Homework 3

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Section 1.4: Permutations

6. If σ and τ fix k, show that $\sigma\tau$ and σ^{-1} both fix k.

Proof. Since σ and τ both fix k, we have $\sigma k = k$ and $\tau k = k$, so that $\sigma \tau k = \sigma(\tau k) = \sigma k = k$, so then $\sigma \tau$ fixes k as well.

Since $\sigma k = k$, multiplying by σ^{-1} on the left, we have $\sigma^{-1}\sigma k = \sigma^{-1}k \implies k = \sigma^{-1}k$, so σ^{-1} fixes k, as desired.

12. Let $\sigma = (1 \ 2 \ 3)$ and $\tau = (1 \ 2)$ in S_3 .

(a) Show that $S_3 = \{\varepsilon, \sigma, \sigma^2, \tau, \tau\sigma, \tau\sigma^2\}$ and that $\sigma^3 = \varepsilon = \tau^2$ and $\sigma\tau = \tau\sigma^2$.

Proof. We know that

$$S_3 = \{ \varepsilon, (1 \ 2 \ 3), (1 \ 3 \ 2), (1 \ 2), (1 \ 3), (2 \ 3) \}.$$

Note that trivially, ε , σ , τ are in S_3 .

Write

$$\sigma = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix}$$

$$\tau = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix}$$

Then we have

$$\sigma^{2} = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 3 & 2 \end{pmatrix}$$

$$\tau \sigma = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix} = \begin{pmatrix} 2 & 3 \end{pmatrix}$$

$$\tau \sigma^{2} = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 3 \end{pmatrix}$$

Thus S_3 is as desired.

We have

$$\sigma^{3} = \sigma\sigma^{2} = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \end{pmatrix} = \varepsilon$$

$$\tau^{2} = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \end{pmatrix} = \varepsilon$$

$$\sigma\tau = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix} = \tau\sigma^{2}$$

as desired.

(b) Use (a) to fill in the multiplication table for S_3 .

Solution. The Cayley table is as follows:

| S_3 | 1 | | | au | | |
|---------------|------------------|---------------|-----------------|-----------------|---------------|---------------|
| ε | | | | au | | |
| σ | σ | σ^2 | ε | $\tau \sigma^2$ | au | $	au\sigma$ |
| σ^2 | σ^2 | ε | σ | $	au\sigma$ | $	au\sigma^2$ | au |
| au | $\mid \tau \mid$ | $\tau\sigma$ | $\tau \sigma^2$ | ε | σ | σ^2 |
| $	au\sigma$ | $\tau\sigma$ | $	au\sigma^2$ | au | σ^2 | ε | σ |
| $	au\sigma^2$ | $\tau \sigma^2$ | au | $	au\sigma$ | σ | σ^2 | ε |

16. If $\sigma = (1 \ 2 \ 3 \ \cdots \ n)$, show that $\sigma^n = \varepsilon$ and that n is the smallest positive integer with this property.

Proof. We may define σ as $\sigma k = (k+1) \pmod{n}$ whenever $k \in \sigma$. This accounts for looping. Then $\sigma^2 k = \sigma(\sigma k) = (k+2) \pmod{n}$, and by induction, we have $\sigma^n k = (k+n) \pmod{n} \equiv k \pmod{n}$. Thus σ^n fixes k so it is the identity permutation, as desired.

It is the smallest positive integer with this property because $(k + x) \equiv k \pmod{n}$ is satisfied whenever n | x, so x = n is the smallest.

Section 2.1: Binary Operations

1. In each case a binary operation * is given on a set M. Decide whether it is commutative or associative, whether a unity exists, and find the units (if there is a unity).

(c) $M = \mathbb{R}; a * b = a + b - ab$

Solution. We have a+b-ab=b+a-ba, so a*b=b*a thus * is commutative. We have

$$a*(b*c) = a*(b+c-bc) = a+b+c-bc-a(b+c-bc) = a+b+c-ab-ac-bc+abc$$

 $(a*b)*c = (a+b-ab)*c = a+b-ab+c-c(a+b-ab) = a+b+c-ab-ac-bc+abc$

thus * is associative.

