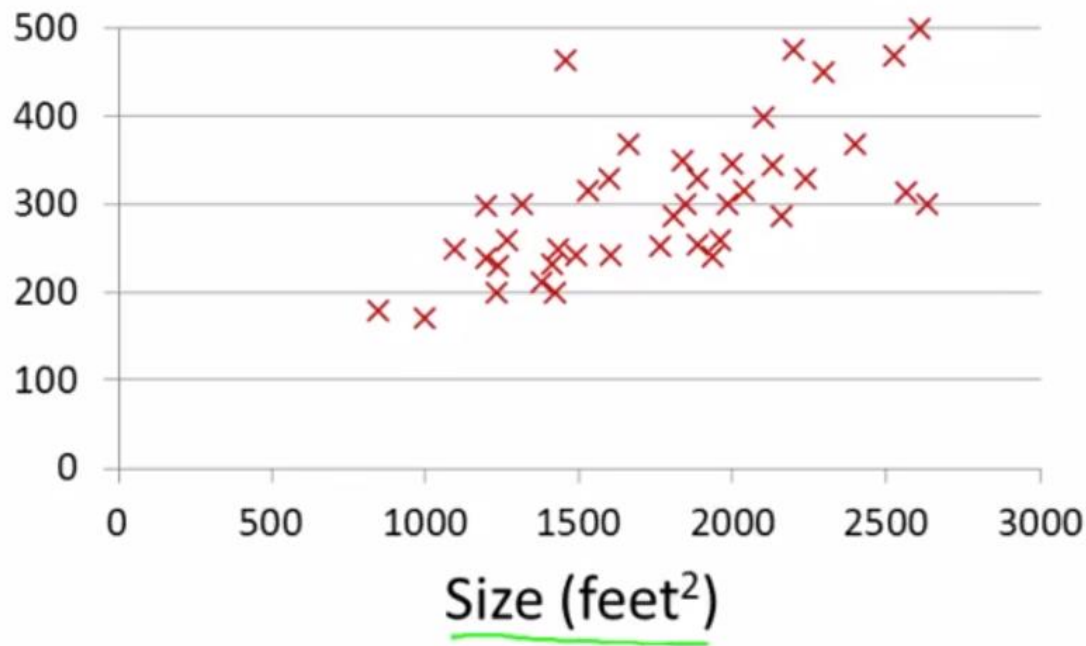


# Model and Cost Function

Model Representation

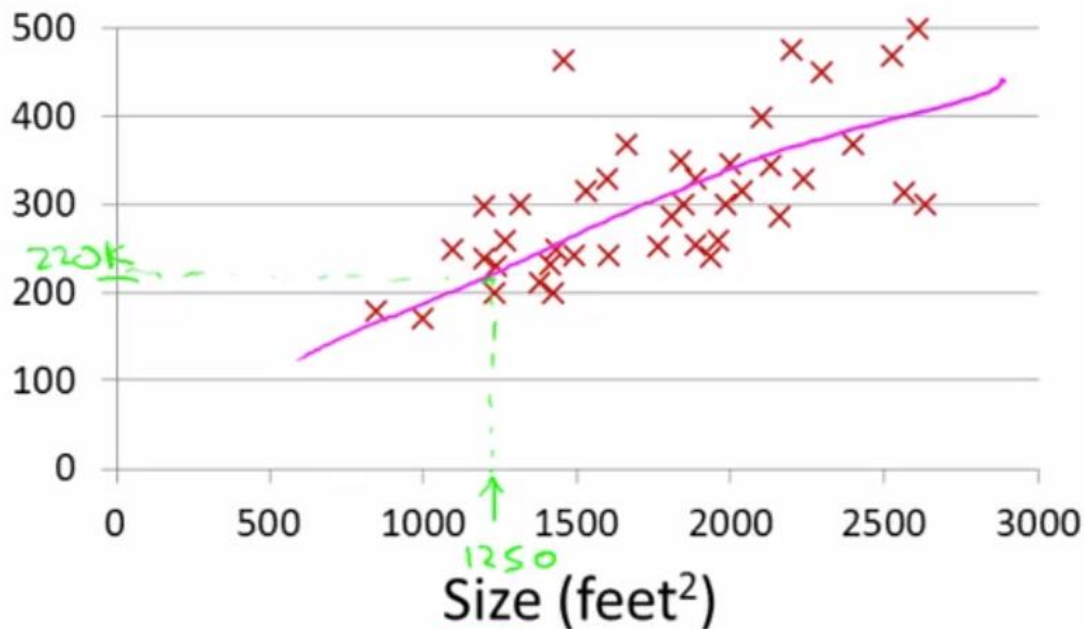
# Housing Prices (Portland, OR)

Price  
(in 1000s  
of dollars)



# Housing Prices (Portland, OR)

Price  
(in 1000s  
of dollars)



## Supervised Learning

Given the “right answer” for each example in the data.

## Regression Problem

Predict real-valued output

**Training set of  
housing prices  
(Portland, OR)**

<b>Size in feet<sup>2</sup> (x)</b>	<b>Price (\$) in 1000's (y)</b>
2104	460
1416	232
1534	315
852	178
...	...

Notation:

**m** = Number of training examples

**x**'s = "input" variable / features

**y**'s = "output" variable / "target" variable

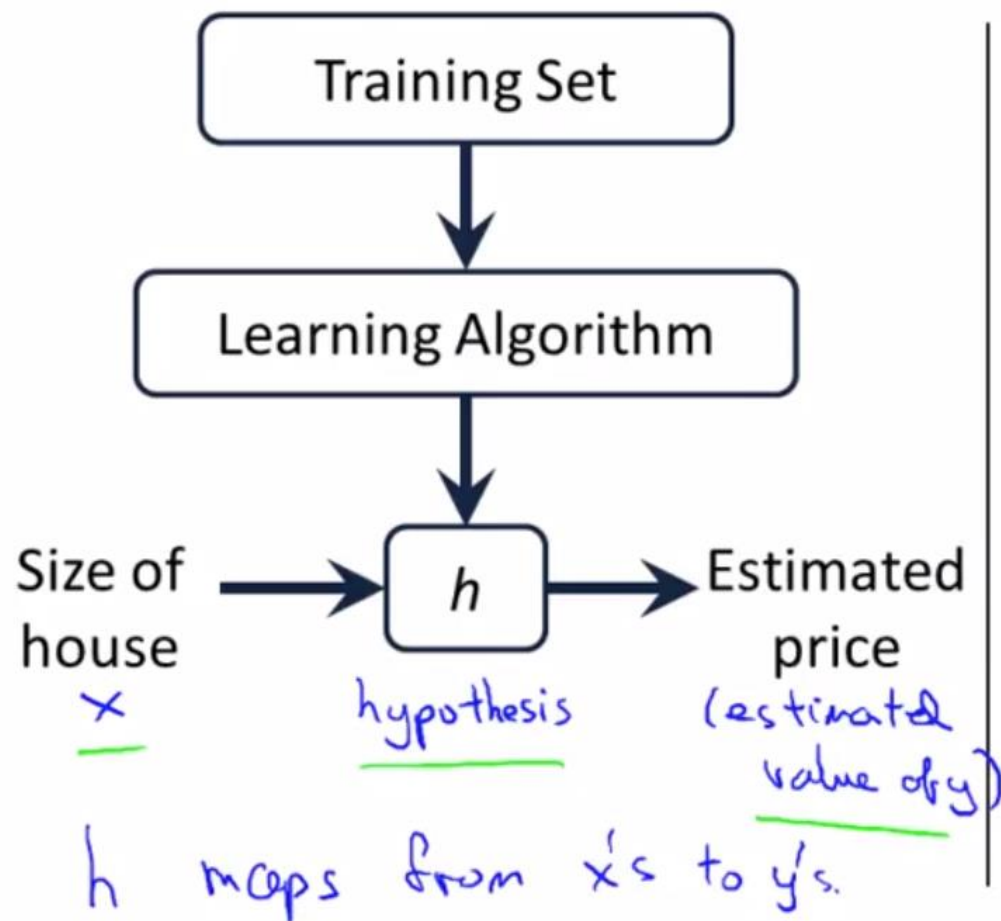
Training Set



Learning Algorithm



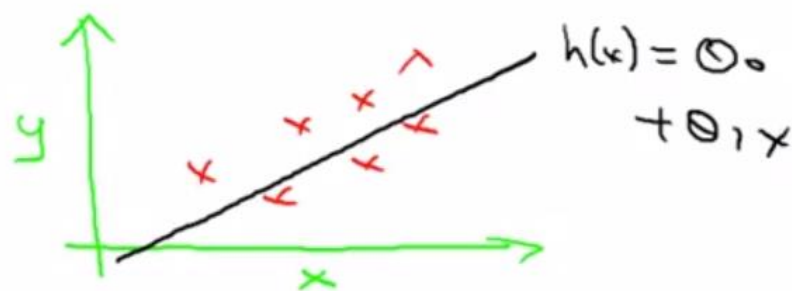
$h$



How do we represent  $h$  ?

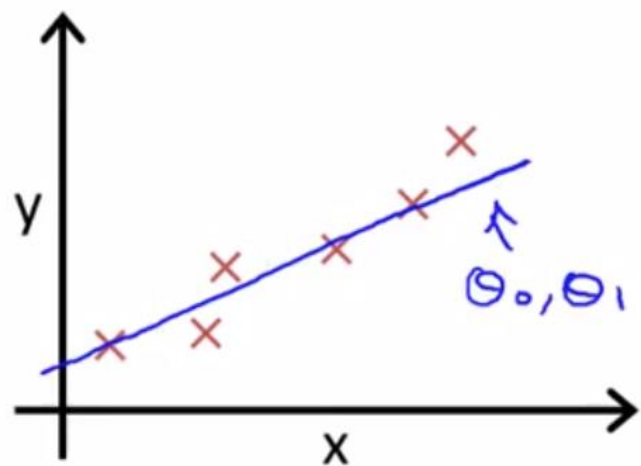
$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

Shorthand:  $h(x)$



Linear regression with one variable. ( $x$ )  
Univariate linear regression.  
↳ one variable

Cost Function: How to choose  $\theta$ s?



