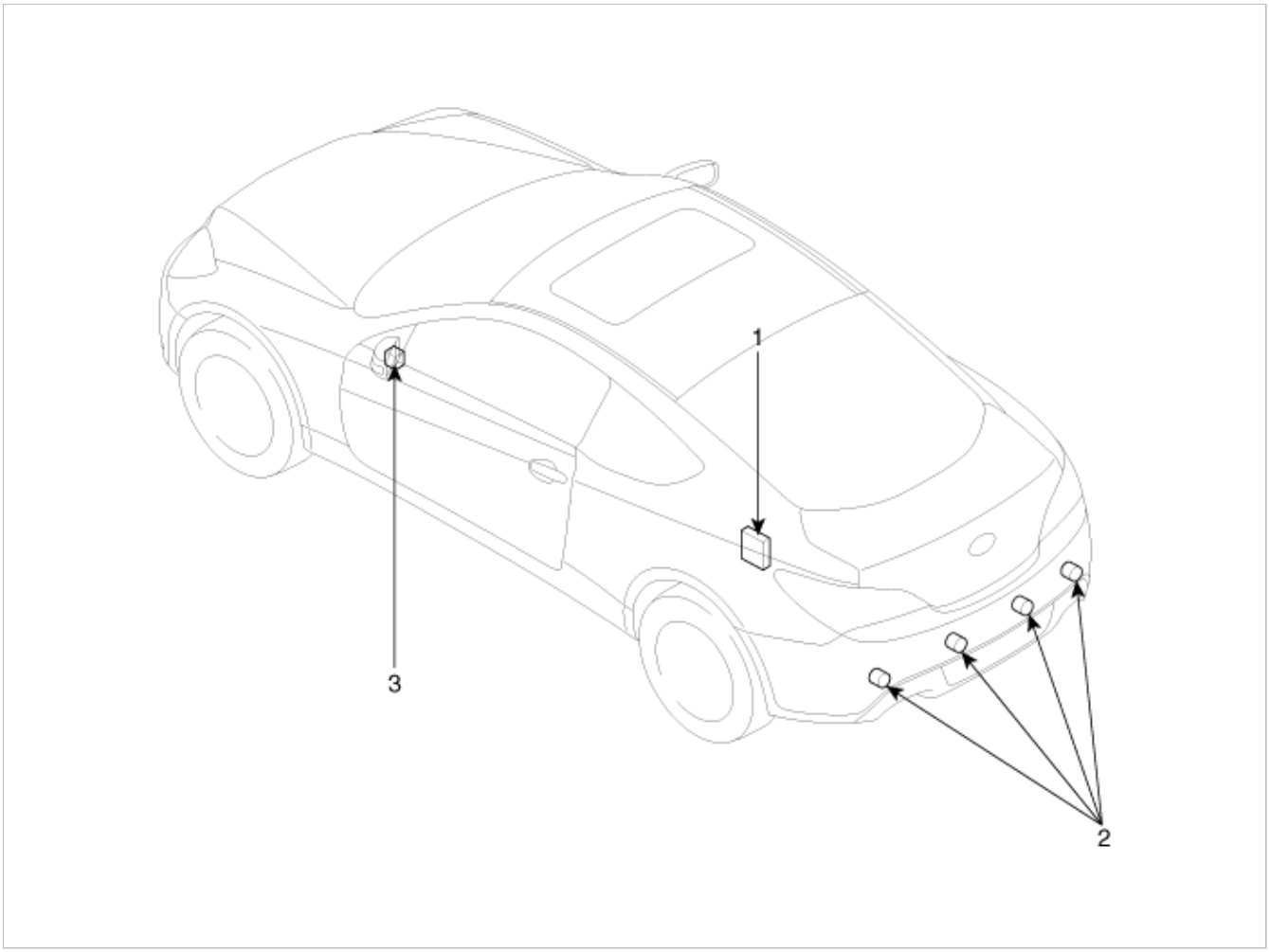
Specification

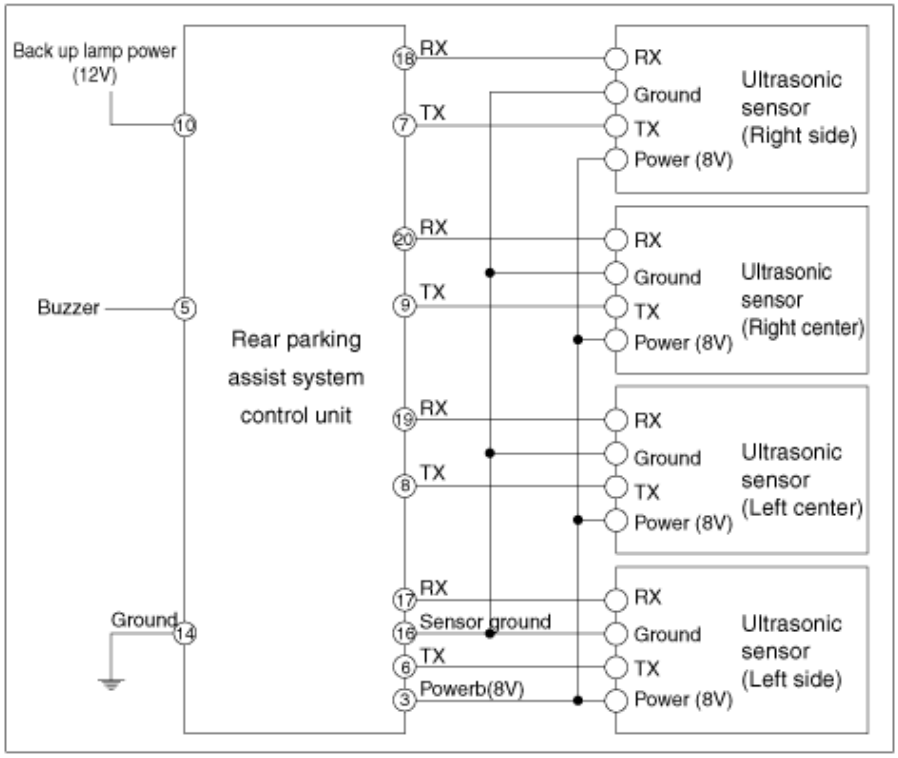
Item		Specification
Back warning control unit	Voltage rating	DC 12V
	Operation voltage	DC 9 ~ 16 V
	Operation temperature	-30°C ~ + 80°C
	Operation current	MAX 600 mA
	Operation frequency	48 ± 5 KHz
	Detective method	Direct and indirect detection
Ultrasonic sensor	Voltage rating	DC 8 V
	Detecting range	40 cm ~ 120 cm
	Operation voltage	DC 7 ~ 9 V
	Operation current	MAX 20 mA
	Operation temperature	-30°C ~ + 80°C
	Operation frequency	40 ± 5 KHz
