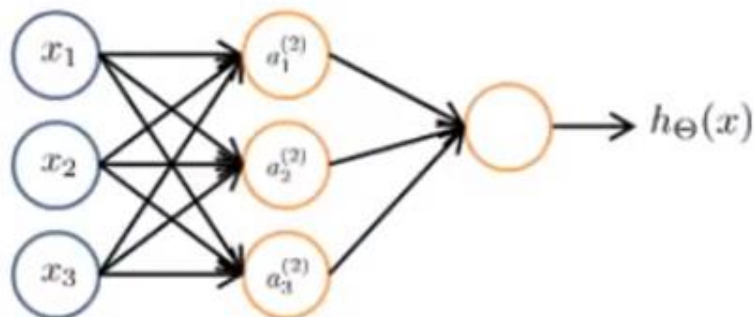


Model Representation 2

Neural Networks

Neural Networks: Representation

Forward propagation: Vectorized implementation



$$a_1^{(2)} = g(\Theta_{10}^{(1)} x_0 + \Theta_{11}^{(1)} x_1 + \Theta_{12}^{(1)} x_2 + \Theta_{13}^{(1)} x_3)$$

$$a_2^{(2)} = g(\Theta_{20}^{(1)} x_0 + \Theta_{21}^{(1)} x_1 + \Theta_{22}^{(1)} x_2 + \Theta_{23}^{(1)} x_3)$$

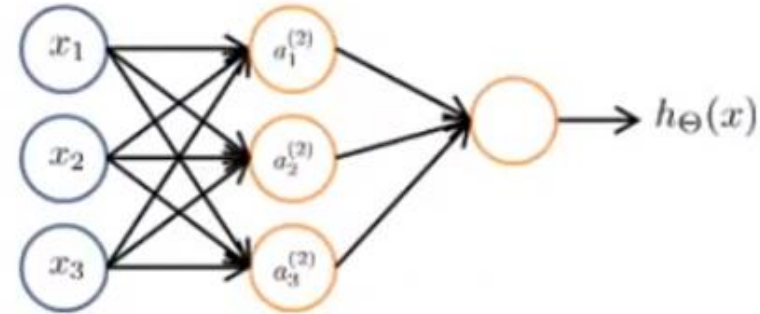
$$a_3^{(2)} = g(\Theta_{30}^{(1)} x_0 + \Theta_{31}^{(1)} x_1 + \Theta_{32}^{(1)} x_2 + \Theta_{33}^{(1)} x_3)$$

$$h_{\Theta}(x) = g(\Theta_{10}^{(2)} a_0^{(2)} + \Theta_{11}^{(2)} a_1^{(2)} + \Theta_{12}^{(2)} a_2^{(2)} + \Theta_{13}^{(2)} a_3^{(2)})$$

Windows'u Etkinleştir
Windows'u etkinleştirmek için Ayarlar'a gidin.

What are the parameters

- θ_{32}^1 :
- it is the **first** layers parameter
- it takes the output of the **second** node in the first layer
- Provides an output for the **third** node
- $a_3^{(2)} \leftarrow \dots + \theta_{32}^1 x_2 + \dots$



$$a_1^{(2)} = g(\Theta_{10}^{(1)} x_0 + \Theta_{11}^{(1)} x_1 + \Theta_{12}^{(1)} x_2 + \Theta_{13}^{(1)} x_3)$$

$$a_2^{(2)} = g(\Theta_{20}^{(1)} x_0 + \Theta_{21}^{(1)} x_1 + \Theta_{22}^{(1)} x_2 + \Theta_{23}^{(1)} x_3)$$

$$a_3^{(2)} = g(\Theta_{30}^{(1)} x_0 + \Theta_{31}^{(1)} x_1 + \Theta_{32}^{(1)} x_2 + \Theta_{33}^{(1)} x_3)$$

$$h_{\Theta}(x) = g(\Theta_{10}^{(2)} a_0^{(2)} + \Theta_{11}^{(2)} a_1^{(2)} + \Theta_{12}^{(2)} a_2^{(2)} + \Theta_{13}^{(2)} a_3^{(2)})$$

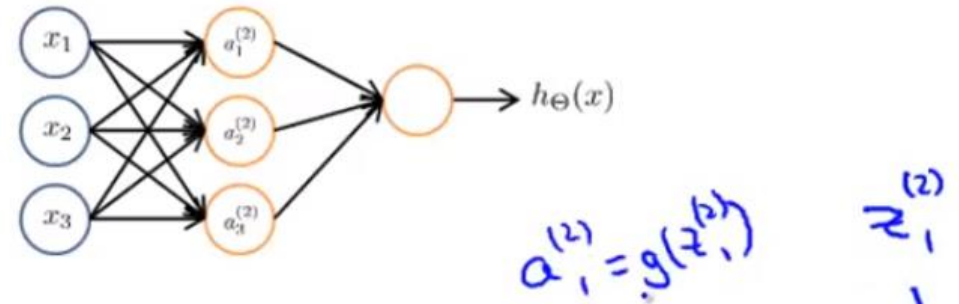
What are the parameters

- $z_1^2 = \theta_{10}^1 x_0 + \theta_{11}^1 x_1 + \theta_{12}^1 x_2 \dots$

- Hence:

- Find the total impact **z** using the weights **θ** .
- Then squeeze this impact using the sigmoid function.
- Assign it to the activation value **a**

- **We can Show this with following matrix notations**



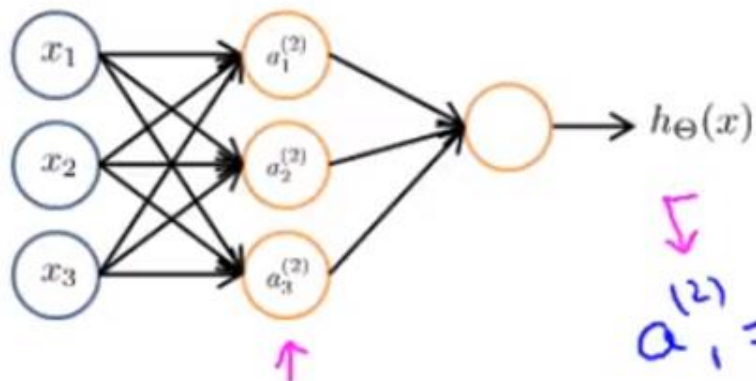
$$\rightarrow a_1^{(2)} = g(\Theta_{10}^{(1)} x_0 + \Theta_{11}^{(1)} x_1 + \Theta_{12}^{(1)} x_2 + \Theta_{13}^{(1)} x_3)$$

$$\rightarrow a_2^{(2)} = g(\Theta_{20}^{(1)} x_0 + \Theta_{21}^{(1)} x_1 + \Theta_{22}^{(1)} x_2 + \Theta_{23}^{(1)} x_3)$$

$$\rightarrow a_3^{(2)} = g(\Theta_{30}^{(1)} x_0 + \Theta_{31}^{(1)} x_1 + \Theta_{32}^{(1)} x_2 + \Theta_{33}^{(1)} x_3)$$

$$\rightarrow h_{\Theta}(x) = g(\Theta_{10}^{(2)} a_0^{(2)} + \Theta_{11}^{(2)} a_1^{(2)} + \Theta_{12}^{(2)} a_2^{(2)} + \Theta_{13}^{(2)} a_3^{(2)})$$