Idea: Choose  $\theta_0, \theta_1$  so that  $h_{\theta}(x)$  is close to  $y$  for our training examples  $(x, y)$



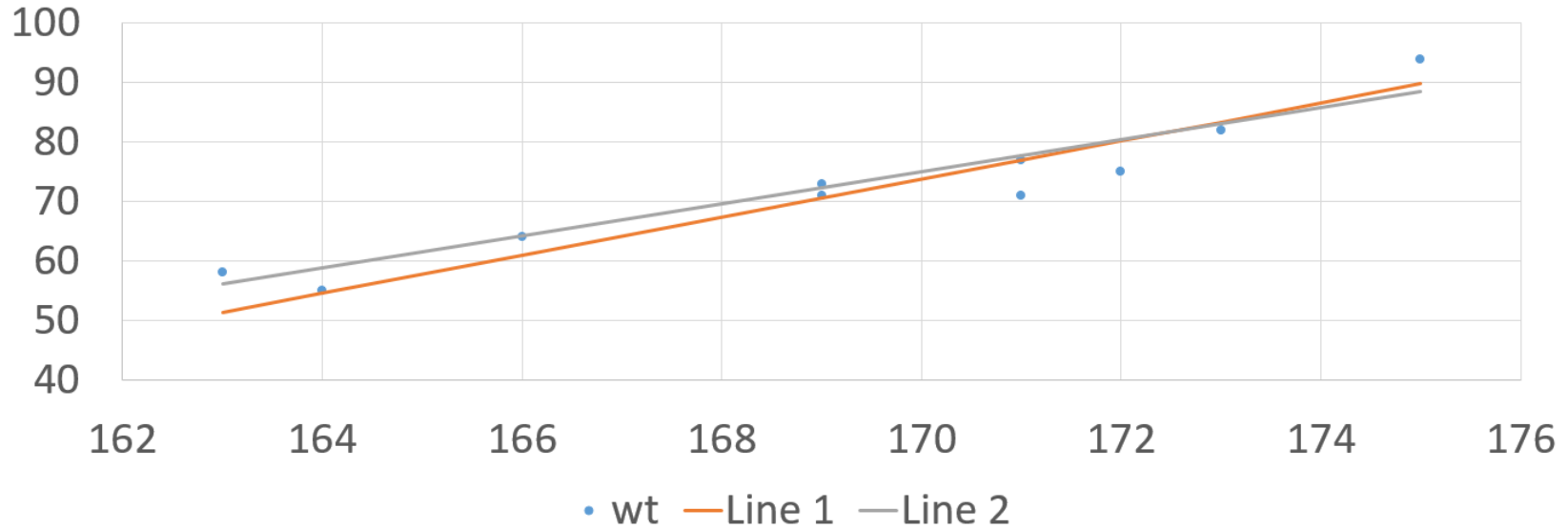
# Sample relations

- Assume we want to find the relation between the weight and the height of the students in this university.
- We have the following data:

Height	Weight
163	58
164	55
166	64
169	71
169	73
171	71
171	77
172	75
173	82
175	94

# Sample relations

Height vs Weight



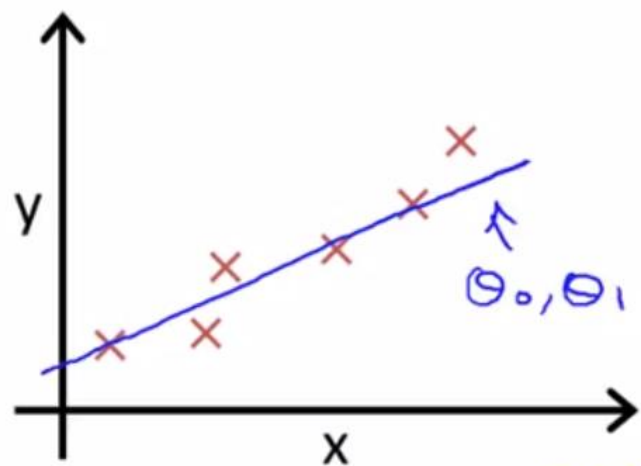
**Line 1:**  $\text{Weight} = -470.2 + 3.2 * \text{Height}$

**Line 2:**  $\text{Weight} = -384 + 2.7 * \text{Height}$

# Which line is better?

$X_i$	$y_i$	$\hat{y}$	$e_i$	$e_i^2$
163	58	51.4	6.6	43.56
164	55	54.6	0.4	0.16
166	64	61	3	9
169	71	70.6	0.4	0.16
169	73	70.6	2.4	5.76
171	71	77	-6	36
171	77	77	0	0
172	75	80.2	-5.2	27.04
173	82	83.4	-1.4	1.96
175	94	89.8	4.2	17.64
				<b>141.28</b>

$y_i$	$\hat{y}$	$e_i$	$e_i^2$
58	56.1	1.9	3.61
55	58.8	-3.8	14.44
64	64.2	-0.2	0.04
71	72.3	-1.3	1.69
73	72.3	0.7	0.49
71	77.7	-6.7	44.89
77	77.7	-0.7	0.49
75	80.4	-5.4	29.16
82	83.1	-1.1	1.21
94	88.5	5.5	30.25
			<b>126.27</b>



$(x^{(i)}, y^{(i)})$

Idea: Choose  $\theta_0, \theta_1$  so that  $h_{\theta}(x)$  is close to  $y$  for our training examples  $(x, y)$

$x, y$

minimize  $\theta_0, \theta_1$

$\frac{1}{2m} \sum_{i=1}^m \left( \underbrace{h_{\theta}(x^{(i)})}_{h_{\theta}(x^{(i)}) = \theta_0 + \theta_1 x^{(i)}} - y^{(i)} \right)^2$

# training examples

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

minimize  $\theta_0, \theta_1$   $J(\theta_0, \theta_1)$

Cost function

Squared error function

Hypothesis:  $h_{\theta}(x) = \theta_0 + \theta_1 x$

Parameters:  $\theta_0, \theta_1$

Cost Function:  $J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$

Goal: minimize  $J(\theta_0, \theta_1)$   
 $\theta_0, \theta_1$

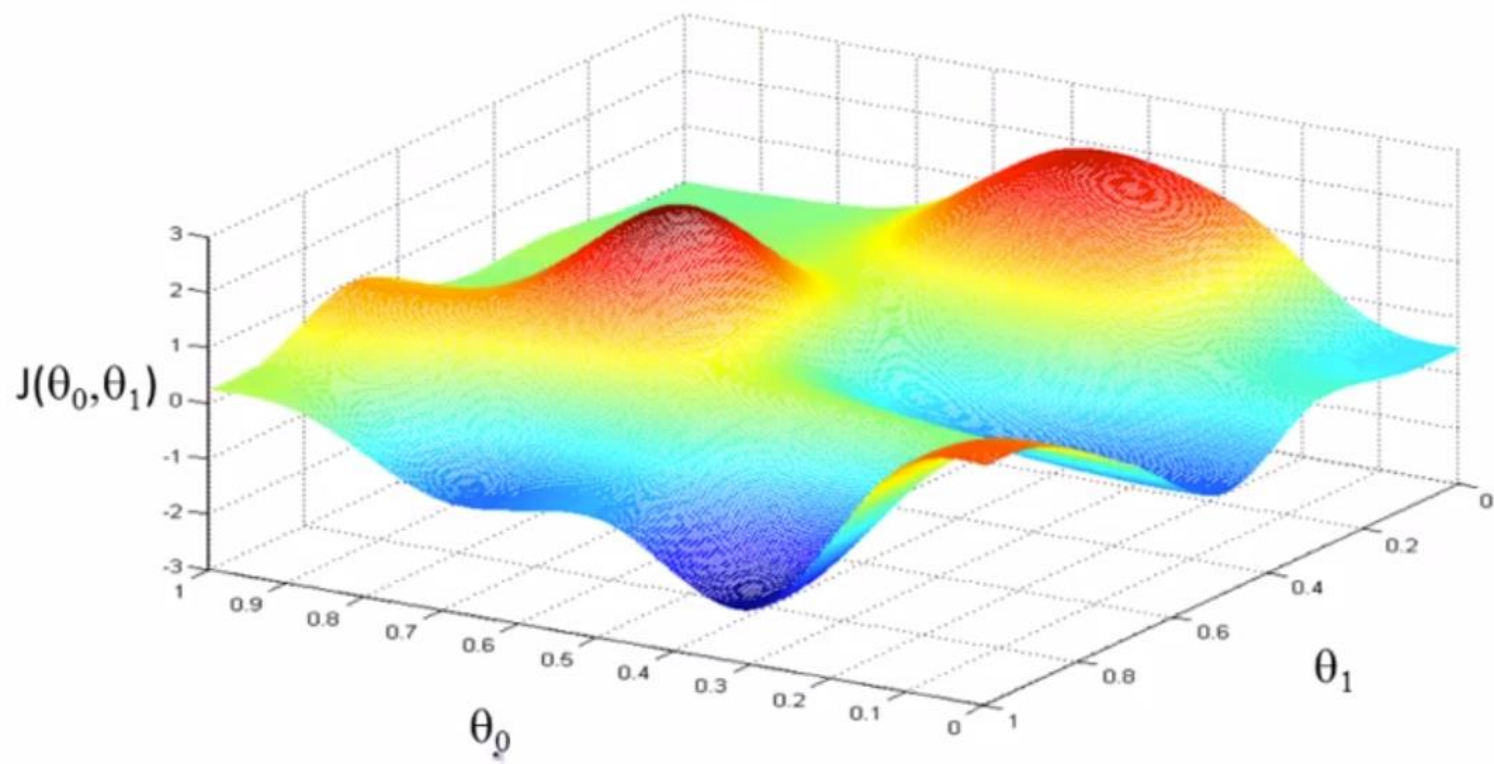
Have some function  $J(\theta_0, \theta_1)$

