Weighted Rules under the Stable Model Semantics

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Abstract

We introduce the concept of weighted rules under the stable model semantics following the log-linear models of Markov Logic. This provides versatile methods to overcome the deterministic nature of the stable model semantics, such as resolving inconsistencies in answer set programs, ranking stable models, associating probability to stable models, and applying statistical inference to computing weighted stable models. We also present formal comparisons with related formalisms, such as answer set programs, Markov Logic, ProbLog, and P-log.

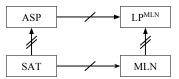
1 Introduction

Logic programs under the stable model semantics (Gelfond and Lifschitz 1988) is the language of Answer Set Programming (ASP). Many extensions of the stable model semantics have been proposed to incorporate various constructs in knowledge representation. Some of them are related to overcoming the "crisp" or deterministic nature of the stable model semantics by ranking stable models using weak constraints (Buccafurri, Leone, and Rullo 2000), by resolving inconsistencies using Consistency Restoring rules (Balduccini and Gelfond 2003) or possibilistic measure (Bauters et al. 2010), and by assigning probability to stable models (Baral, Gelfond, and Rushton 2009; Nickles and Mileo 2014).

In this paper, we present an alternative approach by introducing the notion of weights into the stable model semantics following the log-linear models of Markov Logic (Richardson and Domingos 2006), a successful approach to combining first-order logic and probabilistic graphical models. Instead of the concept of classical models adopted in Markov Logic, language $\mathrm{LP^{MLN}}$ adopts stable models as the logical component. The relationship between $\mathrm{LP^{MLN}}$ and Markov Logic is analogous to the known relationship between ASP and SAT. Indeed, many technical results about the relationship between SAT and ASP naturally carry over between $\mathrm{LP^{MLN}}$ and Markov Logic. In particular, an implementation of Markov Logic can be used to compute "tight" $\mathrm{LP^{MLN}}$ programs, similar to the way "tight" ASP programs can be computed by SAT solvers.

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It is also interesting that the relationship between Markov Logic and SAT is analogous to the relationship between $\mathrm{LP^{MLN}}$ and ASP: the way that Markov Logic extends SAT in a probabilistic way is similar to the way that $\mathrm{LP^{MLN}}$ extends ASP in a probabilistic way. This can be summarized as in the following figure. (The parallel edges imply that the ways that the extensions are defined are similar to each other.)



Weighted rules of LP^{MLN} provides a way to resolve inconsistencies among ASP knowledge bases, possibly obtained from different sources with different certainty levels. For example, consider the simple ASP knowledge base *KB*₁:

$$\begin{array}{lll} \textit{Bird}(x) & \leftarrow & \textit{ResidentBird}(x) \\ \textit{Bird}(x) & \leftarrow & \textit{MigratoryBird}(x) \\ & \leftarrow & \textit{ResidentBird}(x), \textit{MigratoryBird}(x). \end{array}$$

One data source KB_2 (possibly acquired by some information extraction module) says that Jo is a ResidentBird:

ResidentBird(Jo)

while another data source KB_3 states that Jo is a MigratoryBird:

$$MigratoryBird(Jo)$$
.

The data about Jo is actually inconsistent w.r.t. KB_1 , so under the (deterministic) stable model semantics, the combined knowledge base $KB = KB_1 \cup KB_2 \cup KB_3$ is not so meaningful. On the other hand, it is still intuitive to conclude that Jo is likely a Bird, and may be a ResidentBird or a MigratoryBird. Such reasoning is supported in LP^{MLN} .

Under some reasonable assumption, normalized weights of stable models can be understood as probabilities of the stable models. We show that ProbLog (De Raedt, Kimmig, and Toivonen 2007; Fierens et al. 2015) can be viewed as a special case of LP^{MLN}. Furthermore, we present a subset of LP^{MLN} where probability is naturally expressed and show how it captures a meaningful fragment of P-log (Baral, Gelfond, and Rushton 2009). In combination of the result that

relates $\mathrm{LP^{MLN}}$ to Markov Logic, the translation from P-log to $\mathrm{LP^{MLN}}$ yields an alternative, more scalable method for computing the fragment of P-log using standard implementations of Markov Logic.

The paper is organized as follows. After reviewing the deterministic stable model semantics, we define the language $\mathrm{LP^{MLN}}$ and demonstrate how it can be used for resolving inconsistencies. Then we relate $\mathrm{LP^{MLN}}$ to each of ASP, Markov Logic, and ProbLog, and define a fragment of $\mathrm{LP^{MLN}}$ language that allows probability to be represented in a more natural way. Next we show how a fragment of P-log can be turned into that fragment of $\mathrm{LP^{MLN}}$, and demonstrate the effectiveness of the translation-based computation of the P-log fragment over the existing implementation of P-log.

This paper is an extended version of (Lee and Wang 2015; Lee, Meng, and Wang 2015). The proofs are available from the longer version at http://reasoning.eas.asu.edu/papers/lpmln-kr-long.pdf.

2 Review: Stable Model Semantics

We assume a first-order signature σ that contains no function constants of positive arity, which yields finitely many Herbrand interpretations.

We say that a formula is *negative* if every occurrence of every atom in this formula is in the scope of negation.

A rule is of the form

$$A \leftarrow B \land N \tag{1}$$

where A is a disjunction of atoms, B is a conjunction of atoms, and N is a negative formula constructed from atoms using conjunction, disjunction and negation. We identify rule (1) with formula $B \wedge N \to A$. We often use comma for conjunction, semi-colon for disjunction, *not* for negation, as widely used in the literature on logic programming. For example, N could be

$$\neg B_{m+1} \wedge \ldots \wedge \neg B_n \wedge \neg \neg B_{n+1} \wedge \ldots \wedge \neg \neg B_n$$

which can be also written as

not
$$B_{m+1}, \ldots, not B_n, not not B_{n+1}, \ldots, not not B_p$$
.

We write $\{A_1\}^{\operatorname{ch}} \leftarrow Body$, where A_1 is an atom, to denote the rule $A_1 \leftarrow Body \land \neg \neg A_1$. This expression is called a "choice rule" in ASP. If the head of a rule (A in (1)) is \bot , we often omit it and call such a rule *constraint*.

A *logic program* is a finite conjunction of rules. A logic program is called *ground* if it contains no variables.

We say that an Herbrand interpretation I is a model of a ground program Π if I satisfies all implications (1) in Π (as in classical logic). Such models can be divided into two groups: "stable" and "non-stable" models, which are distinguished as follows. The reduct of Π relative to I, denoted Π^I , consists of " $A \leftarrow B$ " for all rules (1) in Π such that $I \models N$. The Herbrand interpretation I is called a (deterministic) stable model of Π if I is a minimal Herbrand model of Π^I . (Minimality is understood in terms of set inclusion. We identify an Herbrand interpretation with the set of atoms that are true in it.)

The definition is extended to any non-ground program Π by identifying it with $gr_{\sigma}[\Pi]$, the ground program obtained from Π by replacing every variable with every ground term of σ .

3 Language LP^{MLN}

Syntax of LP^{MLN}

The syntax of LP^{MLN} defines a set of weighted rules. More precisely, an LP^{MLN} program Π is a finite set of weighted rules w:R, where R is a rule of the form (1) and w is either a real number or the symbol α denoting the "infinite weight." We call rule w:R soft rule if w is a real number, and hard rule if w is α .

We say that an LP^{MLN} program is ground if its rules contain no variables. We identify any LP^{MLN} program Π of signature σ with a ground LP^{MLN} program $gr_{\sigma}[\Pi]$, whose rules are obtained from the rules of Π by replacing every variable with every ground term of σ . The weight of a ground rule in $gr_{\sigma}[\Pi]$ is the same as the weight of the rule in Π from which the ground rule is obtained. By $\overline{\Pi}$ we denote the unweighted logic program obtained from Π , i.e., $\overline{\Pi} = \{R \mid w : R \in \Pi\}$.

Semantics of LP^{MLN}

A model of a Markov Logic Network (MLN) does not have to satisfy all formulas in the MLN. For each model, there is a unique maximal subset of the formulas that are satisfied by the model, and the weights of the formulas in that subset determine the probability of the model.

Likewise, a stable model of an LP^{MLN} program does not have to be obtained from the whole program. Instead, each stable model is obtained from some subset of the program, and the weights of the rules in that subset determine the probability of the stable model. Unlike MLNs, it may not seem obvious if there is a *unique* maximal subset that derives such a stable model. The following proposition tells us that this is indeed the case, and furthermore that the subset is exactly the set of all rules that are satisfied by I.

Proposition 1 For any (unweighted) logic program Π and any subset Π' of Π , if I is a stable model of Π' and I satisfies Π , then I is a stable model of Π as well.

The proposition tells us that if I is a stable model of a program, adding more rules to this program does not affect that I is a stable model of the resulting program as long as I satisfies the rules added. On the other hand, it is clear that I is no longer a stable model if I does not satisfy at least one of the rules added.

For any LP^{MLN} program Π , by Π_I we denote the set of rules w:R in Π such that $I\models R$, and by $SM[\Pi]$ we denote the set $\{I\mid I \text{ is a stable model of }\overline{\Pi_I}\}$. We define the *unnormalized weight* of an interpretation I under Π , denoted $W_{\Pi}(I)$, as

$$W_{\Pi}(I) = \begin{cases} exp\bigg(\sum_{w:R \in \Pi_I} w\bigg) & \text{if } I \in SM[\Pi]; \\ 0 & \text{otherwise.} \end{cases}$$

Notice that $SM[\Pi]$ is never empty because it always contains \emptyset . It is easy to check that \emptyset always satisfies $\overline{\Pi_{\emptyset}}$, and it is the smallest set that satisfies the reduct $(\overline{\Pi_{\emptyset}})^{\emptyset}$.

The normalized weight of an interpretation I under Π , denoted $P_{\Pi}(I)$, is defined as

$$P_{\Pi}(I) = \lim_{\alpha \to \infty} \frac{W_{\Pi}(I)}{\sum_{J \in \text{SM}[\Pi]} W_{\Pi}(J)}.$$

It is easy to check that normalized weights satisfy the Kolmogorov axioms of probability. So we also call them *probabilities*.

We omit the subscript Π if the context is clear. We say that I is a *(probabilistic) stable model* of Π if $P_{\Pi}(I) \neq 0$.

The intuition here is similar to that of Markov Logic. For each interpretation I, we try to find a maximal subset (possibly empty) of $\overline{\Pi}$ for which I is a stable model (under the standard stable model semantics). In other words, the $\mathrm{LP^{MLN}}$ semantics is similar to the MLN semantics except that the possible worlds are the *stable* models of some maximal subset of $\overline{\Pi}$, and the probability distribution is over these stable models. Intuitively, $P_{\Pi}(I)$ indicates how likely to draw I as a stable model of some maximal subset of $\overline{\Pi}$.

For any proposition A, $P_{\Pi}(A)$ is defined as

$$P_{\Pi}(A) = \sum_{I: I \models A} P_{\Pi}(I).$$

Conditional probability under Π is defined as usual. For propositions A and B,

$$P_{\Pi}(A \mid B) = \frac{P_{\Pi}(A \wedge B)}{P_{\Pi}(B)}.$$

Often we are interested in stable models that satisfy all hard rules (hard rules encode definite knowledge), in which case the probabilities of stable models can be computed from the weights of the soft rules only, as described below.

the weights of the soft rules only, as described below. For any LP^{MLN} program Π , by Π^{soft} we denote the set of all soft rules in Π , and by Π^{hard} the set of all hard rules in Π . Let $SM'[\Pi]$ be the set

$$\{I \mid I \text{ is a stable model of } \overline{\Pi_I} \text{ that satisfy } \overline{\Pi^{\text{hard}}} \},$$

and let

$$W_\Pi'(I) = \begin{cases} exp\Bigg(\sum_{w:R \ \in \ (\Pi^{\mathrm{soft}})_I} w\Bigg) & \text{if } I \in \mathrm{SM}'[\Pi]; \\ 0 & \text{otherwise}, \end{cases}$$

$$P'_\Pi(I) = \frac{W'_\Pi(I)}{\sum_{J \in \operatorname{SM}'[\Pi]} W'_\Pi(J)}.$$

Notice the absence of $\lim_{\alpha\to\infty}$ in the definition of $P'_{\Pi}[I]$. Also, unlike $P_{\Pi}(I)$, SM' $[\Pi]$ may be empty, in which case $P'_{\Pi}(I)$ is not defined. Otherwise, the following proposition tells us that the probability of an interpretation can be computed by considering the weights of the soft rules only.

Proposition 2 If SM'[Π] is not empty, for every interpretation I, $P'_{\Pi}(I)$ coincides with $P_{\Pi}(I)$.

It follows from this proposition that if $SM'[\Pi]$ is not empty, then every stable model of Π (with non-zero probability) should satisfy all hard rules in Π .

Examples

The weight scheme of LP^{MLN} provides a simple but effective way to resolve certain inconsistencies in ASP programs.

Example 1 The example in the introduction can be represented in LP^{MLN} as

Assuming that the Herbrand universe is $\{Jo\}$, the following table shows the weight and the probability of each interpretation.

I	Π_I	$W_{\Pi}(I)$	$P_{\Pi}(I)$
Ø	$\{r_1, r_2, r_3\}$	$e^{3\alpha}$	0
$\{R(Jo)\}$	$\{r_2, r_3, r_4\}$	$e^{3\alpha}$	0
$\{M(Jo)\}$	$\{r_1, r_3, r_5\}$	$e^{3\alpha}$	0
$\{B(Jo)\}$	$\{r_1, r_2, r_3\}$	0	0
$\{R(Jo), B(Jo)\}$	$\{r_1, r_2, r_3, r_4\}$	$e^{4\alpha}$	1/3
$\{M(Jo),B(Jo)\}$	$\{r_1, r_2, r_3, r_5\}$	$e^{4\alpha}$	1/3
$\{R(Jo), M(Jo)\}$	$\{r_4, r_5\}$	$e^{2\alpha}$	0
$\{R(Jo), M(Jo), B(Jo)\}$	$\{r_1, r_2, r_4, r_5\}$	$e^{4\alpha}$	1/3

(The weight of $I = \{Bird(Jo)\}\$ is 0 because I is not a stable model of $\overline{\Pi_I}$.) Thus we can check that

- P(Bird(Jo)) = 1/3 + 1/3 + 1/3 = 1.
- $P(Bird(Jo) \mid ResidentBird(Jo)) = 1.$
- $P(ResidentBird(Jo) \mid Bird(Jo)) = 2/3.$

Instead of α , one can assign different certainty levels to the additional knowledge bases, such as

$$KB'_2$$
 2: $ResidentBird(Jo)$ $(r4')$
 KB'_3 1: $MigratoryBird(Jo)$ $(r5')$

Then the table changes as follows.

I	Π_I	$W_{\Pi}(I)$	$P_{\Pi}(I)$
Ø	$\{r_1, r_2, r_3\}$	$e^{3\alpha}$	$\frac{e^0}{e^2 + e^1 + e^0}$
$\{R(Jo)\}$	$\{r_2, r_3, r_4'\}$	$e^{2\alpha+2}$	0
$\{M(Jo)\}$	$\{r_1, r_3, r_5'\}$	$e^{2\alpha+1}$	0
$\{B(Jo)\}$	$\{r_1, r_2, r_3\}$	0	0
$\{R(Jo), B(Jo)\}$	$\{r_1, r_2, r_3, r_4'\}$	$e^{3\alpha+2}$	$\frac{e^2}{e^2 + e^1 + e^0}$
$\{M(Jo), B(Jo)\}$	$\{r_1, r_2, r_3, r_5'\}$	$e^{3\alpha+1}$	$\frac{e^1}{e^2 + e^1 + e^0}$
$\{R(Jo), M(Jo)\}$	$\{r_4',r_5'\}$	e^3	0
$\{R(Jo), M(Jo), B(Jo)\}$	$\{r_1, r_2, r'_4, r'_5\}$	$e^{2\alpha+3}$	0

 $P(Bird(Jo)) = (e^2 + e^1)/(e^2 + e^1 + e^0) = 0.67 + 0.24$, so it becomes less certain, though it is still a high chance that we can conclude that Jo is a Bird.

Notice that the weight changes not only affect the probability, but also the stable models (having non-zero probabilities) themselves: Instead of $\{R(Jo), M(Jo), B(Jo)\}$, the empty set is a stable model of the new program.

Assigning a different certainty level to each rule affects the probability associated with each stable model, representing how certain we can derive the stable model from the knowledge base. This could be useful as more incoming data reinforces the certainty levels of the information.

Remark. In some sense, the distinction between soft rules and hard rules in $\mathrm{LP^{MLN}}$ is similar to the distinction CR-Prolog (Balduccini and Gelfond 2003) makes between consistency-restoring rules (CR-rules) and standard ASP rules: some CR-rules are added to the standard ASP program part until the resulting program has a stable model. On the other hand, CR-Prolog has little to say when the ASP program has no stable models no matter what CR-rules are added (**c.f.** Example 1).

Example 2 "Markov Logic has the drawback that it cannot express (non-ground) inductive definitions" (Fierens et al. 2015) because it relies on classical models. This is not the case with $\mathrm{LP^{MLN}}$. For instance, consider that x may influence y if x is a friend to y, and the influence relation is a minimal relation that is closed under transitivity.