Forward propagation: Vectorized implementation



$$a_1^{(2)} = g(z_1^{(2)})$$

$$\begin{aligned} \rightarrow a_1^{(2)} &= g(\Theta_{10}^{(1)} x_0 + \Theta_{11}^{(1)} x_1 + \Theta_{12}^{(1)} x_2 + \Theta_{13}^{(1)} x_3) \\ \rightarrow a_2^{(2)} &= g(\Theta_{20}^{(1)} x_0 + \Theta_{21}^{(1)} x_1 + \Theta_{22}^{(1)} x_2 + \Theta_{23}^{(1)} x_3) \\ \rightarrow a_3^{(2)} &= g(\Theta_{30}^{(1)} x_0 + \Theta_{31}^{(1)} x_1 + \Theta_{32}^{(1)} x_2 + \Theta_{33}^{(1)} x_3) \\ \rightarrow h_{\Theta}(x) &= g(\Theta_{10}^{(2)} a_0^{(2)} + \Theta_{11}^{(2)} a_1^{(2)} + \Theta_{12}^{(2)} a_2^{(2)} + \Theta_{13}^{(2)} a_3^{(2)}) \end{aligned}$$

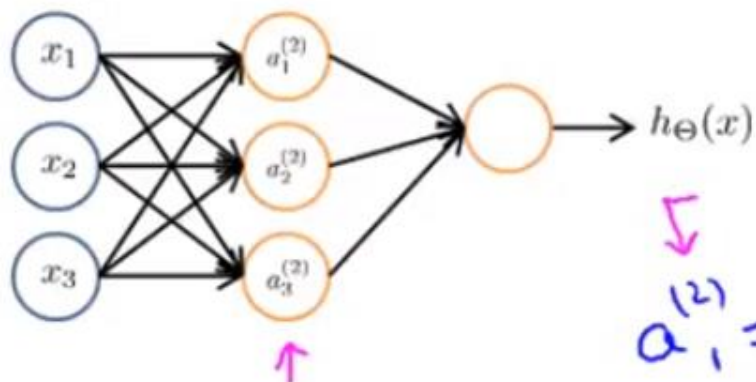
$(1) \times$

$$a_3^{(1)} = g(z_3^{(1)})$$

$$x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$z^{(2)} = \begin{bmatrix} z_1^{(2)} \\ z_2^{(2)} \\ z_3^{(2)} \end{bmatrix}$$

Forward propagation: Vectorized implementation



$$a_1^{(2)} = g(z_1^{(2)})$$

$$z_1^{(2)}$$

$$\begin{aligned} a_1^{(2)} &= g(\Theta_{10}^{(1)} x_0 + \Theta_{11}^{(1)} x_1 + \Theta_{12}^{(1)} x_2 + \Theta_{13}^{(1)} x_3) \\ a_2^{(2)} &= g(\Theta_{20}^{(1)} x_0 + \Theta_{21}^{(1)} x_1 + \Theta_{22}^{(1)} x_2 + \Theta_{23}^{(1)} x_3) \\ a_3^{(2)} &= g(\Theta_{30}^{(1)} x_0 + \Theta_{31}^{(1)} x_1 + \Theta_{32}^{(1)} x_2 + \Theta_{33}^{(1)} x_3) \end{aligned}$$

$$h_{\Theta}(x) = g(\Theta_{10}^{(2)} a_0^{(2)} + \Theta_{11}^{(2)} a_1^{(2)} + \Theta_{12}^{(2)} a_2^{(2)} + \Theta_{13}^{(2)} a_3^{(2)})$$

$$\Theta^{(1)} \times$$

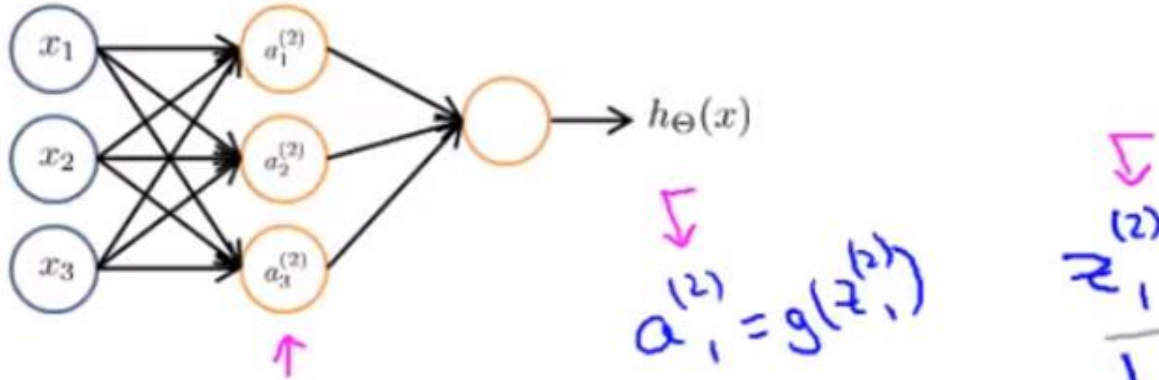
$$a_3^{(2)} = g(z_3^{(2)})$$

$$x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$z^{(2)} = \begin{bmatrix} z_1^{(2)} \\ z_2^{(2)} \\ z_3^{(2)} \end{bmatrix}$$

$$\begin{aligned} z^{(2)} &= \Theta^{(1)} x \\ a^{(2)} &= g(z^{(2)}) \end{aligned}$$

Forward propagation: Vectorized implementation



$$\begin{aligned}
 a_1^{(2)} &= g(\Theta_{10}^{(1)} x_0 + \Theta_{11}^{(1)} x_1 + \Theta_{12}^{(1)} x_2 + \Theta_{13}^{(1)} x_3) \\
 a_2^{(2)} &= g(\Theta_{20}^{(1)} x_0 + \Theta_{21}^{(1)} x_1 + \Theta_{22}^{(1)} x_2 + \Theta_{23}^{(1)} x_3) \\
 a_3^{(2)} &= g(\Theta_{30}^{(1)} x_0 + \Theta_{31}^{(1)} x_1 + \Theta_{32}^{(1)} x_2 + \Theta_{33}^{(1)} x_3) \\
 h_{\Theta}(x) &= g(\Theta_{10}^{(2)} a_0^{(2)} + \Theta_{11}^{(2)} a_1^{(2)} + \Theta_{12}^{(2)} a_2^{(2)} + \Theta_{13}^{(2)} a_3^{(2)})
 \end{aligned}$$

Handwritten notes include $a_3^{(2)} = g(z_3^{(2)})$ and $z_3^{(2)}$.

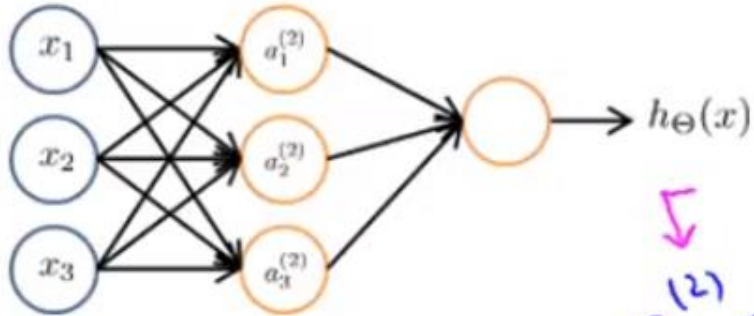
$$x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} \quad z^{(2)} = \begin{bmatrix} z_1^{(2)} \\ z_2^{(2)} \\ z_3^{(2)} \end{bmatrix}$$

$$\begin{aligned}
 z^{(2)} &= \Theta^{(1)} x \\
 a^{(2)} &= g(z^{(2)})
 \end{aligned}$$

Handwritten notes include \mathbb{R}^3 and \mathbb{R}^3 .

Here we apply the sigmoid function to each of the z values.

