

The Eikonal+ Backend

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Abstract

This is the draft manual for the **Eikonal+** Backend

1 Introduction

The Eikonal+ application is divided into a frontend for most purposes and a backend, which can be controlled directly by text commands, or interfaced to other software. Almost any language or major scientific package can launch Eikonal+ as a subprocess and communicate with it. Communication with the backend is done via the stdin (standard in) and stdout (standard out) streams. Stdin is the keyboard if the backend is launched from a terminal (“from the command line”).

Additionally, a SIGINT (usually CTRL-C) can be used to interrupt the backend during some calculations without crashing Eikonal+. (This is not fully implemented.)

A log file is overwritten at the start of execution.

Repetitive calculations can be run using scripts. A script can be piped to stdin when starting the backend, or one can be called during an interactive session. This can be useful in preventing time-consuming mistakes, such as when the source of a problem with the design is not known.

General notes from the original Eikonal manual:

- Always optimize axial focus before starting designing (1S1=0).
- Unless you really start from scratch it is best to correctly fill the aperture stop with off axis pencils of rays using codes PE, PS, 1PE, 1PS at the very beginning of the design.
- Never forget to run computation of parameter increments with code PARI once the optimization variables (construction parameters) have been defined with code PARA, and repeat computation frequently ever after.
- When using the Adaptive Method bring aberrations, functions or constraints to required targets one at a time, unless the residual errors are very small or the entities targeted are completely independent.
- Before using the method of constrained damped least squares (DLS) all functions and constraints must be brought to target with the Adaptive Method for the program to run efficiently.

1.1 Optical system limitations

The following limits apply to systems designed in the front end and in the back end.

Number of configurations in a lens system	5	(from 0 to 4)
Number of optimization parameters	199	
Number of targeted aberrations	199	
Actual number of constraints	117	
Number of surfaces in each configuration	100	(from 0 to 99)
Number of field points in each configuration	15	(from 0 to 14)
Number of groups in each configuration	10	
Number of design wavelengths in each configuration	3	

2 Benchmarking

2.1 Ray Tracing

Without optimization in the compiler, using *a single thread* on the Linux machine described below, the following speed values were obtained. Note that these rays covered a square grid. A circular grid would make use of only $\approx 78\%$ of these points. Currently, Eikonal+ traces rays only in square grids, but this is easy to change if the 22% improvement in speed is required.

Eikonal+ traced 144k rays / second through a Cooke Triplet system, which includes 6 “real” surfaces, or 9 surfaces including the image and reference plane and the aperture stop.

With parallelization, this speed should increase linearly with the number of simultaneous threads.

Including writing to disk on a common laptop, the speed was reduced to 39k rays / second for the same Cooke Triplet system.

System details for the tests above:

```
product           : MacBookPro9,2 (System SKU#)
operating system  : Ubuntu Linux 14.04
vendor           : Apple Inc.
version          : 1.0
width            : 64 bits
*-cpu            : 0
description       : CPU
product          : Intel(R) Core(TM) i7-3520M CPU @ 2.90GHz
```

See the RAYTRA command for instructions on ray tracing.

3 Setup

The backend is configured during installation of the full Eikonal+ package. The Eikonal+ backend can be configured independently by editing the EPLUSCONFIG.IKT file in a text editor.

```
! Eikonal+ namelist format!
&DIRECTORIES
PDIRG = 'C:\Eikonallibs',
DOCS_DIR = 'C:\Eikonal\eikonal\docs'/
```

(This is a Fortran “namelist” file.)

4 Eikonal+ backend commands

4.1 Getting help

A brief help string is available when communicating directly with the backend. The syntax is 'HELP KEYWORD', where KEYWORD is a search term or command name.

4.2 Command syntax

Optional parameters are enclosed in square brackets [], and required parameters are enclosed in angle brackets <>.

Generally, commands are formed from the first three letters of each word in the operation or quantity, e.g. FIRORDPAR is “first order parameter.” Exceptions:

```
WRITE_NOTE
WRITE_LOG
WRITE_WARNING
WRITE_ERROR
WHAT
```

Old style Eikonal commands must be preceded by '\$'.

```
$RT
```

\$RTGL

BACSYS

Makes a *temporary* backup of the lens system in memory for the user. The backup includes more than the lens definitions and thus is different from the .DBS and .A files. This file is destroyed upon restarting Eikonal+. See also RESSYS.

CD

Changes the working directory of the back end. Note that it will fail silently if the directory is badly formed or not found. On Linux / Unix / OS X systems, use the forward slash to separate directories.

CD /home/adam/MyTelescope

Be sure to use “\” (back slash) instead of forward slash on Windows systems. Example:

CD "C:\Users\Adam\My Telescope"

For directories with spaces in them, surround the entire path with quotation marks:

CD "/home/adam/My Telescope"

CHAREFLECSUR

Changes the properties of a reflective surface in the specified configuration. See also INSREFLECSUR. Usage:

CHAREFLECSUR <c> <sn> <r> <dp> <dn> [title]

where **c** is the configuration number (starting from 0),

sn is the index of the surface to change,

r is the new radius of curvature,

dp is the new distance from the previous surface (surface **sn** - 1),

dn is the new distance to the next surface,

[title] is an optional string (no spaces, e.g. 'PRIMARY MIRROR').

Check the inserted surface using LISSUR.

CHAREFRACSUR

Changes the properties of a refractive surface in the specified configuration.

See also INSREFRACSUR. Usage:

CHAREFRACSUR <c> <sn> <r> <dp> <dn> <g> [title]

where **c** is the configuration number (starting from 0),

sn is the index of the surface to change,

r is the new radius of curvature,

dp is the new distance from the previous surface (surface **sn** - 1),

dn is the new distance to the next surface,

g is the new glass code from the catalog (8 characters max, e.g. 'BK7'... and

[title] is an optional string (no spaces, e.g. 'PART-OF-CEMENTED-DOUBLET').

Check the inserted surface using LISSUR.

CHDIR

See CD.

COLLABORATOR2A

Prints a short summary of the system surfaces, glass codes, etc., followed by the 3rd and 5th order Seidel-Buchdahl aberration coefficients.

DANSYSDAT8

Produces a table of the surfaces in the lens system. This is used by the front end.

DANSYSDAT9

This is the same as DANSYSDAT8, except that the output is written to `systemdata.dat` in the working directory.

DUMP

Dumps all system data in binary format to the file DUMP.BIN. See also RESSYS and BAKSYS.

\$EVAL

\$EVAL performs a number of functions that need to be run following any change to the optical system. Some of its functions are

- Calculating the semi-apertures for new surfaces
- ...

FFD

Creates optical path difference (OPD) plot data for a full-field display (FFD). In the `.../examples/full_field_displays/` directory is an example input file `coords_for_ffd.txt` giving a set of polar coordinates used for both field points and pupil points.

