Randomized Matrix Computations Lecture 3

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Trace Estimation

- Motivation
- Analysis

Literature:

Tropp'2023 Joel A. Tropp. *Probability Theory & Computational Mathematics*, Lecture notes, Caltech, 2023.

MT'2020 Per-Gunnar Martinsson and Joel A. Tropp.
Randomized numerical linear algebra: Foundations and algorithms. Acta Numerica'2020.

pdf available on Moodle

Computing determinants

For $n \times n$ matrix A consider determinant

$$\det(A) \coloneqq \sum_{\text{permutation } \sigma} \operatorname{sign}(\sigma) \cdot a_{1,\sigma(1)} \cdot a_{2,\sigma(2)} \cdots a_{n,\sigma(n)}.$$

How would you compute/approximate $\log \det(A)$ numerically?

Computing determinants

For $n \times n$ matrix A consider determinant

$$\det(A) \coloneqq \sum_{\text{permutation } \sigma} \operatorname{sign}(\sigma) \cdot a_{1,\sigma(1)} \cdot a_{2,\sigma(2)} \cdots a_{n,\sigma(n)}.$$

How would you compute/approximate $\log \det(A)$ numerically?

- For $n = O(10^3)$: Via LU factorization PA = LU. $\det(A) = \det(L) \det(U) / \det(P)$
- ► For large *n* and sparse *A*: Via sparse LU factorization.
- For large n and A can only be accessed through matvec products: Assuming that A is symm pos def → Stochastic trace estimator applied to trace log(A) = log det(A).

EFY: Verify trace log(A) = log det(A). What if A is symmetric but not pos def?

Goal of trace estimation:

Compute (an approximation of) trace(A) for large-scale symmetric matrix $A \in \mathbb{R}^{n \times n}$.

Only matvec products with A are available.

Motivation

Example 1: Trace of matrix functions / Determinant

Matrix functions: For symmetric A, given a spectral decomposition $A = Q \cdot \operatorname{diag}(\lambda_1, \dots, \lambda_n) \cdot Q^{\mathsf{T}}$, the matrix function f(A) is defined as

$$f(A) = Q \cdot \operatorname{diag}(f(\lambda_1), \ldots, f(\lambda_n)) \cdot Q^{\mathsf{T}}.$$

Computing f(A)v is faster than computing f(A)!

- Trace(A⁻¹) (Uncertainty quantification [Kalantzis/Bekas/Curioni/ Gallopoulos'2013], Lattice quantum chromodynamics [Wu et al.'2016])
- Network analysis (exp(A), Estrada index)
- Determinant of sym. positive definite A via log det(A) = trace(log A)

Example 2: Frobenius norm estimation $\|B\|_F^2 = \operatorname{trace}(B^T B)$ and other Schatten-p norms [Gratton/Titley-Peloquin'2018,

Dudley/Saibaba/Alexanderian'2021]

Applications of log determinant

Statistical learning



Y. Zhang & W. E. Leithead Approximate implementation of the logarithm of the matrix determinant in Gaussian process regression (Journal of Statistical Computation and Simulation, 2007)



R. H. Affandi, E. Fox, R. Adams, and B. Taskar. Learning the parameters of determinantal point process kernels. (International Conference on Machine Learning 2014)



 Han, D. Malioutov, and J. Shin Large-scale log-determinant computation through stochastic Chebyshev expansions. (International Conference on Machine Learning 2015)



K. Dong, D. Eriksson, H. Nickisch, D. Bindel, and A. Wilson. Scalable Log Determinants for Gaussian Process Kernel Learning. (NeurIPS 2017)



J. R. Gardner, G. Pleiss, D. Bindel, K. Q. Weinberger, and A. G. Wilson. GPy-Torch: Blackbox matrix-matrix Gaussian process inference with GPU acceleration. (NeurIPS 2018)

Lattice quantum chromodynamics



C. Thron, S. J. Dong, K. F. Liu, and H. P. Ying. Padé- Z_2 estimator of determinants. Physical Review D - Particles, Fields, Gravitation and Cosmology, 1998)

- Markov random fields models
- Graph theory: det = number of spanning trees

Motivation



J. R. Gardner, G. Pleiss, D. Bindel, K. Q. Weinberger, and A. G. Wilson. GPy-Torch: Blackbox matrix-matrix Gaussian process inference with GPU acceleration. (NeurlPS 2018)

Gaussian process: Distribution with mean $\mu(\cdot)$ and covariance kernel $k(\cdot,\cdot)$.

Goal: Train Gaussian process on *lots* of data (up to 500k points), that is, given a class of possible k depending on some *hyperparameters* θ , find θ that best fit the data by minimizing

$$L(\theta \mid \text{training data } X, y) := \log \det(K) - y^{\mathsf{T}} K^{-1} y,$$

where *K* is the discretization of $k(\cdot, \cdot)$ on $X \times X$.