	Number of sensors	4 (Left side, Left center, Right center, Right side)
Piezo buzzer	Voltage rating	DC 12 V
	Operation voltage	DC 9 ~ 16 V
	Operation temperature	-30°C ~ + 80°C
	Operation current	MAX 60 mA
	Sound, tone	Oscillation frequency : 2.0 ± 0.5 KHz
		Sound level : 65 dB (DC 13V /m)

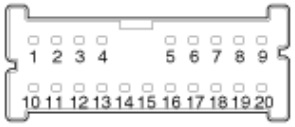
Component Location



1. Rear parking assist system control unit 2. Ultrasonic sensor	3. Buzzer

Circuit Diagram





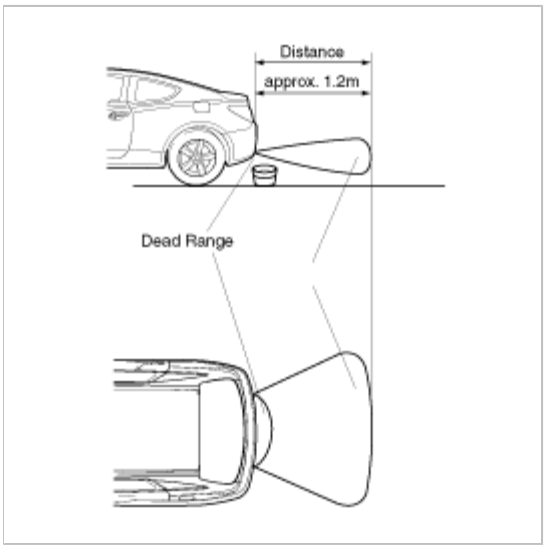
(Rear parking assist system control unit connector)

