

Exercise 1

① First, let's show that given $\delta \in (0, 1)$ and given $0 < \epsilon_1 \leq \epsilon_2 < 1$, we have that $m_{\mathcal{H}}(\epsilon_1, \delta) \geq m_{\mathcal{H}}(\epsilon_2, \delta)$.
Since \mathcal{H} is PAC-learnable with sample complexity $m_{\mathcal{H}}(\cdot, \cdot)$, we get that given a sample of size $m_1 \geq m_{\mathcal{H}}(\epsilon_1, \delta)$, we have that with probability of at least $1 - \delta$ over $S \sim D^{m_1}$, $L_{D, f}(A(S)) < \epsilon_1$.

Since $\epsilon_1 \leq \epsilon_2$, for the sample of size ~~$m_1 \geq m_{\mathcal{H}}(\epsilon_1, \delta)$~~ ^{$m_1 \geq m_{\mathcal{H}}(\epsilon_1, \delta)$} we also have that w.p. of at least $1 - \delta$ over $S \sim D^{m_1}$, $L_{D, f}(A(S)) < \epsilon_2$. Hence, the sample size ~~m_2~~ ^{m_2} required for $L_{D, f}(A(S))$ to be smaller than ϵ_2 w.p. at least $1 - \delta$ over $S \sim D^{m_2}$ is guaranteed to work, if $m_2 \geq m_{\mathcal{H}}(\epsilon_1, \delta)$. Therefore, the sample complexity for ϵ_2 is at most $m_{\mathcal{H}}(\epsilon_1, \delta)$. Hence, we have shown that $m_{\mathcal{H}}(\epsilon_1, \delta) \geq m_{\mathcal{H}}(\epsilon_2, \delta)$.

② Now, let's show that given $\epsilon \in (0, 1)$ and given $0 < \delta_1 \leq \delta_2 < 1$, we have that $m_{\mathcal{H}}(\epsilon, \delta_1) \geq m_{\mathcal{H}}(\epsilon, \delta_2)$.
Since \mathcal{H} is PAC-learnable, given any $m \geq m(\epsilon, \delta_1)$, we have $P_{S \sim D^m}(A(S) < \epsilon) \geq 1 - \delta_1$. Since $\delta_1 \leq \delta_2$, we have that for any $m \geq m(\epsilon, \delta_1)$, $P_{S \sim D^m}(A(S) < \epsilon) \geq 1 - \delta_1 \geq 1 - \delta_2$.
Therefore, the sample complexity for δ_2 is at most $m_{\mathcal{H}}(\epsilon, \delta_1)$.
Hence, $m_{\mathcal{H}}(\epsilon, \delta_1) \geq m_{\mathcal{H}}(\epsilon, \delta_2)$.

By ① and ② we get that $m_{\mathcal{H}}$ is monotonically nonincreasing in each of its parameters.

q. e. d.

Exercise 2

1. Algorithm:

Go through every x in the sample and check whether it belongs to our discrete domain ~~\mathcal{X}~~ \mathcal{X} .

If we find such x , then function h_x , where $z=x$ is the outcome of our algorithm. Due to realizability assumption, there can only be one such x in the sample and, therefore, $L_S(h_x)$ will be 0.

If we don't find such x , then h^- is the outcome of our algorithm. Since in this case we don't have any positives in the sample, $L_S(h^-)$ will be 0.

2. If the algorithm described above outputs h_x , then, due to the realizability assumption it will mean that our hypothesis h_x correctly identifies the only positive in our domain, and hence, $L_{D,f}(h_x)$ will be 0, which is less than ϵ for all $\epsilon > 0$.

The only case in which our algorithm won't identify the correct labeling function is when the only positive ^{in distribution} ~~sample~~ (let's call it x_j) is not selected to our sample S_x and our algorithm incorrectly returns h^- . Since all items in the sample are i.i.d. selected, the probability of this happening is $(1 - P(x_j \text{ ~~in sample~~ }))^m$, where m is the size of our sample. We want this probability to be ~~less than~~ δ , in order for $\mathcal{H}_{\text{singleton}}$ to be PAC-learnable at most \uparrow ($\delta > 0$)

Since in this case, the population risk will be equal to $P_D(x^*)$, we get the inequality for the size of the sample m :

$$(1-\epsilon)^m \leq \delta$$

$$\Leftrightarrow m \geq \left\lceil \log_{(1-\epsilon)} \delta \right\rceil$$

the required upper bound on the sample complexity

Exercise 3

Fix some distribution D over X .

Assuming realizability,

Let R^* with radius r^* be the concentric circle that generates the labels and let f be the corresponding hypothesis. Let $r < r^*$ be ~~such that~~ ^{some} radius of the concentric circle R , such that the probability mass of the area between R and R^* is exactly ϵ . (Let's denote that area R')

~~For R has a positive example from the samples~~

Let A be the algorithm that returns the smallest ^{circle} enclosing all positive examples in the training set. From realizability assumption we get that A does not mislabel any negative examples (if it does, there should be smaller circle enclosing all positive examples, which contradicts definition of $A(S)$). Hence, A is an ERM.

Since $A(S)$ is the smallest circle enclosing all positive examples, $A(S) \subseteq R^*$. If R' contains any positive example, then the boundary of A lies between R^* and R .

Since the probability mass of that region is ϵ , empirical risk of $A(S)$ in this case will be at most ϵ .

