Gradient Descent for Linear Regression

Parameter Learning

repeat until convergence {

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1)$$

(for
$$j = 1$$
 and $j = 0$)

Linear Regression Model

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^2$$





repeat until convergence {

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1)$$

(for
$$j = 1$$
 and $j = 0$)

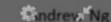
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Linear Regression Model

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^2$$





$$\frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1) = \frac{\partial}{\partial \theta_j} \cdot \frac{1}{2m} = \frac{m}{2} \left(h_0(x^{(i)}) - y^{(i)} \right)^2$$

Windows'u Etkinleştir Windows'u etkinleştirmek için Ayarlar'a gidin.



1:21 / 10:20

$$\frac{\partial}{\partial \theta_{j}} J(\theta_{0}, \theta_{1}) = \frac{\partial}{\partial \theta_{0}} \cdot \frac{1}{2m} \cdot \sum_{i=1}^{m} \left(\frac{h_{0}(x^{(i)}) - y^{(i)}}{h_{0}(x^{(i)}) - y^{(i)}} \right)^{2}$$

$$= \frac{\partial}{\partial \theta_{j}} \frac{1}{2m} \cdot \sum_{i=1}^{m} \left(0_{0} + 0_{1} \times x^{(i)} - y^{(i)} \right)^{2}$$

$$\frac{\partial}{\partial \theta_{j}} J(\theta_{0}, \theta_{1}) = \frac{\partial}{\partial \theta_{0}} \cdot \frac{1}{2m} \sum_{i=1}^{m} \left(\frac{h_{0}(x^{(i)}) - y^{(i)}}{h_{0}(x^{(i)}) - y^{(i)}} \right)^{2}$$

$$= \frac{2}{\partial \theta_{0}} \frac{1}{2m} \sum_{i=1}^{m} \left(0_{0} + 0_{1} x^{(i)} - y^{(i)} \right)^{2}$$

$$\Theta_{\circ} j = 0 : \frac{\partial}{\partial \theta_{0}} J(\theta_{0}, \theta_{1}) = \frac{1}{m} \underbrace{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{i=1}{\overset{m}{\underset{m}}{\overset{m}{\underset{i=1}{\overset{m}{\underset{m}{\underset{i=1}{\overset{m}{\underset{m}}{\overset{m}{\underset{m}}{\overset{m}{\underset{m}}{\overset{m}{\underset{m}}{\overset{m}{\underset{m}}{\overset{m}{\underset{m}}{\overset{m}{\underset{m}}{\overset{m}{\underset{m}}{\overset{m}}{\underset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}}{\overset{m}$$

repeat until convergence { $\theta_0 := \theta_0 - \alpha \frac{1}{m} \sum_{i=1}^m \left(h_{\theta}(x^{(i)}) - y^{(i)} \right)$ $\theta_1 := \theta_1 - \alpha \frac{1}{m} \sum_{i=1}^m \left(h_{\theta}(x^{(i)}) - y^{(i)} \right) \cdot x^{(i)}$ }

repeat until convergence {

$$\theta_0 := \theta_0 - \alpha \prod_{i=1}^m \left(h_{\theta}(x^{(i)}) - y^{(i)} \right)$$

$$\theta_1 := \theta_1 - \alpha \frac{1}{m} \sum_{i=1}^{m} \left(h_{\theta}(x^{(i)}) - y^{(i)} \right) \cdot x^{(i)}$$

}

2 7(0,0)

repeat until convergence {

$$\theta_0 := \theta_0 - \alpha \prod_{i=1}^m \sum_{i=1}^m \left(h_{\theta}(x^{(i)}) - y^{(i)} \right)$$

$$\theta_1 := \theta_1 - \alpha \prod_{i=1}^{m} \sum_{i=1}^{m} \left(h_{\theta}(x^{(i)}) - y^{(i)} \right) \cdot x^{(i)}$$

(10,0) Z 300 J (00,0)

repeat until convergence {

$$\theta_0 := \theta_0 - \alpha \frac{1}{m} \sum_{i=1}^m \left(h_{\theta}(x^{(i)}) - y^{(i)} \right)$$

$$\theta_1 := \theta_1 - \alpha \frac{1}{m} \sum_{i=1}^m \left(h_{\theta}(x^{(i)}) - y^{(i)} \right) \cdot x^{(i)}$$