On the first line of the input file is a pair of integers, the number of radial coordinates and the number of azimuthal coordinates, respectively. Eikonal+ will cycle through all permutations of these coordinates for field points and pupil points. Following the first line are the radial coordinates (one per line) in system units and then the azimuthal coordinates in radians.

```
7, 25
0.15951816143819091089225221066676
0.35949187362206503717137258188947
0.54504809357643057125091582559565
0.70710678118654752440084436210485
0.83840478033507095662135338736221
0.93314821587982325195673413572177
0.98719499399631239330569439839602
0
0.25132741228718345907701147066236
0.50265482457436691815402294132472
0.75398223686155037723103441198708
1.0053096491487338363080458826494
1.2566370614359172953850573533118
1.5079644737231007544620688239742
1.7592918860102842135390802946365
2.0106192982974676726160917652989
2.2619467105846511316931032359612
2.5132741228718345907701147066236
2.764601535159018049847126177286
3.0159289474462015089241376479483
3.2672563597333849680011491186107
3.518583772020568427078160589273
3.7699111843077518861551720599354
4.0212385965949353452321835305978
4.2725660088821188043091950012601
4.5238934211693022633862064719225
```

```

4.7752208334564857224632179425848
5.0265482457436691815402294132472
5.2778756580308526406172408839096
5.5292030703180360996942523545719
5.7805304826052195587712638252343
6.0318578948924030178482752958966

```

The output from the FFD calculation can be used in the Matlab code in the same examples directory to create a plot. The format of the output file is as follows. The first line shows the half-field of view values of the system (in *degrees*) with a comment. All remaining lines of the output file contain the fields r_{fp} (radius of field point), θ_{fp} , (polar angle of field point in *radians*) r_{pp} (radius of the pupil point), θ_{pp} (polar angle of the pupil point), d (the OPD value in wavelengths), in that order.

Below is an example of an output file.

```

0.000000000    0.000000000 HFOV OF SYSTEM FOR Y AND Z (DEGREES)
0.159518161    0.000000000    0.159518161    0.000000000    0.43902704E-02
0.159518161    0.000000000    0.159518161    0.251327412    0.65348162E-02
0.159518161    0.000000000    0.159518161    0.502654825    0.12396494E-01

```

Errors are noted in the file next to each entry:

```

0.933148216    4.021238597    0.545048094    2.764601535    0.21649860E+02 <WARNING> F
0.933148216    4.021238597    0.545048094    3.015928947    0.21649860E+02 <WARNING> W

```

Syntax: FFD <optical system file> <input file> <output file>

FINGLA

Looks up glass data by the name, *e.g.* “BK7”. The name currently has a maximum length of 8 characters.

GETCWD

Prints the working directory of the back end.

GETGENSYSSET

Display the following settings, as appropriate.

Image distance solve ON
 Image distance solve OFF
 Objective
 Common relay
 Afocal relay
 Telescope
 Eyepiece
 Autocollimator (finite)
 Autocollimator (infinite)
 Rotationally symmetric system
 Anamorphic system
 Symmetric image blur
 Asymmetric image blur
 Circular or elliptical pupil
 Square or rectangular pupil
 Strictly collinear System
 Non-collinear System (explicit; dummy sfces)
 Non-collinear System (implicit; hidden sfces)
 Standard coordinate system
 Canonical coordinate system

INSFIEPOI or INSFLDPNT

Adds a field point to the specified configuration. Usage:

INSFIEPOI <"FIH" or "HFOV"> <configuration #> <y-value> <z-value>

where FIH and HFOV indicate that the values to follow are fractional image heights or half-field-of-view values, respectively. See also LISFIEPOI and REMFIEPOI.

INSREFLECSUR

Inserts a reflective surface in the lens system. Usage:

INSREFLECSUR <c> <p> <r> <dp> <dn> [title]

where c is the configuration number (starting from 0),

p is the index of the surface after which to insert this surface (starting from 0),

r is the radius of curvature,

dp is the distance from the previous surface (surface p),

dn is the distance to the next surface,

[title] is an optional string (no spaces, e.g. 'PART-OF-CEMENTED-

DOUBLET'.
NOTES:

1. In order to propagate changes in lens thicknesses (surface positions) \$EVAL should be run following INSREFLECSUR.
2. The distance from the previous surface generally should match the value of "Dist to next" for the previous surface in the LISSUR output. (See the example below.)
3. The distance to the next surface should match in sign the direction light will be traveling after leaving the new surface. The user must do this sensibly.
4. Eikonal+ takes care of signs of the refractive indices internally.
5. Check the results with LISSUR to be sure that the new surface is in the correct position.

The transcript below demonstrates the use of INSREFLECSUR to make a two-mirror system. The system is initially a single spherical mirror (surface 1) 4.0 cm from the reference surface, reflecting light 2.0 cm back toward the reference surface. When the next surface is added after surface 1, the distance of 2.0 cm can be changed using the <dp> field.

```
lissur 0
//   Type |   Curvature | Dist to next   | Refr indx | Gls code | Glass
//-----
  0 SP      0.00000000    4.00000000    1.000000    0.000
  1 SP     -0.12500000   -2.00000000   -1.000000    0.000
  2 SP      0.00000000    0.00000000    1.000000    0.000
<END>
```

To add another mirror 2.0 cm after the reference surface (physically between surfaces 0 and 1) reflecting rays back toward surface 1, insert the new mirror *after* surface 1. Below, a spherical mirror is added after surface 1 using dp = -2.0. Using a different desired value for dp would change the "Dist to next" value for surface 1 in the LISSUR output.

```
insreflecsur 0 1 8 -2 4
```

```
<END>
```

```
lissur 0
```

```
//   Type |   Curvature | Dist to next   | Refr indx | Gls code | Glass
```

```
//-----
```

```
0 SP      0.00000000    4.00000000    1.000000    0.000
```

```
1 SP     -0.12500000   -2.00000000   -1.000000    0.000
```

```
2 SP      0.12500000    4.00000000    1.000000    0.000
```

```
3 SP      0.00000000    0.00000000    1.000000    0.000
```

```
<END>
```

The <dn> value was entered as 4.0 cm, which can be changed when inserting a surface after surface 2. Use \$EVAL to update computed parameters. Running \$EVAL again and listing the surfaces gives the following output. The \$LENS command can be used to see the finished system (Figure 1).

```
$eval
```

```
CURRENT EVALUATION:
```

		W(rms)1	W(rms)2	W(rms)3	Distrn.	1Lt.Clr.	2Lt.Clr.
Config. 0:							
fld. pt.	0	2580.0456	2917.4648	2174.9692	0.0000	0.0000	0.0000
fld. pt.	1	2580.0458	2917.4651	2174.9694	-0.0015	0.0000	0.0000
fld. pt.	2	2580.0460	2917.4653	2174.9696	-0.0022	0.0000	0.0000

```
<END>
```

```
lissur 0
```

```
//   Type |   Curvature | Dist to next   | Refr indx | Gls code | Glass
```

```
//-----
```

```
0 SP      0.00000000    4.00000000    1.000000    0.000
```

```
1 SP     -0.12500000   -2.00000000   -1.000000    0.000
```

```
2 SP      0.12500000    4.00000000    1.000000    0.000
```

```
3 SP      0.00000000    0.00000000    1.000000    0.000
```

```
<END>
```

```
$lens
```

```
INSREFRACZERSUR
```