The probability of positive example being inside R is $1 - \epsilon$, hence the probability of all positive samples to be inside R is $(1 - \epsilon)^m$, where m is the size of the sample. Therefore, the probability that at least one positive is in R' is $1 - (1 - \epsilon)^m$.

We get that $P(L_{0,\epsilon}(A(S)) < \epsilon) \geq 1 - (1 - \epsilon)^m \geq 1 - e^{-\epsilon m}$

Rewriting this inequality, we get $m \geq \frac{\log(1/\delta)}{\epsilon}$

Therefore, we have show that \exists algorithm A ,
s.t. $\forall \epsilon, \delta > 0$, \forall distributions D , \forall labeling fcn F ,
s.t. D, F realizable by \mathcal{H} , given $m \geq \lceil \frac{\log(1/\delta)}{\epsilon} \rceil$,
then w.p. ~~prob~~ at least $1 - \delta$ over $S \sim D^m$, we have
$$L_{D, F}(A(S)) < \epsilon$$

Hence, \mathcal{H} is PAC-learnable and its sample
complexity is bounded by $m_{\mathcal{H}}(\epsilon, \delta) \leq \lceil \frac{\log(1/\delta)}{\epsilon} \rceil$

q. e. d.

Exercise 6

Let \mathcal{H} be agnostic PAC-learnable and let A be a successful agnostic PAC learner for \mathcal{H} .

Then, ~~we~~ consider $m_{\mathcal{H}}(0,1)^2 \rightarrow \mathbb{N}$, s.t. $\forall \epsilon, \delta > 0$, $\forall D$ on $X \times Y$, given $m \geq m_{\mathcal{H}}(\epsilon, \delta)$ w.p. $\geq (1-\delta)$ over $S \sim D^m$, it is true that
$$L_D(A(S)) \leq \inf_{h \in \mathcal{H}} L_D(h) + \epsilon$$

Using definition (3.1 from the book) of the true error, we get that $L_D(h) = \mathbb{P}_{(x,y) \sim D} [h(x) \neq y]$

Therefore, given $m \geq m_{\mathcal{H}}(\epsilon, \delta)$, we know that:

$$\star 1 \quad \mathbb{P}_{S \sim D^m} \left[L_D(A(S)) \leq \inf_{h \in \mathcal{H}} \mathbb{P}_{(x,y) \sim D} [h(x) \neq y] + \epsilon \right] \geq (1-\delta)$$

For the binary classifier loss function is defined as following:

$$\ell(h, (x, y)) = \begin{cases} 0 & \text{if } h(x) = y \\ 1 & \text{if } h(x) \neq y \end{cases}$$

$$\begin{aligned} \text{Hence, } \mathbb{E}_{(x,y) \sim D} [\ell(h, (x, y))] &= 0 \cdot \mathbb{P}_{(x,y) \sim D} [h(x) = y] + 1 \cdot \mathbb{P}_{(x,y) \sim D} [h(x) \neq y] = \\ &= \mathbb{P}_{(x,y) \sim D} [h(x) \neq y] \end{aligned}$$

Therefore, for our algorithm A and function $m_{\mathcal{H}}(\cdot, \cdot)$, we ~~know~~ get that:

$$\star 2 \quad \mathbb{P}_{S \sim D^m} \left[L_D(A(S)) \leq \inf_{h \in \mathcal{H}} \mathbb{E}_{(x,y) \sim D} [\ell(h, (x, y))] + \epsilon \right] \geq (1-\delta)$$

Hence, \mathcal{H} is PAC-learnable and A is a successful PAC learner for \mathcal{H} by definition.

Exercise 7

By definition 3.1 of the true risk, we get that the true risk for randomly chosen classifier g is equal to:

$$L_0(g) = P_{(x,y) \sim D} [g(x) \neq y] = \begin{cases} P(y=1|x), & \text{if } g(x)=0 \\ P(y=0|x), & \text{if } g(x)=1 \end{cases}$$

Predictor is optimal, if it has the lowest possible value of $L_0(g)$.

As we can see from the expression above, $L_0(g)$ has the lowest possible value, when the predictor is such that $L_0(g) = P(y=1|x)$, when $P(y=1|x) \leq P(y=0|x)$ and $L_0(g) = P(y=0|x)$ when $P(y=0|x) \leq P(y=1|x)$.

Now, consider $f_0(x)$ as (Bayes Optimal Predictor)

$$\begin{aligned} L_0(f_0(x)) &= \begin{cases} P(y=1|x), & \text{if } f_0(x)=0 \\ P(y=0|x), & \text{if } f_0(x)=1 \end{cases} = \text{(by definition)} \\ &= \begin{cases} P(y=1|x), & \text{if } P(y=1|x) < \frac{1}{2} \\ P(y=0|x), & \text{if } P(y=1|x) \geq \frac{1}{2} \end{cases} = \begin{cases} P(y=1|x), & \text{if } P(y=1|x) < \frac{1}{2} \\ P(y=0|x), & \text{if } P(y=0|x) \leq \frac{1}{2} \end{cases} \\ &= \begin{cases} P(y=1|x), & \text{if } P(y=1|x) < P(y=0|x) \\ P(y=0|x), & \text{if } P(y=0|x) < P(y=1|x) \end{cases} \quad (\text{since } P(y=1|x) + P(y=0|x) = 1) \end{aligned}$$

As we can see, $L_0(g)$ has the lowest possible value when $g = f_0$

Hence, \forall classifier g from X to $\{0,1\}$, $L_0(f_0) \leq L_0(g)$
q.e.d.