

Part III – Advanced Probability (Incomplete)

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1 Conditional Expectations

Lecture 2 Take a **probability space** $(\Omega, \mathcal{F}, \mathbb{P})$, meaning \mathcal{F} is a σ -algebra and \mathbb{P} is a probability measure, with $\mathbb{P}(\Omega) = 1$. We use the term ‘**almost surely**’ (or a.s.) to mean almost everywhere.

Take X to be a random variable, i.e. $X : \Omega \rightarrow \mathbb{R}$ which is \mathcal{F} -measurable and write

$$\mathbb{E}[X] = \int X \, d\mathbb{P}$$

for the **expectation** of X . We write also

$$\mathbb{E}[X \mathbb{1}_A] = \int_A X \, d\mathbb{P}$$

for $A \in \mathcal{F}$.

Definition 1.1. Let $B \in \mathcal{F}$ with $\mathbb{P}[B] > 0$. We know

$$\mathbb{P}[A|B] = \frac{\mathbb{P}[A \cap B]}{\mathbb{P}[B]},$$

the **conditional probability** of A given B . Similarly,

$$\mathbb{E}[X|B] = \frac{\mathbb{E}[X \mathbb{1}_B]}{\mathbb{P}[B]}$$

the **conditional expectation** of X given B .

There is a significant restriction to this definition: that $\mathbb{P}[B] > 0$. By the end of this lecture, we will generalise this definition to any σ -algebra of events, rather than just one.

Aim. Improve the prediction of X if additional information (given as a sub- σ -algebra $\mathcal{G} \subseteq \mathcal{F}$) is available.

1.1 Discrete case

Take $B_1, B_2, \dots \in \mathcal{F}$ a disjoint decomposition of Ω . We take

$$\mathcal{G} = \sigma(B_1, B_2, \dots) = \left\{ \bigcup_{i \in J} B_i : J \subseteq \mathbb{N} \right\} \subseteq \mathcal{F}.$$

That is, the ‘extra information’ of \mathcal{G} is that we know which of the disjoint events B_i we fall into.

Then,

$$\mathbb{E}[X|\mathcal{G}](\omega) := \sum_{i: \mathbb{P}[B_i] > 0} \mathbb{E}[X|B_i] \mathbb{1}_{B_i}(\omega)$$

is the conditional expectation of X given \mathcal{G} .

It is easy to see that $\mathbb{E}[X|\mathcal{G}]$ is a \mathcal{G} -measurable random variable, and

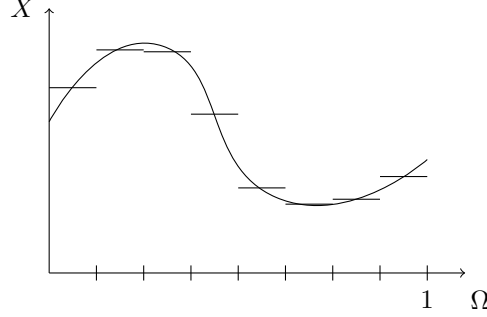
$$\mathbb{E}[\mathbb{1}_A X] = \mathbb{E}[\mathbb{1}_A \mathbb{E}[X|\mathcal{G}]] \quad \forall A \in \mathcal{G}.$$

Example.

- (i) Take now $\Omega = (0, 1]$, and $\mathcal{F} = \mathcal{B}(\Omega)$, and \mathbb{P} to be Lebesgue measure. Use X as shown below, and use

$$\mathcal{G} = \sigma\left(\left(\frac{k}{m}, \frac{k+1}{m}\right] : k = 0, \dots, m-1\right).$$

In the picture, we take $m = 8$, and the conditional expectation $\mathbb{E}(X|\mathcal{G})$ is shown.



- (ii) Take a random variable $Z : \Omega \rightarrow \{z_1, z_2, \dots\} \subseteq \mathbb{R}$, and use $\mathcal{G} = \sigma(Z) = \sigma(\{Z = z_i\} : i = 1, 2, \dots)$. Then,

$$\begin{aligned} \mathbb{E}[X|Z] &:= \mathbb{E}[X|\sigma(Z)] \\ &= \sum_{i: \mathbb{P}[Z=z_i]>0} \mathbb{E}[X|Z=z_i] \mathbb{1}_{\{Z=z_i\}}. \end{aligned}$$

This is not satisfactory quite yet: if Z has an absolutely continuous distribution (eg $\mathcal{N}(0, 1)$), i.e. $\mathbb{P}[Z = z] = 0$ for every z , then $\mathbb{E}[X|Z]$ is not defined yet!

