

Real Analysis

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Chapter 1

The Real and Complex Numbers

1.1 Ordered Sets

Definition. Let S be any set. An **order** on S is a relation $<$ such that:

[label=(0)]

1. For $x, y \in S$, one and only one of the following hold:

$$x < y$$

$$x = y$$

$$y < x$$

We call this property the **trichotomy law**

2. $<$ is transitive over S .

We denote the relations $>$ and \leq to mean $x > y$ if and only if $y < x$, and $x \leq y$ if and only if $x < y$, or $x = y$. We call S together with $<$ an **ordered set**.

Example 1.1. Define $<$ on \mathbb{Q} such that for $r, s \in \mathbb{Q}$, $r < s$ implies $< 0s - r$.

Definition. Let S be an ordered set, and let $E \subseteq S$. We say that E is **bounded above** if there is some $\beta \in S$ for which $x \leq \beta$, for all $x \in E$. We say that E is **bounded below** if $\beta \leq x$, for all $x \in E$. We say an $\alpha \in S$ is a **least upperbound** of E , if α is an upperbound of E , and for all other upperbounds, γ , of E , $\alpha \leq \gamma$. Likewise, α is a **greatest lowerbound** of E if α is a lowerbound of E , and for all other lowerbounds γ of E , $\gamma \leq \alpha$. We denote the least upperbound, and greatest lowerbound by $\sup E$ and $\inf E$, respectively.

Lemma 1.1.1. *Let S be an ordered set, and let $E \subseteq S$. Then E has (if they exist) a unique least upperbound, and a unique greatest lowerbound.*

Proof. Let $\alpha, \beta \in S$ be least upperbounds of E . Then by definition, we have that $\alpha \leq \beta$, and $\beta \leq \alpha$; thus by the trichotomy law, $\alpha = \beta$. The proof is the same for greatest lowerbounds. ■

Example 1.2. [label=(0)]

1. Let $A = \{p \in \mathbb{Q} : p^2 < 2\}$, and $B = \{p \in \mathbb{Q} : p^2 > 2\}$. Clearly, we have that every element of B is an upperbound of A , and every element of A is a lowerbound of B . Now take $p \in \mathbb{Q}$ a positive rational, and take $q \in \mathbb{Q}$ such that $q = p - \frac{p^2-2}{p+2}$. Then $q^2 - 2 = \frac{2(p^2-2)}{(p+2)^2}$. Now if $p \in A$, then $p^2 - 2 < 0$, which implies that $p < q$, and $q^2 < 2$; thus A has no largest element; similarly, if $p \in B$, then $p^2 - 2 > 0$, which implies that $q < p$ and $q^2 > 2$, which shows that B has no least element. Thus $\sup A$ and $\inf B$ do not exist in \mathbb{Q} .
2. If $\alpha = \sup E \in S$, it may or may not be that $\alpha \in E$. Take $E_1 = \{r \in \mathbb{Q} : r < 0\}$, and $E_2 = \{r \in \mathbb{Q} : r \leq 0\}$. Then $\sup E_1 = \sup E_2 = 0$, but $0 \notin E_1$, where as $0 \in E_2$.
3. Consider the set $\frac{1}{\mathbb{Z}^+} = \{\frac{1}{n} : n \in \mathbb{Z}^+\}$. By the well ordering principle, 1 is the least element, and is also an upperbound of all $\frac{1}{n}$ for $n > 1$. Now also notice that as n gets arbitrarily large, then $\frac{1}{n}$ gets arbitrarily small; that is to say $\frac{1}{n}$ “tends” to 0, so $\sup \frac{1}{\mathbb{Z}^+} = 1 \in \frac{1}{\mathbb{Z}^+}$, and $\inf \frac{1}{\mathbb{Z}^+} = 0 \notin \frac{1}{\mathbb{Z}^+}$.

Definition. We say an ordered set S has the **least upperbound property**, if whenever $E \subseteq S$, nonempty, and bounded above, then $\sup E \in S$ exists; likewise, S has the **greatest lowerbound property** if whenever E is nonempty, bounded below then $\inf E \in S$ exists.

Example 1.3. [label=(0)]

1. The set of all rationals \mathbb{Q} does not have the least upperbound property, nor the greatest lowerbound property, take A, B as in the previous example. Letting $E = \{1, \frac{1}{2}, \frac{1}{4}\} \subseteq \frac{1}{\mathbb{Z}^+}$, we see that $\frac{1}{\mathbb{Z}^+}$ satisfies both properties, with $\sup E = 1$, and $\inf E = \frac{1}{4}$.
2. Let $A \subseteq \mathbb{R}$ be nonempty, and be bounded below. Then by the greatest lowerbound property, $\alpha = \inf A \in \mathbb{R}$ exists; Then for all $x \in A$, $\alpha \leq x$, and for all other lowerbounds γ , $\gamma \leq \alpha$. Then $-x \leq -\alpha$, and $-\alpha \leq -\gamma$, then we see that $-\gamma$ and $-\alpha$ are upperbounds of $-A$, and that $-\alpha$ is the least upperbound of $-A$.

Theorem 1.1.2. *If S is an ordered set with the least upperbound property, then S also inherits the greatest lowerbound property.*

Proof. Let $B \subseteq S$, and let $L \subseteq S$ be the set of all lowerbounds of B . Then we have for any $y \in L$, $x \in B$, $y \leq x$. So every element of B is an upperbound of L , and L is nonempty, hence $\alpha = \sup L \in S$ exists. Now if $\gamma \leq \alpha$, then γ is not an upperbound of L , hence $\gamma \notin B$; thus $\alpha \leq x$ for all $x \in B$, so $\alpha \in L$, and by definition of the greatest lowerbound, we get $\alpha = \inf B$. ■

1.2 Fields

Definition. A **field** is a set F , together with binary operations $+$ and \cdot (called **addition** and **multiplication**, respectively) such that:

[label=(0)]

1. F forms an abelian group under $+$.
2. $F \setminus \{0\}$ forms an abelian group under \cdot (where 0 is the additive identity of F).
3. \cdot distributes over $+$.

We now state the following propositions without proof.

Proposition 1.2.1. *For all $x, y, z \in F$:*

$$[label=(0)] x + y = x + z \text{ implies } y = z \quad x + y = x \text{ implies } y = 0 \quad x + y = 0 \text{ implies } y = -x \quad -(-x) = x.$$

Proposition 1.2.2. *For all $x, y, z \in F \setminus \{0\}$:*

$$[label=(0)] xy = xz \text{ implies } y = z \quad xy = x \text{ implies } y = 1 \quad xy = 1 \text{ implies } y = x^{-1} \quad (x^{-1})^{-1} = x.$$

Proposition 1.2.3. *For all $x, y, z \in F$:*

$$[label=(0)] 0x = 0 \quad x \neq 0 \text{ and } y \neq 0 \text{ implies } xy \neq 0 \quad (-x)y = -(xy) = x(-y) \quad (-x)(-y) = xy.$$

Definition. An **ordered field** is a field F that is also an ordered set, such that:

$$[label=(0)] x + y < x + z \text{ whenever } y < z, \text{ for } x, y, z \in F \quad xy > 0 \text{ whenever } x > 0 \text{ and } y > 0, \text{ for } x, y \in F.$$

Proposition 1.2.4. *Let F be an ordered field, then for any $x, y, z \in F$, the following hold:*

$$[label=(0)] x > 0 \text{ implies } -x < 0. \text{ If } x > 0 \text{ and } y < z, \text{ then } xy < xz. \text{ If } x < 0 \text{ and } y < z, \text{ then } xz < xy. \text{ If } x \neq 0, \text{ then } x^2 > 0, \text{ in particular, } 1 > 0. \text{ } 0 < x < y \text{ implies that } 0 < y^{-1} < x^{-1}.$$

4. Proof. $[label=(0)]$

$$\text{If } x > 0, \text{ then } 0 = x + (-x) > 0 + (-x), \text{ so } -x < 0.$$

2. We have $0 < z - y$, so $0 < x(z - y) = xz - xy$, so $xy < xz$.
3. Do the same as (2), multiplying $z - y$ by $-x$.
4. If $x > 0$, we are done. Now suppose that $x < 0$, then $-x > 0$, so $(-x)(-x) = xx = x^2 > 0$; in particular, we also have that $1 \neq 0$, and $1 = 1^2$, so $1 > 0$.
5. We have $0 < xy^{-1} < yy^{-1} = 1$, then $0 < x^{-1}xy^{-1} = y^{-1} < x^{-1}1 = x^{-1}$

■

1.3 The Field of Real Numbers

Theorem 1.3.1. *There exists an ordered field \mathbb{R} with the least upperbound property, such that $\mathbb{Q} \subseteq \mathbb{R}$.*

Definition. We call the field \mathbb{R} the **field of real numbers**, and we call the elements of \mathbb{R} **real numbers**.

Definition. Let S be an ordered field, and let $E \subseteq S$. We say that E is **dense** in S , if for all $r, s \in S$, with $r < s$, there is an $\alpha \in E$ such that $r < \alpha < s$.

Theorem 1.3.2 (The Archimedean Principle). *If $x, y \in \mathbb{R}$, and $x > 0$, then there is an $n \in \mathbb{Z}^+$ such that $nx > y$.*

Proof. Let $A = \{nx : n \in \mathbb{Z}^+\}$, and suppose that $nx \leq y$. Then y is an upperbound of A , and since A is nonempty, $\alpha = \sup A \in \mathbb{R}$, since $x > 0$, we have $\alpha - x < \alpha$, so $\alpha - x$ is not an upperbound of A . Hence $\alpha - x < mx$ for some $m \in \mathbb{Z}^+$. Then $\alpha < (1 + m)x \in A$, contradicting that α is an upperbound of A . ■

Theorem 1.3.3 (The density of \mathbb{Q} in \mathbb{R}). *\mathbb{Q} is dense in \mathbb{R} .*

Proof. Let $x < y$ be real numbers, then $y - x > 0$, so by the Archimedean principle, there is an $n \in \mathbb{Z}^+$ for which $n(y - x) > 1$. By the Archimedean principle again, we have $m_1, m_2 \in \mathbb{Z}^+$ for which $m_1 > nx$ and $m_2 > -nx$, thus $-m_2 < nx < m_1$, and we also have that there is an $m \in \mathbb{Z}^+$ for which $-m_2 < m < m_1$, and $m - 1 \leq nx < m$. Thus combining inequalities, we get $nx < m < ny$, thus $x < \frac{m}{n} < y$. ■

Theorem 1.3.4 (The existence of n^{th} roots of positive reals). *For every real number $X > 0$, and for every $n \in \mathbb{Z}^+$, there is one, and only one positive real number y for which $y^n = x$.*

Proof. Let $y > 0$ be a real number; then $y^n > 0$, so there is at most one such y for which $y^n = x$. Now let $E = \{t \in \mathbb{R} : t^n < x\}$, choosing $t = \frac{x}{1+x}$, we see that $0 \leq t < 1$, hence $t^n < t < x$, so E is nonempty. Now if $1 + x < t$, then $t^n \geq x$, so $t \notin E$, and E has $1 + x$ as an upperbound. Therefore, $\alpha = \sup E \in \mathbb{R}$ exists.

Now suppose that $y^n < x$, choose $0 \leq h < 1$ such that $h < \frac{x - y^n}{n(y+1)^{n-1}}$, then $(y+h)^n - y^n < hn(y+h)^{n-1} < hn(y+1)^{n-1} < x - y^n$, thus $(y+h)^n < x$, so $y+h \in E$, contradicting that y is an upperbound. On the other hand, if $y^n > x$, choosing $k = \frac{y^n - x}{ny^{n-1}}$, then $0 \leq k < y$, and letting $t \geq y - k$, we get that $y^n - t^n \leq y^n + (y - k)^n < kny_{n-1} = y^n - x^n$, so $t^n \geq x$, making $y - k$ an upperbound of E , which contradicts $y = \sup E$. ■

Remark. We denote y as $\sqrt[n]{x}$, or as $x^{\frac{1}{n}}$.

Corollary. *If $a, b \in \mathbb{R}$, with $a, b > 0$, and $n \in \mathbb{Z}^+$, then $\sqrt[n]{ab} = \sqrt[n]{a}\sqrt[n]{b}$.*

Proof. Let $\alpha = \sqrt[n]{a}$, and $\beta = \sqrt[n]{b}$. Then $\alpha^n = a$, and $\beta^n = b$, so $ab = \alpha^n \beta^n = (\alpha\beta)^n$, we are done. ■

Definition. We define the **extended real number system** to be the field \mathbb{R} , together with symbols ∞ , and $-\infty$, called **positive infinity** and **negative infinity**, such that $-\infty < x < \infty$ for all $x \in \mathbb{R}$. We call elements of the extended real numbers **infinite**, and every other element not in the extended real numbers **finite**.

Lemma 1.3.5. ∞ is an upperbound for every subset E , of \mathbb{R} , and $-\infty$ is a lowerbound for every subset E of \mathbb{R} . Moreover, if E is not bounded above, then $\sup E = \infty$, and if E is not bounded below, then $\inf E = -\infty$.

Remark. We make the following assumptions for extended real numbers:

[label=(0)]If $x \in \mathbb{R}$, then $x + \infty = \infty$, $x - \infty = -\infty$, and $\frac{x}{\infty} = \frac{x}{-\infty} = 0$. If $x > 0$, then $x(\infty) = \infty$ and $x(-\infty) = -\infty$. If $x < 0$, then $x(\infty) = -\infty$ and $x(-\infty) = \infty$.

1.4 The Complex Field

Definition. We define a **complex number** to be a pair of real numbers (a, b) . We denote the set of all complex numbers by \mathbb{C} . We define the **addition** and **multiplication** of complex numbers to be the binary operations $+: \mathbb{C} \rightarrow \mathbb{C}$ and $\cdot: \mathbb{C} \rightarrow \mathbb{C}$ such that

$$\begin{aligned}(a, b) + (c, d) &= (a + c, b + d) \\ (a, b)(c, d) &= (ac - bd, ad + bc)\end{aligned}$$

Lastly, we define i to be the complex number such that $i = (0, 1)$.

Theorem 1.4.1. \mathbb{C} forms a field together with $+$ and \cdot .

Theorem 1.4.2. For $(a, 0), (b, 0) \in \mathbb{C}$, $(a, 0) + (b, 0) = (a + b, 0)$, and $(a, 0)(b, 0) = (ab, 0)$.

3. *Proof.* This is a straightforward application of the addition and multiplication of complex numbers. ■

Theorem 1.4.3. $i^2 = -1$.

Proof. $i^2 = (0, 1)(0, 1) = (0 - 1, 1 - 1) = (-1, 0) = -1$. ■

Theorem 1.4.4. Let $(a, b) \in \mathbb{C}$, then $(a + b) = a + ib$.

Proof. $(a, b) = (a, 0) + (0, b) = (a, 0) + (0, 1)(b, 0) = a + ib$. ■

Definition. Let $a, b \in \mathbb{R}$, and let $z \in \mathbb{C}$ such that $z = a + ib$. We define the **complex conjugate** of z to be the complex number $\bar{z} = a - ib$. Moreover, we define the **real part** of z to be a , and the **imaginary part** of z to be b , and we denote them $a = \operatorname{Re} z$, $b = \operatorname{Im} z$

Theorem 1.4.5. Let $z, w \in \mathbb{C}$. Then

[label=(0)] $\overline{z + w} = \bar{z} + \bar{w}$. $\overline{zw} = \bar{z}\bar{w}$. $z + \bar{z} = 2\operatorname{Re} z$ and $z - \bar{z} = 2i\operatorname{Im} z$. $z\bar{z}$ is a nonegative real number.

4. *Proof.* Let $z = a + ib$, and let $w = c + id$. Then $z + w = (a + c) + i(b + d)$, so $\overline{z + w} = (a + b) - i(b + d) = (a - ib) + (c - id) = \bar{z} + \bar{w}$; similarly, we get $\overline{zw} = \bar{z}\bar{w}$. Moreover, we have $(a + ib) + (a - ib) = 2a$, and $(a + ib) - (a - ib) = 2ib$, we also have that $z\bar{z} = (a + ib)(a - ib) = a^2 + b^2 \geq 0$, and $z\bar{z} = 0$ if and only if $a = b = 0$. ■

Definition. Let $z \in \mathbb{C}$. We define the **modulus** of z to be $|z| = \sqrt{z\bar{z}}$.

Remark. $|z|$ exists and is unique.

Theorem 1.4.6. Let $z, w \in \mathbb{C}$, then:

$$|z| \geq 0 \text{ and } |z| = 0 \text{ if and only if } z = 0. \quad |\bar{z}| = |z|. \quad |zw| = |z||w|. \quad \operatorname{Re} z \leq |z|. \\ |z + w| \leq |z| + |w|.$$

Proof. Let $z = a + ib$, and $w = c + id$. Then $|z| = \sqrt{a^2 + b^2} \geq 0$, and $|z| = 0$ if and only if $a, b = 0$. Moreover, $|\bar{z}| = |a + i(-b)| = \sqrt{a^2 + (-b)^2} = \sqrt{a^2 + b^2} = |z|$. We also have $|zw|^2 = (a^2 + b^2)(c^2 + d^2) = |z|^2|w|^2$, likewise, $|\operatorname{Re} z| = |a + i0| = \sqrt{a^2} \leq \sqrt{a^2 + b^2}$. Finally we prove (5).

We have $|z + w|^2 = (z + w)(\bar{z} + \bar{w}) = z\bar{z} + \bar{z}w + \bar{w}z + w\bar{w} = |z|^2 + w\operatorname{Re} z\bar{w} + |w|^2 \leq |z|^2 + 2|z\bar{w}| + |w|^2 = (|z| + |w|)^2$. ■

Theorem 1.4.7 (The Cauchy Schwarz Inequality). Let $a_i, b_i \in \mathbb{C}$, for $1 \leq i \leq n$. Then:

$$\left| \sum_{i=1}^n a_i \bar{b}_i \right| \leq \sum_{i=1}^n |a_i|^2 \sum_{i=1}^n |b_i|^2 \quad (1.1)$$

Proof. Let $A = \sum |a_j|^2$, $B = \sum |b_i|^2$, and $C = \sum a_i \bar{b}_i$. If $B = 0$, then $b_i = 0$ for $1 \leq i \leq n$, and we are done; so suppose that $B > 0$. Then

$$\begin{aligned} \sum |Ba_j - Cb_j|^2 &= \sum (Ba_j - Cb_j)(B\bar{a}_j - \bar{C}\bar{b}_j) \\ &= B \sum |a_j|^2 - B\bar{C} \sum a_j \bar{b}_j - BC \sum \bar{a}_j b_j + |C|^2 \sum |b_j|^2 \\ &= (B^2 A - B|C|^2) = B(AB - |C|^2) \geq 0 \end{aligned}$$

Since $B > 0$, we get $|C|^2 \leq AB$ as required. ■

1.5 Euclidean Spaces

Definition. Let $k \in \mathbb{Z}^+$, and let \mathbb{R}^k be the set of all ordered k -tuples (x_1, x_2, \dots, x_k) , with $x_i \in \mathbb{R}$ for $1 \leq i \leq k$. We call \mathbb{R}^k the **Euclidean space** of **dimension** k ; more simply the **Euclidean k -space**. We call elements of \mathbb{R}^k **vectors** or **points**; and we define **vector addition** and **scalar multiplication** to be:

$$\begin{aligned} (x_1, \dots, x_k) + (y_1, \dots, y_k) &= (x_1 + y_1, \dots, x_k + y_k) \\ \alpha(x_1, \dots, x_k) &= (\alpha x_1, \dots, \alpha x_k) \end{aligned}$$

for $(x_1, \dots, x_k), (y_1, \dots, y_k) \in \mathbb{R}^k$ and $\alpha \in \mathbb{R}$.