Forward propagation: Vectorized implementation



$$a_1^{(2)} = g(z_1^{(2)})$$

$$z_1^{(2)}$$

$$\begin{aligned} a_1^{(2)} &= g(\Theta_{10}^{(1)} x_0 + \Theta_{11}^{(1)} x_1 + \Theta_{12}^{(1)} x_2 + \Theta_{13}^{(1)} x_3) \\ a_2^{(2)} &= g(\Theta_{20}^{(1)} x_0 + \Theta_{21}^{(1)} x_1 + \Theta_{22}^{(1)} x_2 + \Theta_{23}^{(1)} x_3) \\ a_3^{(2)} &= g(\Theta_{30}^{(1)} x_0 + \Theta_{31}^{(1)} x_1 + \Theta_{32}^{(1)} x_2 + \Theta_{33}^{(1)} x_3) \end{aligned}$$

$$h_{\Theta}(x) = g(\Theta_{10}^{(2)} a_0^{(2)} + \Theta_{11}^{(2)} a_1^{(2)} + \Theta_{12}^{(2)} a_2^{(2)} + \Theta_{13}^{(2)} a_3^{(2)})$$

$$\Theta^{(1)} \times$$

$$a_3^{(1)} = g(z_3^{(1)})$$

$$x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

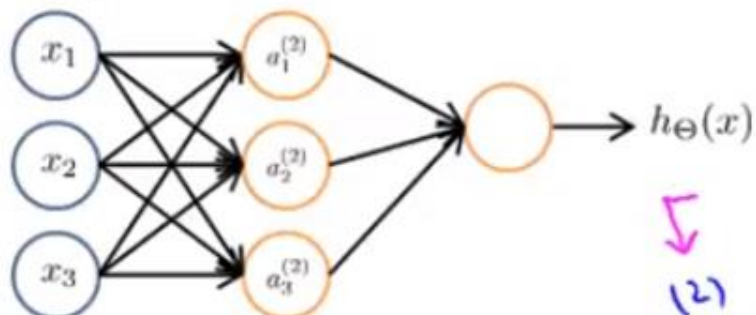
$$z^{(2)} = \begin{bmatrix} z_1^{(2)} \\ z_2^{(2)} \\ z_3^{(2)} \end{bmatrix}$$

$$z^{(2)} = \Theta^{(1)} a^{(1)}$$

$$a^{(2)} = g(z^{(2)})$$

Let $a(1) = x$ in order to have a clear representation

Forward propagation: Vectorized implementation



Handwritten notes and equations for forward propagation:

- $a^{(1)} = x$ (red arrow pointing to x_1, x_2, x_3)
- $a_1^{(2)} = g(z_1^{(2)})$ (pink arrow pointing to $a_1^{(2)}$)
- $a_2^{(2)} = g(z_2^{(2)})$ (pink arrow pointing to $a_2^{(2)}$)
- $a_3^{(2)} = g(z_3^{(2)})$ (pink arrow pointing to $a_3^{(2)}$)
- $h_{\Theta}(x) = g(\Theta_{10}^{(2)} a_0^{(2)} + \Theta_{11}^{(2)} a_1^{(2)} + \Theta_{12}^{(2)} a_2^{(2)} + \Theta_{13}^{(2)} a_3^{(2)})$ (pink arrow pointing to $a_0^{(2)}$)
- $a_0^{(2)} = g(z_0^{(2)})$ (pink arrow pointing to $a_0^{(2)}$)

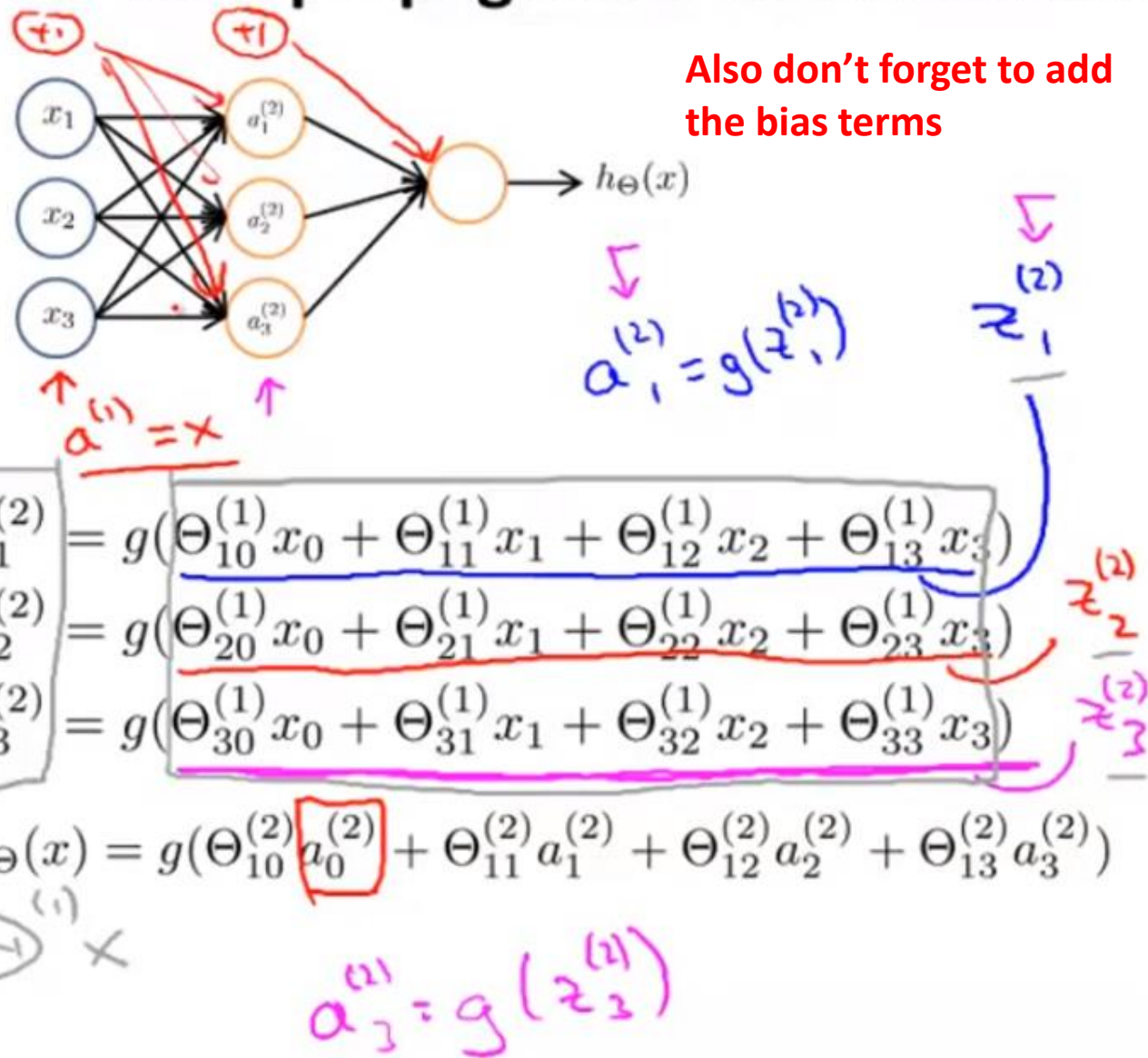
$$x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} \quad z^{(2)} = \begin{bmatrix} z_1^{(2)} \\ z_2^{(2)} \\ z_3^{(2)} \end{bmatrix}$$

$$z^{(2)} = \Theta^{(1)} a^{(1)}$$

$$a^{(2)} = g(z^{(2)})$$

Handwritten notes: \mathbb{R}^3 (red), \mathbb{R}^3 (red), $a^{(2)}$ (red), $a_1^{(2)}$ (red), $a_2^{(2)}$ (red), $a_3^{(2)}$ (red)

Forward propagation: Vectorized implementation



$$x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} \quad z^{(2)} = \begin{bmatrix} z_1^{(2)} \\ z_2^{(2)} \\ z_3^{(2)} \end{bmatrix}$$

