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# FIRST ORDER LOGIC AND PROBABILISTIC INFERENCE

# Inference in Belief Networks

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□ Find  $P(Q=q/E=e)$

■  $Q$  the query variable

■  $E$  set of evidence variables

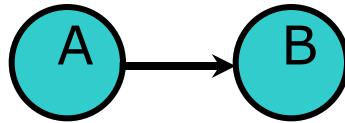
$$P(q \mid \mathbf{e}) = \frac{P(q, \mathbf{e})}{P(\mathbf{e})}$$

$X_1, \dots, X_n$  are network variables except  $Q, \mathbf{E}$

$$P(q, \mathbf{e}) = \sum_{X_1, \dots, X_n} P(q, \mathbf{e}, x_1, \dots, x_n)$$

# Basic Inference

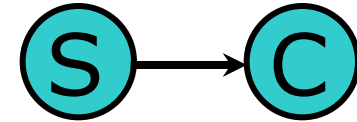
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$$P(b) = ?$$

# Product Rule

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□  $P(C, S) = P(C|S) P(S)$

$S \Downarrow$ $C \Rightarrow$	<i>none</i>	<i>benign</i>	<i>malignant</i>
<i>no</i>	0.768	0.024	0.008
<i>light</i>	0.132	0.012	0.006
<i>heavy</i>	0.035	0.010	0.005

# Marginalization

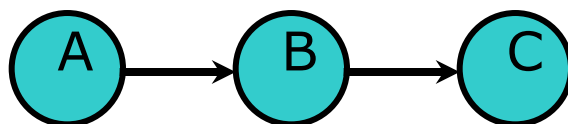
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$S \Downarrow$ $C \Rightarrow$	<i>none</i>	<i>benign</i>	<i>malig</i>	total	} P(Smoke)
<i>no</i>	0.768	0.024	0.008	.80	
<i>light</i>	0.132	0.012	0.006	.15	
<i>heavy</i>	0.035	0.010	0.005	.05	
total	0.935	0.046	0.019		

P(Cancer)

# Basic Inference

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$$P(b) = \sum_a P(a, b) = \sum_a P(b \mid a) P(a)$$

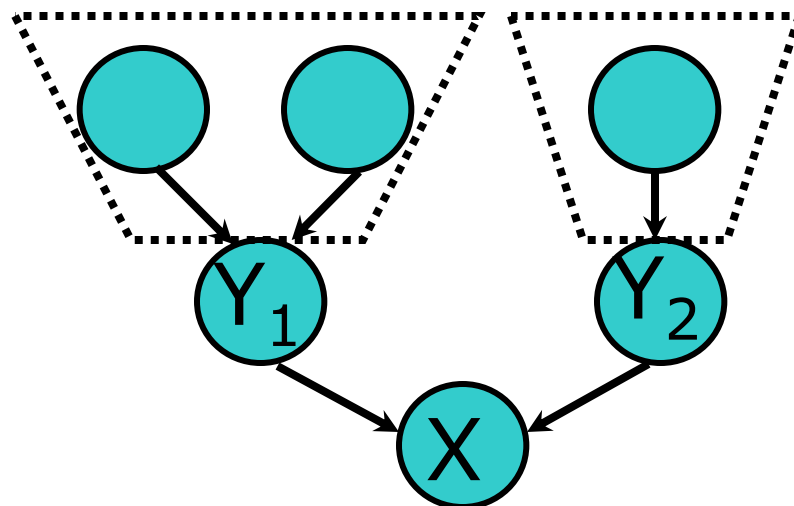
$$\underbrace{\hspace{10em}}_{P(c) = \sum_b P(c \mid b) P(b)}$$

$$P(c) = \sum_{b,a} P(a, b, c) = \sum_{b,a} P(c \mid b) P(b \mid a) P(a)$$

$$= \sum_b P(c \mid b) \underbrace{\sum_a P(b \mid a) P(a)}_{P(b)}$$

# Inference in trees

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$$P(x) = \sum_{Y_1, Y_2} P(x \mid y_1, y_2) P(y_1, y_2)$$