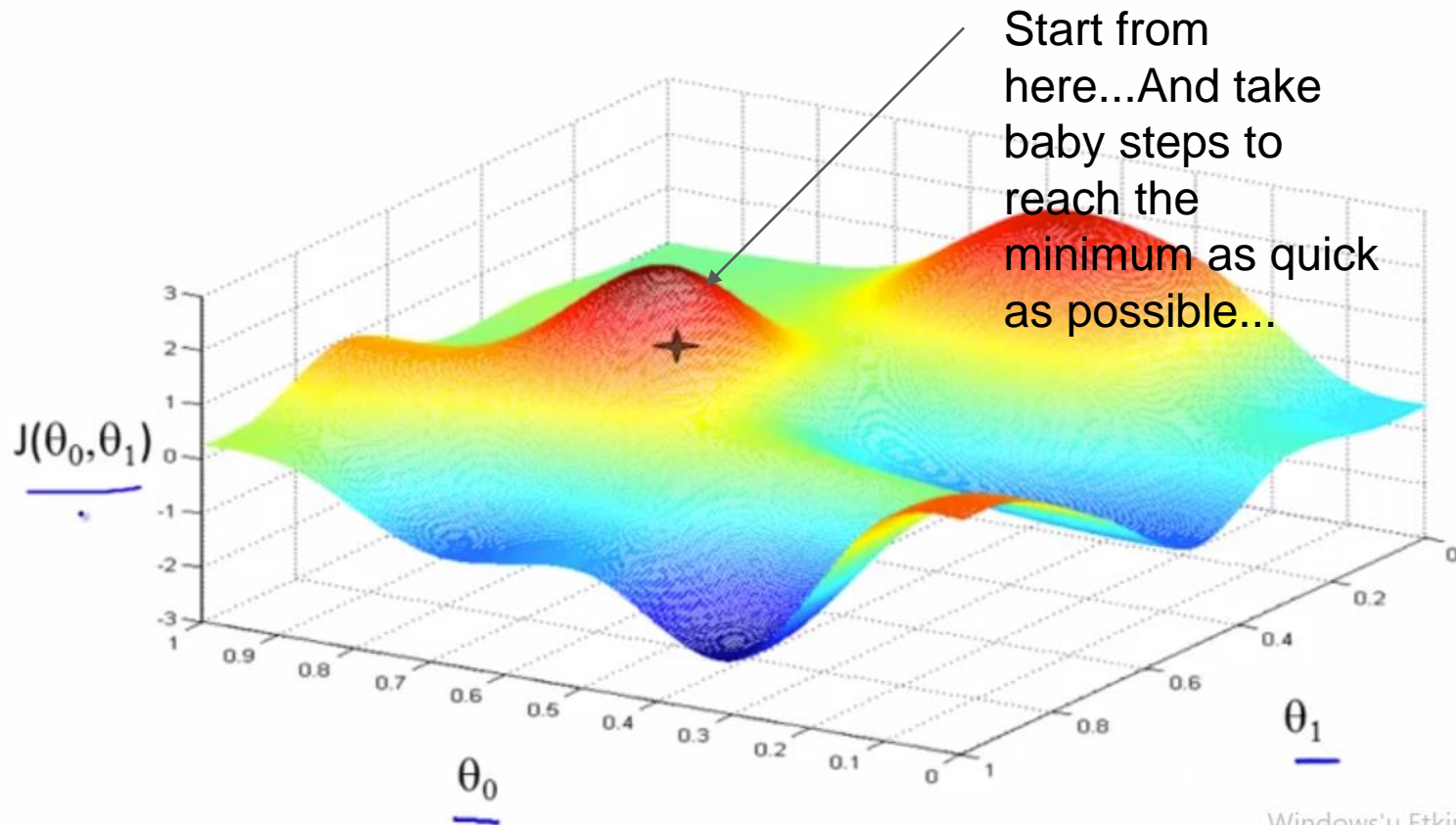
Want  $\min_{\theta_0, \theta_1} J(\theta_0, \theta_1)$

## Outline:

- Start with some  $\theta_0, \theta_1$
- Keep changing  $\theta_0, \theta_1$  to reduce  $J(\theta_0, \theta_1)$   
until we hopefully end up at a minimum

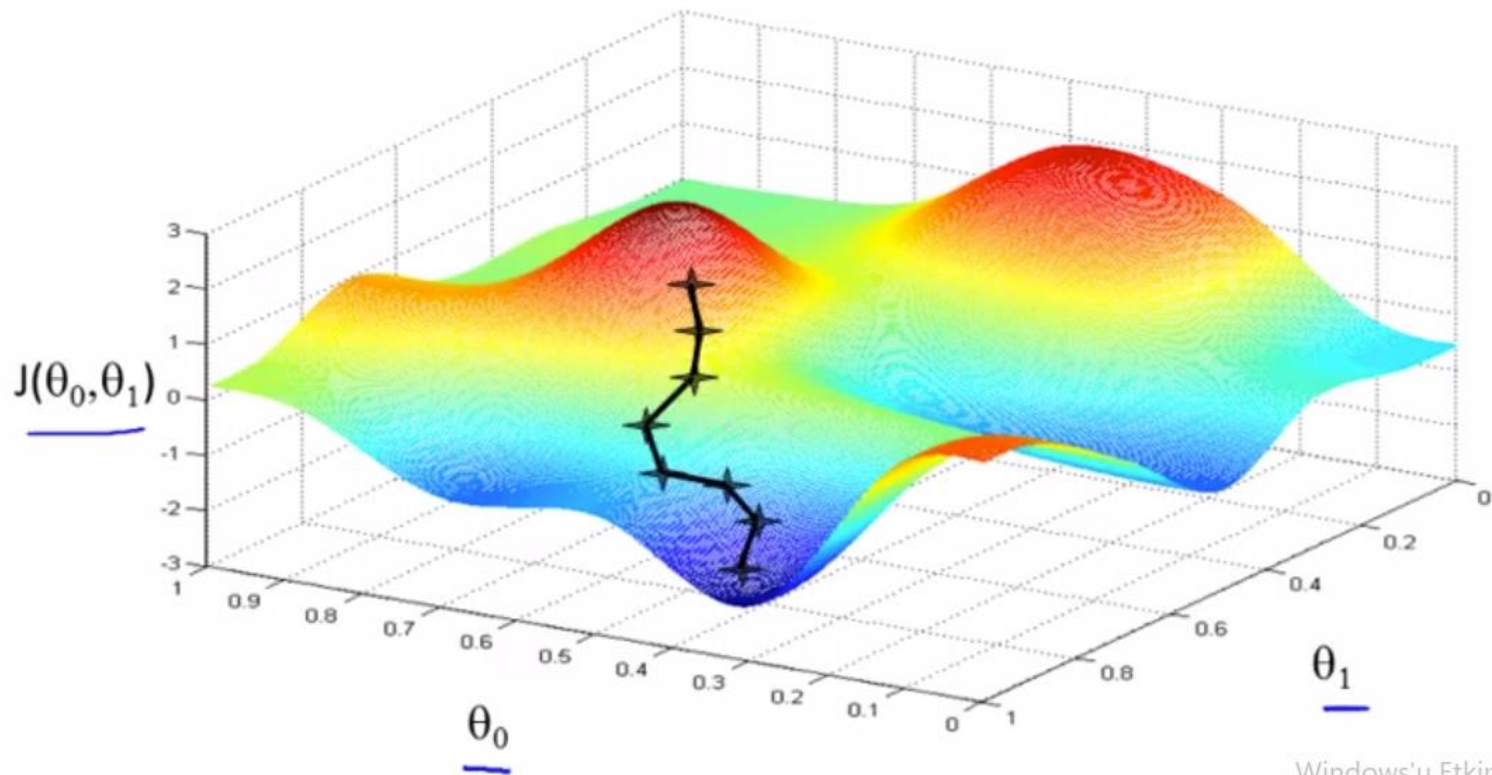
Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.