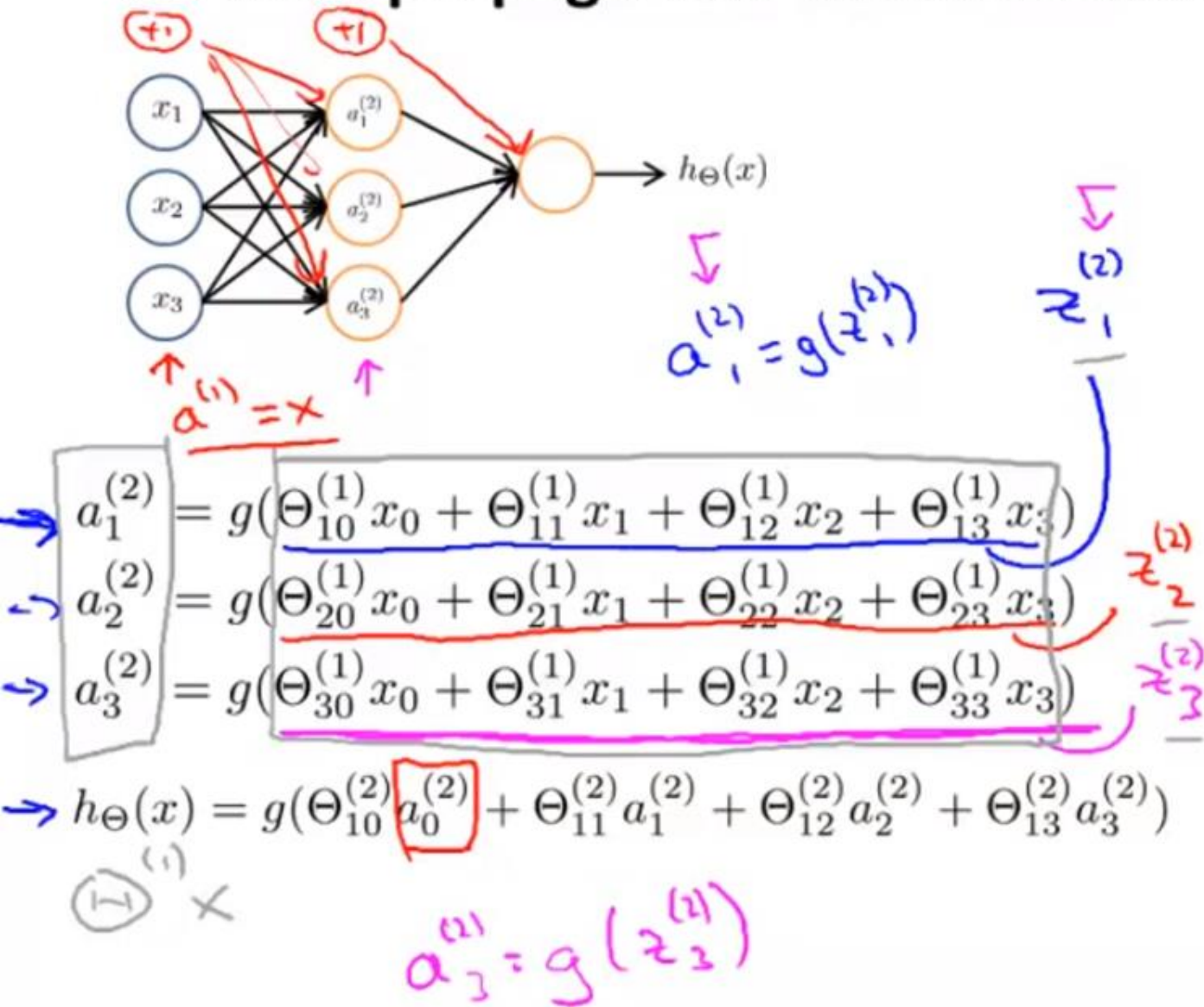
$$z^{(2)} = \Theta^{(1)} a^{(1)}$$

$$a^{(2)} = g(z^{(2)})$$

Handwritten notes include: \mathbb{R}^3 , \mathbb{R}^3 , and $a_1^{(2)}, a_2^{(2)}, a_3^{(2)}$.

Windows'u Etkinleştir
Windows'u etkinleştirmek için Ayarlar'a gidin.

Forward propagation: Vectorized implementation



$$x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} \quad z^{(2)} = \begin{bmatrix} z_1^{(2)} \\ z_2^{(2)} \\ z_3^{(2)} \end{bmatrix}$$

$$z^{(2)} = \Theta^{(1)} a^{(1)}$$

$$a^{(2)} = g(z^{(2)})$$

Handwritten notes: \mathbb{R}^3 (red), $a^{(2)} \in \mathbb{R}^4$ (red), $a_1^{(2)}, a_2^{(2)}, a_3^{(2)}$ (red).

Add $a_0^{(2)} = 1$.

$$z^{(3)} = \Theta^{(2)} a^{(2)}$$

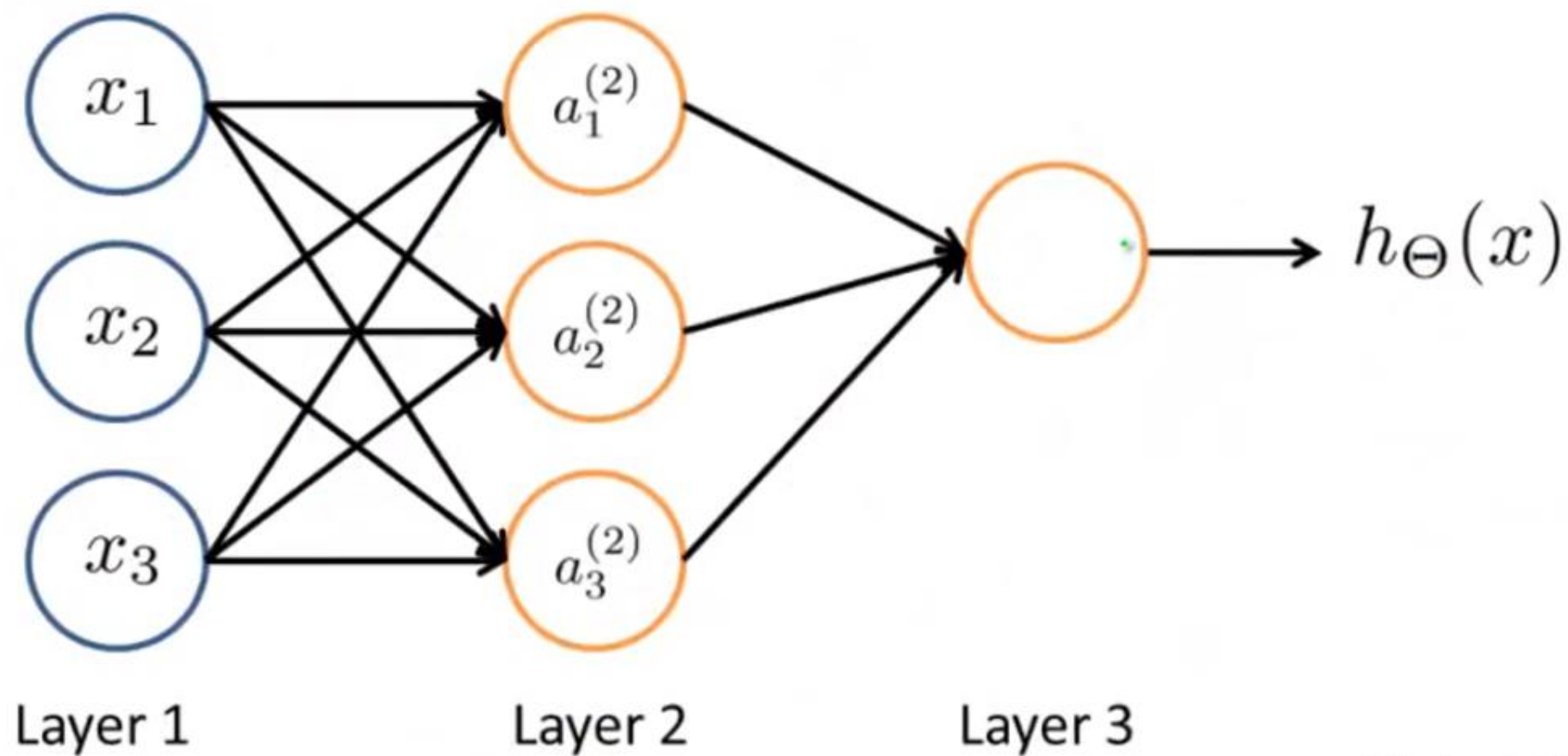
$$h_{\Theta}(x) = a^{(3)} = g(z^{(3)})$$