Theorem 1.5.1. \mathbb{R}^k forms a vector space together with vector addition and scalar multiplication.

Definition. Let $x, y \in \mathbb{R}^k$. We define the **inner product** of x and y to be the binary operation $\langle, \rangle : \mathbb{R}^k \times \mathbb{R}^k \rightarrow \mathbb{R}$ such that

$$\langle x, y \rangle = \sum_{i=1}^k x_i y_i$$

We define the **norm** of x to be $\|x\| = \sqrt{\langle x, x \rangle} = \sqrt{\sum x_i^2}$.

Theorem 1.5.2. Let $x, y \in \mathbb{R}^k$, and $\alpha \in \mathbb{R}$. Then:

$$\begin{aligned} & \|x\| \geq 0 \text{ and } \|x\| = 0 \text{ if and only if } x_i = 0 \text{ for all } 1 \leq i \leq k. \quad \|\alpha x\| = |\alpha| \|x\|. \\ & \|\langle x, y \rangle\| \leq \|x\| \|y\|. \quad \|x + y\| \leq \|x\| + \|y\|, \text{ and } \|x - z\| \leq \|x - y\| + \|y - z\| \end{aligned}$$

Proof. (1) follows by definition of the norm. We also have that $\|\alpha x\| = \sqrt{\sum \alpha^2 x_i^2} = \sqrt{\alpha^2} \sqrt{\sum x_i^2} = |\alpha| \|x\|$.

Now by the Cauchy Schwarz inequality, we have that $\|\langle x, y \rangle\|^2 = \sum x_i^2 y_i^2 \leq \sum x_i^2 \sum y_i^2 = \|x\| \|y\|$. Finally we have that $\|x + y\|^2 = \langle x + y, x + y \rangle = \langle x, x \rangle + 2\langle x, y \rangle + \langle y, y \rangle \leq \|x\|^2 + 2\|x\| \|y\| + \|y\|^2 = (\|x\| + \|y\|)^2$, the last result follows immediately. ■

Chapter 2

Topological Foundations

2.1 Finite, Countable, and Uncountable Sets

Definition. Let A be a set, and let $E \subseteq \mathbb{N}$. We say that A is **finite** if there exists a 1-1 mapping of A onto E , we say A is **countable** if $E = \mathbb{N}$, and we say A is **atmost countable** if A is either finite or countable.

Example 2.1. The set of all integers \mathbb{Z} is countable. Take $f : \mathbb{N} \rightarrow \mathbb{Z}$ such that $f(n) = 2$ if n is even, and $f(n) = -n$ if n is odd.

Definition. Let A be a set, and let $E \subseteq \mathbb{N}$. A **sequence** in A is a mapping $f : E \rightarrow A$ such that $f(n) = x_n$, for $x_n \in A$. We call the values of f **terms** of the sequence. We denote sequences by $\{x_n\}_{n=1}^{\infty}$, and when $E = \mathbb{N}$, we denote them simply by $\{x_n\}$.

Theorem 2.1.1. *Every infinite subset of a countable set is countable.*

Proof. Let A be countable, and let $E \subseteq A$ be infinite. Arrange the elements of A into a sequence $\{x_n\}$, and construct a sequence $\{n_k\}$ such that n_1 is the least term for which $\{x_{n_k}\} \in E$, and n_k is the least term greater than n_{k-1} for which $x_{n_k} \in E$. Let $f(k) = x_{n_k}$, and we get a 1-1 mapping of \mathbb{N} onto E . ■

Theorem 2.1.2. *Let $\{E_n\}$ be a sequence of countable sets. Then $S = \bigcup E_n$ is also countable.*

Proof. Arrange every set E_n in a sequence $\{x_{nk}\}$, and consider the infinite array (x_{ij}) , in which the elements of E_n form the n -th row. Then (x_{ij}) contains all the elements of S , and we can arrange them in a sequence

$$x_{11}, (x_{21}, x_{12}), (x_{31}, x_{22}, x_{13}), \dots$$

Moreover, if $E_i \cap E_j \neq \emptyset$, for $i \neq j$, then the elements of $E_i \cap E_j$ appear more than once in the sequence of S ; so taking $T \subseteq \mathbb{N}$, we get a 1-1 mapping of T onto S , hence S is atmost countable, and since $E_i \subseteq S$ for $i \in \mathbb{N}$, is infinite, by theorem 2.1.1, S is infinite, thus S is countable. ■

▣Figures/diagonalizationArray.png

Figure 2.1: The infinite array (x_{ij})

Corollary. *Let A be atmost countable, and suppose for all $\alpha \in A$ that the sets B_α are atmost countable. Then*

$$T = \bigcup_{\alpha \in A} B_\alpha$$

is atmost countable.

Theorem 2.1.3. *Let A be countable, and let B_n be the set of all n -tuples (a_1, \dots, a_n) such that $a_i \in A$ for $1 \leq i \leq n$. Then B_n is countable.*

Proof. By induction on n , we have that $B_1 = A$, which is countable. Now suppose that B_n is countable, and consider B_{n+1} whose elements are of the form (b, a) where $b \in B_n$ and $a \in A$. Fixing b , we get a 1-1 correspondence between the elements of B_{n+1} and A ; therefore B is countable. ■

Corollary. \mathbb{Q} is countable.

Proof. For every rational $\frac{p}{q} \in \mathbb{Q}$, represent $\frac{p}{q}$ as (p, q) . Then the countability of \mathbb{Q} follows from theorem 2.1.3. ■

Theorem 2.1.4. *Let A be the set of all sequences of 0 and 1; then A is uncountable.*

Proof. Let EA be countable, and let E consist of all the sequences of 0 and 1, s_1, s_2, s_3, \dots . Construct the sequence s such that if the n -th term of the sequence s_i is 0, then the n -th term of s is 1, and vice versa, for $i \in \mathbb{Z}^+$. Then the sequence s differs from the sequence s_i at atleast one place; thus $s \notin E$, but $s \in A$. Therefore $E \subset A$, which establishes the uncountability of A . ■

2.2 Metric Spaces

Definition. A set X , whose elements we will call **points**, is said to be a **metric space** if there exists a mapping $d : X \times X \rightarrow \mathbb{R}$, called a **metric** (or **distance function**) such that for $x, y \in X$

[label=(0)]

1. $d(x, y) \geq 0$, and $d(x, y) = 0$ if and only if $x = y$.
2. $d(x, y) = d(y, x)$.
3. $d(x, y) \leq d(x, z) + d(z, y)$ (The Triangle Inequality).

Example 2.2. The absolute value, $|\cdot|$ for real numbers, the modulus $|\cdot|$ for complex numbers, and the norm $\|\cdot\|$ for vectors are all metrics. They turn \mathbb{R} , \mathbb{C} , and \mathbb{R}^k into metric spaces respectively.

Definition. An **open interval** in \mathbb{R} (or **segment**) is a set of the form $(a, b) = \{a, b \in \mathbb{R} : a < x < b\}$, a **closed interval** in \mathbb{R} is a set of the form $[a, b] = \{x \in \mathbb{R} : a \leq x \leq b\}$; and **half open intervals** in \mathbb{R} are sets of the form $[a, b) = \{x \in \mathbb{R} : a \leq x < b\}$ and $(a, b] = \{x \in \mathbb{R} : a < x \leq b\}$.

If $a_i < b_i$, for $1 \leq i \leq k$, the set of all points $(x_1, \dots, x_k) \in \mathbb{R}^k$ which satisfy the Inequalities $a_i \leq x_i \leq b_i$ is called a **k-cell** in \mathbb{R}^k . If $x \in \mathbb{R}^k$, and $r > 0$, we call the set $B_r(x) = \{y \in \mathbb{R}^k : \|x - y\| < r\}$ an **open ball** in \mathbb{R}^k , and we call the set $B_r[x] = \{y \in \mathbb{R}^k : \|x - y\| \leq r\}$ a **closed ball** in \mathbb{R}^k .

Definition. We call a set $E \subseteq \mathbb{R}^k$ **convex**, if whenever $x, y \in E$, $\lambda x + (1 - \lambda)y \in E$ for $0 < \lambda < 1$.

Lemma 2.2.1. *Open and closed balls, along with k-cells are convex.*

Proof. Let $B_r(x)$ be an open ball; let $y, z \in B_r(x)$, and $0 < \lambda < 1$. Then $\|x - (\lambda y + (1 - \lambda)z)\| = \|\lambda(x - y) + (1 - \lambda)(x - z)\| \leq \lambda\|x - y\| + (1 - \lambda)\|x - z\| < \lambda r + (1 - \lambda)r$. The proof is analogous for closed ball.

Now let K be a k -cell for $a_i < b_i$, for $1 \leq i \leq k$, let $x, y \in K$, then $a_i \leq x_i, y_i \leq b_i$, so $\lambda a_i \leq \lambda x_i \leq \lambda b_i$, and $(1 - \lambda)a_i \leq (1 - \lambda)y_i \leq (1 - \lambda)b_i$, since $0 < \lambda < 1$, $a_i \leq \lambda a_i + (1 - \lambda)a_i \leq \lambda x_i + (1 - \lambda)y_i \leq \lambda b_i + (1 - \lambda)b_i \leq b_i$. ■

Corollary. *Open and closed intervals, along with half open intervals are convex.*

Proof. We just notice that open and closed intervals are open and closed balls in $\mathbb{R}^1 = \mathbb{R}$, we also notice that half open intervals $[a, b)$ and $(a, b]$ are subsets of the closed interval $[a, b]$, and hence inherit convexity. ■

For the following definitions, let X be a metric space with metric d .

Definition. A **neighborhood** of a point $x \in X$ is the set $N_r(x) = \{y \in X : d(x, y) < r\}$ for some $r > 0$ called the **radius** of the neighborhood. We call x a **limit point** of a set $E \subseteq X$ if every neighborhood of x contains a point $y \neq x$ such that $y \in E$. If $y \in E$, and y is not a limit point, we call y an **isolated point**.

Definition. We call a set $E \subseteq X$ **closed** if every limit point of E is in E . A point $x \in X$ is an **interior point** of E if there is a neighborhood N of x such that $N \subseteq E$. We call E **open** if every point of E is an interior point of E .

Definition. $E \subseteq X$ is called **perfect** if E is closed, and every point of E is a limit point of E . We call E **dense** if every point of X is either a limit point of E , or a point of E , or both.

Lemma 2.2.2. *If $E \subseteq X$, then E is perfect in X if and only if $\overline{E} = E$.*

Lemma 2.2.3. *If $E \subseteq X$ is dense in X , then either E is perfect in X , or $X = E$, or both.*

Definition. We call $E \subseteq X$ **bounded** if there is a real number $M > 0$, and a point $y \in X$ such that $d(x, y) < M$ for all $x \in E$.

Theorem 2.2.4. *Let X be a metric space and $x \in X$. Every neighborhood of x is open.*

Proof. Consider the neighborhood $N_r(x)$, and $y \in E$, there is a positive real number h such that $d(x, y) = r - h$, then for $z \in X$ such that $d(y, z) < h$, we have $d(x, z) \leq d(x, y) + d(y, z) < r - h + h = r$, thus $z \in E$, so y is an interior point of E . ■

Theorem 2.2.5. *If x is a limit point of a set E , then every neighborhood of x contains infinitely many points of E .*

Proof. Let N be a neighborhood of x containing only a finite number of points of E . Let y_1, \dots, y_n be points of $N \cap E$ distinct from x and let $r = \min\{d(x, y_i)\}$ for $1 \leq i \leq n$, then $r > 0$, and the neighborhood $N_r(x)$ contains no point y of E for which $y \neq x$, so x is not a limit point; which is a contradiction. ■

Corollary. *A finite point set has no limit points.*

Proof. By theorem 2.2.5, if x is a limit point in the finite point set E , then every neighborhood of x contains infinitely many points of E ; contradicting its finiteness. ■

Example 2.3. [label=(0)]

1. The set of all $z \in \mathbb{C}$ such that $|z| < 1$ is open, and bounded.
2. The set of all $z \in \mathbb{C}$ for which $|z| \leq 1$ is closed, perfect, and bounded.
3. Any nonempty finite set is closed, and bounded.
4. \mathbb{Z} is closed, but it is not open, perfect, or bounded.
5. The set $\frac{1}{\mathbb{Z}^+}$ is neither closed, nor open, it is not perfect; but it is bounded.
6. \mathbb{C} is closed, open, and perfect, but it is not bounded.
7. The open interval in (a, b) is open (only in \mathbb{R}), and bounded.

Theorem 2.2.6. *Let X be a metric space, a set $E \subseteq X$ is open if and only if $X \setminus E$ is closed.*

Proof. Suppose that $X \setminus E$ is closed, let $x \in E$, then $x \notin X \setminus E$, and x is not a limit point of $X \setminus E$. Thus there is a neighborhood N of x such that $N \cap (X \setminus E) = \emptyset$, thus $N \subseteq E$, and so x is an interior point of E .

Conversely, suppose that E is open, and let x be a limit point of $X \setminus E$, then every neighborhood of x contains a point of $X \setminus E$, so x is not an interior point of E , since E is open, it follows that $x \in X \setminus E$, thus $X \setminus E$ is closed. ■

Corollary. *E is closed if and only if $X \setminus E$ is open.*

Proof. This is the converse of theorem 2.2.5. ■

Theorem 2.2.7. *Let X be a metric space. The following are true:*

[label=(0)]If $\{G_\alpha\}$ is a collection of open sets, then $\bigcup G_\alpha$ is open. If $\{G_i\}_{i=1}^n$ is a finite collection of open sets, then $\bigcap_{i=1}^n G_i$ is open. If $\{G_\alpha\}$ is a collection of closed sets, then $\bigcap G_\alpha$ is closed. If $\{G_i\}_{i=1}^n$ is a finite collection of closed sets, then $\bigcup_{i=1}^n G_i$ is closed.

2. *Proof.* Let $G = \bigcup G_\alpha$, then if $x \in G$, $x \in G_\alpha$ for some α , then x is an interior point of G_α , hence an interior point of G , so G is open. Now let $G = \bigcap_{i=1}^n G_i$. For $x \in G$, there are neighborhoods N_i of x , with radii r_i such that $N_i \subseteq G_i$ for $1 \leq i \leq n$. Then let $r = \min\{r_1, \dots, r_n\}$, and let N be the neighborhood of x with radius r , then $N \subseteq G_i$, hence $N \subseteq G$, so G is open.

The proofs of (3) and (4) are just the converse of the proofs of (1) and (2). ■

Definition. Let X be a metric space, and let $E \subseteq X$, and let E' be the set of all limit points of E . We define the **closure** of E to be the set $\overline{E} = E \cup E'$.

Theorem 2.2.8. *If X is a metric space, and $E \subseteq X$, then the following hold*

[label=(0)] \overline{x} is closed. E is closed if and only if $E = \overline{E}$. If $F \subseteq X$ such that $E \subseteq F$, and F is closed, then $\overline{E} \subseteq F$.

2. *Proof.* If $x \in X$, and $x \notin \overline{E}$, then $x \notin E$, nor is it a limit point of E , thus there is a neighborhood of x that is disjoint from E , hence $X \setminus \overline{E}$ is open.

Now if E is closed, then $E' \subseteq E$, so $\overline{E} = E$, conversely, if $E = \overline{E}$, then clearly E is closed. Now if F is closed and $E \subseteq F$, then $F' \subseteq F$, and $E' \subseteq F$, therefore $\overline{E} \subseteq F$. ■

Theorem 2.2.9. *Let $E \subseteq \mathbb{R}$ be nonempty and bounded above, let $y = \sup E$, then $y \in \overline{E}$, hence $y \in E$ if E is closed.*

Proof. Suppose that $y \notin E$, then for every $h > 0$, there exists a point $x \in E$ such that $y - h < x < y$, then y is a limit point of E , thus $y \in \overline{E}$. ■

Theorem 2.2.10. *Let $Y \subseteq X$; a subset E of Y is open in Y if and only if $E = Y \cap G$ for some open subset G of X .*

Proof. Suppose E is open in Y , then for each $x \in E$, there is a $r_p > 0$ such that $d(x, y) < r_p$, if $y \in Y$, that implies that $y \in E$; hence let V_x be the set of all $y \in X$ such that $d(x, y) < r_p$, and define

$$G = \bigcup_{x \in E} V_x$$

Then by theorems 2.2.2 and 2.2.6, G is open in X , and $E \subseteq G \cap Y$. Now we also have that $V_x \cap Y \subseteq E$, thus $G \cap Y \subseteq E$, thus $E = G \cap Y$. Conversely, if G is open in X , and $E = G \cap Y$, then every $x \in E$ has a neighborhood $V_x \subseteq G$, thus $V_x \cap Y \subseteq E$, hence E is open in Y . ■

2.3 Compact Sets

Definition. Let X be a metric space, and let $E \subseteq X$. An **open cover** of E is a collection $\{G_\alpha\}$ of subsets of X such that $E \subseteq \bigcup G_\alpha$. We call a collection $\{E_\beta\}$ of subsets of X an **open subcover** of E if $\{E_\beta\}$ is a cover of E , and $\bigcup E_\beta \subseteq \bigcup G_\alpha$. We call E **compact** if every open cover of E contains a finite open subcover.