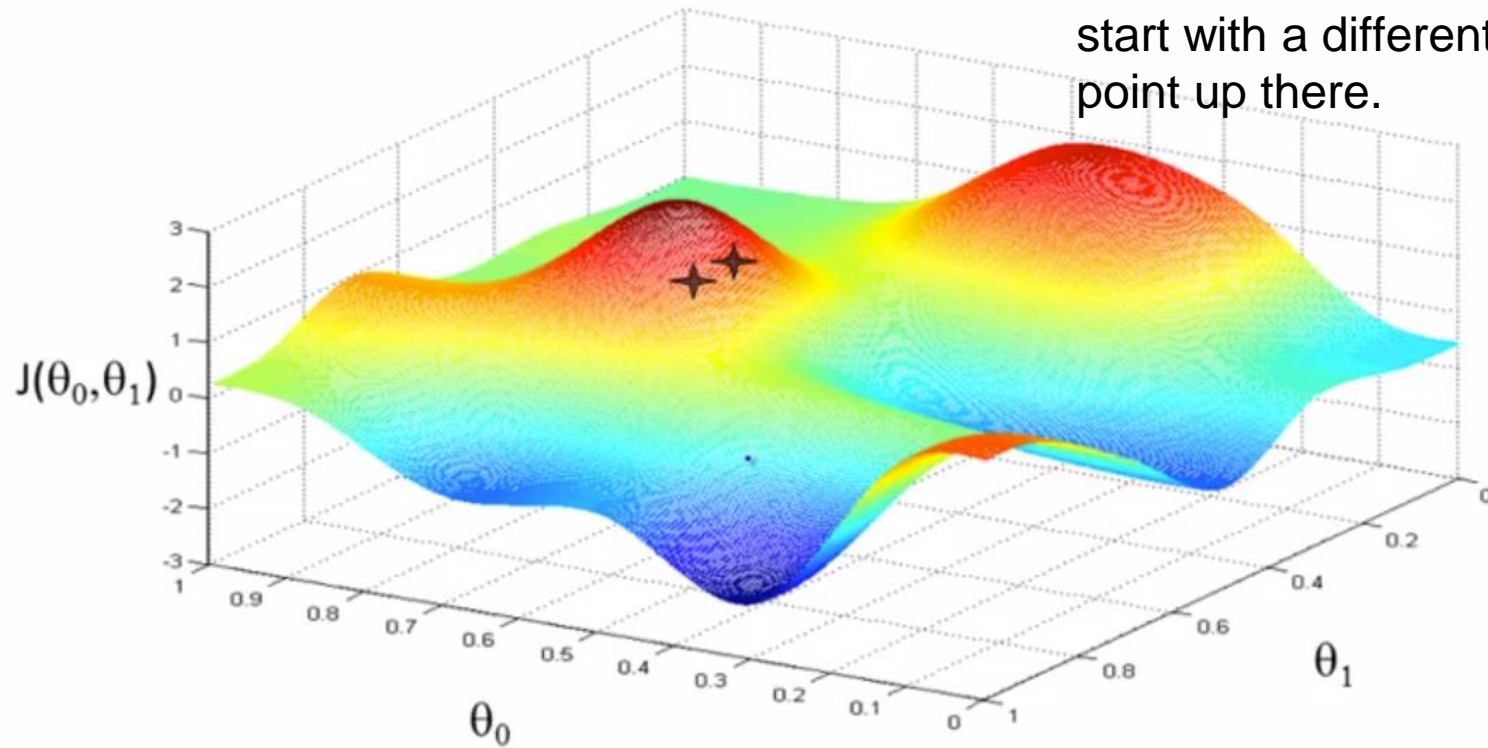
Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.



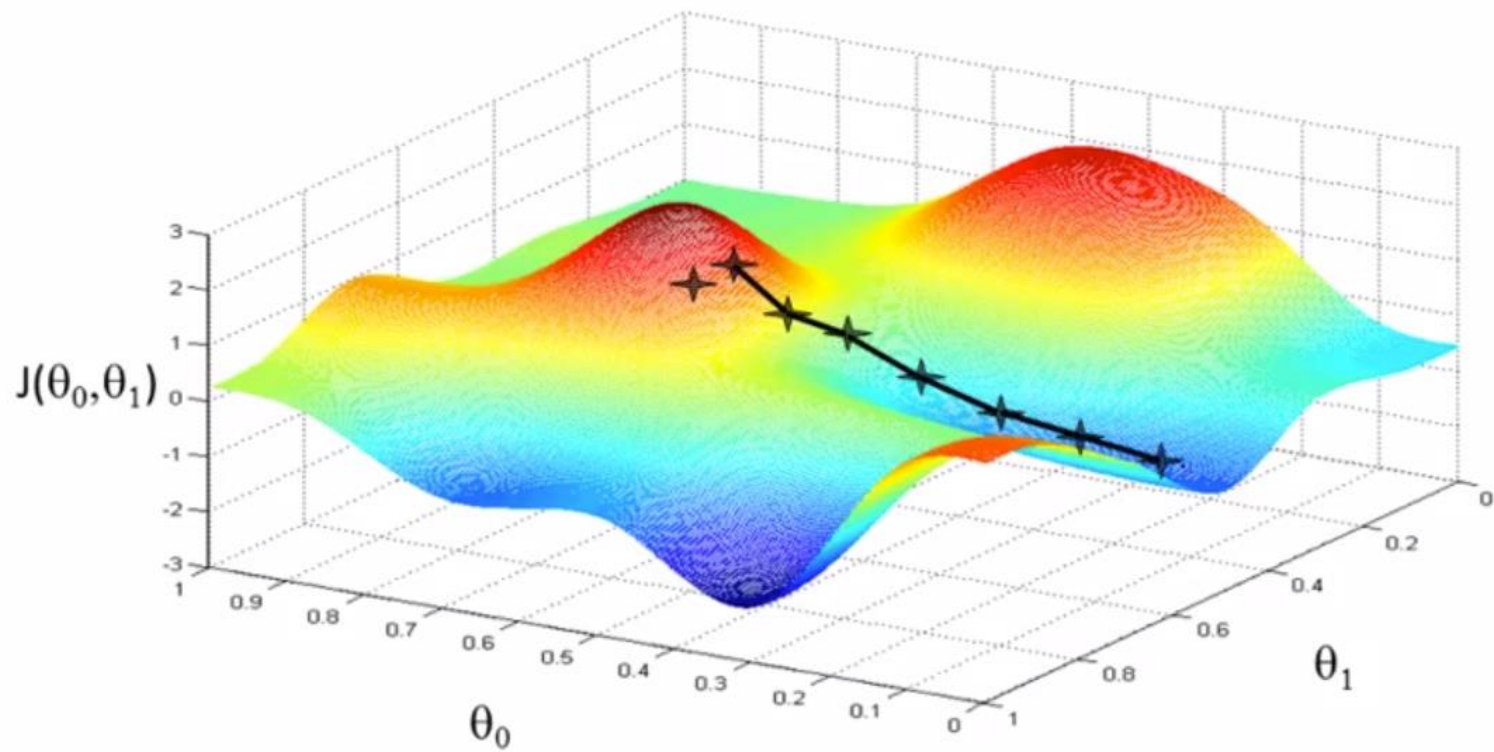


Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.

Now assume we start with a different point up there.



Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.



Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.

# Gradient descent algorithm

repeat until convergence {

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1) \quad (\text{for } j = 0 \text{ and } j = 1)$$

}

Learning  
rate

Derivative

Simultaneously  
update  $\theta_0$  and  $\theta_1$

---

Correct: Simultaneous update

$$\text{temp0} := \theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)$$

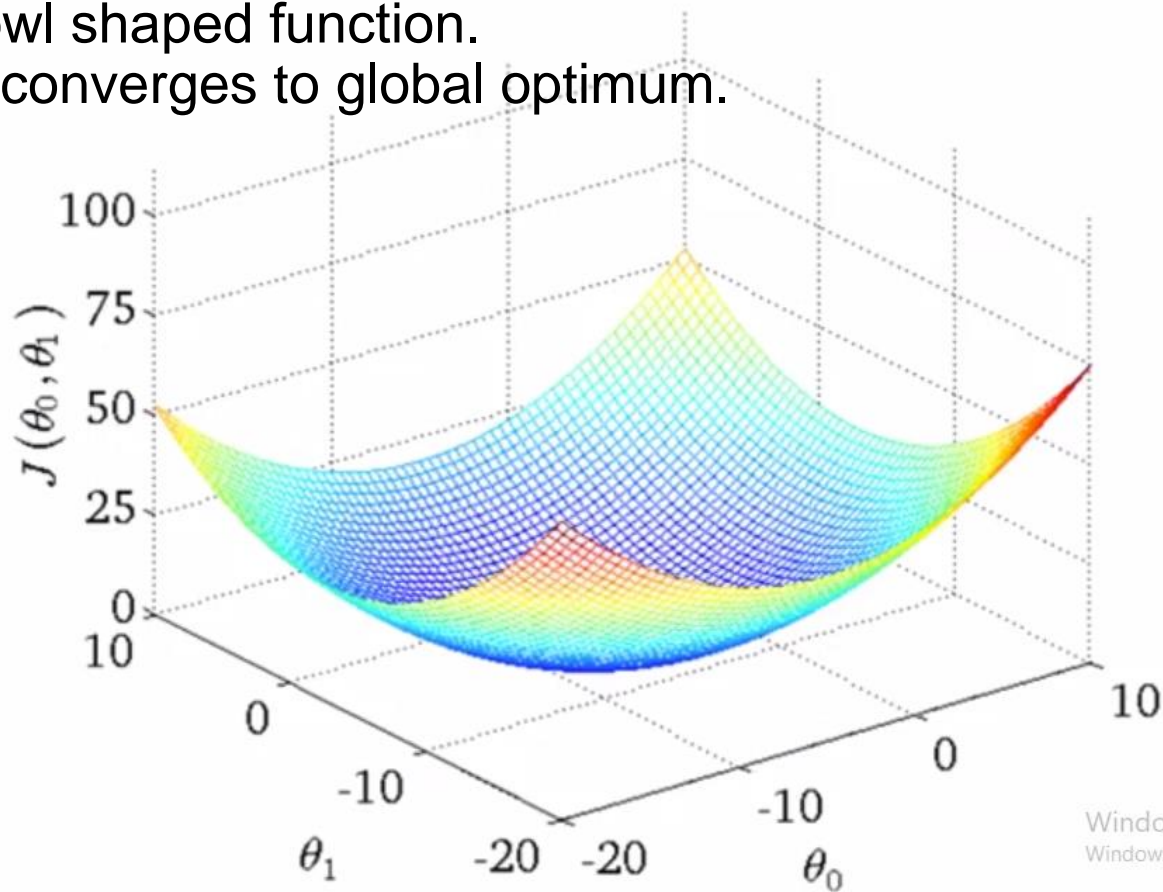
$$\text{temp1} := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)$$

$$\theta_0 := \text{temp0}$$

$$\theta_1 := \text{temp1}$$

Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.