$Y_1, Y_2$

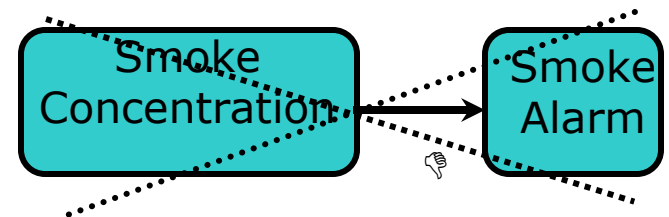
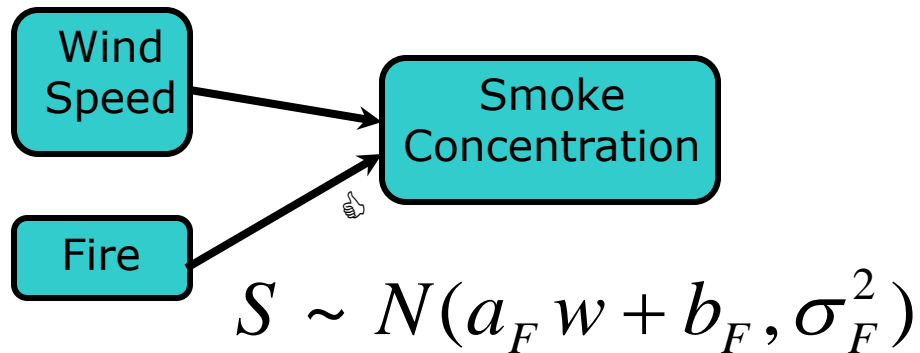
because of independence of  $Y_1, Y_2$ :

$$= \sum_{Y_1, Y_2} P(x \mid y_1, y_2) P(y_1) P(y_2)$$

# Inference with continuous variables

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- Gaussian networks: polynomial time inference regardless of network structure
- Conditional Gaussians:
  - discrete variables cannot depend on continuous

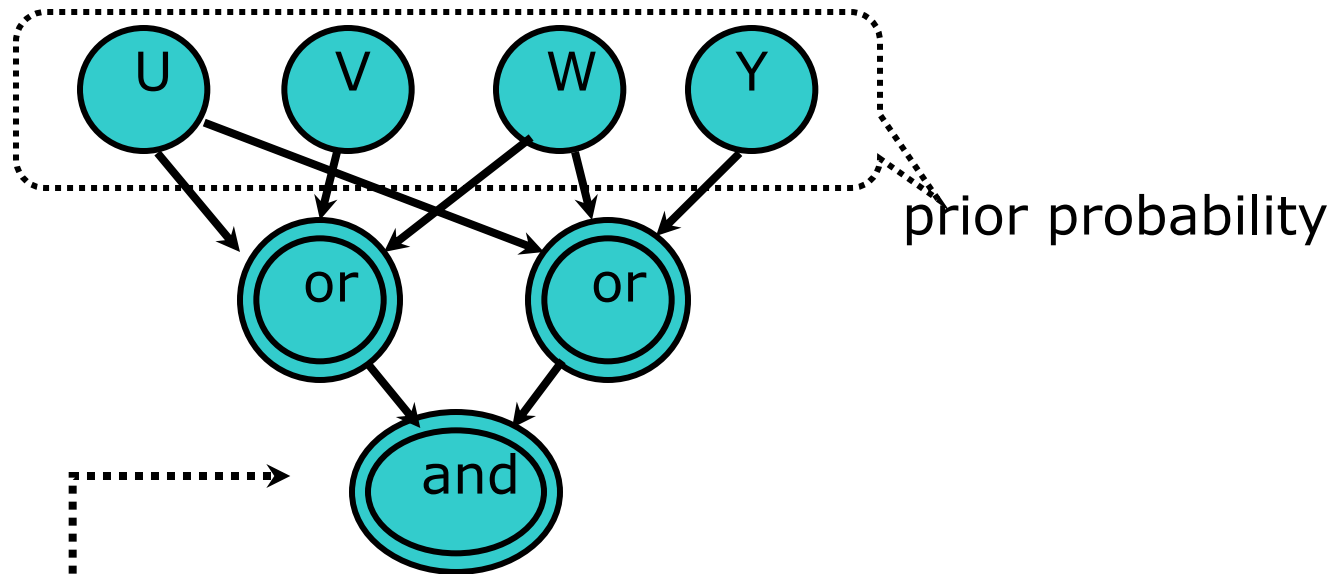


- These techniques do not work for general hybrid networks.