Cholesky decomposition of K too expensive \rightarrow stochastic trace estimation.



S. Ubaru, J. Chen, and Y. Saad. Fast estimation of tr(f(A)) via stochastic Lanczos quadrature. (SIAM J. Matrix Anal. Appl., 2017)

Randomized trace estimation

We call a real random vector X isotropic if $\mathbb{E}[XX^{\top}] = I$. Most common choices:

- Rademacher vectors (±1 entries);
- Gaussian vectors $(X \sim \mathcal{N}(0, I_n))$

Theorem [Girard-Hutchinson trace estimation] For an isotropic random vector *X* it holds that

$$\mathbb{E}\big[X^{\scriptscriptstyle \top} A X\big] = \operatorname{trace}(A).$$

Proof.
$$\mathbb{E}[X^T A X] = \sum_{i,j} \mathbb{E}[X_i X_j] a_{ij} = \sum_i a_{ii} = \operatorname{trace}(A).$$

Idea: Take N independent copies $X^{(1)}, \dots, X^{(N)}$ of X and approximate

trace(A)
$$\approx \frac{1}{N} \sum_{i=1}^{N} (X^{(i)})^{\top} AX^{(i)}$$
.

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♦

Randomized trace estimation: Example

trace(A)
$$\approx$$
 trace_N(A) := $\frac{1}{N} \sum_{i=1}^{N} (X^{(i)})^{\mathsf{T}} A X^{(i)}$

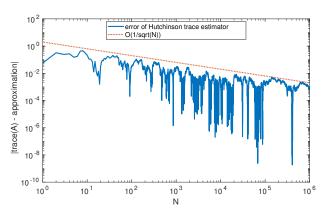


Figure: Behavior of $|\operatorname{trace}(A) - \operatorname{trace}_N(A)|$ when increasing N (# probe vectors).

Chebyshev

Aim to study convergence of $trace_N(A)$ as N increases.

$$\operatorname{Var}\big[\operatorname{trace}_{N}(A)\big] = \frac{1}{N^{2}} \sum \operatorname{Var}\big[(X^{(i)})^{\top}AX^{(i)}\big] = \frac{1}{N} \operatorname{Var}\big[X^{\top}AX\big]$$

Variance depends on choice of X (EFY: Verify these identities):

Rademacher $\Rightarrow Var(X^TAX) = 2||A - diag(A)||_F^2$

Gaussian $\Rightarrow \operatorname{Var}(X^{T}AX) = 2\|A\|_{F}^{2}$.

Chebyshev's inequality gives

$$\mathbb{P}\left\{|\operatorname{trace}_{N}(A) - \operatorname{trace}(A)| \geq \epsilon\right\} \leq \operatorname{Var}(X^{\top}AX)\epsilon^{-2}N^{-1} \leq 2\|A\|_{F}^{2}\epsilon^{-2}N^{-1}.$$

If A is spd, we have $||A||_F^2 \le ||A||_2 \operatorname{trace}(A)$ and can get a relative error bound:

$$\mathbb{P}\{|\operatorname{trace}_{N}(A) - \operatorname{trace}(A)| \ge \epsilon \cdot \operatorname{trace}(A)\} \le 2\rho(A)^{-1} \epsilon^{-2} N^{-1},$$

where $\rho(A) := \operatorname{trace}(A) / ||A||_2$ is called intrinsic dimension of A.

Chebyshev: $N = O(\frac{1}{\delta \rho(A)\epsilon^2})$ needed for rel acc ϵ^{-2} with prob 1 – δ .

Improved bounds: Rademacher

Chebyshev only takes variance into account \sim suboptimal dependence on δ .

Now assume that X is Rademacher.

EFY: Show that Hoeffding's inequality leads to

$$\mathbb{P}\left\{|\operatorname{trace}_{N}(A) - \operatorname{trace}(A)| \ge \epsilon\right\} \le \exp\left(-\frac{2\epsilon^{2}N}{\|A\|_{2}^{2}n^{2}}\right).$$

Conclude that for spd A, $N = O(\frac{\log \delta^{-1} n^2}{\rho(A)^2 \epsilon^2})$ needed for rel acc ϵ^{-2} with prob $1 - \delta$. Improved depend. on δ but unpleasant depend. on n. (unless stable rank is large)

EFY: Show that Bernstein's inequality leads for traceless A to

$$\mathbb{P}\left\{\left|\operatorname{trace}_{N}(A) - \operatorname{trace}(A)\right| \geq \epsilon\right\} \leq \exp\left(-\frac{\epsilon^{2}N}{4\|A\|_{F}^{2} + 2/3n\epsilon\|A\|_{2}}\right).$$

How can one incorporate a *nonzero* trace? Maintains improved depend. on δ and less crazy dependence on n.