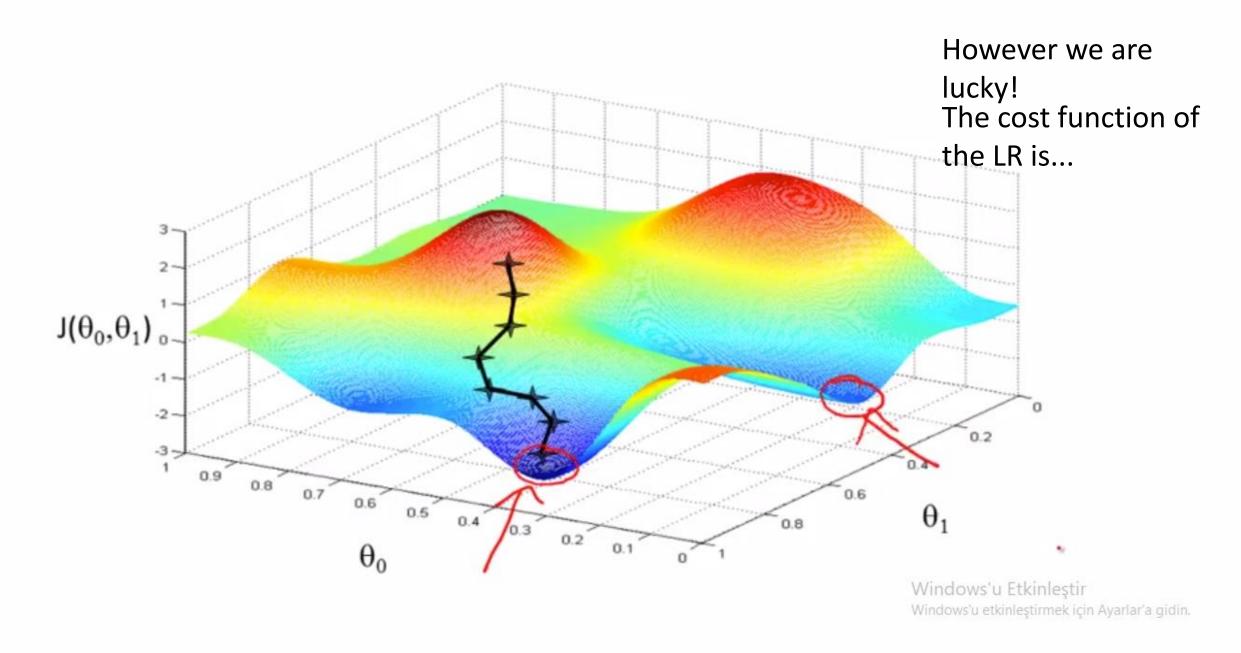
update θ_0 and θ_1 simultaneously

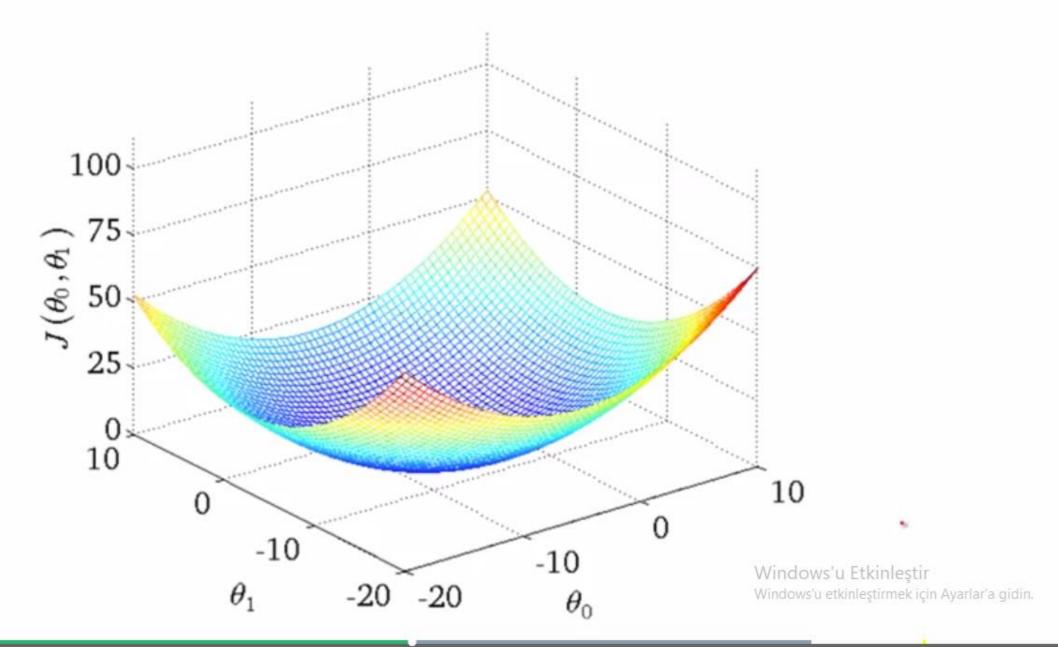
Recall that the initial points are important!