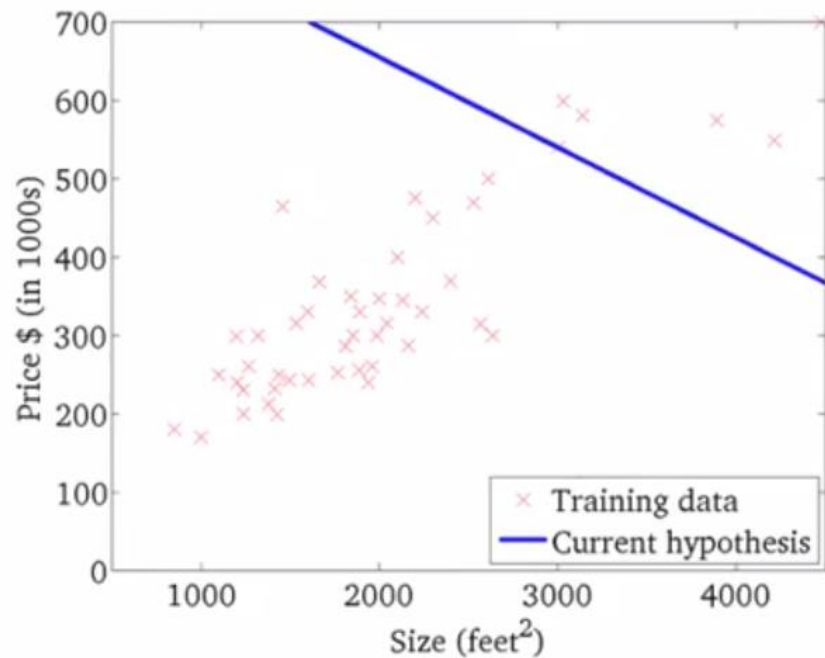
- Convex function.
- It's a bowl shaped function.
- Always converges to global optimum.



Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.

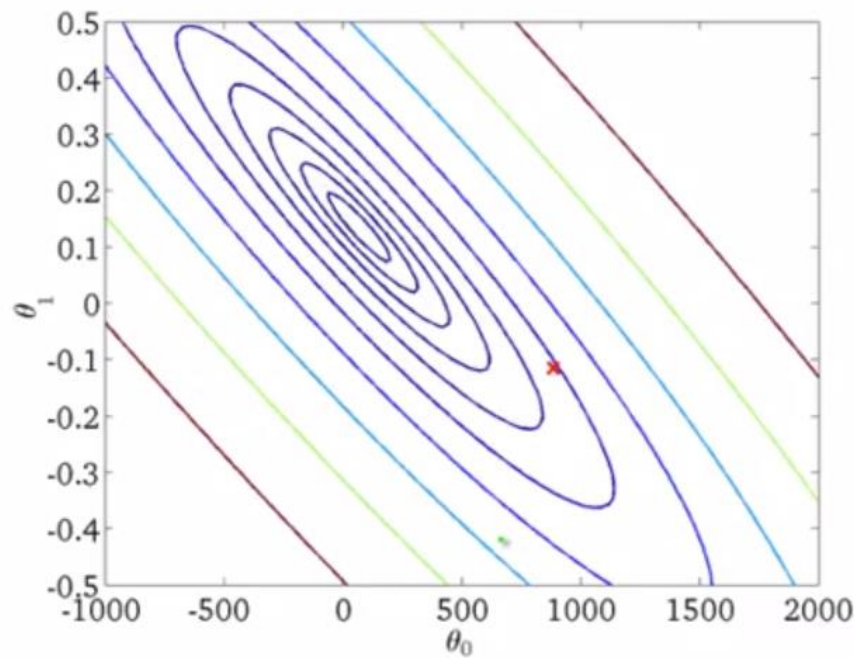
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$ , this is a function of  $x$ )



$$J(\theta_0, \theta_1)$$

(function of the parameters  $\theta_0, \theta_1$ )

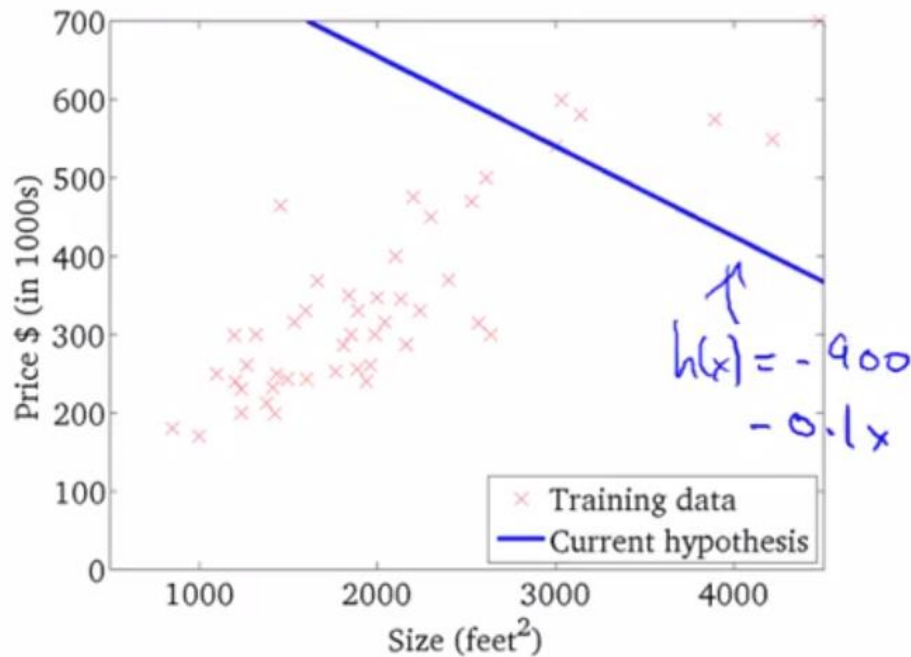


Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.



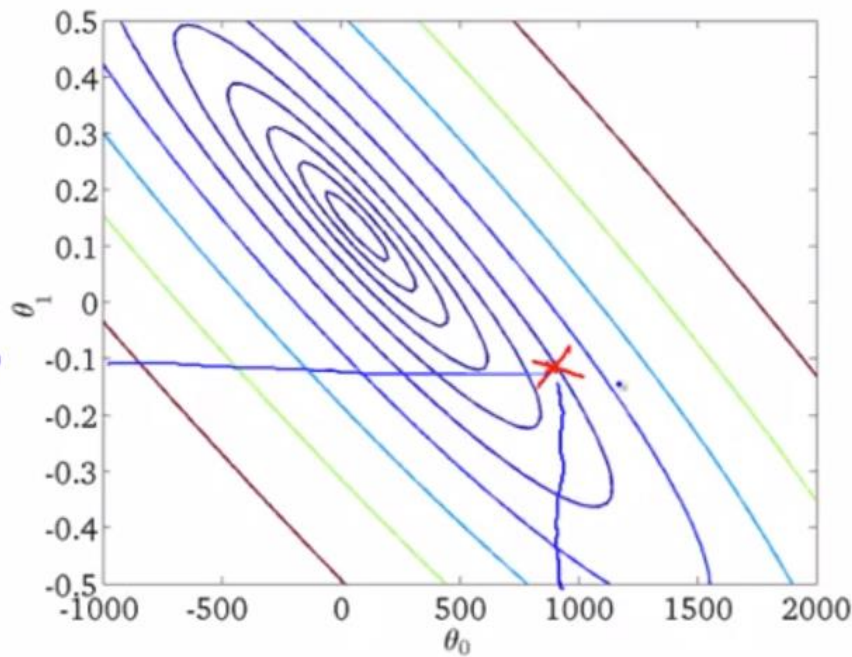
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$ , this is a function of  $x$ )



$$J(\theta_0, \theta_1)$$

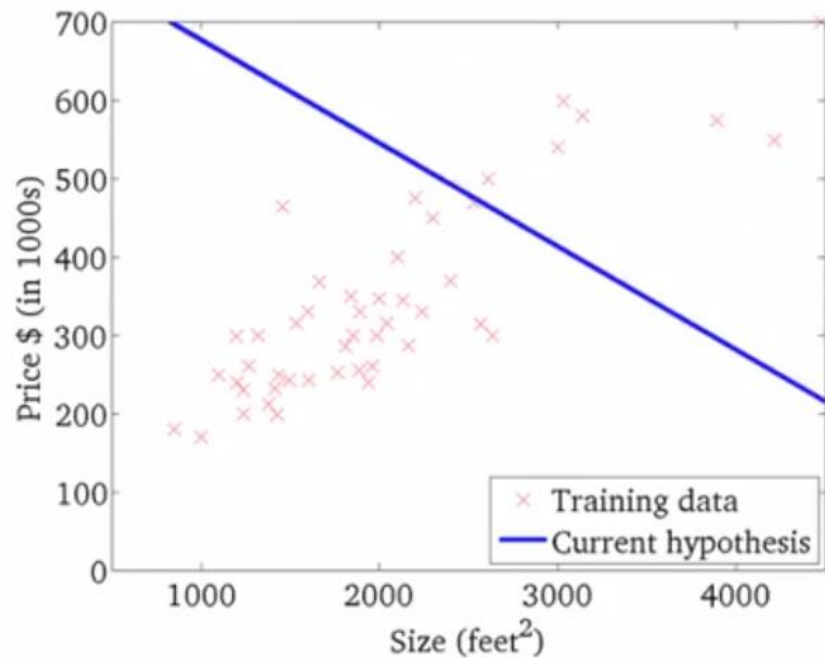
(function of the parameters  $\theta_0, \theta_1$ )



Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.