Lemma 2.3.1. *Every finite set is compact.*

Proof. Let K be finite, and let $\{G_\alpha\}$ be an open subcover of K . Since K is finite, there is a 1-1 mapping of K onto the set $\{1, \dots, n\}$. Let $\{E_i\}_{i=1}^n$ be the finite collection of all subsets of K , clearly, $\{E_i\}$ is an open cover of K . Moreover, if $\bigcup E_i \subseteq \bigcup G_\alpha$, we are done, and if $\bigcup G_\alpha \subseteq \bigcup E_i$, then $\{G_i\}$ is a finite subcollection that covers K , so in either case, K is compact. ■

Theorem 2.3.2. *Let X be a metric space, and let $K \subseteq Y \subseteq X$. Then Y is compact in X if and only if K is compact in Y .*

Proof. Suppose K is compact in Y , and let $\{G_\alpha\}$ be a collection of subsets of $Y \setminus X$ that cover K , and let $V_\alpha = Y \cap G_\alpha$, then $\{V_\alpha\}$ is a collection of subsets of X covering K , in which $V_\alpha \subseteq G_\alpha$ for all α , therefore K is compact in Y .

conversely, suppose that K is compact in X , and let $\{V_\alpha\}$ be a collection of open sets in Y such that $K \subseteq \bigcup V_\alpha$, by theorem 2.2.10, there is a collection $\{G_\alpha\}$ of open sets in Y such that $V_\alpha = Y \cap G_\alpha$, for all α . Then $K \subseteq \bigcup_{i=1}^n G_{\alpha_i}$; therefore, K is compact in Y . ■

Theorem 2.3.3. *Compact subsets of metric spaces are closed.*

Proof. Let X be a metric space, and let K be compact in X and let $x \in X \setminus K$, if $y \in K$, let U and V be neighborhoods of x and y respectively, each of radius $r < \frac{1}{2}d(x, y)$. Since K is compact, there are finitely many points y_1, \dots, y_n such that $K \subseteq \bigcup_{i=1}^n V_i = V$, where V_i is a neighborhood of y_i for $1 \leq i \leq n$. Let $U = \bigcap_{i=1}^n U_i$, then $V \cap U$ is empty, hence $x \notin \overline{K}$, therefore, $x \in X \setminus \overline{K}$, therefore K is closed. ■

Theorem 2.3.4. *Closed subsets of compact sets are compact.*

Proof. Let X be a metric space with $F \subseteq K \subseteq X$, with F closed in X , and K compact. Let $\{V_\alpha\}$ be an open cover of F . If we append $X \setminus F$ to $\{V_\alpha\}$, we get an open cover Θ of K , and since K is compact, there is a finite subcollection Φ which covers K , so Φ is an open cover of F , $X \setminus F \in \Phi$, then $\Phi \setminus (X \setminus F)$ still covers F , therefore F is compact. ■

Theorem 2.3.5. *Let $\{K_\alpha\}$ be a collection of compact sets of a metric space X , such that every finite subcollection of $\{K_\alpha\}$ is nonempty. Then $\bigcap K_\alpha$ is nonempty.*

Proof. Fix $K_1 \subseteq \{K_\alpha\}$, and let $G_\alpha = X \setminus K_\alpha$. Suppose no point of K_1 is in $\bigcap K_\alpha$, then $\{G_\alpha\}$ covers K_1 , and since K_1 is compact, we have $K_1 \subseteq \bigcup_{i=1}^n G_{\alpha_i}$, for $1 \leq i \leq n$, which implies that $\bigcap K_\alpha$ is empty, a contradiction. ■

Corollary. *If $\{K_\alpha\}$ is a sequence of nonempty compact sets, such that $K_{n+1} \subseteq K_n$, then $\bigcap_{i=1}^\infty K_n$ is nonempty.*

Theorem 2.3.6. *If E is an infinite subset of a compact set K , then E has a limit point in K .*

Proof. Suppose no point of K is a limit point of E , then for all $x \in K$, the neighborhood U_x contains at most one point in E . Then no finite subcollection of $\{U_x\}$ covers E , which contradicts the compactness on K . ■

Theorem 2.3.7 (The Nested Interval Theorem). *if $\{I_n\}$ is a sequence of intervals in \mathbb{R} such that $I_{n+1} \subseteq I_n$, then $\bigcap_{j=1}^\infty I_n$ is nonempty.*

Proof. We let $I_n = [a_n, b_n]$. Letting E be the set of all a_n , E is nonempty and bounded above by b_1 . Letting $x = \sup E$, and $m \geq n$, we have $[a_m, b_m] \subseteq [a_n, b_n]$, thus $a_m \leq x \leq b_m$ for all m , thus $x \in I_m = \bigcap_{j=i}^n I_j$ ■

Theorem 2.3.8. *Let $k \in \mathbb{Z}^+$, and $\{I_n\}$ be a nonempty sequence of k -cells of \mathbb{R}^k such that $I_{n+1} \subseteq I_n$. Then $\bigcap_{j=1}^{\infty} I_n$ is nonempty.*

Proof. Let I_n be the set of all points $x \in \mathbb{R}^k$ such that $a_{n,j} \leq x_j \leq b_{n,j}$, and let $I_{n,j} = [a_{n,j}, b_{n,j}]$. Then for each $1 \leq j \leq k$, by the nested interval theorem, $\bigcap_{l=1}^{\infty} I_{l,j}$ is nonempty, hence there are real numbers x'_j such that $a_{n,j} \leq x'_j \leq b_{n,j}$. Letting $x' = (x'_1, \dots, x'_k)$, we get that $x' \in I \bigcap_{l=1}^{\infty} I_l$ ■

Theorem 2.3.9. *Every k -cell is compact.*

Proof. Let I be a k -cell, and let $\delta = \sqrt{\sum_{j=1}^k a(b_j - a_j)^2}$ we get for $x, y \in I$, $\|x - y\| \leq \delta$. Now suppose there is an open cover $\{G_\alpha\}$ of I for which no finite subcover is contained. Let $c_j = \frac{a_j + b_j}{2}$, then the closed intervals $[a_j, c_j]$, $[c_j, b_j]$ determine the 2^k k -cells Q_i such that $\bigcup Q_i = I$. Then atleast one Q_i cannot be covered by any finite subcollection of $\{G_\alpha\}$. Subdividing Q_1 , we get a sequence $\{Q_n\}$ such that $Q_{n+1} \subseteq Q_n$, Q_n is not covered by any finite subcollection of $\{G_\alpha\}$, and $\|x - y\| \leq \frac{\delta}{2^n}$ for $x, y \in Q_n$. Then by theorem 2.3.8, there is a point $x' \in Q_n$, and for some α , $x' \in G_\alpha$; since G_α is open, there is an $r > 0$ for which $\|x - x'\| < r$ implies $y \in G_\alpha$. Then for n sufficiently large, we have that $\frac{\delta}{2^n} < r$, then we get that $Q_n \subseteq G_\alpha$, which is a contradiction. ■

Theorem 2.3.10 (The Heine-Borel Theorem). *If E is a subset of \mathbb{R}^k , then the following are equivalent:*

[label=(0)] E is closed and bounded. E is compact. Every infinite subset of E has a limit point in E .

2. Proof. Suppose that E is closed and bounded, then $E \subseteq I$ for some k -cell I in \mathbb{R}^k , and hence it is compact. By theorem 2.3.4, E is compact. Now suppose that E is compact, then by theorem 2.3.6, every infinite subset of E has a limit point in E .

Now suppose that every infinite subset of E has a limit point in E . If E is not bounded, then $\|x_n\| > n$ for some $x_n \in E$ and $n \in \mathbb{Z}^+$. Then the set of all such x_n is infinite, and has no limit point in E , a contradiction; moreover suppose that E is not closed. Then there is a point $x_0 \in \mathbb{R}^k \setminus E$, which is a limit point of E . Then there are points $x_n \in E$ for which $\|x_n - x_0\| < \frac{1}{n}$, let S be the set of all such points. Then S is infinite and has x_0 as its only limit point; for if $y \neq x_0 \in \mathbb{R}^k$, then $\frac{1}{2}\|x_0 - y\| \leq \|x_0 - y\| - \frac{1}{n} \leq \|x_0 - y\| - \|x_n - x_0\| \leq \|x_n - y\|$ for only some n . Thus by theorem 2.2.3, y is not a limit point of S . Therefore, if every infinite subset of E has a limit point in E , E must be closed. ■

Theorem 2.3.11 (The Bolzano-Weierstrass Theorem). *Every bounded infinite subset E of \mathbb{R}^k has a limit point in \mathbb{R}^k .*

Proof. We have that $E \subseteq I$, for some k -cell I in \mathbb{R}^k . Since k -cells are compact, by the Heine-Borel theorem, E is also compact and has a limit point in I . ■

2.4 Perfect Sets

Theorem 2.4.1. *If $P \subseteq \mathbb{R}^k$ is a nonempty perfect set, then P is uncountable.*

Proof. Since every point of P is a limit point of P , we have that P must be infinite. Then suppose that P is countable. For points $x_n \in P$, construct the sequence $\{U_n\}$ of neighborhoods of x_n , for $n \in \mathbb{Z}^+$; now by induction, if U_1 is a neighborhood of x_1 , then for $y \in \hat{U}_1$, $\|x_1 - y\| \leq r$ for some $r > 0$. Now suppose the neighborhood U_n of x_n has been constructed such that $U_n \cap P$ is nonempty. Then there is a neighborhood U_{n+1} of x_{n+1} such that $\hat{U}_{n+1} \subseteq U_n$, $x_n \notin \hat{U}_{n+1}$, and $U_{n+1} \cap P$ is nonempty. Therefore there is a nonempty $K_n = U_n \cap P$. Since \hat{U}_n is closed and bounded, \hat{U} is compact, and since $x_n \notin K_{n+1}$, $x_n \notin \bigcap_{i=1}^{\infty} K_i$, and since $K_n \subseteq P$, $\bigcap K_i$ is empty, a contradiction. ■

Corollary. *Let $a < b$ be real numbers. Then the closed interval $[a, b]$ is uncountable. Moreover, \mathbb{R} is uncountable.*

Proof. We have $[a, b]$ is closed, and perfect (since $(a, b)[a, b]$ is perfect), thus $[a, b]$ is uncountable. Moreover, take $f : \mathbb{R} \rightarrow [a, b]$, by $f(x) = \frac{a+b}{2}x$; then f is a 1-1 mapping of \mathbb{R} onto $[a, b]$, which makes \mathbb{R} uncountable. ■

Theorem 2.4.2 (The construction of the Cantor set). *There exists a perfect set in \mathbb{R} which contains no open interval.*

Proof. Let $E_0 = [0, 1]$, and remove $(\frac{1}{3}, \frac{2}{3})$, and let $E_1 = [0, \frac{1}{3}] \cup [\frac{2}{3}, 1]$. Now remove the open intervals $(\frac{1}{9}, \frac{2}{9})$, $(\frac{3}{9}, \frac{6}{9})$, $(\frac{7}{9}, \frac{8}{9})$, and let $E_2 = [0, \frac{2}{9}] \cup [\frac{2}{9}, \frac{3}{9}] \cup [\frac{6}{9}, \frac{7}{9}] \cup [\frac{7}{9}, \frac{8}{9}]$. Continuing the removal of the middle third of each interval, we obtain the sequence of compact sets $\{E_n\}$, such that $E_{n+1} \subseteq E_n$, and E_n is the union of 2^n closed intervals of length $\frac{1}{3^n}$. Then let:

$$P = \bigcap_{i=1}^{\infty} E_i \quad (2.1)$$

Then P is nonempty, and compact.

Now let I be the open interval of the form $(\frac{3k+1}{3^m}, \frac{3k+2}{3^m})$, with $k, m \in \mathbb{Z}^+$. Then by the construction of P , I has no point in P , we also see that every other open interval contains a subinterval of the form of I ; then P contains no open interval.

Now let $x \in P$, and let S be any open interval for which $x \in S$. Let I_n be the closed interval of E_n such that $x \in I_n$. Choose n sufficiently large such that $I_n \subseteq S$. If $x_n \neq x$ is an endpoint of I_n , then $x_n \in P$, and so x is a limit point of P . Therefore P is perfect. ■

Definition. We call the set P constructed in the proof of theorem 2.4.2 the **Cantor set**.

2.5 Connected Sets

Definition. Two subsets A and B of a metric space X are **separated** if $A \cap \hat{B}$ and $\hat{A} \cap B$ are both empty. We say a subset E of X is **connected**, if E is not the union of two nonempty separated sets.

Theorem 2.5.1. *A subset E of \mathbb{R} is connected if and only if $x, y \in E$ and $x < z < y$ imply $z \in E$.*

Proof. Let $x, y \in E$ such that for some $z \in (x, y)$, $z \notin E$. Then $E = A \cup B$, with $A = E \cup (-\infty, z)$ and $B = E \cup (z, \infty)$. Then A and B are separated, which contradicts the connectedness of E .

Conversely suppose for $x, y \in E$, that $z \in E$ for $z \in (x, y)$. Then there are nonempty separated sets A and B such that $A \cup B = E$. Choose $x \in A$, $y \in B$ such that $x < y$, and let $z = \sup(A \cap [x, y])$. Then by theorem 2.2.8, $z \in \hat{A}$, so $z \notin B$. In particular, $x \leq z < y$. Now if $z \notin A$, then $x < z < y$, with $z \notin E$. Now if $z \in A$, then $z \notin \hat{B}$, hence there is a z' such that $z < z' < y$, and $z' \notin B$. Then $x < z' < y$ and $z' \notin E$. ■

Chapter 3

Sequences

3.1 Convergent Sequences

Definition. A sequence $\{x_n\}$ in a metric space X is said to **converge** if there is a point $x \in X$ such that for every $\varepsilon > 0$, there is an $N \in \mathbb{Z}^+$ such that $d(x_n, x) < \varepsilon$ whenever $n \geq N$. We say $\{x_n\}$ **converges** to x , and we call x the **limit** of $\{x_n\}$ as n approaches ∞ . We write $x_n \rightarrow x$ as $n \rightarrow \infty$, and $\lim_{n \rightarrow \infty} x_n = x$ (or $\lim x_n = x$). If $\{x_n\}$ does not converge, we say the $\{x_n\}$ **diverges**, or **is divergent**.

Example 3.1. Consider the following sequences in \mathbb{C} .

$\{\frac{1}{n}\}$ is bounded, and $\lim_{n \rightarrow \infty} \frac{1}{n} = 0$. The sequence $\{n^2\}$ is unbounded and diverges. $1 + \frac{(-1)^n}{n} \rightarrow 1$ as $n \rightarrow \infty$, and $\{1 + \frac{(-1)^n}{n}\}$ is bounded. $\{i^n\}$ is bounded and divergent. $\{1\}$ is bounded and converges to 1.

Theorem 3.1.1. Let $\{x_n\}$ be a sequence in a metric space, then:

$\{x_n\}$ converges to $x \in X$ if and only if every neighborhood of x contains x_n for all but finitely many n . If $\{x_n\}$ converges to x , and x' , then $x = x'$. If $\{x_n\}$ converges, then x_n is bounded. If $E \subseteq X$, and x is a limit point of E , then there is a sequence in E that converges to x .

Proof. Suppose $x_n \rightarrow x$, and let U be a neighborhood of x . For some $\varepsilon > 0$, there is an $N \in \mathbb{Z}^+$ for which $d(x_n, x) < \varepsilon$, whenever $n \geq N$, thus $x_n \in U$ for finitely many n . Conversely, suppose that $x_n \in U$ for some $n \geq N$, then letting $\varepsilon > 0$, we have $d(x, x_n) < \varepsilon$, hence $x_n \rightarrow x$.

Let $\varepsilon > 0$, then there are $N_1, N_2 \in \mathbb{Z}^+$ such that $d(x_n, x) < \frac{\varepsilon}{2}$, and $d(x_n, x') < \frac{\varepsilon}{2}$. Then choosing $N = \max\{N_1, N_2\}$, and letting ε be arbitrarily small, we have $d(x, x') \leq d(x, x_n) + d(x_n, x') < \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon$; and so we get that $x = x'$.

Let $x_n \rightarrow x$, then there is an $N \in \mathbb{Z}^+$ for which $d(x_n, x) < 1$ whenever $n \geq N$. Letting $r = \max\{1, d(x_N, x)\}$, then $d(x_n, x) \leq r$.

Finally, let x be a limit point of E , then for each $n \in \mathbb{Z}^+$, there is an $x_n \in E$ such that $d(x, x_n) < \frac{1}{n}$, choose $N > \frac{1}{\varepsilon}$, then whenever $n \geq N$, $d(x, x_n) < \varepsilon$; hence $x_n \rightarrow x$. ■

Theorem 3.1.2. Suppose $\{x_n\}$ and $\{y_n\}$ are sequences in \mathbb{C} , and that $\lim x_n = x$, $\lim y_n = y$ as $n \rightarrow \infty$. Then the following hold as $n \rightarrow \infty$:

$\lim (x_n + y_n) = \lim x_n + \lim y_n = x + y$. $\lim x_n y_n = \lim x_n \lim y_n = xy$.
 $\lim \frac{x_n}{y_n} = \frac{\lim x_n}{\lim y_n} = \frac{x}{y}$; given that $y_n, y \neq 0$.

2. Proof. [label=(0)]

Let $\varepsilon > 0$, then for $N_1, N_2 \in \mathbb{Z}^+$, $|x_n - x| < \frac{\varepsilon}{2}$ and $|y_n - y| < \frac{\varepsilon}{2}$. Then choose $N = \max\{N_1, N_2\}$, then whenever $n \geq N$, we have $|(x_n + y_n) - (x + y)| \leq |x_n - x| + |y_n - y| < \varepsilon$.

2. Notice that $x_n y_n - xy = (x_n - x)(y_n - y) + x(y_n - y) + y(x_n - x)$, then for $N_1, N_2 \in \mathbb{Z}^+$, $|x_n - x| < \sqrt{\varepsilon}$, and $|y_n - y| < \sqrt{\varepsilon}$. Then choosing $N = \max\{N_1, N_2\}$, then $|(x_n - x)(y_n - y)| < \varepsilon$, thus we have $|x_n y_n - xy| \leq |(x_n - x)(y_n - y)| + |x(y_n - y)| + |y(x_n - x)| < \varepsilon$.
3. We first show that $\frac{1}{y_n} \rightarrow \frac{1}{y}$, given that $y_n, y \neq 0$. Choose m such that $|y_n - y| < \frac{1}{2}|y|$ whenever $n \geq m$, then $|y_n| > \frac{1}{2}|y|$. Then for $\varepsilon > 0$, there is an $N > m$ such that whenever $n \geq N$, $|y_n - y| < \frac{1}{2}|y|^2 \varepsilon$. Then $|\frac{1}{y_n} - \frac{1}{y}| \leq \frac{|y_n - y|}{|y_n y|} < \frac{2}{|y|^2} |y_n - y| < \varepsilon$. Then choosing the sequences $\{x_n\}$ and $\{\frac{1}{y_n}\}$, the rest follows. ■

Corollary. [label=(0)]

1. For any $c \in \mathbb{C}$, and a sequence $x_n \rightarrow x$, we have $\lim c x_n = c \lim x_n = c x$ and $\lim (c + x_n) = c + \lim x_n = c + x$ as $n \rightarrow \infty$.
2. Provided that $x, x_n \neq 0$, we have $\lim \frac{1}{x_n} = \frac{1}{\lim x_n} = \frac{1}{x}$, as $n \rightarrow \infty$.

Proof. We choose $\{x_n\}$ and $\{y_n\} = \{c\}$ for all n , then the results follow. ■

Theorem 3.1.3. [label=(0)]

1. Let $x_n = (\alpha_{1n}, \dots, \alpha_{kn}) \in \mathbb{R}^k$. Then $\{x_n\}$ converges to x if and only if $\lim \alpha_{jn} = \alpha_j$ for $1 \leq j \leq k$, as $n \rightarrow \infty$.
2. Let $\{x_n\}, \{y_n\}$ be sequences in \mathbb{R}^k , and let $\{\beta_n\}$ be a sequence in \mathbb{R} such that $x_n \rightarrow x$, $y_n \rightarrow y$, and $\beta_n \rightarrow \beta$. Then $\lim (x_n + y_n) = x + y$, $\lim x_n y_n = xy$, and $\lim \beta_n x_n = \beta x$.

