^2y}{dz^2} = x^2 y''.$$

① changes to

$$\Rightarrow \left( -\frac{dy}{dz} + \frac{d^2y}{dz^2} \right) + a \left( \frac{dy}{dz} \right) + by = 0$$

$$\Rightarrow \boxed{\frac{d^2y}{dz^2} + (a-1) \cdot \frac{dy}{dz} + by = 0} \quad \begin{matrix} \text{General} \\ \text{for ①.} \end{matrix}$$

for given eg.

$$\frac{d^2y}{dz^2} + \frac{dy}{dz} - 12y = 0$$

$$\Rightarrow m^2 + m - 12 = 0 \quad m = 3, -4$$

$$\Rightarrow y(z) = C_1 e^{3z} + C_2 e^{-4z}$$

$$y(x) = C_1 x^3 + C_2 x^{-4}$$

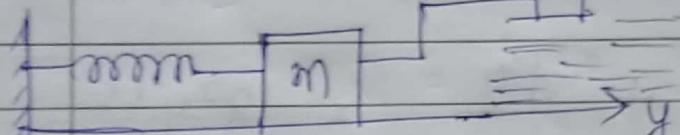
$$(ii) x^2 y'' + xy' + y = 0$$

$$\Rightarrow \frac{d^2y}{dx^2} + (1-1) \cdot \frac{dy}{dx} + y = 0$$

$$\Rightarrow \frac{d^2y}{dx^2} + y = 0.$$

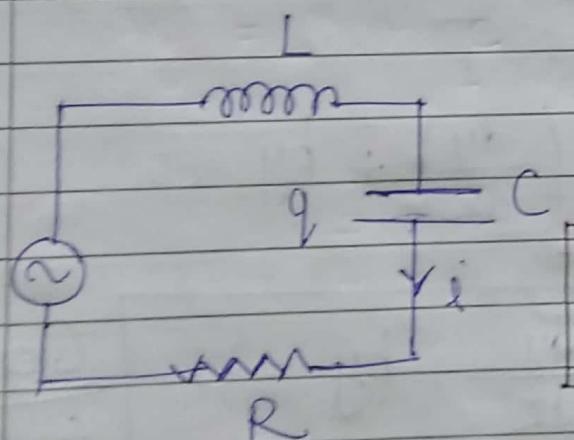
$$\Rightarrow m^2 + 1 = 0 \quad m = \pm 1$$

\*  $y''c + p(x)y' + q(x) \cdot y = r(x)$   
 (Inhomogeneous / Non-homogeneous)



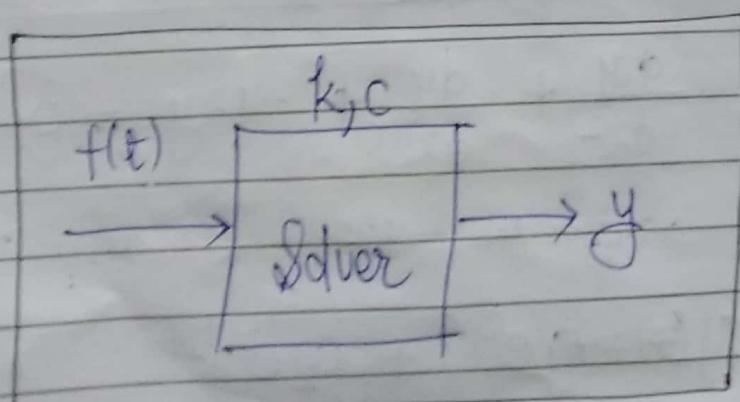
$$y'' = -ky - cy' + f(t)$$

$$\Rightarrow [y'' + cy' + ky = f(t)]$$



$$L \cdot \frac{di}{dt} + \frac{q}{C} + Ri = V_e$$

$$L \cdot \frac{d^2q}{dt^2} + R \cdot \frac{dq}{dt} + \frac{q}{C} = V_e$$



# Differential Operator is linear

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Date \_\_\_\_\_ How to find solution of

$$y'' + p(x) \cdot y' + q(x) \cdot y = r(x) \quad \text{--- (1)}$$

Gen. sol.  $y = y_c + y_p$

Corresponding homogeneous equation of (1)

$$y'' + p(x) \cdot y' + q(x) \cdot y = 0 \quad \text{--- (2)}$$

where,  $y_c$  = sol. of (2)  $\Rightarrow$  complementary sol.  
 $y_p$  = sol. of (1)  $\Rightarrow$  particular solution

$$\begin{array}{l|l} y'' + p y' + q y = r & D^2 y + p D y + q y = 0 \\ y'' + p y' + q y = 0 & \rightarrow (D^2 + p D + q) y = 0 \\ y(x_0) = y_0; y'(x_0) = y_1 & \rightarrow L y = 0 \\ & L = (D^2 + p D + q) \end{array}$$

Gen. sol.  $y = c_1 y_1 + c_2 y_2$

$$L(c_1 y_1 + c_2 y_2) = c_1 L(y_1) + c_2 L(y_2) = 0.$$

$$\left\{ \begin{array}{l} \{c_1 y_1 + c_2 y_2\} = u \\ \{c_1 y'_1 + c_2 y'_2\} \\ c_1 y_1(x_0) + c_2 y_2(x_0) = y_0 \\ c_1 y'_1(x_0) + c_2 y'_2(x_0) = y_1 \end{array} \right. \quad \left[ \begin{array}{l} y_1 \quad y_2 \\ y'_1 \quad y'_2 \end{array} \right] \left[ \begin{array}{l} c_1 \\ c_2 \end{array} \right] = \left[ \begin{array}{l} y_0 \\ y_1 \end{array} \right]$$

If  $L = D^2 + p D + q$ , then (1) becomes

$$Ly = r.$$

Given,  $L y_p = r$ ;  $Ly = r$

$$\therefore L(y - y_p) = 0$$

$\underbrace{\text{solution of homogeneous eqn}}$

$$\therefore y - y_p = y_c$$

$$\therefore \boxed{y = y_c + y_p} \text{ is the general solution}$$

{  $c_1 y_1 + c_2 y_2$  is only (unique) solution for DE }

# Variation of Parameters (VOP)

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$$y'' + py' + qy = r(x) \quad \text{--- (1)}$$

$$y'' + py' + qy = 0 \quad \text{--- (2)}$$

$$\textcircled{1} \quad \text{Solve. } \textcircled{2} \quad y_c = c_1 y_1 + c_2 y_2 \quad \left\{ \begin{array}{l} c_1 \text{ & } c_2 \text{ are} \\ \text{consts.} \end{array} \right\}$$

$$\textcircled{3} \quad y_p = f_1 y_1 + f_2 y_2 \quad \left\{ \begin{array}{l} f_1 \text{ & } f_2 \text{ are functions} \\ \text{of independent variable.} \end{array} \right\}$$