If a unity i exists, it must satisfy a*i=i*a=a for all a. This means that a+i-ai=a, so i-ai=i(1-a)=0 for all a, so 0 is a unity. Since * is commutative this follows in the other direction as well.

Let a be a unit, so that b is its inverse. Then a * b = a + b - ab = i = 0. Manipulating this equation, we have

$$ab - a - b = 0$$

$$ab - a - b + 1 = 1$$

$$(a - 1)(b - 1) = 1$$

$$b - 1 = \frac{1}{a - 1}$$

$$b = 1 + \frac{1}{a - 1} = \frac{a}{a - 1}$$

which is not defined at a=1, thus all elements except 1 are units.

(g)
$$M = \mathbb{N}^+$$
; $a * b = \gcd(a, b)$

Solution. We have gcd(a, b) = gcd(b, a), so a * b = b * a thus $* \lfloor is$ commutative. \rfloor In Homework 2, Section 1.2 #42 we showed that gcd(a, b, c) = gcd(a, gcd(b, c)), so it follows that

$$\gcd(a,\gcd(b,c)) = \gcd(a,b,c) = \gcd(\gcd(a,b),c),$$

so
$$a * (b * c) = (a * b) * c$$
, thus * is associative.

There does not exist a unity. Suppose there did exist a unity i, then $a * i = \gcd(a, i) = a$ for all $a \in M$. However, this means that i is divisible by every natural number, which is impossible (since 0 is excluded from M). Thus there is no unity.

5. Given an alphabet A, call an n-tuple (a_1, a_2, \dots, a_n) with $a_i \in A$ a word of length n from A and write it as $a_1a_2 \cdots a_n$. Multiply two words by $(a_1a_2 \cdots a_n) \cdot (b_1b_2 \cdots b_m) = a_1a_2 \cdots a_nb_1b_2 \cdots b_m$, and call this product juxtaposition. We decree the existence of an empty word λ with no letters. Show that the set W of all words from A is a monoid, noncommutative if |A| > 1, and find the units.

Proof. For a set to be a monoid, its binary operation must be associative and it must have a unity. Obviously if we take two words from W and juxtapose them, the result will still be a word in W, so W is closed under juxtaposition.

Let X, Y, Z be words with

$$X = x_1 x_2 \cdots x_i$$

$$Y = y_1 y_2 \cdots y_j$$

$$Z = z_1 z_2 \cdots z_k$$

Then

$$X \cdot (Y \cdot Z) = X \cdot (y_1 y_2 \cdots y_j z_1 z_2 \cdots z_k)$$

$$= x_1 x_2 \cdots x_i y_1 y_2 \cdots y_j z_1 z_2 \cdots z_k$$

$$(X \cdot Y) \cdot Z = (x_1 x_2 \cdots x_i y_1 y_2 \cdots y_j) \cdot Z$$

$$= x_1 x_2 \cdots x_i y_1 y_2 \cdots y_j z_1 z_1 \cdots z_k$$

so juxtaposition is associative.

Now, λ is a unity of W since $X \cdot \lambda = X = \lambda \cdot X$ since we are either appending or inserting an empty word. Thus W is a monoid, as desired.

If |A| > 1, then there are at least 2 "letters," say a and b. Then let X = ab and Y = ba, so that $X \cdot Y = abba$ but $Y \cdot X = baab$, so $X \cdot Y \neq Y \cdot X$, so W is noncommutative if |A| > 1. On the other hand, if |A| = 1, then W is commutative, since every word is just a repeating string of a single letter, which when juxtaposed with other words, is just another string of the same letter.

11. An element e is called a left unity for an operation if ex = x for all x. If an operation has two left unities, show that it has no right unity.

Proof. Let i_1, i_2 be left unities, so that $i_1 \neq i_2$. Then suppose there exists a right unity e. Then we have $e = i_1 e = i_1$ and $e = i_2 e = i_2$, so by the transitive property $i_1 = i_2$, which is a contradiction. Thus there does not exist a right unity, as desired.