1.2 General case

Definition 1.2. Let $X \in L^1(\Omega, \mathcal{F}, \mathbb{P})$, $\mathcal{G} \subseteq \mathcal{F}$ a σ -algebra. A random variable Y is called (a version of) the **conditional expectation** of X given \mathcal{G} if

- (i) Y is \mathcal{G} -measurable
- (ii) $\mathbb{E}[X \mathbb{1}_A] = \mathbb{E}[Y \mathbb{1}_A]$ for all $A \in \mathcal{G}$.

We notate $Y = \mathbb{E}[X|\mathcal{G}]$.

Remark 1.3.

- (a) We took $X \in L^1$, but this can be changed to $X \geq 0$ throughout.
- (b) If $\mathcal{G} = \sigma(\mathcal{C})$ for some $\mathcal{C} \subseteq \mathcal{F}$ which is a **π -system** (i.e. stable under intersections), it suffices to check (ii) for all $A \in \mathcal{C}$.
- (c) If $\mathcal{G} = \sigma(Z)$ where Z is a random variable, we write $\mathbb{E}[X|Z] := \mathbb{E}[X|\sigma(Z)]$. This is $\sigma(Z)$ measurable by (i), so it's of the form $f(Z)$ for some function f . It's then common to define $\mathbb{E}[X|Z = z] = f(z)$.

Theorem 1.4 (Existence and uniqueness). Let $X \in L^1(\Omega, \mathcal{F}, \mathbb{P})$, and $\mathcal{G} \subseteq \mathcal{F}$ a σ -algebra.

- (i) $\mathbb{E}[X|\mathcal{G}]$ exists

- (ii) Any two versions of $\mathbb{E}[X|\mathcal{G}]$ coincide \mathbb{P} -almost surely.

Proof.

- (ii) Uniqueness. Let Y be as in [Definition 1.2](#), and let Y' satisfy Definition 1.2(i) and (ii) for some $X' \in L^1$ with $X \leq X'$ almost surely. Let $Z = (Y - Y')\mathbb{1}_A$ with $A := \{Y \geq Y'\} \in \mathcal{G}$.

$$\mathbb{E}[Y\mathbb{1}_A] = \mathbb{E}[X\mathbb{1}_A] \leq \mathbb{E}[X'\mathbb{1}_A] = \mathbb{E}[Y'\mathbb{1}_A] < \infty$$

and note that $\mathbb{E}[X'\mathbb{1}_A] < \infty$, so $\mathbb{E}[Y'\mathbb{1}_A] < \infty$.

By definition of Z , this means $\mathbb{E}[Z] \leq 0$. But $Z \geq 0$ almost surely, so $Z = 0$ a.s. therefore $Y \leq Y'$ a.s. (This shows monotonicity of conditional expectation.) If $X = X'$, we can run the same argument to show that $Y = Y'$ almost surely (using $A = \{Y > Y'\}$ and $A = \{Y < Y'\}$, we see both sets are measure zero).

- (i) Existence. Step 1: Assume first $X \in L^2(\mathcal{F})$. Since $L^2(\mathcal{G})$ is a complete subspace of $L^2(\mathcal{F})$, X has an orthogonal projection Y on $L^2(\mathcal{G})$, i.e. there is $Y \in L^2(\mathcal{G})$ such that $\mathbb{E}[(X - Y)Z] = 0$ for every $Z \in L^2(\mathcal{G})$. Choosing $Z = \mathbb{1}_A$ for $A \in \mathcal{G}$ we get $\mathbb{E}[X\mathbb{1}_A] = \mathbb{E}[Y\mathbb{1}_A]$ so Y satisfies the conditions of [Definition 1.2](#).

Step 2: Assume $X \geq 0$. Then $X_n = X \wedge n \in L^2(\mathcal{F})$ and $0 \leq X_n \nearrow X$ as $n \rightarrow \infty$. By Step 1, we can find $Y_n \in L^2(\mathcal{G})$ such that $\mathbb{E}[X_n\mathbb{1}_A] = \mathbb{E}[Y_n\mathbb{1}_A]$ for all $A \in \mathcal{G}$ and $0 \leq Y_n \leq Y_{n+1}$ almost surely (from the proof of (ii)). Let $Y_\infty = \lim_n Y_n \mathbb{1}_{\Omega_0}$ with

$$\Omega_0 = \{\omega \in \Omega : 0 \leq Y_n(\omega) \leq Y_{n+1}(\omega) \forall n\}.$$