$$f_1 = \int \frac{W_1}{W} \cdot r \, dx = - \int \frac{Y_2}{W} r \, dx$$

$$f_2 = \int \frac{W_2}{W} \cdot r \, dx = \int \frac{Y_1}{W} r \, dx.$$

where,

$$W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$$

$W_j$  = replace  $j$ th col of  $W$  by  $\left\{ \begin{array}{l} \text{last column of I} \\ (\text{order of DE}) \end{array} \right\} \left\{ \begin{array}{l} [0] \\ [1] \end{array} \right\}$

$$W_1 = \begin{vmatrix} 0 & y_2 \\ 1 & y_2' \end{vmatrix} = -y_2.$$

$$W_2 = \begin{vmatrix} y_1 & 0 \\ y_1' & 1 \end{vmatrix} = y_1.$$

III

$$y = y_c + y_p.$$

$$Q. \quad y'' + y = \csc x$$

$$W = \begin{vmatrix} \sin x & \cos x \\ \cos x & -\sin x \end{vmatrix}$$

$$\Rightarrow \text{Aux eqn } m^2 + 1 = 0.$$

$$y = y_c + y_p.$$

$$y_c = C_1 \cos x + C_2 \sin x$$

$$y_p = f_1 \cos x + f_2 \sin x.$$

$$\text{where, } f_1 = \int \frac{W_1}{W} \cdot r \cdot dx = - \int \frac{y_2}{W} \cdot r \cdot dx$$

$$= - \int_{-1}^1 \sin x \cdot \csc x \cdot dx$$

$$\Rightarrow f_1 = -x.$$

$$f_2 = \int \frac{W_2}{W} \cdot r \cdot dx = + \int \frac{y_1}{W} \cdot r \cdot dx$$

$$\Rightarrow f_2 = \int \frac{\cos x}{\sin x} \cdot dx = \ln(\sin x).$$

Hence,

$$\therefore y = \underbrace{C_1 \cos x + C_2 \sin x}_{y_c} - x \cos x + \ln(\sin x) \sin x.$$

The: Hom. Eq<sup>n</sup>. Known  $\rightarrow y_1$ ;  $y_2 = uy_1$

$$\text{where, } u = \int \frac{1}{y_1^2} e^{-\int p(x) dx}$$

$$y'' + p y' + q y = 0$$

$$\Rightarrow y = x^m$$

$$\Rightarrow [m(m-1) + mp\chi + qx^2] \cdot x^{m-2} = 0$$

$$\Rightarrow m(m-1) + mp\chi + q\chi^2 = 0$$

If  $px + qx^2 = 0$  then  $y_1 = x$

$$z^2 + 2px + qz^2 = 0 \quad \text{then} \quad y_1 = z^2$$

$$\star x^2 y'' - 2x(1+x) \cdot y' + 2(1+x) \cdot y = x^3$$

$$\Rightarrow y'' - \frac{2x(1+x)}{x^2}y' + \frac{2(1+x)}{x^2}y = x.$$

$$px + qx^2 = 0 \quad \therefore \quad y_1 = x \text{ is one solution}$$

$$y_2 = u y_1 ;$$

$$u = \int \frac{1}{y_1^2} \cdot e^{\int p(x) dx} dx$$

$$= \int \frac{1}{x^2} \cdot e^{\int \frac{2x(1+x)}{x^2} dx} dx$$

$$\therefore I = e^{\int \frac{2(1+x)}{x} dx} = e^{\int \left(\frac{2}{x} + 2\right) dx}$$

$$= e^{+2 \cdot \ln x + 2x} \\ = e^{\ln(x^2)} = \frac{1}{x^2} e^{2x} = x^2 \cdot e^{2x}$$

$$u = \int \frac{1}{x^2} \cdot x^2 \cdot e^{2x} dx = \frac{e^{2x}}{2}$$

$$y_c = C_1 x + \frac{1}{2} C_2 x \cdot e^{2x}$$

$$y_p = f_1 x + f_2 \cdot \frac{x e^{2x}}{2}$$

$$W = \begin{vmatrix} x & \frac{x \cdot e^{2x}}{2} \\ 1 & \frac{e^{2x} + x^2 e^{2x}}{2} \end{vmatrix}$$

$$W = x e^{2x} + x^2 e^{2x}$$

$$f_1 = \int \frac{W_1 y}{W} dx = \int \frac{-y_2 x}{W} dx$$

$$W = x^2 \cdot e^{2x}$$

$$= - \int \frac{x \cdot e^{2x}}{2(x^2 e^{2x})} x dx$$

$$f_2 = \int \frac{W_2 y}{W} dx = \int \frac{y_1 x}{W} dx$$

$$= -\frac{x}{2}$$

$$= \int \frac{x \cdot x}{x^2 e^{2x}} dx = \int e^{-2x} dx$$

$$f_2 = -\frac{e^{-2x}}{2}$$

$$y_p = \frac{-x^2}{2} + \frac{-e^{-2x}}{2} \cdot \frac{x e^{2x}}{2} = \frac{-x^2}{2} - \frac{x}{4}$$

$$y = C_1 x + \frac{C_2 x e^{2x}}{2} - \frac{x^2}{2} - \frac{x}{4}$$

$$= x \left(C_1 - \frac{1}{4}\right) - \frac{x^2}{2} + \frac{C_2 x e^{2x}}{2}$$

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$$* \quad y^{(4)} - 5y^{(2)} + 4y = 0$$

$$\Rightarrow \text{Aux. eqn. } m^4 - 5m^2 + 4 = 0$$

$$m = t$$

$$m^4 - m^2 - 4m^2 + 4 = 0$$

$$\Rightarrow m^2(m^2 - 1) - 4(m^2 - 1) = 0$$

$$\Rightarrow m^2 = 4 ; m^2 = 1$$

$$\Rightarrow m = \pm 2 ; \pm 1$$

$$y = c_1 e^{-x} + c_2 e^x + c_3 e^{-2x} + c_4 e^{+2x}$$

$$* \quad y^{(4)} - 8y^{(2)} + 16y = 0$$

$$\Rightarrow \text{Aux. eqn. } m^4 - 8m^2 + 16 = 0$$

$$m^4 - 4m^2 - 4m^2 + 16 = 0$$

$$\Rightarrow m^2(m^2 - 4) - 4(m^2 - 4) = 0$$

$$\Rightarrow m = \pm 2 ; \pm 2$$

$$y = (c_1 + c_2 x) e^{-2x} + (c_3 + c_4 x) e^{2x}$$

$$( \text{If } m = -2, -2, 2, 2, \text{ then } y = (c_1 + c_2 x + c_3 x^2) e^{-2x} + c_4 e^{2x} )$$

$$* \quad x^3 \cdot y''' - 3x^2 \cdot y'' + 6xy' - 6y = x^4 \ln x$$

$$\Rightarrow \textcircled{1} \quad x^3 \cdot y''' - 3x^2 \cdot y'' + 6xy' - 6y = 0$$

$$\text{Let, } y = x^m$$

$$x^3 \cdot (m)(m-1)(m-2) \cdot x^{m-3} - 3x^2 \cdot (m)(m-1) \cdot x^{m-2} \\ + 6x \cdot m \cdot x^{m-1} - 6x^m = 0$$

$$\Rightarrow m(m-1)(m-2) \cdot x^m - 3m(m-1) \cdot x^m$$

$$+ 6m \cdot x^m - 6x^m = 0$$

$$\rightarrow x^m \{ m(m-1)(m-2) - 3m(m-1) + 6m - 6 \} = 0$$

$m=1$ ,  $\emptyset = 0$ , then  $y_1 = x$ .