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\begin{array}{l} \alpha: \mathit{Friend}(A,B) \\ \alpha: \mathit{Friend}(B,C) \\ 1: \mathit{Influence}(x,y) \leftarrow \mathit{Friend}(x,y) \\ \alpha: \mathit{Influence}(x,y) \leftarrow \mathit{Influence}(x,z), \mathit{Influence}(z,y). \end{array}
```

Note that the third rule is soft: a person does not necessarily influence his/her friend. The fourth rule says if x influences z, and z influences y, we can say x influences y. On the other hand, we do not want this relation to be vacuously true.

Assuming that there are only three people A, B, C in the domain (thus there are 1+1+9+27 ground rules), there are four stable models with non-zero probabilities. Let $Z=e^9+2e^8+e^7$. (Fr abbreviates for Friend and Inf for Influence)

- $I_1 = \{Fr(A, B), Fr(B, C), Inf(A, B), Inf(B, C), Inf(A, C)\}$ with probability e^9/Z .
- $I_2 = \{Fr(A,B), Fr(B,C), Inf(A,B)\}$ with probability e^8/Z .
- $I_3 = \{Fr(A,B), Fr(B,C), Inf(B,C)\}$ with probability e^8/Z .
- $I_4 = \{Fr(A, B), Fr(B, C)\}$ with probability e^7/Z . Thus we get
- $P(Inf(A, B)) = P(Inf(B, C)) = (e^9 + e^8)/Z = 0.7311.$
- $P(Inf(A,C)) = e^9/Z = 0.5344.$

Increasing the weight of the third rule yields higher probabilities for deriving Influence(A,B), Influence(B,C), and Influence(A,C). Still, the first two have the same probability, and the third has less probability than the first two.

4 Relating LP^{MLN} to ASP

Any logic program under the stable model semantics can be turned into an $\mathrm{LP^{MLN}}$ program by assigning the infinite weight to every rule. That is, for any logic program $\Pi = \{R_1, \dots, R_n\}$, the corresponding $\mathrm{LP^{MLN}}$ program \mathbb{P}_Π is $\{\alpha: R_1, \dots, \alpha: R_n\}$.

Theorem 1 For any logic program Π , the (deterministic) stable models of Π are exactly the (probabilistic) stable models of \mathbb{P}_{Π} whose weight is $e^{k\alpha}$, where k is the number of all (ground) rules in Π . If Π has at least one stable model, then all stable models of \mathbb{P}_{Π} have the same probability, and are thus the stable models of Π as well.

Weak Constraints and LP^{MLN}

The idea of softening rules in LP^{MLN} is similar to the idea of *weak constraints* in ASP, which is used for certain optimization problems. A weak constraint has the form ":~ Body [Weight: Level]." The stable models of a program Π (whose rules have the form (1)) plus a set of weak constraints are the stable models of Π with the minimum penalty, where a penalty is calculated from Weight and Level of violated weak constraints.

Since levels can be compiled into weights (Buccafurri, Leone, and Rullo 2000), we consider weak constraints of the form

$$:\sim Body \ [Weight]$$
 (2)

where *Weight* is a positive integer. We assume all weak constraints are grounded. The penalty of a stable model is defined as the sum of the weights of all weak constraints whose bodies are satisfied by the stable model.

Such a program can be turned into an LP^{MLN} program as follows. Each weak constraint (2) is turned into

$$-w: \perp \leftarrow \neg Body.$$

The standard ASP rules are identified with hard rules in $LP^{\rm MLN}.$ For example, the program with weak constraints

$$\begin{array}{lll} a \vee b & :\sim a & [1] \\ c \leftarrow b & :\sim b & [1] \\ & :\sim c & [1] \end{array}$$

is turned into

The LP^{MLN} program has two stable models: $\{a\}$ with the normalized weight $\frac{e^{-1}}{e^{-1}+e^{-2}}$ and $\{b,c\}$ with the normalized weight $\frac{e^{-2}}{e^{-1}+e^{-2}}$. The former, with the larger normalized weight, is the stable model of the original program containing the weak constraints.

Proposition 3 For any program with weak constraints that has a stable model, its stable models are the same as the stable models of the corresponding LP^{MLN} program with the highest normalized weight.

5 Relating LP^{MLN} to MLNs

Embedding MLNs in $\mathrm{LP}^{\mathrm{MLN}}$

Similar to the way that SAT can be embedded in ASP, Markov Logic can be easily embedded in $\mathrm{LP}^{\mathrm{MLN}}.$ More precisely, any MLN $\mathbb L$ can be turned into an $\mathrm{LP}^{\mathrm{MLN}}$ program $\Pi_{\mathbb L}$ so that the models of $\mathbb L$ coincide with the stable models of $\Pi_{\mathbb L}$ while retaining the same probability distribution.

 $\operatorname{LP^{MLN}}$ program $\Pi_{\mathbb{L}}$ is obtained from \mathbb{L} by turning each weighted formula w: F into weighted rule $w: \bot \leftarrow \neg F$ and adding

$$w: \{A\}^{\operatorname{ch}}$$

for every ground atom A of σ and any weight w. The effect of adding the choice rules is to exempt A from minimization under the stable model semantics.

Theorem 2 Any MLN $\mathbb L$ and its LP^{MLN} representation $\Pi_{\mathbb L}$ have the same probability distribution over all interpretations

The embedding tells us that the exact inference in $LP^{\rm MLN}$ is at least as hard as the one in MLNs, which is #P-hard. In fact, it is easy to see that when all rules in $LP^{\rm MLN}$ are non-disjunctive, counting the stable models of $LP^{\rm MLN}$ is in #P, which yields that the exact inference for non-disjunctive $LP^{\rm MLN}$ programs is #P-complete. Therefore, approximation algorithms, such as Gibbs sampling, may be desirable for computing large $LP^{\rm MLN}$ programs. The next section tells us that we can apply the MLN approximation algorithms to computing $LP^{\rm MLN}$ based on the reduction of the latter to the former.

Completion: Turning LP^{MLN} to MLN

It is known that the stable models of a tight logic program coincide with the models of the program's completion (Erdem and Lifschitz 2003). This yielded a way to compute stable models using SAT solvers. The method can be extended to $LP^{\rm MLN}$ so that probability queries involving the stable models can be computed using existing implementations of MLNs, such as Alchemy (http://alchemy.cs.washington.edu).

We define the *completion* of Π , denoted $Comp(\Pi)$, to be the MLN which is the union of Π and the hard formula

$$\alpha:\,A\to \bigvee_{w:A_1\vee\dots\vee A_k\leftarrow Body\in\ \Pi\atop A\in\{A_1,\dots,A_k\}}\left(Body\wedge \bigwedge_{A'\in\{A_1,\dots,A_k\}\backslash\{A\}}\neg A'\right)$$

for each ground atom A.

This is a straightforward extension of the completion from (Lee and Lifschitz 2003) by simply assigning the infinite weight α to the completion formulas. Likewise, we say that LP^{MLN} program Π is tight if $\overline{\Pi}$ is tight according to (Lee and Lifschitz 2003), i.e., the positive dependency graph of $\overline{\Pi}$ is acyclic.

Theorem 3 For any tight LP^{MLN} program Π such that $SM'[\Pi]$ is not empty, Π (under the LP^{MLN} semantics) and $Comp(\Pi)$ (under the MLN semantics) have the same probability distribution over all interpretations.

The theorem can be generalized to non-tight programs by considering loop formulas (Lin and Zhao 2004), which we skip here for brevity.

6 Relation to ProbLog

It turns out that $LP^{\rm MLN}$ is a proper generalization of ProbLog, a well-developed probabilistic logic programming language that is based on the distribution semantics by Sato (1995).

Review: ProbLog

The review follows (Fierens et al. 2015). As before, we identify a non-ground ProbLog program with its ground instance. So for simplicity we restrict attention to ground ProbLog programs only.

In ProbLog, ground atoms over σ are divided into two groups: *probabilistic* atoms and *derived* atoms. A *(ground) ProbLog program* \mathbb{P} is a tuple $\langle PF, \Pi \rangle$, where

- PF is a set of ground probabilistic facts of the form pr::a,
- \bullet II is a set of ground rules of the following form

$$A \leftarrow B_1, \dots, B_m, not \ B_{m+1}, \dots, not \ B_n$$

where $A, B_1, \dots B_n$ are atoms from σ $(0 \le m \le n)$, and A is not a probabilistic atom.

Probabilistic atoms act as random variables and are assumed to be independent from each other. A *total choice TC* is any subset of the probabilistic atoms. Given a total choice $TC = \{a_1, \ldots, a_m\}$, the *probability* of a total choice TC, denoted $Pr_{\mathbb{P}}(TC)$, is defined as

$$pr(a_1) \times \ldots \times pr(a_m) \times (1 - pr(b_1)) \times \ldots \times (1 - pr(b_n))$$

where b_1, \ldots, b_n are probabilistic atoms not belonging to TC, and each of $pr(a_i)$ and $pr(b_j)$ is the probability assigned to a_i and b_j according to the set PF of ground probabilistic atoms.

The ProbLog semantics is only well-defined for programs $\mathbb{P} = \langle PF, \Pi \rangle$ such that $\Pi \cup TC$ has a "total" (two-valued) well-founded model for each total choice TC. Given such \mathbb{P} , the probability of an interpretation I, denoted $P_{\mathbb{P}}(I)$, is defined as $Pr_{\mathbb{P}}(TC)$ if there exists a total choice TC such that I is the total well-founded model of $\Pi \cup TC$, and 0 otherwise.

ProbLog as a Special Case of $\mathrm{LP}^{\mathrm{MLN}}$

Given a ProbLog program $\mathbb{P} = \langle PF, \Pi \rangle$, we construct the corresponding LP^{MLN} program \mathbb{P}' as follows:

- For each probabilistic fact pr::a in \mathbb{P} , $\operatorname{LP}^{\operatorname{MLN}}$ program \mathbb{P}' contains (i) ln(pr):a and $ln(1-pr):\leftarrow a$ if 0< pr<1; (ii) $\alpha:a$ if pr=1; (iii) $\alpha:\leftarrow a$ if pr=0.
- For each rule $R \in \Pi$, \mathbb{P}' contains $\alpha : R$. In other words, R is identified with a hard rule in \mathbb{P}' .

Theorem 4 Any well-defined ProbLog program \mathbb{P} and its LP^{MLN} representation \mathbb{P}' have the same probability distribution over all interpretations.

Example 3 Consider the ProbLog program

which can be identified with the LP^{MLN} program

$$\begin{array}{lll} ln(0.6): & p & ln(0.3): & q & \alpha: & r \leftarrow p \\ ln(0.4): \leftarrow p & ln(0.7): \leftarrow q & \alpha: & r \leftarrow q \end{array}$$

Syntactically, $\mathrm{LP^{MLN}}$ allows more general rules than ProbLog, such as disjunctions in the head, as well as the empty head and double negations in the body. Further, $\mathrm{LP^{MLN}}$ allows rules to be weighted as well as facts, and do not distinguish between probabilistic facts and derived atoms. Semantically, while the ProbLog semantics is based on well-founded models, $\mathrm{LP^{MLN}}$ handles stable model reasoning for more general classes of programs. Unlike ProbLog which is only well-defined when each total choice leads to a unique well-founded model, $\mathrm{LP^{MLN}}$ can handle multiple stable models in a flexible way similar to the way MLN handles multiple models.

7 Multi-Valued Probabilistic Programs

In this section we define a simple fragment of $\mathrm{LP^{MLN}}$ that allows us to represent probability in a more natural way. For simplicity of the presentation, we will assume a propositional signature. An extension to first-order signatures is straightforward.

We assume that the propositional signature σ is constructed from "constants" and their "values." A *constant* c is a symbol that is associated with a finite set Dom(c), called the *domain*. The signature σ is constructed from a finite set of constants, consisting of atoms $c=v^{-1}$ for every constant c and every element v in Dom(c). If the domain of c is $\{\mathbf{f},\mathbf{t}\}$ then we say that c is Boolean, and abbreviate $c=\mathbf{t}$ as c and $c=\mathbf{f}$ as $\sim c$.

We assume that constants are divided into *probabilistic* constants and *regular* constants. A multi-valued probabilistic program Π is a tuple $\langle PF, \Pi \rangle$, where

• *PF* contains *probabilistic constant declarations* of the following form:

$$p_1: c = v_1 \mid \cdots \mid p_n: c = v_n$$
 (3)

one for each probabilistic constant c, where $\{v_1,\ldots,v_n\}=Dom(c),\ v_i\neq v_j,\ 0\leq p_1,\ldots,p_n\leq 1$ and $\sum_{i=1}^n p_i=1$. We use $M_\Pi(c=v_i)$ to denote p_i . In other words, PF describes the probability distribution over each "random variable" c.

 Π is a set of rules of the form (1) such that A contains no probabilistic constants.

The semantics of such a program Π is defined as a short-hand for $\mathrm{LP^{MLN}}$ program $T(\Pi)$ of the same signature as follows.

- For each probabilistic constant declaration (3), $T(\Pi)$ contains, for each $i=1,\ldots,n$, (i) $ln(p_i):c=v_i$ if $0 < p_i < 1$; (ii) $\alpha:c=v_i$ if $p_i=1$; (iii) $\alpha:\leftarrow c=v_i$ if $p_i=0$.
- For each rule in Π of form (1), $T(\Pi)$ contains

$$\alpha: A \leftarrow B, N.$$

• For each constant c, $T(\Pi)$ contains the uniqueness of value constraints

$$\alpha: \quad \bot \leftarrow c = v_1 \land c = v_2 \tag{4}$$

for all $v_1, v_2 \in Dom(c)$ such that $v_1 \neq v_2$. For each probabilistic constant $c, T(\Pi)$ also contains the existence of value constraint

$$\alpha: \perp \leftarrow \neg \bigvee_{v \in Dom(c)} c = v.$$
 (5)

This means that a regular constant may be undefined (i.e., have no values associated with it), while a probabilistic constant is always associated with some value.

Example 4 The multi-valued probabilistic program

$$\begin{array}{l} 0.25:Outcome\!=\!6 \mid 0.15:Outcome\!=\!5 \\ \mid 0.15:Outcome\!=\!4 \mid 0.15:Outcome\!=\!3 \\ \mid 0.15:Outcome\!=\!2 \mid 0.15:Outcome\!=\!1 \\ Win \leftarrow Outcome\!=\!6. \end{array}$$

is understood as shorthand for the LP^{MLN} program

$$\begin{array}{ll} ln(0.25): & Outcome = 6 \\ ln(0.15): & Outcome = i \\ \alpha: & Win \leftarrow Outcome = 6 \\ \alpha: & \bot \leftarrow Outcome = i \land Outcome = j \ (i \neq j) \\ \alpha: & \bot \leftarrow \neg \bigvee_{i=1,\dots 6} Outcome = i. \end{array}$$

We say an interpretation of Π is *consistent* if it satisfies the hard rules (4) for every constant and (5) for every probabilistic constant. For any consistent interpretation I, we define the set TC(I) ("Total Choice") to be $\{c=v\mid c \text{ is a probabilistic constant such that }c=v\in I\}$ and define

$$SM''[\Pi] = \{ I \mid I \text{ is consistent}$$
 and is a stable model of $\Pi \cup TC(I) \}.$

For any interpretation I, we define

$$W_{\mathbf{\Pi}}''(I) = \begin{cases} \prod_{c=v \in TC(I)} M_{\mathbf{\Pi}}(c=v) & \text{if } I \in SM''[\mathbf{\Pi}] \\ 0 & \text{otherwise} \end{cases}$$