Proof. If $x_n \rightarrow x$, then $|\alpha_{jn} - \alpha_j| \leq \|x_n - x\| < \varepsilon$, thus $\lim \alpha_{jn} = \alpha_j$. Conversely, suppose that $\alpha_{jn} \rightarrow \alpha_j$. Then for $\varepsilon > 0$ there is an $N \in \mathbb{Z}^+$ such that $n \geq N$ implies $|\alpha_{jn} - \alpha_j| < \frac{\varepsilon}{\sqrt{k}}$. Then for $n \geq N$,

$$\|x_n - x\| = \sqrt{\sum |\alpha_{jn} - \alpha_j|^2} < \varepsilon$$

To prove (2), we apply part (1) of this theorem together with theorem 3.1.2. ■

Theorem 3.1.4 (The Sandwich Theorem). Let $\{x_n\}$, $\{y_n\}$, and $\{w_n\}$ be sequences in \mathbb{R} , and Suppose that $\lim x_n = \lim y_n = a$ and that there is an $N \in \mathbb{Z}^+$ such that $x_n \leq w_n \leq y_n$ for all $n \geq N$. Then $\lim_{n \rightarrow \infty} w_n = a$.

Proof. Let $\varepsilon > 0$ and let $\{x_n\}$ and $\{y_n\}$ both converge to a . Then by definition there are $N_1, N_2 \in \mathbb{Z}^+$ such that $|x_n - a| < \varepsilon$ and $|y_n - a| < \varepsilon$ for $n \geq N_1, N_2$. Now choose $N = \max\{N_0, N_1, N_2\}$, if $n \geq N$, we have $-\varepsilon < x_n - a < \varepsilon$, and we also have $x_n - a < w_n - a < y_n - a$, thus we have that:

$$-\varepsilon < x_n - a < w_n - a < y_n - a < \varepsilon$$

Thus we have that $|w_n - a| < \varepsilon$. ■

Corollary. *If $x_n \rightarrow \infty$ as $n \rightarrow \infty$, and $\{y_n\}$ is bounded, then $x_n y_n \rightarrow 0$ as $n \rightarrow \infty$.*

Proof. We have that $\{y_n\}$ is bounded, hence, there is $M > 0$ such that $|y_n| < M$ for all $n \in \mathbb{Z}^+$. And since $\{x_n\}$ converges to 0 we have that for any ε there is an $N \in \mathbb{Z}^+$ such that for $n \geq N$, $|x_n - 0| < \frac{\varepsilon}{M}$. For $|x_n y_n - 0| = |x_n y_n| < M|x_n| < M \frac{\varepsilon}{M} = \varepsilon$. Therefore, $x_n y_n \rightarrow 0$ as $n \rightarrow \infty$. ■

Corollary. *Let $\{x_n\}, \{y_n\}$ be sequences such that $0 \leq x_n \leq y_n$ for $n \geq N > 0$. Then if $y_n \rightarrow 0$, then $x_n \rightarrow 0$ as $n \rightarrow \infty$.*

Proof. This is a special case of the sandwich theorem. ■

3.2 Subsequences

Definition. Let $\{x_n\}$ be a sequence, and let $\{n_k\} \subset \mathbb{Z}^+$ such that $n_k < n_{k+1}$. We call the sequence $\{x_{n_k}\}$ a **Subsequence** of $\{x_n\}$. If $\{x_{n_k}\}$ converges, we call its limit the **subsequential limit** of $\{x_n\}$.

Theorem 3.2.1. *A sequence $\{x_n\}$ converges to a point x if and only if every subsequence $\{x_{n_k}\}$ converges to x .*

Proof. Clearly if $x_n \rightarrow x$, then every subsequence $x_{n_k} \rightarrow x$, (since subsequences can be thought of as subsets of their parent sequences). On the other hand, let $x_{n_k} \rightarrow x$ for $\{n_k\} \subseteq \mathbb{Z}^+$. Then for $\varepsilon > 0$, there is a $K \in \mathbb{Z}^+$ for which $d(x_{n_k}, x) < \frac{\varepsilon}{2}$ for $k \geq K$. Let $N \in \mathbb{Z}^+$, and choose $n \geq \max\{N, K\}$, then $d(x_n, x) \leq d(x_n, x_{n_k}) + d(x_{n_k}, x) < \varepsilon$. ■

Theorem 3.2.2. *If $\{x_n\}$ is a sequence in a compact metric space X , then some subsequence of $\{x_n\}$ converges to a point x .*

Proof. If $\{x_n\}$ is finite, then there is an $x \in \{x_n\}$ and a sequence $\{n_k\}$ with $n_k < n_{k+1}$ such that $x_{n_i} = x$ for $1 \leq i \leq k$, then the subsequence converges to x .

Now if $\{x_n\}$ is infinite, there is a limit point $x \in X$ of $\{x_n\}$, then choose n_i such that $d(x, x_i) < \frac{1}{i}$ for $1 \leq i \leq k$. Obtaining $\{n_k\}$ from this, we see that $n_k < n_{k+1}$, and so we get that $\{x_{n_k}\}$ converges to x . ■

Corollary. *Every bounded sequence in \mathbb{R}^k contains a convergent subsequence.*

Theorem 3.2.3. *The subsequential limits of $\{x_n\}$ in a metric space X form a closed subset of X .*

Proof. Let E be the set of all subsequential limits of $\{x_n\}$, and let x be a limit point of E . Choose n_i such that $x_{n_i} \neq x$ and let $\delta = d(x, x_{n_i})$, for $1 \leq i \leq k$. Then consider the sequence $\{n_k\}$, since x is a limit point of E , there is an $x' \in E$ for which $d(x, x') < \frac{\delta}{2^i}$. Thus there is an $N_I > n_i$ such that $d(x', x_{n_i}) < \frac{\delta}{2^i}$, thus $d(x, x_{n_i}) < \frac{\delta}{2^i}$. So $\{x_n\}$ converges to x and $x \in E$. ■

3.3 Cauchy Sequences

Definition. We call a sequence $\{x_n\}$ in a metric space X a **Cauchy sequence** in X , or more simply, **Cauchy** in X if for all $\varepsilon > 0$, there is an $N \in \mathbb{Z}^+$ such that $d(x_n, x_m) < \varepsilon$ whenever $m, n \geq N$.

Definition. Let E be a nonempty subset of a metric space X , and let $S \subseteq \mathbb{R}$ be the set of all real numbers $d(x, y)$, with $x, y \in E$. We call $\sup S$ the **diameter** of E , and denote it $\text{diam } E$.

Theorem 3.3.1. Let $\{x_n\}$ be a sequence, and let E_N be the set of all points p_N such that $N < p_{n+1}$. Then $\{x_n\}$ is Cauchy if and only if $\lim \text{diam } E_N = 0$ as $N \rightarrow \infty$.

Proof. Let $\{x_n\}$ be Cauchy. Let $x_{N_1}, x_{N_2} \in E$ such that $d(x_n, x_{N_1}) < \frac{\varepsilon}{2}$, and $d(x_{N_2}, x_m) < \frac{\varepsilon}{2}$. Then we see that $d(x_{N_1}, x_{N_2}) \leq d(x_{N_1}, x_n) + d(x_n, x_{N_2}) < \varepsilon$, so $\{x_{N_k}\}$ is Cauchy and we see that $\lim \text{diam } E_N = 0$. Now suppose that $\lim \text{diam } E_N = 0$, then for any $x_n, x_m \in S$, $d(x_n, 0) < \frac{\varepsilon}{2}$ and $d(0, x_m) < \frac{\varepsilon}{2}$ implies that $d(x_n, x_m) \leq d(x_n, 0) + d(0, x_m) < \varepsilon$, whenever $n, m > N$, for $\varepsilon > 0$. ■

Theorem 3.3.2. [label=(0)]

1. If $E \subseteq X$, then $\text{diam } \hat{E} = \text{diam } E$.
2. If $\{K_n\}$ is a sequence of compact sets in X , such that $K_{n+1} \subseteq K_n$, and if $\lim \text{diam } K_n = 0$ as $n \rightarrow \infty$, then $\bigcap_{i=1}^{\infty} K_i$ contains exactly one point.

Proof. Clearly $\text{diam } E \leq \text{diam } \hat{E}$. Now let $\varepsilon > 0$, and choose $x, y \in \hat{E}$, then there are points $x', y' \in E$ such that $d(x, x') < \frac{\varepsilon}{2}$ and $d(y, y') < \frac{\varepsilon}{2}$. Hence, $d(x, y) \leq d(x, x') + d(x', y') + d(y', y) < \varepsilon \text{diam } E$, then choosing ε arbitrarily small, $\text{diam } \hat{E} \leq \text{diam } E$.

Now, we also have that by the nested interval theorem that $K = \bigcap K_i$ is nonempty. Now suppose that K contains more than one point. then $\text{diam } K > 0$, and since $K \subseteq K_n$ for all n , $\text{diam } K \leq \text{diam } K_n$, a contradiction. Thus K contains exactly one element. ■

Theorem 3.3.3. [label=(0)]

1. In any metric space X , every convergent sequence is a Cauchy sequence.
2. If X is compact, and $\{x_n\}$ is Cauchy in X , then $\{x_n\}$ converges to a point in X .

Proof. [label=(0)]

If $x_n \rightarrow x$, and $\varepsilon > 0$ such that there is an $N \in \mathbb{Z}^+$ such that $d(x_n, x) < \frac{\varepsilon}{2}$ for all $n \geq N$, then for $m \geq N$, we have $d(x_n, x_m) \leq d(x_n, x) + d(x, x_m) < \varepsilon$. Thus $\{x_n\}$ is Cauchy.

2. Let $\{x_n\}$ be Cauchy, and let E_N be the set of all points x_N for which $x_N < x_{N+1}$. Then $\lim \text{diam } \hat{E} = 0$, then being closed in X , each \hat{E}_N is compact in X , and $\hat{E}_{N+1} \subseteq \hat{E}_N$, so by theorem 3.3.2, there is a unique $x \in X$ in all of \hat{E}_N . Now for $\varepsilon > 0$, there is an $N_0 \in \mathbb{Z}^+$ for which $\text{diam } \hat{E} < \varepsilon$. Then for all $x_n \in \hat{E}$, $d(x_n, x) < \varepsilon$ whenever $n \geq N_0$. ■

Corollary (The Cauchy Criterion). *Every Cauchy sequence in \mathbb{R}^k converges to a point in \mathbb{R}^k .*

Proof. Let $\{x_n\}$ be Cauchy in \mathbb{R}^k , define E_N as in (2), then for some $N \in \mathbb{Z}^+$, $\text{diam } E < 1$, and so $\{x_n\}$ is the union of all E_n , and the set of points $\{x_1, \dots, x_{N-1}\}$, so $\{x_n\}$ is bounded, and thus has a compact closure, it follows then that $x_n \rightarrow x$ for some $x \in \mathbb{R}^k$. ■

Definition. We call a metric space **complete** if every Cauchy sequence in the space converges.

Theorem 3.3.4. *All compact metric spaces, and all Euclidean spaces are complete.*

Example 3.2. Consider \mathbb{Q} together with the metric $|x - y|$. The metric space induced on \mathbb{Q} by $|\cdot|$ is not complete.

Definition. A sequence $\{x_n\}$ in \mathbb{R} is said to be **monotonically increasing** if $x_n \leq x_{n+1}$, $\{x_n\}$ is said to be **monotonically decreasing** if $x_{n+1} < x_n$. We call $\{x_n\}$ **monotonic** if it is either monotonically increasing or monotonically decreasing.

Theorem 3.3.5. *A monotonic sequence converges if and only if it is bounded.*

Proof. Suppose, without loss of generality, that $\{x_n\}$ is monotonically increasing. If $\{x_n\}$ is bounded, then $x_n \leq x$, then for all $\varepsilon > 0$, there is an $N \in \mathbb{Z}^+$ for which $x - \varepsilon < x_N \leq x$. Then for $n \geq N$, $x_n \rightarrow x$. The converse follows from theorem 3.1.2. ■

3.4 Upper and Lower Limits.

Let $\{\xi_n\}$ be a sequence in \mathbb{R} such that for all $M > 0$, there is an $N \in \mathbb{Z}^+$ for which $n \geq N$ implies that either $x_n \geq M$, or $x_n \leq -M$. Then we write $x_n \rightarrow \infty$ and $x_n \rightarrow -\infty$, respectively.

Definition. Let $\{x_n\}$ be a sequence in \mathbb{R} , and let E be the set of all extended real numbers x such that $x_{n_k} \rightarrow x$ for some subsequence $\{x_{n_k}\}$. Then E contains all subsequential limits of $\{x_n\}$, and possible $\pm\infty$. We then call $\sup E$ the **upper limit** of E , and $\inf E$ the **lower limit** of E .

Theorem 3.4.1. *Let $\{x_n\}$ be a sequence in \mathbb{R} , and let E be the set of all extended real numbers x , let $s = \sup E$ and $s' = \inf E$. Then the following hold:*

[label=(0)]s, s' \in E. If x \notin E, and x' \notin E, there is an N \in \mathbb{Z}^+ such that n \geq N implies that x' < x_n < x.

2. *Proof.* We prove the theorem for the case of s , since it is analogous for s' .

[label=(0)]If $s = \infty$, then E is not bounded above, so neither is $\{x_n\}$, and there is a subsequence for which $x_n \rightarrow \infty$. Now if $s \in \mathbb{R}$, then E is bounded above, and has at least one subsequential limit. Then $s \in E$. Now if $s = -\infty$, then E contains only $-\infty$, and so by definition $x_n \rightarrow -\infty$. Suppose there is an $x > s$, such that $x_n \geq x$ for all n . Then there is a $y \in E$ such that $y \geq x \geq s$, a contradiction of the definition of s .

■

Example 3.3. [label=(0)]

1. Let $\{x_n\}$ be a sequence in \mathbb{Q} , then every real number is a subsequential limit, and $\limsup x_n = \infty$ and $\liminf x_n = -\infty$.
2. Let $\{x_n\} = \{\frac{(-1)^n}{1+\frac{1}{n}}\}$; then $\limsup x_n = 1$ and $\liminf x_n = -1$ as $n \rightarrow \infty$.
3. For a sequence $\{x_n\}$ in \mathbb{R} , $\lim x_n = x$ if and only if $\limsup x_n = \liminf x_n = x$ as $n \rightarrow \infty$.

Theorem 3.4.2. *If $x_n \leq y_n$, for $n \geq N > 0$, then $\liminf x_n \leq \liminf y_n$ and $\limsup x_n \leq \limsup y_n$ as $n \rightarrow \infty$.*

3.5 Special Sequences

Theorem 3.5.1. *Let $n, p \in \mathbb{Z}^+$. Then the following hold as $n \rightarrow \infty$.*

[label=(0)]

1. $\lim \frac{1}{n^p} = 0$.
2. $\lim \sqrt[p]{n} = 1$.
3. $\lim \sqrt[n]{n} = 1$.
4. If $\alpha \in \mathbb{R}$, then $\lim \frac{n^\alpha}{(1+p)^n} = 0$.
5. If $|x| < 1$, then $\lim x^n = 0$.

Proof. [label=(0)]

Let $n > [p] \frac{1}{\varepsilon}$; then $|\frac{1}{n^p}| < \varepsilon$.

2. If $p = 1$, we are done. If $p > 1$, let $x_n = \sqrt[p]{n} - 1$, then $x_n > 0$. By the binomial theorem, $1 + nx_n \leq (1 + x_n)^p = n$, hence $0 \leq x_n \leq \frac{n-1}{p}$. Now if $1 > p > 0$, then $\frac{1}{p} > 0$, so we notice that $0 \leq \frac{1}{x_n} \leq \frac{1}{\frac{n-1}{p}}$.
3. Let $x_n = \sqrt[n]{n} - 1$, then $x_n \geq 0$, then by the binomial theorem again, $n = (1 + x_n)^n \geq \frac{n(n-1)}{2} x_n^2$, then $0 \leq x_n \leq \sqrt{\frac{2}{n-1}}$.

4. Let $k \in \mathbb{Z}^+$ such that $k > \alpha$. Then $n > 2k$, let $(1+p)^n > \binom{n}{k} p^k > \frac{n^k p^k}{2^k k!}$. So $0 < \frac{n^\alpha}{(1+p)^n} < \frac{2^k k!}{p^k} n^{-k}$, since $\alpha - k < 0$, $n^{\alpha-k} \rightarrow 0$ and we are done.
5. Take $\alpha = 0$, and let $x = \frac{1}{1+p}$, then the result follow. ■

Chapter 4

Series.

4.1 Convergent Series.

Chapter 5

Continuity

5.1 Limits of Functions.

Definition. Let X , and Y be metric spaces, and let $E \subseteq X$, and let $f : E \rightarrow Y$ be a function. We say that f **converges** to a point $q \in Y$, as x **approaches** a limit point $p \in X$ if for every $\varepsilon > 0$, there is a $\delta > 0$ for which $d_Y(f(x), q) < \varepsilon$, whenever $0 < d_X(x, p) < \delta$. We say that q is the **limit** of f at p and we write $f \rightarrow q$ as $x \rightarrow p$, and $\lim_{x \rightarrow p} f(x) = q$, or more simply, $\lim f = q$.

Example 5.1. [label=(0)]

1. Let $X = Y = \mathbb{R}$, under the absolute value $|\cdot|$, and let $I \subseteq \mathbb{R}$ be an interval, and $f : I \rightarrow \mathbb{R}$. Then f has a limit L as x approaches a limit point $c \in \mathbb{R}$ if for every $\varepsilon > 0$, there is a $\delta > 0$ such that $|f(x) - L| < \varepsilon$ whenever $0 < |x - c| < \delta$. We call functions that map into \mathbb{R} **real valued**.
2. Let $X = Y = \mathbb{C}$, under the modulus $|\cdot|$, and let $D \subseteq \mathbb{R}$ be an domain, and $f : D \rightarrow \mathbb{R}$. Then f has a limit L as z approaches a limit point $w \in \mathbb{R}$ if for every $\varepsilon > 0$, there is a $\delta > 0$ such that $|f(x) - L| < \varepsilon$ whenever $0 < |z - w| < \delta$. We call functions that map into \mathbb{C} **complex valued**.
3. Let $X = Y = \mathbb{R}^k$, under the norm $\|\cdot\|$, and let $D \subseteq \mathbb{R}^k$ be an domain, and $f : D \rightarrow \mathbb{R}^k$. Then f has a limit L as x approaches a limit point $c \in \mathbb{R}^k$ if for every $\varepsilon > 0$, there is a $\delta > 0$ such that $\|f(x) - L\| < \varepsilon$ whenever $0 < \|x - c\| < \delta$. We call functions that map into \mathbb{R}^k **vector valued**.