Inserts a refractive Zernike polynomial surface in the lens system. NOTE:

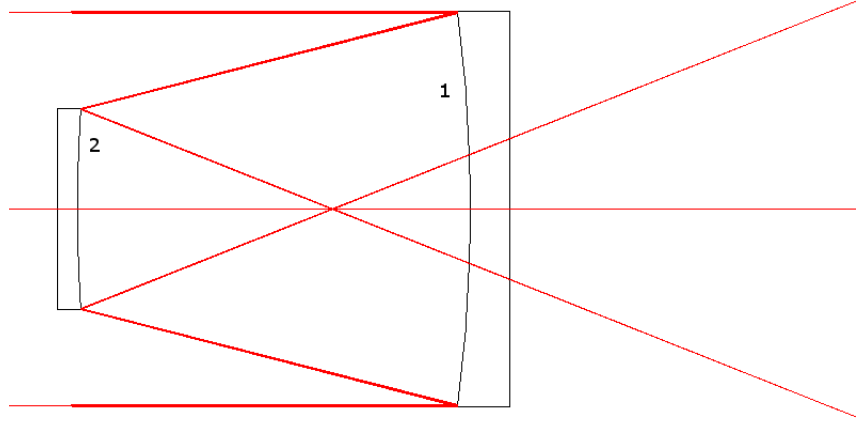


Figure 1: The two-mirror system created using INSREFLECSUR commands. The numbered surfaces correspond to the final system.

In order to propagate changes in lens thicknesses (surface positions) `$EVAL` should be run following `INSREFRACZERSUR`.

Usage:

```
INSREFRACZERSUR <c> <p> <r> <dp> <dn> <su> <a1, a2, ..., a20> <g> [title]
```

where `c` is the configuration number (starting from 0),
`p` is the index of the surface after which to insert this surface (starting from 0),
`r` is the radius of curvature to first order (the spherical term),
`dp` is the distance from the previous surface (surface `p`),
`dn` is the distance to the next surface,
`su` is the radius over which the Zernike polynomials are defined[†],
`a1, a2, ..., a20` are the coefficients of the Zernike polynomial[‡],
`g` is the glass code from the catalog (8 characters max, e.g. 'BK7'... and
`[title]` is an optional string (no spaces, maximum 40 characters, e.g. 'PART-OF-CEMENTED-DOUBLET').

Check the inserted surface using `LISSUR`.

[†]The `<su>` parameter is the radius in the lens plane (not the radius of curvature) that will be treated as a unit circle over which the Zernike poly-

nomials are defined.

‡The numbering of the Zernike polynomials is given in Table 1. [Put the table in the common-parts directory]

INSREFRACSUR

Inserts a refractive surface in the lens system. NOTE: In order to propagate changes in lens thicknesses (surface positions) \$EVAL should be run following INSREFRACSUR.

Usage:

INSREFRACSUR <c> <p> <r> <dp> <dn> <g> [title]

where c is the configuration number (starting from 0),

p is the index of the surface after which to insert this surface (starting from 0),

r is the radius of curvature,

dp is the distance from the previous surface (surface p),

dn is the distance to the next surface,

g is the glass code from the catalog (8 characters max, e.g. 'BK7'... and

[title] is an optional string (no spaces, e.g. 'PART-OF-CEMENTED-DOUBLET'.

Check the inserted surface using LISSUR.

LISFIEPOI or LISFLDPNT

Lists field points for the specified configuration. Usage:

LISFIEPOI <configuration #>

The output should look similar to the following:

			FRCT. IMG. HGT		PUPIL SHIFT COEFF.		PUPIL EXPN. COEFF.	
	Weight	Y-axis	Z-axis	Y-axis	Z-axis	Y-axis	Z-axis	
0:BASIC								
fld., 1	+	0.700000	0.000000	0.00000000	0.00000000	1.00000000	1.00000000	
				0.00000000	0.00000000	1.00000000	1.00000000	
				0.00000000	0.00000000	1.00000000	1.00000000	
fld., 2	+	0.700000	0.000000	0.03067568	0.00000000	0.96262707	0.99930000	
				0.03067568	0.00000000	0.96262707	0.99930000	
				0.03067568	0.00000000	0.96262707	0.99930000	
fld., 3	+	1.000000	0.000000	-0.00225698	0.00000000	0.79630930	0.97903000	

-0.00225698	0.00000000	0.79630930	0.97903
-0.00225698	0.00000000	0.79630930	0.97903

See also ADDFIEPOI and REMFIEPOI.

LOASYS

Loads an optical system from a file. Usage: LOASYS "<file-path>", e.g. LOASYS "/home/mary/optics/telescope.dbs". The surrounding quotation marks are required for files not in the current directory. LOASYS loads both .DBS and .A files. See SAVSYS.

OPETEXFIL

Opens a user text file. Usage: OPETEXFIL filename unit#. See CLO.

RAYTRA

Traces rays through the optical system. Usage: RAYTRA <wavelengths> <last obj point> <pupil points>, where <last obj point> is the index (starting from 0) of the last field point to be used. Field points will be used cyclically if more are requested than are currently defined. The number of rays traced is the square of the <pupil points> argument (for a circular aperture).

REMFIEPOI

Removes a field point from a configuration of the lens system. Usage: REMFIEPOI <c> <fn>, where <c> is the configuration number (starting from 0), and <fn> is the field number to remove (starting with 0). Note that after removing a field point the rest of the field points will be re-ordered with respect to an increasing fractional image height.

REMSUR

Removes a surface from a configuration of the lens system. Usage: REMSUR <c> <sn>, where <c> is the configuration number (starting from 0), and <sn> is the surface number to remove (starting with 0).

RESSYS

Restores the user's *temporary* backup of the lens system. This file is destroyed upon restarting Eikon+. See also BAKSYS.

SAVSYS

Saves the optical system in memory to a file. Usage: SAVSYS "<file-path>", e.g. SAVSYS "/home/mary/optics/telescope.dbs". The surrounding quotation marks are required for files not in the current directory. SAVSYS works with both .DBS and .A files. See LOASYS.

SETIMADISSOL <configuration #> <'yes' or 'no'>

Turns on ('yes') or off ('no') solving for the image distance when command \$EVAL is run.

configuration # is the number of the configuration to set the image-distance solve flag for. The numbering begins with 0.

SETABESYM <configuration #> <symmetry code>

where <symmetry code> is one of "SYM" and "ASYM." This command sets the appropriate flags and other values to change the ray tracing from half-pupil to full-pupil, used for rotationally symmetric ("SYM") and asymmetric ("ASYM") aberrations (blur), respectively.

SETROTSYS <configuration #> <symmetry code>

where <symmetry code> is one of "RS", "NRS", "NSRT" (rotational symmetry, non-rotational symmetry and non-symmetric ray tracing, respectively). This command sets the appropriate flags and other values to change the system's symmetry, which controls the methods used by Eikonal+ for ray tracing.

SHOCOD

Prints the complete list of Eikonal (not Eikonal+) command codes to stdout.

