<Lecture 3)</pre>

< Regular Operations>

 The idea is to build a new regular language using existing regular languages

Def - Union: $AUB = 3x \mid x \in A$ or $x \in B$?

- Concatenation: AOB = 3xy | x < A and y < B

- Star: $A^* = 3x_1x_2 - x_k \mid k \ge 0$ and each $x_i \in A_i$

Example: A=3a,b,c}, B=1d,es

AUB= 3

A.B= 3

 $A^* =$

In general, we say that a set A is <u>closed</u> under operation O if the result of applying O for each element in A belongs to A as well.

Example: N=31,2,3 .. 3

Thm: The set of regular languages is closed under regular operations.

I.e., for any regular languages Aand B, AUB, A.B., A* are all regular!

That's why U, o, * are called regular operations.

Thm 1.25. For any regular language A and B, AVB is regular

Q. How to prove this?

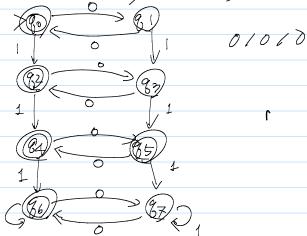
Idea:

We need to construct machine M that simulates both machines M, and Me. But how?

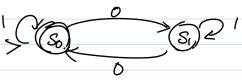
Q. What if we run M, on w, and if accepts, run M= on w?

Recall Pl.6 (HWI)

1. }ω | ω contains an even # of Os or contains exactly two (8)



 $A = 3 \omega / \omega$ contains an even number of $0s^2$



B= 3 w | w contains exactly two (s}



9 t, t, to to t,

rtotitite

How to combine them?

Given $M_1 = (Q_1, \Sigma, \delta_1, g_1, F_1)$ that recognizes A, and $M_2 = (Q_2, \Sigma, \delta_2, g_2, F_2)$ that recognizes B, we need to construct machine $M = (Q_1, \Sigma_1, O_2, g_2, F_2)$ that simulates M_1 and M_2 together?

How?

- Q. How many states do we need?
- Q. What should be the start state go?
- Q. What should be the accept states?
- Q What should be the transition function?

1. States:

 $Q = \beta(r_1, r_2) \mid r_1 \in Q_1 \text{ and } r_2 \in Q_2$

(So, to), (S, to), (So, ti), (S, ti), (So, ti), (S, ti), (So, ti), (S, ti), (So, ti), (S, ti)}

2. Bo is the "common start state"
: go = (B1, B2)

(50, to)

1 Show the constructions

Zo, ro

(gi ro

go ri

(ZI)

(go 12)

91 r2

(g) [3)

8, r2

3. accept states?

$$F = \frac{1}{3}(r_1, r_2) \mid r_1 \in F_1 \text{ or } r_3 \in F_2.$$

$$= (F_1 \times Q_2) \cup (Q_1 \times F_2)$$

$$\neq F_1 \times F_2.$$

(So, to), (S1, to), (So, ti), (S1, ti), (So, ti), (S1, ti), (So, to), (S1, to)}

4. transition function.

Q. How many transitions (edges)?

 $\delta((r_i,r_i),a)=(\delta_i(r_i,a),\delta_i(r_i,a))$

3 consider each transition by M, and M. {