

# Randomized Matrix Computations Lecture 5

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# Random Embeddings

- ▶ Overdetermined least-squares
- ▶ JL and subspace embeddings
- ▶ Gaussian embeddings
- ▶ Structured random embeddings
- ▶ Overdetermined least-squares revisited
- ▶ Sketched Gram-Schmidt
- ▶ Kaczmarz

## Literature:

[Tropp'2020](#) Joel A. Tropp. *Randomized Algorithms for Matrix Computations*, Lecture notes, Caltech, 2020.

[Vershynin'2012](#) Roman Vershynin. *Introduction to the non-asymptotic analysis of random matrices*. In “Compressed Sensing, Theory and Applications”. CUP'2012.

[Vershynin'2018](#) Roman Vershynin's HDP.  
pdf available on Moodle

# Overdetermined least-squares problems

Consider overdetermined least-squares problem

$$\min\{\|Ax - b\|_2 : x \in \mathbb{R}^m\}, \quad A \in \mathbb{R}^{d \times m}, \quad b \in \mathbb{R}^d.$$

*Assumptions:*  $d$  (number of observations)  $\gg m$  (number of variables).  
 $A$  has full rank  $m \leadsto$  solution  $x$  uniquely determined

Classical approach:

- ▶ Compute  $QR$  decomposition  $A = QR$  s.t.  $R \in \mathbb{R}^{m \times m}$  is upper triangular and  $Q \in \mathbb{R}^{d \times m}$  has orthonormal columns.
- ▶ Solve reduced problem  $Rx = Q^\top b$ .

Reinterpretation: The application of  $Q^\top$  produces a *sketch*  $Q^\top A \approx Q^\top b$  of  $Ax \approx b$  and we obtain the solution of the original problem from solving the sketched problem.

# Overdetermined least-squares problems

Idea of **sketching**: Replace  $Q^T \in \mathbb{R}^{m \times d}$  by more general sketching matrix  $S \in \mathbb{R}^{n \times d}$  with  $m \leq n \ll d$  and solve sketched problem

$$\min\{\|SA\tilde{x} - Sb\|_2 : \tilde{x} \in \mathbb{R}^m\}. \quad (1)$$

A good sketching matrix  $S$  should approximately capture the range of  $A$  and (optionally)  $b$ . A common way to quantify this is the subspace embedding property. Given subspace  $\mathcal{U} \subset \mathbb{R}^d$ ,  $S$  is called an  **$\epsilon$ -subspace embedding** for  $0 < \epsilon < 1$  if

$$(1 - \epsilon)\|u\|_2^2 \leq \|Su\|_2^2 \leq (1 + \epsilon)\|u\|_2^2 \quad \forall u \in \mathcal{U}.$$

**Lemma (sketch and solve)**. Suppose that  $\tilde{x}$  solves the sketched least-squares problem (1) with an  $\epsilon$ -subspace embedding  $S$  of the subspace  $\text{span}([A, b])$ . Then

$$\|A\tilde{x} - b\|_2^2 \leq \frac{1 + \epsilon}{1 - \epsilon} \|Ax - b\|_2^2.$$

# Overdetermined least-squares problems

*Proof of Lemma.* Let  $x$  solve  $\min \|Ax - b\|_2$ . Then

$$\begin{aligned}\|A\tilde{x} - b\|_2^2 &\leq \frac{1}{1 - \epsilon} \|SA\tilde{x} - Sb\|_2^2 \leq \frac{1}{1 - \epsilon} \|SAx - Sb\|_2^2 \\ &\leq \frac{1 + \epsilon}{1 - \epsilon} \|Ax - b\|_2^2,\end{aligned}$$

where we used that  $Ax - b, A\tilde{x} - b \in \text{span}([A, b])$ . ◇

A trivial subspace embedding (with  $\epsilon = 0$ ) is to take  $S = U^\top$ , where  $U$  is an orthonormal basis of  $\text{span}([A, b])$ . But this is not what the lemma is aiming for. We aim for cheap constructions that use little or even no information about  $A, b$ .

# OSE

A subspace embedding is called oblivious if it works for an arbitrary subspace.

**Definition** A  $(k, \epsilon, \delta)$ -Oblivious Subspace Embedding (OSE) is a random matrix  $S$  such that, for a *fixed but arbitrary*  $k$ -dimensional subspace  $\mathcal{U} \subset \mathbb{R}^d$ ,  $S$  is an  $\epsilon$ -subspace embedding with probability at least  $1 - \delta$ , that is,

$$(1 - \epsilon) \|u\|_2^2 \leq \|Su\|_2^2 \leq (1 + \epsilon) \|u\|_2^2 \quad \forall u \in \mathcal{U} \quad (2)$$

holds.<sup>1</sup>

EFY. Let  $U \in \mathbb{R}^{n \times k}$  be an orthonormal basis for  $\mathcal{U}$ . Show that each of the following properties is equivalent to OSE:

1.  $\max\{\|\|Su\|_2^2 - 1\| : u \in \mathcal{U}, \|u\|_2 = 1\} \leq \epsilon$
2.  $\sigma_{\min}(SU)^2 \geq 1 - \epsilon, \sigma_{\max}(SU)^2 \leq 1 + \epsilon$
3.  $\lambda_{\min}(U^T S^T S U) \geq 1 - \epsilon, \lambda_{\max}(U^T S^T S U) \leq 1 + \epsilon$
4.  $\|I - U^T S^T S U\|_2 \leq \epsilon$

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<sup>1</sup>One sometimes finds this definition without the squares. This only makes a marginal difference.