and

$$P''_{\mathbf{\Pi}}(I) = \frac{W''_{\mathbf{\Pi}}(I)}{\sum_{J \in SM''[\mathbf{\Pi}]} W''_{\mathbf{\Pi}}(J)}.$$

The following proposition tells us that the probability of an interpretation can be computed from the probabilities assigned to probabilistic atoms, similar to the way ProbLog is defined.

Proposition 4 For any multi-valued probabilistic program Π such that each p_i in (3) is positive for every probabilistic constant c, if $SM''[\Pi]$ is not empty, then for any interpretation I, $P''_{\Pi}(I)$ coincides with $P_{T(\Pi)}(I)$.

8 P-log and LP^{MLN}

Simple P-log

In this section, we define a fragment of P-log, which we call *simple P-log*.

Syntax Let σ be a multi-valued propositional signature as in the previous section. A simple P-log program Π is a tuple

$$\Pi = \langle R, S, P, Obs, Act \rangle \tag{6}$$

where

• R is a set of normal rules of the form

$$A \leftarrow B_1, \dots, B_m, not \ B_{m+1}, \dots, not \ B_n.$$
 (7)

Here and after we assume A, B_1, \ldots, B_n are atoms from σ $(0 \le m \le n)$.

• S is a set of random selection rules of the form

[r]
$$random(c) \leftarrow B_1, \dots, B_m, not \ B_{m+1}, \dots, not \ B_n$$
(8)

where r is an identifier and c is a constant.

• P is a set of probability atoms (pr-atoms) of the form

$$pr_r(c=v \mid B_1,\ldots,B_m, not \mid B_{m+1},\ldots,not \mid B_n) = p$$

where r is the identifier of some random selection rule in S, c is a constant, and $v \in Dom(c)$, and $p \in [0, 1]$.

¹Note that here "=" is just a part of the symbol for propositional atoms, and is not equality in first-order logic.

- Obs is a set of atomic facts of the form Obs(c=v) where c is a constant and $v \in Dom(c)$.
- Act is a set of atomic facts of the form Do(c=v) where c is a constant and $v \in Dom(c)$.

Example 5 We use the following simple P-log program as our main example $(d \in \{D_1, D_2\}, y \in \{1, \dots 6\})$:

$$Owner(D_1) = Mike$$

$$Owner(D_2) = John$$

$$Even(d) \leftarrow Roll(d) = y, \ y \ mod \ 2 = 0$$

$$\sim Even(d) \leftarrow not \ Even(d)$$

$$[r(d)] \ random(Roll(d))$$

$$pr(Roll(d) = 6 \mid Owner(d) = Mike) = \frac{1}{4}.$$

Semantics Given a simple P-log program Π of the form (6), a (standard) ASP program $\tau(\Pi)$ with the multivalued signature σ' is constructed as follows:

- σ' contains all atoms in σ , and atom $Intervene(c) = \mathbf{t}$ (abbreviated as Intervene(c)) for every constant c of σ ; the domain of Intervene(c) is $\{\mathbf{t}\}$.
- $\tau(\Pi)$ contains all rules in R.
- For each random selection rule of the form (8) with $Dom(c) = \{v_1, \ldots, v_n\}$, $\tau(\Pi)$ contains the following rules:

$$c=v_1;\ldots;c=v_n \leftarrow B_1,\ldots,B_m,not\ B_{m+1},\ldots,not\ B_n,not\ Intervene(c).$$

- $\tau(\Pi)$ contains all atomic facts in *Obs* and *Act*.
- For every atom c = v in σ ,

$$\leftarrow Obs(c=v), not c=v.$$

• For every atom c = v in σ , $\tau(\Pi)$ contains

$$c = v \leftarrow Do(c = v)$$

 $Intervene(c) \leftarrow Do(c = v).$

Example 5 continued The following is $\tau(\Pi)$ for the simple P-log program Π in Example 5 ($x \in \{Mike, John\}$, $b \in \{\mathbf{t}, \mathbf{f}\}$):

$$Owner(D_1) = \textit{Mike} \\ Owner(D_2) = \textit{John} \\ Even(d) \leftarrow Roll(d) = y, \ y \ mod \ 2 = 0 \\ \sim Even(d) \leftarrow not \ Even(d) \\ Foll(d) = 1; \ Roll(d) = 2; \ Roll(d) = 3; \ Roll(d) = 4; \\ Roll(d) = 5; \ Roll(d) = 6 \leftarrow not \ Intervene(Roll(d)) \\ \leftarrow Obs(Owner(d) = x), not \ Owner(d) = x \\ \leftarrow Obs(Even(d) = b), not \ Even(d) = b \\ \leftarrow Obs(Roll(d) = y), not \ Roll(d) = y \\ Owner(d) = x \leftarrow Do(Owner(d) = x) \\ Even(d) = b \leftarrow Do(Even(d) = b) \\ Roll(d) = y \leftarrow Do(Roll(d) = y) \\ Intervene(Owner(d)) \leftarrow Do(Owner(d) = x) \\ Intervene(Even(d)) \leftarrow Do(Even(d) = b) \\ Intervene(Roll(d)) \leftarrow Do(Roll(d) = y). \\ Intervene(Roll(d)) \leftarrow Do(Roll(d)) + Do$$

The stable models of $\tau(\Pi)$ are called the *possible worlds* of Π , and denoted by $\omega(\Pi)$. For an interpretation W and an

atom $c\!=\!v$, we say $c\!=\!v$ is *possible* in W with respect to Π if Π contains a random selection rule for c

$$[r] \ random(c) \leftarrow B,$$

where B is a set of atoms possibly preceded with *not*, and W satisfies B. We say r is applied in W if $W \models B$.

We say that a pr-atom $pr_r(c=v \mid B) = p$ is applied in W if $W \models B$ and r is applied in W.

As in (Baral, Gelfond, and Rushton 2009), we assume that simple P-log programs Π satisfy the following conditions:

- Unique random selection rule For any constant c, program Π contains at most one random selection rule for c that is applied in W.
- Unique probability assignment If Π contains a random selection rule r for constant c that is applied in W, then, for any two different probability atoms

$$pr_r(c=v_1 \mid B') = p_1$$

 $pr_r(c=v_2 \mid B'') = p_2$

in Π that are applied in W, we have $v_1 \neq v_2$ and B' = B''.

Given a simple P-log program Π , a possible world $W \in \omega(\Pi)$ and a constant c for which c = v is possible in W, we first define the following notations:

• Since c=v is possible in W, by the unique random selection rule assumption, it follows that there is exactly one random selection rule r for constant c that is applied in W. Let $r_{W,c}$ denote this random selection rule. By the unique probability assignment assumption, if there are pr-atoms of the form $pr_{r_{W,c}}(c=v\mid B)$ that are applied in W, all B in those pr-atoms should be the same. We denote this B by $B_{W,c}$. Define $PR_W(c)$ as

$$\{pr_{r_{W,c}}(c=v \mid B_{W,c}) = p \in \Pi \mid v \in Dom(c)\}.$$

if $W \not\models Intervene(c)$ and \emptyset otherwise.

• Define $AV_W(c)$ as

$$\{v \mid pr_{r_{W,c}}(c=v \mid B_{W,c}) = p \in PR_{W}(c)\}.$$

- For each $v \in AV_W(c)$, define the assigned probability of c = v w.r.t. W, denoted by $ap_W(c = v)$, as the value p for which $pr_{r_{W,c}}(c = v \mid B_{W,c}) = p \in PR_W(c)$.
- Define the *default probability* for c w.r.t. W, denoted by $dp_W(c)$, as

$$dp_W(c) = \frac{1 - \sum_{v \in AV_W(c)} ap_W(c=v)}{|Dom(c) \setminus AV_W(c)|}.$$

For every possible world $W\in\omega(\Pi)$ and every atom $c\!=\!v$ possible in W, the causal probability $P(W,c\!=\!v)$ is defined as follows:

$$P(W,c\!=\!v) = \begin{cases} ap_W(c\!=\!v) & \text{if } v \in AV_W(c) \\ dp_W(c) & \text{otherwise.} \end{cases}$$

The unnormalized probability of a possible world W, denoted by $\hat{\mu}_{\Pi}(W)$, is defined as

$$\hat{\mu}_{\Pi}(W) = \prod_{\substack{c=v \in W \text{ and} \\ c=v \text{ is possible in } W}} P(W, c=v)$$

Assuming Π has at least one possible world with nonzero unnormalized probability, the *normalized probability* of W, denoted by $\mu_{\Pi}(W)$, is defined as

$$\mu_{\Pi}(W) = \frac{\hat{\mu}_{\Pi}(W)}{\sum_{W_i \in \omega(\Pi)} \hat{\mu}_{\Pi}(W_i)}.$$

Given a simple P-log program Π and a formula A, the probability of A with respect to Π is defined as

$$P_\Pi(A) = \sum_{W \text{ is a possible world of }\Pi \text{ that satisfies }A} \mu_\Pi(W).$$

We say Π is *consistent* if Π has at least one possible world.

Example 5 continued Given the possible world $W = \{Owner(D_1) = Mike, Owner(D_2) = John, Roll(D_1) = 6, Roll(D_2) = 3, Even(D_1)\}$, the probability of $Roll(D_1) = 6$ is $P(W, Roll(D_1) = 6) = 0.25$, the probability of $Roll(D_2) = 3$ is $\frac{1}{6}$. The unnormalized probability of W, i.e., $\hat{\mu}(W) = P(W, Roll(D_1) = 6) \cdot P(W, Roll(D_2) = 3) = \frac{1}{24}$.

The main differences between simple P-log and P-log are as follows.

- The unique probability assignment assumption in P-log is more general: it does not require the part B' = B''. However, all the examples in the P-log paper (Baral, Gelfond, and Rushton 2009) satisfy our stronger unique probability assignment assumption.
- P-log allows a more general random selection rule of the form

$$[r] random(c : \{x : P(x)\}) \leftarrow B'.$$

Among the examples in (Baral, Gelfond, and Rushton 2009), only the "Monty Hall Problem" encoding and the "Moving Robot Problem" encoding use "dynamic range $\{x: P(x)\}$ " in random selection rules and cannot be represented as simple P-log programs.

Turning Simple P-log into Multi-Valued Probabilistic Programs

The main idea of the syntactic translation is to introduce auxiliary probabilistic constants for encoding the assigned probability and the default probability.

Given a simple P-log program Π , a constant c, a set of literals B, and a random selection rule $[r] \, random(c) \leftarrow B'$ in Π , we first introduce several notations, which resemble the ones used for defining the P-log semantics.

• We define $PR_{B,r}(c)$ as

$$\{pr_r(c=v\mid B) = p \in \Pi \mid v \in Dom(c)\}$$

if Act in Π does not contain Do(c = v') for any $v' \in Dom(c)$ and \emptyset otherwise.

• We define $AV_{B,r}(c)$ as

$$\{v \mid pr_r(c=v \mid B) = p \in PR_{B,r}(c)\}.$$

For each v ∈ AV_{B,r}(c), we define the assigned probability of c = v w.r.t. B, r, denoted by ap_{B,r}(c = v), as the value p for which pr_r(c=v | B) = p ∈ PR_{B,r}(c).

• We define the *default probability* for c w.r.t. B and r, denoted by $dp_{B,r}(c)$, as

$$dp_{B,r}(c) = \frac{1 - \sum_{v \in AV_{B,r}(c)} ap_{B,r}(c = v)}{|Dom(c) \setminus AV_{B,r}(c)|}.$$

• For each $c \in v$, define its *causal probability* w.r.t. B and r, denoted by P(B, r, c = v), as

$$P(B,r,c\!=\!v) = \begin{cases} ap_{B,r}(c\!=\!v) & \text{if } v \in AV_{B,r}(c) \\ dp_{B,r}(c) & \text{otherwise.} \end{cases}$$

Now we translate Π into the corresponding multi-valued probabilistic program $\Pi^{\mathrm{LP^{MLN}}}$ as follows:

• The signature of $\Pi^{LP^{MLN}}$ is

$$\begin{split} \sigma' \cup \{pf^c_{B,r} = v \mid PR_{B,r}(c) \neq \emptyset \text{ and } v \in Dom(c)\} \\ \cup \{pf^c_{\square,r} = v \mid r \text{ is a random selection rule of } \Pi \text{ for } c \\ \text{and } v \in Dom(c)\} \end{split}$$

 $\cup \{Assigned_r = \mathbf{t} \mid r \text{ is a random selection rule of } \Pi\}.$

- $\Pi^{LP^{MLN}}$ contains all rules in $\tau(\Pi)$.
- For any constant c, any random selection rule r for c, and any set B of literals such that $PR_{B,r}(c) \neq \emptyset$, include in $\Pi^{\mathrm{LP^{MLN}}}$:
 - the probabilistic constant declaration:

$$P(B, r, c = v_1) : pf_{B,r}^c = v_1 \mid \dots \mid P(B, r, c = v_n) : pf_{B,r}^c = v_n$$

for each probabilistic constant $pf_{B,r}^c$ of the signature, where $\{v_1,\ldots,v_n\}=Dom(c)$. The constant $pf_{B,r}^c$ is used for representing the probability distribution for c when condition B holds in the experiment represented by r.

- the rules

$$c = v \leftarrow B, B', pf_{B,r}^c = v, not Intervene(c).$$
 (9)

for all $v \in Dom(c)$, where B' is the body of the random selection rule r. These rules assign v to c when the assigned probability distribution applies to c = v.

- the rule

$$Assigned_r \leftarrow B, B', not\ Intervene(c)$$

where B' is the body of the random selection rule r (we abbreviate $Assigned_r = \mathbf{t}$ as $Assigned_r$). $Assigned_r$ becomes true when any pr-atoms for c related to r is applied.

- For any constant c and any random selection rule r for c, include in $\Pi^{\mathrm{LP^{MLN}}}$:
 - the probabilistic constant declaration

$$\frac{1}{|Dom(c)|}: pf_{\Box,r}^c = v_1 \mid \dots \mid \frac{1}{|Dom(c)|}: pf_{\Box,r}^c = v_n$$

for each probabilistic constant $pf_{\square,r}^c$ of the signature, where $\{v_1,\ldots,v_n\}=Dom(c)$. The constant $pf_{\square,r}^c$ is used for representing the default probability distribution for c when there is no applicable pr-atom.

 $^{^{2}}$ A literal is either an atom A or its negation not A.

Example	Parameter	plog1	plog2	Alchemy (default)	Alchemy (maxstep=5000)
	$N_{dice} = 2$	$0.00s + 0.00s^a$	$0.00s + 0.00s^b$	$0.02s + 0.21s^c$	0.02s + 0.96s
	$N_{dice} = 7$	1.93s + 31.37s	0.00s + 1.24s	0.13s + 0.73s	0.12s + 3.39s
dice	$N_{dice} = 8$	12.66s + 223.02s	0.00s + 6.41s	0.16s + 0.84s	0.16s + 3.86s
	$N_{dice} = 9$	timeout	0.00s + 48.62s	0.19s + 0.95s	0.19s + 4.37s
	$N_{dice} = 10$	timeout	timeout	0.23s + 1.06s	0.24s + 4.88s
	$N_{dice} = 100$	timeout	timeout	19.64s + 16.34s	19.55s + 76.18s
	maxstep = 5	0.00s + 0.00s	segment fault	2.34s + 2.54s	2.3s + 11.75s
	maxstep = 10	0.37s + 4.86s	segment fault	4.78s + 5.24s	4.74s + 24.34s
robot	maxstep = 12	3.65 + 51.76s	segment fault	5.72s + 6.34s	5.75s + 29.46s
	maxstep = 13	11.68s + 168.15s	segment fault	6.2s + 6.89s	6.2s + 31.96s
	maxstep = 15	timeout	segment fault	7.18s + 7.99s	7.34s + 37.67s
	maxstep = 20	timeout	segment fault	9.68s + 10.78s	9.74s + 50.04s

Table 1: Performance Comparison between Two Ways to Compute Simple P-log Programs

- the rules

$$c = v \leftarrow B', pf_{\square,r}^c = v, not Assigned_r.$$

for all $v \in Dom(c)$, where B' is the body of the random selection rule r. These rules assign v to c when the uniform distribution applies to c = v.

Example 5 continued The simple P-log program Π in Example 5 can be turned into the following multi-valued probabilistic program. In addition to $\tau(\Pi)$ we have

$$\begin{array}{l} \text{BSIC Program. In addition to } \tau(\Pi) \text{ we have} \\ 0.25: pf_{O(d)=M,r(d)}^{Roll(d)} = 6 \mid 0.15: pf_{O(d)=M,r(d)}^{Roll(d)} = 5 \mid \\ 0.15: pf_{O(d)=M,r(d)}^{Roll(d)} = 4 \mid 0.15: pf_{O(d)=M,r(d)}^{Roll(d)} = 3 \mid \\ 0.15: pf_{O(d)=M,r(d)}^{Roll(d)} = 2 \mid 0.15: pf_{O(d)=M,r(d)}^{Roll(d)} = 1 \\ \frac{1}{6}: pf_{\Box,r(d)}^{Roll(d)} = 6 \mid \frac{1}{6}: pf_{\Box,r(d)}^{Roll(d)} = 5 \mid \frac{1}{6}: pf_{\Box,r(d)}^{Roll(d)} = 4 \mid \\ \frac{1}{6}: pf_{\Box,r(d)}^{Roll(d)} = 3 \mid \frac{1}{6}: pf_{\Box,r(d)}^{Roll(d)} = 2 \mid \frac{1}{6}: pf_{\Box,r(d)}^{Roll(d)} = 1 \\ Roll(d) = x \leftarrow Owner(d) = \text{Mike}, pf_{O(d)=M,r(d)}^{Roll(d)} = x, \\ & \text{not Intervene}(Roll(d)) \\ Assigned_{r(d)} \leftarrow Owner(d) = \text{Mike}, not Intervene}(Roll(d)) \\ Roll(d) = x \leftarrow pf_{\Box,r(d)}^{Roll(d)} = x, not Assigned_{r(d)}. \end{array}$$

Theorem 5 For any consistent simple P-log program Π of signature σ and any possible world W of Π , we construct a formula F_W as follows.