STASCR <filename>

Begins taking input from the script file. Use STOSCR to return to standard input. STOSCR must be in the script file, or Eikonal will hang. This is to be used in interactive mode, *not* when Eikonal is fed a script at startup. See STOSCR.

STOSCR

Stops a script in progress and returns to standard input. This is to be used in a script file that is called in interactive mode, *not* when a script is piped to Eikonal+ at startup. See STASCR.

SURMOV Moves (displaces, decenters) one or more surfaces. In order to

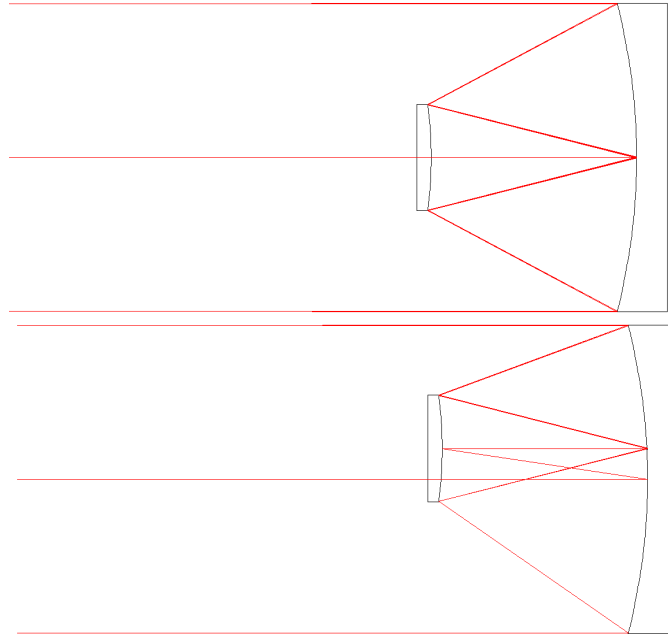


Figure 2: A two-mirror system before (top) and after (bottom) a displacement using SURMOV.

move surface n , insert the displacement with **SURMOV** before surface n . Note: surfaces cannot be moved along the optical axis. Instead, use **CHAREFRACSUR** or **CHAREFLECSUR**. *Removing and replacing tilts and displacements is not robust in Eikonal or Eikonal+. It may be helpful to write a script that builds the system, in case you need to start from scratch.* Usage:

SURMOV <c> <n> <d> <axis>

where c is the configuration number (starting from 0),

n is the index of the surface to move,

d is the distance in system units,

axis is one of “x,” “y,” or “z,” the pivot axis.

Example: The following script will displace the first mirror (bottom of Figure 2) from the original system (top of Figure 2). The following script will reproduce Figure 2.

```
loasys 111113.dbs
```

```

$eval
$lens
setimadissol 0 yes
setrotsym 0 nrs
lissur 0
surmov 0 1 0.2 y
$eval
lissur 0
$lens
stoscr

```

The surface list before and after the displacement are shown below. Note that the first mirror is on the *right* and the second mirror is on the *left*.

//	Type	Curvature	Dist to next	Refr indx	Gls code	Glass
//-----						
0	SP	0.00000000	4.09206570	1.000000	0.000	
1	A1	-0.25000000	-1.33333300	-1.000000	0.000	
2	A1	-0.37499981	1.33333300	1.000000	0.000	
3	SP	0.00000000	0.00000000	1.000000	0.000	

//	Type	Curvature	Dist to next	Refr indx	Gls code	Glass
//-----						
0	SP	0.00000000	4.09206570	1.000000	0.000	
1	A1	-0.25000000	-1.00000000	-1.000000	0.000	
2	YD	0.20000000	-0.33333300	-1.000000	0.000	
3	A1	-0.37499981	1.33333399	1.000000	0.000	
4	SP	0.00000000	0.00000000	1.000000	0.000	

SURTIL Tilts (rotates) one or more surfaces. In order to rotate surface *n*, insert the tilt with **SURTIL** before surface *n*. *Removing and replacing tilts and displacements is not robust in Eikonal or Eikonal+. It may be helpful to write a script that builds the system, in case you need to start from scratch.*

Usage:

SURTIL <c> <n> <a> <p> <axis>

where *c* is the configuration number (starting from 0),

n is the index of the surface to tilt,

a is the tilt angle in degrees,

p is the distance from surface *n* to the pivot axis and

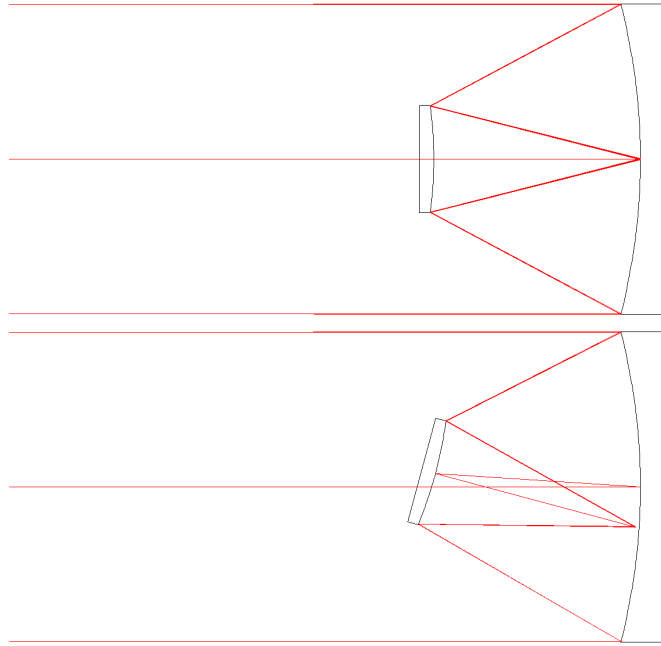


Figure 3: A two-mirror system before (top) and after (bottom) a tilt using SURTIL.

axis is one of “x,” “y,” or “z,” the pivot axis.

Example: The following script will produce the tilted system (bottom of Figure 3) from the original system (top of Figure 3). The following script will reproduce Figure 3.

```
loasys 111113.dbs
$eval
$lens
setimadissol 0 yes
setrotsym 0 nrs
lissur 0
surttil 0 1 -15 0 y
$eval
lissur 0
$lens
stoscr
```

The surface list before and after the tilt are shown below. Note that the first mirror is on the *right* and the second mirror is on the *left*.

//	Type	Curvature	Dist to next	Refr indx	Gls code	Glass
0	SP	0.00000000	4.09206570	1.000000	0.000	
1	A1	-0.25000000	-1.33333300	-1.000000	0.000	
2	A1	-0.37499981	1.33333300	1.000000	0.000	
3	SP	0.00000000	0.00000000	1.000000	0.000	

//	Type	Curvature	Dist to next	Refr indx	Gls code	Glass
0	SP	0.00000000	4.09206570	1.000000	0.000	
1	A1	-0.25000000	-1.00000000	-1.000000	0.000	
2	YD	0.20000000	-0.33333300	-1.000000	0.000	
3	A1	-0.37499981	1.33333399	1.000000	0.000	
4	SP	0.00000000	0.00000000	1.000000	0.000	

CLO n

Closes the file with unit number n.