Windows'u Etkinleştir Windows'u etkinleştirmek için Ayarlar'a gidin.



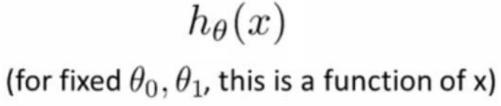
10:20

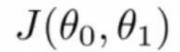




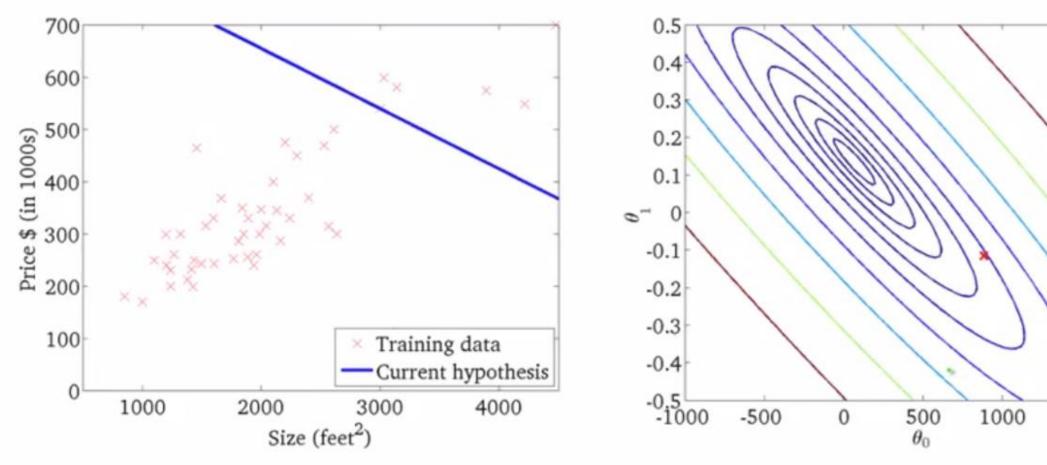
Cost function of the LR

- Convex function.
- It's a bowl shaped function.
- Always converges to global optimum.





(function of the parameters θ_0, θ_1)