Windows'u Etkinleştir
Windows'u etkinleştirmek için Ayarlar'a gidin.

So what do we have?

- So again, we use the weights over **a**'s to find their weighted sums **z**'s
 - $z_1^2 = \theta_{10}^1 a_0^{(1)} + \theta_{11}^1 a_1^{(1)} + \theta_{12}^1 a_2^{(1)} \dots$
 - $z = \theta^{(1)} a^{(1)}$
- Then apply sigmoid function to find **a**'s of that particular node:
 - $a^{(3)} = g(z^{(3)})$

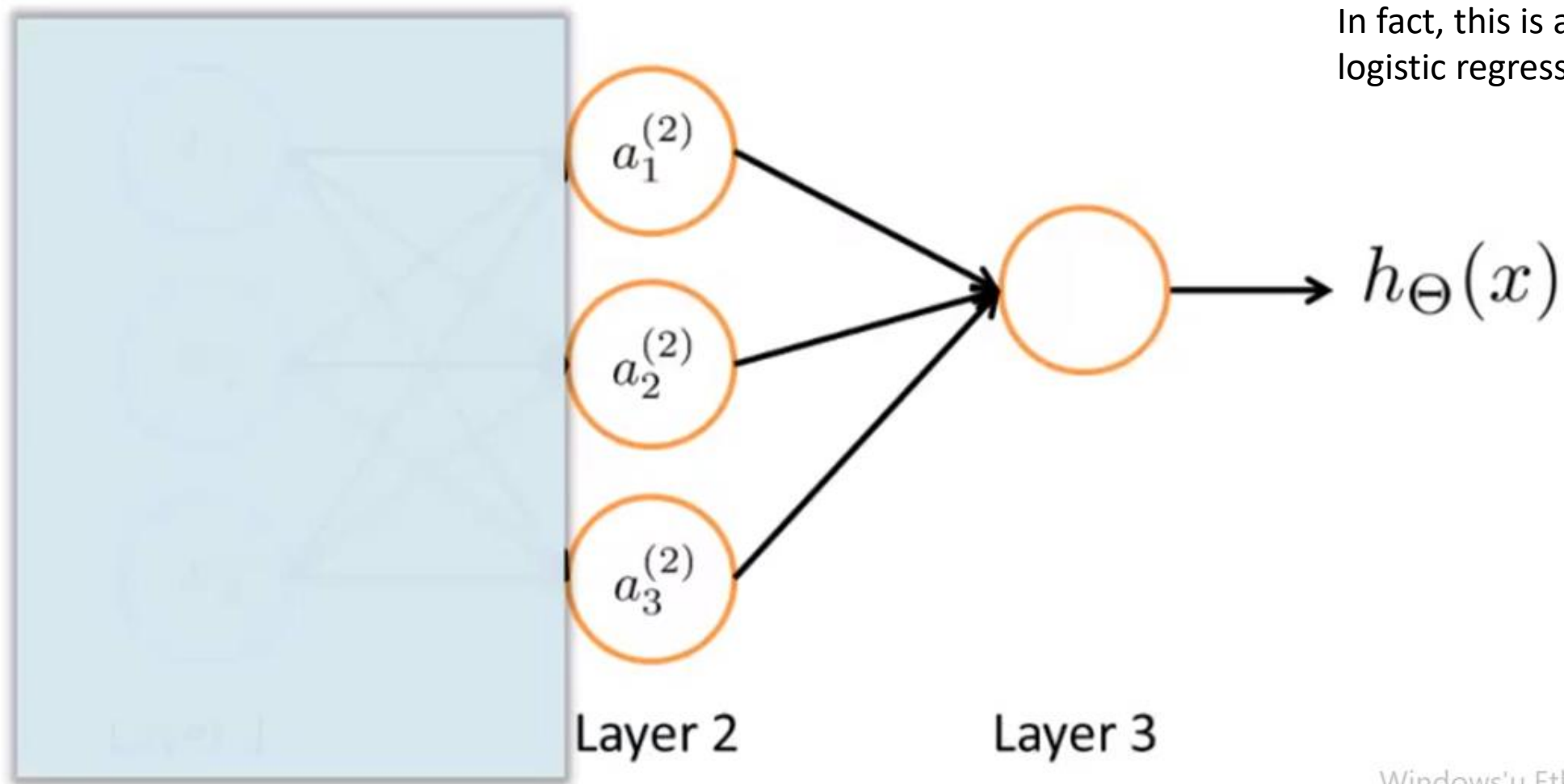
Neural Network learning its own features



Windows'u Etkinleştir
Windows'u etkinleştirmek için Ayarlar'a gidin.

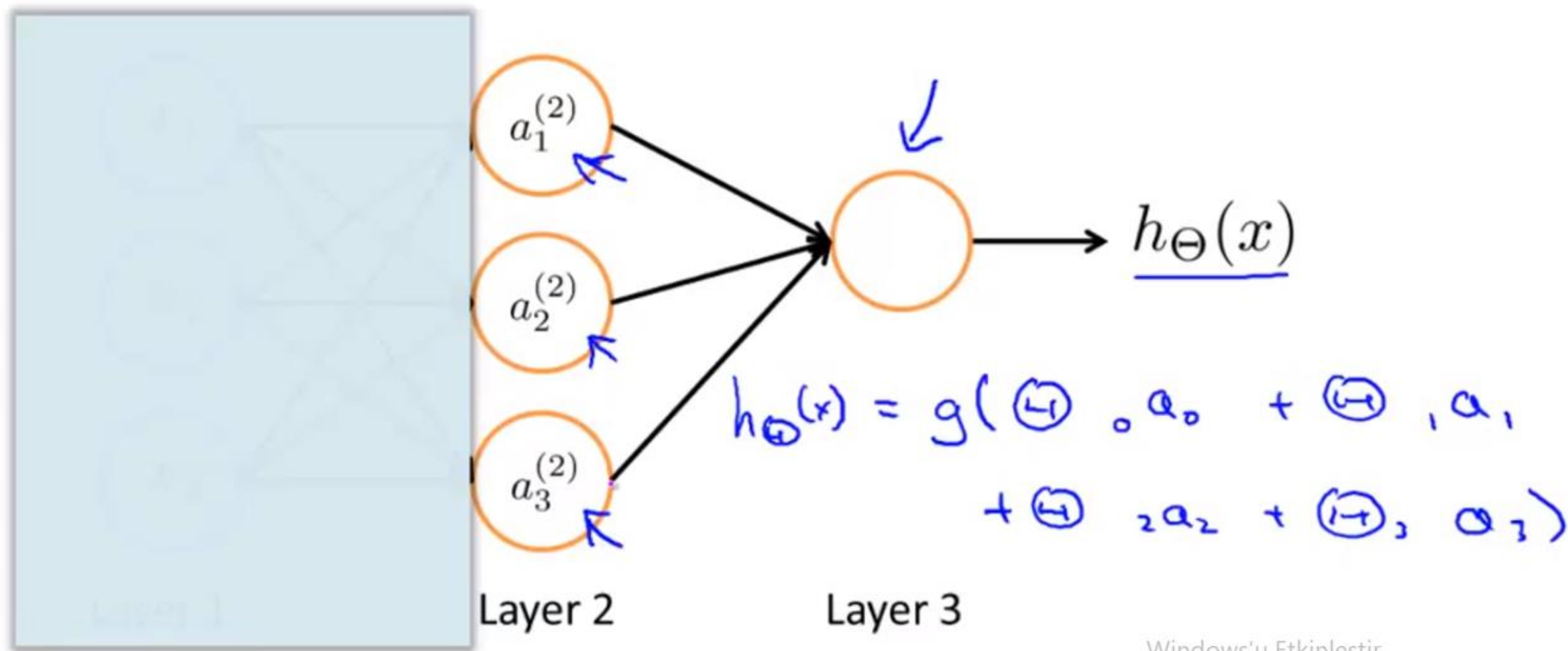
Neural Network learning its own features