Then Y_∞ is a non-negative random variable, is \mathcal{G} -measurable as a limit of \mathcal{G} -measurable r.v.s and by monotone convergence $\mathbb{E}[X\mathbb{1}_A] = \mathbb{E}[Y_\infty\mathbb{1}_A]$ for every $A \in \mathcal{G}$. Taking $A = \Omega$, $\mathbb{E}[Y_\infty] = \mathbb{E}[X] < \infty$, since $X \in L^1$. So $Y_\infty < \infty$ almost surely and $Y := Y_\infty \mathbb{1}_{\{Y_\infty < \infty\}}$ satisfies [Definition 1.2](#)(i) and (ii).

Step 3: For general $X \in L^1$, apply Step 2 on X^+ and X^- to obtain Y^+ and Y^- . Then $Y = Y^+ - Y^-$ satisfies the conditions of [Definition 1.2](#). \square

Lecture 3 **Example** (Conditional density functions). Let U and V be random variables with a joint density function $f_{U,V}$ in \mathbb{R}^2 . Then

$$f_U(u) = \int_{\mathbb{R}} f_{U,V}(u, v) dv$$

is the density of U , and

$$f_{V|U}(v|u) = \begin{cases} \frac{f_{U,V}(u, v)}{f_U(u)} & \text{if } f_U(u) > 0 \\ 0 & \text{else} \end{cases}$$

is the conditional density of V given U .

Assume $X = h(V) \in L^1$. Then $\mathbb{E}[X|U] = g(U)$ with $g(u) = \int_{\mathbb{R}} h(v) f_{V|U}(v|u) dv$. Indeed, since every $A \in \sigma(U)$ takes the form $A = \{U \in B\}$ for some $B \in \mathcal{B}(\mathbb{R})$.

$$\begin{aligned} \mathbb{E}[X\mathbb{1}_A] &= \int_{\mathbb{R}^2} h(v) \mathbb{1}_B(u) f_{U,V}(u, v) du dv \\ &= \int_{\mathbb{R}} \underbrace{\left(\int_{\mathbb{R}} h(v) f_{V|U}(v|u) dv \right)}_{g(u)} f_U(u) \mathbb{1}_B(u) du \\ &= \mathbb{E}[g(U) \mathbb{1}_{\{U \in B\}}] = \mathbb{E}[g(U) \mathbb{1}_A]. \end{aligned}$$

1.3 Properties of conditional expectation

Let $X \in L^1$, $\mathcal{G} \subseteq \mathcal{F}$ σ -algebras.

- (i) $\mathbb{E}[\mathbb{E}[X|\mathcal{G}]] = \mathbb{E}[X]$ (proof: use $A = \Omega$ in [Definition 1.2\(ii\)](#))
- (ii) If X is \mathcal{G} -measurable, then $\mathbb{E}[X|\mathcal{G}] = X$ a.s. (proof: X satisfies the conditions of [Definition 1.2](#))
- (iii) If X is independent of \mathcal{G} (i.e. $\mathbb{P}[A \cap B] = \mathbb{P}[A]\mathbb{P}[B]$ for all $A \in \mathcal{G}$ and $B \in \sigma(X)$) then $\mathbb{E}[X|\mathcal{G}] = \mathbb{E}[X]$ a.s. Proof: $\mathbb{E}[X]$ is constant and thus \mathcal{G} -measurable. For $A \in \mathcal{G}$

$$\mathbb{E}[X \mathbb{1}_A] = \mathbb{E}[X]\mathbb{E}[\mathbb{1}_A] = \mathbb{E}[\mathbb{E}[X]\mathbb{1}_A]$$

by independence then linearity.

- (iv) If $X \geq 0$ almost surely then $\mathbb{E}[X|\mathcal{G}] \geq 0$ almost surely. (proof: see [Theorem 1.4\(ii\)](#)).
- (v) $\mathbb{E}[\alpha X + \beta Y|\mathcal{G}] = \alpha \mathbb{E}[X|\mathcal{G}] + \beta \mathbb{E}[Y|\mathcal{G}]$ almost surely for $Y \in L^1$ and $\alpha, \beta \in \mathbb{R}$.
- (vi) If $0 \leq X_n \nearrow X$ almost surely, then $\mathbb{E}[X_n|\mathcal{G}] \nearrow \mathbb{E}[X|\mathcal{G}]$ almost surely. Proof: $\mathbb{E}[X_n|\mathcal{G}] \nearrow Y$ almost surely for some \mathcal{G} -measurable Y . For every $A \in \mathcal{G}$,

$$\mathbb{E}[X \mathbb{1}_A] = \lim_n \mathbb{E}[X_n \mathbb{1}_A] = \lim_n \mathbb{E}[\mathbb{E}[X_n|\mathcal{G}] \mathbb{1}_A] = \mathbb{E}[Y \mathbb{1}_A]$$

so $Y = \mathbb{E}[X|\mathcal{G}]$.