LISCON

Prints a list of all configurations of the current system in memory.

LISGLACAT <n>

Prints a list of glasses in one of the catalogs (n) below.

- 0 Schott
- 1 Ohara
- 2 S-Ohara
- 3 Hoya
- 4 Chance and Sovirel
- 5 Miscellaneous (IR materials)

- 6 Schott (obsolete)
- 7 Schott radiation resistant
- 8 for Selfoc materials
- 9 for S-ohara (Sellmeir formula)

LSKIN

Prints a list of all surface types. (List kinds)

NEWSYS

Creates an empty lens *system* containing one configuration.

4.3 GET and SET commands

GET and SET retrieve and set a stored parameter or variable. Some quantities may be calculated by GET each time they are retrieved, and there will be no corresponding SET call. The exact syntax depends on the parameter or variable. See for example FIRORDPAR.

FIRORDPAR

Use with GET to access or calculate a first-order parameter, such as the numerical apertures, pupil sizes, etc. For systems that are not strictly collinear, the values returned by this function may not accurately describe the first-order properties of the lens because the system is not strictly collinear.' Syntax: GET FIRORDPAR [configuration number] [M or E] [parameter name] Either none or both of [configuration number] and [parameter name] must be given. If neither are given, then a report of all applicable first-order parameters is returned. For example, GET FIRORDPAR 0 M EXIPUPSIZ would return the exit pupil size for configuration 0 of the system, in the meridional plane. If the system is not collinear, the meridional or equatorial plane must be specified using M or E. If the system is collinear, then the meridional plane (M) must be specified.

The following first-order parameters are available.

```
GET FIRORDPAR 0 M UNI
GET FIRORDPAR 0 M EXIANGHALFIE
GET FIRORDPAR 0 M ENTANGHALFIE
GET FIRORDPAR 0 M IMASPANUMAPE
```

```

GET FIRORDPAR 0 M OBJSPANUMAPE
GET FIRORDPAR 0 M IMASPAFNUM
GET FIRORDPAR 0 M OBJSPAFNUM
GET FIRORDPAR 0 M ANGDEM
GET FIRORDPAR 0 M ANGMAG
GET FIRORDPAR 0 M LATDEM
GET FIRORDPAR 0 M LATMAG
GET FIRORDPAR 0 M EXIPUPSIZ
GET FIRORDPAR 0 M ENTPUPSIZ
GET FIRORDPAR 0 M IMAHEI
GET FIRORDPAR 0 M OBJHEI
GET FIRORDPAR 0 M SECNODPOIDIS
GET FIRORDPAR 0 M FIRNODPOIDIS
GET FIRORDPAR 0 M SECPRIPLADIS
GET FIRORDPAR 0 M FIRPRIPLADIS
GET FIRORDPAR 0 M SECPRIRAYFOCDIS
GET FIRORDPAR 0 M FIRPRIRAYFOCDIS
GET FIRORDPAR 0 M EXIPUPDIS
GET FIRORDPAR 0 M ENTPUPDIS
GET FIRORDPAR 0 M IMADIS
GET FIRORDPAR 0 M OBJDIS
GET FIRORDPAR 0 M PETSUM
GET FIRORDPAR 0 M LAGINV
GET FIRORDPAR 0 M OBJIMADIS
GET FIRORDPAR 0 M PUPPUPDIS
GET FIRORDPAR 0 M VERVERDIS
GET FIRORDPAR 0 M EQUFNUM
GET FIRORDPAR 0 M EQUFOCLEN
GET FIRORDPAR 0 M LASSUR
GET FIRORDPAR 0 M FIRSUR
GET FIRORDPAR 0 M DES
GET FIRORDPAR 0 M CONTAG
GET FIRORDPAR 0 M NAM

```

INSTR n [filename]

Begins taking input from unit *n*, which may or may not be a regular file. If a file name is given, then the file is opened and assigned a unit number of

n. Subsequent changes of the input stream do *not* close the file. Use **CLO** to close a file.

OUTSTR <n> [filename]

Redirects output to file unit **n**, which may or may not be a regular file. If a file name is given, then the file is opened and assigned a unit number of **n**. Subsequent changes of the output stream do *not* close the file. Use **CLO** to close a file.

The EAF entries need cleanup.

EAF <configuration #> <"M" or "E">

GET: Returns the object-space half-angle field in degrees.

EAF <configuration #> <"M" or "E">

SET: The first required parameter is a flag, either “1” or “2,” for the meridional or equatorial plane, respectively. The meridional and equatorial EAF values should *both* be set by the user for a non-rotationally symmetric system; changing one does not update the other. For a rotationally symmetric system, the user *must* set the half-angle for the meridional plane. Eikonal+ will then set the same EAF for the equatorial plane. The half-angle is then given in degrees. Use **GET FIRORDPAR** to check the value of EAF.

XFN <ME> <f-number>

Sets the image-space f-number. The first required parameter is a flag, either “1” or “2,” for the meridional or equatorial plane, respectively. The meridional and equatorial XFN values should *both* be set by the user for a non-rotationally symmetric system; changing one does not update the other. For a rotationally symmetric system, the user *must* set the f-number for the meridional plane. Eikonal+ will then set the same f-number for the equatorial plane. The f-number is then given as a float. Use **GET FIRORDPAR** to check the value of XFN.

5 Common User Procedures

5.1 Constructing a lens system

Generally, it is best to define systems by adding surfaces numbered consecutively in ascending order. As an example, take a base system with a reference surface (0), an aperture stop (1) and an image plane (2). Surfaces could be added by inserting after surface 1, then inserting after surface 2, etc.

Note: It is helpful to define a system by writing a script that can be run repeatedly until the system is set up properly. (See the command `STASCR`.) This will avoid situations where a mistake forces the user to start from scratch by hand.

It may be helpful to start with one of the systems in the `Eikonal+` library. (More info on this to come.) Alternatively, a good starting point is to load the empty system `InitLens.A`. It contains only one field point, an aperture stop and the reference surface.

5.2 Changing surfaces

The command `CHAREFRACSUR` will change the parameters of a refractive surface. An alternative is to insert a new surface before the one that is to be changed with the new parameters and then remove the original surface. `CHAREFRACSUR` does both of these operations at once.

Below is an example of a sequence of insert and remove commands that will add, then change a surface. A surface of radius 10 is added. Then a replacement surface of radius 11 is added. (The simplest way to make a replacement is to add the new surface before removing the old one.) Last, the surface of radius 10 is removed. See commands `INSREFRACSUR`, `REMSUR`, `LISSUR`. , , .