# OSE and a second encounter with JL

For  $k = 1$ , OSE reduces to JL.

**Definition** A random matrix  $S$  satisfies the  $(\epsilon, \delta)$ -**Johnson-Lindenstrauss (JL) property** if for a *fixed but arbitrary* vector  $u$  the inequalities

$$(1 - \epsilon)\|u\|_2^2 \leq \|Su\|_2^2 \leq (1 + \epsilon)\|u\|_2^2 \quad (3)$$

hold with probability at least  $1 - \delta$ .

We have already seen that  $S = \Omega/\sqrt{n}$  for  $n \times d$  Gaussian random matrix satisfies the  $(\epsilon, \delta)$ -JL property if

$$n \geq 8\epsilon^{-2} \log 2/\delta.$$

Bad dependence on  $\epsilon$ ; great dependence on  $\delta$ !

# From JL to OSE

When extending JL to OSE for  $k$ -dimensional subspaces  $\mathcal{U} \subset \mathbb{R}^d$ , the union bound suffers from the obvious problem that  $\mathcal{U}$  contains infinitely many vectors. Popular techniques in stochastic analysis to overcome such problems: **epsilon nets** and **chaining**.

**Idea of  $\epsilon$ -nets:** Given ONB  $U \in \mathbb{R}^{d \times k}$ , every (normalized) vector in  $\mathcal{U}$  takes the form  $Ux$ ,  $x \in S^{k-1}$  (unit sphere in  $\mathbb{R}^k$ ). Cover the sphere with vectors up to a distance  $\epsilon = O(1)$  and use union bound. MANY vectors will be needed, so  $O(|\log \delta|)$  dependence of JL is needed to save us!

**Lemma 5.2 in Vershynin'2012.**  $S^{k-1}$  has an epsilon net  $\mathcal{N}_{\epsilon_{\text{net}}} \subset S^{k-1}$  of cardinality at most  $(1 + 2/\epsilon_{\text{net}})^k$ , that is, for every  $x \in S^{k-1}$  there is  $y \in \mathcal{N}_{\epsilon_{\text{net}}}$  such that

$$\|x - y\|_2 \leq \epsilon_{\text{net}}.$$

Think of  $\epsilon_{\text{net}}$  not too small, like  $\epsilon_{\text{net}} = 1/2$  or  $\epsilon_{\text{net}} = 1/4$ .



# From JL to OSE

For *symmetric*  $k \times k$  matrix  $C$ :  $\|C\|_2 = \max\{|x^\top Cx| : x \in S^{k-1}\}$ .

**Corollary.** Let  $N_{\epsilon_{\text{net}}}$  be epsilon net from Lemma. Then

$$\|C\|_2 \leq (1 - 2\epsilon_{\text{net}}^2)^{-1} \max\{|y^\top Cy| : y \in N_{\epsilon_{\text{net}}}\}.$$

*Proof.* Let  $x \in S^{k-1}$  s.t.  $Cx = \lambda_1 x$  and  $\|C\|_2 = |\lambda_1|$ . Let  $y \in N_{\epsilon_{\text{net}}}$  s.t.  $\|x - y\|_2 \leq \epsilon_{\text{net}}$ . Then

$$|y^\top Cy - x^\top Cx| = |(x - y)^\top (C - \lambda_1 I)(x - y)| \leq 2\|C\|_2 \|x - y\|_2^2 \leq 2\epsilon_{\text{net}}^2 \|C\|_2.$$

This implies  $|y^\top Cy| \geq |x^\top Cx| - |x^\top Cx - y^\top Cy| \geq (1 - 2\epsilon_{\text{net}}^2) \|C\|_2. \quad \diamond$

# From JL to OSE

**Theorem.** Any random matrix  $S$  satisfying the  $(\epsilon/2, \delta/5^k)$ -JL property also satisfies the  $(k, \epsilon, \delta)$ -OSE property.

*Proof.* Choose  $\epsilon = 1/2$ . By JL we have

$$|y^\top (I - U^\top S^\top S U) y| \leq \epsilon/2 \quad \text{with probability} \geq 1 - \delta/5^k.$$

for arbitrary  $y \in S^{k-1}$ . By the union bound this shows JL holds for all vectors in  $\mathcal{N}_{1/2}$  with prob  $\geq 1 - \delta$ . By the corollary,

$$\|I - U^\top S^\top S U\|_2 \leq 2 \max\{|y^\top (I - U^\top S^\top S U) y| : y \in \mathcal{N}_{1/2}\} \leq \epsilon,$$

which shows OSE. ◇

By JL for Gaussian random matrices, this establishes OSE if

$$n \geq 32\epsilon^{-2}(k \log 5 + \log 2/\delta) = \mathcal{O}(\epsilon^{-2}(k + \log \delta^{-1})).$$

This general construction gets the asymptotics right, but the constants are slightly too large.