- (vii) Fatou. If $X_n \geq 0$ almost surely $\forall n$, then

$$\mathbb{E}[\liminf X_n|\mathcal{G}] \leq \liminf \mathbb{E}[X_n|\mathcal{G}].$$

(Proof as for $\mathbb{E}[\cdot]$).

- (viii) Dominated convergence. If $X_n \rightarrow X$ almost surely, and $|X_n| \leq Y$ almost surely $\forall n$ for $Y \in L^1$ then $\mathbb{E}[X_n|\mathcal{G}] \rightarrow \mathbb{E}[X|\mathcal{G}]$ almost surely. Proof as for $\mathbb{E}[\cdot]$.
- (ix) Jensen's inequality. If $c : \mathbb{R} \rightarrow (-\infty, \infty]$ convex, then $c(\mathbb{E}[X|\mathcal{G}]) \leq \mathbb{E}[c(X)|\mathcal{G}]$. Proof: c can be written as

$$c(x) = \sup_n (a_n x + b_n) \quad x \in \mathbb{R}$$

so

$$\mathbb{E}[c(X)|\mathcal{G}] \geq a_n \mathbb{E}[X|\mathcal{G}] + b_n$$

for all n . Taking \sup_n on the right gives the claim.

- (x) $\mathbb{E}[|\mathbb{E}[X|\mathcal{G}]|^p] \leq \mathbb{E}[|X|^p]$ for $1 \leq p < \infty$. Follows from (ix) and (ii).
- (xi) Tower property: If $\mathcal{H} \subseteq \mathcal{G} \subseteq \mathcal{F}$ σ -algebras, then

$$\mathbb{E}[\mathbb{E}[X|\mathcal{G}|\mathcal{H}]] = \mathbb{E}[X|\mathcal{H}]$$

almost surely. Proof: Clearly $\mathbb{E}[\mathbb{E}[X|\mathcal{G}|\mathcal{H}]]$ is \mathcal{H} -measurable. Take $A \in \mathcal{H}$, so $A \in \mathcal{G}$. Then

$$\begin{aligned} \mathbb{E}[X \mathbb{1}_A] &= \mathbb{E}[\mathbb{1}_A \mathbb{E}[X|\mathcal{G}]] \\ &= \mathbb{E}[\mathbb{1}_A \mathbb{E}[\mathbb{E}[X|\mathcal{G}|\mathcal{H}]]]. \end{aligned}$$

(xii) Let $Y \in L^1$ be \mathcal{G} -measurable, and such that $XY \in L^1$. Then

$$\mathbb{E}[YX|\mathcal{G}] = Y\mathbb{E}[X|\mathcal{G}]$$

almost surely. ‘ \mathcal{G} -measurable random variables behave like constants’.

Proof: The right hand side of \mathcal{G} -measurable. If $Y = \mathbb{1}_B$ for $B \in \mathcal{G}$. Then $\forall A \in \mathcal{G}$,

$$\mathbb{E}[XY\mathbb{1}_A] = \mathbb{E}[X\mathbb{1}_{A \cap B}] = \mathbb{E}[(\mathbb{E}[X|\mathcal{G}]\mathbb{1}_B)\mathbb{1}_A].$$

So the claim holds for simple random variables. For general Y , the statement follows by linearity, approximation, etc.