Pin configuration

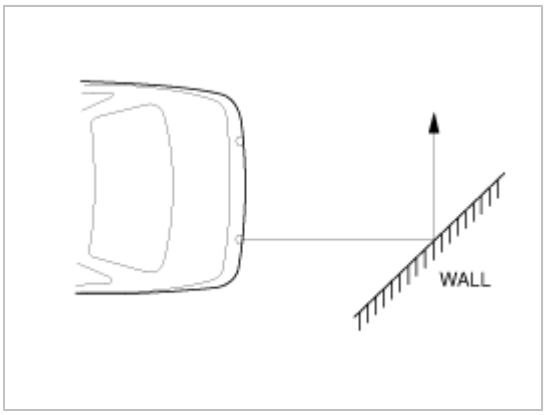
Pin No.	Signal	Test : Desired result
3	Sensor power	8V (While operating)
5	Buzzer	0V (While operating)
6	TX - Sensor(Left)	0~3V voltage change (Inspect waveform)
7	TX - Sensor(Right)	0~3V voltage change (Inspect waveform)
8	TX - Sensor(Left center)	0~3V voltage change (Inspect waveform)
9	TX - Sensor(Right center)	0~3V voltage change (Inspect waveform)
10	Back up lamp power	12V (While shifting to "R")
14	Ground	0V
16	Sensor ground	0V
17	RX - Sensor(Left)	0~1V voltage change (Inspect waveform)
18	RX - Sensor(Right)	0~1V voltage change (Inspect waveform)
19	RX - Sensor(Left center)	0~1V voltage change (Inspect waveform)
20	RX - Sensor(Right center)	0~1V voltage change (Inspect waveform)

Warning

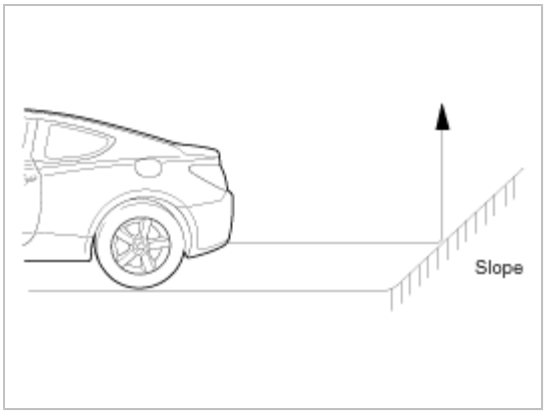
1. Range detected by back sensors is limited.
   Watch back before reversing.
2. There is a blind spot below the bumper. Low objects (for example boundary barrier) may be detected from minimum 1.5m away unable to detect at nearer.
3. Besides there are some materials unable to be detected even in detection range as follows.
   (1) Needles, ropes, rods, or other thin objects.
   (2) Cotton, snow and other material absorbing ultrasonic wave(for example, fire extinguisher device covered with snow)