$m=2$ ,  $\emptyset = 0$ , then  $y_2 = x^2$ .

$m=3$ ,  $\emptyset = 0$ , then  $y_3 = x^3$ .

$$\therefore y_c = c_1 x + c_2 x^2 + c_3 x^3.$$

$$(ii) \quad y_p = f_1 x + f_2 x^2 + f_3 x^3.$$

$$W = \begin{vmatrix} x & x^2 & x^3 \\ 1 & 2x & 3x^2 \\ 0 & 2 & 6x \end{vmatrix} = 2x^3. \quad W_1 = \begin{vmatrix} x & 0 & x^3 \\ 1 & 0 & 3x^2 \\ 0 & 1 & 6x \end{vmatrix} = -3x^3 + x^3 = -2x^3$$

$$W_2 = \begin{vmatrix} 0 & x^2 & x^3 \\ 0 & 2x & 3x^2 \\ 1 & 2 & 6x \end{vmatrix} = x^4. \quad W_3 = \begin{vmatrix} x & x^2 & 0 \\ 1 & 2x & 0 \\ 0 & 2 & 1 \end{vmatrix}$$

$$f_1 = \int \frac{W_1}{W} x dx = \int \frac{x^4}{2x^3} \cdot x \ln x dx. \quad \begin{aligned} &= 2x^2 \\ &= -x^2 \\ &= x^2. \end{aligned}$$

$$= \int \frac{x^2 \ln x}{2} dx = \ln x \cdot \frac{x^3}{6} - \int \frac{x^3}{6} \cdot \frac{1}{x} dx.$$

$$f_1 = \ln x \cdot \frac{x^3}{6} - \frac{x^3}{18} = \frac{x^3}{6} \left( \ln x - \frac{1}{3} \right)$$

$$f_2 = \int \frac{W_2}{W} x dx = \frac{-2x^3}{2x^3} x \ln x = -\int \frac{x}{u} \ln u.$$

$$f_2 = -\ln u \cdot \frac{x^2}{2} + \int \frac{x^2}{2} \cdot \frac{1}{u} dx$$

$$f_2 = -\frac{x^2}{2} \ln u + \frac{x^2}{4} = \frac{x^2}{2} \left( -\ln u + \frac{1}{2} \right).$$

$$f_3 = \frac{\int w_3 r dm}{w} = \int \frac{x^2}{2x^3} x \ln x dx$$

$$= \int \frac{\ln x}{2} dx = \frac{1}{2} x(\ln x - 1)$$

$$y = y_c + y_p.$$

$$y = c_1 x + c_2 x^2 + c_3 x^3 + \frac{x^3}{6} (\ln x - 1) x' \\ + \frac{x^2}{2} \left( \frac{1}{2} - \ln x \right) x^2 + \frac{x}{2} (\ln x - 1) x^3.$$

\* Inhom  $y'' + py' + qy = r \quad \text{--- (1)}$

Let,  $u$  be a sol. of  $y'' + py' + qy = 0$   
 Assume :-  $[y = uv]$  is general sol. of (1).

Change  $y \Rightarrow v$  in (1). — ide.

$$\begin{aligned} y &= uv \\ y' &= uv' + u'v \\ y'' &= 2uv' + uv'' + u''v \end{aligned} \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} \text{put in (1)}.$$

$$2u'v' + uv'' + u''v + puv' + pu'v + quv = r.$$

$$\Rightarrow uv'' + (2u' + pu)v' + \underbrace{(u'' + pu' + qu)}_{=0} v = r.$$

$\Rightarrow 0$  as  $u$  is a solution.

$$\Rightarrow uv'' + (2u' + pu)v' = r.$$

Take  $v^1 = z \quad \text{--- (2)}$

$$uz' + (qu' + pu)z = x$$

On Solving for  $z$ :

use  $z$  to solve eqn (2)  
we will get  $v$ .

Put  $v$  in  $y = uv$  to obtain general solution.

$$\star \quad xy'' - 2x(1+x)y' + 2(1+x)y = x^3.$$

$$\Rightarrow y'' - \frac{2x(1+x)y'}{x^2} + \frac{2(1+x)y}{x^2} = x.$$

$px + qx^2 = 0$ ,  $y_1 = x$  is the solution.  
Here  $y = (x)v$ ,  $u = x$

Let,  $y = uv$  be the solution

$$\Rightarrow y = xv$$

$$\Rightarrow y' = xv' + v$$

$$\Rightarrow y'' = v' + xv'' + v'$$

$$\Rightarrow y'' = 2v' + xv''$$

$$\star \quad (2v' + xv'') - \frac{2x(1+x)}{x^2} \cdot (xv' + v) + \frac{2(1+x)}{x^2} \cdot xv = x$$

$$\Rightarrow xv'' + (2 - 2(1+x))v' + \left(\frac{-2x(1+x)}{x^2} + \frac{2(1+x)}{x^2}\right)v = x$$