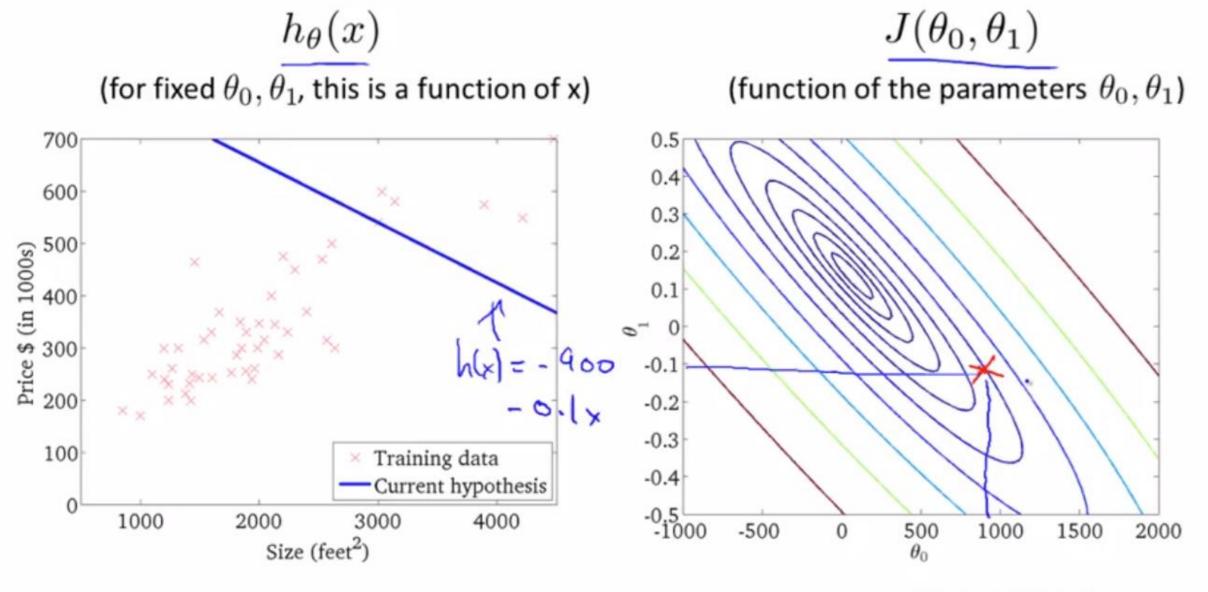
Windows'u Etkinlestir Windows'u etkinleştirmek için Ayarlar'a gidin.

1500



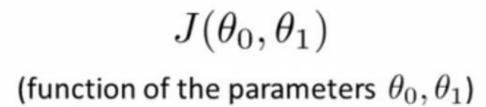


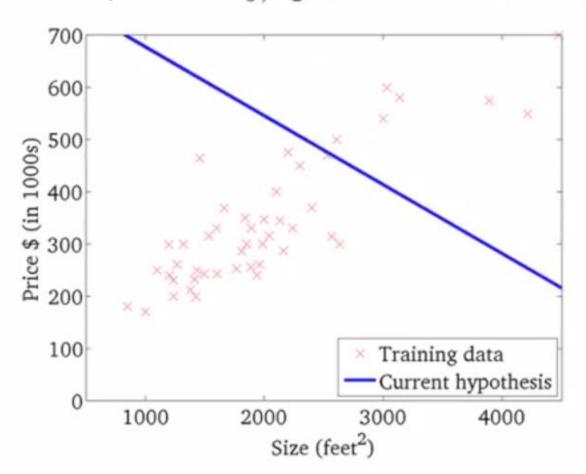
2000

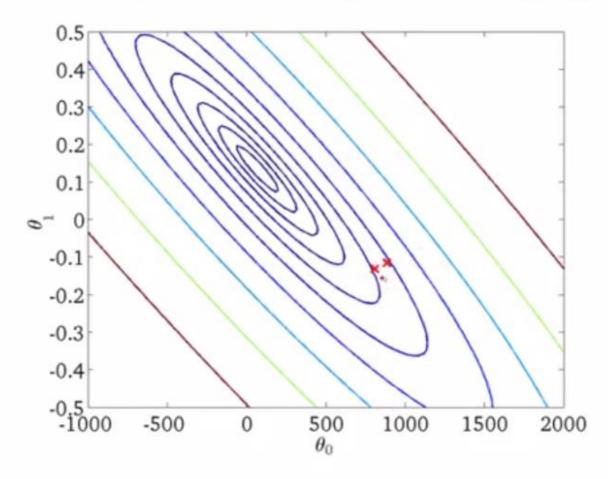


Windows'u Etkinleştir Windows'u etkinleştirmek için Ayarlar'a gidin.