$$F_{W} = (\bigwedge_{c=v \in W} c = v) \land \\ (\bigwedge_{c=v \in W} c = v) \land \\ (\bigwedge_{c=v \text{ is possible in } W,} pf_{B_{W,c},r_{W,c}}^{c} = v) \\ \land (\bigwedge_{c,v :} c = v \text{ is possible in } W, \\ c = v \text{ is possible in } W, \\ W \models c = v \text{ and } PR_{W}(c) = \emptyset$$

We have

$$\mu_{\Pi}(W) = P_{\Pi^{\mathrm{LPMLN}}}(F_W),$$

and, for any proposition A of signature σ ,

$$P_{\Pi}(A) = P_{\Pi L P^{\text{MLN}}}(A).$$

Example 5 continued For the possible world

$$W = \{Roll(D_1) = 6, Roll(D_2) = 3, Even(D_1), \sim Even(D_2), \\ Owner(D_1) = Mike, Owner(D_2) = John\},$$

 F_W is

$$\begin{array}{l} \textit{Roll}(D_1) = 6 \land \textit{Roll}(D_2) = 3 \land \textit{Even}(D_1) \land \sim \textit{Even}(D_2) \\ \land \textit{Owner}(D_1) = \textit{Mike} \land \textit{Owner}(D_2) = \textit{John} \\ \land \textit{pf}_{O(D_1) = M,r}^{\textit{Roll}(D_1)} = 6 \land \textit{pf}_{\Box,r}^{\textit{Roll}(D_2)} = 3. \end{array}$$

It can be seen that
$$\hat{\mu}_{\Pi}(W) = \frac{1}{4} \times \frac{1}{6} = P_{\Pi^{LPMLN}}(F_W)$$
.

The embedding tells us that the exact inference in simple P-log is no harder than the one in $\mathrm{LP}^{\mathrm{MLN}}$.

Experiments

Following the translation described above, it is possible to compute a tight P-log program by translating it to $\mathrm{LP^{MLN}}$, and further turn that into the MLN instance following the translation introduced in Section 5, and then compute it using an MLN solver.

Table 1 shows the performance comparison between this method and the native P-log implementation on some examples, which are modified from the ones from (Baral, Gelfond, and Rushton 2009). P-log 1.0.0 (http://www.depts.ttu.edu/cs/research/ krlab/plog.php) implements two algorithms. The first algorithm (plog1) translates a P-log program to an ASP program and uses ASP solver SMODELS to find all possible worlds of the P-log program. The second algorithm (plog2) produces a partially ground P-log program relevant to the query, and evaluates partial possible worlds to compute the probability of formulas. ALCHEMY 2.0 implements several algorithms for inference and learning. Here we use MC-SAT for lazy probabilistic inference, which combines MCMC with satisfiability testing. ALCHEMY first creates Markov Random Field (MRF) and then perform MC-SAT on the MRF created. The default setting of ALCHEMY performs 1000 steps sampling. We also tested with 5000 steps sampling to produce probability that is very close to the true probability. The experiments were performed on an Intel Core2 Duo CPU E7600 3.06GH with 4GB RAM running Ubuntu 13.10. The timeout was for 10 minutes.

The experiments showed the clear advantage of the translation method that uses ALCHEMY. It is more scalable, and can be tuned to yield more precise probability with more

^a smodels answer set finding time + probability computing time

^bpartial grounding time + probability computing time

^cmrf creating time + sampling time

sampling or less precise but fast computation, by changing sampling parameters. The P-log implementation of the second algorithm led to segment faults in many cases.

9 Other Related Work

We observed that ProbLog can be viewed as a special case of $\mathrm{LP^{MLN}}$. This result can be extended to embed Logic Programs with Annotated Disjunctions (LPAD) in $\mathrm{LP^{MLN}}$ based on the fact that any LPAD program can be further turned into a ProbLog program by eliminating disjunctions in the heads (Gutmann 2011, Section 3.3).

It is known that LPAD is related to several other languages. In (Vennekens et al. 2004), it is shown that Poole's ICL (Poole 1997) can be viewed as LPAD, and that acyclic LPAD programs can be turned into ICL. This indirectly tells us how ICL is related to $\mathrm{LP^{MLN}}$.

CP-logic (Vennekens, Denecker, and Bruynooghe 2009) is a probabilistic extension of FO(ID) (Denecker and Ternovska 2007) that is closely related to LPAD.

PrASP (Nickles and Mileo 2014) is another probabilistic ASP language. Like P-log and $\mathrm{LP^{MLN}}$, probability distribution is defined over stable models, but the weights there directly represent probabilities.

Similar to LP^{MLN}, log-linear description logics (Niepert, Noessner, and Stuckenschmidt 2011) follow the weight scheme of log-linear models in the context of description logics.

10 Conclusion

Adopting the log-linear models of MLN, language $LP^{\rm MLN}$ provides a simple and intuitive way to incorporate the concept of weights into the stable model semantics. While MLN is an undirected approach, $LP^{\rm MLN}$ is a directed approach, where the directionality comes from the stable model semantics. This makes $LP^{\rm MLN}$ closer to P-log and ProbLog. On the other hand, the weight scheme adopted in $LP^{\rm MLN}$ makes it amenable to apply the statistical inference methods developed for MLN computation. More work needs to be done to find how the methods studied in machine learning will help us to compute weighted stable models. While a fragment of $LP^{\rm MLN}$ can be computed by existing implementations of and MLNs, one may design a native computation method for the general case.

The way that we associate weights to stable models is orthogonal to the way the stable model semantics are extended in a deterministic way. Thus it is rather straightforward to extend $\mathrm{LP^{MLN}}$ to allow other advanced features, such as aggregates, intensional functions and generalized quantifiers.

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Appendix to "Weighted Rules under the Stable Model Semantics"

11 Proof of Proposition 1

We use $I \models_{SM} \Pi$ to denote "the interpretation I is a (deterministic) stable model of the program Π ".

The proof of Proposition 1 uses the following theorem, which is a special case of Theorem 2 in (?). Given an ASP program Π of signature σ and a subset Y of σ , we use $LF_{\Pi}(Y)$ to denote the loop formula of Y for Π .

Theorem 6 Let Π be a program of a finite first-order signature σ with no function constants of positive arity, and let I be an interpretation of σ that satisfies Π . The following conditions are equivalent to each other:

- (a) $I \models_{SM} \Pi$;
- (b) for every nonempty finite subset Y of atoms formed from constants in σ , I satisfies $LF_{\Pi}(Y)$;
- (c) for every finite loop Y of Π , I satisfies $LF_{\Pi}(Y)$.

Proposition 1 For any (unweighted) logic program Π of signature σ , and any subset Π' of Π , if an interpretation I is a stable model of Π' and I satisfies Π , then I is a stable model of Π as well.

Proof.

For any subset L of σ , since I is a stable model of Π' , by Theorem 6, I satisfies $LF_{\Pi'}(L)$, that is, I satisfies $L^{\wedge} \to ES_{\Pi'}(L)$. It can be seen that the disjunctive terms in $ES_{\Pi}(L)$ is a subset of the disjunctive terms in $ES_{\Pi}(L)$, and thus $ES_{\Pi'}(L)$ entails $ES_{\Pi}(L)$. So I satisfies $L^{\wedge} \to ES_{\Pi}(L)$, which is $LF_{\Pi}(L)$, and since in addition we have $I \models \Pi$, I is a stable model of Π .

12 Proof of Proposition 2

Proposition 2 If SM'[Π] is not empty, for every interpretation I, $P'_{\Pi}(I)$ coincides with $P_{\Pi}(I)$.

Proof. For any interpretation I, by definition, we have

$$\begin{split} P_{\Pi}(I) &= \lim_{\alpha \to \infty} \frac{W_{\Pi}(I)}{\sum_{J \in SM[\Pi]} W_{\Pi}(J)} \\ &= \lim_{\alpha \to \infty} \frac{W_{\Pi}(I)}{\sum_{J \vDash_{SM} \overline{\Pi_J}} exp(\sum_{w: F \in \Pi_J} w)}. \end{split}$$

We notice the following fact: If an interpretation I belongs to $SM'[\Pi]$, then I satisfies $\overline{\Pi^{hard}}$ and I is a stable model of $\overline{\Pi_I}$. This can be seen from the fact that if $I \models \overline{\Pi^{hard}}$, then we have $\Pi_I = \Pi^{hard} \cup (\Pi^{soft})_I$.

• Suppose $I \in SM'[\Pi]$, which implies that I satisfies $\overline{\Pi^{hard}}$ and is a stable model of $\overline{\Pi_I}$. Then we have

$$P_{\Pi}(I) = \lim_{\alpha \to \infty} \frac{exp(\sum_{w:F \in \Pi_I} w)}{\sum_{J \vDash_{SM} \overline{\Pi_J}} exp(\sum_{w:F \in \Pi_J} w)}.$$

Splitting the denominator into two parts: those J's that satisfy $\overline{\Pi^{hard}}$ and those that do not, and extracting the weights of formulas in $\overline{\Pi^{hard}}$, we have

$$P_{\Pi}(I) = \lim_{\alpha \to \infty} \frac{exp(|\Pi^{hard}| \cdot \alpha) \cdot exp(\sum_{w: F \in \Pi_{I} \backslash \Pi^{hard}} w)}{exp(|\Pi^{hard}| \cdot \alpha) \cdot \sum_{J \vDash_{SM} \overline{\Pi_{J}} : J \vDash \overline{\Pi^{hard}}} exp(\sum_{w: F \in \Pi_{J} \backslash \Pi^{hard}} w) + \sum_{J \vDash_{SM} \overline{\Pi_{J}} : J \nvDash \overline{\Pi^{hard}}} exp(|\Pi^{hard} \cap \Pi_{J}| \cdot \alpha) \cdot exp(\sum_{w: F \in \Pi_{J} \backslash \Pi^{hard}} w)}$$

We divide both the numerator and the denominator by $exp(|\Pi^{hard}| \cdot \alpha)$.

$$P_{\Pi}(I) = \lim_{\alpha \to \infty} \frac{\exp(\sum_{w:F \in \Pi_I \backslash \Pi hard} w)}{\sum_{J \vDash_{SM} \overline{\Pi_J}:J \vDash \overline{\Pi hard}} \exp(\sum_{w:F \in \Pi_J \backslash \Pi hard} w) + \frac{\sum_{J \vDash_{SM} \overline{\Pi_J}:J \nvDash \overline{\Pi hard}} \exp(|\Pi^{hard} \cap \Pi_J| \cdot \alpha) \cdot \exp(\sum_{w:F \in \Pi_J \backslash \Pi hard} w)}{\exp(|\Pi^{hard} \cap \Omega_J| \cdot \alpha)}}$$

$$= \lim_{\alpha \to \infty} \frac{\exp(\sum_{w:F \in \Pi_J \backslash \Pi hard} w)}{\sum_{J \vDash_{SM} \overline{\Pi_J}:J \vDash \overline{\Pi hard}} \exp(\sum_{w:F \in \Pi_J \backslash \Pi hard} w) + \sum_{J \vDash_{SM} \overline{\Pi_J}:J \nvDash \overline{\Pi hard}} \frac{\exp(|\Pi^{hard} \cap \Pi_J| \cdot \alpha)}{\exp(|\Pi^{hard} \cap \Pi_J| \cdot \alpha)} \cdot \exp(\sum_{w:F \in \Pi_J \backslash \Pi hard} w)}$$

For $J \nvDash \overline{\Pi^{hard}}$, we note $|\Pi^{hard} \cap \Pi_J| \leq |\Pi^{hard}| - 1$, so

$$P_{\Pi}(I) = \frac{exp(\sum_{w:F \in \Pi_{I} \setminus \Pi^{hard}} w)}{\sum_{J \models_{SM} \overline{\Pi_{J}}:J \models \overline{\Pi^{hard}}} exp(\sum_{w:F \in \Pi_{J} \setminus \Pi^{hard}} w)}$$
$$= P'_{\Pi}(I).$$

• Suppose $I \notin SM'[\Pi]$, which implies that I does not satisfy $\overline{\Pi^{hard}}$ or is not a stable model of $\overline{\Pi_I}$. Let K be any interpretation in $SM'[\Pi]$. By definition, K satisfies $\overline{\Pi^{hard}}$ and K is a stable model of $\overline{\Pi_K}$.

- Suppose I is not a stable model of $\overline{\Pi_I}$. Then by definition, $W_{\Pi}(I) = W'_{\Pi}(I) = 0$, and thus $P_{\Pi}(I) = P'_{\Pi}(I) = 0$.
- Suppose I is a stable model of $\overline{\Pi_I}$ but I does not satisfy $\overline{\Pi^{hard}}$.

$$P_{\Pi}(I) = \lim_{\alpha \to \infty} \frac{exp(\sum_{w:F \in \Pi_I} w)}{\sum_{J \vDash_{SM} \overline{\Pi_I}} exp(\sum_{w:F \in \Pi_J} w)}.$$

Since K satisfies $\overline{\Pi^{hard}}$, we have $\overline{\Pi^{hard}} \subseteq \overline{\Pi_K}$. By assumption we have that K is a stable model of $\overline{\Pi_K}$. We split the denominator into K and the other interpretations, which gives

$$P_{\Pi}(I) = \lim_{\alpha \to \infty} \frac{exp(\sum_{w:F \in \Pi_I} w)}{exp(\sum_{w:F \in \Pi_K} w) + \sum_{J \neq K:J \vDash_{SM} \overline{\Pi_I}} exp(\sum_{w:F \in \Pi_I} w)}.$$

Extracting weights from the formulas in Π^{hard} , we have

$$\begin{split} P_{\Pi}(I) &= \lim_{\alpha \to \infty} \frac{exp(|\Pi^{hard} \cap \Pi_I| \cdot \alpha) \cdot exp(\sum_{w: F \in \Pi_I \setminus \Pi^{hard}} w)}{exp(|\Pi^{hard}| \cdot \alpha) \cdot exp(\sum_{w: F \in \Pi_K \setminus \Pi^{hard}} w) + \sum_{J \neq K: J \vDash_{SM} \overline{\Pi_J}} exp(\sum_{w: F \in \Pi_J} w)} \\ &\leq \lim_{\alpha \to \infty} \frac{exp(|\Pi^{hard} \cap \Pi_I| \cdot \alpha) \cdot exp(\sum_{w: F \in \Pi_I \setminus \Pi^{hard}} w)}{exp(|\Pi^{hard}| \cdot \alpha) \cdot exp(\sum_{w: F \in \Pi_K \setminus \Pi^{hard}} w)}. \end{split}$$

Since I does not satisfy $\overline{\Pi^{hard}}$, we have $|\Pi^{hard} \cap \Pi_I| \leq |\Pi^{hard}| - 1$, and thus

$$P_{\Pi}(I) \leq \lim_{\alpha \to \infty} \frac{exp(|\Pi^{hard} \cap \Pi_I| \cdot \alpha) \cdot exp(\sum_{w: F \in \Pi_I \setminus \Pi^{hard}} w)}{exp(|\Pi^{hard}| \cdot \alpha) \cdot exp(\sum_{w: F \in \Pi_K \setminus \Pi^{hard}} w)} = 0 = P'_{\Pi}(I).$$

The following proposition establishes a useful property.

Proposition 5 Given an LP^{MLN} program Π such that $SM'[\Pi]$ is not empty, and an interpretation I, the following three statements are equivalent:

- 1. I is a stable model of Π ;
- 2. $I \in SM'[\Pi]$;
- 3. $P'_{\Pi}(I) > 0$.

Proof. Firstly, it is easy to see that the second and third conditions are equivalent. We notice that exp(x)>0 for all $x\in (-\infty,+\infty)$. So it can be seen from the definition that $W'_\Pi(I)>0$ if and only if $I\in SM'[\Pi]$, and consequently $P'_\Pi(I)>0$ if and only if $I\in SM'[\Pi]$. Secondly, by Proposition 2, we know that $P'_\Pi(I)$ is equivalent to $P_\Pi(I)$. By definition, the first condition is equivalent to " $P_\Pi(I)>0$ ". So we have that the first condition is equivalent to the third condition.

Proposition 5 does not hold if we replace " $SM'[\Pi]$ " by " $SM[\Pi]$ ".

Example 6 Consider the following LP^{MLN} program Π :

$$(r_1)$$
 α : p (r_2) 1 : q

and the interpretation $I = \{q\}$. I belongs to $SM[\Pi]$ since I is a stable model of $\overline{\Pi_I}$, which contains r_2 only. However, $P_{\Pi}(I) = 0$ since I does not satisfy the hard rule r_1 . On the other hand, I does not belong to $SM'[\Pi]$.

13 Proof of Theorem 1

Theorem 1 For any logic program Π , the (deterministic) stable models of Π are exactly the (probabilistic) stable models of \mathbb{P}_{Π} whose weight is $e^{k\alpha}$, where k is the number of all (ground) rules in Π . If Π has at least one stable model, then all stable models of \mathbb{P}_{Π} have the same probability, and are thus the stable models of Π as well.

