

CHAPTER II Polynomial Interpolation

Any polynomial can be represented in the following form,

$$P_n(x) = a_0x^0 + a_1x^1 + a_2x^2 + a_3x^3 + \dots + a_nx^n$$

Where, variable = x
degree = n

constant coefficients = $\{a_0, a_1, a_2, \dots, a_n\}$

basis set = $\{x^0, x^1, x^2, \dots, x^n\}$

Some other attributes are,

dimensional space = $(n+1)$ = # of elements in the coeff set or the basis set

Thus, polynomials can be considered as vectors, where a polynomial of degree n , $P_n(x)$ belongs to a vector space of $(n+1)$ dimension.

Basis Vector

a set of vectors that spans the whole vector space

$$P_n(x) \in V^{n+1}$$

Weierstrass Approximation Theorem (has to be real & continuous)

For a continuous function $f(x)$ on a bounded interval can be uniformly approximated as closely as desired by a polynomial function, with high enough degree.

$$f(x) \Rightarrow \text{approximated} \Rightarrow P_n(x)$$

$$f(x) \in V^\infty$$

$$P_n(x) \in V^{n+1}$$

$n \uparrow$ error \downarrow

$n \downarrow$ error \uparrow

$$\max |f(x) - P_n(x)| < \epsilon; \text{ where } \epsilon > 0$$

$$\lim_{n \rightarrow \infty} \frac{f^{(n)}(x) - f^{(n)}(x_0)}{n!} = 0$$

Taylor Series

As we know, any cont. func. can be converted to a polynomial of infinite dimensions.

$$\text{So, } f(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3 + a_4 x^4 + \dots$$

We can also write this as,

$$\text{Eq 1 } f(x) = a_0 + a_1(x-x_0) + a_2(x-x_0)^2 + a_3(x-x_0)^3 + a_4(x-x_0)^4 + \dots$$

where, x_0 is a constant.

$$\text{Eq 2 } f'(x) = 0 + a_1 + 2a_2(x-x_0) + 3a_3(x-x_0)^2 + 4a_4(x-x_0)^3 + \dots$$

$$\text{Eq 3 } f''(x) = 0 + 0 + 2 \cdot 1 \cdot a_2 + 3 \cdot 2 \cdot a_3(x-x_0) + 4 \cdot 3 \cdot a_4(x-x_0)^2 + \dots$$

$$\text{Eq 4 } f'''(x) = 0 + 0 + 0 + 3 \cdot 2 \cdot 1 \cdot a_3 + 4 \cdot 3 \cdot 2 \cdot a_4(x-x_0) + \dots$$

If we consider x to be x_0 ($x = x_0$) then,

$$\text{from Eq 1 } f(x_0) = a_0 \Rightarrow a_0 = f(x_0)$$

$$\text{Eq 2 } f'(x_0) = a_1 \Rightarrow a_1 = \frac{f'(x_0)}{1} = f'(x_0)$$

$$\text{Eq 3 } f''(x_0) = 2 \cdot 1 \cdot a_2 \Rightarrow a_2 = \frac{f''(x_0)}{2!}$$

$$\text{Eq 4 } f'''(x_0) = 3 \cdot 2 \cdot 1 \cdot a_3 \Rightarrow a_3 = \frac{f'''(x_0)}{3!}$$

Replacing $\{a_0, a_1, a_2, a_3, \dots\}$ in equation 1 we get,

$$f(x) = f(x_0) + f'(x_0)(x-x_0) + \frac{f''(x_0)}{2!}(x-x_0)^2 + \frac{f'''(x_0)}{3!}(x-x_0)^3 + \dots$$

General Structure of Taylor series.

$$f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(x_0)}{n!} (x-x_0)^n$$

Maclaurin Series is just a special case of Taylor Series where $x_0 = 0$

Thus, we get,

$$\sin(x) = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots$$

Taylor's Theorem (Error Analysis)

Let f be $n+1$ differentiable on (a, b) and $f^{(n)}$ to be continuous on $[a, b]$.

If $x, x_0 \in [a, b]$ then there exists $\xi \in (a, b)$ such that,

$$f(x) = \underbrace{\sum_{k=0}^n \frac{f^{(k)}(x_0)}{k!} (x-x_0)^k}_{\text{Taylor polynomial of degree } n} + \underbrace{\frac{f^{(n+1)}(\xi)}{(n+1)!} (x-x_0)^{n+1}}_{\substack{\text{Lagrange form or} \\ \text{remainder} \\ \text{Basically error}}}$$

↑

Truncated a polynomial of degree ∞ to n due to the limitation of computation.

Taylor Series

$$f(x) = \sum_{k=0}^{\infty} \frac{f^{(k)}(x_0)}{k!} (x-x_0)^k \quad \parallel \text{Infinite series}$$

$$f(x) = \sum_{k=0}^n \frac{f^{(k)}(x_0)}{k!} (x-x_0)^k + \frac{f^{(n+1)}(\xi)}{(n+1)!} (x-x_0)^{n+1}$$

Example

$$x^3 \quad x^5 \quad x^7 \quad x^9$$

$n=6$

$$T(x) = \sin(x) = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \frac{x^9}{9!} - \dots$$

Let's consider if we truncate till $n=6$

$$\frac{f^{(7)}(z)}{7!} (x-x_0)^7$$

$$\text{So, } f(x) = P_6(x) + \frac{f^{(7)}(z)}{7!} (x-x_0)^7$$

$$|f^{(7)}(\sin x)| = -\sin x$$

$$\Rightarrow |f(x) - P_6(x)| = \left| \frac{f^{(7)}(z)}{7!} (x-x_0)^7 \right|$$

$$\Rightarrow \underbrace{|f(x) - P_6(x)|}_{\substack{\downarrow \\ 0.1}} = \frac{(0.1-0)^7}{7!} \underbrace{|-\sin(z)|}_{\substack{\downarrow \\ 0.1}}$$

considering $x_0=0$
 $x=0.1$

the value is bounded in $[0,1]$

taking the maximum possible error we get,

$$\frac{|f(0.1) - P_6(0.1)|}{\text{Error}} \leq \underline{\underline{1.98412 \times 10^{-11}}}$$