Improved bounds: Rademacher

SOTA: Use Hanson-Wright inequality.

Theorem [Cortinovis/DK'2021] Let A be symmetric with diag(A) = 0.

Then

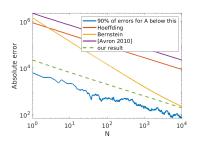
$$\mathbb{P}\left(\left|X^{\top}AX\right| \geq \varepsilon\right) \leq 2\exp\left(-\frac{\varepsilon^2}{8\|A\|_F^2 + 8\varepsilon\|A\|_2}\right).$$

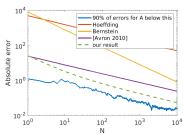
Embedding trick: write $\operatorname{trace}_{N}(A) = \frac{1}{N} \sum_{i=1}^{N} (X^{(i)})^{\top} A X^{(i)}$

$$= \underbrace{X^{(1)^{\mathsf{T}}}...X^{(N)^{\mathsf{T}}}} \cdot \underbrace{\begin{bmatrix} \frac{1}{N}A \\ & \frac{1}{N}A \\ & & \ddots \\ & & \frac{1}{N}A \end{bmatrix}}_{N} \cdot \underbrace{X^{(1)}}_{X^{(N)}} \leftarrow \mathsf{Rademacher}$$

Corollary. For $N \ge \frac{8}{\varepsilon^2} \left(\|A - \operatorname{diag}(A)\|_F^2 + \varepsilon \|A - \operatorname{diag}(A)\|_2 \right) \log \frac{2}{\delta}$ we have $\mathbb{P} \left(|\operatorname{trace}_N(A) - \operatorname{trace}(A)| \ge \varepsilon \right) \le \delta.$

Comparison of estimates





2000 × 2000 matrices:

- ▶ Left: A = randn(n); A = A + A';
- Right: d=[(1:n/2).^ (-2), -((n/2+1):n).^ (-2)];
 [Q,]=qr(randn(n)); A=Q*diag(d)*Q';

Blue curve: for each value of N, compute 20 trace estimates, throw away the worst 10%, and plot the largest error of the remaining estimates.

Improved bounds: Gaussian

Now, suppose that X is Gaussian and that A is symmetric (not necessarily pos def) with eigenvalues $\lambda_1, \ldots, \lambda_n$.

By unitary invariance

$$X^{T}AX - \text{trace}(A) = \lambda_{1}(Z_{1}^{2} - 1) + \dots + \lambda_{n}(Z_{n}^{2} - 1), \quad Z_{k} \sim N(0, 1) \text{ i.i.d.}$$

We already know that

$$\log \mathbb{E}\big[\exp\big(\theta(Z^2-1)\big)\big] = \log \frac{e^{-\theta}}{\sqrt{1-2\theta}} = -\frac{1}{2}\log(1-2\theta) - \theta \le \frac{\theta^2}{1-2\theta}$$

for θ < 1/2. Could continue with sub-exponential properties, but would give slightly sub-optimal bounds. Instead, one continues with

$$\log \mathbb{E}\big[\exp\big(\theta(X^{\mathsf{T}}AX - \operatorname{trace}(A))\big)\big] \leq \frac{\theta^2 \|A\|_F^2}{1 - 2\theta \|A\|_2}, \quad \theta < 1/(2\|A\|_2).$$

Chernoff gives Hanson-Wright inequality

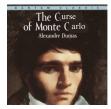
$$\mathbb{P}\left(|X^{\mathsf{T}}AX - \operatorname{trace}(A))| \geq \varepsilon\right) \leq 2 \exp\left(-\frac{\varepsilon^2}{4\|A\|_{\mathsf{F}}^2 + 4\varepsilon\|A\|_2}\right).$$

Conclude with embedding trick. (Vershynin: Technique works for all sub-Gaussian vectors!).

The curse of Monte Carlo

For Rademacher/Gaussian, we were able to improve dependence on δ and properties of A, but not on ϵ^{-2} !

The central limit theorem tells us that



$$\sqrt{N}(\operatorname{trace}_N(A) - \operatorname{trace}(A)) \to N(0, \operatorname{Var}[X^T A X])$$
 (in distribution)

For sufficiently large N, we expect the error to behave like $\sqrt{N} \cdot Z \sim N(0, \text{Var}[X^{T}AX])$. We already know that

$$\mathbb{P}\{\sqrt{N}Z \ge \epsilon\} \le \exp(-\epsilon^2/(4\|A\|_F^2))$$

and, hence,

$$\mathbb{P}\{Z \ge \epsilon\} \le \exp(-N\epsilon^2/(4\|A\|_F^2)).$$

It follows that $N \sim \epsilon^{-2}$ is needed to attain constant failure probability.

In order to improve convergence of Monte Carlo (with respect to ϵ), need to reduce variance!