Proof. We notice that $\overline{(\mathbb{P}_{\Pi})^{hard}} = \Pi$. We first show that an interpretation I is a stable model of Π if and only if it is a stable model of \mathbb{P}_{Π} whose weight is $e^{k\alpha}$. Suppose I is a stable model of Π . Then I is a stable model of $\overline{(\mathbb{P}_{\Pi})^{hard}}$. Obviously $(\mathbb{P}_{\Pi})^{hard}$ is $(\mathbb{P}_{\Pi})_{I}$. So the weight of I is $e^{k\alpha}$. Suppose I is a stable model of \mathbb{P}_{Π} whose weight is $e^{k\alpha}$. Then I satisfies all the rules in \mathbb{P}_{Π} , since all rules in \mathbb{P}_{Π} contribute to its weight, and I is a stable model of $\overline{(\mathbb{P}_{\Pi})_{I}} = \overline{(\mathbb{P}_{\Pi})^{hard}}$, which is equivalent to Π . So I is a stable model of Π .

Now suppose Π has at least one stable model. It follows that $\overline{(\mathbb{P}_{\Pi})^{hard}}$ has some stable model.

- Suppose I is not a stable model of Π .
 - Suppose I does not satisfy Π . Then $I \nvDash \overline{(\mathbb{P}_{\Pi})^{hard}}$. By Proposition 2, $P_{\mathbb{P}_{\Pi}}(I) = 0$, and consequently I is not a stable model of \mathbb{P}_{Π} .

- Suppose I satisfies Π . Then $\overline{(\mathbb{P}_{\Pi})_I}=\Pi$ and I is not a stable model of $\overline{(\mathbb{P}_{\Pi})_I}$. By definition, $W_{\mathbb{P}_{\Pi}}(I)=0$ and consequently $P_{\mathbb{P}_{\Pi}}(I)=0$, which means that I is not a stable model of \mathbb{P}_{Π} .
- Suppose I is a stable model of Π . Then $I \models \overline{(\mathbb{P}_{\Pi})^{hard}}$, $\overline{(\mathbb{P}_{\Pi})_I} = \Pi$ and I is a stable model of $\overline{(\mathbb{P}_{\Pi})_I}$. By Proposition 2,

$$\begin{split} P_{\mathbb{P}_{\Pi}}(I) &= \frac{exp(\sum_{w:F \in (\mathbb{P}_{\Pi})_{I} \setminus (\mathbb{P}_{\Pi})^{hard}} w)}{\sum_{J \models_{SM}} \overline{(\mathbb{P}_{\Pi})_{J}:J \models (\mathbb{P}_{\Pi})^{hard}}} exp(\sum_{w:F \in \overline{(\mathbb{P}_{\Pi})_{J} \setminus (\mathbb{P}_{\Pi})^{hard}}} w)} \\ &= \frac{exp(0)}{\sum_{J \models_{SM}} \overline{(\mathbb{P}_{\Pi})_{J}:J \models (\mathbb{P}_{\Pi})^{hard}}} exp(\sum_{w:F \in \overline{(\mathbb{P}_{\Pi})_{J} \setminus (\mathbb{P}_{\Pi})^{hard}}} w)}. \end{split}$$

It can be seen that " $J \vDash_{SM} \overline{(\mathbb{P}_{\Pi})_J}: J \vDash \overline{(\mathbb{P}_{\Pi})^{hard}}$ " is equivalent to "J is a stable model of Π ", since $\overline{(\mathbb{P}_{\Pi})^{hard}} = \Pi$. Furthermore, since $\Pi \setminus \overline{(\mathbb{P}_{\Pi})^{hard}} = \emptyset$, we have $exp(\sum_{w: F \in \overline{(\mathbb{P}_{\Pi})_J \setminus (\mathbb{P}_{\Pi})^{hard}}} w) = exp(0)$ for all $J \vDash_{SM} \overline{\mathbb{P}_J}: J \vDash \overline{(\mathbb{P}_{\Pi})^{hard}}$. So

$$P_{\mathbb{P}_{\Pi}}(I) = \frac{exp(0)}{\sum_{J \vDash_{SM} \Pi} exp(0)}$$
$$= \frac{1}{L}$$

where k is the number of stable models of Π .

14 Proof of Proposition 3

To facilitate the proof, we introduce a formal definition of ASP programs with weak constraints, as follows.

An ASP program with weak constraints is a pair

 $\langle \Pi, CONSTR \rangle$,

where Π is a set of standard ASP rules of the form (1), and *CONSTR* is a set of weak constraints C of the following form

$$:\sim Body \ [Weight], \tag{10}$$

where Weight is a positive integer, and Body is a set of literals. We will refer to Body by Body(C), and Weight by Weight(C). The penalty that I receives, denoted as Penalty(I), is defined as

$$Penalty(I) = \sum_{C \in CONSTR: I \vDash Body(C)} Weight(C).$$

The stable models of an ASP program with weak constraints $\langle \Pi, CONSTR \rangle$ are the elements of the following set

 $\{I \mid I \models_{SM} \Pi \text{ and there does not exists } J \neq I \text{ such that } J \models_{SM} \Pi \text{ and } Penalty(J) < Penalty(I)\}.$

By $\langle \Pi, CONSTR \rangle^{LP^{MLN}}$ we denote the following LP^{MLN} program:

$$\{\alpha: R \mid R \in \Pi\} \cup \{-Weight(C): \bot \leftarrow Body(C) \mid C \in \textit{CONSTR}\}.$$

For any interpretation K, let $CONSTR_K$ denote the following set:

$$\{\bot \leftarrow Body(C) \mid C \in CONSTR, K \vDash \neg Body(C)\}$$

Lemma 1 For any program with weak constraints $\langle \Pi, CONSTR \rangle$ that has a stable model, an interpretation I is a stable model of Π if and only if I is a stable model of $\langle \Pi, CONSTR \rangle^{\mathrm{LP^{MLN}}}$.

Proof. (\Rightarrow) Since $CONSTR_I$ consists of constraints only, we can derive from the fact that I is a stable model of Π that I is a stable model of $\Pi \cup CONSTR_I$, which is $\overline{(\langle \Pi, CONSTR \rangle^{\text{LP}^{\text{MLN}}})^{hard}} \cup \overline{((\langle \Pi, CONSTR \rangle^{\text{LP}^{\text{MLN}}})^{soft})_I}$. So $I \in SM' \left[\langle \Pi, CONSTR \rangle^{\text{LP}^{\text{MLN}}} \right]$ and by Proposition 5, I is a stable model of $\langle \Pi, CONSTR \rangle^{\text{LP}^{\text{MLN}}}$.

(\Leftarrow) Consider any stable model I of $\langle \Pi, CONSTR \rangle^{\text{LPMLN}}$. By Proposition 5, $I \in SM' \left[\langle \Pi, CONSTR \rangle^{\text{LPMLN}} \right]$. This means I is a stable model of $\overline{(\langle \Pi, CONSTR \rangle^{\text{LPMLN}})^{hard}} \cup \overline{((\langle \Pi, CONSTR \rangle^{\text{LPMLN}})^{soft})_I}$, which is equivalent to $\Pi \cup CONSTR_I$. Since $CONSTR_I$ contains constraints only, I is a stable model of Π .

Proposition 3 For any program with weak constraints that has a stable model, its stable models are the same as the stable models of the corresponding LP^{MLN} program with the highest normalized weight.

Proof.

 (\Rightarrow) For any program with weak constraints $\langle \Pi, CONSTR \rangle$ that has a stable model, let I be any one of its stable models. Since I is a stable model of $\langle \Pi, CONSTR \rangle$, by definition, we have:

- 1. $I \models_{SM} \Pi$;
- 2. There does not exist $J \neq I$ such that $J \models_{SM} \Pi$ and Penalty(J) < Penalty(I).

From the first condition, by Lemma 1, it follows that I is a stable model of $\langle \Pi, CONSTR \rangle^{\text{LP}^{\text{MLN}}}$

Now we show that there does not exist any $J \neq I$ such that J is a stable model of $\langle \Pi, CONSTR \rangle^{\text{LPMLN}}$ and $P_{\langle \Pi, CONSTR \rangle^{\text{LPMLN}}}(J) > 0$ $P_{(\Pi,CONSTR)^{\text{LPMLN}}}(I)$. Assume, for the sake of contradiction, that such J exists. Then J must be a stable model of Π by Lemma 1. $\text{Since } P_{\langle \Pi, \mathit{CONSTR} \rangle \mathtt{LPMLN}}(J) > P_{\langle \Pi, \mathit{CONSTR} \rangle \mathtt{LPMLN}}(I), \text{ due to how we translate } \langle \Pi, \mathit{CONSTR} \rangle \text{ to } \langle \Pi, \mathit{CONSTR} \rangle^{\mathtt{LPMLN}}, Penalty(J) < \mathbb{E}[P] = \mathbb{E}[P] =$

Penalty(I), which is a contradiction to the second condition. So such J does not exist. So I is a stable model of $\langle \Pi, CONSTR \rangle^{\mathrm{LP^{MLN}}}$ with the highest normalized weight. (\Leftarrow) Let I be any stable model of $\langle \Pi, CONSTR \rangle^{\mathrm{LP^{MLN}}}$ with the highest normalized weight.

- $I \models_{SM} \Pi$: Since I is a stable model of $\langle \Pi, CONSTR \rangle^{LP^{MLN}}$, by Lemma 1, I is a stable model of Π .
- There does not exist any J s.t. $J \models_{\text{SM}} \Pi$ and Penalty(J) < Penalty(I): Suppose, to the contrary, that there exists such J. By Lemma 1, J is a stable model of $\langle \Pi, CONSTR \rangle^{\text{LP}^{\text{MLN}}}$. Since Penalty(J) < Penalty(I), $P_{\langle \Pi, CONSTR \rangle^{\text{LP}^{\text{MLN}}}}(J) > P_{\langle \Pi, CONSTR \rangle^{\text{LP}^{\text{MLN}}}}(I)$. This is a contradiction to the fact that I is a stable model of $\langle \Pi, CONSTR \rangle^{\text{LP}^{\text{MLN}}}$ with the highest normalized weight. So there cannot

In conclusion, I is a stable model of $\langle \Pi, CONSTR \rangle$.

15 **Proof of Theorem 2 and Theorem 3**

The following is a review of MLN from (Richardson and Domingos 2006), slightly reformulated in order to facilitate our discussion.

A Markov Logic Network (MLN) \mathbb{L} of signature σ is a finite set of pairs $\langle F, w \rangle$ (also written as a "weighted formula" w : F), where F is a first-order formula of σ and w is either a real number or a symbol α denoting the "hard weight." We say that $\mathbb L$ is *ground* if its formulas contain no variables.

We first define the semantics for ground MLNs. For any ground MLN \mathbb{L} of signature σ and any Herbrand interpretation I of σ , we define \mathbb{L}_I to be the set of formulas in \mathbb{L} that are satisfied by I. The weight of an interpretation I under \mathbb{L} , denoted $W_{\mathbb{L}}(I)$, is defined as

$$W_{\mathbb{L}}(I) = exp \left(\sum_{\substack{w: F \in \mathbb{L} \\ F \in \mathbb{L}_I}} w \right).$$

The probability of I under \mathbb{L} , denoted $P_{\mathbb{L}}(I)$, is defined as

$$P_{\mathbb{L}}(I) = \lim_{\alpha \to \infty} \frac{W_{\mathbb{L}}(I)}{\sum_{J \in PW} W_{\mathbb{L}}(J)},$$

where PW ("Possible Worlds") is the set of all Herbrand interpretations of σ . We say that I is a model of \mathbb{L} if $P_{\mathbb{L}}(I) \neq 0$.

The definition is extended to any non-ground MLN by identifying it with its ground instance. Any MLN $\mathbb L$ of signature σ can be identified with the ground MLN, denoted $gr_{\sigma}[\mathbb{L}]$, by turning each formula in \mathbb{L} into a set of ground formulas. The weight of each ground formula in $gr_{\sigma}[\mathbb{L}]$ is the same as the weight of the formula in \mathbb{L} from which it is obtained.

Given a signature σ , we use $At(\sigma)$ to denote the set of all ground atoms that can be constructed from symbols in σ .

Theorem 2 Any MLN $\mathbb L$ and its LP^{MLN} representation $\Pi_{\mathbb L}$ have the same probability distribution over all interpretations.

Proof. We show that for any interpretation I, $P_{\mathbb{L}}(I) = P_{\Pi_{\mathbb{L}}}(I)$. For a set of atoms \mathbf{p} , let $\mathbf{Choice}(\mathbf{p})$ denote the set of weighted rules $\bigcup_{p \in \mathbf{p}} \{ w : p \leftarrow not \ not \ p \}.$

$$\begin{split} P_{\mathbb{L}}(I) &= \lim_{\alpha \to \infty} \frac{W_{\mathbb{L}}(I)}{\sum_{J \in PW} W_{\mathbb{L}}(J)} \\ &= \lim_{\alpha \to \infty} \frac{exp(\sum_{w:F \in \mathbb{L}_I} w)}{\sum_{J \in PW} exp(\sum_{w:F \in \mathbb{L}_J} w)}. \end{split}$$

Multiplying the weight of every interpretation by $exp(|At(\sigma)| \cdot w)$, we have

$$\begin{split} P_{\mathbb{L}}(I) &= \lim_{\alpha \to \infty} \frac{exp(|\mathbf{A}\mathbf{f}(\sigma)| \cdot w) \cdot exp(\sum_{w: F \in \mathbb{L}_I} w)}{\sum_{J \in PW} exp(|\mathbf{A}\mathbf{f}(\sigma)| \cdot w) \cdot exp(\sum_{w: F \in \mathbb{L}_J} w)} \\ &= \lim_{\alpha \to \infty} \frac{exp(\sum_{w: F \in \mathbb{L}_I \cup \mathbf{Choice}(\mathbf{A}\mathbf{f}(\sigma))} w)}{\sum_{J \in PW} exp(\sum_{w: F \in \mathbb{L}_I \cup \mathbf{Choice}(\mathbf{A}\mathbf{f}(\sigma))} w)}. \end{split}$$

Clearly $\mathbf{Choice}(\mathbf{At}(\sigma))$ is a set of tautologies, and it can be seen from the construction of $\Pi_{\mathbb{L}}$ that $(\Pi_{\mathbb{L}})_K = \mathbb{L}_K \cup \mathbf{Choice}(\mathbf{At}(\sigma))$ for any interpretation K. So

$$P_{\mathbb{L}}(I) = \lim_{\alpha \to \infty} \frac{exp(\sum_{w:F \in (\Pi_{\mathbb{L}})_I} w)}{\sum_{J \in PW} exp(\sum_{w:F \in (\Pi_{\mathbb{L}})_J} w)}.$$

By Theorem 2 in (?), for any interpretation K, the stable models of $\overline{(\Pi_{\mathbb{L}})_K}$ are exactly the models of $\overline{\mathbb{L}_K}$. Since K itself is a model of $\overline{\mathbb{L}_K}$, K is a stable model of $\overline{(\Pi_{\mathbb{L}})_K}$. So

$$P_{\mathbb{L}}(I) = \lim_{\alpha \to \infty} \frac{W_{\Pi_{\mathbb{L}}}(I)}{\sum_{J \in SM[\Pi]} W_{\Pi_{\mathbb{L}}}(J)}$$
$$= P_{\Pi_{\mathbb{L}}}(I).$$

We prove a more general version of Theorem 3 here, which is Theorem 4 in (Lee and Wang 2015). For a (deterministic) logic program Π , we use LF_{Π} to denote the set $\{LF_{\Pi}(L) \mid L \text{ is a loop of } \Pi\}$.

Lemma 2 For any LP^{MLN} program Π and any interpretation I of the underlying signature σ , $I \vDash LF_{\overline{\Pi}}$ if and only if $I \vDash LF_{\overline{\Pi}_{\overline{I}}}$.

Proof. (\Rightarrow) Suppose $I \models LF_{\overline{\Pi}}$. Consider any subset K of σ . There are two possible cases:

- $I \nvDash K^{\wedge}$. In this case, $K^{\wedge} \to ES_{\overline{\Pi_I}}(K)$ is trivially satisfied by I.
- $I \vDash K^{\wedge}$. Since $I \vDash LF_{\overline{\Pi}}$, by Theorem 6, we have

$$K^{\wedge} \to \bigvee_{\substack{A \cap K \neq \emptyset \\ A \leftarrow B \wedge N \in \overline{\Pi} \\ B \cap K = \emptyset}} (B \wedge N \wedge \bigwedge_{b \in A \backslash K} \neg b)$$

is satisfied by I. Consider the rules which contribute to the external support for K in $\overline{\Pi}$, i.e., $A \leftarrow B \land N \in \overline{\Pi}$ such that $A \cap K \neq \emptyset$ and $B \cap K = \emptyset$. Since $A \cap K \neq \emptyset$ and $I \models K^{\land}$, we get $I \models A^{\lor}$. So all these rules are satisfied by I and thus they all belong to $\overline{\Pi}_I$, which means

$$\bigvee_{\substack{A\cap K\neq\emptyset\\A\leftarrow B\wedge N\in\overline{\Pi}\\B\cap K=\emptyset}}(B\wedge N\wedge \bigwedge_{b\in A\backslash K}\neg b)=\bigvee_{\substack{A\cap K\neq\emptyset\\A\leftarrow B\wedge N\in\overline{\Pi_I}\\B\cap K=\emptyset}}(B\wedge N\wedge \bigwedge_{b\in A\backslash K}\neg b).$$

So

$$K^{\wedge} \to \bigvee_{\substack{A \cap K \neq \emptyset \\ A \leftarrow B \wedge N \in \overline{\Pi_I} \\ B \cap K = \emptyset}} (B \wedge N \wedge \bigwedge_{b \in A \backslash K} \neg b)$$

i.e.,

$$K^{\wedge} \to ES_{\overline{\Pi_I}}(K)$$

is satisfied by I.

In conclusion, I satisfies $K^{\wedge} \to ES_{\overline{\Pi_I}}(K)$ for all subsets K of σ . By Theorem 6, $I \vDash LF_{\overline{\Pi_I}}$.

 (\Leftarrow) (The reasoning is similar to the proof of Proposition 1) Suppose I satisfies $LF_{\overline{\Pi_I}}$. For all subsets L of σ , since $I \models LF_{\overline{\Pi_I}}$, by Theorem 6, $I \models L^{\wedge} \to ES_{\overline{\Pi_I}}(L)$. Since $\Pi_I \subseteq \Pi$, it can be seen that the disjunctive terms in $ES_{\overline{\Pi_I}}(L)$ is a subset of the disjunctive terms in $ES_{\overline{\Pi_I}}(L)$, and thus $ES_{\overline{\Pi_I}}(L)$ entails $ES_{\overline{\Pi}}(L)$. So $I \models L^{\wedge} \to ES_{\overline{\Pi}}(L)$. So $I \models LF_{\overline{\Pi}}$.

Lemma 3 Let $\underline{\mathbb{L}}$ be an MLN, and let \mathbb{L}^{hard} be the hard formulas in \mathbb{L} . Let $\overline{\mathbb{L}^{hard}}$ be the set of formulas obtained from \mathbb{L}^{hard} by dropping all weights. When $\overline{\mathbb{L}^{hard}}$ is satisfiable,