Theorem 5.1.1 (The Sequential Criterion). *Let X and Y be metric spaces, and let $E \subseteq X$, and $f : E \rightarrow Y$ be a function, and $p \in E$ be a limit point. Then $\lim f(x) = q$ as $x \rightarrow p$ if and only if $\lim f(x_n) = q$ as $n \rightarrow \infty$ for any sequence $\{x_n\} \in E$, such that $x_n \neq p$ and $\lim x_n = p$.*

Proof. Suppose that $\lim f(x) = q$ as $x \rightarrow p$, and choose $\{x_n\} \subseteq E$ such that $x_n \neq p$ and $\lim x_n = p$ as $n \rightarrow \infty$. Then for $\varepsilon > 0$, there is a $\delta > 0$ such that $d_Y(f(x), q) < \varepsilon$ whenever $0 < d_X(x, p) < \delta$, and since $d_X(x_n, p) < \delta$ whenever $n \geq N$ for some $N > 0$, we have $d_Y(f(x_n), q) < \varepsilon$ whenever $d_X(x_n, p) < \delta$.

Conversely, suppose that $\lim f \neq q$, that is for some $\varepsilon > 0$, $d_Y(f(x), q) \geq \varepsilon$ whenever $d_X(x, p) < \delta$ for all $\delta > 0$. Then choose $\delta = \frac{1}{n}$, for $n \in \mathbb{Z}^+$, then we have $\lim x_n = p$, but $\lim f(x_n) \neq q$. ■

The importance of the sequential criterion is that it lets us translate theorems about limits of sequences into theorems about limits of functions.

Corollary. *If f has a limit at p , then the limit of f is unique.*

Definition. Letting $f, g : E \rightarrow Y$, we define the **sum**, **product**, **scalar product** and the **quotient** of f and g to be the functions from E into Y :

$$\begin{aligned} f + g(x) &= f(x) + g(x). \quad fg(x) = f(x)g(x). \quad (\lambda f)(x) = \lambda f(x) \text{ for } \lambda \in X. \\ \frac{f}{g}(x) &= \frac{f(x)}{g(x)}, \text{ provided that } g(x) \neq 0. \end{aligned}$$

It is well known that the set of all functions from E into Y form an algebra under these operations.

Theorem 5.1.2. *Let $E \subseteq X$ a metric space, and let $p \in E$ be a limit point. Let $f, g : E \rightarrow Y$ be functions, such that $\lim f = A$ and $\lim g = B$ as $x \rightarrow p$. Then the following hold as $x \rightarrow p$.*

$$\begin{aligned} \lim (f + g) &= \lim f + \lim g = A + B. \quad \lim fg = \lim f \lim g = AB. \quad \lim \frac{f}{g} = \\ &= \frac{\lim f}{\lim g} = \frac{A}{B}, \text{ provided that } B \neq 0. \end{aligned}$$

Corollary. *The following hold:*

$$\begin{aligned} \lim \lambda f &= \lambda \lim f = \lambda A, \text{ and } \lim (\lambda + f) = \lambda + \lim f = \lambda + A. \quad \lim \frac{1}{f} = \\ &= \frac{1}{\lim f} = \frac{1}{A}, \text{ provided that } A \neq 0. \end{aligned}$$

Theorem 5.1.3 (The Sandwich Theorem). *Let f, g , and h be real valued functions defined on \mathbb{R} such that $\lim f = \lim g = A$ as $x \rightarrow p$, and suppose that $f(x) \leq h(x) \leq g(x)$ for all $x \in \mathbb{R}$. Then $\lim h = A$ as $x \rightarrow p$.*

Corollary. *Let f, g be real valued functions defined on \mathbb{R} such that $0 \leq f(x) \leq g(x)$ for all $x \in \mathbb{R}$. Then if $g \rightarrow 0$ as $x \rightarrow p$, then $f \rightarrow 0$.*

The proofs of all these are the result of applying the sequential criterion.

5.2 Continuous Functions.

Definition. Let X and Y be metric spaces and let $p \in E \subseteq X$, and $f : E \rightarrow Y$ be a function. We say that f is **continuous** at p if for every $\varepsilon > 0$, there is a $\delta > 0$ such that $d_Y(f(x), f(p)) < \varepsilon$ whenever $0 < d_X(x, p) < \delta$. If f is continuous at every point in X , we say that f is **continuous on X** .

Theorem 5.2.1. *If $E \subseteq X$ a metric space, and if f is a function defined on X , and $p \in E$ is a limit point, then f is continuous if and only if $\lim f(x) = f(p)$ as $x \rightarrow p$.*

Theorem 5.2.2. *Suppose X, Y , and Z are metric spaces, and that $f : E \rightarrow Y$, $g : Y \rightarrow Z$, are functions (with $E \subseteq X$) such that f is continuous at p and g is continuous at $f(p)$. Then $g \circ f$ is continuous at p .*

2. *Proof.* For every $\varepsilon > 0$, we have $\delta_1, \delta_2 > 0$ such that $d_Y(f(x), f(p)) < \varepsilon$, when $0 < d_X(x, p) < \delta_1$, and $d_Z(g(y), g(f(p))) < \varepsilon$ whenever $d_Y(y, f(p)) < \delta_2$. Then choose $\delta = \min\{\delta_1, \delta_2\}$, and we see that $d_Z(g(f(x)), g(f(p))) < \varepsilon$ whenever $0 < d_X(x, p) < \delta$. ■

Theorem 5.2.3. *A mapping f of a metric space X into a metric space Y is continuous if and only if for every open set $V \subseteq Y$, $f^{-1}(V)$ is open in X .*

Proof. Let f be continuous on X , and let V be open in Y . For $p \in X$, $f(p) \in V$, and since V is open, there is an $\varepsilon > 0$ such that $y \in V$ when $d_Y(y, f(p)) < \varepsilon$. Since f is continuous, there is a $\delta > 0$ such that $d_Y(f(x), f(p)) < \varepsilon$, whenever $0 < d_X(x, p) < \delta$. Thus $f^{-1}(V)$ is open in X .

Conversely, suppose that $f^{-1}(V)$ is open in X for V open in Y . Let $p \in X$ and $\varepsilon > 0$, and let $V = \{y \in Y : d_Y(y, f(p)) < \varepsilon\}$; V is open in Y , so $f^{-1}(V)$ is open in X , thus there is a $\delta > 0$ such that $x \in f^{-1}(V)$ when $0 < d_X(x, p) < \delta$, then $f(x) \in V$, so $d_Y(f(x), f(p)) < \varepsilon$; therefore, f is continuous at p . ■

Corollary. *A mapping f from X into Y is continuous if and only if $f^{-1}(C)$ is closed in X , whenever C is closed in Y .*

Proof. This is the converse of the previous theorem. ■

Theorem 5.2.4. *Let $f, g : X \rightarrow \mathbb{C}$ be continuous complex valued functions defined on a metric space X , then $f + g$, fg , and $\frac{f}{g}$ are continuous.*

Proof. This follows from theorem 5.1.2 and the sequential criterion. ■

Theorem 5.2.5. *Let f_1, \dots, f_k be realvalued functions defined on a metric space X , and define $f : X \rightarrow \mathbb{R}^k$ by $f(x) = (f_1(x), \dots, f_k(x))$ for all $x \in X$. Then f is continuous if and only if f_i is continuous for $1 \leq i \leq k$. Moreover, if $g : X \rightarrow \mathbb{R}^k$ and f are continuous, then so is $f + g$ and fg .*

Proof. Notice that $|f_i(x) - f_i(y)| \leq \|f(x) - f(y)\| = \sqrt{\sum |f_i(x) - f_i(y)|^2}$ for $1 \leq i \leq k$. It follows then that f is continuous if and only if f_i is. Moreover, if $g : X \rightarrow \mathbb{R}^k$ is also continuous, then by the previous theorem, so is $f + g$ and fg . ■

Example 5.2. [label=(0)]

1. Let $x \in \mathbb{R}^k$, define the functions $\phi_i : \mathbb{R}^k \rightarrow \mathbb{R}$ by $\phi_i(x) = x_i$ for all $1 \leq i \leq k$, then ϕ_i is continuous on \mathbb{R}^k
2. The monomials $x_1^{n_1} x_2^{n_2} \dots x_k^{n_k}$, with $n_i \in \mathbb{Z}^+$ for $1 \leq i \leq k$ are continuous on \mathbb{R}^k . So are all constant multiples, thus the polynomial $\sum c_{n_1, \dots, n_k} x_1^{n_1} x_2^{n_2} \dots x_k^{n_k}$ is also continuous on \mathbb{R}^k .
3. We have $|||x| - |y||| \leq \|x - y\|$ for all $x, y \in \mathbb{R}^k$, thus the mapping $x \rightarrow \|x\|$ is continuous on \mathbb{R}^k .

5.3 Continuity and Compactness.

Definition. A mapping $f : E \rightarrow \mathbb{R}^k$ is said to be **bounded** if there is a real number $M > 0$ such that $\|f\| \leq M$ for all $x \in E$.

Theorem 5.3.1. *Let f be a continuous mapping of a compact metric space X into a metric space Y . Then $f(X)$ is compact in Y .*

Proof. Let $\{V_\alpha\}$ be an open cover of $f(X)$, since f is continuous, then $f^{-1}(V_\alpha)$ is open in X , and since X is compact, $X \subseteq \bigcup_{i=1}^n V_{\alpha_i}$, and $f(f^{-1}(E)) \subseteq E$, we have that $f(X) \subseteq \bigcup_{i=1}^n V_{\alpha_i}$. ■

Theorem 5.3.2. *If $f : X \rightarrow \mathbb{R}^k$ is continuous, where X is a compact metric space, then $f(X)$ is closed and bounded; in particular, f is bounded.*

Proof. From theorem 5.3.1, we have that $f(X)$ is compact in \mathbb{R}^k , therefore, it is closed and bounded. ■

Theorem 5.3.3 (The Extreme Value Theorem). *Suppose f is a continuous, realvalued function on a metric space X , and that $M = \sup f$, and $m = \inf f$. Then there exist points $p, q \in X$ such that $f(p) = M$ and $f(q) = m$.*

Proof. By theorem 5.3.2, $f(X)$ is closed and bounded, thus $M, m \in f(X)$. ■

Theorem 5.3.4. *Suppose f is a continuous 1-1 mapping of a compact metric space X onto a metric space Y . Then the inverse mapping $f^{-1} : Y \rightarrow X$ is a Continuous mapping of Y onto X .*

Proof. By theorem 5.2.3, it suffices to show that $f(V)$ is open in Y whenever V is open in X . We have that $X \setminus V$ is closed in X , and compact, thus $f(X \setminus V)$ is closed and compact in Y , thus $f(V) = Y \setminus f(X \setminus V)$ is open in Y . ■

Definition. Let f be a mapping of a metric space X into a metric space Y . We say that f is **uniformly continuous** on X if for every $\varepsilon > 0$, there is a $\delta > 0$ such that $d_Y(f(q), f(p)) < \varepsilon$, for all $p, q \in X$ for which $d_X(p, q) < \delta$.

Lemma 5.3.5. *If f is uniformly continuous, then f is continuous.*

Theorem 5.3.6. *Let f be a continuous mapping of a compact metric space X into a metric space Y . Then f is uniformly continuous on X .*

Proof. Let $\varepsilon > 0$, by the continuity of f , we can associate for each $p \in X$ a number $\phi(p) > 0$ such that for $q \in X$, $d_X(p, q) < \phi(p)$ implies $d_Y(f(p), f(q)) < \frac{1}{2}\phi(p)$. Now let $J(p) = \{q \in X : d_X(p, q) < \phi(p)\}$. Clearly, $p \in J(p)$, so $J(p)$ is an open cover of X , and since X is compact, there are p_1, \dots, p_n for which $X \subseteq \bigcup_{i=1}^n J(p_i)$, then take $\delta = \min\{\phi(p_1), \dots, \phi(p_n)\}$; we have $\delta > 0$. Now let $p, q \in X$ such that $d_X(p, q) < \delta$. Then there is an $m \in \mathbb{Z}^+$ with $1 \leq m \leq n$ such that $p \in J(p_m)$, thus $d_X(p, q) < \frac{1}{2}\phi(p_m)$, by the triangle inequality, we get $d_Y(f(p), f(q)) \leq d_Y(f(p), f(p_m)) + d_Y(f(p_m), f(q)) < \varepsilon$. Thus, f is uniformly continuous. ■

Remark. What this theorem says, is that in any compact metric space, continuity and uniform continuity are equivalent.

Theorem 5.3.7. *Let $E \subseteq \mathbb{R}$ be noncompact, then:*

[label=(0)]There exists a continuous function on E which is not bounded. There is a bounded, continuous function on E which has no maximum. If E is bounded, there exists a continuous function on E that is not uniformly continuous.

2. Proof. Suppose first that E is bounded. Then there is a limit point $x_0 \notin E$ of E . Consider the function

$$f(x) = \frac{1}{x - x_0} \text{ for all } x \in E$$

Then f is continuous on E , but not bounded. Then let $\varepsilon > 0$ and $\delta > 0$, and choose $x \in E$ such that $|x - x_0| < \delta$, then taking t arbitrarily close to x_0 , we can get $|f(x) - f(t)| \geq \varepsilon$, even though $|x - t| < \delta$. Thus f is not uniformly continuous.

Now choose

$$g(x) = \frac{1}{1 + (x - x_0)^2} \text{ for all } x \in E$$

g is continuous, and bounded on E ($0 \leq g \leq 1$), then $\sup g = 1$, and since $g(x) < 1$ for all x , we see that g attains no maximum.

Lastly, suppose that E is unbounded, then the functions $f(x) = x$ and $h(x) = \frac{x^2}{1+x^2}$ for all $x \in E$ establish (1) and (2). ■

Example 5.3. Let f be the mapping of the interval $[0, 2\pi)$ onto the unit circle. That is $f(t) = (\cos t, \sin t)$ for $0 \leq t < 2\pi$. Then f is a continuous 1-1 mapping of $[0, 2\pi)$ onto the unit circle, however, the inverse mapping, f^{-1} fails to be continuous at the point $f(0) = (1, 0)$.

5.4 Continuity and Connectedness.

Theorem 5.4.1. *If f is a continuous mapping of a metric space X into a metric space Y , and if $E \subseteq X$ is Connected, then so is $f(E)$.*

Proof. Suppose that $f(E) = A \cup B$ with $A, B \subseteq Y$ nonempty and separated. Let $G = E \cap f^{-1}(A)$ and $H = E \cap f^{-1}(B)$, then $E = G \cup H$, and G and H are both nonempty. Then since $A \subseteq \overline{A}$, $G \subseteq f^{-1}(\overline{A})$, and since f is continuous, $f^{-1}(\overline{A})$ is closed, so $\overline{G} \subseteq f^{-1}(\overline{A})$, thus $f(\overline{G}) \subseteq \overline{A}$. Since $f(H) = B$, and $\overline{A} \cap B$ is empty, $\overline{G} \cap H$, and $H \cap \overline{H}$ are also empty, which contradicts the connectedness of E . ■

Theorem 5.4.2 (The Intermediate Value Theorem). *Let $f[a, b] \rightarrow \mathbb{R}$ be a realvalued function. If $f(a) < f(b)$, and $c \in \mathbb{R}$ such that $f(a) < c < f(b)$, then there is an $x \in (a, b)$ such that $f(x) = c$.*

Proof. We have that $[a, b]$ is connected in \mathbb{R} , thus by theorem 5.4.1, $f([a, b])$ is connected in \mathbb{R} , hence there is an $x \in (a, b)$ for which $f(x) = c$. ■

Corollary. *If $f : [a, b] \rightarrow \mathbb{R}$ is a realvalued function such that $f(a) < 0 < f(b)$, then there is an $x \in (a, b)$ such that $f(x) = 0$.*

5.5 Discontinuities.

Definition. Let X and Y be metric spaces, and let $f : E \rightarrow Y$ for $E \subseteq X$. If there is a point $x \in E$ for which f is not continuous, we say that f is discontinuous at x , and we say that f has a **discontinuity** at x .

Definition. Let f be defined on (a, b) , and let x be such that $a \leq x < b$. We write $f(x+) = q$ if $f(t_n) \rightarrow q$ for all sequences $\{t_n\}$ in (x, b) such that $t_n \rightarrow x$. Similarly, if $a < x \leq b$, we write $f(x-) = q$ if $f(t_n) \rightarrow q$ for all sequences $\{t_n\}$ in (a, x) such that $t_n \rightarrow x$. We call $f(x+)$ and $f(x-)$ the **right handed limit** and **left handed limit** of f at x respectively, and write $\lim_{t \rightarrow x+} f = f(x+)$ and $\lim_{t \rightarrow x-} f = f(x-)$.

Theorem 5.5.1. If $x \in (a, b)$, then $\lim f$ exists as $t \rightarrow x$ if and only if, $f(x+) = f(x-) = \lim f$.

Proof. Suppose that $\lim f$ exists, by the uniqueness of the limit, and the sequential criterion, we get that $f(x+) = f(x-) = \lim f$. Conversely, suppose that $f(x+) = f(x-) = q$. Then $f(t_n) \rightarrow q$ for all sequences $\{t_n\}$ in (x, b) and (a, x) , then $f(t_n) \rightarrow q$ for all sequences $\{t_n\}$ in (a, b) , thus by the sequential criterion again, $\lim f$ exists, and $\lim f = q$. ■

Definition. Let f be defined on (a, b) . If f is discontinuous at a point x , and $f(x+)$ and $f(x-)$ exists, we say that f has a **removable discontinuity** at x , otherwise, we say the f has an **infinite discontinuity**.

Example 5.4. [label=(0)]

1. The function $f(x) = 1$ for $x \in \mathbb{Q}$ and $f(x) = 0$ for $x \in \mathbb{R} \setminus \mathbb{Q}$ has an infinite discontinuity at every point x .
2. The function $f(x) = x$ for $x \in \mathbb{Q}$ and $f(x) = 0$ for $x \in \mathbb{R} \setminus \mathbb{Q}$ is continuous at $x = 0$, and has an infinite discontinuity at every other point x .
3. The function $f(x) = \sin \frac{1}{x}$ for $x \neq 0$ and $f(x) = 0$ for $x = 0$, has an infinite discontinuity at $x = 0$.
4. The function $f(x) = x + 2$ for $-3 < x < -2$ and $0 \leq x < 1$ and $f(x) = -x - 2$ for $-2 \leq x < 0$ has a removable discontinuity at $x = 0$, and is continuous everywhere else.

Remark. The discontinuities in examples (1) and (2) are the result of \mathbb{Q} and $\mathbb{R} \setminus \mathbb{Q}$ being dense in \mathbb{R} .

5.6 Monotonic Functions.

Definition. Let f be a realvalued function on an interval (a, b) . We say that f is **monotonically increasing** on (a, b) if $a < x < y < b$ implies $f(x) \leq f(y)$. We say that f is **monotonically decreasing** on (a, b) if $a < x < y < b$ implies $f(y) \leq f(x)$. We say f is **monotonic** if it is either monotonically increasing or monotonically decreasing.