<END>

loasys triplet.a

READING FROM FILE: TRIPLET.A **IN WORKING DIRECTORY**

Current Lens System

Cooke Triplet f/4.5

TRIPLE 23 Apr2012 10: 47: 32

0:BASIC

ECP	EPD	ENP	QFL	XNP	XPD	XCP
*****	8.2156	10.4323	50.0007	-6.9498	-9.2694	43.0508
ECH	EPS	EFN	QFN	XFN	XPS	XCH
*****	11.1113*****		4.5000	4.5000	11.6267	18.1988
EMX	EAF	EVD	VTV	XVD	XAF	XME
0.0000	20.0000	58.5008	15.4500	0.0000	19.1794*****	
ASS	ASD	ASN	CTC	FSS	FSD	FSN
8.7367	0.0000	3.0000*****		0.0000	0.0000	0.0000

WARNING:

*) Please run code EVAL (evaluation of system)
before using any codes related to optimization.

<END>

lissur 0

//	Type	Curvature	Dist from last	Refr indx	Gls code	Glass
//	-----	-----	-----	-----	-----	-----
0	SP	0.00000000	10.00000000	1.000000	0.000	
1	SP	0.04655190	2.00000000	1.622861	620.603	SK16
2	SP	-0.00805802	5.26000000	1.000000	0.000	
3	AS	0.00000000	0.00000000	1.000000	0.000	
4	SP	-0.05235602	1.25000000	1.620578	617.366	F4
5	SP	0.04545454	4.69000000	1.000000	0.000	
6	SP	0.00304044	2.25000000	1.622861	620.603	SK16
7	SP	-0.05988024	43.05082831	1.000000	0.000	
8	SP	0.00000000	0.00000000	1.000000	0.000	

<END>

insrefracsur 0 2 10 3 4 BK7

<END>

lissur 0

//	Type	Curvature	Dist from last	Refr indx	Gls code	Glass
//	-----	-----	-----	-----	-----	-----
0	SP	0.00000000	10.00000000	1.000000	0.000	
1	SP	0.04655190	2.00000000	1.622861	620.603	SK16
2	SP	-0.00805802	3.00000000	1.000000	0.000	
3	SP	0.10000000	4.00000000	1.518721	517.642	BK7

```

4 AS      0.00000000      0.00000000      1.000000      0.000
5 SP      -0.05235602      1.25000000      1.620578      617.366      F4
6 SP       0.04545454      4.69000000      1.000000      0.000
7 SP       0.00304044      2.25000000      1.622861      620.603      SK16
8 SP      -0.05988024      43.05082831      1.000000      0.000
9 SP       0.00000000      0.00000000      1.000000      0.000
<END>
insrefracsur 0 2 11 3 4 BK7
<END>
lissur 0
//   Type |   Curvature | Dist from last | Refr indx | Gls code | Glass
//-----
0 SP      0.00000000      10.00000000      1.000000      0.000
1 SP      0.04655190      2.00000000      1.622861      620.603      SK16
2 SP      -0.00805802      3.00000000      1.000000      0.000
3 SP      0.09090909      4.00000000      1.518721      517.642      BK7
4 SP      0.10000000      4.00000000      1.518721      517.642      BK7
5 AS      0.00000000      0.00000000      1.000000      0.000
6 SP      -0.05235602      1.25000000      1.620578      617.366      F4
7 SP       0.04545454      4.69000000      1.000000      0.000
8 SP       0.00304044      2.25000000      1.622861      620.603      SK16
9 SP      -0.05988024      43.05082831      1.000000      0.000
10 SP     0.00000000      0.00000000      1.000000      0.000
<END>
remsur 0 4
      STATUS= 0:BASIC  is a Strictly collinear System

      ECP      EPD      ENP      QFL      XNP      XPD      XCP
*****      8.2156      6.9848      19.4559      -11.4688      -10.3112      7.9872
      ECH      EPS      EFN      QFN      XFN      XPS      XCH
*****      11.1113*****      1.7510      1.7510      10.4502      7.0814
      EMX      EAF      EVD      VTV      XVD      XAF      XME
0.0000      20.0000      25.1772      17.1900      0.0000      21.1561*****
      ASS      ASD      ASN      CTC      FSS      FSD      FSN
7.8953      -0.8983      4.0000*****      14.1628      7.9872      8.0000
<END>
lissur 0
//   Type |   Curvature | Dist from last | Refr indx | Gls code | Glass

```

```
//-----
0 SP      0.00000000    10.00000000    1.000000    0.000
1 SP      0.04655190    2.00000000    1.622861    620.603    SK16
2 SP     -0.00805802    3.00000000    1.000000    0.000
3 SP      0.09090909    4.00000000    1.518721    517.642    BK7
4 AS      0.00000000    0.00000000    1.000000    0.000
5 SP     -0.05235602    1.25000000    1.620578    617.366    F4
6 SP      0.04545454    4.69000000    1.000000    0.000
7 SP      0.00304044    2.25000000    1.622861    620.603    SK16
8 SP     -0.05988024    7.98717872    1.000000    0.000
9 SP      0.00000000    0.00000000    1.000000    0.000
<END>
```

Similarly, the command CHAREFLECSUR can be used to change a mirror surface. Refer to section for syntax and instructions.

5.3 Changing field points

After changing, adding, or removing a field point, vignetting factors (pupil shift and pupil expansion) can be recalculated using the command \$VIFA.

6 Scripts

The syntax used in script mode is the same as the syntax in an interactive session. The exit command should be the last line in the script. If it is not, Eikonal+ will hang, because it is not reading from stdin during script execution.

Linux:

```
cat MYSCRIPT | /usr/local/bin/eikonalplus > OUTPUT.TXT
```

Windows using PowerShell:

```
cat MYSCRIPT | C:/Program\ Files/Eikonal/eikonalplus.exe > OUTPUT.TXT
```

Redirecting output is optional.

7 Glass Data

7.1 The Glass Codes

Each glass in the Eikonal+ catalog has a 6-digit number ‘‘nnnaaa’’ or ‘‘nnn.aaa’’ that uniquely identifies it (unless two manufacturers make glasses that are very similar. The original code does not handle this in an unambiguous way.

The code is constructed from the refractive index and the Abbe number as follows.

The first 3 digits of the code, ‘‘nnn,’’ come from the first 3 significant digits of the refractive index *after the decimal point*, e.g. if the refractive index is 1.2468, then ‘‘nnn’’ is ‘‘247’’.

The last 3 digits, ‘‘aaa,’’ are the first 3 significant digits of the Abbe number v_d , e.g. if $v_d = 25.76$, then ‘‘aaa’’ = ‘‘258’’.

For the glass SF11 with refractive index $n_d = 1.7847$ and Abbe number $v_d = 25.76$, the glass code would be ‘‘785.258’’ or ‘‘785258’’.