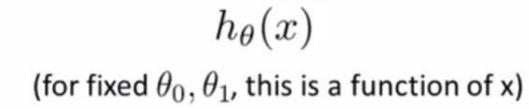
 $h_{ heta}(x)$ (for fixed $heta_0, heta_1$, this is a function of x)

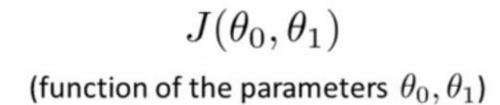


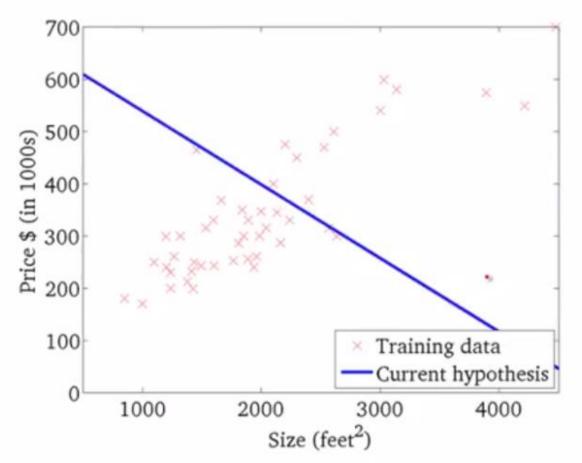


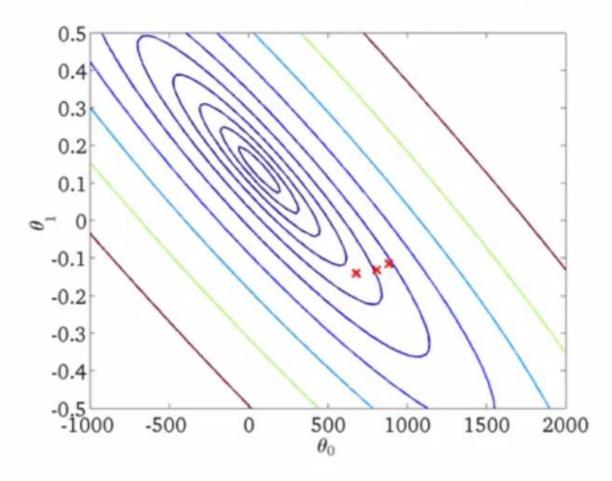


Windows'u Etkinleştir Windows'u etkinleştirmek için Ayarlar'a gidin.



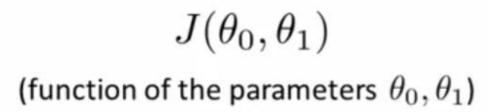


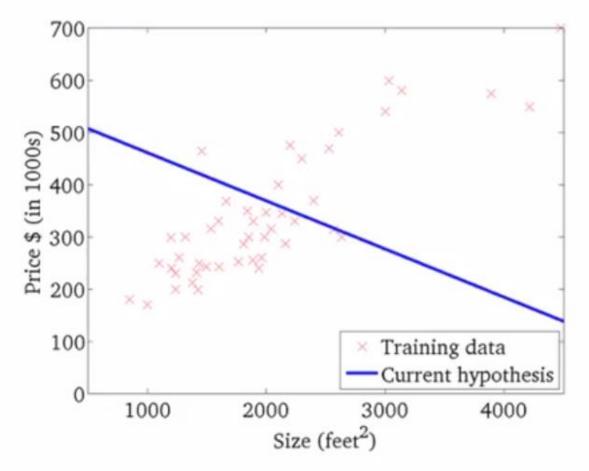


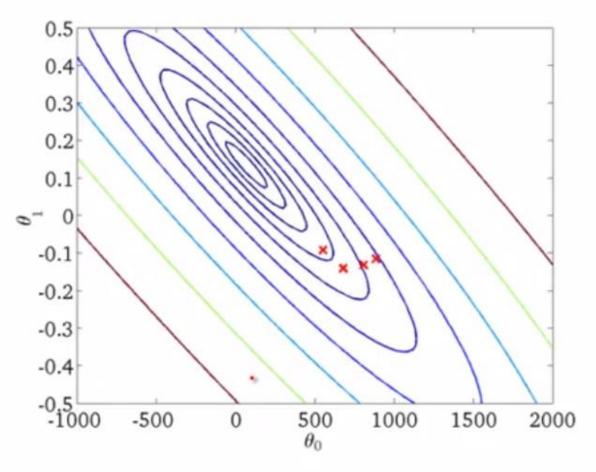


Windows'u Etkinleştir Windows'u etkinleştirmek için Ayarlar'a gidin.

