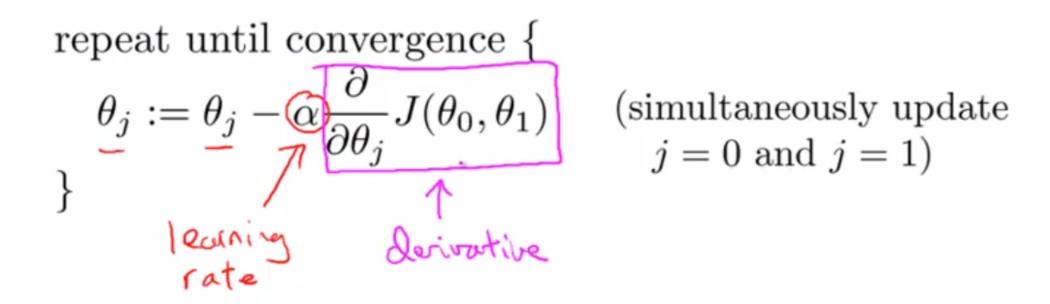
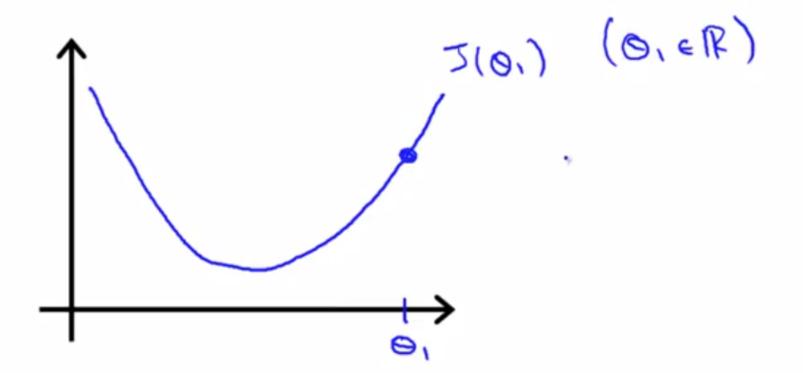
GRADIENT DESCENT INTUITION

