

# Computer Aided Design

## CAD

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LECTURE 3

# Network Equilibrium Equations

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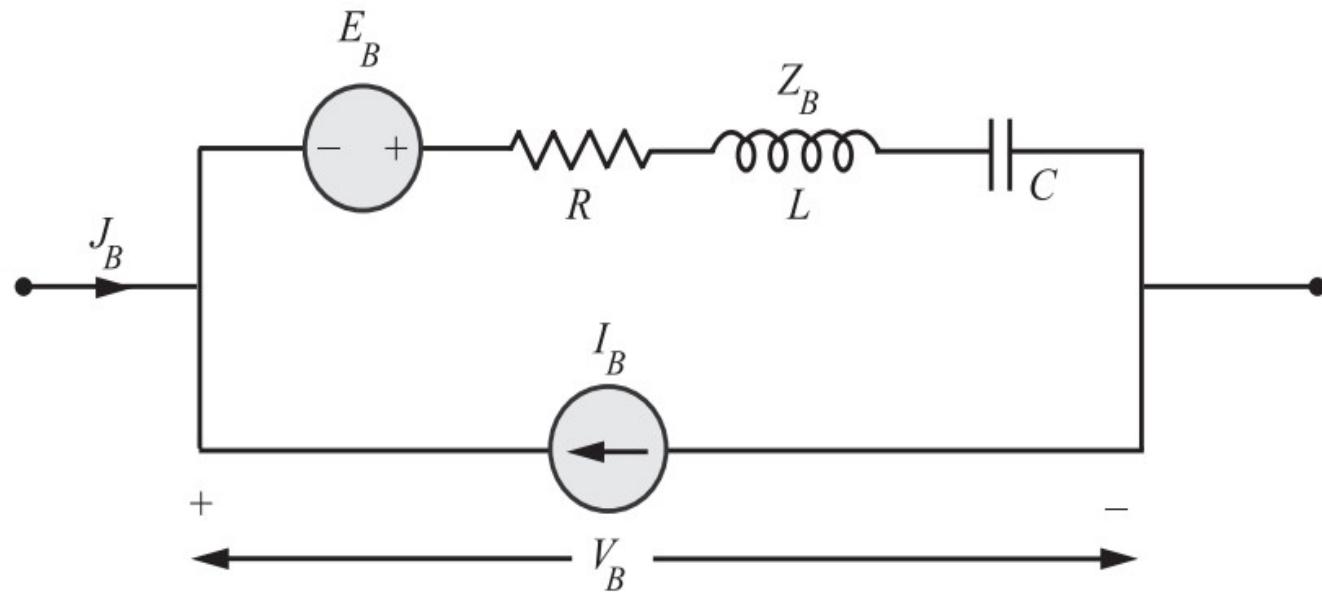
□ Loop equations: A branch of a network can, in general, be represented as shown in Fig

where  $E_B$  is the voltage source of the branch.

$I_B$  is the current source of the branch

$Z_B$  is the impedance of the branch

$J_B$  is the current in the branch



# Network Equilibrium Equations

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The voltage-current relation is then given by

$$\mathbf{V}_B = (\mathbf{J}_B + \mathbf{I}_B) Z_B - \mathbf{E}_B$$

For a general network with many branches, the matrix equation is

$$\mathbf{V}_B = \mathbf{Z}_B (\mathbf{J}_B + \mathbf{I}_B) - \mathbf{E}_B \quad \Rightarrow \quad \mathbf{V}_B = \mathbf{Z}_B (\mathbf{I}_B + \mathbf{I}_s) - \mathbf{V}_S \quad (1)$$

Where  $\mathbf{V}_B$ ,  $\mathbf{J}_B$ ,  $\mathbf{I}_B$ , and  $\mathbf{E}_B$  are  $B \times 1$  vectors and  $\mathbf{Z}_B$  is the branch impedance matrix of  $B \times B$

# Network Equilibrium Equations

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Each row of the tie-set matrix corresponds to a loop and involves all the branches of the loop. As per KV L, the sum of the corresponding branch voltages may be equated to zero. That is

$$\mathbf{BV}_B = \mathbf{0} \quad (2)$$

where  $\mathbf{B}$  is the tie-set matrix.

In the same matrix, each column represents a branch current in terms of loop currents. Transposed  $\mathbf{M}$  is used to give the relation between branch currents and loop currents.

$$\mathbf{J}_B = \mathbf{B}^T \mathbf{I}_L \quad (3)$$

This equation is called loop transformation equation.

# Network Equilibrium Equations

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Substituting equation (1) in (2),

$$\mathbf{V}_B = \mathbf{Z}_B (\mathbf{J}_B + \mathbf{I}_B) - \mathbf{E}_B \quad (1)$$

$$\mathbf{B}\mathbf{V}_B = 0 \quad (2)$$

we get

$$\mathbf{B}\mathbf{Z}_B \{ \mathbf{J}_B + \mathbf{I}_B \} - \mathbf{B}\mathbf{E}_B = 0 \quad (4)$$

$$\mathbf{J}_B = \mathbf{B}^T \mathbf{I}_L \quad (3)$$

Substituting equation (3) in (4)

we get

$$\mathbf{B}\mathbf{Z}_B \mathbf{B}^T \mathbf{I}_L + \mathbf{B}\mathbf{Z}_B \mathbf{I}_B - \mathbf{B}\mathbf{E}_B = 0$$

$$\mathbf{B}\mathbf{Z}_B \mathbf{B}^T \mathbf{I}_L = \mathbf{B}\mathbf{E}_B - \mathbf{B}\mathbf{Z}_B \mathbf{I}_B \Rightarrow \mathbf{B}\mathbf{Z}_B \mathbf{B}^T \mathbf{I}_L = \mathbf{B}\mathbf{V}_S - \mathbf{B}\mathbf{Z}_B \mathbf{I}_S$$

# Network Equilibrium Equations

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Get  $V_B$  branch voltage and  $J_B$  branch current using cut-set matrix

Each row of the cut-set matrix corresponds to a particular node pair voltage and indicates different branches connected to a particular node. KCL can be applied to the node and the algebraic sum of the branch currents at that node is zero.

$$CJ_B = 0 \quad (5)$$

Each column of cut-set matrix relates a branch voltage to node pair voltages. Hence,

$$V_B = C^T E_N \quad (6)$$

# Network Equilibrium Equations

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Current voltage relation for a branch is.

$$J_B = Y_B (V_B + E_B) - I_B$$

For a network with many branches the above equation may be written in matrix form as,

$$J_B = Y_B V_B + Y_B E_B - I_B \quad (7)$$

where  $Y_B$  is branch admittance matrix of  $B \times B$ .

# Network Equilibrium Equations

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Substituting equation (7) in (5)

$$CJ_B = 0 \quad (5)$$

$$J_B = Y_B V_B + Y_B E_B - I_B \quad (7)$$

We get

$$CY_B V_B + CY_B E_B - CI_B = 0 \quad (8)$$

Substituting equation (6) in (8)

$$V_B = C^T E_N \Rightarrow V_B = C^T V_T \quad (6)$$

We get

$$CY_B C^T E_N = C (I_B - Y_B E_B) \Rightarrow CY_B C^T V_T = C I_S - C Y_B V_S$$

# Example

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For the network shown in Figure write a tie-set matrix and then find all the branch currents and voltages.