## Tighter bounds on Gaussian embeddings

Let  $\Omega$  be an  $n \times k$  Gaussian random matrix. Then Section 7.3 of [Vershynin'2018] shows the following properties:

$$\mathbb{E}\|\mathbf{A}\|_2 \leq \sqrt{n} + \sqrt{k}, \quad \mathbb{E}\sigma_{\min}(\mathbf{A}) \geq \sqrt{n} - \sqrt{k}.$$

Now let  $S$  be an  $n \times d$  Gaussian random matrix scaled by  $1/\sqrt{n}$ . Then, by invariance of Gaussian random vectors under rotations,  $\tilde{\Omega} = SU$  is  $n \times k$  Gaussian random matrix scaled by  $1/\sqrt{n}$ . Section 8.5 in [Martinson/Tropp] shows

$$\mathbb{P}\left\{\sigma_{\min}(\tilde{\Omega}) \leq 1 - \frac{\sqrt{k} + 1}{\sqrt{n}} - t\right\} \leq e^{-nt^2/2}$$

$$\mathbb{P}\left\{\|\tilde{\Omega}\|_2 \geq 1 + \frac{\sqrt{k}}{\sqrt{n}} + t\right\} \leq e^{-nt^2/2}$$

EFY: Show that these bounds imply that  $S$  is  $(k, \epsilon, \delta)$ -OSE if

$$n \geq 4\epsilon^{-2}(1 + k + \log 2/\delta).$$

# OSE beyond Gaussians

Results essentially extend to matrices with sub-Gaussian iid entries (e.g., Rademacher).

Sketching arbitrary  $d \times m$  matrix  $A$  with  $n \times d$  (sub-)Gaussian matrix  $S$  requires require  $O(ndm) = O(kdm)$  operations. Can be reduced by imposing structure on  $S$ .

Most popular choices for structured random embeddings:

- ▶ Coordinate sampling
- ▶ Sparse sign matrices
- ▶ Subsampled unitary transforms
- ▶ Khatri-Rao products

# Coordinate sampling

An immediate and cheap choice:

$$S = \begin{bmatrix} \mathbf{s}_1^\top \\ \mathbf{s}_2^\top \\ \vdots \\ \mathbf{s}_n^\top \end{bmatrix}, \quad \mathbf{s}_i \text{ are iid with } \mathbb{P}\{\mathbf{s}_i = \mathbf{e}_j / \sqrt{p_j n}\} = p_j,$$

for unit vectors  $\mathbf{e}_1, \dots, \mathbf{e}_d \in \mathbb{R}^d$  and prescribed sampling probabilities  $p_1, \dots, p_n$ .

- ▶ **Computing SA requires  $nm$  operations.** Looks like the LARGE dimension  $d$  disappeared!<sup>2</sup>
- ▶ OSE characterization 4 (see Slide 6) links to matrix Monte Carlo:

$$\|I - U^\top S^\top S U\|_F \leq \epsilon.$$

$(k, \epsilon, \delta)$ -OSE = Approximate matmul from Lecture 4 applied to  $U^\top U = I$  returns error  $\epsilon$  with probability  $\geq 1 - \delta$ .

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<sup>2</sup>well, well... this is not exactly true as we will see on the next slides

## Coordinate sampling: Uniform

Uniform sampling:  $p_1 = \dots = p_d = 1/d$ . Already know that performance depends on coherence

$$\mu(U) = d \cdot \max_{i=1, \dots, d} \|U(i, :)\|_2^2$$

- ▶  $\mu(U)$  is independent of choice of ONB  $U$  for  $\mathcal{U}$
- ▶  $k \leq \mu(U) \leq d$ . Smaller  $\mu(U)$  is better.

EFY: Prove lower bound. Can you find a matrix  $U$  that nearly attains lower bound?

Apply Matrix Monte Carlo Theorem (L4S16) with  $\|X\|_2$ ,  $\|\mathbb{E}[XX^\top]\|_2$ ,  $\|\mathbb{E}[X^\top X]\|_2$  bounded by  $\mu(U)$ :

$$\mathbb{P}\{\|I - U^\top S^\top S U\|_F \geq \epsilon\} \leq 2k \exp\left(-\frac{n\epsilon^2}{\mu(U)(1 + 2\epsilon/3)}\right).$$

Hence, given  $U$ ,  $S$  is  $\epsilon$ -subspace embedding for  $0 < \epsilon \leq 1$  with probability  $\geq 1 - \delta$  when

$$n \geq 2\mu(U)\epsilon^{-2}(\log(2k) + \log \delta^{-1}).$$

$\leadsto$  In the best case  $n = O(k \log k)$ . In the worst case  $n = O(d \log k)$  (completely useless).

## Coordinate sampling: Leverage scores

We now set

$$p_i = \frac{1}{k} \|U(i, :)\|_2^2, \quad i = 1, \dots, d. \quad (4)$$

By the discussion from L4S20, we can apply Matrix Monte Carlo Theorem with

$$\|X\|_2 \leq k, \quad \|\mathbb{E}[XX^\top]\|_2 \leq 2k, \quad \|\mathbb{E}[X^\top X]\|_2 \leq 2k.$$

Hence,  $S$  is  $(k, \epsilon, \delta)$ -subspace embedding for  $U$  with  $0 < \epsilon \leq 1$  when

$$n \geq 3k\epsilon^{-2}(\log(2k) + \log \delta^{-1}).$$

This looks good, but **subspace embedding is not oblivious**.

# Sparse sign matrices

Sparse sign matrices come in two flavors:

## 1. Fixed sparsity sign matrices:

Each *column* of  $S$  has exactly  $s$  (scaled)  $\pm 1$  entries at random locations.

