






# Arsh Zahed

Machine Learning Engineer

 azahed98.github.io  azahed98  arsh-zahed  \*\*\*\*\*  \*\*\*\*\*

Objective:  $\max \mathbb{E} [\| \text{Experience} \|^2 + \| \text{Knowledge} \|^2]$   
Optimization Method: Full-Time Engineer/Researcher

## EXPERIENCE



### NVIDIA | DEEP LEARNING ENGINEER

AI Applications | July '20 – Current

- Deployed model conversion tool for Riva Speech Services to optimize models for server deployment with Triton using ONNX and TensorRT. Supports over 15 different pipelines, accelerating for >12x.
- Designed and built TAO-LM, tool for training/tuning N-Gram models.
- Standardized testing framework to increase coverage from 40% to 72%.
- Contributed to online demo for Riva, used by >500 users a day.



### BERKELEY AI RESEARCH | RESEARCHER & GRADER

AutoLab | Jan '19 - Jan '20

- Research in Reinforcement, Imitation and Online Learning.
- Reduced failure of safety using uncertainty estimation by 14%.
- Built 8 experiments for imitation learning with an improving supervisor.
- Graded/tutored for Deep Learning and Optimization for >600 students.



### GOOGLE | SOFTWARE ENGINEER INTERN

Chrome Media Audio | May '18- Aug '18

- Created TF Estimators experimentation framework to predict the speech coding quality of WaveNet/Lyra while reducing bitrate by 50%.
- Collected 7000 user-rated WaveNet samples. Ran experiments with RNNs, Dilated Convolutions and Variational Autoencoders.



### LAUNCHPAD | PRESIDENT & PROJECT LEAD

UC Berkeley Student Org | Jan '17 - May '20

- As president, led and organized educational ML workshops and meetings for 40+ members. Maintained relationships with 3 sponsors.
- As PL, led 16 developers on 2 research-oriented projects.

## PUBLICATIONS

### “On-Policy Imitation Learning from an Improving Supervisor”

- Conference on Robot Learning (CORL), 2019
- Real World Sequential Decision Making Workshop at ICML, 2019.

## PROJECTS

### UNCERTAINTY AWARE PHYSICS ESTIMATION Python, PyTorch | 2021

- Used uncertainty estimation to create an active learning framework for physics estimation. Achieved a >50% decrease in required data.

### EXPRESSIVE TTS FROM INFERRED EMBEDDINGS Python, PyTorch | 2020

- Inferred style-embeddings from text to improve generated speech.
- Improved F0 Frame Error by 8% with audible improvement.

### METAL - MAML EXPLORATION WITH METRICS Python, TensorFlow | 2019

- Developed Policy Metrics to form a topology on the set of policies of an MDP that helps guide task-specific exploration.
- Used with imitation learning for 22% reduction in training speed.

### SEMI-GENERALIZED GRASPING Python, ROS | 2018

- Built an algorithm to sense and grasp using a Kinect and Sawyer robot.

## SKILLS

### TOPICS & FIELDS

Deep Learning • Speech Processing • Natural Language Processing • Digital Signal Processing • Generative Models • Reinforcement Learning

### PROGRAMMING

Python • C • C ++ • JavaScript • R • Java • Protobuf • Bash • LaTeX

### LIBRARIES & TOOLS

TensorFlow • PyTorch • Triton • AWS • GCP • Docker • Kubernetes

## EDUCATION



### STANFORD UNIVERSITY

NON-DEGREE | SEP '21 - PRESENT  
CS | GPA: 3.7



### UC BERKELEY

B.S. | AUG '16 - MAY '20  
EECS | GPA: 3.703

## COURSEWORK

### STANFORD

CS 224n Natural Language Processing  
CS 236 Deep Generative Models

### UC BERKELEY

CS 194-26 Quantum Computing  
CS 191 Computational Photography  
CS 189 Machine Learning  
CS 188 Artificial Intelligence  
CS 170 Algorithms  
CS 162 Operating Systems  
CS 161 Computer Security  
EE 225b Digital Image Processing  
EE 127 Convex Optimization  
EE 126 Probability Theory  
EE 123 Discrete Signal Processing  
EE 120 Signals & Systems  
EE 106a Robotics  
Math 141 Differential Topology  
Math 110 Linear Algebra  
Math 104 Real Analysis  
Music 108 Music Cognition  
Stat 154 Stochastic Processes  
Stat 153 Time Series Analysis