- **Theorem:** Inference in a multi-connected Bayesian network is NP-hard.

Boolean 3CNF formula  $\phi = (u \vee v \vee w) \wedge (u \vee w \vee y)$



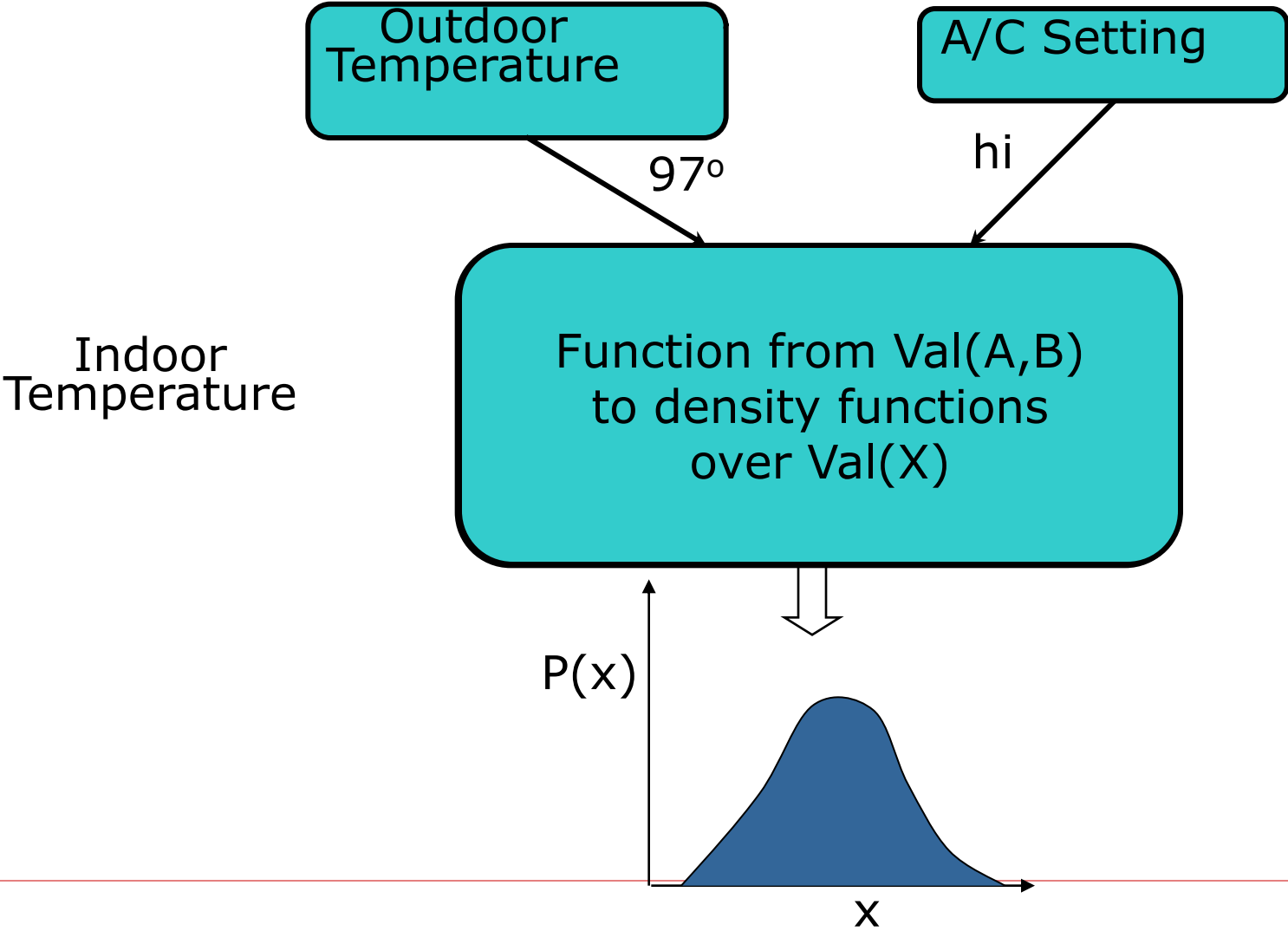
Probability ( ) = # satisfying assignments of  $\phi$