Extreme case  $s = 1$ : OSE holds for  $n = O(k^2 \epsilon^{-2} \delta^{-1})$  [Nelson/Nguyen'2013].

Reasonable choice  $s = O(\epsilon^{-1} (\log k + \log \delta^{-1}))$ :  
OSE holds for  $n = O(\epsilon^{-2} k (\log k + \log \delta^{-1}))$  [Cohen'2016]

## 2. iid sparsity sign matrices: Consider random sparse sign matrix

$$S = \frac{1}{\sqrt{pn}} \begin{bmatrix} s_{11} & \cdots & s_{1d} \\ \vdots & & \vdots \\ s_{n1} & \cdots & s_{nd} \end{bmatrix} \in \mathbb{R}^{n \times d}, \text{ with iid } s_{ij} \text{ s.t. } \begin{aligned} \mathbb{P}(s_{ij} = +1) &= p/2, \\ \mathbb{P}(s_{ij} = -1) &= p/2, \\ \mathbb{P}(s_{ij} = 0) &= 1 - p. \end{aligned}$$

Scaling ensures that  $\mathbb{E}[S^\top S] = I_d$ .



# Sparse sign matrices

Focus on iid sparsity sign matrices in the following.

EFY: Show that  $\mathbb{E}\|Sx\|_2^2 = \|x\|_2^2$  for all  $x \in \mathbb{R}^d$ . An embedding satisfying this property is called **isotropic**.

Decompose

$$Y = U^T S^T S U = \frac{1}{pn} \sum_{j=1}^n U^T s_j s_j^T U = \sum_{j=1}^n X_j, \quad X_j := \frac{1}{pn} U^T s_j s_j^T U,$$

where  $s_j^T$  is  $j$ th row of  $S$ . Then  $\mathbb{E}Y = I$  and

$$\mathbb{E}\|X_j\|_2 = \frac{1}{pn} \mathbb{E}\|U^T s_j\|_2^2 = \frac{k}{n}, \quad \text{but} \quad \|X_j\|_2 = \frac{1}{pn} \|U^T s_j\|_2^2 \leq \frac{d}{pn}.$$

Unfortunate dependence on LARGE  $d$  in upper bound!

# Sparse sign matrices

Cohen'2016 / Tropp'2020: Truncation of distribution to cap large  $\|X_j\|$  + Chernoff.

Intuition of the argument: Need sufficiently large  $p$  to have concentration of norm:

$$p \gtrsim \epsilon^{-2} n^{-1} (\log k + \log \delta^{-1})$$

Chernoff gives  $(k, \epsilon, \delta)$ -OSE for

$$n \gtrsim \epsilon^{-2} k (\log k + \log \delta^{-1})$$

More refined analysis in [Tropp'2016] based on Matrix Rosenthal inequalities.

For fixed  $\epsilon^{-2}, \delta$ , there are  $O(d \log k)$  nonzero entries in  $S$   
 $\leadsto$  Sketching  $d \times m$  matrix requires  $O(md \log k)$  operations.

However, reduced dimension increases to  $k \log k$ . Idea: Apply another  $O(k \times k \log k)$  Gaussian sketch to bring dimension down to  $O(k)$ . Cheap when  $d \gg k^2$ .

# Subsampled trigonometric transforms

Idea: First apply (random) orthogonal transformation to assure incoherence. Then use uniform sampling.

**Theorem [Avron et al.2010]** Let  $U \in \mathbb{R}^{d \times k}$  be ONB. Let  $F$  be  $d \times d$  orthogonal matrix and  $D$  diagonal with iid Rademacher diagonal entries. Then

$$\mu(FDU) \leq Ckd\eta \log d, \quad \text{with} \quad \eta = \max_{ij} |f_{ij}|^2.$$

holds with probability at least 0.95 for some constant  $C$ .

*Proof.* W.l.o.g., may assume  $\eta = 1$ . Let  $x_{ij}$  denote  $(i, j)$  entry of  $FDU$  with  $i = 1, \dots, d, j = 1, \dots, k$ . EFY: Show that  $x_{ij}$  is sub-Gaussian(1).

Hoeffding's inequality shows that

$$\mathbb{P}\{|x_{ij}| \geq t\} \leq 2 \exp(-t^2/2).$$

By the union bound, this implies

$$\mathbb{P}\{|x_{ij}| \geq t\} \leq 2dk \exp(-t^2/2), \quad \forall i, j.$$

## Subsampled trigonometric transforms

For the squared row norms, this implies that

$$\mathbb{P}\{|x_{i1}|^2 + \dots + |x_{ik}|^2 \geq kt^2\} \leq 2dk \exp(-t^2/2), \quad \forall i.$$

Setting  $t = \sqrt{2 \log(40dk)}$  gives

$$\mathbb{P}\{|x_{i1}|^2 + \dots + |x_{ik}|^2 \geq 2k \log(40dk)\} \leq 0.05, \quad \forall i.$$

Using that  $k \leq d$ , this shows the desired result by the definition of  $\mu$ .  $\diamond$

# Subsampled trigonometric transforms

The result of the theorem is *not* optimal! We can avoid taking the union bound wrt  $j$  by using refined results on functions of Rademacher vectors.