(xiii) If $\sigma(X, \mathcal{G})$ is **independent** of \mathcal{H} then $\mathbb{E}[X|\sigma(\mathcal{G}, \mathcal{H})] = \mathbb{E}[X|\mathcal{G}]$ almost surely. Proof: For $A \in \mathcal{G}$ and $B \in \mathcal{H}$,

$$\begin{aligned} \mathbb{E}[\mathbb{E}[X|\sigma(\mathcal{G}, \mathcal{H})]\mathbb{1}_{A \cap B}] &= \mathbb{E}[X\mathbb{1}_{A \cap B}] \\ &= \mathbb{E}[X\mathbb{1}_{A \cap B}] \\ &= \mathbb{E}[X\mathbb{1}_A]\mathbb{P}[B] \\ &= \mathbb{E}[\mathbb{E}[X|\mathcal{G}]\mathbb{1}_A]\mathbb{P}[B] \\ &= \mathbb{E}[\mathbb{E}[X|\mathcal{G}]\mathbb{1}_{A \cap B}] \\ \implies \mathbb{E}[(\mathbb{E}[X|\sigma(\mathcal{G}, \mathcal{H})] - \mathbb{E}[X|\mathcal{G}])\mathbb{1}_{A \cap B}] &= 0 \end{aligned}$$

The set of such intersections $A \cap B$ is a **π -system** generating $\sigma(\mathcal{G}, \mathcal{H})$, and it is a standard result of measure theory that this implies $\mathbb{E}[X|\sigma(\mathcal{G}, \mathcal{H})] - \mathbb{E}[X|\mathcal{G}] = 0$ almost surely (see PM notes, Proposition 3.1.4).

Lecture 4 **Lemma 1.5.** Let $X \in L^n$. Then

$$\mathcal{C} = \{Y : Y = \mathbb{E}[X | \mathcal{G}] \text{ for some } \mathcal{G} \subseteq \mathcal{F}\}$$

is uniformly integrable, i.e.

$$\sup_{Y \in \mathcal{C}} \mathbb{E}[|Y|\mathbb{1}_{\{|Y| \geq \lambda\}}] \xrightarrow{\lambda \rightarrow \infty} 0.$$

Proof. For every $\epsilon > 0$ there is $\delta > 0$ such that $\mathbb{E}[|X|\mathbb{1}_A] \leq \epsilon$ for every A with $\mathbb{P}[A] \leq \delta$. (See PM Lemma 6.7.1).

Choose λ such that $\mathbb{E}[|X|] \leq \lambda\delta$. For $Y = \mathbb{E}[X | \mathcal{G}]$, $|Y| \leq \mathbb{E}[|X| | \mathcal{G}]$, so $\mathbb{E}[|Y|] \leq \mathbb{E}[\mathbb{E}[|X| | \mathcal{G}]] = \mathbb{E}[|X|] \leq \lambda\delta$. Standard bounds give

$$\mathbb{P}[|Y| \geq \lambda] \leq \frac{1}{\lambda} \mathbb{E}[|Y|] \leq \delta.$$

So

$$\begin{aligned} \mathbb{E}[|Y|\mathbb{1}_{\{|Y| \geq \lambda\}}] &\leq \mathbb{E}[\mathbb{E}[|X| | \mathcal{G}]\mathbb{1}_{\{|Y| \geq \lambda\}}] \\ &= \mathbb{E}[\mathbb{E}[|X|\mathbb{1}_{\{|Y| \geq \lambda\}} | \mathcal{G}]] \\ &= \mathbb{E}[|X|\mathbb{1}_{\{|Y| \geq \lambda\}}] \leq \epsilon \end{aligned}$$

(λ independent of \mathcal{G}). □

2 Martingales in discrete time

2.1 Definitions

Let $(\Omega, \mathcal{F}, \mathbb{P})$ a probability space.

Definition 2.1. A **filtration** is a sequence of σ -algebras such that

$$\mathcal{F}_n \subseteq \mathcal{F}_{m+n} \subseteq \mathcal{F} \quad \forall n.$$

Let $\mathcal{F}_\infty = \sigma(\mathcal{F}_n, n \geq 0)$, so $\mathcal{F}_\infty \subseteq \mathcal{F}$, but possibly $\mathcal{F}_\infty \neq \mathcal{F}$. Usually n represents time, and \mathcal{F}_n represents the information available at time n . A **stochastic process** in discrete time $(X_n)_{n \geq 0}$ (i.e. a sequence of random variables) has a **natural filtration** $(\mathcal{F}_n^X)_{n \geq 0}$ given by $\mathcal{F}_n^X = \sigma(X_0, \dots, X_n)$.

Definition 2.2. A **stochastic process** $(X_n)_{n \geq 0}$ is **adapted** to a **filtration** $(\mathcal{F}_n)_n$ if X_n is \mathcal{F}_n -measurable, for all n .

Definition 2.3. A **stochastic process** $(X_n)_{n \geq 0}$ is a **martingale** (with respect to a **filtration** $(\mathcal{F}_n)_{n \geq 0}$) if

- (i) X is **adapted**
- (ii) X is integrable, i.e. each $\mathbb{E}[|X_n|] < \infty$.
- (iii) $\mathbb{E}[X_{n+1} | \mathcal{F}_n] = X_n$ almost surely (martingale property).