7.2 Searching the Glass Catalog

8 Freeform Surfaces

8.1 Surfaces calculated by Eikonal+

Eikonal+ can define freeform surfaces using fringe Zernike polynomials up to the 21st term. (list below)

9 Appendix

Term	Fringe Zernike polynomial	Aberration type
1	1	Piston (constant)
2	$R\cos\theta$	Distortion - Tilt (x-axis)
3	$R\sin\theta$	Distortion - Tilt (y-axis)
4	$2R^2 - 1$	Defocus - Field curvature
5	$R^2\cos(2\theta)$	Astigmatism, Primary (axis)
6	$R^2\sin(2\theta)$	Astigmatism, Primary (axis)
7	$(3R^3 - 2R)\cos\theta$	Coma, Primary (x-axis)
8	$(3R^3 - 2R)\sin\theta$	Coma, Primary (y-axis)
9	$6R^4 - 6R^2 + 1$	Spherical Aberration, Primary
10	$R^3\cos(3\theta)$	Trefoil, Primary (x-axis)
11	$R^3\sin(3\theta)$	Trefoil, Primary (y-axis)
12	$(4R^4 - 3R^2)\cos(2\theta)$	Astigmatism, Secondary (axis)
13	$(4R^4 - 3R^2)\sin(2\theta)$	Astigmatism, Secondary (axis)
14	$(10R^5 - 12R^3 + 3R)\cos\theta$	Coma, Secondary (x-axis)
15	$(10R^5 - 12R^3 + 3R)\sin\theta$	Coma, Secondary (y-axis)
16	$20R^6 - 30R^4 + 12R^2 - 1$	Spherical Aberration, Secondary
17	$R^4\cos(4\theta)$	Tetrafoil, Primary (x-axis)
18	$R^4\sin(4\theta)$	Tetrafoil, Primary (y-axis)
19	$(5R^5 - 4R^3)\cos(3\theta)$	Trefoil, Secondary (x-axis)
20	$(5R^5 - 4R^3)\sin(3\theta)$	Trefoil, Secondary (y-axis)
21	$(15R^6 - 20R^4 + 6R^2)\cos(2\theta)$	Astigmatism, Tertiary (axis)
22	$(15R^6 - 20R^4 + 6R^2)\sin(2\theta)$	Astigmatism, Tertiary (axis)
23	$(35R^7 - 60R^5 + 30R^3 - 4R)\cos\theta$	Coma, Tertiary (x-axis)
24	$(35R^7 - 60R^5 + 30R^3 - 4R)\sin\theta$	Coma, Tertiary (y-axis)
25	$70R^8 - 140R^6 + 90R^4 - 20R^2 + 1$	Spherical Aberration, Tertiary
26	$R^5\cos(5\theta)$	Pentafoil, Primary (x-axis)
27	$R^5\sin(5\theta)$	Pentafoil, Primary (y-axis)
28	$(6R^6 - 5R^4)\cos(4\theta)$	Tetrafoil, Secondary (x-axis)
29	$(6R^6 - 5R^4)\sin(4\theta)$	Tetrafoil, Secondary (y-axis)
30	$(21R^7 - 30R^5 + 10R^3)\cos(3\theta)$	Trefoil, Tertiary (x-axis)
31	$(21R^7 - 30R^5 + 10R^3)\sin(3\theta)$	Trefoil, Tertiary (y-axis)
32	$(56R^8 - 105R^6 + 60R^4 - 10R^2)\cos(2\theta)$	Astigmatism, Quaternary (axis)
33	$(56R^8 - 105R^6 + 60R^4 - 10R^2)\sin(2\theta)$	Astigmatism, Quaternary (axis)
34	$(126R^9 - 280R^7 + 210R^5 - 60R^3 + 5R)\cos\theta$	Coma, Quaternary (x-axis)
35	$(126R^9 - 280R^7 + 210R^5 - 60R^3 + 5R)\sin\theta$	Coma, Quaternary (y-axis)
36	$252R^{10} - 630R^8 + 560R^6 - 210R^4 + 30R^2 - 1$	Spherical Aberration, Quaternary
37	$924R^{12} - 2772R^{10} + 3150R^8 - 1680R^6 + 420R^4 - 42R^2 + 1$	Spherical Aberration, Quintary

Table 1: Fringe Zernike polynomials as defined for surfaces in Eikonal+.

Taken from the *CODE V Lens System Setup Reference Manual*.

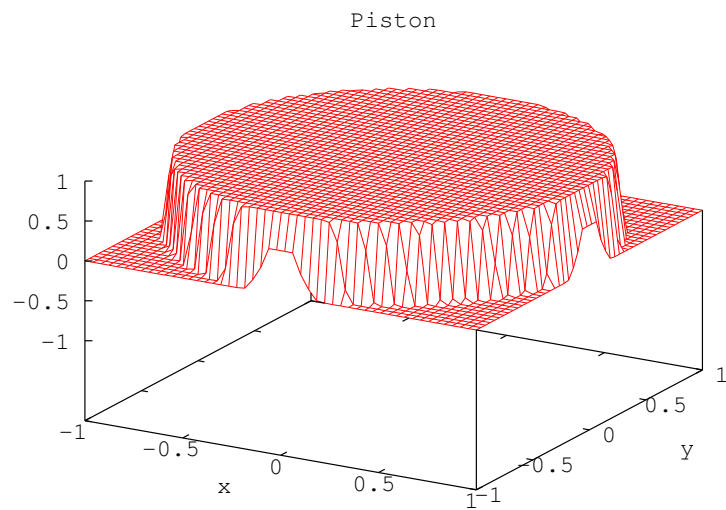


Figure 4: Piston

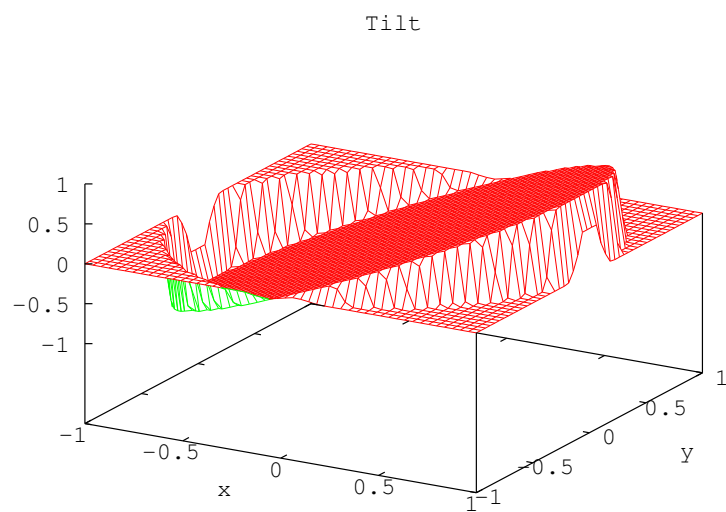


Figure 5: Tilt

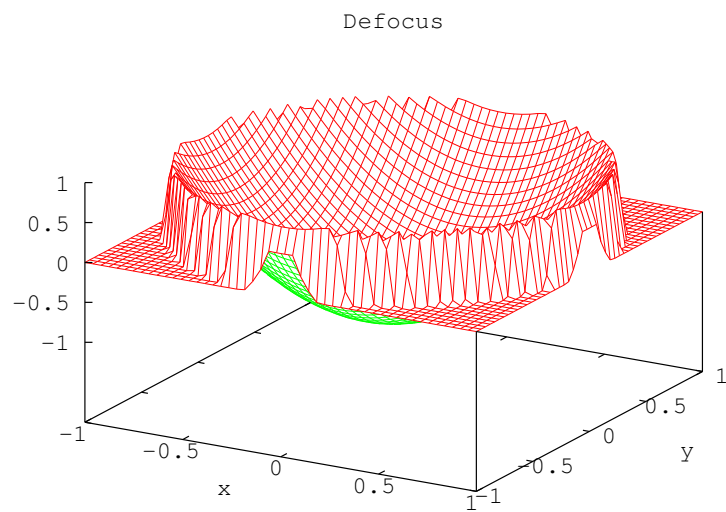


Figure 6: Defocus (field curvature)