$$\Rightarrow xv'' + -2xv' = x$$

$$\Rightarrow v'' - 2v' = 1$$

$$\Rightarrow v' = z$$

$$\Rightarrow z' - 2z = 1$$

$$\Rightarrow \frac{dz}{1+2z} = dx \Rightarrow \ln(1+2z) = 2x + C$$

$$z = \frac{e^{2x+C} - 1}{2}$$

$$v^1 = \frac{c_1 e^{2x} - 1}{2}$$

$$\Rightarrow 2dv = (e^{2x} - 1)dx$$

$$\Rightarrow v = \frac{c_1 e^{2x}}{2} - x$$

$$\Rightarrow v = \frac{c_1 e^{2x}}{4} - \frac{x}{2} + c_2$$

$$y = (x) \left( \frac{c_1 e^{2x}}{4} - \frac{x}{2} + c_2 \right)$$

$$y' = c_1 \frac{x e^{2x}}{4} - \frac{x^2}{2} + c_2 x$$

$$y = c_2 x - \frac{x^2}{2} + \frac{c_1 x e^{2x}}{4}$$

\* Proof of VOP :-

$$y'' + p(x)y' + q(x)y = r(x) \quad \text{--- (1)}$$

$$y'' + p(x)y' + q(x)y = 0 \quad \text{--- (2)}$$

$$(1) \quad y_c = c_1 y_1 + c_2 y_2 \quad (y_c \text{ is gen. soln of (2)})$$

$$(2) \quad y_p = f_1 y_1 + f_2 y_2$$

$$\text{Assume :- } y = f_1 y_1 + f_2 y_2$$

$$y' = f_1 y'_1 + f_2 y'_2 + \boxed{(f_1' y_1 + f_2' y_2)}$$

Assume 0

$$y'' = f_1 y_1' + f_1 y_1'' + f_2 y_2' + f_2 y_2''$$

subs  $y, y', y''$  in ①

$$\Rightarrow (f_1 y_1' + f_1 y_1'' + f_2 y_2' + f_2 y_2'') + p(f_1 y_1' + f_2 y_2') \\ + q(f_1 y_1 + f_2 y_2) = \gamma.$$

$$\Rightarrow f_1 (\underbrace{y_1'' + py_1' + qy_1}_= 0) + f_2 (\underbrace{y_2'' + py_2' + qy_2}_= 0) \\ + f_1 y_1' + f_2 y_2' = \gamma \quad \left( \begin{array}{l} \text{since } y_1 \text{ & } y_2 \\ \text{are L.I. solutions} \\ \text{of ①} \end{array} \right)$$

$$\Rightarrow \boxed{f_1 y_1' + f_2 y_2' = \gamma}$$

$$\left. \begin{array}{l} f_1 y_1' + f_2 y_2' = 0 \\ f_1 y_1' + f_2 y_2' = \gamma \end{array} \right\} \begin{array}{l} \text{obtained} \\ \text{equations} \end{array} \quad \begin{array}{l} \text{--- ③} \\ \text{--- ④} \end{array}$$

$$\text{eqn ③} \times y_1' - \text{eqn ④} \times y_1$$

$$f_1 y_1 y_1' + f_2 y_2 y_1' = 0$$

$$- f_1 y_1 y_1' - f_2 y_2 y_1' = +\gamma y_1$$

$$f_2' (y_2 y_1' - y_2' y_1) = -\gamma y_1$$

$$\Rightarrow f_2' = \frac{-\gamma y_1}{y_2 y_1' - y_2' y_1}$$

$$\Rightarrow f_2 = \int \frac{y_1 \gamma}{y_1 y_2' - y_2 y_1'} dx$$

Similarly,

$$\text{eqn } ③ \times y_2' - \text{eqn } ④ \times y_1'$$

$$f_1'(y_1 y_2' - y_2 y_1') = -y_2 r$$

$$\Rightarrow f_1 = - \int \frac{y_2}{y_1 y_2' - y_2 y_1'} \cdot r \, dx$$

$$\therefore f_1 = - \int \frac{y_2}{y_1 y_2' - y_2 y_1'} \cdot r \, dx; f_2 = \int \frac{y_1}{y_1 y_2' - y_2 y_1'} \cdot r \, dx$$

$$\equiv \int \frac{w \cdot r \, dx}{W} \quad \equiv \int \frac{W_2 \cdot r \, dx}{W}$$

\* Pg. ①

$$A = \begin{bmatrix} -2 & 2 \\ 2 & -5 \end{bmatrix}$$

eigen vector

$A \in n \times n$   
( $R^n \rightarrow R$ )

$$|A - \lambda I| = 0$$

of  $A$  is element  
of null space  
of  $(A - \lambda I)$ .

$$[Ax=b] \quad [Ax=\lambda x]$$

$$\text{① } (A - \lambda I) x = 0$$

has non-zero  $x$   
as solution

$$\begin{vmatrix} -2-\lambda & 2 \\ 2 & -5-\lambda \end{vmatrix} = 0$$

$$\lambda^2 + 7\lambda + 6 = 0$$

$$\lambda = -1, -6$$



$$|A - \lambda I| = 0$$

\* Algebraic Multiplicity (a.m.)

The frequency of a specific eigen value  
is called its algebraic multiplicity.

-1 has a.m. 1; -6 has a.m. 1.

★ Geometric Multiplicity :- (g.m.)

Number of linearly independent eigen vectors corresponding to a specific  $\lambda$ , is the geometric multiplicity of that  $\lambda$ . = Nullity of  $[A - \lambda I]$ .

① eigen vector calculation.

$$\text{for } \lambda = 1; \begin{bmatrix} -1 & 2 \\ 2 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$-x_1 + 2x_2 = 0$$

$$2x_1 - 4x_2 = 0$$

REF

RREF

Eigen  
vectors

$$[A - \lambda I] = \begin{bmatrix} -1 & 2 \\ 2 & -4 \end{bmatrix} \sim \begin{bmatrix} -1 & 2 \\ 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

for  $\lambda = -6$ 

REF

RREF

$$[A - \lambda I] = \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix} \sim \begin{bmatrix} 4 & 2 \\ 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & \frac{1}{2} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} -\frac{1}{2} \\ 1 \end{bmatrix}$$

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$$\star \quad \begin{bmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{bmatrix} \quad |A - \lambda I| = 0$$

$$\begin{bmatrix} -2-\lambda & 1 & 1 \\ 1 & -2-\lambda & 1 \\ 1 & 1 & -2-\lambda \end{bmatrix} = 0$$

$$(-2-\lambda) [4 + \lambda^2 + 4\lambda] - 1 [-3-\lambda] + 1 [3+\lambda] = 0$$

$$-8 - 2\lambda^2 - 8\lambda - 4\lambda - \lambda^3 - 4\lambda^2 + 6 + 2\lambda = 0$$

$$\Rightarrow \lambda^3 + 9\lambda + 6\lambda^2 = 0$$

$$\Rightarrow \lambda(\lambda^2 + 9 + 6\lambda) = 0$$

$$\Rightarrow \lambda = 0, -3, -3$$

Here, (-3 has a.m. 2).

for  $\lambda = -3$ ,

RREF.

$$[A - \lambda I] = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

eigen vectors of A for  $\lambda = -3$   $\begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$   $\Rightarrow$  Basis of Null Space of  $[A - \lambda I]$ .

Here, (-3 has g.m. 2)

for  $\lambda = 0$

$$[A - \lambda I] = \begin{bmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{bmatrix}$$

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eigen vector

$$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

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 { good eigen value g.m.  $\geq$  a.m.  
 Bad eigen value g.m.  $<$  a.m.

## \* System of Linear Differential Equations :-

①.