• if I satisfies $\overline{\mathbb{L}^{hard}}$,

$$P_{\mathbb{L}}(I) = \frac{exp(\sum_{w: F \in \mathbb{L}_I \setminus \mathbb{L}^{hard}} w)}{\sum_{J \in PW: J \models \mathbb{L}^{hard}} exp(\sum_{w: F \in \mathbb{L}_J \setminus \mathbb{L}^{hard}} w)}$$

• otherwise, $P_{\mathbb{L}}(I) = 0.^3$

³This proposition does not hold when $\overline{\mathbb{L}^{hard}}$ is not satisfiable. For example, consider $\mathbb{L} = \{\alpha : p, \alpha : \leftarrow p\}$ and $I = \{p\}$. $I \nvDash \overline{\mathbb{L}^{hard}}$ but $P_{\mathbb{P}}(I) = \frac{exp(\alpha)}{exp(\alpha) + exp(\alpha)} = 0.5$.

Proof.

For any interpretation I, by definition, we have

$$\begin{split} P_{\mathbb{L}}(I) &= \lim_{\alpha \to \infty} \frac{W_{\mathbb{L}}(I)}{\sum_{J \in PW} W_{\mathbb{L}}(J)} \\ &= \lim_{\alpha \to \infty} \frac{W_{\mathbb{L}}(I)}{\sum_{J \in PW} exp(\sum_{w: F \in \mathbb{L}_I} w)}. \end{split}$$

• Suppose I satisfies $\overline{\mathbb{L}^{hard}}$. We have

$$P_{\mathbb{L}}(I) = \lim_{\alpha \to \infty} \frac{exp(\sum_{w: F \in \mathbb{L}_I} w)}{\sum_{J \in PW} exp(\sum_{w: F \in \mathbb{L}_J} w)}.$$

Splitting the denominator into two parts: those J that satisfies $\overline{\mathbb{L}^{hard}}$ and those that do not, and extracting the weight of formulas in \mathbb{L}^{hard} , we have

$$P_{\mathbb{L}}(I) = \lim_{\alpha \to \infty} \frac{\exp(|\mathbb{L}^{hard}| \cdot \alpha) \cdot \exp(\sum_{w: F \in \mathbb{L}_I \backslash \mathbb{L}^{hard}} w)}{\exp(|\mathbb{L}^{hard}| \cdot \alpha) \cdot \sum_{J \models \mathbb{L}^{hard}} \exp(\sum_{w: F \in \mathbb{L}_J \backslash \mathbb{L}^{hard}} w) + \sum_{J \nvDash \mathbb{L}^{hard}} \exp(|\mathbb{L}^{hard} \cap \mathbb{L}_J| \cdot \alpha) \cdot \exp(\sum_{w: F \in \mathbb{L}_J \backslash \mathbb{L}^{hard}} w)}$$

We divide both the numerator and the denominator by $exp(|\mathbb{L}^{hard}| \cdot \alpha)$.

$$\begin{split} P_{\mathbb{L}}(I) &= \lim_{\alpha \to \infty} \frac{exp(\sum_{w: F \in \mathbb{L}_I \backslash \mathbb{L}^{hard}} w)}{\sum_{J \vDash \overline{\mathbb{L}^{hard}}} exp(\sum_{w: F \in \mathbb{L}_J \backslash \mathbb{L}^{hard}} w) + \frac{\sum_{J \nvDash \overline{\mathbb{L}^{hard}}} exp(|\mathbb{L}^{hard} \cap \mathbb{L}_J| \cdot \alpha) \cdot exp(\sum_{w: F \in \mathbb{L}_J \backslash \mathbb{L}^{hard}} w)}{exp(|\mathbb{L}^{hard}| \cdot \alpha)}}{\\ &= \lim_{\alpha \to \infty} \frac{exp(\sum_{w: F \in \mathbb{L}_I \backslash \mathbb{L}^{hard}} w)}{\sum_{J \vDash \overline{\mathbb{L}^{hard}}} exp(\sum_{w: F \in \mathbb{L}_J \backslash \mathbb{L}^{hard}} w) + \sum_{J \nvDash \overline{\mathbb{L}^{hard}}} \frac{exp(|\mathbb{L}^{hard} \cap \mathbb{L}_J| \cdot \alpha)}{exp(|\mathbb{L}^{hard}| \cdot \alpha)} \cdot exp(\sum_{w: F \in \mathbb{L}_J \backslash \mathbb{L}^{hard}} w)}. \end{split}$$

For $J \nvDash \overline{\mathbb{L}^{hard}}$, we have $|\mathbb{L}^{hard} \cap \mathbb{L}_J| \leq |\mathbb{L}^{hard}| - 1$, so

$$P_{\mathbb{L}}(I) = \frac{exp(\sum_{w:F \in \mathbb{L}_I \setminus \mathbb{L}^{hard}} w)}{\sum_{J \models \overline{\mathbb{L}^{hard}}} exp(\sum_{w:F \in \mathbb{L}_I \setminus \mathbb{L}^{hard}} w)}.$$

• Suppose I does not satisfy $\overline{\mathbb{L}^{hard}}$. Since $\overline{\mathbb{L}^{hard}}$ is satisfiable, there is at least one interpretation that satisfies $\overline{\mathbb{L}^{hard}}$. Let K denote any such interpretation. We have

$$P_{\mathbb{L}}(I) = \lim_{\alpha \to \infty} \frac{exp(\sum_{w: F \in \mathbb{L}_I} w)}{\sum_{J \in PW} exp(\sum_{w: F \in \mathbb{L}_I} w)}.$$

Splitting the denominator into K and the other interpretations, we have

$$P_{\mathbb{L}}(I) = \lim_{\alpha \to \infty} \frac{exp(\sum_{w:F \in \mathbb{L}_I} w)}{exp(\sum_{w:F \in \mathbb{L}_I} w) + \sum_{J \neq K} exp(\sum_{w:F \in \mathbb{L}_I} w)}.$$

Extracting the weight from formulas in \mathbb{L}^{hard} , we have

$$P_{\mathbb{L}}(I) = \lim_{\alpha \to \infty} \frac{exp(|\mathbb{L}^{hard} \cap \mathbb{L}_{I}| \cdot \alpha) \cdot exp(\sum_{w:F \in \mathbb{L}_{I} \setminus \mathbb{L}^{hard}} w)}{exp(|\mathbb{L}^{hard}| \cdot \alpha) \cdot exp(\sum_{w:F \in \mathbb{L}_{K} \setminus \mathbb{L}^{hard}} w) + \sum_{J \neq K} exp(\sum_{w:F \in \mathbb{L}_{J}} w)}$$

$$\leq \lim_{\alpha \to \infty} \frac{exp(|\mathbb{L}^{hard} \cap \mathbb{L}_{I}| \cdot \alpha) \cdot exp(\sum_{w:F \in \mathbb{L}_{I} \setminus \mathbb{L}^{hard}} w)}{exp(|\mathbb{L}^{hard}| \cdot \alpha) \cdot exp(\sum_{w:F \in \mathbb{L}_{K} \setminus \mathbb{L}^{hard}} w)}.$$

Since I does not satisfy $\overline{\mathbb{L}^{hard}}$, $|\mathbb{L}^{hard} \cap \mathbb{L}_I| \leq |\mathbb{L}^{hard}| - 1$, and thus

$$P_{\mathbb{L}}(I) \leq \lim_{\alpha \to \infty} \frac{exp(|\mathbb{L}^{hard} \cap \mathbb{L}_I| \cdot \alpha) \cdot exp(\sum_{w: F \in \mathbb{L}_I \setminus \mathbb{L}^{hard}} w)}{exp(|\mathbb{L}^{hard}| \cdot \alpha) \cdot exp(\sum_{w: F \in \mathbb{L}_K \setminus \mathbb{L}^{hard}} w)} = 0.$$

For any LP^{MLN} program Π , define MLN program \mathbb{L}_{Π} to be the union of Π and $\{\alpha: LF_{\overline{\Pi}}(L) \mid L \text{ is a loop of } \overline{\Pi}\}$.

Lemma 4 For any LP^{MLN} program Π and any interpretation I, if $I \in SM'[\Pi]$, then $I \models LF_{\overline{\Pi}}$.

Proof. Suppose $I \in SM'[\Pi]$, then $I \models_{\text{SM}} \overline{\Pi^{hard}} \cup \overline{(\Pi^{soft})_I}$, which implies $I \models_{\text{SM}} \overline{\Pi_I}$, and further implies $I \models LF_{\overline{\Pi}_I}$. By Lemma 2, $I \models LF_{\overline{\Pi}}$.

Theorem 4 For any LP^{MLN} program Π such that $SM'[\Pi]$ is not empty, Π and \mathbb{L}_{Π} have the same probability distribution over all interpretations, and consequently, the stable models of Π and the models of \mathbb{L}_{Π} coincide.

Proof. We will show that $P_{\Pi}(I) = P_{L_{\Pi}}(I)$ for all interpretations I. Since $SM'[\Pi]$ is not empty, by Lemma 4, there exists at least one interpretation J such that $J \models LF_{\overline{\Pi}}$.

• Suppose I is a stable model of $\overline{\Pi_I}$. By definition,

$$P_{\mathbb{L}_{\Pi}}(I) = \lim_{\alpha \to \infty} \frac{exp(\sum_{r_i \in \overline{(\mathbb{L}_{\Pi})_I}} w_i)}{\sum_{J \in PW} exp(\sum_{r_i \in \overline{(\mathbb{L}_{\Pi})_I}} w_i)}.$$

Splitting the denominator into interpretations that satisfy $LF_{\overline{\Pi}}$ and those that do not, we get

$$P_{\mathbb{L}_{\Pi}}(I) = \lim_{\alpha \to \infty} \frac{exp(\sum_{r_i \in (\overline{\mathbb{L}_{\Pi}})_I} w_i)}{\sum_{J \vDash LF_{\overline{\Pi}}} exp(\sum_{r_i \in (\overline{\mathbb{L}_{\Pi}})_J} w_i) + \sum_{J \nvDash LF_{\overline{\Pi}}} exp(\sum_{r_i \in (\overline{\mathbb{L}_{\Pi}})_J} w_i)}.$$

Extracting the weights from the formulas in $LF_{\overline{\Pi}},$ we get

$$P_{\mathbb{L}_{\overline{\Pi}}}(I) = \lim_{\alpha \to \infty} \frac{exp(|LF_{\overline{\Pi}}| \cdot \alpha) \cdot exp(\sum_{r_i \in \overline{(\mathbb{L}_{\overline{\Pi}})_I} \backslash LF_{\overline{\overline{\Pi}}}} w_i)}{\sum_{J \models LF_{\overline{\overline{\Pi}}}} exp(|LF_{\overline{\Pi}}| \cdot \alpha) \cdot exp(\sum_{r_i \in \overline{(\mathbb{L}_{\overline{\Pi}})_J} \backslash LF_{\overline{\overline{\Pi}}}} w_i) + \sum_{J \nvDash LF_{\overline{\overline{\Pi}}}} exp(|\overline{(\mathbb{L}_{\overline{\Pi}})_J} \cap LF_{\overline{\overline{\Pi}}}| \cdot \alpha) \cdot exp(\sum_{r_i \in \overline{(\mathbb{L}_{\overline{\Pi}})_J} \backslash LF_{\overline{\overline{\Pi}}}} w_i)}$$

Dividing both the numerator and the denominator by $exp(|LF_{\Pi}| \cdot \alpha)$, we have

$$P_{\mathbb{L}_{\overline{\Pi}}}(I) = \lim_{\alpha \to \infty} \frac{exp(\sum_{r_i \in \overline{(\mathbb{L}_{\overline{\Pi}})_I} \backslash LF_{\overline{\Pi}}} w_i)}{\sum_{J \models LF_{\overline{\Pi}}} exp(\sum_{r_i \in \overline{(\mathbb{L}_{\overline{\Pi}})_J} \backslash LF_{\overline{\Pi}}} w_i) + \sum_{J \not\models LF_{\overline{\Pi}}} \frac{exp(|\overline{(\mathbb{L}_{\overline{\Pi}})_J} \cap LF_{\overline{\Pi}}| \cdot \alpha)}{exp(|\overline{LF_{\overline{\Pi}}}| \cdot \alpha)} \cdot exp(\sum_{r_i \in \overline{(\mathbb{L}_{\overline{\Pi}})_J} \backslash LF_{\overline{\Pi}}} w_i)}.$$

For those J that do not satisfy $LF_{\overline{\Pi}}$, $|\overline{(\mathbb{L}_{\Pi})_J} \cap LF_{\overline{\Pi}}| \leq |LF_{\overline{\Pi}}| - 1$. So $\lim_{\alpha \to \infty} \frac{exp(|\overline{(\mathbb{L}_{\Pi})_J} \cap LF_{\overline{\Pi}}| \cdot \alpha)}{exp(|LF_{\overline{\Pi}}| \cdot \alpha)} = 0$. Consequently

$$P_{\mathbb{L}_\Pi}(I) = \frac{\exp(\sum_{r_i \in \overline{(\mathbb{L}_\Pi)_I} \backslash LF_{\overline{\Pi}}} w_i)}{\sum_{J \vDash LF_{\overline{\Pi}}} \exp(\sum_{r_i \in \overline{(\mathbb{L}_{Pi})_J} \backslash LF_{\overline{\Pi}}} w_i)}.$$

From the construction of \mathbb{L}_{Π} it can be easily seen that $\overline{(\mathbb{L}_{\Pi})_K} \setminus LF_{\overline{\Pi}} = \overline{\Pi_K}$ for all interpretations K. So

$$P_{\mathbb{L}_{\Pi}}(I) = \frac{exp(\sum_{r_i \in \overline{\Pi_I}} w_i)}{\sum_{J \models LF_{\overline{\Pi}}} exp(\sum_{r_i \in \overline{\Pi_J}} w_i)}.$$

By Lemma 2, for any $J \models LF_{\overline{\Pi}}$, we have $J \models LF_{\overline{\Pi}}$ and thus J is a stable model of $\overline{\Pi}_J$. So

$$P_{\mathbb{L}_{\Pi}}(I) = \frac{exp(\sum_{r_i \in \overline{\Pi}_I} w_i)}{\sum_{J \models_{SM} \overline{\Pi}_J} exp(\sum_{r_i \in \overline{\Pi}_J} w_i)}$$
$$= \frac{W_{\Pi}(I)}{\sum_{J \in SM[\Pi]} W_{\Pi}(J)}$$
$$= P_{\Pi}(I).$$

• Suppose I is not a stable model of $\overline{\Pi_I}$. Then $P_\Pi(I)=0$. On the other hand, since $I \vDash \overline{\Pi_I}$ by definition, it must be the case that $I \nvDash LF_{\overline{\Pi_I}}$. By Lemma 2, $I \nvDash LF_{\overline{\Pi}}$. So there is at least one subset L of σ such that $I \nvDash LF_{\overline{\Pi}}(L)$. Clearly $\alpha: LF_{\overline{\Pi}}(L) \in \mathbb{L}_\Pi$ and $LF_{\overline{\Pi}}(L) \in \overline{(\mathbb{L}_\Pi)^{hard}}$. So $I \nvDash \overline{(\mathbb{L}_\Pi)^{hard}}$. From the construction of \mathbb{L}_Π we can see that $\overline{(\mathbb{L}_\Pi)^{hard}} = \overline{\Pi^{hard}} \cup LF_{\overline{\Pi}}$. Since $SM'[\Pi]$ is not empty, there is at least one interpretation J such that $J \models_{\mathrm{SM}} \overline{\Pi^{hard}} \cup \overline{(\Pi^{soft})_J}$. This interpretation J satisfies $LF_{\overline{\Pi}hard} \cup \overline{\Pi^{hard}} \cup LF_{\overline{\Pi}}$ and thus $\mathbb{L}_\Pi \cap \mathbb{L}_\Pi \cap \mathbb{L}_\Pi$

The above theorem is a more general version of Theorem 3 because, for any tight program Π , $Comp(\Pi)$ coincide with \mathbb{L}_{Π} . This result can be found in (?).

16 Proof of Theorem 4

In this section and the next section, we write $\sum_x f(x)$, where f is some function over a Boolean variable, as a shorthand of $\sum_{x \in \{true, false\}} f(x)$, and write $\sum_{x_1, \dots, x_m} f(x_1, \dots, x_m)$ as a shorthand of $\sum_{x_1} \sum_{x_2} \dots \sum_{x_m} f(x_1, \dots, x_m)$. Given a ProbLog program \mathbb{P} , let $PA_{\mathbb{P}}$ denote the set of all probabilistic atoms in \mathbb{P} . We say a subset TC of $PA_{\mathbb{P}}$ is the total choice of an interpretation I if for all $p \in TC$, $I \vDash p$ and for all $q \in PA_{\mathbb{P}} \setminus TC$, $I \nvDash q$.

Lemma 5 For any ProbLog program \mathbb{P} ,

$$\sum_{TC \subseteq PA_{\mathbb{P}}} Pr_{\mathbb{P}}(TC) = 1.$$

Suppose $PA_{\mathbb{P}} = \{a_1, a_2, \dots, a_k\}.$

$$\sum_{TC \subseteq PA_{\mathbb{P}}} Pr_{\mathbb{P}}(TC)$$

$$= \sum_{TC \subseteq PA_{\mathbb{P}}} (\prod_{a_i \in TC} p_i \cdot \prod_{a_j \in PA_{\mathbb{P}} \setminus TC} (1 - p_j)).$$

Let $\mathbf{p_i}(x)$ where $x \in \{true, false\}$ be defined as

$$\mathbf{p_i}(x) = \begin{cases} p_i & if \ x = true \\ 1 - p_i & if \ x = false \end{cases}.$$

Clearly $\sum_a \mathbf{p_i}(a) = 1$ for any $i \in \{1, \dots, k\}$. $\sum_{TC \subseteq PA_{\mathbb{P}}} Pr_{\mathbb{P}}(TC)$ can be rewritten as

$$\sum_{TC \subseteq PA_{\mathbb{P}}} Pr_{\mathbb{P}}(TC)$$

$$= \sum_{\mathbf{a}_{1}, \mathbf{a}_{2}, \dots, \mathbf{a}_{k}} \mathbf{p}_{\mathbf{i}}(\mathbf{a}_{i}) \cdot \dots \cdot \mathbf{p}_{\mathbf{i}}(\mathbf{a}_{i})$$

where $\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_k$ are Boolean variables representing whether or not $a_i \in TC$, i.e., $\mathbf{a}_i = true$ if $a_i \in TC$, $\mathbf{a}_i = false$ otherwise. Rearranging the equation we have

$$\begin{split} &\sum_{C \subseteq PA_{\mathbb{P}}} Pr_{\mathbb{P}} \left[C \right] \\ &= \sum_{\mathbf{a}_1} \mathbf{p_1}(\mathbf{a}_1) \sum_{\mathbf{a}_2} \mathbf{p_2}(\mathbf{a}_2) \cdot \sum_{\mathbf{a}_k} \mathbf{p_k}(\mathbf{a}_k) \\ &= 1. \end{split}$$

Theorem 7 When Π has a total well-founded model, then this model is also the single stable model of Π .

Lemma 6 Let \mathbb{P} be any ProbLog program that does not contain any probabilistic atom for which the probability is 0 or 1. \mathbb{P} and its LP^{MLN} representation \mathbb{P}' have the same probability distribution over all interpretations.

Proof. Since \mathbb{P} is a well-defined ProbLog program, for all $TC \subseteq PA_{\mathbb{P}}$, $TC \cup \Pi$ has one total well-founded model. Let TC(I) denote the total choice of I.

• Suppose I is the total well-founded model of $TC(I) \cup \Pi$. According to the definition,

$$\begin{split} P_{\mathbb{P}}(I) &= Pr_{\mathbb{P}}(TC(I)) \\ &= \prod_{a_i \in TC(I)} p_i \cdot \prod_{b_j \in PA_{\mathbb{P}} \setminus TC(I)} (1 - p_j). \end{split}$$

By Theorem 7, I is also the unique stable model of $TC(I) \cup \Pi$. It can be seen that I is the only stable model of $TC(I) \cup \Pi$ $\{\leftarrow p\mid p\notin TC(I)\}$, which is $\overline{\mathbb{P}'_I}$. Clearly $\overline{(\mathbb{P}')^{hard}}=\Pi\subseteq\overline{\mathbb{P}'_I}$ and consequently $I\models_{\mathrm{SM}}\overline{(\mathbb{P}')^{hard}}\cup\overline{(\mathbb{P}')^{soft}_I}$. By Proposition 2,