If the '=' in (iii) is replaced by ' \geq ' (respectively ' \leq ') X is called a **submartingale** (resp. **supermartingale**).

2.2 Optional stopping

Definition 2.4. A random time $\tau : \Omega \rightarrow \{0, 1, 2, \dots\} \cup \{+\infty\}$ is called a **stopping time** (with respect to a filtration \mathcal{F}_n) if

$$\{\tau \leq n\} \in \mathcal{F}_n \quad \forall n \geq 0$$

(or equivalently $\{\tau = n\} \in \mathcal{F}_n \quad \forall n$.)

Example. Take X **adapted**, $A \in \mathcal{B}(\mathbb{R})$.

$$\tau_A(\omega) = \inf\{n \geq 0 : X_n(\omega) \in A\}$$

the first hitting time of A is a **stopping time**.

We write

$$\mathcal{F}_\tau = \{A \in \mathcal{F}_\infty : A \cap \{\tau \leq n\} \in \mathcal{F}_n \quad \forall n \geq 0\}.$$

Define also $X_\tau(\omega) = X_{\tau(\omega)}(\omega)$ whenever $\tau < \infty$. The **stopped process** X^τ is given by

$$X_n^\tau(\omega) = X_{\tau(\omega) \wedge n}(\omega).$$

Proposition 2.5. Take σ, τ **stopping times**, X **adapted**.

- (i) $\sigma \wedge \tau$ is a **stopping time**
- (ii) \mathcal{F}_τ is a σ -algebra
- (iii) If $\sigma \leq \tau$, $\mathcal{F}_\sigma \subseteq \mathcal{F}_\tau$.

(iv) $X_\tau \mathbb{1}_{\{\tau < \infty\}}$ is \mathcal{F}_τ -measurable

(v) X^τ is adapted

(vi) If X is integrable, X^τ is integrable

Theorem 2.6 (Hunt's optional stopping theorem). Let X be a **supermartingale**, σ, τ bounded **stopping times** with $\sigma \leq \tau$. Then

$$\mathbb{E}[X_\tau] \leq \mathbb{E}[X_\sigma].$$

Proof. Let $n \geq 0$ be such that $\tau \leq n$.

$$X_\tau = X_\sigma + \sum_{\sigma \leq k < \tau} (X_{k+1} - X_k) = X_\sigma + \sum_{k=0}^n (X_{k+1} - X_k) \mathbb{1}_{\{\sigma \leq k < \tau\}}. \quad (2.1)$$

Now, we have

$$\begin{aligned} \mathbb{E}[(X_{k+1} - X_k) \mathbb{1}_{\{\sigma \leq k < \tau\}}] &= \mathbb{E}[\mathbb{E}[(X_{k+1} - X_k) \mathbb{1}_{\{\sigma \leq k\}} \mathbb{1}_{\{\tau > k\}} | \mathcal{F}_k]] \\ &= \underbrace{\mathbb{E}[\mathbb{E}[X_{k+1} - X_k | \mathcal{F}_k] \mathbb{1}_{\{\sigma \leq k < \tau\}}]}_{\leq 0}. \end{aligned}$$

But X is a **supermartingale**, so taking expectations in (2.1) gives $\mathbb{E}[X_\tau] \leq \mathbb{E}[X_\sigma]$. \square

Remark. The same proof shows that if σ, τ are bounded **stopping times**, X **submartingale** then $\mathbb{E}[X_\sigma] \leq \mathbb{E}[X_\tau]$. Similarly if X is a martingale, we have equality.

Theorem 2.7. Let X be **adapted**, integrable. The following are equivalent.

- (i) X is a **supermartingale**
- (ii) For any **stopping times** σ, τ with τ bounded, $\mathbb{E}[X_\tau | \mathcal{F}_\sigma] \leq X_{\sigma \wedge \tau}$ almost surely.
- (iii) X^τ is a supermartingale for all stopping times τ (not necessarily bounded).
- (iv) $\mathbb{E}[X_\tau] \leq \mathbb{E}[X_\sigma]$ for all σ, τ stopping times with $\sigma \leq \tau$.