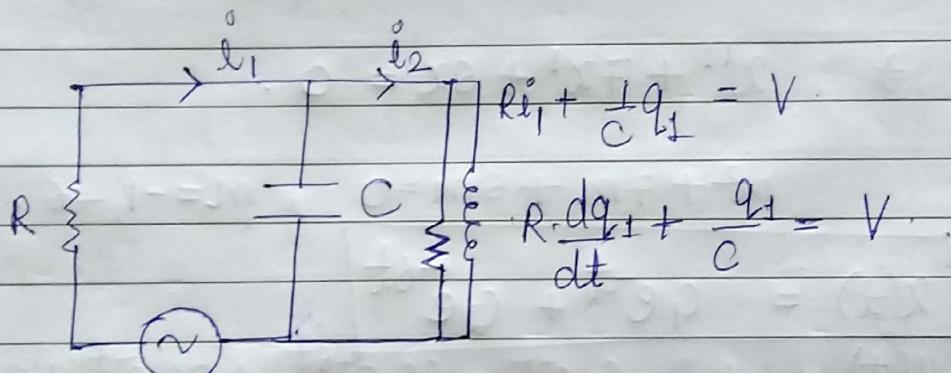
$$\frac{dT_1}{dt} = a(T_2 - T_1)$$

$$\frac{dT_2}{dt} = a(T_1 - T_2) + b(T_3 - T_2)$$

$$\frac{dT_1}{dt} = -aT_1 + aT_2$$

$$\frac{dT_2}{dt} = aT_1 - (a+b)T_2 + bT_3$$

②.



const. coefficient  
homogeneous system

$$\frac{dx}{dt} = ax + by ; \quad \frac{dy}{dt} = cx + dy$$

$x, y$  are dependent variables  
 $t$  is independent variable.

① Elimination Method :-

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$$\text{eg} \quad (1) \quad \frac{dx}{dt} = -2x + 2y \quad ; \quad \frac{dy}{dt} = 2x - 5y$$

$$x(0) = x_0 = 5$$

$$\Rightarrow y = \frac{x^1 + 2x}{2}$$

$$y(0) = y_0 = 10$$

$$\Rightarrow \left( \frac{x^1 + 2x}{2} \right)' = 2x - \frac{5}{2} (x^1 + 2x)$$

$$\Rightarrow \frac{x'' + x^1}{2} = 2x - \frac{5x^1}{2} - \frac{10x}{2}$$

$$\Rightarrow \frac{x''}{2} + \frac{2x^1}{2} = \frac{4x - 10x - 5x^1}{2}$$

$$\Rightarrow x'' + 7x^1 + 6x = 0.$$

$$m^2 + 7m + 6 = 0 ; m = -1, -6.$$

$$\Rightarrow \begin{cases} x(t) = C_1 e^{-t} + C_2 e^{-6t} \\ y(t) = \frac{1}{2} \left\{ -C_1 e^{-t} - 6C_2 e^{-6t} + 2C_1 e^{-t} + 2C_2 e^{-6t} \right\} \end{cases}$$

$$= \frac{1}{2} \left\{ C_1 e^{-t} - 4C_2 e^{-6t} \right\}$$

$$\Rightarrow \begin{cases} y(t) = \frac{C_1}{2} e^{-t} - 2C_2 e^{-6t} \end{cases}$$

$$\text{At } t=0 ; x=5 ; 2 \times 5 = 2C_1 + 2C_2$$

$$\text{At } t=0 ; y=10 ; 10 = \frac{C_1}{2} - 2C_2$$

$$20 = \frac{5C_1}{2} \Rightarrow C_1 = 8$$

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$$\underline{\underline{C_2 = -3}}$$

Method II

(works only if no. of eigen values and no. of LI eigenvectors is equal)

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equivalent  
form

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}; \begin{bmatrix} x(0) \\ y(0) \end{bmatrix} = \begin{bmatrix} x_0 \\ y_0 \end{bmatrix}$$

$$X' = AX; X(0) = X_0, \quad X(t) = Z e^{At}$$

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} e_1 \\ e_2 \end{bmatrix} e^{\lambda t}, \text{ trial solution}$$

$$\Rightarrow \lambda \begin{bmatrix} e_1 \\ e_2 \end{bmatrix} e^{\lambda t} = A \begin{bmatrix} e_1 \\ e_2 \end{bmatrix} e^{\lambda t}$$

$$\Rightarrow \underset{\neq 0}{e^{\lambda t}} \left( A \begin{bmatrix} e_1 \\ e_2 \end{bmatrix} - \lambda \begin{bmatrix} e_1 \\ e_2 \end{bmatrix} \right) = 0$$

$$A \begin{bmatrix} e_1 \\ e_2 \end{bmatrix} = \lambda \begin{bmatrix} e_1 \\ e_2 \end{bmatrix}$$

for eg. ①.

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{-t} + c_2 \begin{bmatrix} -\frac{1}{2} \\ 1 \end{bmatrix} e^{-6t}$$

for ③  $\times 3$  system;

$$\begin{bmatrix} x(t) \\ y(t) \\ z(t) \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} e^{ot} + c_2 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} e^{-3t} + c_3 \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} e^{-3t}$$

eg.  $\begin{bmatrix} 2 & 1 \\ 0 & 2 \end{bmatrix}$  only one LI eigen vector.

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\* For Real Symmetric Matrix, all eigen values are good.

\* Algorithm to solve system of d.e. :

$$\dot{x} = Ax \quad ; \quad x = \begin{bmatrix} x \\ y \end{bmatrix} \quad ; \quad A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

Step I :- find eigen values/ vectors of A.

Step II :-  $\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \vec{x}_1 e^{\lambda_1 t} + c_2 \vec{x}_2 e^{\lambda_2 t}$

where,  $\vec{x}_1, \vec{x}_2$  are eigen vectors corresponding to  $\lambda_1, \lambda_2$ .

Works only if all eigen values are good.  
i.e. For every eigen value, a.m. (algebraic multiplicity) is equal to g.m. (geometric multiplicity).

Date \_\_\_\_\_, (from here on  $t$  is considered as independent variable) generally domain for  $t \in [0, \infty)$

## \* Laplace Transformation :-

for a function  $f(t)$ ,

$$L[f(t)] = F(s) = \int_0^{\infty} f(t)e^{-st} dt \quad \text{is Laplace transform}$$

where,  $s$  is parameter (variable constant).

