



**KHULNA UNIVERSITY OF ENGINEERING AND TECHNOLOGY,
KUET**

SESSIONAL REPORT

Course No: CSE 2204

Department of: Computer Science and Engineering

Experiment No: 13

Name of the Experiment: To write an assembly program which convert a BCD number to Binary number.

Remarks

Date of Performance: 31.05.21

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Year: 2nd

Semester: 2nd

No. of experiment: 13

Name of experiment: To write an assembly program which convert a BED number to Binary number.

Objectives:

1. To get introduced with CALL instruction and its classification.
2. To learn about procedure.
3. To learn and implement how to convert a BED number to Binary number.

Introduction:

In the program, we use CALL instruction to transfer execution to a procedure. There are two basic types of calls, near and far.

A near call is a call to a procedure

which is in the same code segment as the CALL instruction. When the 8086 executes a near CALL instruction, it decrements the stack pointer by 2 and copies the offset of the next instruction after the call onto the stack. A RET instruction at the end of the procedure will return execution to the instruction after the call by copying the offset set saved back to IP.

A far call is a call to a procedure which is in different section. When the 8086 executes a far call, it decrements the stack pointer by 2 and copies the contents of the CS register to the stack. It then decrements the stack pointer by 2 again and copies the offset of the instruction after the CALL instruction to the stack. Finally it loads the CS with

the segment base of the segment which contains the procedure and loads IP with the offset of the first instruction of the procedure in the segment. A RET instruction at the end of the procedure will return execution to the next instruction after the CALL by restoring the saved values of CS and IP from the stack.

In this program, we use procedure. A procedure is a set of code that can be branched to and returned from in such a way that the code is as if it were inserted at the point from which it is branched to.

In this program, we use 'and', 'ror' instructions. Using 'AND' instruction we perform logical and

Operation.

Again ROR instruction is used to rotate from LSB to MSB.

Example:

```
MOV AL, 1Ch ; AL = 00011100 b
ROR AL, 1 ; AL = 00001110 b
RET
```

Apparatus Required: emu 8086, Laptop.

Methodology:

Code:

org 100h

Call 'BCD to Bin' ; call procedure 'BCD to Bin'
the execution jump to the
procedure 'BCD to Bin'

ret

BOD to Bin proc near ; starting of a near

pushf

~~add~~ procedure "BOD to Bin"
; store the conditions of flags to stack

mov al, 56h ; al is initialized with 56h.

mov bl, al ; ^{copy} move the value of al to bl

and bl, 00Fh ; 'and' with 00Fh to the value
of bl register to

and al, 0F0h ; Perform AND operation ~~with~~ to
al register value with 0F0h.

ror al, 04h ; We use ROR instruction to al
register for 4 times because

If we perform AND operation

then, $AL = 50h = 11110000$

So if we rotate right for 4
times then, $AL = 5h$

mov cl, 0Ah

mul cl ; perform multiplication ^{to} ~~with~~ the
value of al with the value of
cl.

add al, bl ; perform addition ~~exit~~ to the
value of al with the value of bl.

popf ; restore the initial conditions^{of flags}, before
the procedure performed

ret

BcdToBin endp ; end of procedure.

Result and Discussion :

Through the instruction experiment, we performed BCD number to Binary number. We carefully implemented according to algorithm to perform our task properly. From this experiment, we used CALL instructions for procedure. We learnt procedure perfectly from the experiment. We also tried for various inputs to check our program.

By checking with various inputs, we ensured that our program was perfect.

Conclusion: Procedure is one of the basic things of the assembly language programming.

We tried to learn procedure perfectly from the experiment. So it would be very much necessary matter for us to perform solving various problem.

We learnt some new instructions. And by ensuring our experiment ~~can~~ to be correct, we can say that we have clear idea about procedures and other new instructions and we have fulfilled our objectives properly.

References:

1. Microprocessors and Interfacing - by D.V. Hall
2. C:/emu8086/documentation/index.html.