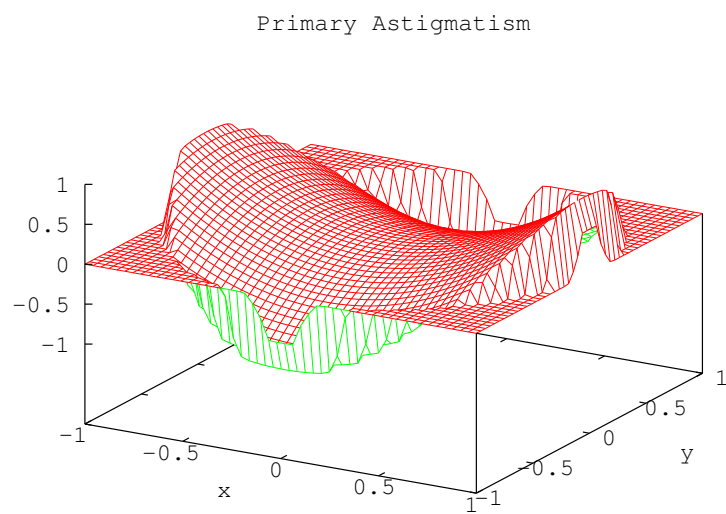


Figure 7: Primary astigmatism

Primary Coma

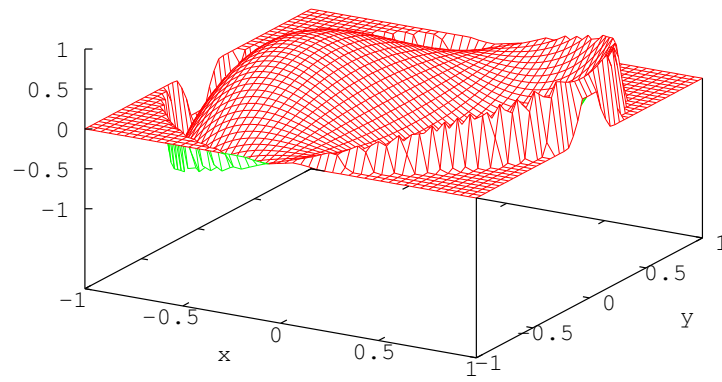


Figure 8: Primary coma

Primary Spherical Aberration

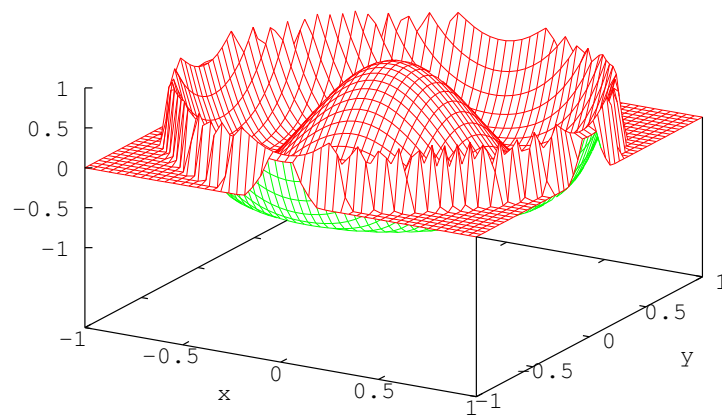


Figure 9: primary-spherical-aberration

Primary Trefoil

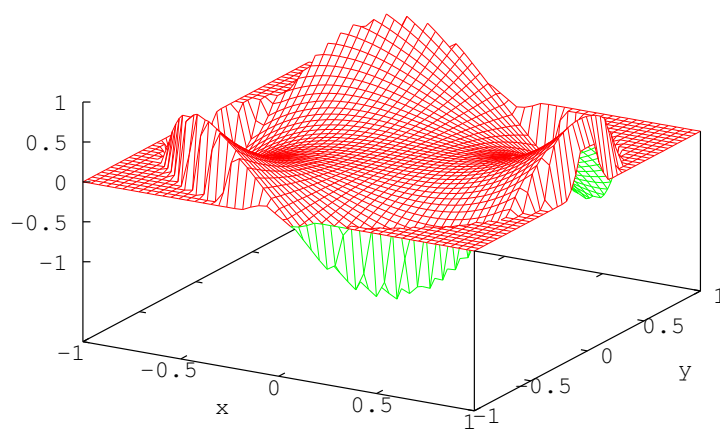


Figure 10: primary-trefoil

Primary Tetrafoil

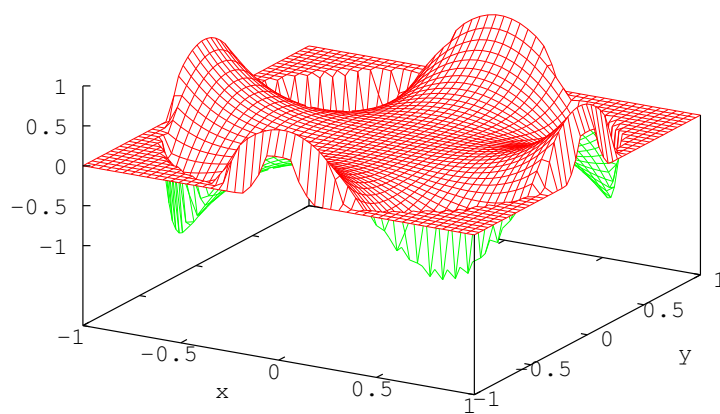


Figure 11: primary-tetrafoil

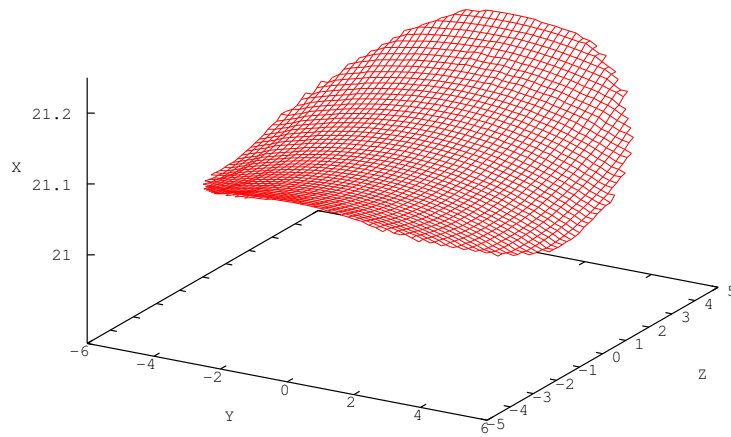


Figure 12: A freeform surface including the Zernike tilt, defocus and astigmatism terms. This surface, a set of ray-surface intersection points, was produced by Eikonol+ during ray tracing.

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