(provided integral converges).

e.g. Laplace transform of  $f(t) = 1$

$$L[1] = \int_0^{\infty} e^{-st} dt.$$

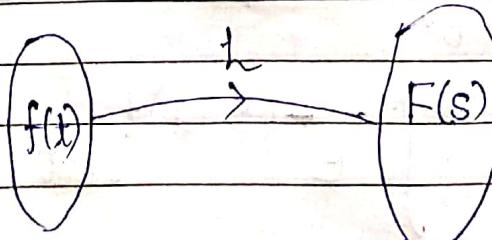
$$= \lim_{R \rightarrow \infty} \int_0^R e^{-st} dt.$$

$$= \lim_{R \rightarrow \infty} \frac{e^{-st}}{-s} \Big|_0^R$$

$$= \lim_{R \rightarrow \infty} \frac{e^{-sR}}{-s} \Big|_0^R + \frac{1}{s}$$

If  $s$  is positive,  $\lim_{R \rightarrow \infty} \frac{e^{-sR}}{-s} \rightarrow 0$ .

$$L[1] = \frac{1}{s} \quad (s > 0)$$



Laplace transform

$$= L$$

\* Condition of existence for Laplace transform of  $f(t)$ .

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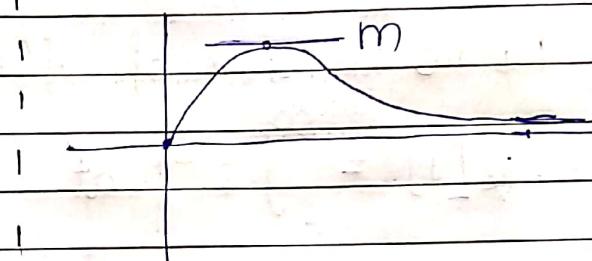
For a Laplace transform to exist,  
 $f(t)$  is of 'exponential order'.

~~sufficient  
only condition  
Not necessary~~

$$|f(t)| < me^{kt} \quad \text{for some } m > 0, k > 0$$

Let,  $f(t) = e^{t^2}$  ;  $f(t) = t^n$ ;  $t^n \leq me^{kt}$   
Laplace transform ;  
for  $e^{t^2}$  does not exist ;  $\frac{t^n}{e^{kt}} \leq m$ .

$$f(t) = \frac{1}{t}$$



for  $t^n$ , LT exists.  
(Laplace transform)

\* Basically, the growth of  $f(t)$  should not exceed the growth of  $e^{kt}$  i.e.  $f(t)$  should not become  $\infty$  before  $e^{kt}$ .

Because in this case; for the product  $f(t) \cdot e^{-st}$ ;  $e^{-st}$  will be able to counter the growth of  $f(t)$ .

$$\text{eg. calculate } L[e^{at}] \quad L[f(t)] = \int_0^\infty f(t) \cdot e^{-st} dt$$

$$\Rightarrow L[e^{at}] = \int_0^\infty e^{at} \cdot f(t) e^{-st} dt$$

$$= \int_0^\infty e^{-(s-a)t} dt$$

$$= \lim_{R \rightarrow \infty} \frac{e^{-(s-a)t}}{-(s-a)} \Big|_0^R$$

$$= 0 + 1 \quad (\text{If } s > a).$$

$$\therefore \boxed{\mathcal{L}[e^{at}] = \frac{1}{s-a}} \quad s > a.$$

e.g. calculate  $\mathcal{L}[e^{at} f(t)] \Rightarrow F(s-a)$  first shifting them  
exp. shift formula

$$\Rightarrow = \int_0^\infty e^{at} f(t) e^{-st} dt$$

$$= \int_0^\infty f(t) \cdot e^{-(s-a)t} dt$$

$$= F(s-a)$$

Here,  $s-a > 0 \Rightarrow s > a$  for integral to converge.

$$\therefore \boxed{\mathcal{L}[e^{at} f(t)] = F(s-a)}$$

\* Calculate  $L[t^n]$ .

$$\Rightarrow L[t^n] = \int_0^\infty t^n e^{-st} dt$$

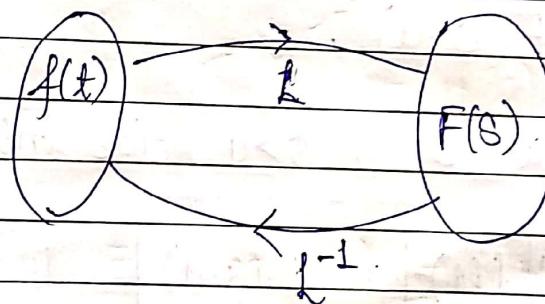
$$= \lim_{R \rightarrow \infty} \left[ t^n e^{-st} \right]_0^R + \frac{n}{s} \int_0^\infty t^{n-1} e^{-st} dt -$$

$$= \frac{n}{s} L[t^{n-1}]$$

$$= \frac{n(n-1)}{s^2} L[t^{n-2}]$$

$$\therefore L[t^n] = \frac{n!}{s^n} L[1] = \frac{n!}{s^n} \cdot \frac{1}{s} = \frac{n!}{s^{n+1}}$$

$$\boxed{\therefore L[t^n] = \frac{n!}{s^{n+1}}}$$



\* Inverse Laplace :-

$$L[t^n] = \frac{n!}{s^{n+1}} ; t^n \text{ is inverse Laplace of } \frac{n!}{s^{n+1}}$$

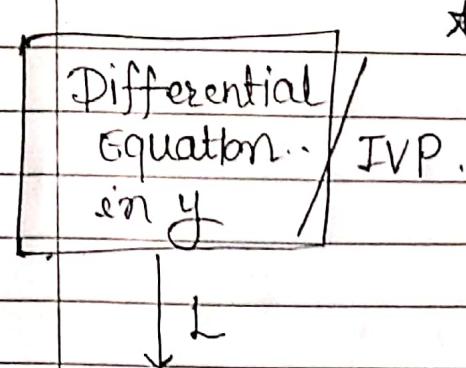
$$L[1] = \frac{1}{s} ; \frac{1}{s} \text{ is inverse Laplace of } \frac{1}{s}$$

Maharaja  
(s > 0)

Date \_\_\_\_\_ / \_\_\_\_\_ / \_\_\_\_\_ → frequency domain. Page No.: \_\_\_\_\_

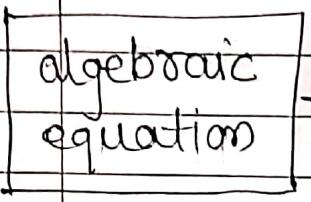
time domain → frequency domain. Laplace Transformation

### \* Algorithm :-



IVP.

$\downarrow L$



Solve it  
for  $y$

$$y(s) = \frac{p(s)}{q(s)}$$

$L^{-1}$  Set of  
D.E.  
 $y(t)$ .