4. Reversing toward the sloped walls.



5. Reversing toward the sloped terrain.



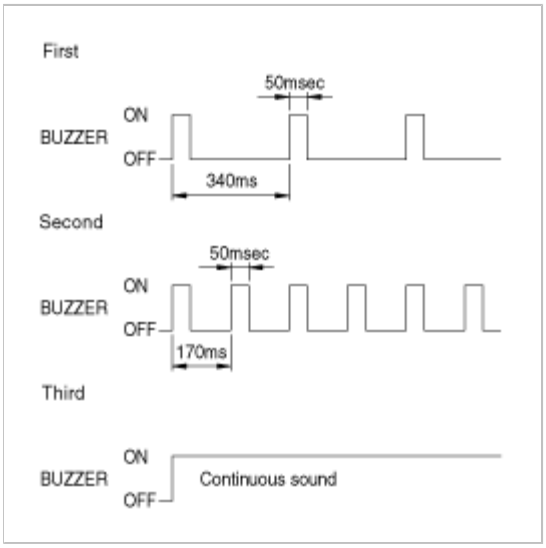
6. False alarm may operate in the following condition: irregular road surface, gravel road, sloped road and grass. Upon alarm generation by grass the alarm may be generated by rock behind grass. Be sure to check for the safety.
   The sensors cannot discriminate between materials.
7. Sensors may not operate correctly in the below conditions.
   Ensure sensors are clean from mud or dirt.
   (1) When spraying the bumper, the sensor opening is covered with something in order not to be contaminated. If sensor opening is contaminated with mud, snow, or dirt, detection range will be reduced and alarm may not be generated under the crash condition. Dirt accumulated on the sensor opening shall be removed with water. Do not wipe or scrape sensor with a rod or a hard object.
   (2) If the sensor is frozen, alarm may not operate until sensor thaws.
   (3) If a vehicle stays under extremely hot or cold environment, the detection range may be reduced. It will be restored at the normal temperature.
   (4) When heavy cargo is loaded in trunk, it changes the vehicle balance, which reduces the detection range.
   (5) When other vehicle's horn, motor cycle engine noise, or other ultra-sonic wave sources are near.
   (6) Under heavy rain.
   (7) When reversing towards a vertical wall and the gap between the vehicle and the wall is 15cm. (Alarm may sound despite the absence of a barrier)
   (8) If radio antenna is installed at the rear.
   (9) If the vehicle rear wiring is re-routed or electrical component is added at the rear part.
   (10) Vehicle balance is changed due to the replacement of the rear spring.
   (11) The unit will operate normally when the vehicle speed is 5km/h or less. Above this speed, the unit may not operate normally.
8. Check the rear bumper for installation condition and deformation. If installed improperly or the sensor orientation is deviated, it may cause malfunction.
9. Be careful not to apply shock during sensor installation on the transmission or reception unit.
10. When adding electrical devices or modifying harness at the rear body of the vehicle, ensure not to change the transmission and reception unit wiring. Tagging the transmission side and reception side, it may cause malfunction.
11. High power radio transmitter (above 10W) may cause malfunction. Do not install it on the vehicle.
12. Be careful that excessive heat or sharp objects shall not touch ultrasonic sensor surface.
    Do not cover the sensor opening or press the sensor.

Description

When reversing, the driver is not easy to find objects in the blind spots and to determine the distance from the object. In order to provide the driver safety and convenience, back warning system will operate upon shifting to "R" Ultrasonic sensor will emit ultrasonic wave rearward and detect the reflected wave. Control unit will calculate distance to the object using the sensor signal input and output buzzer alarm in three steps (first, second and third alarm).

Alarm Range

Upon detecting an object at each range out of 3 ranges as stated below within the operation range, it will generate alarm.
First alarm : Object comes near to the sensor located at the rear of vehicle, within 81-120cm ± 15cm
Second alarm : Object comes near to the sensor located at the rear of vehicle, within 41-80cm ± 10cm
Third alarm : Object comes near to the sensor located at the rear of vehicle, within 40cm ± 10cm