Theorem 5.6.1. *Let f be monotonic on (a, b) then $f(x+)$ and $f(x-)$ exist at every point of (a, b) and $\sup f = f(x-)$ and $\inf f = f(x+)$, and the following hold:*

[label=(0)]If f is monotonically increasing $f(x-) \leq f(x) \leq f(x+)$ If f is monotonically decreasing $f(x+) \leq f(x) \leq f(x-)$

(b) *Proof.* We prove only (1), since (2) is analogous. Suppose that f is monotonically increasing, clearly, f has an upperbound A for which $A \leq f$. Now let $\varepsilon > 0$, then there is a $\delta > 0$ for which $a < x - \delta < x$, and $A - \varepsilon < f(x - \delta) \leq A$. Then we have $f(x - \delta) < f(t) \leq A$ for all $x - \delta < t < x$, then we get $|f(t) - A| < \varepsilon$, hence $f(x-) = A$. Similarly, we get $f(+) = -\inf f$. Now since $\sup f \leq f \leq \inf f$, we get the desired result. ■

Corollary. *Monotonic functions have no infinite discontinuities.*

Theorem 5.6.2. *Let f be monotonic on (a, b) , then the set of all points of (a, b) for which f is discontinuous is atmost countable.*

Proof. Suppose, without loss of generality that g is monotonically increasing, and let E be the set of all points of (a, b) for which f is discontinuous. By the density of \mathbb{Q} in \mathbb{R} , for each $x \in E$ associate $r(x) \in \mathbb{Q}$ such that $f(x+) < f(x) < f(x-)$. Since $x_1 < x_2$ implies $f(x_1+) \leq f(x_2-)$, then $r(x_1) \neq r(x_2)$, thus $x_1 \neq x_2$, and so r is a 1-1 mapping of E into \mathbb{Q} . ■

Now, given a countable E in an interval (a, b) , we can construct a monotonic function f that is discontinuous at every point in E and continuous everywhere else. Arrange the points of E into a sequence $\{x_n\}$ and let $\{c_n\}$ be a sequence such that $c_n > 0$ for all $n \in \mathbb{Z}^+$, such that $\sum c_n$ converges. Define $f(x) = \sum_{x_n < x} c_n$, for $x \in (a, b)$. Then we have that

[label=(0)] f is monotonically increasing on (a, b) . f is discontinuous at every point in E with $f(x_n+) - f(x_n-) = c_n$. f is continuous at every point in $(a, b) \setminus E$.

Definition. Let f be a realvalued function defined on an interval (a, b) . We say that f is **continuous from the right** if $f(x+) = f(x)$, and we say f is **continuous from the left** if $f(x-) = f(x)$.

5.7 Infinite Limits and Limits at Infinity.

Definition. For any $c \in \mathbb{R}$, the set of all real numbers x such that $x > c$ is called the **neighborhood of ∞** , and denoted (c, ∞) . The set of all real numbers x such that $x < c$ is called the **neighborhood of $-\infty$** , and denoted $(-\infty, c)$.

Definition. Let $f : E \rightarrow \mathbb{R}$ be a realvalued function. We say that $f(t) \rightarrow A$ as $t \rightarrow x$, with A , and x extended real numbers if for every neighborhood of U A , there is a neighborhood V of x such that $V \cap E$ is nonempty, and $f(t) \in U$ for all $t \neq x \in V \cup E$.

Theorem 5.7.1. *Let $f, g : E \rightarrow \mathbb{R}$ be realvalued functions such that $f \rightarrow A$, and $g \rightarrow B$ as $t \rightarrow x$, for extended real numbers A, B , and x . Then the following hold as $t \rightarrow x$.*

[label=(0)] $f \rightarrow A'$ implies $A = A'$. $f + g \rightarrow A + B$. $fg \rightarrow AB$. $\frac{f}{g} \rightarrow \frac{A}{B}$. Provided that (1), (2), and (3) are not of the forms $\infty - \infty$, $0 \cdot \infty$, $\frac{\infty}{\infty}$, and A_0 , respectively.

2. Proof. This is a direct application of the sequential criterion using the appropriate definition. ■

Chapter 6

Differentiation

6.1 The Derivative of Real valued Functions.

Definition. Let $f : [a, b] \rightarrow \mathbb{R}$ be a realvalued function defined on $[a, b]$. The **derivative** of f at a point $x \in (a, b)$ is the function $f' : (a, b) \rightarrow \mathbb{R}$ defined by

$$f'(x) = \lim_{t \rightarrow x} \frac{f(t) - f(x)}{t - x} \quad (6.1)$$

If f' is defined at $x \in [a, b]$, then we say that f is **differentiable** at x , and if f' is defined for all $x \in (a, b)$, we say that f is **differentiable** on (a, b) .

Theorem 6.1.1. Let $f : [a, b] \rightarrow \mathbb{R}$ be a realvalued function. If f is differentiable at a point $x \in (a, b)$, then f is continuous.

Proof. As $t \rightarrow x$, we get $|f(t) - f(x)| = \left| \frac{f(t) - f(x)}{t - x} \right| |t - x| \rightarrow f'(x) \cdot 0 = 0$, thus $f(t) \rightarrow f(x)$. ■

Theorem 6.1.2. Suppose $f, g : [a, b] \rightarrow \mathbb{R}$ are realvalued functiond differentiable at a point $x \in (a, b)$. Then $f + g$, fg , and $\frac{f}{g}$ are differentiable at x , and as $t \rightarrow x$:

$$[label=(0)](f + g)' = f' + g'. \quad (fg)' = f'g + fg'. \quad \left(\frac{f}{g}\right)' = \frac{f'g - fg'}{g^2}, \text{ provided that } g(x) \neq 0.$$

2. Proof. (1) follows directly from the definiton. Now notice that $fg(t) - fg(x) = f(t)(g(t) - g(x)) + g(t)(f(t) - f(x))$, then dividing by $t - x$, the result follows by definition.

Now also notice that $\frac{\frac{f}{g}(t) - \frac{f}{g}(x)}{t - x} = \frac{1}{g(t)g(x)}(g(x)\frac{f(t) - f(x)}{t - x} - f(x)\frac{g(t) - g(x)}{t - x})$, and the result again follows by definition. ■

Example 6.1. [label=(0)]

1. The derivative of constant functions are always 0, and the derivative of the identity function is always 1.
2. Let $f(x) = x^n$, for $n \in \mathbb{Z}$, and $x \neq 0$ for $n < 0$, then f is differentiable and $f'(x) = nx^{n-1}$.
3. Polynomial functions are differentiable, and so are rational functions $\frac{p}{q}$, provided that $q \neq 0$.

Theorem 6.1.3 (Caratheodory's Theorem). *Let $f : [a, b] \rightarrow \mathbb{R}$ be a continuous realvalued function. Then f is differentiable at a point $x \in (a, b)$ if and only if there is a continuous function $\phi : (a, b) \rightarrow \mathbb{R}$ such that $f(t) - f(x) = \phi(t)(t - x)$; moreover, $\phi = f'$.*

Proof. Suppose f' exists at x , and define $\phi : (a, b) \rightarrow \mathbb{R}$ by $\phi(t) = \frac{f(t)-f(x)}{t-x}$ when $t \neq x$, and $\phi(t) = f'(x)$ at $t = x$. Then by the continuity of f , ϕ is continuous at x , moreover, at $t \neq x$ we see that $f(t) - f(x) = \phi(t)(t - x)$.

Conveersesly, sup[ose there is a ϕ , continuous at x such that $f(t) - f(x) = \phi(t)(t - x)$, then clearly, $\lim \phi = f'(x)$ as $t \rightarrow x$, and since ϕ is continuous, $\phi(x) = f'(x)$. ■

Theorem 6.1.4 (The Chain Rule). *Suppose that $f : [a, b] \rightarrow \mathbb{R}$ and $g : I \rightarrow \mathbb{R}$ are continuous, where $f([a, b]) \subseteq I \subseteq [a, b]$, and suppose that f is differentiable at x , and that g is differentiable at $f(x)$. Then $g \circ f$ is differentiable at x , and $(g \circ f)' = (g' \circ f)f'$.*

Proof. We have by Caratheodory's theorem that $f(t) - f(x) = (t - x)(f'(x) - u(t))$, and $g(s) - g(y) = (s - y)(g'(y) - v(s))$. Then letting $y = f(x)$, and $s \rightarrow y$ as $t \rightarrow x$, we see that $u, v \rightarrow 0$, and we get that $g(f(t)) - g(f(x)) = g'(f(x))f(t) - g'(f(x))f(x)$, dividing by $t - x$ give the desired result. ■

Example 6.2. [label=(0)]

1. Let $f(x) = \sin \frac{1}{x}$ at $x \neq 0$, and $f(x) = 0$ at $x = 0$. We have at $x \neq 0$, that $f'(x) = \sin \frac{1}{x} - \frac{1}{x} \cos \frac{1}{x}$, but at $x = 0$, we must appeal to the definition, and we get $f(t) = \sin \frac{1}{t}$, which diverges at $t \rightarrow 0$, thus $f'(0)$ does not exist.
2. Let $f(x) = x^2 \sin \frac{1}{x}$ at $x \neq 0$, and $f(x) = 0$ at $x = 0$. For $x \neq 0$, we get $f'(x) = 2x \sin \frac{1}{x} - \cos \frac{1}{x}$, and at $x = 0$, we notice that $|t \sin \frac{1}{t}| \leq |t|$, so by the sandwich theorem, $f'(0) = 0$ as $t \rightarrow 0$.

6.2 Mean Value Theorems.

Definition. Let $f : X \rightarrow \mathbb{R}$ be defined on a metric space X . We say that f has a **local maximum** at a point $p \in X$, if there is a $\delta > 0$ for which $f(q) \leq f(p)$ whenever $d(q, p) < \delta$. Likewise f has a **local minimum** at a point $p \in X$, if there is a $\delta > 0$ for which $f(q) \geq f(p)$ whenever $d(q, p) < \delta$. We call local maxima and local minumums **local extrema**.

Theorem 6.2.1. *Let $f : [a, b] \rightarrow \mathbb{R}$ be a realvalued function, and suppose that f has a local extremum at $x \in (a, b)$. If f' exists, then $f'(x) = 0$.*

Proof. Suppose, without loss of generality that f has a local maximum at x . Choosse $\delta > 0$ such that $a < x - \delta < x < x + \delta < b$. Then if $x - \delta < t < x$, we have $|t - x + \delta| < \delta$, so $f(t) \leq f(x)$, thus $\frac{f(t)-f(x)}{t-x} \leq 0$. Similarly, for $x < t < x + \delta$, we get $\frac{f(t)-f(x)}{t-x} \geq 0$, hence, as $t \rightarrow x$, we get $0 \leq f'(0) \leq 0$, thus $f'(x) = 0$. ■

Theorem 6.2.2 (The Generalized Mean Value Theorem). *If $f, g : [a, b] \rightarrow \mathbb{R}$ are continuous on $[a, b]$, and differentiable on (a, b) , then there is a point $x \in (a, b)$ such that $(f(b) - f(a))g'(x) = (g(b) - g(a))f'(x)$.*

Proof. Let $h(t) = (f(b) - f(a))g'(x) - (g(b) - g(a))f'(x)$, for $t \in [a, b]$, then h is continuous on $[a, b]$, and differentiable on (a, b) , moreover, we have $h(b) = f(b)g(a) - f(a)g(b) = h(a)$. Now if h is constant, then $h' = 0$ for all t and we are done. Now suppose that $h(a) < h(b)$, and let $x \in (a, b)$, be a local minimum of h , then $h'(x) = 0$, and we are done; the same result follows for local maxima of h . ■

Corollary (The Mean Value Theorem). *Let $f : [a, b] \rightarrow \mathbb{R}$ be continuous on $[a, b]$, and differentiable on (a, b) . Then there is an $x \in (a, b)$ such that $f(b) - f(a) = (b - a)f'(x)$.*

Proof. Take $g(t) = t$. ■

Theorem 6.2.3. *Suppose that $f : [a, b] \rightarrow \mathbb{R}$ is differentiable on (a, b) . Then the following hold for all $x \in (a, b)$:*

[label=(0)]If $f' \geq 0$, then f is monotonically increasing. If $f' = 0$, then f is constant. If $f' \leq 0$, then f is monotonically decreasing.

2. *Proof.* Let $x_1, x_2 \in (a, b)$, then by the mean value theorem, there is an $x \in (x_1, x_2)$ such that $f(x_2) - f(x_1) = (x_2 - x_1)f'(x)$. Then if $f'(x) = 0$, we get $f(x_2) = f(x_1)$, and that f is constant. If $f'(x) \geq 0$, we get $f(x_2) \geq f(x_1)$, making f monotonically increasing, similarly, if $f'(x) \leq 0$, we get f monotonically decreasing. ■

6.3 The Continuity of Derivatives.

Theorem 6.3.1. *Let $f : [a, b] \rightarrow \mathbb{R}$ be differentiable on all of $[a, b]$, and suppose that $f'(a) < \lambda < f'(b)$. Then there is an $x \in (a, b)$ such that $f'(x) = \lambda$.*

Proof. Let $g(t) = f(t) - \lambda t$, then $g'(a) < 0$ and $g'(b) > 0$. Then for $t_1, t_2 \in (a, b)$, $g(t_1) < g(a)$, and $g(b) < g(t_2)$. Then by the extreme value theorem, g attains a maximum at a point $x \in (t_1, t_2)$, hence $g'(x) = 0$, hence $f'(x) = \lambda$. ■

Corollary. *If $f : [a, b] \rightarrow \mathbb{R}$ is differentiable, then f cannot have any removable discontinuities, nor jump discontinuities.*

Remark. f' may have infinite discontinuities.

6.4 L'Hospital's Rule.

Theorem 6.4.1 (L'Hospital's Rule). *Suppose f and g are realvalued functions differentiable on (a, b) , and that $g' \neq 0$ for all $x \in (a, b)$, where $-\infty \leq a < b \leq \infty$, and suppose that $\frac{f'}{g'} \rightarrow A$ as $x \rightarrow a$. If $f, g \rightarrow 0$, or if $g \rightarrow \pm\infty$, as $x \rightarrow a$, then $\frac{f}{g} \rightarrow A$ as $x \rightarrow a$.*

Proof. Suppose first that $-\infty \leq A < \infty$, and choose $q, r \in \mathbb{R}$ such that $A < r < q$. By hypothesis, there is a $c \in (a, b)$ for which $a, x < c$ implies $\frac{f}{g} < r$. If $a < x < y < c$, then by the generalized mean value theorem, $\frac{f(x) - f(y)}{g(x) - g(y)} = \frac{f'(t)}{g'(t)} < r$, thus letting $x \rightarrow a$, we see that $\frac{f(y)}{g(y)} \leq r < q$. Now suppose, without loss of generality, that $g \rightarrow \infty$. Fixing y , and choosing

$c_1 \in (a, y)$ such that $g(x) > g(y)$, and $g(x) > 0$, if $a < x < c_1$, then $\frac{f(x)}{g(x)} < r - r \frac{g(y)+f(y)}{g(x)}$, then as $x \rightarrow a$, there is a $c_2 \in (x, c_1)$ such that $\frac{f}{g} < q$.

Likewise, if we suppose that $-\infty < A \leq \infty$, by the same reasoning, we can choose a $p < A$ and $c_3 \in (a, b)$ such that $p < \frac{f}{g}$ as $x \rightarrow a$. Since $p < A < q$, by the sandwich theorem, we get $\frac{f}{g} = A$ as $x \rightarrow a$. ■

6.5 Taylor's Theorem.

Definition. If f has a derivative f' on an interval, and f' is differentiable, we denote f'' to be $(f')'$ and call it the **second derivative** of f ; likewise, if f'' is differentiable, we denote the **third derivative** by $f^{(3)} = (f'')'$. More generally, for $n \in \mathbb{Z}^+$, we define recursively the **n th derivative** to be:

[label=(0)]

1. $f^{(0)} = f$ and $f^{(1)} = f'$.
2. $f^{(n+1)} = (f^{(n)})'$, given that $f^{(n)}$ is differentiable.

We call f **n th differentiable** if $f^{(n)}$ exists.

Theorem 6.5.1 (Taylor's Theorem). *Suppose $f : [a, b] \rightarrow \mathbb{R}$ is a realvalued function, that is n th differentiable, and let $n \in \mathbb{Z}^+$ be such that $f^{(n-1)}$ is continuous on $[a, b]$, and that $f^{(n)}$ exists on (a, b) . Let $\alpha, \beta \in [a, b]$ be distinct, and define:*

$$p(t) = \sum_{k=0}^{n-1} \frac{f^{(k)}(\alpha)}{k!} (t - \alpha)^k \quad (6.2)$$

Then there exists a point $x \in (\alpha, \beta)$ such that $f(\beta) = p(\beta) + \frac{f^{(n)}(x)}{n!} (\beta - \alpha)^n$.

Proof. For $n = 1$, this reduces to the mean value theorem, so suppose that $n > 1$. Let $M \in \mathbb{R}$ be such that $f(\beta) = p(\beta) + M(\beta - \alpha)^n$, and let $g(t) = f(t) - p(t) + M(\beta - \alpha)^n$, for $t \in [a, b]$. Then g is n th differentiable, and we get $g^{(n)} = f^{(n)} - n!M$ for $t \in (a, b)$. We wish to show that $f^{(n)} = n!M$.

We have that $p^{(k)} = f^{(k)}(\alpha)$ for $0 \leq k \leq n-1$, then $g(\alpha) = g'(\alpha) = \dots = g^{(n-1)}(\alpha) = 0$, and our choice of M shows that $g(\beta) = 0$. So $g'(x_1) = 0$ for $x_1 \in (\alpha, \beta)$, so by the mean value theorem, since $g'(\alpha) = 0$, then $g''(\xi_2) = 0$ for $x_2 \in (\alpha, x_1)$. Proceeding inductively, we then get that $g^{(n)}(x_n) = 0$ for $x_n \in (\alpha, x_{n-1})$, hence we get that $n!M = f^{(n)}(x)$. ■

Definition. We call the series in equation (5.2) the **Taylor series** (or **Taylor polynomial**) of f about α . We call the realnumber M such that $n!M = f^{(n)}(x)$ the **tail**, (or **error**) of the Taylor series.