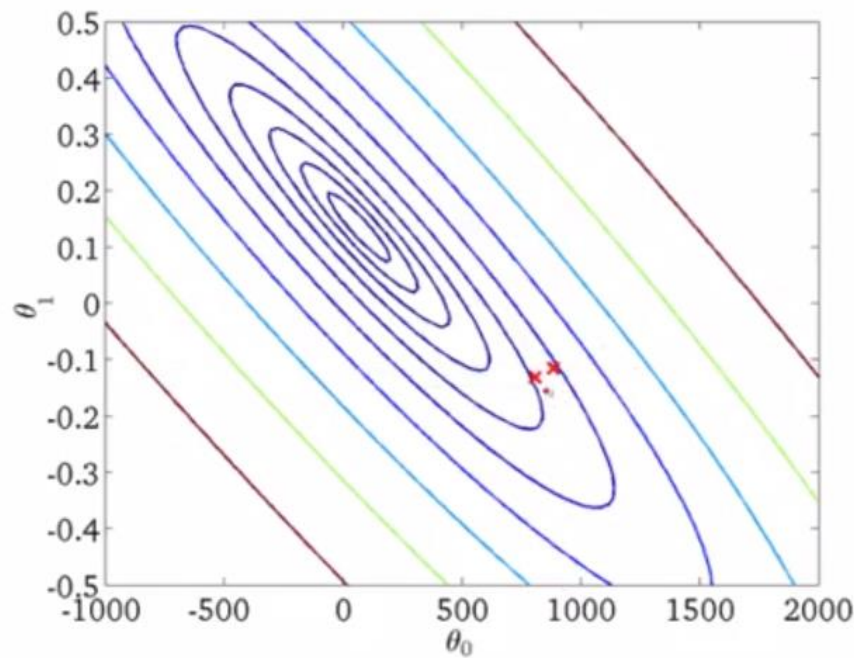
$$h_{\theta}(x)$$

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$$J(\theta_0, \theta_1)$$

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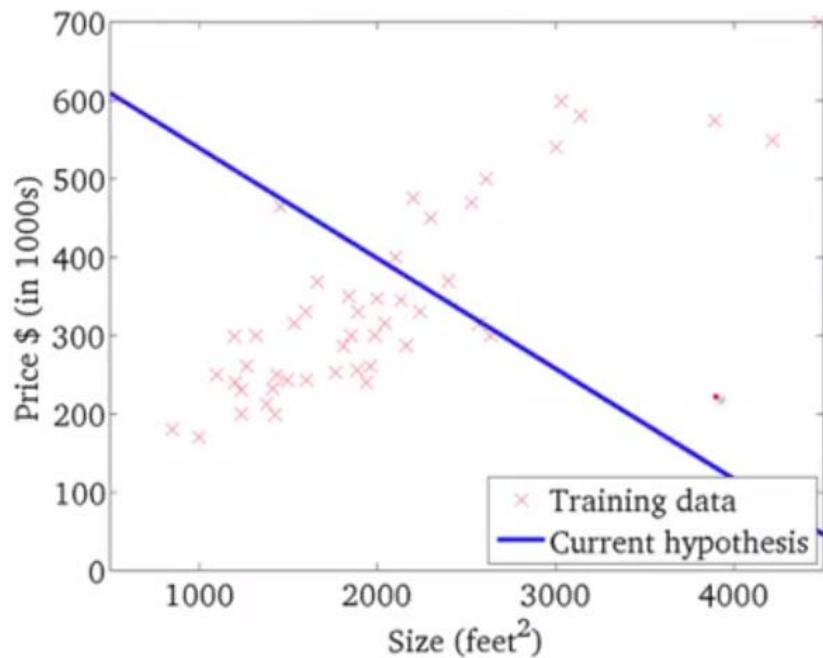


Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.



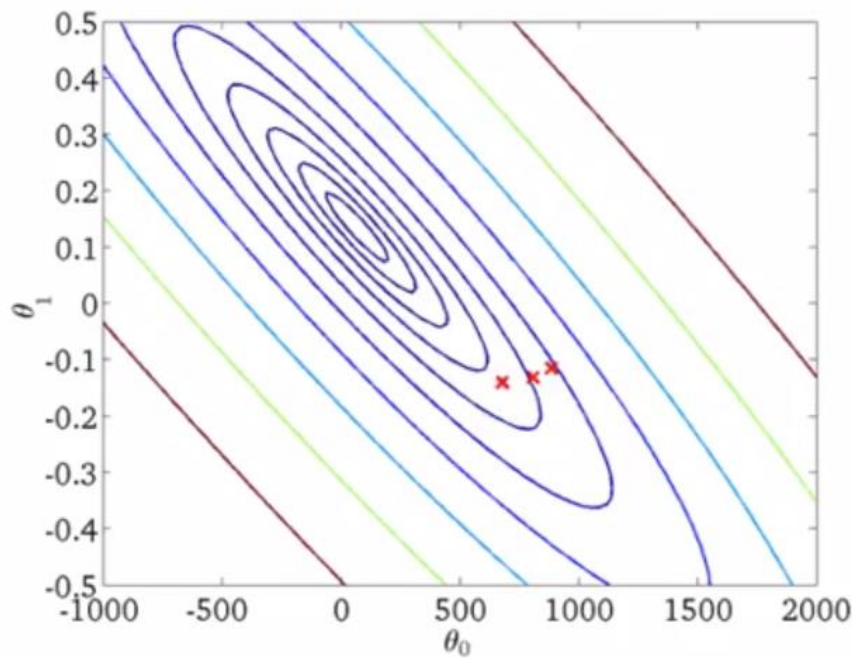
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$ , this is a function of  $x$ )



$$J(\theta_0, \theta_1)$$

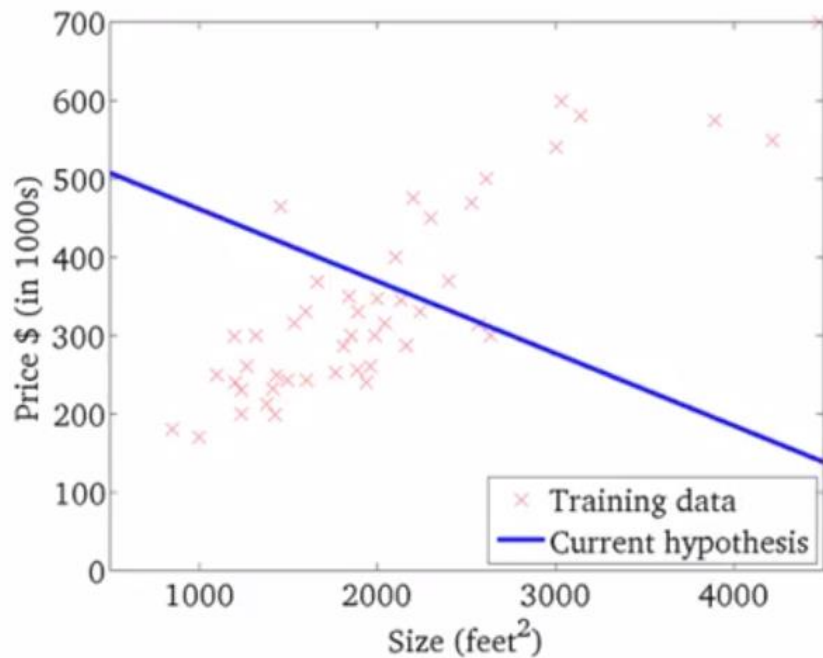
(function of the parameters  $\theta_0, \theta_1$ )



Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.

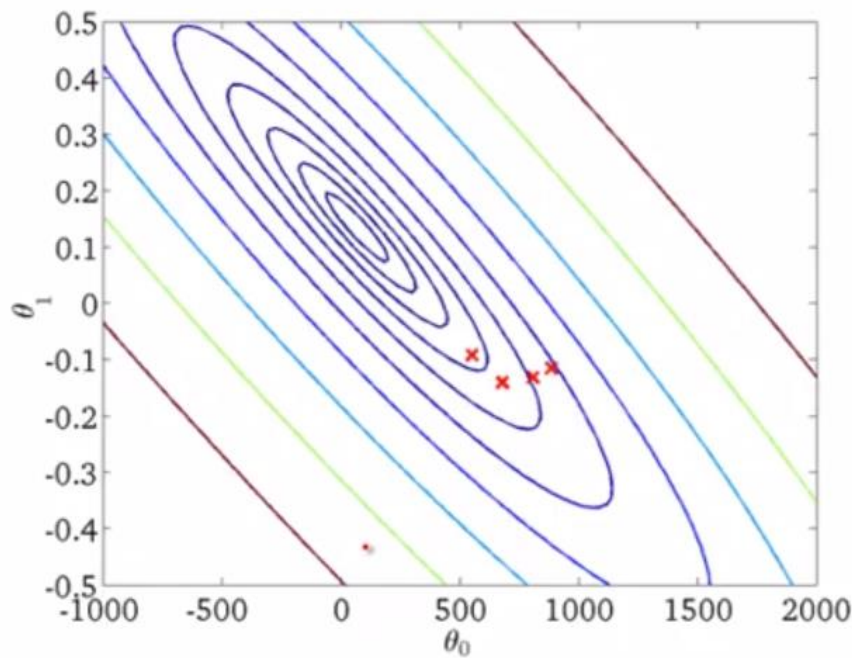
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$ , this is a function of  $x$ )



$$J(\theta_0, \theta_1)$$

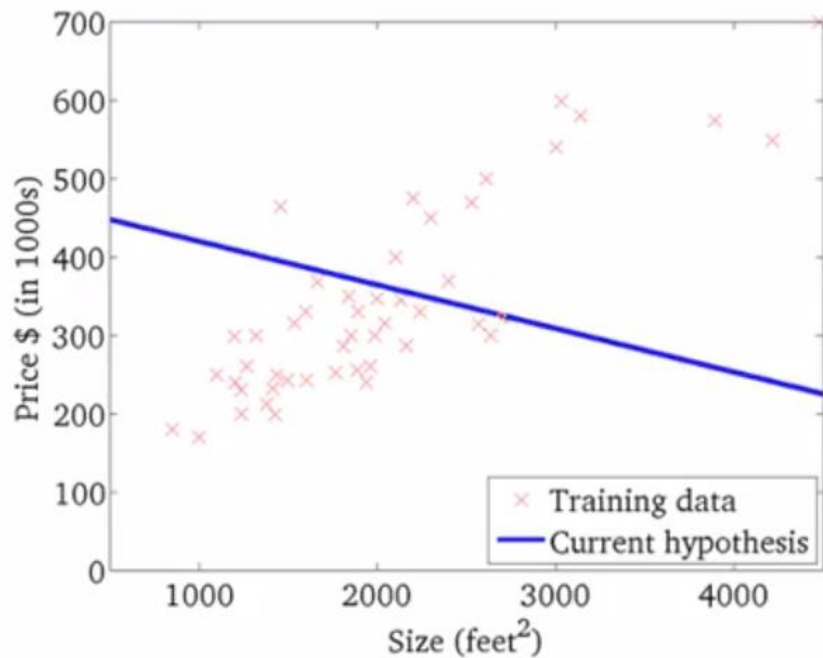
(function of the parameters  $\theta_0, \theta_1$ )



Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.

