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#!/usr/bin/env python
# coding: utf-8
# In[1]:
get_ipython().system('pip install
easyocr')
get_ipython().system('pip install imutils')
get_ipython().system('pip install
plyer')
# read the further module in google
# In[2]:
import cv2
#cv2 module uses for
frame gray scale countors and canny edges
from matplotlib import pyplot as plt
#plotting the
plate test image
import numpy as np
#creating array for using numpy
import imutils
#used to
handle the camera framing
import easyocr
#optical character recozigion
from datetime import
date
#using the data and time creating for the dataframe
import pandas as pd
#used for reading
the exiting dataframe
from datetime import datetime
# from IPython.display import Audio
from
plyer import notification
#used for creating the notification bar
In[3]:
list1=[]
list2=[]
list3=[]
#creating list for handling the entry in the dataframe and
used for binary search for finding the dataframe belongs to society or not
# In[4]:
list1=[]
# list2=[]
# list3=[]
def capture():
    camera = cv2.VideoCapture(0)
    i = 0
while i < 5:
         raw_input('Press Enter to capture')
        return_value, image =
camera.read()
        cv2.imwrite('image_'+str(i)+'.jpg', image)
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i += 1
```

#finding the location of array

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del(camera)
#function for capturing the frame of live car number and creating different frame
which is used for extracting the car plate test
# In[109]:
# importing the python open cv
library
capture()
img = cv2.imread('image3.jpg')
gray = cv2.cvtColor(img,
cv2.COLOR_BGR2GRAY)
plt.imshow(cv2.cvtColor(gray, cv2.COLOR_BGR2RGB))
#reading the image and
coverting it into gray scale for reducing countors and parameters for noisy image
In[110]:
bfilter = cv2.bilateralFilter(gray, 11, 17, 17) #Noise reduction
edged =
cv2.Canny(bfilter, 30, 200) #Edge detection
plt.imshow(cv2.cvtColor(edged,
cv2.COLOR_BGR2RGB))
#used for filtering the image and coverting it into countor and edges for
reducing the parameters
# In[111]:
keypoints = cv2.findContours(edged.copy(),
cv2.RETR_TREE, cv2.CHAIN_APPROX_SIMPLE)
contours = imutils.grab_contours(keypoints)
sorted(contours, key=cv2.contourArea, reverse=True)[:10]
#used for finding the contours
In[ ]:
# In[112]:
location = None
for contour in contours:
    approx =
cv2.approxPolyDP(contour, 10, True)
    if len(approx) == 4:
        location = approx
break
#used for coverting array by making loop or array coversion
In[113]:
location
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# In[114]:
mask = np.zeros(gray.shape,
np.uint8)
new image = cv2.drawContours(mask, [location], 0,255, -1)
new_image =
cv2.bitwise_and(img, img, mask=mask)
#used for coverting numpy arrays of image for calculation
in the image
# In[115]:
plt.imshow(cv2.cvtColor(new_image, cv2.COLOR_BGR2RGB))
#show the
extracted image
# In[12]:
#plt.imshow(cv2.cvtColor(new_image, cv2.COLOR_BGR2RGB))
In[116]:
(x,y) = np.where(mask==255)
(x1, y1) = (np.min(x), np.min(y))
(x2, y2) = (np.max(x),
np.max(y))
cropped_image = gray[x1:x2+5, y1:y2+5]
th3 =
cv2.adaptiveThreshold(cropped_image, 255, cv2.ADAPTIVE_THRESH_GAUSSIAN_C,
cv2.THRESH_BINARY, 11, 2)
#threshold adaptive used for coverting the image into binary
format
#Thresholding is a very popular segmentation technique,
#used for separating an object
considered as a foreground from its background.
# In[117]:
plt.imshow(cv2.cvtColor(th3,
cv2.COLOR_BGR2RGB))
# In[118]:
reader = easyocr.Reader(['en'])
result =
reader.readtext(th3)
#reading the test and stored into result
def getdate():
    now =
date.today()
    return now.strftime("%d/%m/%Y")
    list_fun()
#function for
getting date
def gettime():
    n= datetime.now()
    return
n.strftime("%H:%M:%S")
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```
#function for getting time
def notifyMe(title, message):
notification.notify(
        title = title,
        message = message,
        app icon =
"alert.ico",
        timeout = 6
    )
#function for generating the notification bar
# import pandas as pd
data=pd.read_csv("entry.csv")
data.head()
#used for reading
the entry csv with the help of pandas
# In[119]:
test=result[0][-2]
print(test)
#sorting
the extracted image in the test by using slicing
ntitle= "ALERT ALARM
nmessage="CAR NUMBER NOT BELONG TO SOCIETY KINDLY CHECK FOR SAFETY PURPOSE"
song=r'/content/note.mp3'
# print('playing sound using pydub')
play(song)
list1.append(test)
list2.append(getdate())
list3.append(gettime())
pd.DataFrame(list(zip(list1, list2,list3)),
               columns =['numer',
'date','time'])
#creating the dataframe of entered car by using detection with date and
time
# In[93]:
# df.to_csv('saved.csv')
In[120]:
number=(data["name"]).to_list()
print(number)
#list for entry dataframe
cars which belong to society
# In[121]:
if test in number:
    df =
pd.DataFrame(list(zip(list1, list2,list3)),
               columns =['numer',
'date','time'])
else:
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df1 = pd.DataFrame(list(zip(list1)),
               columns
=['number2'])
    print("ping the alarm")
  # Audio(data=song,autoplay=False)
  notifyMe(ntitle,nmessage)
#if else function for find belonging car in the society and cars
which is not belong to society
# In[122]:
df.to_csv("saved.csv")
#generating the
csv file of the dataframe
# In[21]:
def list_fun():
    list1=[]
    list2=[]
list3=[]
# In[ ]:
```