6.6 Derivatives of vector valued functions.

Definition. Let $f : [a, b] \rightarrow \mathbb{C}$ be a complex valued function, such that $f(t) = f_1(t) + if_2(t)$. We say that f is **differentiable** at a point x if and only if f_1 and f_2 are differentiable, and we denote the **derivative** of f to be the function $f : (a, b) \rightarrow \mathbb{C}$ such that $f' = f'_1 + if'_2$

Definition. Let $f : [a, b] \rightarrow \mathbb{R}^k$ be a vectorvalued function for $k \in \mathbb{Z}^+$. f is said to be **differentiable** at $x \in (a, b)$ if there is some point $f'(x) \in \mathbb{R}^k$ such that:

$$\lim_{t \rightarrow x} \left\| \frac{f(t) - f(x)}{t - x} - f'(x) \right\| = 0 \quad (6.3)$$

We define the **derivative** of f at x to be the function $f' : (a, b) \rightarrow \mathbb{R}^k$ such that the values of f' satisfy equation (6.3)

Remark. If $f : [a, b] \rightarrow \mathbb{R}^k$ is defined by $f = (f_1, \dots, f_k)$, then f is differentiable at a point $x \in (a, b)$ if and only if f_i is differentiable at x for $1 \leq i \leq k$, and we have that $f' = (f'_1, \dots, f'_k)$.

Theorem 6.1.1 follows naturally, and so does theorem 6.1.2(a) and (2), where we define fg as $\langle f, g \rangle$, however, the mean value theorem in general does not hold.

Example 6.3. [label=(0)]

1. Define $f : \mathbb{R} \rightarrow \mathbb{C}$ by $f(x) = e^{ix} = \cos x + i \sin x$. Then $f(2\pi) - f(0) = 0$, however, $f'(x) = ie^{ix} \neq 0$ for all x (moreover, $|f'| = 1$), so the generalized mean value theorem fails here.
2. Define $f, g : (0, 1) \rightarrow \mathbb{C}$ by $f(x) = x$ and $g(x) = x + x^2 e^{\frac{i}{x^2}}$ for all x . Since $|e^{it}| = 1$, we have that $\lim_{x \rightarrow 0} \frac{f}{g} = 1$ as $x \rightarrow 0$. Now $g'(x) = 1 + (2x - i\frac{2}{x})e^{\frac{i}{x^2}}$ on $(0, 1)$, hence $|g'| = |2x - i\frac{2}{x}| - 1 \geq \frac{2}{x} - 1$, so $|\frac{f'}{g'}| \leq \frac{x}{2-x} \rightarrow 0$ as $x \rightarrow 0$, so L'Hospital's rule fails in \mathbb{C} as well, and hence in \mathbb{R}^2 (as \mathbb{C} is isomorphic to \mathbb{R}^2).

Theorem 6.6.1. Suppose $f : [a, b] \rightarrow \mathbb{R}^k$, for $k \in \mathbb{Z}^+$ is continuous, and that f is differentiable on (a, b) . Then there is an $x \in (a, b)$ for which $\|f(b) - f(a)\| \leq (b - a)\|f'(x)\|$.

Proof. Let $z = f(b) - f(a)$, and define $\phi = \langle f, g \rangle$ for all $t \in [a, b]$, then ϕ is a realvalued function continuous on $[a, b]$, moreover it is differentiable on (a, b) ; therefore, by the mean value theorem, $\phi(b) - \phi(a) = (b - a)\phi'(a) = (b - a)\langle z, f'(x) \rangle$ for $x \in (a, b)$. On the other hand, we have that $\phi(b) - \phi(a) = \langle z, z \rangle = \|z\|^2$, hence, by the Cauchy Schwarz inequality, we have that $\|z\|^2 = (b - a)\langle z, f' \rangle \leq \|z\|\|f'\|$, which gives the desired result. ■

Chapter 7

Integration

7.1 The Riemann-Stieltjes Integral.

Definition. Let $[a, b]$ be an interval. A **partition** of $[a, b]$ is a set of points $P = \{x_0, x_1, \dots, x_n\}$ such that $a = x_0 < x_1 < \dots < x_n = b$, and we write $\Delta x_i = x_i - x_{i-1}$. Now let $f : [a, b] \rightarrow \mathbb{R}$ be a bounded realvalued function, and for each partition P of $[a, b]$ let $M_i = \sup f$ and $m_i = \inf f$ for all $x_{i-1} \leq x \leq x_i$. We define the **upper Riemann sum** and the **lower Riemann sum** to of f with respect to be:

$$U(f, P) = \sum_{i=1}^n M_i \Delta x_i \quad (7.1)$$

$$L(f, P) = \sum_{i=1}^n m_i \Delta x_i \quad (7.2)$$

respectively. We also define the **upper Riemann integral** and the **lower Riemann integral** of f over $[a, b]$ to be:

$$\overline{\int_a^b} f(x) dx = \inf U(f, P) \quad (7.3)$$

$$\underline{\int_a^b} f(x) dx = \sup L(f, P) \quad (7.4)$$

Respectively.

If $\overline{\int_a^b} f = \underline{\int_a^b} f$, then we say that f is **Riemann integrable** on $[a, b]$, and we its value the **Riemann integral**, and denote it to be:

$$\int_a^b f(x) dx = \overline{\int_a^b} f(x) dx = \underline{\int_a^b} f(x) dx \quad (7.5)$$

Lemma 7.1.1. $\overline{\int_a^b} f$, and $\underline{\int_a^b} f$ are defined for every bounded realvalued function f over $[a, b]$.

Proof. Let f be bounded on $[a, b]$, then there are m and M such that $m \leq f \leq M$ for all $a \leq x \leq b$. Now let P be a partition of $[a, b]$. Since $\inf f \leq \sup f$, we have that $m \leq m_i = \inf f \leq M_i = \sup f \leq M$, thus $m(b-a) \leq L(f, P) \leq U(f, P) \leq M(b-a)$, hence L and U form a bounded set, and we are done. ■

Corollary. $L(f, P) \leq U(f, P)$ for every bounded function f .

Now the question of the integrability of f is a very delicate matter, and requires a closer scrutiny on the concepts of upper and lower sums. Infact, it turns out that the Riemann integral is a consequence of a more general class of integrals. Developng this more general situation will allow us to discern facts about the Riemann integral.

Definition. Let α be a bounded monotonically increasing function on $[a, b]$, and let P be a partition of $[a, b]$ and let $\Delta\alpha_i = \alpha(x_i) - \alpha(x_{i-1})$. For any realvalued, bounded function on $[a, b]$, defined the **upper sum** and the **lower sum** of f with respect to P and α to be:

$$U(f, P, \alpha) = \sum_{i=1}^n M_i \Delta\alpha_i \quad (7.6)$$

$$L(f, P, \alpha) = \sum_{i=1}^n m_i \Delta\alpha_i \quad (7.7)$$

Where $M_i = \sup f$ and $m_i = \inf f$ for all $x_{i-1} \leq x \leq x_i$, and again, define the **upper integral** and **lower integral** of f with respect to α on $[a, b]$ to be:

$$\overline{\int_a^b} f(x) d\alpha = \inf U(f, P, \alpha) \quad (7.8)$$

$$\underline{\int_a^b} f(x) d\alpha = \sup L(f, P, \alpha) \quad (7.9)$$

If $\overline{\int_a^b} f d\alpha = \underline{\int_a^b} f d\alpha$, we call the value:

$$\int_a^b f(x) d\alpha = \overline{\int_a^b} f(x) d\alpha = \underline{\int_a^b} f(x) d\alpha \quad (7.10)$$

the **Riemann-Stieltjes integral** of f with respect to α on $[a, b]$. If such an integra exists, we say that f is **integrable** with respect to α on $[a, b]$.

Example 7.1. Let $\alpha(x) = x$, be defined over $[a, b]$. Then α is monotonically increasing, and our definitions reduces to those for the Riemann integral. Here $U(f, P, x) = U(f, P)$ and $L(f, P, x) = L(f, P)$.

We are now in a position to investigate the properties of integrability, in the Riemann-Stieltjes sense.

Definition. Let $[a, b]$ be an interval, and let P and Q be partitions of $[a, b]$. We say that Q is a **refinement** of P if PQ , and we also say that Q is **finer** than P . Now if neither P nor Q is a refinement of the other, we say that the two partitions are **noncomparable**.

Lemma 7.1.2. *Let P and Q be partitions of an interval $[a, b]$, then $P \cup Q$ is a partition of $[a, b]$, and is a refinement of both P and Q .*

Proof. If P is a refinement of Q , or viceversa, then we are done; so suppose that P and Q are noncomparable. Let $P = \{x_0, x_1, \dots, x_n\}$ and $Q = \{y_0, y_1, \dots, y_m\}$ with $a = x_0 < x_1 < \dots < x_n = b$ and $a = y_0 < y_1 < \dots < y_m = b$. Then $P \cup Q = \{x_0, y_0, x_1, y_1, \dots, x_n, y_m\}$ and $a = x_0 = y_0 < x_1, y_1 < \dots < x_n = y_m = b$, thus $P \cup Q$ is a partition of $[a, b]$, that it is a refinement of P and Q follows trivially. ■

Theorem 7.1.3. *Let α be monotonically increasing, and bounded on $[a, b]$, and let P and Q be partitions of $[a, b]$. If Q is a refinement of P , then $L(f, P, \alpha) \leq L(f, Q, \alpha)$ and $U(f, Q, \alpha) \leq U(f, P, \alpha)$.*

Proof. Let $Q = P \cup \{x'\}$ and suppose that $x_{i-1} \leq x' \leq x_i$. Let $w_1 = \inf f$ for $x_{i-1} \leq x \leq x'$ and let $w_2 = \inf f$ for $x' \leq x \leq x_i$. Then $m_i \leq w_1, w_2$, thus $L(f, Q, \alpha) - L(f, P, \alpha) = (w_1 - m_i)(\alpha(b) - \alpha(a)) - (w_2 - m_i)(\alpha(b) - \alpha(a)) \geq 0$, we are done. The proof is analogous for U . ■

Corollary. *$L(f, P, \alpha)$ is monotonically increasing and $U(f, P, \alpha)$ is monotonically decreasing.*

Proof. We note that if Q is a refinement of P , then $|P| \leq |Q|$, the result follows by direct application. ■

Remark. If Q contains k more points than P , we can repeat the proof inductively.

Theorem 7.1.4. $\int f d\alpha \leq \bar{\int} f d\alpha$.

Proof. Let $P = P_1 \cup P_2$ for partitions P_1 and P_2 of $[a, b]$. By theorem 7.1.3 and lemma 7.1.1, we have:

$$L(f, P_1, \alpha) \leq L(f, P_2, \alpha) \leq U(f, P_2, \alpha) \leq U(f, P_1, \alpha) \quad (7.11)$$

Fixing P_2 and taking the supremum over all P_1 , we get $\int f \leq U(f, P_2, \alpha)$, the infimum over P_2 we get $\int f \leq \bar{\int} f$ ■

Theorem 7.1.5. *A realvalued function f is integrable over an interval $[a, b]$ if and only if for $\varepsilon > 0$, there is a partition P such that:*

$$U(f, P, \alpha) - L(f, P, \alpha) < \varepsilon \quad (7.12)$$

Proof. For every P , we have that $L(f, P, \alpha) \leq \int f \leq \bar{\int} f \leq U(f, P, \alpha)$, so if for $\varepsilon > 0$, we assume that $U(f, P, \alpha) - L(f, P, \alpha) < \varepsilon$, then we get that:

$$0 \leq \bar{\int}_a^b f d\alpha - \int_a^b f d\alpha < \varepsilon \quad (7.13)$$

implying integrability for small enough ε .

Conversely, suppose that $\bar{\int} f = \int f$. Let $\varepsilon > 0$. Then there are partitions P_1 and P_2 such that $U(f, P_2, \alpha) - \int f < \frac{\varepsilon}{2}$ and $\int f - L(f, P_1, \alpha) < \frac{\varepsilon}{2}$. Take $P = P_1 \cup P_2$, then by theorem 7.1.4, adding the inequalities we get $U(f, P, \alpha) - L(f, P, \alpha) < \varepsilon$. ■

Theorem 7.1.6. *The following hold:*

[label=(0)]If $U(f, P, \alpha) - L(f, P, \alpha) < \varepsilon$ for some $\varepsilon > 0$ and some P , then it holds, with the same ε , for every refinement of P . If $U(f, P, \alpha) - L(f, P, \alpha) < \varepsilon$ for $P = \{x_0, \dots, x_n\}$, and if $s_i, t_i \in [x_{i-1}, x_i]$, then:

$$\sum_{i=1}^n |f(s_i) - f(t_i)| \Delta \alpha_i < \varepsilon \quad (7.14)$$

If f is integrable with respect to α on $[a, b]$, and (2) holds, then:

$$\left| \sum_{i=1}^n f(t_i) \Delta \alpha_i - \int_a^b f d\alpha \right| < \varepsilon \quad (7.15)$$

2. Proof. [label=(0)]

Theorem 7.1.3 implies this.

2. If $U(f, P, \alpha) - L(f, P, \alpha) < \varepsilon$, we have that $f(s_i), f(t_i) \in [m_i, M_i]$, hence $|f(s_i) - f(t_i)| \leq M_i - m_i$, thus we get that $\sum |f(s_i) - f(t_i)| \Delta \alpha_i \leq U(f, P, \alpha) - L(f, P, \alpha) < \varepsilon$
3. We have $L(f, P, \alpha) \leq \sum f(t_i) \Delta \alpha_i \leq U(f, P, \alpha)$, and $L(f, P, \alpha) \leq \int f d\alpha_i \leq U(f, P, \alpha)$, taking differences, we get the following. ■

Theorem 7.1.7. *If f is continuous on $[a, b]$, then f is integrable with respect to α on $[a, b]$.*

Proof. Let $\varepsilon > 0$, and choose $\xi > 0$ such that $(\alpha(b) - \alpha(a))\xi < \varepsilon$. Now we have that f is uniformly continuous on $[a, b]$, so there is a $\delta > 0$ such that $|f(x) - f(t)| < \xi$ whenever $|x - t| < \delta$ for $x, t \in [a, b]$. Now since P is a partition of $[a, b]$, with $\Delta x_i < \delta$ for all i , then we have $M_i - m_i \leq \xi$ for $i = 1, \dots, n$ thus $U(f, P, \alpha) - L(f, P, \alpha) = \sum (M_i - m_i) \Delta \alpha_i \leq \xi(\alpha(b) - \alpha(a)) < \varepsilon$, therefore, f is integrable. ■

Theorem 7.1.8. *If f is monotonic on $[a, b]$, and α is monotonic and continuous on $[a, b]$, then f is integrable with respect to α on $[a, b]$.*

Proof. Let $\varepsilon > 0$, and for $n > 0$, construct a partition P such that $\Delta \alpha_i = \frac{\alpha(b) - \alpha(a)}{n}$ for $1 \leq i \leq n$, which is guaranteed by the intermediate value theorem.

Now suppose without loss of generality that f is monoton increasing, then $M_f(x_i)$ and $m_i = f(x_{i-1})$ by the extreme value theorem, Then:

$$U(f, P, \alpha) - L(f, P, \alpha) = \frac{\alpha(b) - \alpha(a)}{n} \sum f(x_i) - f(x_{i-1}) = \frac{\alpha(b) - \alpha(a)}{n} (f(b) - f(a)) < \varepsilon$$

Taking n large enough implies integrability. ■

Theorem 7.1.9. *Suppose that f is bounded on $[a, b]$, with only finitely many discontinuities on $[a, b]$. Suppose that α is continuous at every discontinuity of f , then f is integrable with respect to α on $[a, b]$.*

Proof. Let $\varepsilon > 0$ and $M = \sup |f|$ and let E be the set of all discontinuities of f . Since E is finite, and α is continuous on E , then E can be covered by finitely many disjoint intervals $[u_j, v_j] \subseteq [a, b]$ such that $\sum \alpha(u_j) - \alpha(v_j) < \varepsilon$.

Now suppose that we construct these intervals in such a way that every point of $E \cap [a, b]$ lies in (u_j, v_j) , for some j . Taking $K = [a, b] \setminus (u_j, v_j)$, K is compact, so f is uniformly continuous on K . Thus there is a $\delta > 0$ such that $|f(s) - f(t)| < \varepsilon$ whenever $|s - t| < \delta$ for $s, t \in K$.

Now construct the partition P of $[a, b]$ such that $u_j, v_j \in P$, but $(u_j, v_j) \not\subseteq P$ for some j . If $x_i \neq u_j$, then $\Delta x_i < \delta$. Notice that $M_i - m_i \leq 2M$ for all i and that $M_i - m_i \leq \varepsilon$. Thus for ε small enough, we have $U(f, P, \alpha) - L(f, P, \alpha) \leq (\alpha(b) - \alpha(a))\varepsilon + 2M\varepsilon$, thus f is integrable. ■

Theorem 7.1.10. *Suppose that f is integrable with respect to α on an interval $[a, b]$, and that $m \leq f \leq M$, and let ϕ be continuous on $[m, M]$, and let $h = \phi \circ f$ be defined on $[a, b]$. Then h is integrable with respect to α on $[a, b]$.*

Proof. Let $\varepsilon > 0$. We have that ϕ is uniformly continuous on $[m, M]$, so there is a $\varepsilon > \delta > 0$ for which $|\phi(s) - \phi(t)| < \varepsilon$ whenever $|s - t| < \delta$, for $s, t \in [m, M]$.

Now since f is integrable, there is a partition P of $[a, b]$ such that $U(f, P, \alpha) - L(f, P, \alpha) < \delta^2$. Let $M_i = \sup f$, $m_i = \inf f$ and $M'_i = \sup h$, $m'_i = \inf h$ for all $x_{i-1} \leq x \leq x_i$. Now divide $\{1, \dots, n\}$ into two sets A and B such that $i \in A$ if $M_i - m_i < \delta$ and $i \in B$ if $M_i - m_i > \delta$ (then A and B are disjoint). Then for $i \in A$, we get $M'_i - m'_i \leq \varepsilon$, and for $i \in B$, we get $M'_i - m'_i \leq 2K$ with $K = \sup |\phi|$ for $m \leq t \leq M$.

$$\delta \sum_{i \in B} \Delta \alpha_i \leq \sum_{i \in B} (M_i - m_i) \Delta \alpha_i < \delta^2$$

so $\sum \Delta \alpha_i < \delta$. Then

$$\begin{aligned} U(h, P, \alpha) - L(h, P, \alpha) &= \sum_{i \in A} (M'_i - m'_i) \Delta \alpha_i + \sum_{i \in B} (M'_i - m'_i) \Delta \alpha_i \\ &\leq \varepsilon(\alpha(b) - \alpha(a)) + 2K\delta \\ &< \varepsilon(\alpha(b) - \alpha(a) + 2K) \end{aligned}$$

Then for ε small enough, we get that h is integrable. ■

7.2 Properties of the Integral.

Theorem 7.2.1. *Let f and g be realvalued functions integrable with respect to α over an interval $[a, b]$. Then:*

[label=(0)]

1. $f + g$ and cf

$$\int_a^b f + g d\alpha = \int_a^b f d\alpha + \int_a^b g d\alpha \quad (7.16)$$

2. If $f \leq g$ on $[a, b]$, then:

$$\int_a^b f d\alpha \leq \int_a^b g d\alpha \quad (7.17)$$

3. If $c \in (a, b)$ and f then:

$$\int_a^c f d\alpha + \int_c^b f d\alpha = \int_a^b f d\alpha \quad (7.18)$$

4. If $|f| \leq M$ on $[a, b]$, then:

$$\left| \int_a^c f d\alpha \right| \leq M(\alpha(b) - \alpha(a)) \quad (7.19)$$

5. If f is intergrable with respect to α_1 , and α_2 on $[a, b]$, and $c > 0$, then:

$$\int_a^b f d(\alpha_1 + \alpha_2) = \int_a^b f d\alpha_1 + \int_a^b f d\alpha_2 \quad (7.20)$$

Proof. [label=(0)]

Let P be a partition of $[a, b]$, then $L(f, P, \alpha) + L(f, P, \alpha) \leq L(f + g, P, \alpha) \leq U(f + g, P, \alpha) \leq U(f, P, \alpha) + U(g, P, \alpha)$. Now let $\varepsilon > 0$, there are partitions P_1, P_2 , with $P = P_1 \cup P_2$ such that $U(f, P_1, \alpha) - L(f, P_1, \alpha) < \frac{\varepsilon}{2}$, and $U(g, P_2, \alpha) - L(g, P_2, \alpha) < \frac{\varepsilon}{2}$. Then we get $U(f + g, P, \alpha) - L(f + g, P, \alpha) < \varepsilon$, so $f + g$ is intergrable. Moreover, we have that $U(f, P, \alpha) < \int f + \frac{\varepsilon}{2}$ which guarantees $\int f + g \leq \int f + \int g$. Doing the same with L , we get $\int f + \int g \leq \int f + g$, and we are done.