Section 2.2: Groups

7. Show that the set

$$G = \left\{ \begin{bmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix} \middle| a, b, c \in \mathbb{R} \right\}$$

is a group under matrix multiplication.

Proof. A group must satisfy 4 axioms:

1. G is closed under matrix multiplication. Let

$$A = \begin{bmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix}$$
$$X = \begin{bmatrix} 1 & x & y \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix}$$

be in G. Then

$$AX = \begin{bmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & x & y \\ 0 & 1 & z \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & x+a & y+az+b \\ 0 & 1 & z+c \\ 0 & 0 & 1 \end{bmatrix}$$
$$XA = \begin{bmatrix} 1 & x & y \\ 0 & 1 & z \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & a+x & b+xc+y \\ 0 & 1 & c+z \\ 0 & 0 & 1 \end{bmatrix}$$

Thus AX and XA are both in G.

2. Matrix multiplication is associative. Let A, X as before, and let $P = \begin{bmatrix} 1 & p & q \\ 0 & 1 & r \\ 0 & 0 & 1 \end{bmatrix}$. Then we have

$$A(XP) = \begin{bmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix} \begin{pmatrix} \begin{bmatrix} 1 & x & y \\ 0 & 1 & z \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & p & q \\ 0 & 1 & r \\ 0 & 0 & 1 \end{bmatrix} \end{pmatrix} = \begin{bmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & p+x & q+xr+y \\ 0 & 1 & r+z \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & p+x+a & q+xr+y+ar+az+b \\ 0 & 1 & r+z+c \\ 0 & 0 & 1 \end{bmatrix}$$

$$(AX)P = \begin{pmatrix} \begin{bmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & x & y \\ 0 & 1 & z \\ 0 & 0 & 1 \end{bmatrix} \begin{pmatrix} 1 & p & q \\ 0 & 1 & r \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & a+x & y+az+b \\ 0 & 1 & z+c \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & p & q \\ 0 & 1 & r \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & p+x+a & q+rx+ra+y+az+b \\ 0 & 1 & r+z+c \\ 0 & 0 & 1 \end{bmatrix}$$

so A(XP) = (AX)P, thus the operation is associative.

3. There is a unity element in G. This is

$$I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Let A be as before, then

$$AI = \begin{bmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix}$$
$$IA = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix}$$

Thus I is a unity.

4. Every element of G has an inverse in G. Indeed, if A is as before, then we can find its inverse A^{-1} to be

$$A^{-1} = \begin{bmatrix} 1 & -a & ac - b \\ 0 & 1 & -c \\ 0 & 0 & 1 \end{bmatrix}$$

and $A^{-1} \in G$ as well.

Thus G is a group, as desired.

16. If fgh = 1 in a group G, show that ghf = 1. Must gfh = 1?

Proof. Since fgh = f(gh) = 1, that means that $f^{-1} = gh$. Then $ghf = f^{-1}f = 1$, as desired. It is not necessary that gfh = 1, which is not true if f and h don't commute.

20. Show that a group G is abelian if $g^2 = 1$ for all $g \in G$. Give an example showing that the converse is false.

Proof. Since gg = 1 for all $g \in G$, this means that all elements of g are self-inverses. Consider the product (gf)(fg) = g(ff)g = gg = 1. Thus gf and fg are inverses, but since all elements of G are their own inverse, it follows that gf = fg, so G is abelian, as desired.

To show the converse is not necessarily true, consider the abelian group $(\mathbb{Z}_3, +)$. Then $\bar{1} + \bar{1} = \bar{2} \neq \bar{0}$, so the condition $g^2 = 1$ does not hold in this case.

28. Let a and b be elements of a group G. If $a^n = b^n$ and $a^m = b^m$ where gcd(m, n) = 1, show that a = b.

Proof. Since gcd(m,n) = 1, we may find $x, y \in \mathbb{Z}$ such that xm + yn = 1. Since $a^n = b^n$, we may raise both sides to the y power, so that $a^{yn} = b^{yn}$, and similarly with the other equation to get $a^{xm} = b^{xm}$. Multiplying the two equations, we have

$$a^{xm+yn} = a = b^{xm+yn} = b.$$

as desired.