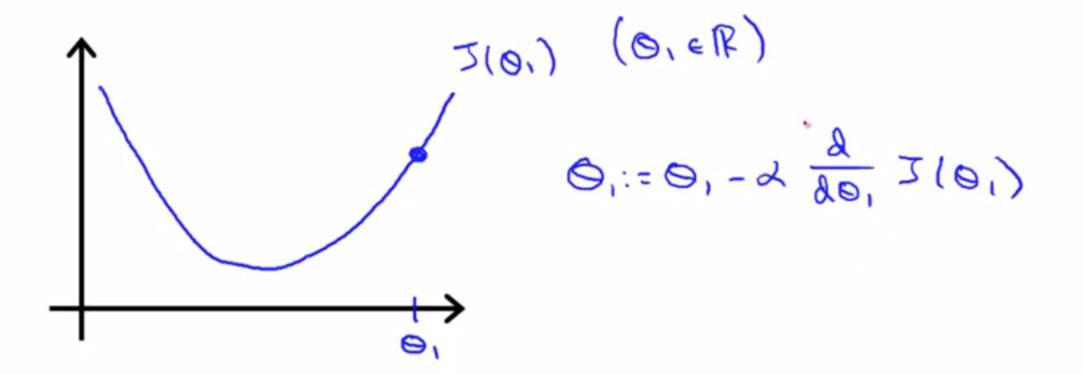
Parameter Learning

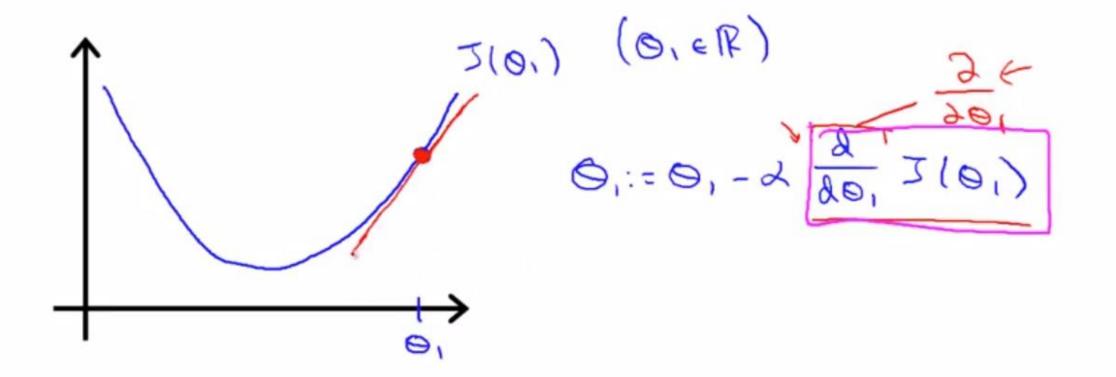
Gradient descent algorithm

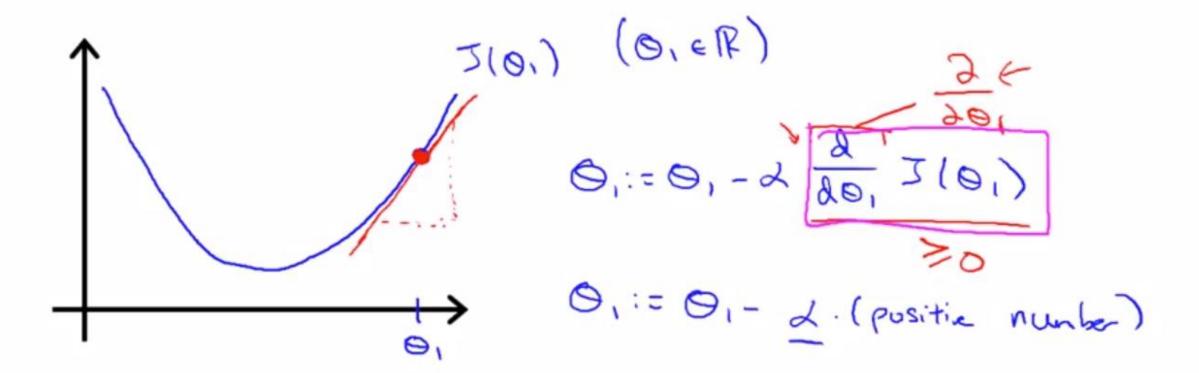




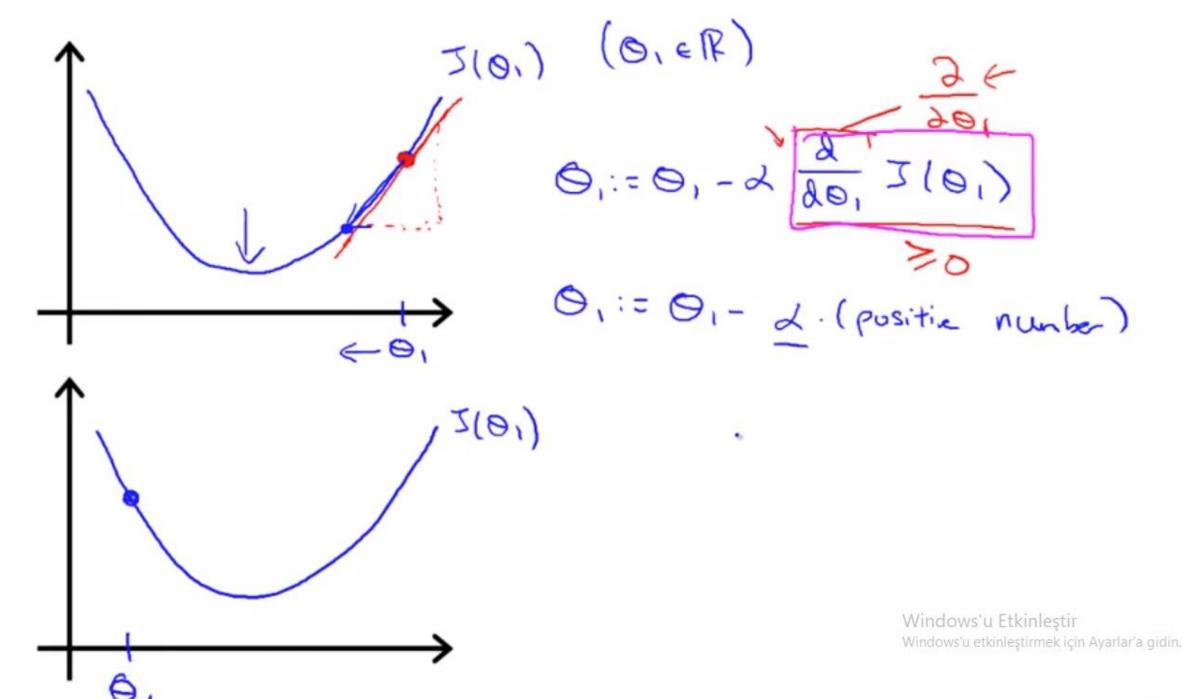
Windows'u Etkinleştir Windows'u etkinleştirmek için Ayarlar'a gidin.