In fact, this is a
logistic regression!



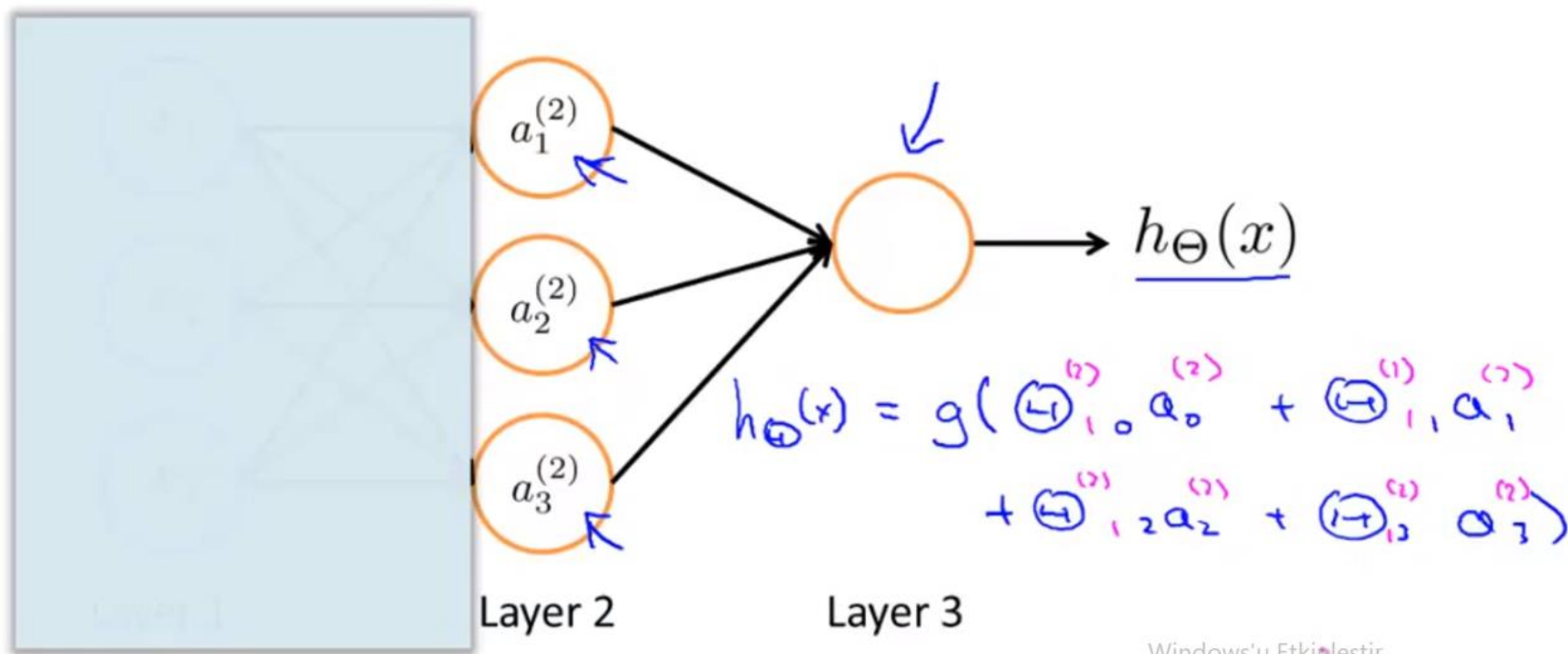
Windows'u Etkinleştir
Windows'u etkinleştirmek için Ayarlar'a gidin.

Neural Network learning its own features



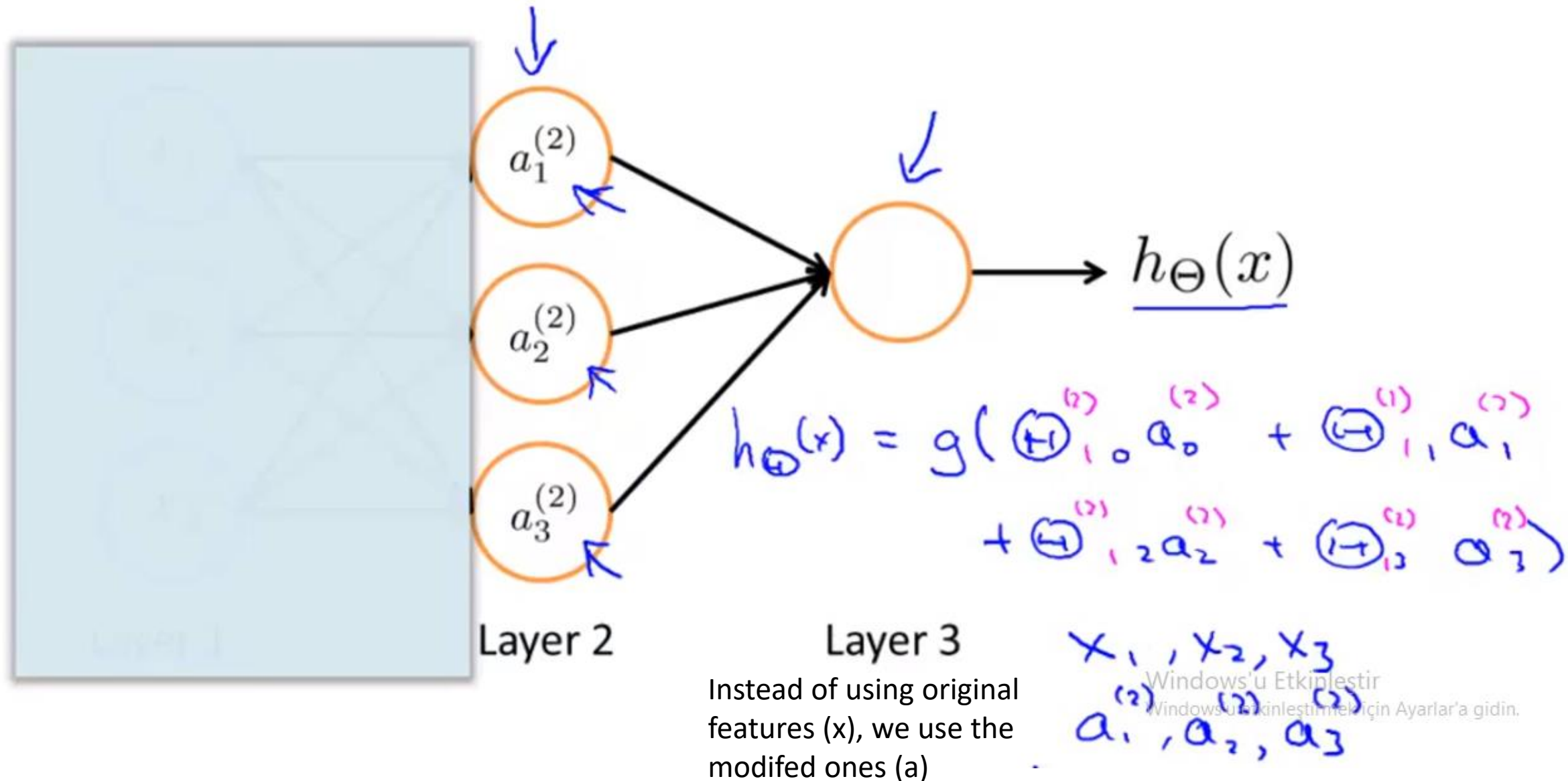
Windows'u Etkinleştir
Windows'u etkinleştirmek için Ayarlar'a gidin.