Proof. (i) \implies (ii). For $\sigma \geq 0$ and $\tau < n$,

$$\begin{aligned} X_\tau &= X_{\sigma \wedge \tau} + \sum_{\sigma \leq k < \tau} (X_{k+1} - X_k) \\ &= X_{\sigma \wedge \tau} + \sum_{k=0}^n (X_{k+1} - X_k) \mathbb{1}_{\{\sigma \leq k < \tau\}}. \end{aligned}$$

and as in the last proof

$$\mathbb{E}[(X_{k+1} - X_k) \mathbb{1}_{\{\sigma \leq k < \tau\}} \mathbb{1}_A] \leq 0 \quad \forall A \in \mathcal{F}_\sigma$$

(note we have $A \cap \{\sigma \leq k\} \in \mathcal{F}_k$). Multiplying the earlier equation with $\mathbb{1}_A$ and taking expectations gives

$$\mathbb{E}[X_\tau \mathbb{1}_A] \leq \mathbb{E}[X_{\sigma \wedge \tau} \mathbb{1}_A]$$

which implies (ii).

Lecture 5 Clearly (ii) \implies (iii) and (ii) \implies (iv) (take expectations). Also clearly (iii) \implies (i), by choosing τ deterministic and very large. Remains to show (iv) \implies (i). Let $m \leq n$, $A \in \mathcal{F}_m$, $\tau := m \mathbb{1}_A + n \mathbb{1}_{A^c} \leq n$.

$$\mathbb{E}[X_n \mathbb{1}_A] - \mathbb{E}[X_m \mathbb{1}_A] = \mathbb{E}[X_n] - \mathbb{E}[X_n \mathbb{1}_{A^c} + X_m \mathbb{1}_A].$$

Observe that the rightmost term is just $\mathbb{E}[X_\tau]$, so

$$= \mathbb{E}[X_n] - \mathbb{E}[X_\tau] \leq 0$$

by (iv), since $\tau \leq n$. Thus $\mathbb{E}[X_n \mathbb{1}_A] \leq \mathbb{E}[X_m \mathbb{1}_A] \quad \forall A \in \mathcal{F}_m$, hence $\mathbb{E}[X_n | \mathcal{F}_m] \leq X_m$ hence X is a supermartingale. \square

2.3 Doob's upcrossing inequality

Let $X = (X_n)_n$ be a [stochastic process](#). Fix an interval $[a, b]$.

Definition 2.8. We say that an of $[a, b]$ occurs between times m and n if

- (i) $X_m < a$ and $X_n > b$
- (ii) $X_k \in [a, b]$ for every $k \in (m, n)$

Write $U_N(a, b) :=$ number of upcrossings on $[0, N]$ Define also the monotone limit $U_\infty(a, b) := \lim_{N \rightarrow \infty} U_N(a, b)$.

Consider the gambling strategy: wait until the process X (say price of a share) drops below a . Buy a share and hold it until the price exceeds b ; sell, wait until the price drops below a , and so on.

Our wealth process is then given by

$$W_n = \sum_{k=1}^n c_k (X_k - X_{k-1})$$

with

$$\begin{aligned} c_1 &= \mathbb{1}_{\{X_0 < a\}} \\ c_n &= \mathbb{1}_{\{c_{n-1}=1\}} \mathbb{1}_{\{X_{n-1} \leq b\}} + \mathbb{1}_{\{c_{n-1}=0\}} \mathbb{1}_{\{X_{n-1} < a\}}. \end{aligned}$$

Each time there is an [upcrossing](#), we win at least $(b - a)$. Thus, at time N

$$W_n \geq (b - a)U_n(a, b) - \underbrace{|a - X_N| \mathbb{1}_{\{X_N < a\}}}_{|X_N - a|^-}. \quad (2.3)$$

$|X_N - a|^-$ represents the maximum loss if invested at time N and price $< a$.

Theorem 2.9 (Doob's upcrossing lemma). Let X be a [supermartingale](#). Then

$$\mathbb{E}[U_\infty(a, b)] \leq \sup_{n \geq 0} \frac{\mathbb{E}[(X_n - a)^-]}{b - a}.$$

Proof. c_n is F_{n-1} -measurable and non-negative. Hence (W_n) is a [supermartingale](#) (easy exercise) with $W_0 = 0$. Therefore $\mathbb{E}[W_N] \leq 0$ and taking expectations in (2.3) gives

$$\begin{aligned} \mathbb{E}[U_N(a, b)] &\leq \frac{\mathbb{E}[(X_N - a)^-]}{b - a} \\ \mathbb{E}[U_\infty(a, b)] &\leq \sup_{n \geq 0} \frac{\mathbb{E}[(X_n - a)^-]}{b - a} \end{aligned}$$

by monotone convergence. □

2.4 Doob's maximal inequalities

Ideal goal: exchange \mathbb{E} and sup.