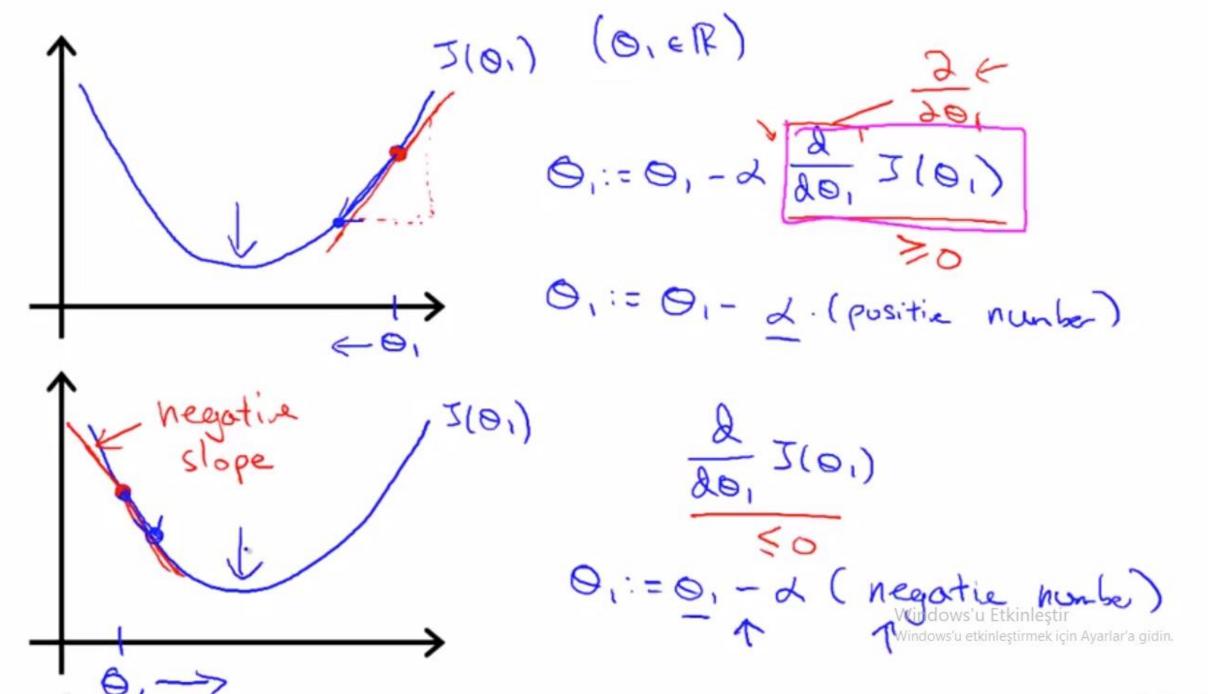






Windows'u Etkinleştir Windows'u etkinleştirmek için Ayarlar'a gidin.

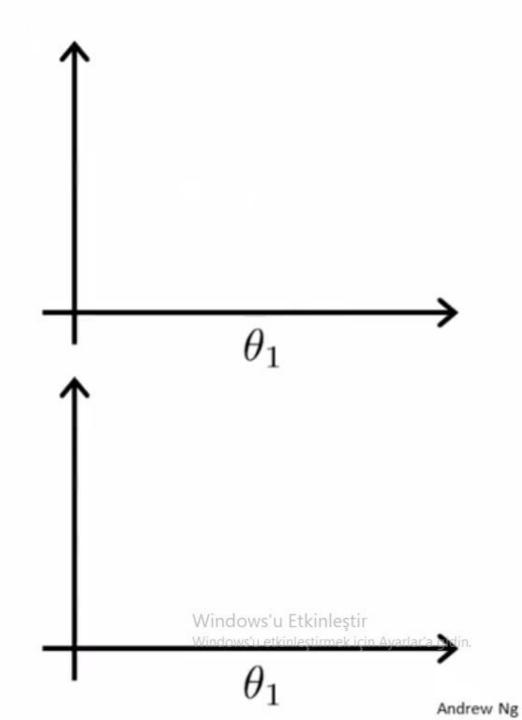




$$\theta_1 := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_1)$$

If α is too small, gradient descent can be slow.