Neural Network learning its own features

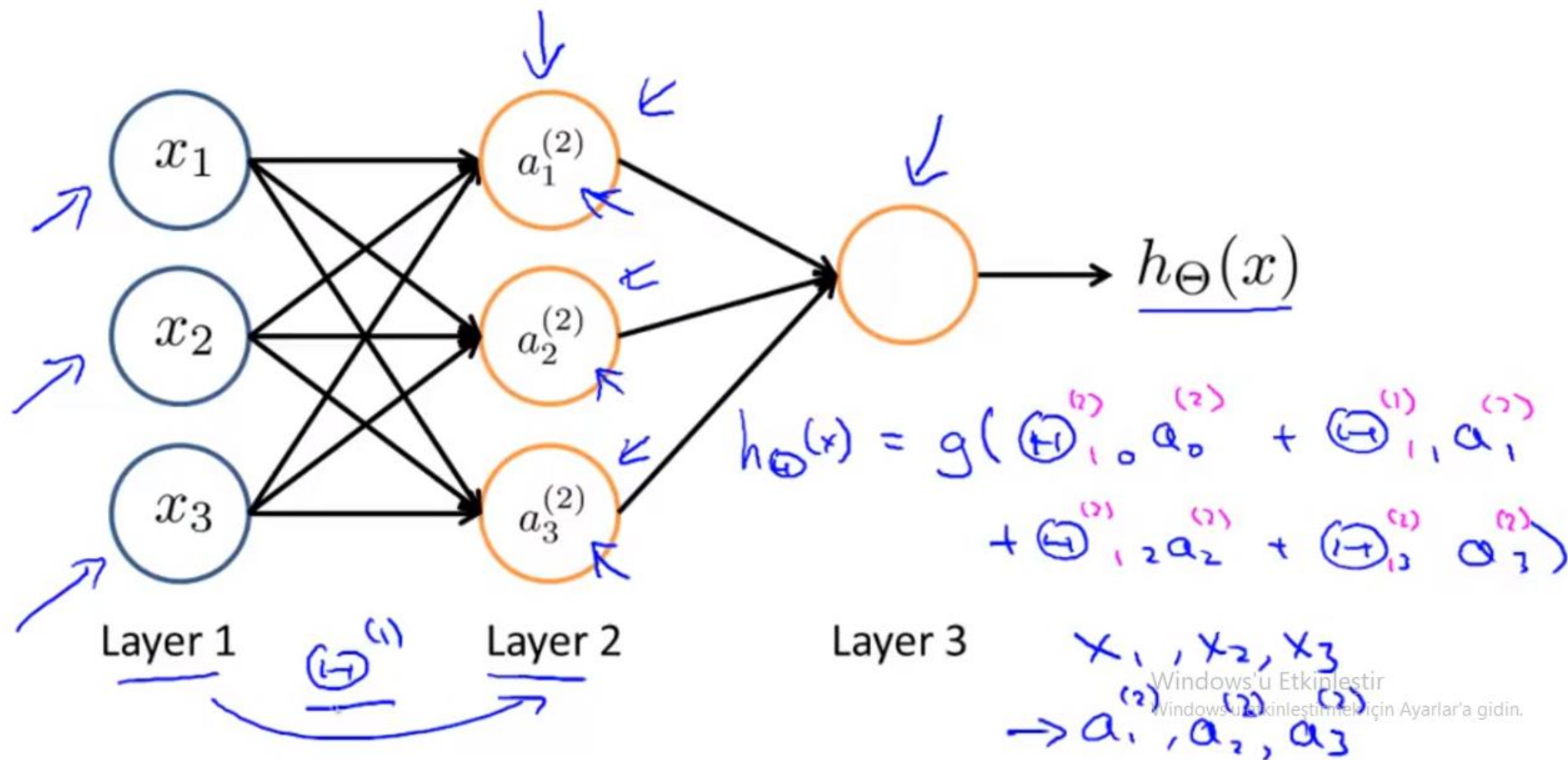


Windows'u Etkinleştir
Windows'u etkinleştirmek için Ayarlar'a gidin.

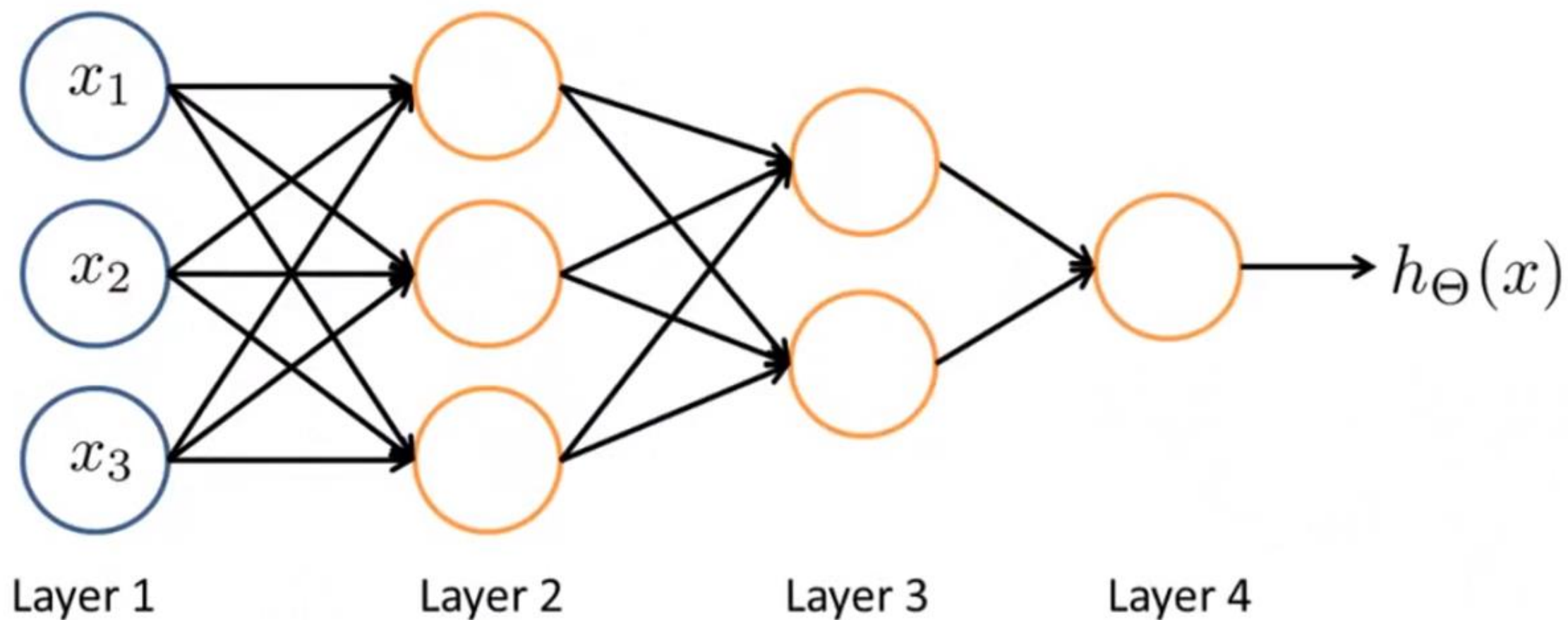
Neural Network learning its own features