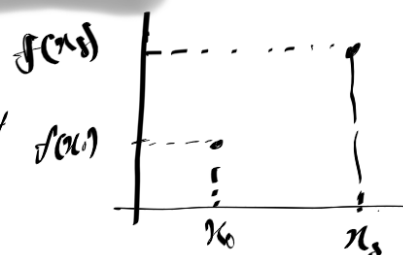
the value found from the polynomial $P_6(0.1)$ will be accurate upto atleast 11 digit after the decimal point.

See how the curve changes with the increased value of k

<https://www.desmos.com/calculator/7zxy20wqbc>

Polynomial Interpolation & Vandermonde Matrix

So far we predicted the value of any random point x' point in a $f(x)$ curve

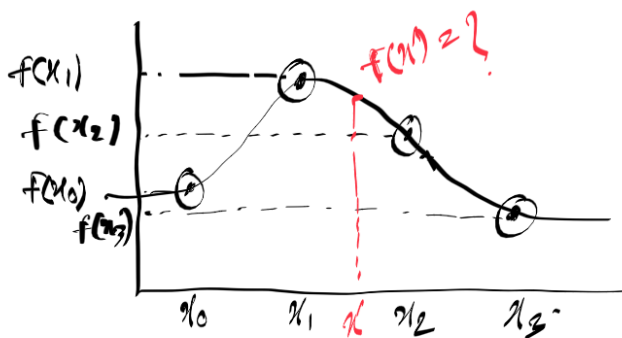


Known values $f(x_0)$, $f'(x_0)$, $f''(x_0)$, $f'''(x_0)$...

(But now we have multiple points $(x_0, f(x_0)), (x_1, f(x_1))$

$(x_2, f(x_2)), \dots$ then we would like to find any polynomial that will go through all of them.

Polynomial Interpolation - Populating some polynomial of n degree where $(n+1)$ nodes are known, and the polynomial will go through all the points
 Node Set, $N = \{(x_0, f(x_0)), (x_1, f(x_1)), \dots, (x_n, f(x_n))\}$
 item $(n+1)$



x_0	\rightarrow	$f(x_0)$	known values
x_1	\rightarrow	$f(x_1)$	
x_2	\rightarrow	$f(x_2)$	
\vdots		\vdots	
x_n	\rightarrow	$f(x_n)$	

\leftarrow the polynomial $P_n(x)$ will have to go through all these points

$N \rightarrow$ will generate $\rightarrow P_n(x)$ So.
 $P_n(x') = f(x')$

Let's consider, if there were 2 nodes, so the polynomial would be of degree $n=1$

Nodes	x_0	$f(x_0)$
	x_1	$f(x_1)$

So, the polynomial will be in the form,

$$P_1(x) = a_0 + a_1 x$$

these are unknown.

$$\begin{cases} P_1(x_0) = a_0 + a_1 x_0 = f(x_0) & \dots \text{eq. (1)} \\ P_1(x_1) = a_0 + a_1 x_1 = f(x_1) & \dots \text{eq. (2)} \end{cases}$$

$$\begin{bmatrix} 1 & x_0 \\ 1 & x_1 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \end{bmatrix} = \begin{bmatrix} f(x_0) \\ f(x_1) \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} a_0 \\ a_1 \end{bmatrix} = \begin{bmatrix} 1 & x_0 \\ 1 & x_1 \end{bmatrix}^{-1} \begin{bmatrix} f(x_0) \\ f(x_1) \end{bmatrix}$$

Now, if we consider $(n+1)$ number of nodes, we can come up with,

$$\begin{matrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \\ \vdots \\ a_n \end{bmatrix} & = & \begin{bmatrix} 1 & x_0 & x_0^2 & x_0^3 & \dots & x_0^n \\ 1 & x_1 & x_1^2 & x_1^3 & \dots & x_1^n \\ 1 & x_2 & x_2^2 & x_2^3 & \dots & x_2^n \\ 1 & x_3 & x_3^2 & x_3^3 & \dots & x_3^n \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_n & x_n^2 & x_n^3 & \dots & x_n^n \end{bmatrix}^{-1} & \begin{bmatrix} f(x_0) \\ f(x_1) \\ f(x_2) \\ f(x_3) \\ \vdots \\ f(x_n) \end{bmatrix} \end{matrix}$$

(A)
Vandermonde Matrix (V)
(F)

So, $A = V^T F$ Issue: inverse matrix requires $O(n^3)$

Uniqueness aka Existence Theorem

given $(n+1)$ nodes there exists a polynomial $P_n \in V^{n+1}$ that interpolates the function $f(x)$

Let's consider any function could be interpolated by both $P_n(x)$ and $Q_n(x)$

$$r_n(x) := P_n(x) - Q_n(x) \quad \text{where, } r_n \text{ has degree } \leq n$$

So, for, $r_n(x_i) = P_n(x_i) - Q_n(x_i) = 0$ and for all points $i = 0, 1, \dots, n$

$(r_n(x) = 0) \Rightarrow$ so, $r_n(x)$ should have $(n+1)$ roots

but, a n degree ^{non zero} polynomial should have n roots, but the
 $r_n(x)$ should have n roots.

So, $r_n(x) = 0$