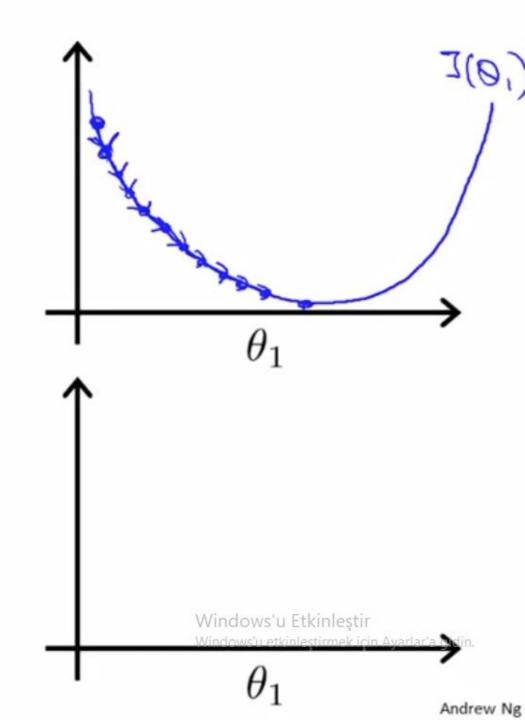
If α is too large, gradient descent can overshoot the minimum. It may fail to converge, or even diverge.



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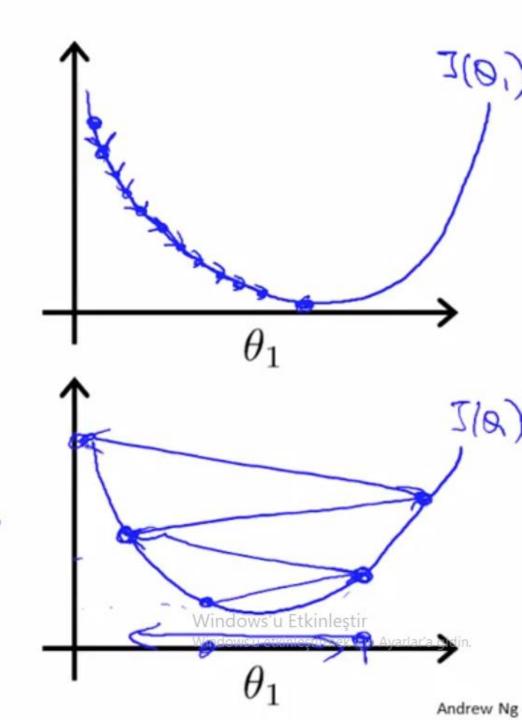
If α is too large, gradient descent can overshoot the minimum. It may fail to converge, or even diverge.



$$\theta_1 := \theta_1 - \frac{\partial}{\partial \theta_1} J(\theta_1)$$

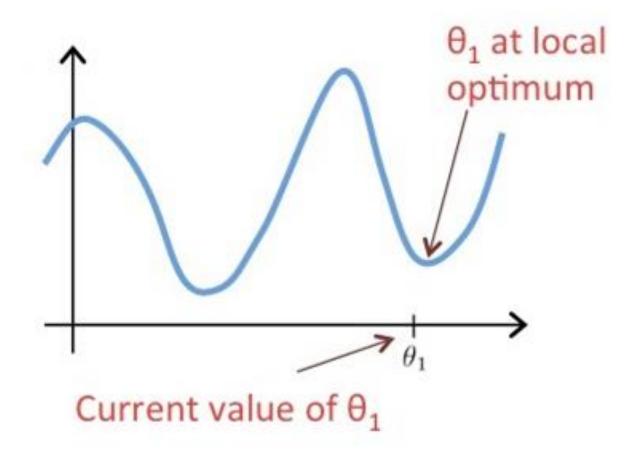
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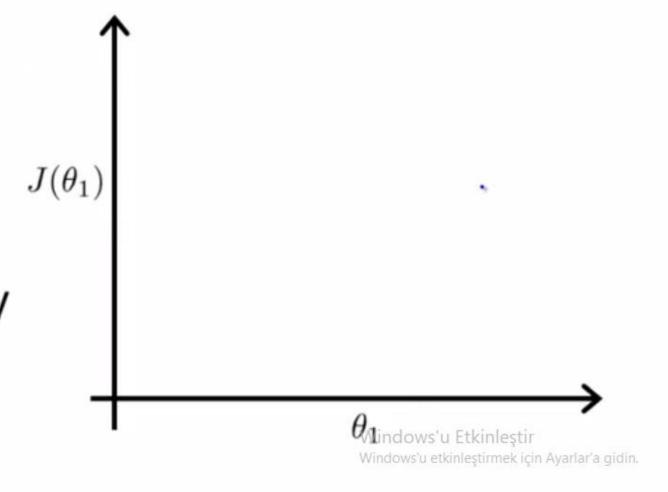


Suppose $heta_1$ is at a local optimum of $J(heta_1)$, such as shown in the figure.