\*  $y = y(t); y' = \frac{dy}{dt}$

$$\mathcal{L}[y'(t)] = \int_0^\infty y'(t) \cdot e^{-st} dt$$

$$= \lim_{R \rightarrow \infty} e^{-st} \cdot y(t) \Big|_0^R + s \int_0^\infty e^{-st} y(t) dt$$

$$\mathcal{L}[y'(t)] = s \cdot \mathcal{L}[y(t)] - y(0).$$

$$\therefore \mathcal{L}[y'(t)] = s \cdot \mathcal{L}[y(t)] - y(0)$$

$$= s \cdot Y(s) - y(0)$$

$\boxed{\mathcal{L}[y'(t)] = s \cdot Y(s) - y(0)}$

$$\mathcal{L}[y''(t)] = s \cdot \mathcal{L}[y'] - y'(0).$$

$\boxed{\mathcal{L}[y''(t)] = s^2 \cdot Y(s) - s \cdot y(0) - y'(0)}$

$$\cos at = \frac{e^{iat} + e^{-iat}}{2}; \sin at = \frac{e^{iat} - e^{-iat}}{2}$$

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\*  $L[1] = \frac{1}{s} \quad (s > 0)$

\*  $L[e^{at}] = \frac{1}{s-a} \quad (s > a)$

\*  $L[e^{at} f(t)] = F(s-a) \quad (s > a)$

\*  $L[t^n] = \frac{n!}{s^{n+1}}$

\*  $L[f(t)] = \int_0^{\infty} f(t) \cdot e^{-st} dt = F(s).$

\*  $L(\cos at) = \frac{s}{s^2 + a^2} \quad (s > 0)$

\*  $L(\sin at) = \frac{a}{s^2 + a^2} \quad (s > 0)$

\*  $L[y'(t)] = sY(s) - y(0)$

\*  $L[y''(t)] = s^2 Y(s) - sy(0) - y'(0)$

\*  $L[f+g] = L(f) + L(g); L[cf] = cL[f]$

e.g.  $y'' + y = t ; \quad y(0) = 1 ; \quad y'(0) = -2$

$$\Rightarrow (s^2Y - s + 2) + Y = \frac{1}{s^2}$$

$$\Rightarrow Y = \frac{1}{s^2(s^2+1)} + \frac{s}{s^2+1} - \frac{2}{s^2+1}$$

Take Inverse Laplace;

$$y(t) = \cos t - 2\sin t + \frac{t^{-1}}{s^2(s^2+1)}$$

$$t^{-1} \left[ \frac{1}{s^2(s^2+1)} \right] = t^{-1} \left[ \frac{1}{s^2} - \frac{1}{s^2+1} \right]$$

$$= t - \sin t$$

$$y(t) = \underbrace{\cos t - 3\sin t}_y + \underbrace{t}_p$$

\* Laplace transform & Inverse Laplace both are linear transformations.

\* ESE | Sat 4/5 | Max. marks = 50 | Time = 3H.

ODE (I/II order)  $\rightarrow$  Marks 18-15

Laplace / Sys. of DE / Numerical methods  $\rightarrow$  12-15  $\rightarrow$  4 Post MSE

Linear Algebra  $\rightarrow$  10  $\rightarrow$  6 Pre MSE

Small marks questions  $\rightarrow$  10 (like quiz)

$$f^{-1}(y) = \{x \in D : f(x) = y\}.$$

Inverse of a Laplace Transform



Unique  $\Rightarrow$  if functions are considered continuous

\* May not be unique when discontinuous functions are also considered.

e.g.

$$g(t) = \begin{cases} 1 & ; 0 \leq t < 3 \\ 2 & ; t = 3 \\ 1 & ; t \geq 3 \end{cases}$$

$$\begin{aligned} L[g(t)] &= \int_0^3 g(t) e^{-st} dt + \int_3^\infty g(t) e^{-st} dt \\ &= \left( \frac{e^{-3s}}{-s} + 1 \right) + \left. \frac{e^{-st}}{-s} \right|_3^\infty \end{aligned}$$

$$L[g(t)] = \frac{1}{s}$$



$$L[f(t)] \rightsquigarrow F(s)$$

$$L[f(t).g(t)] = \int_0^\infty f(t).g(t) e^{-st} dt$$

$$L[g(t)] \rightsquigarrow G(s)$$

$$L^{-1}[f(t) * g(t)]$$

$$F(s) \cdot G(s) \rightsquigarrow f(t) * g(t) . \left\{ \text{convolution} \right\}$$

$$= \int_0^t f(u).g(t-u) du$$

Integration w.r.t dummy variable (u)

\* Inverse Laplace of  $\int \frac{1}{s(s^2+1)} \{$

(I)

$$\Rightarrow \mathcal{L}^{-1} \left[ \frac{1}{s(s^2+1)} \right] = \mathcal{L}^{-1} \left[ \frac{1}{s} - \frac{s}{s^2+1} \right]$$

$$\frac{1}{s(s^2+1)} = \frac{A}{s} + \frac{Bs+C}{s^2+1} = \frac{1}{s} - \frac{s}{s^2+1}$$

$$\frac{1}{s(s^2+1)} = \frac{As^2 + Bs^2 + (A+C)s}{s(s^2+1)}$$

$$A+B=0$$

$$A=1; B=-1; C=0$$

$$= \mathcal{L}^{-1} \left[ \frac{1}{s} \right] - \mathcal{L}^{-1} \left[ \frac{s}{s^2+1} \right]$$

$$\boxed{\mathcal{L}^{-1} \left[ \frac{1}{s(s^2+1)} \right] = 1 - \cos t}$$

(II)

$$1 * \sin t = \sin t * 1 = \int_0^{2\pi} (1) (\sin u) du$$

$$= -\cos u \Big|_0^t$$

$$= -\cos t + 1 = 1 - \cos t$$

$$\mathcal{L}^{-1} \left[ \frac{1}{s(s^2+1)} \right] = 1 - \cos t$$

$$9. \quad y'' - 3y' + 2y = 4e^{2t};$$

$$y(0) = -3; \quad y'(0) = 5.$$

$$\Rightarrow (s^2Y + 3s - 5) - 3[8Y + 3] + 2Y = \frac{4}{s-2} \quad 1.$$

$$\Rightarrow s^2Y + 3s - 5 - 3sY - 9 + 2Y = \frac{4}{s-2}$$

$$\Rightarrow Y(s^2 - 3s + 4) + Ys - 2Y + 3s - 14 = \frac{4}{s-2}$$

$$\Rightarrow Y(s-2)^2 + Y$$

$$Y(s^2 - 3s + 2) + 3s - 14 = \frac{4}{s-2}$$

$$\Rightarrow Y(s-1)(s-2) + 3s - 14 = \frac{4}{s-2}$$

$$\Rightarrow Y(s-1)(s-2) = \frac{4}{s-2} + 14 - 3s$$

$$= \frac{4 + 14s - 28 - 3s^2 + 6s}{s-2}$$

$$\Rightarrow Y = \frac{-3s^2 + 20s - 24}{(s-1)(s-2)^2}$$

$$\Rightarrow Y = \frac{-7}{s-1} + \frac{4}{s-2} + \frac{4}{(s-2)^2}$$

$$y(t) = -7e^t + 4e^{2t} + 4te^{2t}$$

\* Assign.

