

MOTH ERADICATION

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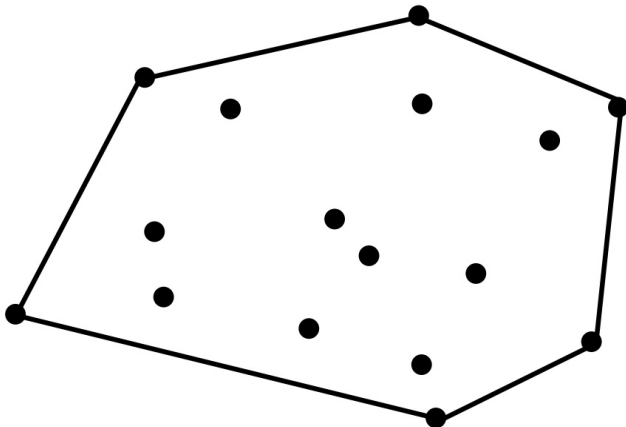
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INTRODUCTION

- You must write a program that can take as input the locations of traps in a region and output the locations of traps that lie on the perimeter of the region as well as the length of the perimeter.

GRAPH



DESCRIPTION

- Input:

The first line of each record contains the number (an integer) of traps for that region. Subsequent lines of the record contain 2 real numbers that are the x- and y-coordinates of the trap locations.

SAMPLE INPUT

- 3
1 2
4 10
5 12.3
- 6
0 0
1 1
3.1 1.3
3 4.5
6 2.1
2 -3.2

SAMPLE INPUT CONTD

- 7
1 0.5
5 0
4 1.5
3 -0.2
2.5 -1.5
0 0
2 2
0

SAMPLE OUTPUT

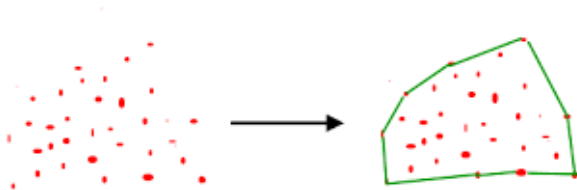
- Region 1:
(1.0,2.0)-(4.0,10.0)-(5.0,12.3)-(1.0,2.0)
Perimeter length = 22.10
Region2:
(0.0,0.0)-(3.0,4.5)-(6.0,2.1)-(2.0,-3.2)-
(0.0,0.0)
Perimeter length = 19.66
Region 3:
(0.0,0.0)-(2.0,2.0)-(4.0,1.5
)-(5.0,0.0)-(2.5,-1.5)-(0.0,0.0)
Perimeter length = 12.52

PROBLEM UNDERSTANDING

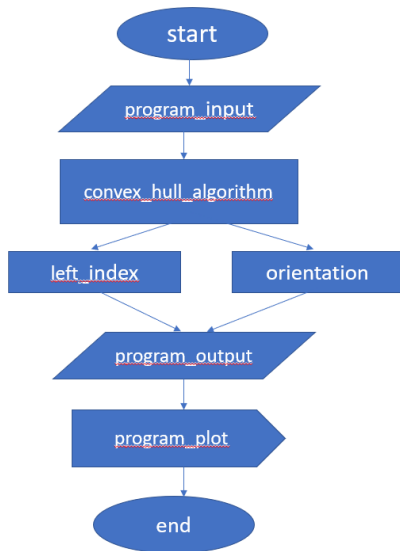
- We have to find a polygon(region) that should have all traps inside the polygon or on the outline of the polygon
- To find a polygon of minimum perimeter length and enclose all the traps we need to use Convex Hull Algorithm.

APPROACH

- Convex Hull: Given a set of points in the plane. the convex hull of the set is the smallest convex polygon that contains all the points of it.
- Graham Scan: Graham's Scan Algorithm will find the corner points of the convex hull. The time complexity is $O(n \log n)$.



PROJECT FLOW DIAGRAM



TEAMMEMBER CONTRIBUTION

- 108-

Worked on 1 modules and helped in LaTeX presentation

5B1-

Worked on 1 module and LaTeX presentation

5B2-

Worked on 3 modules and debugging and testing

4A1-

Worked on 1 module and collecting resources

4A2-

Worked on 1 module

LEARNINGS

- GitLab
- matplotlib library
- Convex Hull Method
- Graham Scan Algorithm
- LaTeX

CHALLENGES

- Framing the logic
- Convex hull Algorithm
- Graham Scan Method
- Visualisation of the polygon

TO OVERCOME THE CHALLENGES

- We referred internet and understood the necessary algorithms to be used.
- It is difficult to develop the entire code at once so we divided them into modules.
- Debugging helped us to overcome errors in the problem.

ALGORITHM

- `int ymin = points[0].y`
- `min = 0`
- `for i in range(1,n):`
 `int y = points[i].y` pick
 the bottom-most or choose the left
 most the point in case of tie
 if `((y < ymin) - (ymin == y and points[i].x < points[min].x))`
 `ymin = points[i].y`
 `min = i`

TECHNICAL STACK:

- PROGRAMMING LANGUAGE: python 3
- EDITOR: Google Colaboratory
- SITE: LaTeX
- REPOSITORY: GitLab

STATISTICS

- Functions in the code: program input, convex hull, left index, orientation, perimeter length, program output, program plot.
- Class in the code: Point
- Methods used: Methods in matplotlib
- Number of Lines of code: 115

CODE STATUS

- Day Wise code implementation
26-03-2022: Problem Understanding
28-03-2022: Algorithmic Approach for solving the problem statement
29-03-2022: Solving Modules of the problem
30-03-2022: Testing and Debugging the Modules
31-03-2022: Review of the Project

SCREEN SHOT

● Screen Shot of the Project

```
[ ] no_of_traps=1
while(no_of_traps!=0) :
    for region in range(1,1000):
        no_of_traps = int(input())
        if (no_of_traps == 0):
            break
        poly_vertices,x_points,y_points = program_input(no_of_traps)
        print()
        print("Region #",region,":")
        program_output(poly_vertices)
        print("Perimeter Length = ",perimeter_length(poly_vertices))
        program_plot(x_points,y_points,poly_vertices)
```

3

1 2

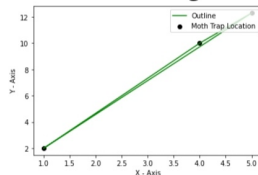
4 10

5 12.3

Region # 1 :

(1.0, 2.0)-(4.0, 10.0)-(5.0, 12.3)-(1.0, 2

Perimeter Length = 22.1



REPOSITORY

- <https://gitlab.com/Azzu78699/moth-eradication.git>

THANK YOU!