

Computational Models of Event Type Classification in Context

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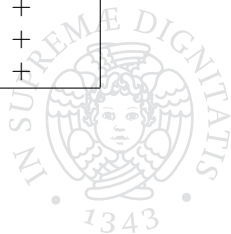
Event Types

Event Types

by event type (ET) we refer here to the standard Vendler's classification of predicates (1967)

Event type	[telic]	[durative]	[dynamic]
states	—	+	—
activities	—	+	+
accomplishments	+	+	+
achievements	+	—	+

Table: The features of Vendler's event types



Event Types in Context

- ① *John has been reading **for the whole day** (atelic, durative)*
*John has read “The Great Gatsby” **in an hour** (telic, durative)*
*John has been reading **papers** for the whole day (atelic, durative)*
- ② *John has been pushing the chart (atelic, durative)*
*John has pushed the chart **to the checkout line** (telic, durative)*
- ③ *The train arrived **at 5 o’clock** (telic, non durative)*
***Europeans** had been arriving sporadically, sometimes with long intervals between arrivals (atelic, durative)*
- ④ ***The path** goes from the street into the forest (state)*
***The cat** is going to the door (dynamic)*
- ⑤ ***John** has hung the picture on the wall (telic, dynamic)*
***The picture** hangs on the wall (state)*



Event Types in Context

Event type polysemy

the ET expressed by a sentence is the result of a **complex interplay** between the verb meaning and its linguistic context

Event type shifts

various contextual factors can shift the verb ET to a new class

Linguistic models of event type hybridism and shifts:

- Dowty 1979
- Bertinetto 1986
- Pustejovsky 1995
- Rothstein 2004

Computational models of event type classification:

- Siegel and McKeown (2000)
- Palmer et al. (2007)



Goal of the paper

task: event type classification in context

hypothesis: the ET expressed by a sentence is the result of a complex interplay between the verb meaning and its linguistic context

- aims:**
- 1 model this interplay
 - 2 evaluate the contribution of different types of linguistic indicators to identify the ET of a sentence
 - 3 model various cases of context-driven event type shift

linguistic models: Vendler's event type categories, theories of event type shift

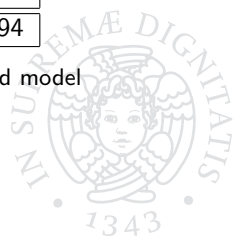
computational models: Maximum Entropy, Self-Organizing Maps

Data

- no corpora annotated for event types available for Italian
- manual annotation of part of the Italian Treebank (Montemagni et al. 2000)
- semi-automatic extraction of contextual features

Verbs	OCCURR.	STA	ACT	ACC	ACH
28	3129	583	430	822	1294

Table: The composition of the corpus for the supervised model



Feature selection

- **adverbial features:**

- temporal adverbs (“in X time”, “for X time”, etc.);
- intentional adverbs (“deliberately”, “intentionally”, etc.);
- frequency adverbs (“rarely”, “often”, etc.);
- iterative adverbs (“X times”);

- **morphological features:**

- present tense;
- imperfect tense;
- future tense;
- simple past;
- perfect tenses;
- progressive periphrasis;

- **syntactic and argument structure features:**

- absence of arguments besides the subject;
- presence of direct object;
- presence of indirect object;
- presence of a locative argument;
- presence of a complement sentence;
- passive diatesis;
- subject and direct object, number, animacy and definiteness.



Data and method

- the same lexical item can exhibit different ET values in different contexts
- verbs can be more or less polysemous
- groups:
 - 60%:** most frequent ET covers $\leq 60\%$ of their tokens
 - 70%:** most frequent ET covers $\leq 70\%$ of their tokens
 - 80%:** most frequent ET covers $\leq 80\%$ of their tokens
 - 90%:** most frequent ET covers $\leq 90\%$ of their tokens



Data and method

Maximum Entropy classifiers (Berger 1996)

$p(a|c)$ is found assuming that the distributions of a set of relevant features $f_i(a, c)$ of c are the only probabilistic constraints involved

task: find the most likely ET given a context c :

$$\operatorname{argmax} (p(a | c))$$

$$p(a | c) = \frac{1}{Z_c} \prod_{i=1}^k a_i^{f_i(a, c)}$$

training phase: feature weights estimated with GIS (Generalized Iterative Scaling) algorithm on the training contexts

test phase: weights combined to compute the most likely ET for each new context

Experiment 1

	Baseline	Exp 1
60 % group	56.1%	69.3%
70 % group	60%	72.8%
80 % group	64.6%	75.5%
90 % group	69.6%	78.4%
Whole corpus	79.8%	85.4%

Table: model accuracy

- whole set of features
- most frequent mistakes: non-finite clauses and idiomatic senses



Experiment 2

- to show the contribution to event type classification offered by feature subsets corresponding to specific types of linguistic information
- optimal precision and recall values with the complete feature set

