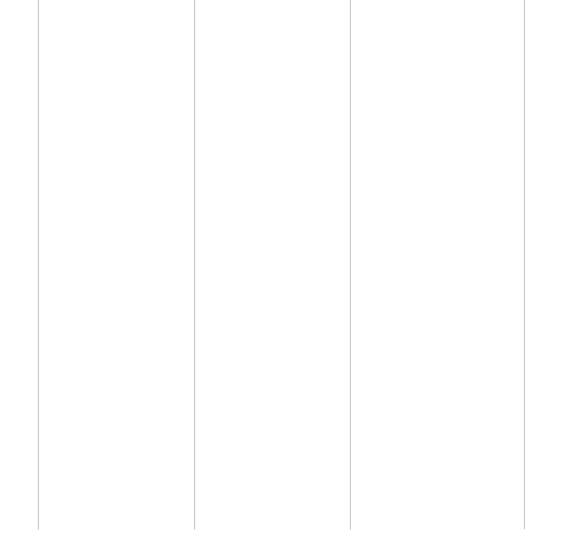
## **ProIT Report**



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Passivity-Based Bilateral Tele-Driving System With Parametric Uncertainty and Communication Delays.

Yimeng Dong, Nikhil Chopra

2003