2. If $f \leq g$, then $0 \leq g - f$, and we have by part (1) that $g - f$ is intergrable, and that $0 \leq \int g - f = \int g - \int f$, wich gives us the established inequality.

3. Let P_1 be a ppartition of $[a, c]$, and let P_2 be a partition of $[c, b]$, and let $P = P_1 \cup P_2$ be a partition of $[a, b]$. Since f is intergrable on $[a, b]$, there is an $\varepsilon > 0$ such that $U(f, P, \alpha) - L(f, P, \alpha) < \varepsilon$, by theorem 7.1.3, we have that $L(f, P_1, \alpha) \leq L(f, P, \alpha) \leq U(f, P, \alpha) \leq U(f, P_1, \alpha)$ and $L(f, P_2, \alpha) \leq L(f, P, \alpha) \leq U(f, P, \alpha) \leq U(f, P_2, \alpha)$, thus we get $U(f, P_1, \alpha) - L(f, P_2, \alpha) < \varepsilon$ and $U(f, P_2, \alpha) - L(f, P, \alpha) < \varepsilon$, thus f is integrable on $[a, c]$ and on $[c, b]$.

Now we have that $U(f, P_1, \alpha) < \int_a^c f + \frac{\varepsilon}{2}$ and $\int_c^b f + \frac{\varepsilon}{2}$, so $\int_a^b f \leq \int_a^c f + \int_c^b f$. With L we get the reverse inequality, and we are done.

4. We have that $-M \leq f \leq M$, now let P be a partition of $[a, b]$, and let $\varepsilon > 0$. Since f is integrable, we have that

$$-M(\alpha(b) - \alpha(a)) \leq U(f, P, \alpha) - L(f, P, \alpha) < \varepsilon \leq M(\alpha(b) - \alpha(a)) \quad (7.21)$$

which goves us for arbitrarily small ε , $|\int f| \leq M(\alpha(b) - \alpha(a))$.

5. Let P_1 and P_2 be partitions of $[a, b]$, respective to α_1 and α_2 , and construct $P = P_1 \cup P_2$ respective to $\alpha_1 + \alpha_2$. We have that $U(f, P_1, \alpha_1) - L(f, P_1, \alpha_1) < \frac{\varepsilon}{2}$ and $U(f, P_2, \alpha_2) - L(f, P_2, \alpha_2) < \frac{\varepsilon}{2}$, then we have by the previous inequalities that:

$$U(f, P, \alpha_1 + \alpha_2) - L(f, P, \alpha_1 + \alpha_2) \leq (U(f, P_1, \alpha_1) + U(f, P_2, \alpha_2)) - (L(f, P_1, \alpha_1) + L(f, P_2, \alpha_2)) < \varepsilon$$

Thus, f is integrable with respect to $\alpha_1 + \alpha_2$. Now again, by the similar reasoning used in parts (1) and (3), we get that $\int f d(\alpha_1 + \alpha_2) = \int f d\alpha_1 + \int f d\alpha_2$. ■

Corollary. $\int c f d\alpha = c \int f d\alpha$ and $\int f d(c\alpha) = c \int f d\alpha$

Theorem 7.2.2. *If f and g are integrable with respect to α on an interval $[a, b]$, then:*

[label=(0)] fg is integrable with respect to α on $[a, b]$. $|f|$ is integrable with respect to α on $[a, b]$ and:

$$\left| \int_a^b f d\alpha \right| \leq \int_a^b |f| d\alpha \quad (7.22)$$

2. *Proof.* [label=(0)]

Take $\phi(t) = t^2$, then by theorem 7.1.10, $\phi \circ f = f^2$ is integrable; then notice that $4fg = (f+g)^2 - (f-g)^2$ is integrable, hence, so is fg .

2. Take $\phi(t) = |t|$, then again by theorem 7.1.10, $\phi \circ f = |f|$ is integrable. Furthermore, choose $c = \pm 1$ such that $0 \leq c \int f$, since $cf \leq |f|$, we have that $|\int f| = c \int f = \int cf \leq \int |f|$. ■

Definition. We define the **unit step function** $I : \mathbb{R} \rightarrow \{0, 1\}$ to be $I(x) = 1$ if $x > 0$ and $I(x) = 0$ if $x \leq 0$.

Theorem 7.2.3. *If $s \in (a, b)$, and f is bounded on $[a, b]$ and continuous at s , and if $\alpha(x) = I(x - s)$, then $\int f = f(s)$.*

Proof. Let $P = \{x_0, x_1, x_2, x_3\}$ be a partition of $[a, b]$, such that $a = x_0 < s = x_1 < x_2 < x_3 = b$. Then $U(f, P, \alpha) = M_2$ and $L(f, P, \alpha) = m_2$. Now since f is continuous, $M_2, m_2 \rightarrow f(s)$ as $x_2 \rightarrow s$, and we are done. ■

Theorem 7.2.4. *Suppose that α is monotonically increasing, and differentiable on an interval $[a, b]$, and suppose that α' is Riemann integrable on $[a, b]$. Let f be a bounded realvalued function on $[a, b]$, then f is integrable with respect to α on $[a, b]$ if and only if $f\alpha'$ is Riemann integrable.*

Proof. Let $\varepsilon > 0$, and let P be a partition of $[a, b]$ such that $U(\alpha', P) - L(\alpha', P) < \varepsilon$. By the mean value theorem, there is a $t_i \in [x_{i-1}, x_i]$ for which $\Delta\alpha_i = \alpha'(t_i)\Delta x_i$, for $1 \leq i \leq n$. Now if $s_i \in [x_{i-1}, x_i]$, then $\sum |\alpha'(s_i) - \alpha'(t_i)|\Delta x_i < \varepsilon$, and by theorem 7.1.6, with $M = \sup |f|$, since $\sum f(s_i)\Delta\alpha_i = \sum f(s_i)\alpha'(t_i)\Delta x_i$, we get

$$\left| \sum f(s_i)\Delta\alpha_i - \sum f(s_i)\alpha'(t_i)\Delta x_i \right| \leq M\varepsilon$$

in particular, $\sum f(s_i)\Delta\alpha_i \leq U(f, \alpha', P) + M\varepsilon$, hence we get $U(f, P, \alpha) \leq U(f\alpha', P) + M\varepsilon$, hence we have:

$$\left| \overline{\int} f d\alpha - \overline{\int} f\alpha' dx \right| \leq M\varepsilon$$

for small enough ε , $\overline{\int} f d\alpha = \overline{\int} f\alpha' dx$. We get an analogous result for lower sums. ■

Remark. Taking α to be a step function allows us to reduce the integral to be a finite or infinite series; similarly, if the derivative of α (if it exists) is integrable, then the Riemann-Stielhes integral reduces to just the Riemann integral.

Theorem 7.2.5 (Change of Variables). *Of ϕ is a strictly increasing continuous function, mapping the interval $[A, B]$ onto the interval $[a, b]$, and if α is monotonically increasing on $[a, b]$, and if f is integrable with respect to α on $[a, b]$, define β and g on $[a, b]$ by $\beta = \alpha \circ \phi$ and $g = f \circ \phi$, then g is integrable with respect to β on $[A, B]$, and*

$$\int_A^B g d\beta = \int_a^b f d\alpha \quad (7.23)$$

Proof. For each partition P of $[a, b]$, construct a partition Q of $[A, B]$ such that $x_i = \phi(y_i)$. Then the values of f on $[x_{i-1}, x_i]$ are the same as the values of g on $[y_{i-1}, y_i]$. Then $U(g, Q, \beta) = U(f, P, \alpha)$ and $L(g, Q, \beta) = L(f, P, \alpha)$. It follows that since f is integrable, then $U(g, Q, \beta) - L(g, Q, \beta) < \varepsilon$ for $\varepsilon > 0$, thus g is integrable; and the equality is established by the equality of their sums. ■

Corollary. *Let $\alpha(x) = x$ and $\beta = \phi$, and suppose that ϕ' is Riemann integrable on $[A, B]$. Then:*

$$\int_a^b f dx = \int_A^B (f \circ \phi) \phi' dy \quad (7.24)$$

7.3 Integration and Differentiation.

Theorem 7.3.1. *Let f be Riemann integrable on an interval $[a, b]$, and for $a \leq x \leq b$, let $F(x) = \int_a^x f(t) dt$, then F is continuous on $[a, b]$. Furthermore, if f is continuous at $x_0 \in [a, b]$, then F is differentiable at x_0 and $F'(x_0) = f(x_0)$.*

Proof. We have that f is bounded, so for some $a \leq t \leq b$, we have $|f| \leq M$. Now if $a \leq x < y \leq b$, then $|F(y) - F(x)| = |\int_x^y f(t) dt| \leq M(y - x)$.

Now given $\varepsilon > 0$, we see that $|F(y) - f(x)| < \varepsilon$, whenever $|y - x| < \frac{\varepsilon}{M}$. Thus f is continuous at x_0 . Let $\varepsilon > 0$ and $\delta > 0$ such that $|f(t) - f(x_0)| < \varepsilon$ whenever $|t - x_0| < \delta$ whenever $a \leq t \leq b$. Thus if $x_0 - \delta < s \leq x_0 \leq t < x_0 + \delta$, and $a \leq s < t \leq b$, then:

$$\left| \frac{F(s) - F(t)}{s - t} \right| = \left| \frac{\int_x^y f(u) - f(x_0) du}{s - t} \right| < \varepsilon$$

thus, we get $F'(x_0) = f(x_0)$. ■

Theorem 7.3.2 (The Fundamental Theorem of Calculus). *If f is Riemann integrable on $[a, b]$, and if there is a differentiable function F on $[a, b]$ such that $F' = f$, then:*

$$\int_a^b f(x) dx = F(b) - F(a) \quad (7.25)$$

Proof. Let $\varepsilon > 0$, and construct a partition P of $[a, b]$ such that $U(f, P) - L(f, P) < \varepsilon$. Then by the mean value theorem, there is a $t_i \in [x_{i-1}, x_i]$ such that $F(x_i) - F(x_{i-1}) = f(t_i)\Delta x_i$, for $1 \leq i \leq n$. Taking sums, we have

$$\sum f(t_i)\Delta x_i = F(b) - F(a) \quad (7.26)$$

thus, by theorem 7.1.6, we have:

$$\left| \int_a^b f(x)dx - (F(b) - F(a)) \right| < \varepsilon.$$

■

Theorem 7.3.3 (Integration by Parts). *Let F and G be differentiable functions on $[a, b]$, and let $F' = f$ and $G' = g$ be Riemann integrable on $[a, b]$. Then:*

$$\int_a^b Fg(x)dx = FG(b) - FG(a) - \int_a^b fG(x)dx \quad (7.27)$$

Proof. By theorem 7.2.2, FG is Riemann integrable, and also notice that $(FG)' = Fg + fG$, thus by the fundamental theorem of calculus:

$$\int_a^b FGdx = \int_a^b Fgdx + \int_a^b fGdx = FG(b) - FG(a)$$

■

Remark. Integration by parts is what will allow us to find integrals of products of functions.

7.4 Integration of Vector Valued Functions.

We extend the concept of integrability to general Euclidean spaces. Let f_1, \dots, f_k be realvalued functions defined on an interval $[a, b]$, and let $f = (f_1, \dots, f_k)$ be a vectorvalued function of $[a, b]$ onto \mathbb{R}^k . If α is a monotonically increasing function on $[a, b]$, we say that f is **integrable** with respect to α of $[a, b]$ if and only if f_i is integrable with respect to α for $1 \leq i \leq k$. If this integrable exists, we define it to be:

$$\int_a^b f d\alpha = \left(\int_a^b f_1 d\alpha, \dots, \int_a^b f_k d\alpha \right). \quad (7.28)$$

The usual theorems for integrability extend to \mathbb{R}^k .

Theorem 7.4.1 (The Fundamental Theorem of Calculus for Vector valued functions). *If $f : [a, b] \rightarrow \mathbb{R}^k$ is a vector valued function that is Riemann integrable, and if F is a differentiable function such that $F' = f$, then:*

$$\int_a^b f dx = F(b) - f(a) \quad (7.29)$$

Proof. We apply the fundamental theorem of calculus to each of the components of f . ■

Theorem 7.4.2. *If $f : [a, b] \rightarrow \mathbb{R}^k$ is integrable with respect to α on an interval $[a, b]$, then $\|f\|$ is integrable, with respect to α on $[a, b]$, and:*

$$\left\| \int_a^b f d\alpha \right\| \leq \int_a^b \|f\| d\alpha$$

Proof. Let $f = (f_1, \dots, f_k)$, then $\|f\| = \sqrt{\sum f_i^2}$ for $1 \leq i \leq k$. Now f is integrable, hence so is $\sum f_i^2$, and furthermore, since $\|f\|$ is continuous on $[0, M]$ for $M > 0$, it is integrable by theorem 7.1.10.

Now let $y = (y_1, \dots, y_k)$, with $y_i = \int_a^b f_i d\alpha$ for $1 \leq i \leq k$. Then $y = \int_a^b f d\alpha$, and

$$\|y\|^2 = \sum y_i^2 = \sum y_i \int_a^b f_i d\alpha = \int_a^b \sum y_i f_i d\alpha$$

hence, by the Cauchy-Schwarz inequality, $\sum y_i f_i \leq \|y\| \|f\|$ for $a \leq t \leq b$, hence $\|y\|^2 \leq \|y\| \int_a^b \|f\| d\alpha$. ■

7.5 Rectifiable Curves.

Definition. We call a continuous mapping $\gamma : [a, b] \rightarrow \mathbb{R}^k$ a **curve** in \mathbb{R}^k , on an interval $[a, b]$. If γ is 1-1, we call the curve an **arc**, and we call γ a **closed curve** if $\gamma(a) = \gamma(b)$.

Now, for each partition P of $[a, b]$, and for γ a curve on $[a, b]$, and let:

$$\Lambda(\gamma, P) = \sum_{i=1}^n \|\gamma(x_i) - \gamma(x_{i-1})\| \quad (7.30)$$

We define the **length** of γ to be :

$$\Lambda(\gamma) = \sup_P \Lambda(\gamma, P) \quad (7.31)$$

If γ is of finite length (i.e. $\Lambda(\gamma) < \infty$), then we call γ a **rectifiable** curve.

Theorem 7.5.1. *Let γ be a differentiable curve on $[a, b]$, if γ' is continuous, then γ is rectifiable and*

$$\Lambda(\gamma) = \int_a^b \|\gamma'\| dt \quad (7.32)$$

Proof. If $a \leq x_{i-1} < x_i \leq b$, then $\|\gamma(x_i) - \gamma(x_{i-1})\| = \left\| \int_{x_{i-1}}^{x_i} \gamma' dt \right\| \leq \int_{x_{i-1}}^{x_i} \|\gamma'\| dt$, by the Fundamental theorem of calculus, thus $\Lambda(\gamma, P) \leq \int_a^b \|\gamma'\| dt$ for every partition P of $[a, b]$, then consequently, we have $\Lambda(\gamma) = \int_a^b \|\gamma'\| dt$. Consequently, γ is rectifiable.

Now let $\varepsilon > 0$, since γ' is uniformly continuous on $[a, b]$, there is a $\delta > 0$ such that $\|\gamma'(s) - \gamma'(t)\| < \varepsilon$ whenever $|s - t| < \delta$ for $s, t \in [a, b]$. Let P be a partition of $[a, b]$, with

$\Delta x_i < \delta$ for all i , and if $x_{i-1} \leq t \leq x_i$, we have $\|\gamma'(t)\| \leq \|\gamma'(x_i)\| + \varepsilon$, hence:

$$\begin{aligned}
 \int_{x_{i-1}}^{x_i} \|\gamma'\| \Delta x_i &\leq \|\gamma'(x_i)\| \Delta x_i + \varepsilon \Delta x_i \\
 &= \left\| \int_{x_{i-1}}^{x_i} (\gamma'(t) + \gamma'(x_i) - \gamma'(t)) dt \right\| + \varepsilon \Delta x_i \\
 &\leq \left\| \int_{x_{i-1}}^{x_i} \gamma' dt \right\| + \left\| \int_{x_{i-1}}^{x_i} (\gamma'(x_i) - \gamma'(t)) dt \right\| + \varepsilon \Delta x_i \\
 &\leq \|\gamma(x_i) - \gamma(x_{i-1})\| + 2\varepsilon \Delta x_i
 \end{aligned}$$

Thus, $\int_a^b \|\gamma'\| dt \leq \Lambda(\gamma, P) + 2\varepsilon(b-a)$, so for ε small enough, we get that $\int \|\gamma'\| \leq \Lambda(\gamma)$. ■

Chapter 8

Lebesgue Theory

8.1 σ -algebras

Definition. Let X be a set and $\mathcal{A} = \{A_\alpha\}$ a collection of subsets of X . We call \mathcal{A} a σ -algebra if:

- (1) $\emptyset \in \mathcal{A}$.
- (2) $X \setminus A_\alpha \in \mathcal{A}$ for any α .
- (3) \mathcal{A} is closed under countable unions.

Theorem 8.1.1. *Let X be a set and \mathcal{A} a collection of subsets of X . Then there exists a smallest σ -algebra containing \mathcal{A} .*

Definition. The collection \mathcal{B} of **Borel sets** of real numbers is the smallest σ -algebra containing all open sets of \mathbb{R} . We call \mathcal{B} the **Borel algebra**.

8.2 The Lebesgue Outer Measure

8.3 Lebesgue Measurable Sets

8.4 Outer and Inner Approximations

8.5 The Borel-Cantelli Lemma

8.6 Nonmeasurable Sets

8.7 The Cantor Set

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