	ACT	STA	ACC	ACH
	adv feat			
precision:	0.49	0.35	0.29	0.66
recall:	0.05	0.1	0	0.14
f-measure:	0.09	0.15	0	0.24
	morph feat			
precision:	0.36	0.38	0.15	0.53
recall:	0.08	0.62	0	0.49
f-measure:	0.13	0.47	0	0.51

ACT	STA	ACC	ACH
synt-arg feat			
0.89	0.79	0.78	0.86
0.66	0.7	0.92	0.88
0.76	0.75	0.84	0.87
whole set			
0.84	0.83	0.84	0.88
0.74	0.78	0.89	0.9
0.79	0.8	0.86	0.89

Table: Precision and recall results from experiment 2

Experiment 3

- 3 different models, a 2-way classification: *durative* vs. *non-durative*, *dynamic* vs. *non-dynamic*, *telic* vs. *non-telic*
- higher baseline
- baseline outperformed, durativity appears to be the hardest feature to discriminate

	Baseline	Exp 3		Baseline	Exp 3		Baseline	Exp 3
	+/- DUR			+/- DIN			+/- TEL	
60 % group	63.9%	72.8%		60.9%	79.9%		56.9%	79.5%
70 % group	68.3%	74.3%		62.2%	84.9%		66.8%	81.7%
80 % group	75.5%	79.1%		70%	85.4%		71.9%	83.2%
Whole group	88.3%	90.6%		87.7%	92%		84.4%	89.9%

Table: Model accuracy in 2-way classification

Data and method

- 40 Italian verbs from “La Repubblica” (Baroni 2004), high degree of prototypicality with respect to ET
- each verb = distributional vector of co-occurrence frequencies with a number of contextual features
- two verbs with similar context feature distributions = similar ET values

Self-Organizing Maps (SOM, Kohonen 1997)

unsupervised neural network, used to project n -dimensional vectors into a 2-dimensional space (map) preserving the topological properties of the input space

Experiment 4

honeycomb map of 100 nodes

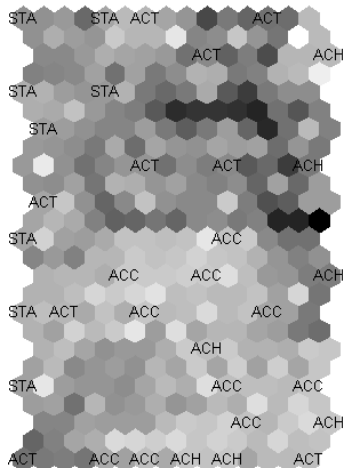


Figure: Experiment 4: the SOM

Experiment 4

honeycomb map of 100 nodes

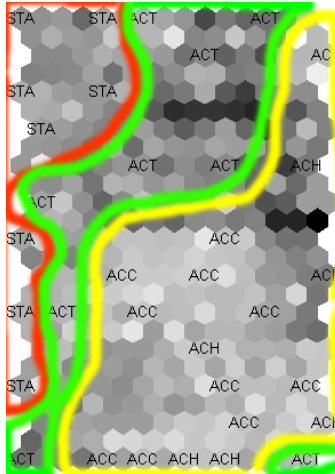


Figure: Experiment 4: the SOM

Experiment 5

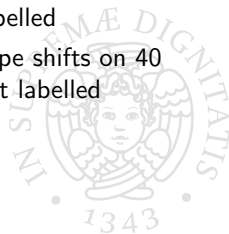
- how to model ET shifts with an unsupervised model?
- how to evaluate an unsupervised model for ET classification?



analogy with IR vector space model: an “Aktionsart semantic space”,
context-driven shifts move a verb towards a new class

training phase: SOM trained as in Experiment 4, then labelled

test phase: SOM used to model context-driven event type shifts on 40
new contexts (for each test item, the nearest labelled
BMU is looked for)



Experiment 5

	ACT	STA	ACC	ACH
ACT	1	0	1	0
STA	2	3	4	2
ACC	1	0	6	0
ACH	0	1	9	10
precision:	0.25	0.75	0.3	0.83
recall:	0.5	0.27	0.86	0.5
f-measure:	0.33	0.4	0.44	0.63
accuracy:	50%			

	ACT	STA	TEL
precision:	0.25	0.75	0.78
recall:	0.5	0.27	0.93
f-measure:	0.33	0.4	0.85
accuracy:	72.5%		

Table: Precision and recall results from experiment 5



Conclusions

Event type classification: highly challenging task

- interaction of various contextual factors
- not a trivial task even for humans

Two models: both supervised and unsupervised approaches can account for the contribution of contextual features in identifying the sentence event type

Stochastic algorithms: able to grasp the complex interaction of contextual features (probabilistic cues)

Computational models of ET classification in context can help to

- shed new light on the real structure of event type classes
- gain a better understanding of context-driven semantic shifts