Neural Network learning its own features

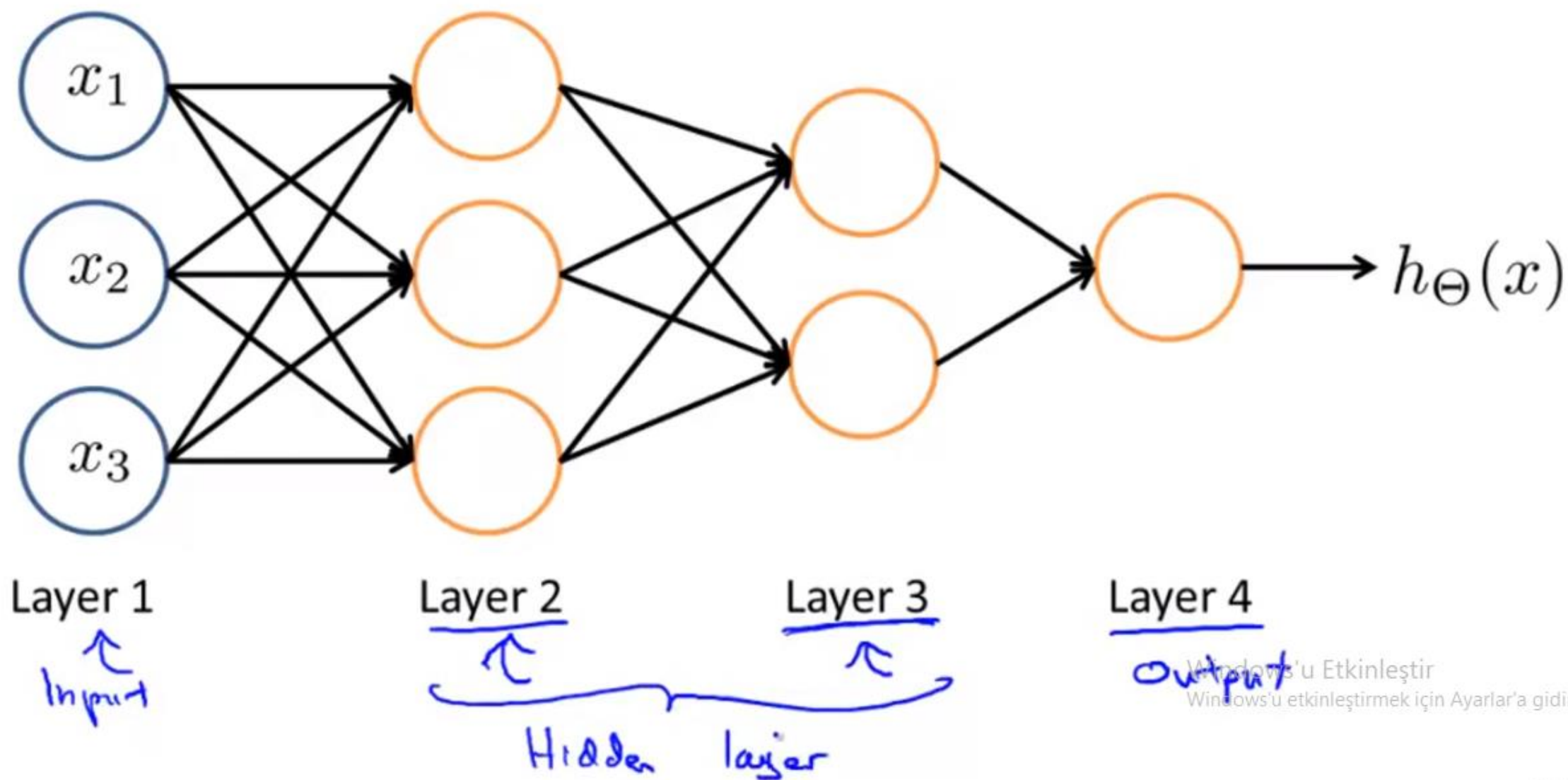


Other network architectures



Windows'u Etkinleştir
Windows'u etkinleştirmek için Ayarlar'a gidin.

Other network architectures



Exercise

Let $a^{(1)} = x \in \mathbb{R}^{n+1}$ denote the input (with $a_0^{(1)} = 1$).

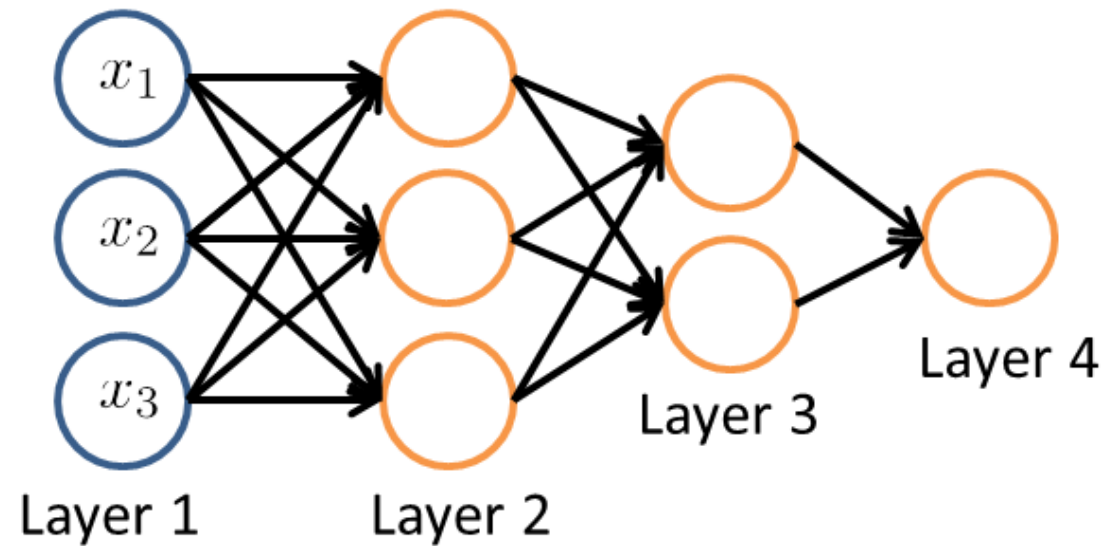
How would you compute $a^{(2)}$?

$$a^{(2)} = \Theta^{(1)} a^{(1)}$$

$$z^{(2)} = \Theta^{(2)} a^{(1)}; a^{(2)} = g(z^{(2)})$$

$$z^{(2)} = \Theta^{(1)} a^{(1)}; a^{(2)} = g(z^{(2)})$$

$$z^{(2)} = \Theta^{(2)} g(a^{(1)}); a^{(2)} = g(z^{(2)})$$



Summary

- Brief summary
- Calculate the weighted sum of the outputs of the nodes

$$z^{(j)} = \Theta^{(j-1)} a^{(j-1)}$$

- This output enters to a node where the node squeezes it between 0 and 1 using the sigmoid function to generate its own output:

$$a^{(j)} = g(z^{(j)})$$