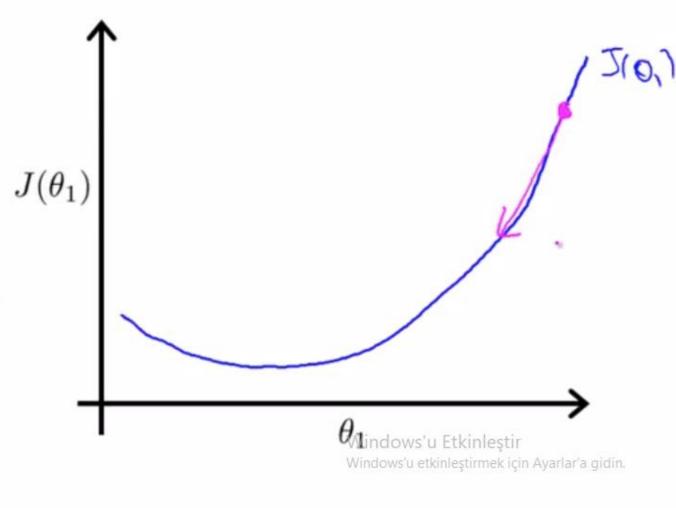
What will one step of gradient descent $heta_1:= heta_1-lpha rac{d}{d heta_1}J(heta_1)$ do?



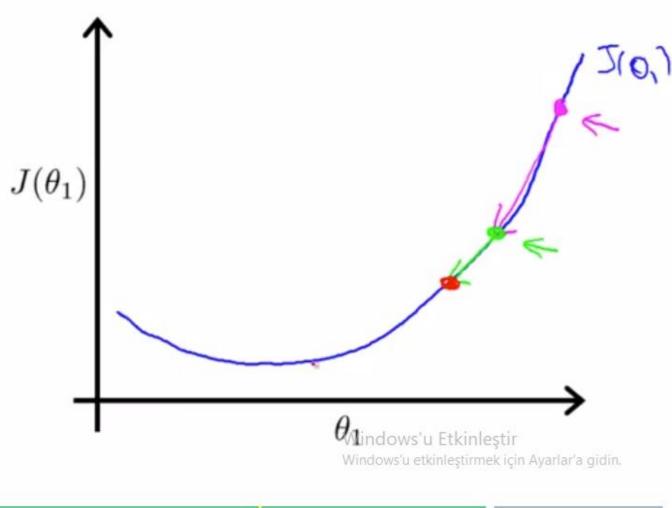
$$\theta_1 := \theta_1 - \alpha \frac{d}{d\theta_1} J(\theta_1)$$



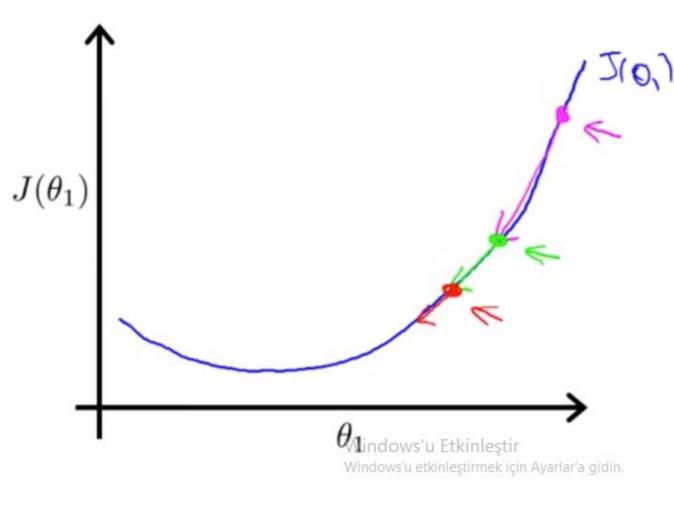
$$\theta_1 := \theta_1 - \alpha \frac{d}{d\theta_1} J(\theta_1)$$



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