

VHDL  
CODE

```
library ieee;
use ieee.std_logic_1164.all;
use ieee.numeric_std.all;

entity universal_shift_register is
    port (
        clk      : in  std_logic;
        reset_n : in  std_logic; -- Asynchronous active-low reset
        mode     : in  std_logic_vector(1 downto 0); -- Selects operation
        parallel_in : in  std_logic_vector(3 downto 0); -- Parallel data input
        serial_in_right : in  std_logic; -- Serial input for right shift
        serial_in_left  : in  std_logic; -- Serial input for left shift
        data_out : out std_logic_vector(3 downto 0) -- Parallel data output
    );
end entity universal_shift_register;

architecture behavioral of universal_shift_register is
    signal q_reg : std_logic_vector(3 downto 0) := (others => '0');
begin

    process (clk, reset_n)
    begin
        if reset_n = '0' then
            q_reg <= (others => '0');
        elsif rising_edge(clk) then
            case mode is
                when "00" => -- Hold
                    q_reg <= q_reg;
                when "01" => -- Shift Right
                    q_reg <= serial_in_right & q_reg(3 downto 1);
                when "10" => -- Shift Left
                    q_reg <= q_reg(2 downto 0) & serial_in_left;
                when "11" => -- Parallel Load
                    q_reg <= parallel_in;
                when others => -- Default to hold or reset value
                    q_reg <= q_reg;
            end case;
        end if;
    end process;

    data_out <= q_reg;

end architecture behavioral;
```

TEST BENCH	<pre>library ieee; use ieee.std_logic_1164.all; use ieee.numeric_std.all;  entity universal_shift_register_tb is end entity universal_shift_register_tb;  architecture tb_arch of universal_shift_register_tb is      -- Component declaration for the UUT     component universal_shift_register         port (             clk      : in  std_logic;             reset_n : in  std_logic;             mode     : in  std_logic_vector(1 downto 0);             parallel_in : in  std_logic_vector(3 downto 0);             serial_in_right : in  std_logic;             serial_in_left  : in  std_logic;             data_out : out std_logic_vector(3 downto 0)         );     end component;</pre>
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-- Signals for the testbench
signal clk_tb      : std_logic := '0';
signal reset_n_tb : std_logic;
signal mode_tb     : std_logic_vector(1 downto 0);
signal parallel_in_tb : std_logic_vector(3 downto 0);
signal serial_in_right_tb : std_logic;
signal serial_in_left_tb  : std_logic;
signal data_out_tb   : std_logic_vector(3 downto 0);

-- Clock period definition
constant CLK_PERIOD : time := 10 ns;

begin

  -- Instantiate the Unit Under Test (UUT)
  uut : universal_shift_register
    port map (
      clk      => clk_tb,
      reset_n  => reset_n_tb,
      mode     => mode_tb,
      parallel_in => parallel_in_tb,
      serial_in_right => serial_in_right_tb,
      serial_in_left  => serial_in_left_tb,
      data_out => data_out_tb
    );

```

```
-- Clock generation process
clk_gen : process
begin
    loop
        clk_tb <= '0';
        wait for CLK_PERIOD / 2;
        clk_tb <= '1';
        wait for CLK_PERIOD / 2;
    end loop;
end process clk_gen;

-- Test stimulus process
stimulus : process
begin
    -- Initial reset
    reset_n_tb <= '0';
    mode_tb <= "00";
    parallel_in_tb <= (others => '0');
    serial_in_right_tb <= '0';
    serial_in_left_tb <= '0';
    wait for CLK_PERIOD * 2;
    reset_n_tb <= '1';
    wait for CLK_PERIOD;
```

```

-- Test Parallel Load
mode_tb <= "11";
parallel_in_tb <= "1010";
wait for CLK_PERIOD;
assert data_out_tb = "1010" report "Parallel Load Failed" severity error;

-- Test Shift Right
mode_tb <= "01";
serial_in_right_tb <= '1'; -- Shift in '1' from right
wait for CLK_PERIOD;
assert data_out_tb = "1101" report "Shift Right 1 Failed" severity error;
serial_in_right_tb <= '0'; -- Shift in '0' from right
wait for CLK_PERIOD;
assert data_out_tb = "0110" report "Shift Right 2 Failed" severity error;

-- Test Shift Left
mode_tb <= "10";
serial_in_left_tb <= '1'; -- Shift in '1' from left
wait for CLK_PERIOD;
assert data_out_tb = "1101" report "Shift Left 1 Failed" severity error;
serial_in_left_tb <= '0'; -- Shift in '0' from left
wait for CLK_PERIOD;
assert data_out_tb = "1100" report "Shift Left 2 Failed" severity error;

-- Test Hold
mode_tb <= "00";
wait for CLK_PERIOD * 2;
assert data_out_tb = "1100" report "Hold Failed" severity error;

-- End simulation
wait;
end process stimulus;

end architecture tb_arch;

```