$$\begin{split} P_{\mathbb{P}'}(I) &= \frac{\exp(\sum_{F_i \in \overline{\mathbb{P}_I'} \backslash \overline{(\mathbb{P}')^{hard}}} w_i)}{\sum_{J \in SM'[\mathbb{P}']} \exp(\sum_{F_i \in \overline{\mathbb{P}_J'} \backslash \overline{(\mathbb{P}')^{hard}}} w_i)} \\ &= \frac{\exp(\sum_{a_i \in PA_{\mathbb{P}:I \vDash a_i}} \ln(p_i) + \sum_{a_i \in PA_{\mathbb{P}:I \nvDash a_i}} \ln(1-p_i))}{\sum_{J \in SM'[\mathbb{P}']} \exp(\sum_{a_i \in PA_{\mathbb{P}:J \vDash a_i}} \ln(p_i) + \sum_{a_i \in PA_{\mathbb{P}:J \nvDash a_i}} \ln(1-p_i))} \\ &= \frac{\prod_{a_i \in TC(I)} p_i \prod_{a_i \notin TC(I)} (1-p_i)}{\sum_{J \in SM'[\mathbb{P}']} \prod_{a_i \in TC(J)} p_i \prod_{a_i \notin TC(J)} (1-p_i)}. \end{split}$$

Clearly for every J such that $J \in SM'[\mathbb{P}']$, there is a total choice TC(J). And since the ProbLog program \mathbb{P} is well-defined, for every total choice C there is a total well-founded model of $C \cup \Pi$. By Theorem 7, this means for every total choice C there is a unique stable model of $C \cup \Pi$. It can be seen that this stable model is also the unique stable model of $C \cup \Pi \cup \{\neg p \mid p \notin TC(I)\}$. So

$$\begin{split} P_{\mathbb{P}'}(I) &= \frac{\prod_{a_i \in TC(I)} p_i \prod_{a_i \notin TC(I)} (1-p_i)}{\sum_{TC' \subseteq PA_{\mathbb{P}}} \prod_{a_i \in C} p_i \prod_{a_i \notin C} (1-p_i)} \\ &= \frac{\prod_{a_i \in TC(I)} p_i \prod_{a_i \notin TC(I)} (1-p_i)}{\sum_{TC' \subseteq PA_{\mathbb{P}}} Pr_{\mathbb{P}}(TC')}. \end{split}$$

By Lemma 5, the denominator equals 1, so

$$P_{\mathbb{P}'}(I) = \prod_{a_i \in TC(I)} p_i \prod_{a_i \notin TC(I)} (1 - p_i)$$
$$= P_{\mathbb{P}}(I).$$

- Suppose I is not the total well-founded model of $TC(I) \cup \Pi$. Then $P_{\mathbb{P}}(I) = 0$. Since \mathbb{P} is well-defined. The total well-founded model J of $TC(I) \cup \Pi$ exists and by Theorem 7, J is also the unique stable model of $TC(I) \cup \Pi$. It must be the case that $I \neq J$ and thus I cannot be a stable model of $TC(I) \cup \Pi$. There are following two cases:
 - Suppose $I \nvDash TC(I) \cup \Pi$. Since TC(I) is the total choice of $I, I \vDash TC(I)$. It follows that $I \nvDash \Pi$, i.e., there is at least one rule $F \in \Pi$ such that $I \nvDash F$. According to the definition, $\alpha : F \in (\mathbb{P}')^{hard}$. By Proposition 2, $P_{\mathbb{P}'}(I) = 0$.
 - Suppose $I \models TC(I) \cup \Pi$ but I is not a stable model of $TC(I) \cup \Pi$. By Theorem 6, it follows that there must be at least one loop L of $\overline{\Pi}$ such that $I^\models L^\land$ but $I \nvDash ES_{TC(I) \cup \Pi}(L)$. It can be seen that

$$\mathbb{P}_I' = TC(I) \cup \Pi \cup \{\leftarrow p \mid p \notin TC(I)\}.$$

It can be seen that $ES_{\mathbb{P}_I'}(L) = ES_{TC(I) \cup \Pi}(L)$. It follows that $I \nvDash_{SM} \overline{\mathbb{P}_I'}$. So $W_{\mathbb{P}'}(I) = 0$ and thus $P_{\mathbb{P}'}(I) = 0$.

Theorem 4 Any well-defined ProbLog program \mathbb{P} and its LP^{MLN} representation \mathbb{P}' have the same probability distribution over all interpretations.

Proof. We first convert $\mathbb{P} = \langle PF, \Pi \rangle$ into a ProbLog program that does not contain any probabilistic atom for which the probability is 0 or 1 as follows.

- For each probabilistic atom p such that pr(p) = 0:
 - Remove all the rules in Π where p occurs in the body positively (i.e., as the literal p);
 - Remove all the literals not p that occurs in Π .
- For each probabilistic atom q such that pr(q) = 1:
 - Remove all the literals p that occurs in Π ;
 - Remove all the rules in Π where p occurs in the body negatively (i.e., as the literal not p).

Let \mathbb{P}' denote the program obtained from \mathbb{P} as above. Clearly \mathbb{P}' specifies the same probability distribution as \mathbb{P} , if we restrict attention to atoms other than those atoms for which the probability is 0 or 1. By Lemma 6, \mathbb{P}' and its LP^{MLN} representation $\overline{\mathbb{P}'}$ have the same probability distribution over all interpretations. From the construction of \mathbb{P}' , it can be seen that \mathbb{P}' specifies the same probability distribution as $\overline{\mathbb{P}'}$ if we restrict attention to atoms other than those atoms for which the probability is 0 or 1. Also it is clearly that those atoms in \mathbb{P} for which the probability is 0 or 1 have exactly the same constant truth values ass these atoms in \mathbb{P}' . So \mathbb{P} and its LP^{MLN} representation \mathbb{P}' have the same probability distribution over all interpretations.

17 Proof of Theorem 4

Given a multi-valued probabilistic LP^{MLN} program $\Pi = \langle PF, \Pi \rangle$, we use $\sigma^{pf}(\Pi)$ to denote the set of all probabilistic constants in Π . It can be seen that, if we have $M_{\Pi}(c=v)>0$ for all constants c and $v\in Dom(c)$, then given a consistent interpretation I, we have $\Pi^{hard}=UEC\cup\Pi\cup SINGLE$, where

$$\left\{ \bot \leftarrow \neg \bigvee_{v \in Dom(c)} c = v \mid c \in \sigma^{pf}(\mathbf{\Pi}) \right\},\,$$

and

$$SINGLE = \{c = v \mid M_{\Pi}(c = v) = 1\},$$

and
$$(\mathbf{\Pi}^{\text{soft}})_I = TC(I) \setminus SINGLE$$
.

Lemma 7 For any multi-valued probabilistic program $\Pi = \langle PF, \Pi \rangle$, for which $SM''[\Pi]$ is not empty and $M_{\Pi}(c = v) > 0$ for all constants c and $v \in Dom(c)$, and any interpretation I, I belongs to $SM'[\Pi]$ if and only if I belongs to $SM''[\Pi]$.

$$\overline{T(\mathbf{\Pi})^{\text{hard}}} \cup \overline{(T(\mathbf{\Pi})^{\text{soft}})_I}$$
$$= \Pi \cup UEC \cup SINGLE \cup (TC(I) \setminus SINGLE).$$

(⇒) Suppose I belongs to SM' $[T(\Pi)]$. By definition, I satisfies $\overline{T(\Pi)^{hard}}$, which contains UEC. Obviously since I satisfies UEC, I is consistent. For those $c=v\in SINGLE$, it must be the case that $Dom(c)=\{v\}$. In this case, we have $c=v\in I$ since I is consistent. So $SINGLE\subseteq TC(I)$ and thus $SINGLE\cup (TC(I)\setminus SINGLE)=TC(I)$. So we have

$$\overline{T(\mathbf{\Pi})^{\text{hard}}} \cup \overline{(T(\mathbf{\Pi})^{\text{soft}})_I}$$
$$= \Pi \cup UEC \cup TC(I).$$

and since I is a stable model of $\overline{T(\Pi)}^{\text{hard}} \cup \overline{(T(\Pi)^{\text{soft}})_I}$, I is a stable model of $\Pi \cup UEC \cup TC(I)$. It follows that I is a stable model of $\Pi \cup TC(I)$ since UEC contains constraints only. Since in addition we have I is consistent, I belongs to $SM''[\Pi]$.

(\Leftarrow) Suppose I belongs to SM'' [Π]. By definition, I is consistent, and I is a stable model of $\Pi \cup TC(I)$. Clearly I satisfies UEC since I is consistent. Since UEC contains constraints only, I is a stable model $\Pi \cup TC(I) \cup UEC$. For those $c = v \in SINGLE$, it must be the case that $Dom(c) = \{v\}$. In this case, we have $c = v \in I$ since I is consistent. So $SINGLE \subseteq TC(I)$ and thus $SINGLE \cup (TC(I) \setminus SINGLE) = TC(I)$. So we have

$$\begin{split} &\Pi \cup UEC \cup TC(I) \\ &= \Pi \cup UEC \cup SINGLE \cup (TC(I) \setminus SINGLE) \\ &= \overline{\Pi^{\text{hard}}} \cup \overline{(\Pi^{\text{soft}})_I} \end{split}$$

(11)

So I is a stable model of $\overline{T(\Pi)^{\text{hard}}} \cup \overline{(T(\Pi)^{\text{soft}})_I}$, and by definition I belongs to $SM'[T(\Pi)]$.

Lemma 8 For any multi-valued probabilistic program $\Pi = \langle PF, \Pi \rangle$, for which $SM''[\Pi]$ is not empty and $M_{\Pi}(c = v) > 0$ for all constants c and $v \in Dom(c)$, and any interpretation I, I is a stable model of $T(\Pi)$ if and only if $I \in SM''[\Pi]$.

Proof

By Lemma 7, I belongs to SM' $[T(\Pi)]$ if and only if I belong to SM'' $[\Pi]$. By Proposition 5, I is a stable model of $T(\Pi)$ if and only if $I \in SM'$ $[T(\Pi)]$. So I is a stable model of $T(\Pi)$ if and only if $I \in SM''$ $[\Pi]$.

Lemma 8 does not hold when $M_{\Pi}(c=v)=0$ for some constant c and $v\in Dom(c)$.

Example 7 Consider the following multi-valued probabilistic $\operatorname{LP}^{\operatorname{MLN}}\Pi$:

$$1: c = 1 \mid 0: c = 2$$

p

which translates into

$$\begin{array}{lll} \alpha & : & c = 1 \\ \alpha & : & \bot \leftarrow c = 2 \\ \alpha & : & p. \end{array}$$

The interpretation $I=\{c=2,p\}$ belongs to the set $SM''[\Pi]$. However, it is not a stable model of $T(\Pi)$, since one hard rule is violated.

Theorem 4 For any multi-valued probabilistic program Π such that each p_i in (3) is positive for every probabilistic constant c, if $SM''[\Pi]$ is not empty, then for any interpretation I, $P''_{\Pi}(I)$ coincides with $P_{T(\Pi)}(I)$.

Proof

• Suppose $I \in SM''[\Pi]$. By Lemma 7, we have $I \in SM'[\Pi]$. By Proposition 2, we have

$$\begin{split} P_{T(\Pi)}(I) &= P'_{T(\Pi)}(I) \\ &= \frac{W'_{T(\Pi)}(I)}{\sum_{J \in SM'[T(\Pi)]} W'_{T(\Pi)}(J)} \\ &= \frac{exp(\sum_{w:R \in T(\Pi)_I} w)}{\sum_{J \in SM'[T(\Pi)]} exp(\sum_{w:R \in T(\Pi)_J} w)} \\ &= \frac{\prod_{w:R \in T(\Pi)_I} exp(w)}{\sum_{J \in SM'[T(\Pi)]} \prod_{w:R \in T(\Pi)_J} exp(w)} \\ &= \frac{\prod_{c \in \sigma^{pf}(\Pi) \text{ and } c^I = v} M_{\Pi}(c = v)}{\sum_{J \in SM'[T(\Pi)]} \prod_{c \in \sigma^{pf}(\Pi) \text{ and } c^J = v} M_{\Pi}(c = v)} \\ &= P''_{\Pi}(I) \end{split}$$

• Suppose $I \notin SM''[\Pi]$. By Lemma 8, I is not a stable model of $T(\Pi)$, so $P_{T(\Pi)}(I) = 0$. On the other hand, $P''_{\Pi}(I) = 0$ since $W''_{\Pi}(I) = 0$.

18 Proof of Theorem 5

It can be easily seen from the definition of P(B, r, c = v) and the definition of P(W, c = v) that the following two lemmas hold:

Lemma 9 For any mini P-log program Π , any possible world W of Π , any constant c and any $v \in Dom(c)$ such that c = v is possible in W, we have

$$P(W, c = v) = P(B_{W,c}, r_{W,c}, c = v)$$

Lemma 10 For any mini P-log program Π , any possible world W of Π , any constant c and any $v \in Dom(c)$ such that c = v is possible in W, we have

$$PR_W(c) = PR_{B_{W,c},r_{W,c}}(c).$$

Furthermore, the following corollary can be derived:

Corollary 1 For any mini P-log program Π , any possible world W of Π , any constant c and any $v \in Dom(c)$ such that c = v is possible in W and $W \models c = v$, we have

• If $PR_W(c) \neq \emptyset$, then

$$P(W, c = v) = M_{\Pi^{LPMLN}} (p f_{B_{W,c},r_{W,c}}^c = v);$$

• If $PR_W(c) = \emptyset$, then

$$P(W, c = v) = M_{\Pi^{\text{LPMLN}}}(pf^{c}_{\square, r_{W, c}} = v).$$

For any interpretation I of Π , we define the set $SM_{\Pi}(I)$ of stable models of $\Pi^{\mathrm{LP^{MLN}}}$ as follows:

$$SM_{\Pi}(I) = \left\{ J \mid J \text{ is a (probabilistic) stable model of } \Pi^{\text{LPMLN}} \text{ such that } J \vDash F_I \right\}.$$

The proof of the next lemma uses a restricted version of the splitting theorem in (?), which is reformulated as follows:

Theorem 8 Let Π_1 , Π_2 be two finite ground programs where rules are of the form (1), and \mathbf{p} , \mathbf{q} be disjoint tuples of distinct atoms. If

- Each strongly connected component of the dependency graph of $\Pi_1 \cup \Pi_2$ w.r.t. $\mathbf{p} \cup \mathbf{q}$ is a subset of \mathbf{p} or a subset of \mathbf{q} .
- No atom in **p** has a strictly positive occurrence in Π_2 , and
- No atom in **q** has a strictly positive occurrence in Π_1 .

then an interpretation I of $\Pi_1 \cup \Pi_2$ is a stable model of $\Pi_1 \cup \Pi_2$ relative to $\mathbf{p} \cup \mathbf{q}$ if and only if I is a stable model of Π_1 relative to \mathbf{p} and I is a stable model of Π_2 relative to \mathbf{q} .

Lemma 11 Given a mini P-log program Π and a possible world I of Π , let $AIRRE_{\Pi}(I)$ denote the set of all assignments of the constants in the set

$$\mathit{IRRE}_{\Pi}(I) = \sigma^{pf}(\Pi^{\mathrm{LPMLN}}) \setminus \left\{ pf^{c}_{\square,r_{I,c}} \mid \begin{smallmatrix} c = v,I : \\ c = v \text{ is possible in } I, \\ I \vdash c = v \\ \mathit{and } \mathit{PR}_{I}(c) = \emptyset \end{smallmatrix} \right\} \setminus \left\{ pf^{c}_{B_{I,c},r_{I,c}} \mid \begin{smallmatrix} c = v,I : \\ c = v \text{ is possible in } I, \\ I \vdash c = v \\ \mathit{and } \mathit{PR}_{I}(c) \neq \emptyset \end{smallmatrix} \right\}.$$

There is a 1-1 correspondence between $SM_{\Pi}(I)$ and $AIRRE_{\Pi}(I)$.

Proof. We use σ to refer to the signature of $\tau(\Pi)$, and σ' to refer to the signature of $\Pi^{LP^{MLN}}$. We construct the 1-1 correspondence as follows.

Given an element J in $SM_{\Pi}(I)$, i.e., a stable model of $\Pi^{LP^{MLN}}$ which satisfies F_I , due to the UEC constraint for constants in $IRRE_{\Pi}(I)$, $SM_{\Pi}(I)$ must assign some value to all constants in $IRRE_{\Pi}(I)$ to be a stable model. We extract the assignment of atoms in $IRRE_{\Pi}(I)$ from J to obtain the corresponding element in $AIRRE_{\Pi}(I)$.

Given any arbitrary assignment of constants in $IRRE_{\Pi}(I)$, we extend this assignment by assigning the constants in $\sigma(\Pi^{LP^{MLN}}) \setminus IRRE_{\Pi}(I)$ in the following way, to obtain the corresponding element J in $SM_{\Pi}(I)$:

- For all $c = v \in I$, set $c^J = v$.
- For all constants of the form $pf_{\square,r_{I,c}}^c$, where $c \in \sigma$, $c^I = v$, c = v is possible in I and $PR_I(c) = \emptyset$, set $(pf_{\square,r_{I,c}}^c)^J = v$, and set $(Assigned_{r_{I,c}})^J$ to be undefined.
- For all constants of the form $pf_{B_{I,c},r_{I,c}}^c$, where $c \in \sigma$, $c^I = v$, c = v is possible in I and $PR_I(c) \neq \emptyset$, set $(pf_{B_{I,c},r_{I,c}}^c)^J = v$, and set $(Assigned_{r_{I,c}})^J = \mathbf{t}$.

The above construction of J guarantees that J satisfies $\overline{(\Pi^{\mathrm{LPMLN}})^{hard}}$ and F_I . Next we show that J is a stable model of Π^{LPMLN} : We split rules in $\overline{\Pi^{\mathrm{LPMLN}}_J}$ into two subsets $\overline{\Pi^{\mathrm{LPMLN}}_{J,1}}$ and $\overline{\Pi^{\mathrm{LPMLN}}_{J,2}}$ as follows:

⁴The formula F_I is defined in Theorem 5.

- $\overline{\Pi_{11}^{\mathrm{LPMLN}}}$ contains all rules in $\tau(\Pi)$, and rules of the following forms:
 - $1. \ \ c=v \leftarrow B, B', pf^c_{B',r}=v, not\ intervene(c), \ \text{where}\ c \ \text{is a constant of}\ \sigma, v \in Dom(c), B \ \text{is the body of some random selection rule}$ $r \ \text{of the form}\ [r]\ random(c) \leftarrow B, \ \text{and}\ B' \ \text{appears in some pr-atom of the form}\ pr(c=v\mid B')=p \ \text{where}\ p\in[0,1];$