 $h_{ heta}(x)$ (for fixed $heta_0, heta_1$, this is a function of x)



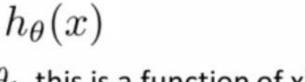




Windows'u Etkinleştir Windows'u etkinleştirmek için Ayarlar'a gidin.

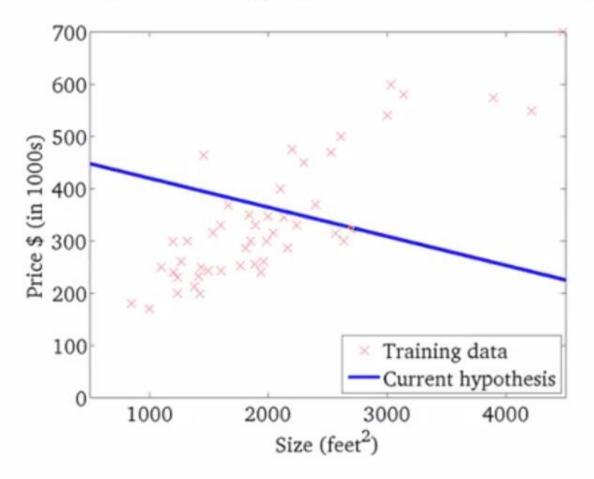
 $h_{\theta}(x)$

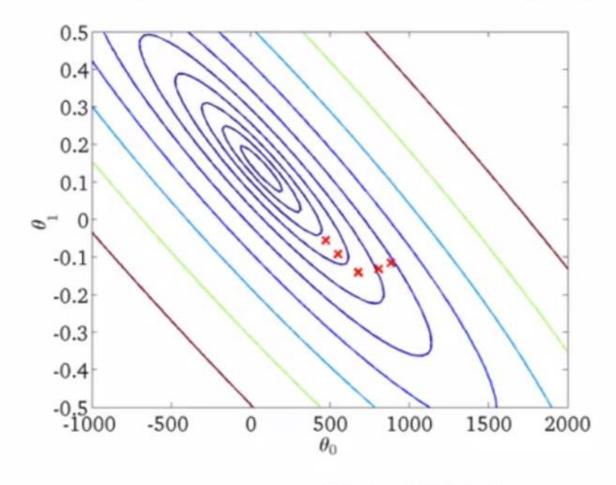
(for fixed θ_0 , θ_1 , this is a function of x)



$J(\theta_0, \theta_1)$

(function of the parameters θ_0, θ_1)





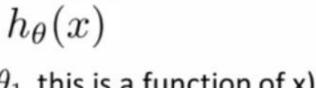
Windows'u Etkinleştir Windows'u etkinleştirmek için Ayarlar'a gidin.

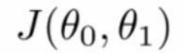
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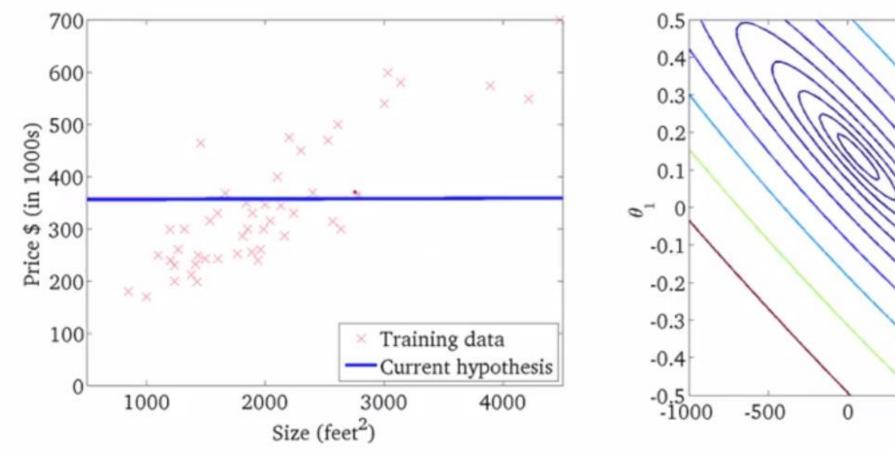
 $h_{\theta}(x)$