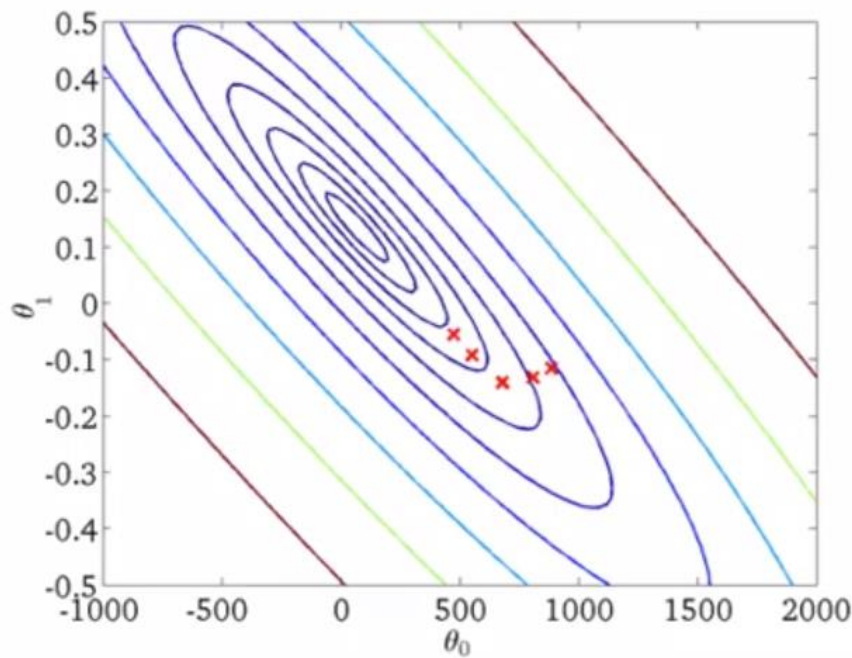
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$ , this is a function of  $x$ )



$$J(\theta_0, \theta_1)$$

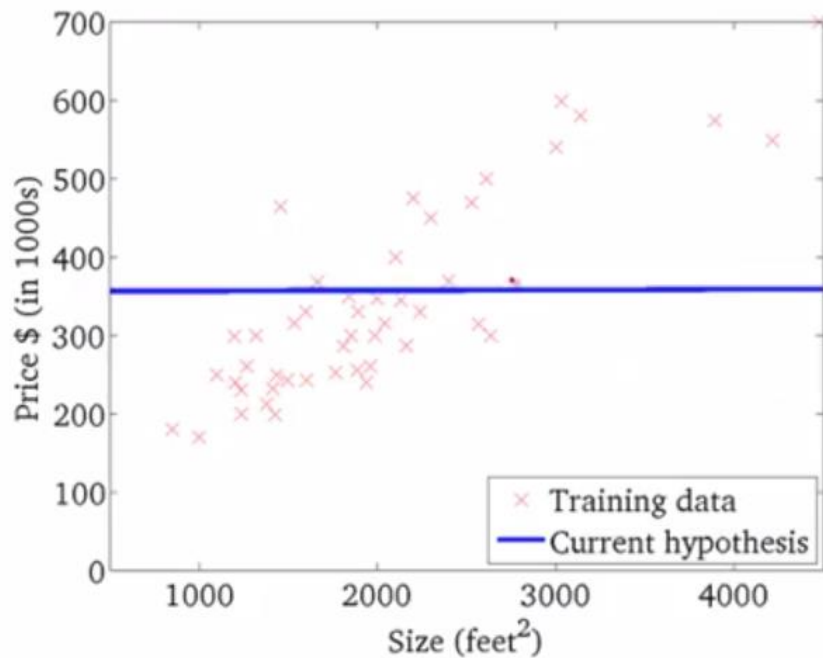
(function of the parameters  $\theta_0, \theta_1$ )



Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.

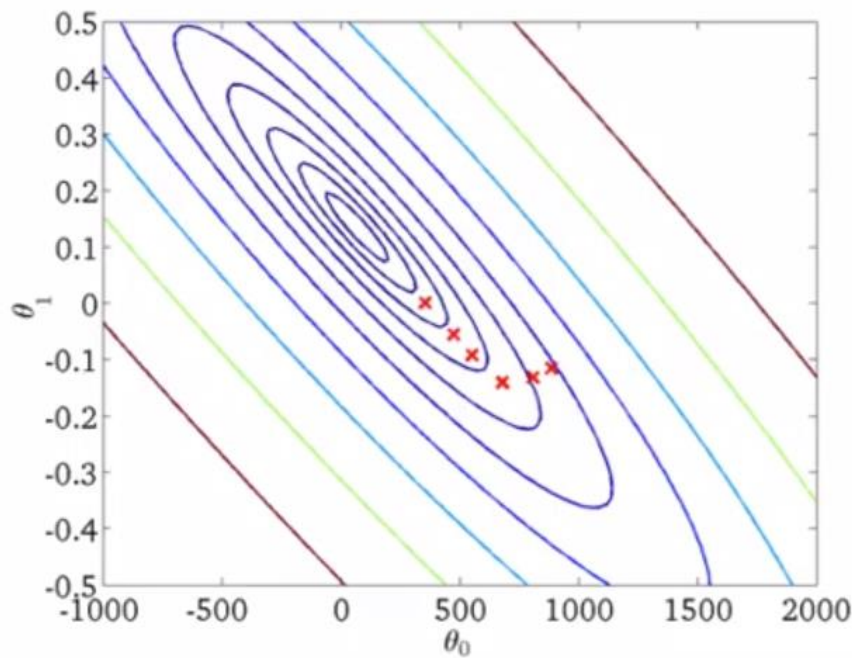
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$ , this is a function of  $x$ )



$$J(\theta_0, \theta_1)$$

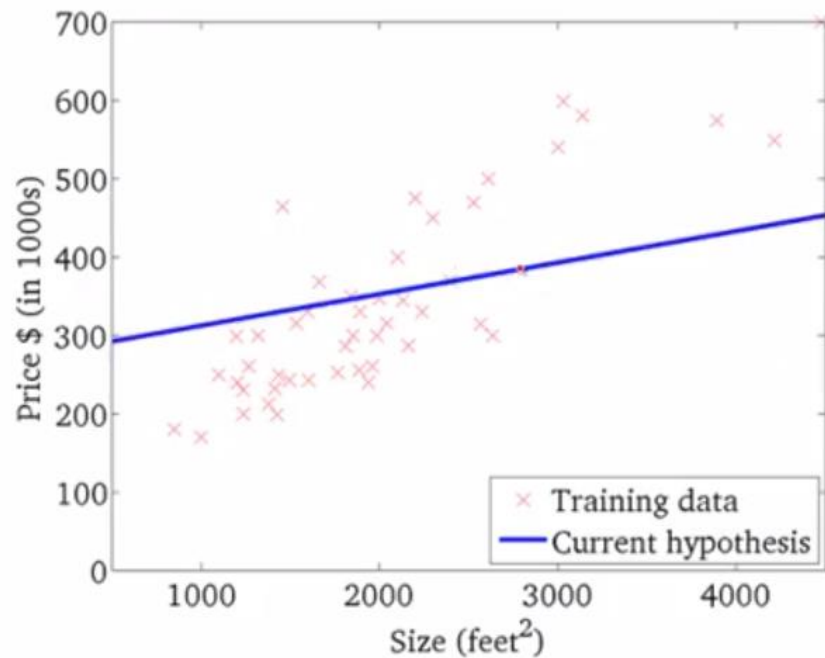
(function of the parameters  $\theta_0, \theta_1$ )



Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.

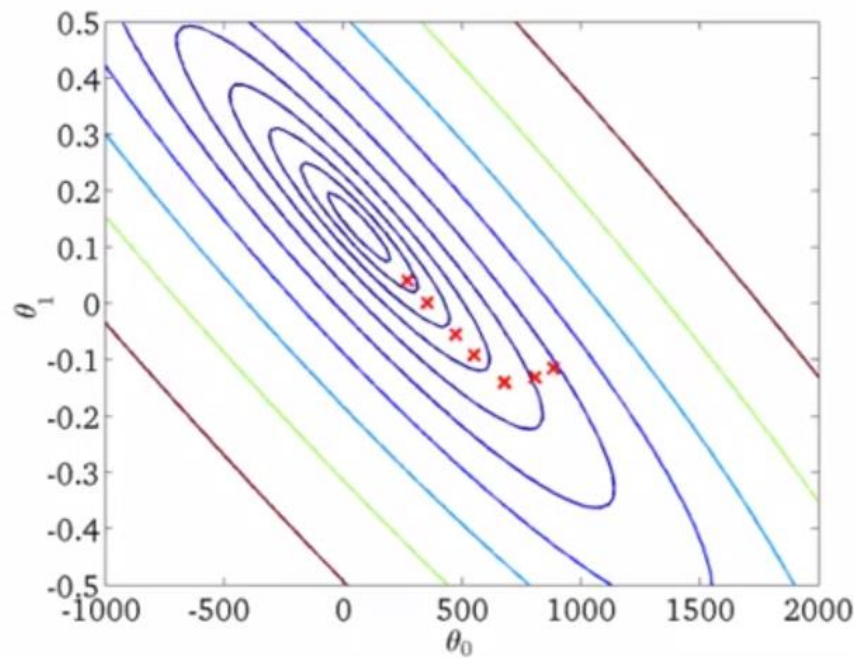
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$$J(\theta_0, \theta_1)$$