**Lemma [Ledoux'1996]** Suppose that  $f : \mathbb{R}^d \rightarrow \mathbb{R}$  is convex and Lipschitz continuous with Lipschitz constant  $L_f$ . Let  $Z \in \mathbb{R}^d$  be a Rademacher random vector. Then for all  $t \geq 0$ ,

$$\mathbb{P}\{f(Z) \geq \mathbb{E}f(Z) + L_f t\} \leq e^{-t^2/8}.$$

We apply this result to the norm of the  $i$ th row of  $FDU$ :

$$f(z) = \|e_i^\top F \text{diag}(z) U\|_2 = \|z^\top E U\|_2, \quad E = \text{diag}(f_{i1}, \dots, f_{id}).$$

$f$  is clearly convex. EFY: Show that  $f$  is Lipschitz with  $L_f = 1$ , assuming that  $\eta = 1$ . Show that  $\mathbb{E}f(Z) = \sqrt{k}$ . Ledoux tells us that

$$\mathbb{P}\{\|e_i^\top F \text{diag}(z) U\|_2 \geq \sqrt{k} + t\} \leq e^{-t^2/8}.$$

# Subsampled trigonometric transforms

By the union bound,  $\mathbb{P}\{\|e_i^\top F \text{diag}(z) U\|_2 \geq \sqrt{k} + t\} \leq de^{-t^2/8}, \quad \forall i$ .  
Following the steps above, this shows:

**Theorem [Tropp'2011]** Let  $U \in \mathbb{R}^{d \times k}$  be ONB. Let  $F$  be  $d \times d$  orthogonal matrix and  $D$  diagonal with iid Rademacher diagonal entries. Then

$$\mu(FDU) \leq C\eta d(k + \log d), \quad \text{with} \quad \eta = \max_{ij} |f_{ij}|^2.$$

holds with probability at least 0.95 for some constant  $C$ .

Note the result also holds for unitary matrix  $F$ .

- ▶ Best we can hope for is  $\eta = 1/d$ .
- ▶ Let  $R$  be  $n \times d$  coordinate sampling matrix, that is, each row is  $e_j^\top / \sqrt{n}$  with probability  $1/d$ .
- ▶ Then  $S = RFD$  is  $(k, \epsilon, \delta)$ -OSE for  $0 < \epsilon \leq 1$  when

$$n \sim \mu(S) \epsilon^{-2} \log k \sim \epsilon^{-2} (k + \log d) \log k,$$

for fixed  $\delta$ . EFY: Prove the second relation rigorously and work out the asymptotic dependence on  $\delta$ .

# Subsampled trigonometric transforms

Most popular choices for  $F$ :

- ▶ **SRFT** (Subsampled Randomized Fourier Transform):  $F$  is the discrete Fourier transform

$$f_{ij} = \frac{1}{\sqrt{d}} \left( e^{-2\pi i/d} \right)^{(i-1)(j-1)}, \quad \eta = 1/d.$$

Applying subsampled Fourier transform  $RF$  to a vector can be carried out in  $O(d \log n)$  ops. With  $n \sim (k + \log d) \log k$ , need

$$O(d(\log(k + \log d) + \log \log k)) \approx O(d \log k)$$

ops to apply  $RFD$  to a vector.

- ▶ Subsampled Randomized Hartley Transform / Subsampled Randomized Cosine Transform = real variants of SRFT.
- ▶ **SRHT** (Subsampled randomized Hadamard transform)  $\Omega = RHD$ ,

$$\text{where } H = \frac{1}{\sqrt{n}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \otimes \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \otimes \cdots \otimes \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

(zero padding if  $n$  is not a power of 2)

**OSE holds for  $n = \mathcal{O}(k \log(1/\delta) \log(d/\delta))$**  [Boutsidis/Gittens'2013]

# Overdetermined least-squares revisited

$$\min\{\|Ax - b\|_2 : x \in \mathbb{R}^m\}, \quad A \in \mathbb{R}^{d \times m}, \quad b \in \mathbb{R}^d.$$

Recall result of Lemma (sketch and solve):

$$\|A\tilde{x} - b\|_2^2 \leq \frac{1 + \epsilon}{1 - \epsilon} \|Ax - b\|_2^2.$$

Two issues:

- ▶ Quality of sketch directly impacts quality of the LSQ solution.
- ▶ VERY expensive to get high accuracy! ( $n \sim \epsilon^{-2}$ )

Idea: Use sketching as preconditioner in iterative solver  $\rightsquigarrow$   
BLENDENPIK.



# Iterative solvers for LSQ problems

Consider  $m \times m$  SPD linear system  $Cx = d$ . The method of conjugate gradients (CG) only requires  $j$  matrix-vector products with  $C$  and  $O(m)$  extra storage to produce approximation  $x_j$  satisfying

$$\|x - x_j\|_C \leq 2\|x - x_0\|_C \left( \frac{\sqrt{\kappa(C)} - 1}{\sqrt{\kappa(C)} + 1} \right)^j,$$

with condition number

$$\kappa(C) = \frac{\sigma_{\max}(C)}{\sigma_{\min}(C)} = \frac{\lambda_{\max}(C)}{\lambda_{\min}(C)},$$

see, e.g., [Golub/Van Loan'2013].

LSQR [Paige/Saunders] for solving LSQ problem is *mathematically* equivalent to applying CG to normal equations  $A^T Ax = A^T b$ .