$$X_n^* := \sup_{k \leq n} |X_k|.$$

Theorem 2.10 (Doob's maximal inequality). Let X be a [martingale](#) or non-negative [submartingale](#), then

$$\mathbb{P}[X_n^* \geq \lambda] \leq \frac{1}{\lambda} \mathbb{E}[|X_n| \mathbb{1}_{\{X_n^* \geq \lambda\}}] \leq \frac{1}{\lambda} \mathbb{E}[|X_n|] \quad \forall \lambda > 0.$$

Proof. X martingale $\Rightarrow |X|$ non-negative submartingale. Without loss of generality, assume $X_n \geq 0$ for all n . Let $\tau := \inf\{k \geq 0 : X_k \geq \lambda\} \wedge n \leq n$, a [stopping time](#).

$$\begin{aligned}\mathbb{E}[X_n] &\geq \mathbb{E}[X_\tau] = \mathbb{E}\left[\underbrace{X_\tau}_{\geq \lambda} \mathbb{1}_{\{X_n^* \geq \lambda\}}\right] + \mathbb{E}\left[\underbrace{X_\tau}_{X_n} \mathbb{1}_{\{X_n^* < \lambda\}}\right] \\ &\geq \lambda \mathbb{P}[X_n^* \geq \lambda] + \mathbb{E}[X_n \mathbb{1}_{\{X_n^* < \lambda\}}]\end{aligned}$$

hence

$$\lambda \mathbb{P}[X_n^* \geq \lambda] \leq \mathbb{E}[X_n \mathbb{1}_{\{X_n^* \geq \lambda\}}]. \quad \square$$

Theorem 2.11 (Doob's L^p inequality). Let X be a [martingale](#) or non-negative [submartingale](#). For all $p > 1$,

$$\mathbb{E}[(X_n^*)^p] \leq \left(\frac{p}{p-1}\right)^p \mathbb{E}[|X_n|^p].$$

Proof. Again $X \geq 0$ without loss of generality. Fix $k < \infty$.

$$\begin{aligned}\int_0^k p \lambda^{p-1} \mathbb{1}_{\{X_n^* \geq \lambda\}} d\lambda &= p \int_0^{k \wedge X_n^*} \lambda^{p-1} d\lambda \\ &= (k \wedge X_n^*)^p.\end{aligned}$$

Then using Fubini,

$$\begin{aligned}\mathbb{E}[(k \wedge X_n^*)^p] &= \int_0^k p \lambda^{p-1} \mathbb{P}[X_n^* \geq \lambda] d\lambda \\ &\leq \int_0^k p \lambda^{p-2} \mathbb{E}[X_n \mathbb{1}_{\{X_n^* \geq \lambda\}}] d\lambda \\ &= \frac{p}{p-1} \mathbb{E} \left[X_n \underbrace{\int_0^k (p-1) \lambda^{p-2} \mathbb{1}_{\{X_n^* \geq \lambda\}} d\lambda}_{(k \wedge X_n^*)^{p-1}} \right] \\ &= \frac{p}{p-1} \mathbb{E} [X_n (k \wedge X_n^*)^{p-1}] \\ &\leq \frac{p}{p-1} \mathbb{E} [X_n^p]^{\frac{1}{p}} \mathbb{E} [(k \wedge X_n^*)^p]^{\frac{p-1}{p}} \quad (\text{using Hölder}) \\ \implies \mathbb{E}[(k \wedge X_n^*)^p]^{\frac{1}{p}} &\leq \frac{p}{p-1} \mathbb{E}[X_n^p]^{\frac{1}{p}}\end{aligned}$$

Finally, use monotone convergence as $k \rightarrow \infty$ to give the result. \square

Let $X^* = \sup_{n \geq 0} |X_n|$. Taking $n \rightarrow \infty$ in [Theorem 2.10](#) and [Theorem 2.11](#) by monotone convergence, we get

$$\begin{aligned}\mathbb{P}[X^* > \lambda] &\leq \frac{1}{\lambda} \sup_{n \geq 0} \mathbb{E}[|X_n|] \\ \mathbb{E}[(X^*)^p] &\leq \left(\frac{p}{p-1}\right) \sup_{n \geq 0} \mathbb{E}[|X_n|^p].\end{aligned}$$

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