(function of the parameters  $\theta_0, \theta_1$ )



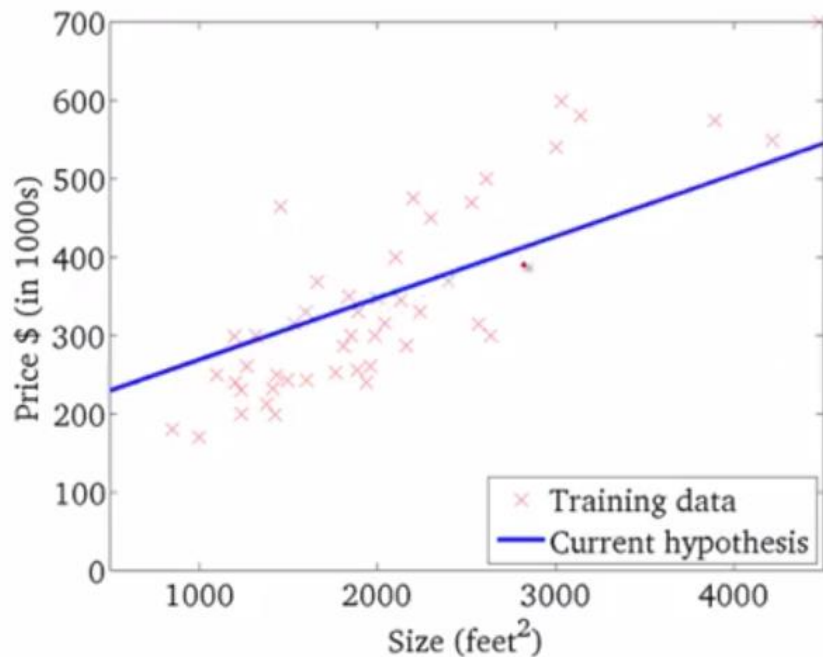
Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.

07:02



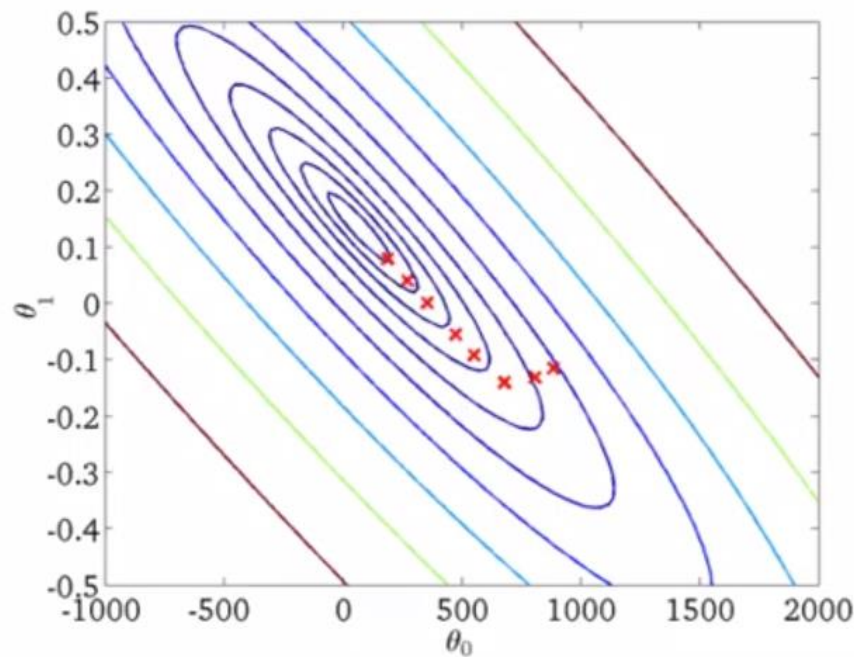
$$h_{\theta}(x)$$

(for fixed  $\theta_0, \theta_1$ , this is a function of  $x$ )



$$J(\theta_0, \theta_1)$$

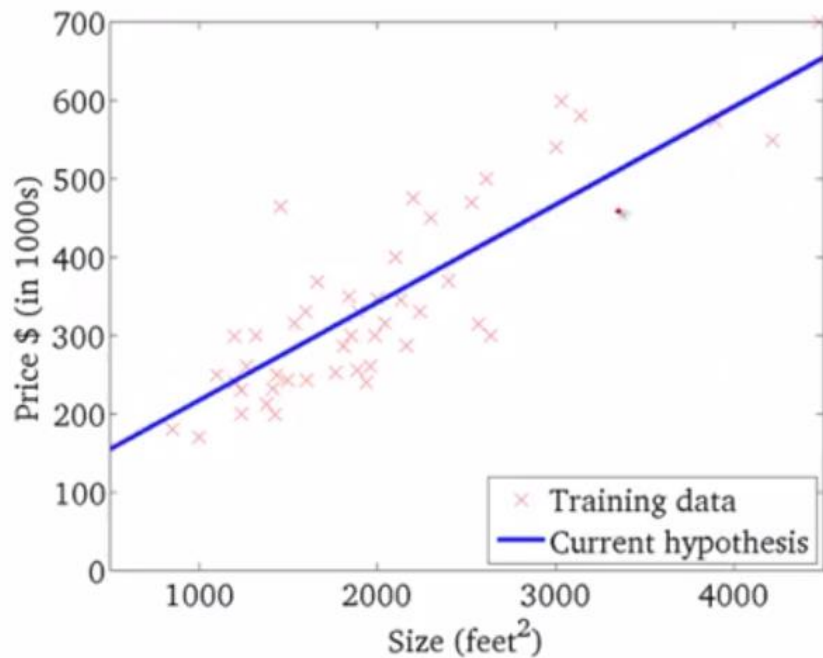
(function of the parameters  $\theta_0, \theta_1$ )



Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.

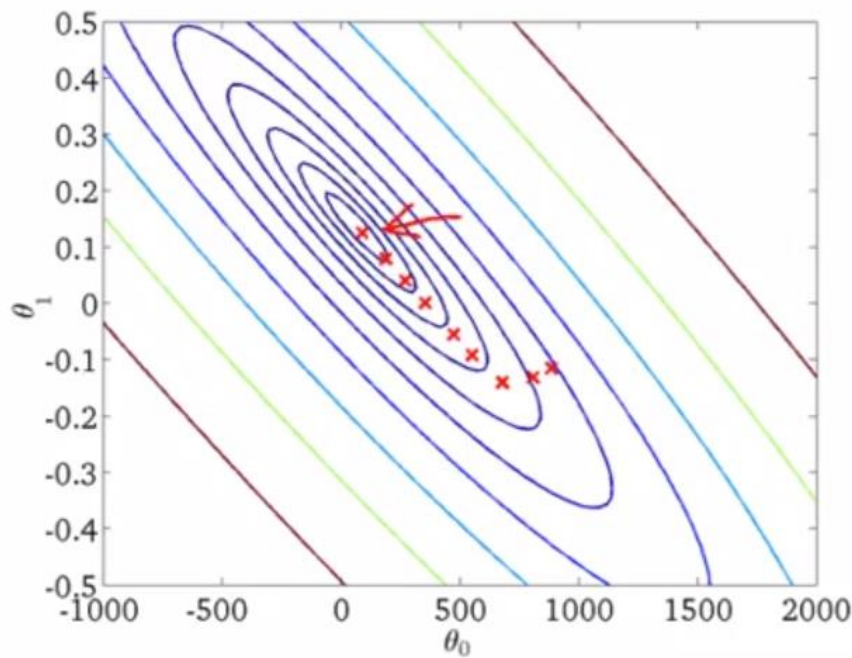
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Windows'u Etkinleştir  
Windows'u etkinleştirmek için Ayarlar'a gidin.

# The Best Fitting Line (from END2991)

- "best" line: minimum SSE.
- "least squares criterion," which says
- "minimize the **Sum of the Squared prediction Errors (SSE)** or residual **sum of squares**."
- Find  $b_0$  and  $b_1$  that minimize:

$$SSE = \sum_{i=1}^n e_i^2 = \sum_{i=1}^n (y_i - \hat{y}_i)^2 = \sum_{i=1}^n (y_i - b_0 - b_1 x_i)^2$$



# Method of Least Squares (from END2991)

- Differentiating  $SSE$  with respect to  $b_0$  and  $b_1$  and setting the resulting equations to zero we get:
- Solving these two equations will yield the computing formulas for  $b_0$  and  $b_1$  as follows:

$$\frac{\partial(SSE)}{\partial b_0} = -2 \sum_{i=1}^n (y_i - b_0 - b_1 x_i) \quad \frac{\partial(SSE)}{\partial b_1} = -2 \sum_{i=1}^n (y_i - b_0 - b_1 x_i) x_i.$$

# Method of Least Squares (from END2991)

$$nb_0 + b_1 \mathop{\mathring{\sum}}_{i=1}^n x_i = \mathop{\mathring{\sum}}_{i=1}^n y_i, \quad b_0 \mathop{\mathring{\sum}}_{i=1}^n x_i + b_1 \mathop{\mathring{\sum}}_{i=1}^n x_i^2 = \mathop{\mathring{\sum}}_{i=1}^n x_i y_i$$

$$b_1 = \frac{n \sum_{i=1}^n x_i y_i - \left( \sum_{i=1}^n x_i \right) \left( \sum_{i=1}^n y_i \right)}{n \sum_{i=1}^n x_i^2 - \left( \sum_{i=1}^n x_i \right)^2} = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=1}^n (x_i - \bar{x})^2}$$

$$b_0 = \frac{\sum_{i=1}^n y_i - b_1 \sum_{i=1}^n x_i}{n} = \bar{y} - b_1 \bar{x}.$$