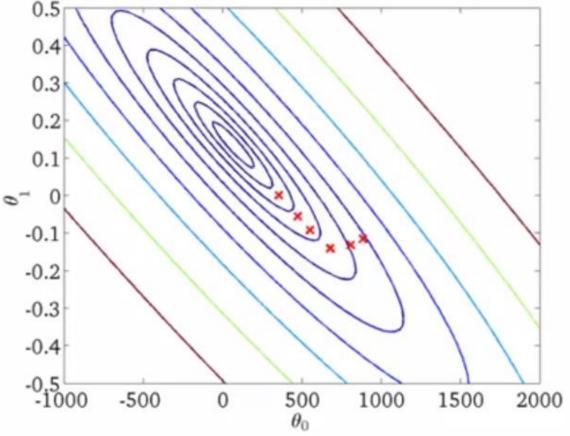
(for fixed θ_0 , θ_1 , this is a function of x)





(function of the parameters θ_0, θ_1)

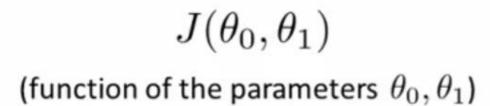


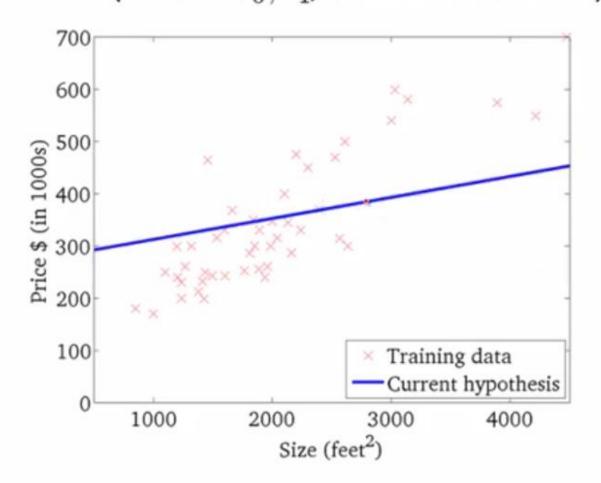


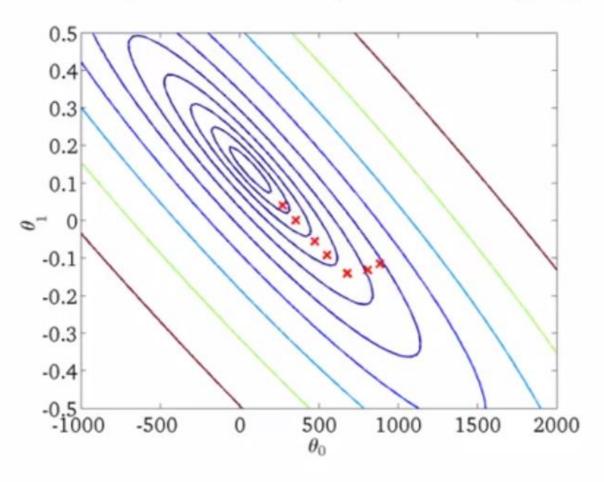
Windows'u Etkinleştir Windows'u etkinleştirmek için Ayarlar'a gidin.



 $h_{ heta}(x)$ (for fixed $heta_0, heta_1$, this is a function of x)

