

# Advanced Optimization

Logistic Regression Model

*Logistic Regression*

## Optimization algorithm

Cost function  $J(\theta)$ . Want  $\min_{\theta} J(\theta)$ .

Given  $\theta$ , we have code that can compute

- $J(\theta)$
- $\frac{\partial}{\partial \theta_j} J(\theta)$  (for  $j = 0, 1, \dots, n$ )

Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.

## Optimization algorithm

Cost function  $J(\theta)$ . Want  $\min_{\theta} J(\theta)$ .

Given  $\theta$ , we have code that can compute

→  $-J(\theta)$

→  $-\frac{\partial}{\partial \theta_j} J(\theta)$  (for  $j = 0, 1, \dots, n$ )

Gradient descent:

Repeat {

→  $\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta)$

}

Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.

## Optimization algorithm

Given  $\theta$ , we have code that can compute

$$\begin{bmatrix} - J(\theta) \\ - \frac{\partial}{\partial \theta_j} J(\theta) \end{bmatrix} \quad (\text{for } j = 0, 1, \dots, n)$$

Optimization algorithms:

→ - Gradient descent



Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.



1:48 / 14:06



Andrew Ng

## Optimization algorithm

Given  $\theta$ , we have code that can compute

$$\left[ \begin{array}{l} - J(\theta) \\ - \frac{\partial}{\partial \theta_j} J(\theta) \end{array} \right] \quad (\text{for } j = 0, 1, \dots, n)$$

Optimization algorithms:

- - Gradient descent
- Conjugate gradient
- BFGS
- L-BFGS

Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.

## Optimization algorithm

Given  $\theta$ , we have code that can compute

$$\begin{aligned} & - J(\theta) \\ & - \frac{\partial}{\partial \theta_j} J(\theta) \end{aligned} \quad \leftarrow \quad (\text{for } j = 0, 1, \dots, n)$$

Optimization algorithms:

- - Gradient descent
- Conjugate gradient
- BFGS
- L-BFGS

Advantages:

- No need to manually pick  $\alpha$
- Often faster than gradient descent.

Disadvantages:

- More complex

Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.

Example:

$$\theta = \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix}$$

$$J(\theta) = (\theta_1 - 5)^2 + (\theta_2 - 5)^2$$

$$\frac{\partial}{\partial \theta_1} J(\theta) = 2(\theta_1 - 5)$$

$$\frac{\partial}{\partial \theta_2} J(\theta) = 2(\theta_2 - 5)$$

Example:

$$\rightarrow \theta = \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix} \quad \min_{\theta} J(\theta) \quad \theta_1=5, \theta_2=5.$$

$$\rightarrow J(\theta) = (\theta_1 - 5)^2 + (\theta_2 - 5)^2$$

$$\rightarrow \frac{\partial}{\partial \theta_1} J(\theta) = 2(\theta_1 - 5)$$

$$\frac{\partial}{\partial \theta_2} J(\theta) = 2(\theta_2 - 5)$$



Example:

$\theta = \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix}$   $\min_{\theta} J(\theta)$   
 $\theta_1 = 5, \theta_2 = 5.$

$$J(\theta) = (\theta_1 - 5)^2 + (\theta_2 - 5)^2$$
$$\frac{\partial}{\partial \theta_1} J(\theta) = 2(\theta_1 - 5)$$
$$\frac{\partial}{\partial \theta_2} J(\theta) = 2(\theta_2 - 5)$$

```
function [jVal, gradient]
    = costFunction(theta)
jVal = (theta(1)-5)^2 + ...
      (theta(2)-5)^2;
gradient = zeros(2,1);
gradient(1) = 2*(theta(1)-5);
gradient(2) = 2*(theta(2)-5);
```

Example:

$\theta = \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix}$

$J(\theta) = (\theta_1 - 5)^2 + (\theta_2 - 5)^2$

$\frac{\partial}{\partial \theta_1} J(\theta) = 2(\theta_1 - 5)$

$\frac{\partial}{\partial \theta_2} J(\theta) = 2(\theta_2 - 5)$

```
function [jVal, gradient]
    = costFunction(theta)
    jVal = (theta(1)-5)^2 + ...
           (theta(2)-5)^2;
    gradient = zeros(2,1);
    gradient(1) = 2*(theta(1)-5);
    gradient(2) = 2*(theta(2)-5);
```

```
options = optimset('GradObj', 'on', 'MaxIter', '100');
initialTheta = zeros(2,1);
[optTheta, functionVal, exitFlag] ...
    = fminunc(@costFunction, initialTheta, options);
```

Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.

$$\text{theta} = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_n \end{bmatrix}$$

```
function [jVal, gradient] = costFunction(theta)
```

```
    jVal = [code to compute  $J(\theta)$ ];
```

```
    gradient(1) = [code to compute  $\frac{\partial}{\partial \theta_0} J(\theta)$ ];
```

```
    gradient(2) = [code to compute  $\frac{\partial}{\partial \theta_1} J(\theta)$ ];
```

```
    :
```

```
    gradient(n+1) = [code to compute  $\frac{\partial}{\partial \theta_n} J(\theta)$ ];
```

$$\underline{\text{theta}} = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_n \end{bmatrix}$$

$\theta_0$  — theta(1)  
 $\theta_1$  — theta(2)  
 $\theta_n$  — theta(n+1)

```
function [jVal, gradient] = costFunction(theta)
```

```
    jVal = [code to compute  $J(\theta)$ ];
```

```
    gradient(1) = [code to compute  $\frac{\partial}{\partial \theta_0} J(\theta)$ ];
```

```
    gradient(2) = [code to compute  $\frac{\partial}{\partial \theta_1} J(\theta)$ ];
```

```
    :
```

```
    gradient(n+1) = [code to compute  $\frac{\partial}{\partial \theta_n} J(\theta)$ ];
```



$$\underline{\text{theta}} = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_n \end{bmatrix}$$

$\xrightarrow{\text{theta}(1)}$   
 $\xrightarrow{\text{theta}(2)}$   
 $\xrightarrow{\text{theta}(n+1)}$

function [jVal, gradient] = costFunction(theta)

jVal = [code to compute  $J(\theta)$ ];

gradient(1) = [code to compute  $\frac{\partial}{\partial \theta_0} J(\theta)$ ];

gradient(2) = [code to compute  $\frac{\partial}{\partial \theta_1} J(\theta)$ ];

$\vdots$

gradient(n+1) = [code to compute  $\frac{\partial}{\partial \theta_n} J(\theta)$ ];

Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.

# Exercise

- Suppose you want to use an advanced optimization algorithm to minimize the cost function for logistic regression with parameters  $\theta_0$  and  $\theta_1$ . You write the following code :
- *function [jVal, gradient] = costFunction(theta)*  
    *jVal = % code to compute J*
- *gradient(1) = CODE#1 % derivative for theta\_0*
- *gradient(2) = CODE#2 % derivative for theta\_1*

# Exercise

- What should CODE#1 and CODE#2 above compute?

What should CODE#1 and CODE#2 above compute?

- ☐ CODE#1 and CODE#2 should compute  $J(\theta)$ .
- ☐ CODE#1 should be  $\theta_1$  and CODE#2 should be  $\theta_2$ .
- ☐ CODE#1 should compute  $\frac{1}{m} \sum_{i=1}^m [(h_{\theta}(x^{(i)}) - y^{(i)}) \cdot x_0^{(i)}] (= \frac{\partial}{\partial \theta_0} J(\theta))$ ,  
and CODE#2 should compute  $\frac{1}{m} \sum_{i=1}^m [(h_{\theta}(x^{(i)}) - y^{(i)}) \cdot x_1^{(i)}] (= \frac{\partial}{\partial \theta_1} J(\theta))$
- ☐ None of them.