

Ans 1- `int L_search(int *ar, int n, int key)`
`{`
`for (int i = 0; i < n; i++)`
`if (ar[i] == key)`
`return i;`
`}`
`return -1;`
`}`

Ans 2- `void insertion_sort(int ar[], int n)`
`{`
`int i, temp, j;`
`for (int i = 1; i < n; i++)`
`{`
`temp = ar[i];`
`j = i - 1;`
`while (j >= 0 && ar[j] > temp)`
`ar[j+1] = ar[j];`
`j--;`
`ar[j+1] = temp;`
`}`
`}`

`void insertion_sort(int ar[], int n)`
`{`
`if (n <= 1)`
`return;`
`insertion_sort(ar, n-1);`


```

int last = arr[n-1];
int j = n-2;
while (j >= 0 && arr[j] > last)
{
    arr[j+1] = arr[j];
    j--;
}
arr[j+1] = last;
};
    
```

Ans 3: Insertion sort is called online sort because it does not need to know anything about what values it will sort and the information is requested while the algorithm is running

| | | Best | Worst |
|---------------------------------|------------------|---------------|---------------|
| <u>Ans 3 (i)</u> Selection Sort | Time Complexity | $O(n^2)$ | $O(n^2)$ |
| | Space Complexity | $O(1)$ | |
| (ii) Insertion Sort | Time Complexity | $O(n)$ | $O(n^2)$ |
| | Space Complexity | $O(1)$ | |
| (iii) Merge Sort | Time Complexity | $O(n \log n)$ | $O(n \log n)$ |
| | Space Complexity | $O(n)$ | |
| (iv) Quick Sort | Time Complexity | $O(n \log n)$ | $O(n^2)$ |
| | Space Complexity | $O(n)$ | |
| (v) Heap Sort | Time Complexity | $O(n \log n)$ | $O(n \log n)$ |
| | Space Complexity | $O(1)$ | |
| (vi) Bubble Sort | Time Complexity | $O(n^2)$ | $O(n^2)$ |
| | Space Complexity | $O(1)$ | |

| Ans 4. Sorting | Inplace | Stable | Online |
|----------------|---------|--------|--------|
| Selection | ✓ | | |
| Insertion | ✓ | ✓ | ✓ |
| Merge | | ✓ | |
| Quick | ✓ | | |
| Heap | ✓ | | |
| Bubble | ✓ | ✓ | |

Ans: `int bsearch (vector<int> arr, int key)`

```

{
    int lo = 0, hi = arr.size() - 1;
    int mid;
    while (lo <= hi)
    {

```

```

        mid = lo + (hi - lo) / 2;

```

```

        if (arr[mid] == key)
            return mid;

```

```

        else if (arr[mid] > key)
            hi = mid - 1;

```

```

        else
            lo = mid + 1;

```

```

    }
    return -1;
}

```

`int bsearch (int arr[], int l, int h, int key)`

```

{
    if (h >= l)
    {
        int mid = l + (h - l) / 2;

```

```

        if (arr[mid] == key)
            return mid;

```

```

        else if (arr[mid] > key)

```

because it does not
values it will sort and
algorithm is running

est $O(n^2)$
worst $O(n^2)$
(1)

$O(n^2)$

$O(n \log n)$

$O(n^2)$

$O(n^2)$

$O(n \log n)$

$O(n^2)$


```

        }
        else
        {
            return b_search(arr, l, mid-1, key);
        }
        return b_search(arr, mid+1, h, key);
    }
    return -1;
}

```

Time Complexity - Best - $O(1)$
 Avg. - $O(\log n)$
 Worst - $O(\log n)$

Ans 6: Recurrence Relation for Binary Search.

$$T(n) = T(n/2) + 1$$

Ans 8: Quick sort is the fastest general purpose sort. In most practical situation Quick sort is the method of choice. If stability is concern and space is available, Merge sort can be the best option.

Ans 9: How far or close the array is from being sorted if the array is already sorted then the insertion count is 0 but if array is sorted in reverse order the insertion count is max.

Merge Sort
 int main()

```

int arr[] = { 7, 21, 31, 8, 10, 1, 20, 6, 4, 5 };
int n = sizeof(arr) / sizeof(arr[0]);
int ans = mergeSort(arr, n);

```


, l, mid-1, Reg);

mid+1, h, Reg);

cout << "No. of Inversion " << ans << endl;

return 0;

}
int mergesort (int arr[], int n)

{
int temp[an];

return mergesort(arr, temp, 0, ~~arr~~ⁿ - 1);

}
int mergesort (int arr[], int temp[], int left, int right)

{
int mid, inv-count = 0;

if (right > left)

{
mid = (right + left) / 2;

inv-count += mergesort(arr, temp, left, mid);

inv-count += mergesort(arr, temp, mid+1, right);

inv-count += mergesort(arr, temp, left, mid+1, right);

}
return inv-count;

}
int mergesort (int arr[], int temp[], int left, int mid, int right)

{
int inv-count = 0;

int i = left, j = mid, k = left;

while (i <= mid-1 && j <= right)

{
if (arr[i] < arr[j])

temp[k++] = arr[i++];

else

temp[k++] = arr[j++];

inv-count += inv-count + (mid-i);

}
}

purpose sort. In
method of choice
is available,
option.

being sorted if
the insertion
in reverse order

, 4, 5};
});


```

while (i <= mid-1)
    temp[k++] = arr[i++];
while (j <= right)
    temp[k++] = arr[j++];
for (i = left; i <= right; i++)
    arr[i] = temp[i];

```

```

return inv_count;
}

```

Q10: The worst case time complexity of Quick Sort is $O(n^2)$.
The worst case occurs when the pivot is always an extreme (smallest or largest) element. This happens when input array is sorted or reverse sorted and either first or last element is picked as pivot.

The best case of Quick Sort is when we select pivot element as a median element.

Ans 11: Recurrence Relation.

(1) Merge Sort: $T(n) = 2T(n/2) + n$

(2) Quick Sort: $T(n) = 2T(n/2) + n$

Merge Sort is more efficient and works faster than Quick Sort in case of larger array size or data sets.

The worst case complexity for Quick Sort is $O(n^2)$ where $O(n \log n)$ for Merge Sort.

Ans 12: Stable Selection Sort.

```

void stableSelSort(int arr[], int n)
{

```

```

    for (int i = 0; i < n-1; i++)
    {

```



```

int min = i;
for (int j = i+1; j < n; j++)
    if (a[min] > a[j])
        min = j;

int key = a[min];
while (min > i)
    a[min] = a[min-1];
    min--;

a[i] = key;
}

int main()
{

```

```

    int a[] = {4, 5, 3, 2, 4, 1};
    int n = sizeof(a) / sizeof(a[0]);
    stable_sel_sort(a, n);
    for (int i = 0; i < n; i++)
        cout << a[i] << " ";

    cout << endl;
    return 0;
}

```

Ans 13: The easiest way to do this is to use external sorting. We divide our source file into temporary files of size equals to the size of RAM & first sort these files.

→ External Sorting

If the input data is such that it can't adjust in the memory entirely at once, it needs to be stored in a hard disk, floppy disk or any other storage device. This is external sorting.

Internal Sorting - If the input data is such that it can be adjust in the main memory at once then it is called internal sorting.

4) Polynomial
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