1. Find the Laplace Transform of following equations

$$\textcircled{1} \quad \sin \hat{a}t \quad \sin \hat{a}t = \frac{1}{2} (e^{at} - e^{-at})$$

$$\Rightarrow L[\sin \hat{a}t] = L\left[\frac{1}{2} e^{at} - e^{-at}\right]$$

$$= \frac{1}{2} \cdot L[e^{at}] - \frac{1}{2} L[e^{-at}]$$

$$= \frac{1}{2} \left[ \frac{1}{s-a} - \frac{1}{s+a} \right]$$

$$\Rightarrow \frac{1}{2} \left[ \frac{s+a - s+a}{s^2 - a^2} \right] = \frac{a}{s^2 - a^2}$$

$$\textcircled{2} \quad \cos(\omega t + \theta) \quad \cos(\omega t + \theta) = \cos \omega t \cos \theta - \sin \omega t \sin \theta$$

$$\Rightarrow L[\cos \omega t \cos \theta - \sin \omega t \sin \theta]$$

$$= \cos \theta \cdot L[\cos \omega t] - \sin \theta \cdot L[\sin \omega t]$$

$$= \cos \theta \cdot \left( \frac{s}{s^2 + \omega^2} \right) - \sin \theta \cdot \left( \frac{\omega}{s^2 + \omega^2} \right)$$

$$= \frac{s \cos \theta - \omega \sin \theta}{s^2 + \omega^2}$$

2. Find Inverse Laplace transform of following.

$$\textcircled{1} \quad \frac{1}{s^2(s^2 + a^2)} = F(s)$$

$$\Rightarrow L^{-1}[F(s)] = L^{-1}\left(\frac{1}{s^2(s^2 + a^2)}\right)$$

$$= L^{-1}\left(\frac{1}{a^2} \left( \frac{1}{s^2} - \frac{1}{s^2 + a^2} \right)\right)$$

$$= \frac{1}{a^2} \cdot L^{-1}\left(\frac{1}{s^2}\right) - \frac{1}{a \cdot a^2} \cdot L^{-1}\left(\frac{a}{s^2 + a^2}\right)$$

$$= \frac{1}{a^2} \cdot t - \frac{1}{a^3} \sin at. \quad e^{-t} + \frac{1}{3} \sin 3t - \cos 3t$$

(Actual question in tut)  $y'' + 9y = 10e^{-t}$

$\Rightarrow y'' + 9y' = 10e^{-t}, \quad y(0) = 0; \quad y'(0) = 0.$

$$\Rightarrow L[y''] + 9L[y'] = 10L[e^{-t}]$$

$$\Rightarrow [S^2Y - 9s(0) - (0)] + 9[SY - (0)] = 10 \cdot \frac{1}{(S+1)}$$

$$\Rightarrow S^2Y + 9SY = 10$$

$$\Rightarrow (S^2 + 9S)Y = 10$$

$$\Rightarrow Y = \frac{10}{(S+1)(S)(S+9)}$$

Take Inverse Laplace,

$$\Rightarrow y(t) = A \frac{1}{S+1} + B \frac{1}{S} + C \frac{1}{S+9}$$

~~$$\Rightarrow \frac{10}{(S+1)(S)(S+9)} = \frac{A(S^2+9) + B(S^2+10S+9) + C(S^2+S)}{S(S+1)(S+9)}$$~~

~~$$\Rightarrow 10 = (A+B+C)S^2 + (10B+C)S + 9(A+B)$$~~

~~$$A+B+C=0 \quad A+B = 10/9 \quad B = 1/9 \therefore A = 1.$$~~

~~$$10B+C=0 \quad 10B = 10/9 \quad C = -10/9$$~~

~~$$9B-A=0$$~~

$$Y = \frac{1}{s+1} + \frac{1}{9s} + \frac{-10}{9(s+9)}$$

$$y(t) = t^{-1} \left[ \frac{1}{s+1} \right] + \frac{1}{9} t^{-2} \left[ \frac{1}{s} \right] - \frac{10}{9} t^{-1} \left[ \frac{1}{s+9} \right]$$

$$y(t) = e^{-t} + \frac{1}{9} - \frac{10}{9} e^{-9t}$$

\* (Convolution Theorem)

Let  $F(s)$  and  $G(s)$  denote the Laplace transform of functions  $f(t)$  and  $g(t)$  resp. Then the product  $F(s) \cdot G(s)$  is the Laplace transform of the convolution of functions  $f$  and  $g$ , defined by

$$f * g(t) = \int_0^t f(u) \cdot g(t-u) du \text{ i.e.}$$

$$\mathcal{L}(f * g(t)) = F(s) \cdot G(s).$$

a. Prove above thm & b. Show  $f * g = g * f$ .

Proof :- a.  $F(s) = \mathcal{L}(f(t))$ ;  $G(s) = \mathcal{L}(g(t))$

$$\mathcal{L}[f * g(t)] = F(s) \cdot G(s).$$

$$F(s) \cdot G(s) = \int_0^\infty f(\sigma) e^{-s\sigma} d\sigma \int_0^\infty g(t) e^{-st} dt.$$

$$= \int_0^\infty \left[ \int_0^\infty f(\sigma) e^{-s(\sigma+t)} d\sigma \right] g(t) dt$$

$$\text{Take } \tau + \sigma = t ;$$

$$\Rightarrow d\sigma = dt ; \quad T \leq t < \infty$$

$$= \int_{-\infty}^{\infty} \left[ \int_{-\infty}^{\infty} f(t-\tau) \cdot e^{-st} \cdot d\tau \right] g(\tau) \cdot d\tau \quad dt \cdot d\tau$$

Changing order of Integration. limits for  $dt \cdot d\tau \Rightarrow \tau = 0 ; t = \infty$

$$= \int_0^{\infty} \left[ \int_0^t f(t-\tau) \cdot g(\tau) \cdot e^{-st} \cdot d\tau \right] dt$$

$$= \int_0^{\infty} \left[ \int_0^t f(t-\tau) \cdot g(\tau) \cdot d\tau \right] \cdot e^{-st} \cdot dt$$

limit for  $d\tau \cdot dt \Rightarrow \tau = 0 \quad t = 0 \quad \tau = t \quad t = \infty$ .

Here;  $f(t) = \int_0^t f(t-\tau) \cdot g(\tau) \cdot d\tau$

$$= \int_0^{\infty} \left[ \int_0^t f(\tau) \cdot g(t-\tau) \cdot d\tau \right] dt$$

$$= [f * g](t)$$

$$\therefore L(f * g) = F(s) \cdot G(s)$$

$$L(g * f) = G(s) \cdot F(s)$$

$$\Rightarrow f * g = g * f$$