# Summary

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- Bayesian networks provide a natural representation for (causally induced) conditional independence
  - Topology + CPTs = compact representation of joint distribution
  - Generally easy for domain experts to construct
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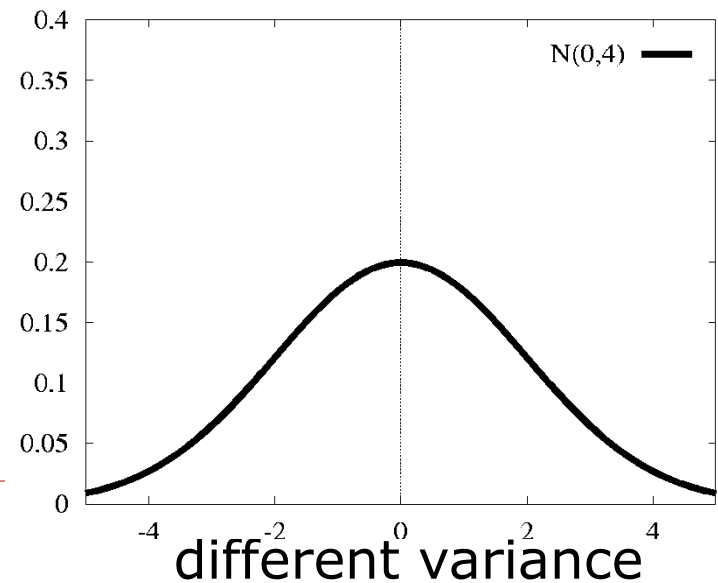
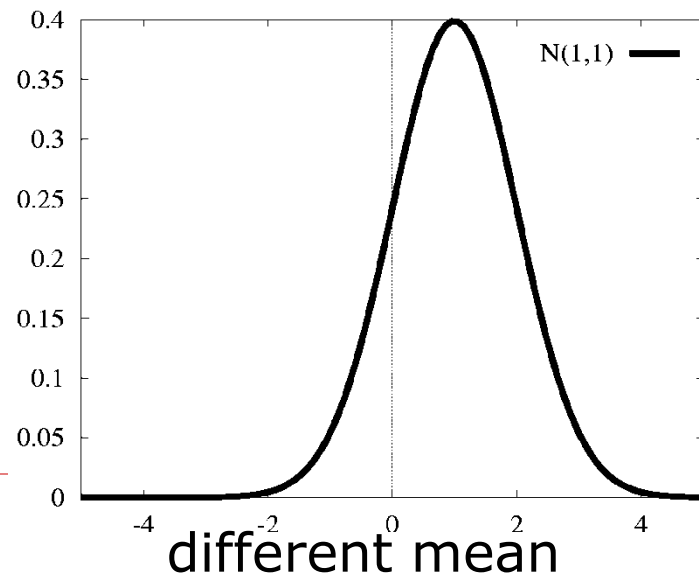
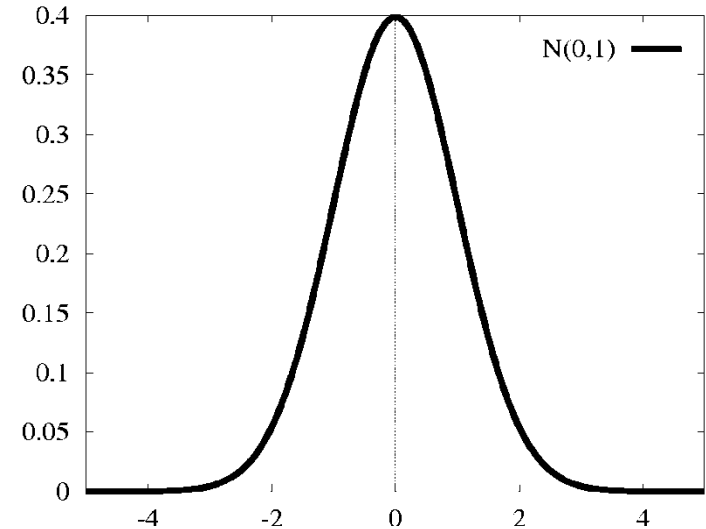
# Continuous variables