 - 2. $c = v \leftarrow B, pf_{\Box,r}^c = v, not \ Assigned_r, not \ intervene(c), \text{ where } c \text{ is a constant of } \sigma, v \in Dom(c), \text{ and } B \text{ is the body of some } random \ selection \ rule \ r \ of \ the \ form \ [r] \ random(c) \leftarrow B;$
- $\overline{\Pi_{J,2}^{\text{LPMLN}}}$ is $\overline{\Pi_{J}^{\text{LPMLN}}} \setminus \overline{\Pi_{J,1}^{\text{LPMLN}}}$

It can be seen that no atom in σ has a strictly positive occurrence in $\overline{\Pi_{J,2}^{\mathrm{LPMLN}}}$, and no atom in $\sigma' \setminus \sigma$ (Atoms of the form "Assigned" and " $pf_{\neg,r}^c$ ") has a strictly positive occurrence in $\overline{\Pi_{J,1}^{\mathrm{LPMLN}}}$. Furthermore, the construction of Π^{LPMLN} guarantees that all loops of size greater than one involves atoms in σ only. So each strongly connected component of the dependency graph of Π_J^{LPMLN} w.r.t. σ' is a subset of σ or a subset of $\sigma' \setminus \sigma$. By Theorem 8, it suffices to show that J is a stable model of $\overline{\Pi_{J,1}^{\mathrm{LPMLN}}}$ relative to σ and J is a stable model of $\overline{\Pi_{J,2}^{\mathrm{LPMLN}}}$ relative to $\sigma' \setminus \sigma$.

- J is a stable model of $\overline{\Pi_{J,1}^{\mathrm{LP^{MLN}}}}$ relative to σ : Since I is a stable model of $\tau(\Pi)$ relative to σ , J is a stable model of $\tau(\Pi)$ relative to σ . It can be easily seen from the construction of J that $J \vDash \overline{\Pi_{J,1}^{\mathrm{LP^{MLN}}}}$. Since $\tau(\Pi)$ is a subset of $\overline{\Pi_{J,1}^{\mathrm{LP^{MLN}}}}$, by Proposition 1, J is a stable model of $\overline{\Pi_{J,1}^{\mathrm{LP^{MLN}}}}$ relative to σ .
- J is a stable model of $\overline{\Pi_{J,2}^{\mathrm{LPMLN}}}$ relative to $\sigma' \setminus \sigma$: It can be easily seen from the construction of J that $J \vDash \overline{\Pi_{J,2}^{\mathrm{LPMLN}}}$. Also as we discussed earlier, all loops of size greater than one do not involve atoms in $\sigma' \setminus \sigma$. So it suffices to show that the loop formula of each loop consisting of a single atom in $\sigma' \setminus \sigma$ is satisfied by J. $\sigma' \setminus \sigma$ contains two types of atoms: 1) atoms of the form $Assigned_r$, where r is some random selection rule, and 2) atoms of the form $pf_{\neg r}^c = v$, where c is a constant of σ , \neg is \square or B such that $pr(c = v' \mid B) = p$ is a pr-atom in Π , $v \in Dom(c)$, and r is a random selection rule of the form $[r] random(c) \leftarrow B'$.
 - Consider atoms of the form 1). These atoms appear and only appear at the head of rules of the form

$$Assigned_r \leftarrow B, B'not\ Intervene(c).$$

where c is the atom associated with the random selection rule r, B' is the body of the random selection rule r, and B occurs in some pr-atom $pr(c=v\mid B)=p$. The body of this rule involves atoms in σ only. The construction of J sets $Assigned_r$ to be true only when $PR_I(c) \neq \emptyset$, which implies $Assigned_r$ is true in J only when J satisfies not Intervene(c), B and B'. Note that B, not Intervene(c) does not contain $Assigned_r$. So clearly B, B'not Intervene(c) is a one disjunctive term in $ES_{\Pi LPMLN}(\{Assigned_r\})$. So $Assigned_r \rightarrow ES_{\Pi LPMLN}(\{Assigned_r\})$ is satisfied.

- Consider atoms of the form 2). Each of these atoms appears and only appears as an atomic fact in $\overline{\Pi}_{J,2}^{\mathrm{LPMLN}}$. So the loop formulas for these atoms are of the form $pf_{...r}^c = v \to \top$. Clearly these formulas are satisfied by J.

So J must be a stable model of $\overline{\Pi_{J,2}^{\mathrm{LPMLN}}}$ relative to $\sigma' \setminus \sigma$.

Lemma 12 For any mini P-log program Π and any possible world I of Π , we have

$$\hat{\mu}_{\Pi}(I) = \sum_{J: J \in SM_{\Pi}(I)} W_{\Pi^{\text{LPMLN}}}''(J).$$

Proof.

$$\begin{split} \hat{\mu}_{\Pi}(I) &= \prod_{\substack{c = v, \, I : \\ c = v \text{ is possible in } I \\ and \, I \vDash c = v}} P(I, c = v) \times \prod_{\substack{c = v, \, I : \\ I \vDash c = v \text{ is possible in } I, \\$$

Consider interpretations in the set $SM_{\Pi}(I)$. By Lemma 11, there is a 1-1 correspondence between those interpretations and assignments to constants in the set $\sigma^{pf}(\Pi^{\mathrm{LP^{MLN}}}) \setminus \left\{ pf_{\square,r_{I,c}}^c \mid {c=v \text{ is possible in }I, \atop I\models c=v \atop \text{and }PR_I(c)=\emptyset} \right\} \setminus \left\{ pf_{B_{I,c},r_{I,c}}^c \mid {c=v \text{ is possible in }I, \atop I\models c=v \atop \text{and }PR_I(c)=\emptyset} \right\}.$ Furthermore, for each of those interpretations J, W''(J) is precisely the product of the probability assigned to constants in $\sigma^{pf}(\Pi^{\mathrm{LPMLN}})$. Since the third term of the last equation above ranges over all assignments to constants in the set $\sigma^{pf}(\Pi^{\mathrm{LPMLN}}) \setminus \left\{ pf_{\square,r_{I,c}}^c \mid {c=v \text{ is possible in }I, \atop I\models c=v \atop \text{and }PR_I(c)=\emptyset} \right\} \setminus \left\{ pf_{B_{I,c},r_{I,c}}^c \mid {c=v \text{ is possible in }I, \atop I\models c=v \atop \text{and }PR_I(c)=\emptyset} \right\},$ we have

$$\begin{split} \hat{\mu}_{\Pi}(I) &= \prod_{\substack{c \ e \ v, I : \\ I \ | e \ e \ v \text{ is possible in } I, \\ I \ | e \ e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible in } I, \\ I \ | e \ | e \ v \text{ is possible } I, \\ I \ | e \ | e \ v \text{ is possible }$$

Lemma 13 Given a consistent mini P-log program Π of signature σ , for every stable model J of Π^{LPMLN} (whose signature is denoted by σ'), J's restriction on σ is a possible world of Π .

Proof. We construct J's restriction on σ by defining $c^I = c^J$ for all $c \in \sigma$.

- Clearly $J \in SM_{\Pi}(I)$.
- Now we show that I is a possible world of Π . Since Π is consistent, $\tau(\Pi)$ is satisfiable, and thus $J \vDash \tau(\Pi)$ (Otherwise J would not be a stable model of $\Pi^{\mathrm{LP}^{\mathrm{MLN}}}$ according to Proposition 2). Since $J \vDash \tau(\Pi)$, we get $I \vDash \tau(\Pi)$. To see that I is a stable model of $\Pi^{\mathrm{LP}^{\mathrm{MLN}}}$, we consider the loop formula $L^{\wedge} \to ES_{\tau(\Pi)}(L)$ for any loop of L of $\tau(\Pi)$ such that $I \vDash L^{\wedge}$. L is a loop of Π_J^{LPMLN} as well since $J \vDash \tau(\Pi)$, and it is satisfied by J since $I \subseteq J$. Since J is a stable model of Π_J^{LPMLN} , we have

$$J \vDash ES_{\overline{\Pi_{\tau}^{\mathrm{LPMLN}}}}(L),$$

i.e.,

$$J \vDash \bigvee_{\substack{A \cap L \neq \emptyset \\ A \leftarrow B \land N \in \Pi_L^{\mathrm{PPMLN}} \\ B \cap L = \emptyset}} (B \land N \land \bigwedge_{b \in A \setminus L} \neg b).$$

Consider the following two cases:

- L contains only atoms that are not possible in I. Since those atoms do not occur in the head of any rules in $\overline{\Pi^{\mathrm{LPMLN}}} \setminus \tau(\Pi)$, those rules do not contribute in $ES_{\overline{\Pi^{\mathrm{LPMLN}}_J}}(L)$. So $ES_{\overline{\Pi^{\mathrm{LPMLN}}_J}}(L) = ES_{\tau(\Pi)}(L)$ in this case. Since $\tau(\Pi)$ involves atoms in σ only, and I and J agree on atoms in σ , we have

$$I \vDash ES_{\tau(\Pi)}(L)$$
.

- L contains some atoms that are possible in I. In this case, since $J \models ES_{\overline{\Pi_J^{\mathrm{LPMLN}}}}(L)$, there must be at least one rule $A \leftarrow B \land N \in \overline{\Pi_J^{\mathrm{LPMLN}}}$ such that $A \cap L \neq \emptyset$, $B \cap L = \emptyset$ and $J \models B \land N \land \bigwedge_{b \in A \setminus L} \neg b$. There are again two possible cases:
- * $A \leftarrow B \land N \in \tau(\Pi)$. In this case, since $\tau(\Pi)$ involves atoms in σ only, and I and J agree on atoms in σ , we have $I \vDash B \land N \land \bigwedge_{b \in A \setminus L} \neg b$. Since this rule contributes to $ES_{\tau(\Pi)}(L)$ as well, we have $I \vDash ES_{\tau(\Pi)}(L)$.
- * $A \leftarrow B \land N \notin \tau(\Pi)$. According to the construction of $\Pi^{\mathrm{LP^{MLN}}}$, $A \leftarrow B \land N$ must be of one of the following two forms:

$$c = v \leftarrow B', pf_{\square,r}^c = v, not \ Assigned_r$$

or

$$c = v \leftarrow B'', B', pf_{B,r}^c = v, not \ Intervene(c)$$

where c = v is some atom possible in I, r is the random selection rule of the form

$$[r] random(c) \leftarrow B',$$

and B'' is the body of some pr-atom related to c and r. In either case, J satisfies B', which involves atoms in σ only. So I satisfies B' as well.

Consider the following rule in $\tau(\Pi)$:

$$c = v_1; \dots; c = v_n \leftarrow B', not Intervene(c).$$
 (12)

There are two possible cases:

· J does not satisfy Intervene(c). In this case, (12) is satisfied by J, and clearly

$$c = v_1; \dots; c = v_n \leftarrow B', not \ Intervene(c) \in \left\{ A \leftarrow B \land N \mid A \leftarrow B \land N \in \tau(\Pi) \atop B \cap L = \emptyset \right\}.$$

So one disjunctive term of $ES_{\tau(\Pi)}(L)$ is satisfied by I. So $ES_{\tau(\Pi)}(L)$ is satisfied by I.

· J satisfies Intervene(c). In this case, for J to be a stable model of $\Pi^{\mathrm{LP}^{\mathrm{MLN}}}$, there must be a rule of the following form

$$Intervene(c) \leftarrow Do(c = v)$$

in $\tau(\Pi)$, where $c = v \in J$ and $c = v \in I$, whose body is satisfied by J, which means the following rule

$$c = v \leftarrow Do(c = v)$$

in $\tau(\Pi)$ is satisfied by J. Clearly

$$c = v \leftarrow Do(c = v) \in \left\{ A \leftarrow B \land N \mid A \leftarrow B \land N \in \tau(\Pi) \atop B \cap L = \emptyset \atop B \cap L = \emptyset \right\}.$$

So one disjunctive term of $ES_{\tau(\Pi)}(L)$ is satisfied by I. So $ES_{\tau(\Pi)}(L)$ is satisfied by I.

So I satisfies $ES_{\tau(\Pi)}(L)$ for all loops L of $\tau(\Pi)$. Consequently, I is a stable model of $\tau(\Pi)$, and thus I is a possible world of Π . So I is a stable model of $\tau(\Pi)$, and thus a possible world of Π . **Theorem 5** For any consistent mini P-log program Π of signature σ and any possible world I of Π , we construct a formula F_I as follows.

$$F_{I} = (\bigwedge_{c=v \in I} c = v) \land (\bigwedge_{c=v \text{ is possible in } I, \atop c = v \text{ is possible in } I, \atop f \models c = v \text{ and } PR_{I}(c) \neq \emptyset \\ \land (\bigwedge_{c=v \text{ is possible in } I, \atop c = v \text{ is possible in } I, \atop f \models c = v \text{ and } PR_{I}(c) = \emptyset } pf_{\square,r_{I,c}}^{c} = v)$$

We have

$$\mu_{\Pi}(I) = P_{\Pi^{\mathrm{LPMLN}}}(F_I).$$

For any proposition A of signature σ ,

$$P_{\Pi}(A) = P_{\Pi^{\mathrm{LPMLN}}}(A).$$

Proof.

We first show

$$\sum_{I \text{ is a possible world of }\Pi} \hat{\mu}_{\Pi}(I) \qquad = \qquad \sum_{J \in SM^{\prime\prime}\left[\Pi^{\mathrm{LPMLN}}\right]} W^{\prime\prime}_{\Pi^{\mathrm{LPMLN}}}(J)$$

i.e., the normalization factor of $\hat{\mu}$ is the normalization factor of $W''_{\Pi^{\mathrm{LPMLN}}}$. By Lemma 12 we have,

$$\sum_{I \text{ is a possible world of }\Pi} \hat{\mu}_{\Pi}(I) = \sum_{I \text{ is a possible world of }\Pi} \sum_{J \in SM_{\Pi}(I)} W_{\Pi^{\text{LPMLN}}}''(J)$$
(13)

By Lemma 13, for every stable model J of $\Pi^{\mathrm{LP^{MLN}}}$, there exists a possible world I of Π such that $J \in SM_{\Pi}(I)$. So we can enumerate all stable models of $\Pi^{\mathrm{LP^{MLN}}}$ by enumerating all possible worlds I of Π and enumerating all elements in $SM_{\Pi}(I)$ for each I, and thus the right-hand side of (13) can be rewritten as

$$\sum_{J \text{ is a stable model of }\Pi^{\mathrm{LPMLN}}}W''_{\Pi^{\mathrm{LPMLN}}}(J).$$

By Lemma 8, an interpretation J is a stable model of $\Pi^{\mathrm{LP^{MLN}}}$ if and only if $J \in SM''\left[\Pi^{\mathrm{LP^{MLN}}}\right]$. So the right-hand side of (13) can be further rewritten as

$$\sum_{J \in SM^{\prime\prime}\left\lceil\Pi^{\mathrm{LPMLN}}\right\rceil} W^{\prime\prime}_{\Pi^{\mathrm{LPMLN}}}(J).$$

Thus we have

$$\begin{split} \mu_{\Pi}(I) &= \frac{\hat{\mu}_{\Pi}(I)}{\sum_{I \text{ is a possible world of }\Pi} \hat{\mu}(I)} \\ &= \frac{\hat{\mu}_{\Pi}(I)}{\sum_{J \in SM'' \left[\Pi^{\text{LPMLN}}\right]} W''_{\Pi^{\text{LPMLN}}}(J)} \\ (\textit{By Lemma 12}) &= \frac{\sum_{J \in SM_{\Pi}[I]} W''_{\Pi^{\text{LPMLN}}}(J)}{\sum_{J \in SM'' \left[\Pi^{\text{LPMLN}}\right]} W''_{\Pi^{\text{LPMLN}}}(J)} \\ &= \sum_{J \in SM_{\Pi}[I]} \frac{W''_{\Pi^{\text{LPMLN}}}(J)}{\sum_{J \in SM'' \left[\Pi^{\text{LPMLN}}\right]} W''_{\Pi^{\text{LPMLN}}}(J)} \\ &= \sum_{J \in SM_{\Pi}[I]} P''_{\Pi^{\text{LPMLN}}}(J) \end{split}$$

For those interpretations J that do not belong to $SM_{\Pi}[I]$ but satisfy F_I , it must be the case that J is not a stable model of $\Pi^{LP^{MLN}}$. By Lemma 8, $P''_{\Pi LP^{MLN}}(J) = 0$. So we have

$$\mu_{\Pi}(I) = \sum_{J \in SM_{\Pi}[I] \text{ and } J \models F_{I}} P''_{\Pi LPMLN}(J) + \sum_{J \notin SM_{\Pi}[I] \text{ and } J \models F_{I}} P''_{\Pi LPMLN}(J)$$

$$= \sum_{J \models F_{I}} P''_{\Pi LPMLN}(J)$$
(14)

and consequently by Theorem 4,

$$\mu_{\Pi}(I) = \sum_{J \models F_I} P_{\Pi^{LPMLN}}(J)$$

$$= P_{\Pi^{LPMLN}}(F_I). \tag{15}$$

According to the definition,

$$P_\Pi(F) = \sum_{W ext{ is a possible world of }\Pi ext{ that satisfies } F} \mu_\Pi(W).$$

Using the above result (15), we have

$$\begin{split} P_{\Pi}(F) &= \sum_{W \text{ is a possible world of }\Pi \text{ that satisfies } F} P_{\Pi^{\text{LPMLN}}}(F_W) \\ &= \sum_{W \text{ is a possible world of }\Pi \text{ that satisfies } F} \sum_{I \in SM_{\Pi}(W)} P_{\Pi^{\text{LPMLN}}}(I). \end{split}$$

The right-hand side of the last equation is the sum of the probabilities of a collection of stable models of $\Pi^{\mathrm{LP^{MLN}}}$. Clearly all those stable models of $\Pi^{\mathrm{LP^{MLN}}}$ satisfies F since they are all from some $SM_{\Pi}(I)$ for some possible world I of Π that satisfies F. Furthermore, given any stable model J of $\Pi^{\mathrm{LP^{MLN}}}$ that satisfies F, by lemma 13, there exists a possible world I of Π such that $J \in SM_{\Pi}(I)$. Since I and J agree on all atoms in $\sigma(\Pi)$ and $J \models F$, $I \models F$. So the probability of J is counted in the right-hand side of the above equation. Finally, obviously no two stable models of $\Pi^{\mathrm{LP^{MLN}}}$ are counted twice. Hence, the right-hand side can be rewritten as

$$P_{\Pi^{\mathrm{LPMLN}}}(F),$$

and thus we have

$$P_{\Pi}(F) = P_{\Pi^{\mathrm{LPMLN}}}(F).$$