Convergence:

$$\|b - Ax_j\|_2 \leq 2\|b - Ax_0\|_2 \left( \frac{\kappa(A) - 1}{\kappa(A) + 1} \right)^j,$$

# Iterative solvers for LSQ problems

Use sketching as preconditioner: Compute QR decomposition

$$SA = \hat{Q}\hat{R}$$

and precondition least-squares problem

$$\min \|Ax - b\|_2 = \min \|A\hat{R}^{-1} \underbrace{\hat{R}x}_{:=\tilde{x}} - b\|_2$$

Let  $S$  be  $\epsilon$ -embedding of  $\text{range}(A)$  and consider QR decomposition  $A = QR$ . Then

$$\kappa(A\hat{R}^{-1}) = \kappa(QR\hat{R}^{-1}) = \kappa(R\hat{R}^{-1}) = \kappa(\hat{Q}\hat{R}R^{-1}) = \kappa(SQ) \leq \sqrt{\frac{1+\epsilon}{1-\epsilon}}.$$

Choose  $\epsilon = 1/2$ . Then LSQR applied to  $\min \|A\hat{R}^{-1}\tilde{x} - b\|_2$  converges at rate  $\approx 0.27$ .

To attain accuracy  $\epsilon \rightsquigarrow \sim |\log \epsilon|$  iterations needed. Complexity depends on  $|\log \epsilon|$  instead of  $\epsilon^{-2}$ ! More detailed discussion of complexity in Sec 8.3 of [Tropp'2020].

# Sketched Gram-Schmidt

An ubiquitous (and often expensive) task in scientific computing:

Given a set of (linearly independent) vectors  $x_1, \dots, x_k \in \mathbb{R}^d$ , determine **orthonormal basis**  $q_1, \dots, q_k$  of  $\text{span}(x_1, \dots, x_k)$ .

**Gram-Schmidt process.** For  $j = 1, \dots, k$ :

$$q'_j = x_j - \sum_{i=1}^{j-1} \langle q_i, x_j \rangle q_i = x_j - Q_{j-1} Q_{j-1}^\top x_j, \quad q_j = q'_j / \|q'_j\|_2, \quad (5)$$

where  $Q_{j-1} = [q_1, \dots, q_{j-1}]$ . On (distributed memory) massive parallel computers,  $\langle q_i, x_j \rangle$  requires global communication and is expensive.

**Idea:** Instead of orthonormality, attain sketch-orthonormality, that is, only  $\hat{Q}_k = SQ_k \in \mathbb{R}^{n \times k}$  is orthonormal.

Sketched Gram-Schmidt process:

$$\hat{q}'_j = Sx_j - \hat{Q}_{j-1} \hat{Q}_{j-1}^\top (Sx_j), \quad \hat{q}_j = \hat{q}'_j / \|\hat{q}'_j\|_2.$$

# Sketched Gram-Schmidt

Set  $r_j = \hat{Q}_{j-1}^\top (Sx_j)$  and  $r_{jj} = \|\hat{q}'_j\|_2$ . Then sketched Gram-Schmidt becomes

$$\hat{q}'_j = Sx_j - \hat{Q}_{j-1} r_j, \quad \hat{q}_j = \hat{q}'_j / r_{jj}.$$

At the same time, we compute

$$q'_j = x_j - Q_{j-1} r_j, \quad q_j = q'_j / r_{jj}.$$

By induction  $\rightsquigarrow$  Relation  $\hat{Q}_j = SQ_j$  is maintained.

## Randomized Gram-Schmidt

**Input:**  $x_1, \dots, x_k \in \mathbb{R}^d$ , sketching matrix  $S \in \mathbb{R}^{n \times d}$

**Output:** Sketch-orthonormal basis  $Q_k$  of  $\text{span}\{x_1, \dots, x_k\}$ .

- 1:  $Q_0 = []$ ,  $\hat{Q}_0 = []$ .
- 2: **for**  $j = 1, 2, \dots, k$  **do**
- 3:   Sketch vector  $s_j = Sx_j$
- 4:   Sketched GS:  $r_j = \hat{Q}_{j-1}^\top (Sx_j)$ ,  $\hat{q}'_j = s_j - \hat{Q}_{j-1} r_j$ ,  $r_{jj} = \|\hat{q}'_j\|_2$ ,  
       $\hat{Q}_j = [\hat{Q}_{j-1}, \hat{q}'_j / r_{jj}]$
- 5:   Update in  $\mathbb{R}^d$ :  $q'_j = x_j - Q_{j-1} r_j$ ,  $Q_j = [Q_{j-1}, q'_j / r_{jj}]$
- 6: **end for**

# Sketched Gram-Schmidt

**Analysis** of Randomized Gram-Schmidt: By construction,  $\hat{Q}_k$ ,  $Q_k$  satisfy the decompositions

$$S[x_1, \dots, x_k] = \hat{Q}_k \hat{R}_k, \quad [x_1, \dots, x_k] = Q_k \hat{R}_k,$$

where the upper triangular matrix  $R_k \in \mathbb{R}^{k \times k}$  contains the coefficients from the sketched GS process.