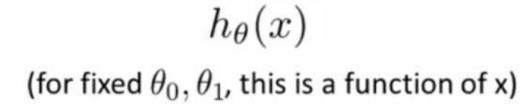


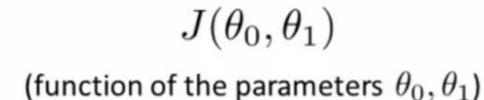


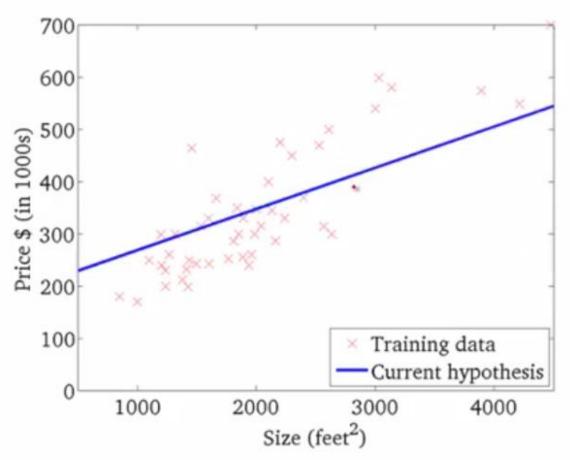


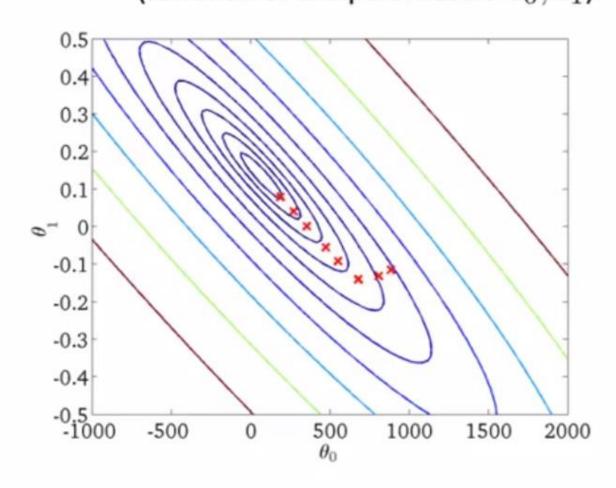
Windows'u Etkinleştir Windows'u etkinleştirmek için Ayarlar'a gidin.

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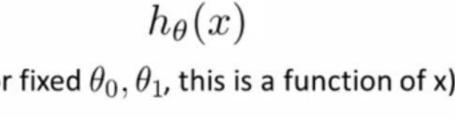






Windows'u Etkinleştir Windows'u etkinleştirmek için Ayarlar'a gidin.

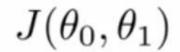
(for fixed θ_0 , θ_1 , this is a function of x)



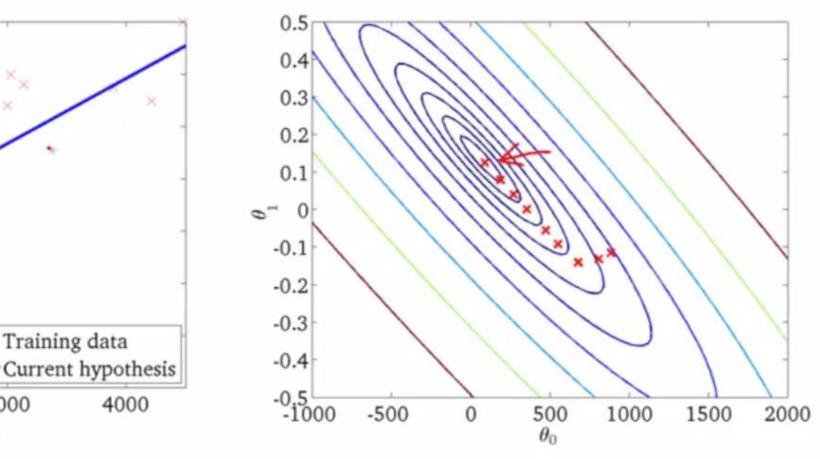
Training data

4000

3000



(function of the parameters θ_0, θ_1)



Windows'u Etkinleştir Windows'u etkinleştirmek için Ayarlar'a gidin.





1000

2000

Size (feet²)

700

600

500

400

300

200

100

Price \$ (in 1000s)

Gradient Descent for LR

- Batch Gradient Descent:
- Batch: Each step of gradient descent uses all training examples.

Which of the following are true statements? Select all that apply.

- \square To make gradient descent converge, we must slowly decrease α over time.
- \square Gradient descent is guaranteed to find the global minimum for any function $J(\theta_0,\theta_1)$.
- \square Gradient descent can converge even if α is kept fixed. (But α cannot be too large, or else it may fail to converge.)
- \blacksquare For the specific choice of cost function $J(\theta_0, \theta_1)$ used in linear regression, there are no local optima (other than the global optimum).