# Gaussian (normal) distributions

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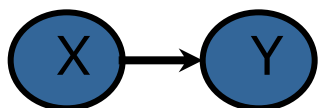
$$P(x) = \underbrace{\frac{1}{\sqrt{2\pi} \sigma} \exp\left(\frac{-(x - \mu)^2}{2\sigma}\right)}_{N(\mu, \sigma)}$$



## Gaussian networks

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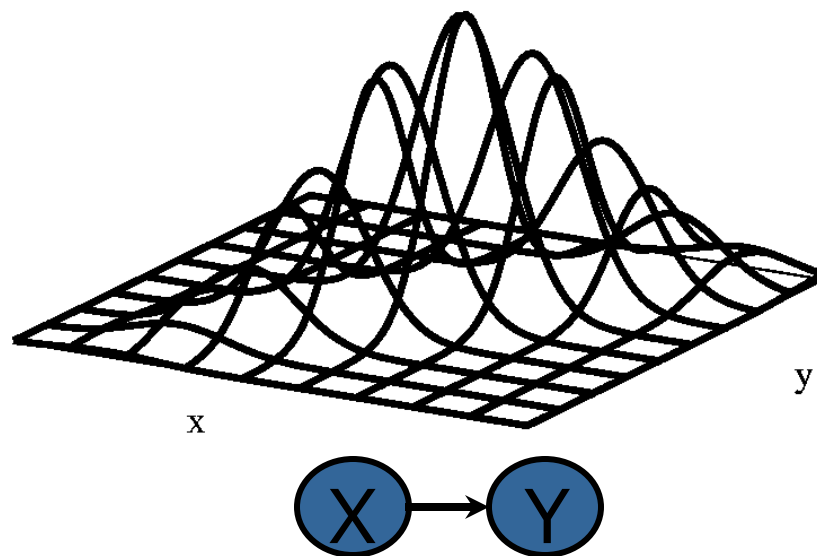
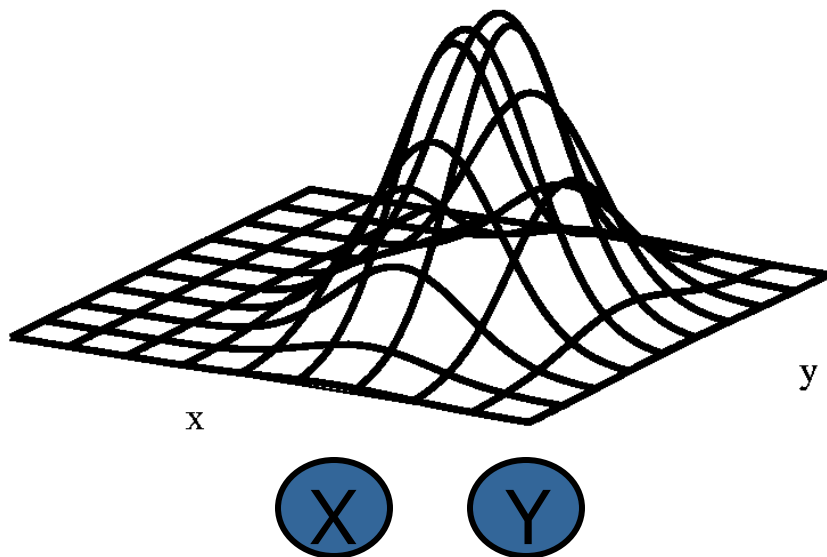
$$X \sim N(\mu, \sigma_X^2)$$



$$Y \sim N(ax + b, \sigma_Y^2)$$

Each variable is a linear function of its parents, with Gaussian noise

Joint probability density functions:



# D-Separation

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- X is d-separated from Y if, **for all paths** between X and Y **there exists** an intermediate node Z for which:
  - The connection is serial or diverging and there is evidence for Z.
  - The connection is converging and Z (nor any of its descendants) have received any evidence.
  
- X is independent of Y given Z for some conditional probabilities if and only if X is d-separated from Y given Z.

# Example of Independence Questions

- If there was evidence for B, which probabilities would change?
- If there was evidence for N, which probabilities would change?
- If there was evidence for M and N, which variables probabilities would change?
- Etc...