By a QR decomposition  $[x_1, \dots, x_k] = UR_U$ , we compute an ONB  $U$  of  $[x_1, \dots, x_k]$ . This yields  $SU = \hat{Q}_k R$  for  $R = \hat{R}_k R_U^{-1}$ . If  $S$  is random and has the  $(k, \epsilon, \delta)$ -OSE property we have

$$\kappa(SU)^2 = \kappa(R)^2 \leq \frac{1 + \epsilon}{1 - \epsilon} \quad \text{with probability } \geq 1 - \delta.$$

OTOH,  $U = Q_k R$  and hence  $Q_k = UR^{-1}$ , which implies

$$\kappa(Q_k)^2 = \kappa(R)^2 \leq \frac{1 + \epsilon}{1 - \epsilon} \quad \text{with probability } \geq 1 - \delta.$$

For  $\epsilon = 1/2 \rightsquigarrow$  **reasonably well-conditioned**  $Q_k$ .

# Sketched Gram-Schmidt

Additional remarks:

- ▶ A proper analysis also needs to take roundoff error into account [Balabanov/Grigori'2022].
- ▶ Krylov subspaces + Gram-Schmidt = Arnoldi [CLA]  $\rightsquigarrow$   
Krylov subspaces + randomized Gram-Schmidt  
= randomized Arnoldi.

Basis of randomized iterative solvers for linear systems, eigenvalue problems, matrix functions. Development and analysis of such solver under active development.

[Balabanov/Grigori'2022], [Burke/Güttel'2023], [Cortinovis/DK/Nakatsukasa'2024], [de Damas/Grigori'2024], [Güttel/Schweitzer'2024], [Nakatsukasa/Tropp'2024], [Palitta/Schweitzer/Simoncini'2023], [Timsit/Grigori/Balabanov'2023], and many more.

# Kaczmarz

**Disadvantage of BLENDENPIK:** Need to assemble and apply whole matrix  $A$  (even when doing coordinate sampling).

**Idea of (randomized) Kaczmarz:** Merge coordinate sampling with simple iterative refinement.

Suppose one has an approximation  $x_{t-1}$  of the minimizer for  $\|Ax - b\|$ . To determine next iterate  $x_t = x_{t-1} + c$ , the optimal correction  $c$  solves

$$\min \|A(x_{t-1} + c) - b\|_2.$$

Sketching this correction equation  $\leadsto \min \|SA(x_{t-1} + c) - Sb\|_2$ .

Kaczmarz takes an extreme choice for  $S$ . Sample *one* coordinate  $j$ :

$$\min \|e_{j(t)}^T A(x_{t-1} + c) - e_{j(t)}^T b\|_2 = \min \|\langle a_j, x_{t-1} \rangle + \langle a_j, c \rangle - b_j\|_2 = 0,$$

where  $a_j^T$  denotes  $j$ th row of  $A$ .

Many choices of  $c$  possible. The solution of smallest 2-norm is given by

$$c = a_j \frac{b_j - \langle a_j, x_{t-1} \rangle}{\|a_j\|_2^2}.$$

# Randomized Kaczmarz

**Randomized Kaczmarz** chooses  $j$  randomly and independently in each iteration from discrete pdf  $p_1, \dots, p_d$ . Canonical choices: Uniform sampling and Leverage scores / **Importance sampling**:

$$\mathbb{P}\{J(t) = i\} = p_i = \frac{\|a_i\|_2^2}{\|A\|_F^2}, \quad i = 1, \dots, d.$$

**Input:**  $A \in \mathbb{R}^{d \times m}$ ,  $b \in \mathbb{R}^n$ , initial iterate  $x_0$ , #iterations  $T$ .

**Output:** Approximation  $x_T$  of LSQ problem  $\min \|Ax - b\|_2$ .

- 1: Set  $p_i = \|a_i\|_2^2 / \|A\|_F^2$ ,  $i = 1, \dots, d$
- 2: **for**  $t = 1, 2, \dots, T$  **do**
- 3:   Sample  $j(t) \in \{1, \dots, d\}$  according to pdf  $(p_1, \dots, p_d)$ .
- 4:    $x_t = x_{t-1} - \frac{\langle a_{j(t)}, x_{t-1} \rangle - b_{j(t)}}{\|a_{j(t)}\|_2^2} \cdot a_{j(t)}$
- 5: **end for**

See also [Kireeva/Tropp'2024, arXiv:2402.17873] for a nice intro to Kaczmarz.



# Analysis of randomized Kaczmarz

**Simplifying assumption:**<sup>3</sup> LSQ problem is consistent, that is,  $b \in \text{range}(A)$ .  $A$  has full column rank  $\leadsto \exists! x_*$  s.t.  $Ax_* = b$ .

**Theorem [Strohmer/Vershynin'2009].** The iterates of randomized Kaczmarz satisfy

$$\mathbb{E} \|x_t - x_*\|_2^2 \leq (1 - \kappa_{\text{Demmel}}^{-2})^t \cdot \|x_0 - x_*\|_2^2,$$

with  $\kappa_{\text{Demmel}} = \|A\|_F / \sigma_{\min}(A)$ .

*Proof.* The expectation is to be understood with respect to the randomness in the choice of row indices in every step  $1, \dots, t$ . Let  $J(1), \dots, J(t)$  denote corresponding r.v. Law of total expectation helps us to reduce the analysis to a single step:

$$\begin{aligned} \mathbb{E} \|x_t - x_*\|_2^2 &= \mathbb{E}_{J(1), \dots, J(t)} \|x_t - x_*\|_2^2 \\ &= \mathbb{E}_{J(1), \dots, J(t-1)} \left[ \mathbb{E}_{J(t)} \|x_t - x_*\|_2^2 \mid J(1), \dots, J(t-1) \right]. \end{aligned}$$

To simplify notation, we will simply write  $\mathbb{E}_{J(t)} \|x_t - x_*\|_2^2$ .

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<sup>3</sup>Work by Zouzias/Freris'2013 lifts this assumption.

# Analysis of randomized Kaczmarz

For fixed  $j \equiv j(t)$ , we can write

$$\begin{aligned} \mathbf{e}_t &:= \mathbf{x}_t - \mathbf{x}_* = (\mathbf{x}_{t-1} - \mathbf{x}_*) - \frac{\langle \mathbf{a}_j, \mathbf{x}_{t-1} \rangle - b_j}{\|\mathbf{a}_j\|_2^2} \cdot \mathbf{a}_j \\ &= \mathbf{e}_{t-1} - \frac{\mathbf{a}_j \mathbf{a}_j^\top}{\|\mathbf{a}_j\|_2^2} \cdot \mathbf{e}_{t-1} = (\mathbf{I} - \mathbf{P}_j) \mathbf{e}_{t-1}, \end{aligned}$$

where we used  $\langle \mathbf{a}_j, \mathbf{x}_* \rangle = b_j$  in the 2nd equality and set  $\mathbf{P}_j := \mathbf{a}_j \mathbf{a}_j^\top / \|\mathbf{a}_j\|_2^2$ . Using that  $\mathbf{P}_j$  is an orthogonal projector, one obtains

$$\|\mathbf{e}_t\|_2^2 = \mathbf{e}_{t-1}^\top (\mathbf{I} - \mathbf{P}_j) (\mathbf{I} - \mathbf{P}_j) \mathbf{e}_{t-1} = \mathbf{e}_{t-1}^\top (\mathbf{I} - \mathbf{P}_j) \mathbf{e}_{t-1}.$$

Now, consider random choice  $J(t)$  for  $j$ . Then

$$\mathbb{E}_{J(t)} \mathbf{P}_{J(t)} = \sum_{j=1}^d \mathbb{P}\{J(t) = j\} \cdot \mathbf{P}_j = \sum_{j=1}^d \frac{\|\mathbf{a}_j\|_2^2}{\|\mathbf{A}\|_F^2} \cdot \frac{\mathbf{a}_j \mathbf{a}_j^\top}{\|\mathbf{a}_j\|_2^2} = \frac{1}{\|\mathbf{A}\|_F^2} \mathbf{A}^\top \mathbf{A}.$$

# Analysis of randomized Kaczmarz

Hence,

$$\begin{aligned}\mathbb{E}_{J(t)} \|e_t\|_2^2 &= e_{t-1}^\top (I - \mathbb{E}_{J(t)} P_j) e_{t-1} = e_{t-1}^\top (I - \|A\|_F^{-2} A^\top A) e_{t-1} \\ &\leq \lambda_{\max}(I - \|A\|_F^{-2} A^\top A) \|e_{t-1}\|_2^2 = (1 - \|A\|_F^{-2} \sigma_{\min}(A)^2) \|e_{t-1}\|_2^2 \\ &= (1 - \kappa_{\text{Demmel}}^{-2}) \|e_{t-1}\|_2^2.\end{aligned}$$

In summary, we obtain

$$\begin{aligned}\mathbb{E} \|x_t - x_*\|_2^2 &\leq (1 - \kappa_{\text{Demmel}}^{-2}) \mathbb{E} \|x_{t-1} - x_*\|_2^2 \\ &\leq (1 - \kappa_{\text{Demmel}}^{-2})^2 \mathbb{E} \|x_{t-2} - x_*\|_2^2 \\ &\vdots \\ &\leq (1 - \kappa_{\text{Demmel}}^{-2})^t \mathbb{E} \|x_0 - x_*\|_2^2,\end{aligned}$$

which concludes the proof.  $\diamond$

EFY: Using the Borel-Cantelli lemma, conclude from the theorem that Kaczmarz converges almost surely with a rate arbitrarily close to  $1 - \kappa_{\text{Demmel}}^{-2}$ .

# Kaczmarz is SGD

Stochastic gradient descent (SGD) applies to differentiable objective function of the form

$$\varphi(x) = \varphi_1(x) + \varphi_2(x) + \cdots + \varphi_d(x).$$

Each step of SGD updates

$$x_t = x_{t-1} - \eta \nabla \varphi_j(x_{t-1})$$

with randomly chosen index  $j$  and learning rate  $\eta > 0$ .

For  $\varphi(x) := \|Ax - b\|_2^2$ , we have the decomposition

$$\|Ax - b\|_2^2 = (\langle a_1, x \rangle - b_1)^2 + (\langle a_2, x \rangle - b_2)^2 + \cdots + (\langle a_d, x \rangle - b_d)^2.$$

Because of  $\nabla(\langle a_j, x \rangle - b_j)^2 = 2(\langle a_j, x \rangle - b_j)a_j$ , one step of SGD becomes

$$x_t = x_{t-1} - 2\eta(\langle a_j, x_{t-1} \rangle - b_j)a_j.$$

With adaptive learning rate  $\eta = 1/(2\|a_j\|_2^2)$ , this is Kaczmarz!