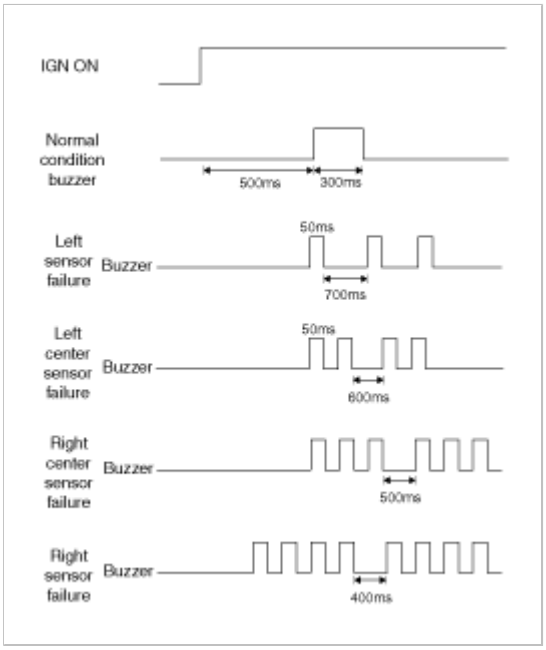


NOTE

1. Time tolerance of the above waveform : Time ± 10%
2. At nearer distance than 40cm, detection may not occur.
3. Alarm will be generated with vehicle reversing speed 5km/h or less.
   For moving target, maximum operation speed shall be target approach speed of 5km/h.
4. When the vehicle or the target is moving, sequential alarm generation or effective alarm may be failed.
5. Misalarm may occur in the following conditions.
   - Irregular road surface, gravel road, reversing toward grass.
   - Horn, motor cycle engine noise, large vehicle air brake, or other object generating ultrasonic wave is near.
   - When a wireless transmitter is used near to the sensor.
   - Dirt on the sensor.
   - Sequential alarm may not occur due to the reversing speed or the target shape.

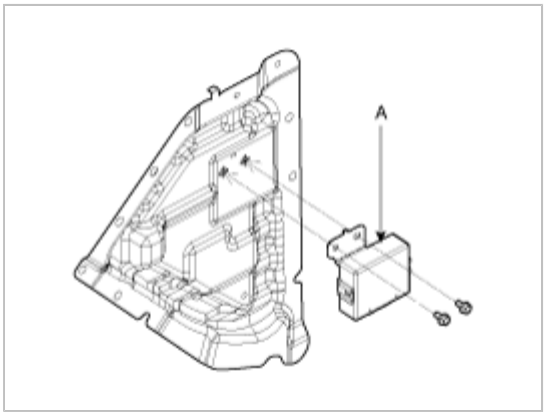
Diagnosis

1. Operate with ignition switch on and shift the lever to position "R"
2. Then it checks the system condition.
   If no trouble, it generates buzzer alarm sound for 0.3 seconds after 0.8 seconds from power approval. In case of system failure, then it indicates the failed point as follows.
   A. Left sensor failure : beep-beep-beep
   B. Left center sensor failure : beep beep-beep beep-beep beep
   C. Right center sensor failure: beep beep beep-beep beep beep-beep beep beep
   D. Right sensor failure: beep beep beep beep-beep beep beep beep-beep beep beep beep
3. Alarm is generated 3 times sequentially.
4. Effective operation range is 10km/h or less for the vehicle speed.



Removal

1. Disconnect the negative (-) battery terminal.
2. Remove the rear seat.
   (Refer to BD group - "Rear seat")
3. Remove the interior left side quarter trim.
4. Loosen the mounting bolts and disconnect the connector.
5. Remove the rear parking assist system control unit (A).



Installation

1. Install the rear parking assist system control unit.
2. Install the left side quarter trim.
3. Install the rear seat.

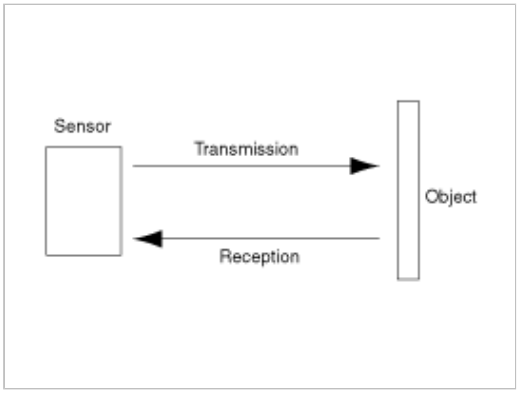
Operation Principle

The sensor emits ultrasonic wave to the objects, and it measures the time until reflected wave returns, and calculates the distance to the object.

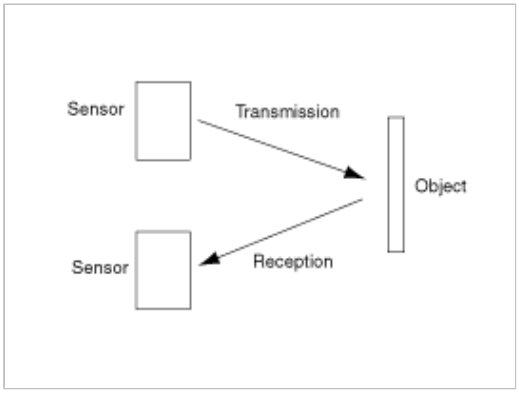
Distance Detection Type

Direct detection type and indirect detection type are used together for improving effectiveness of the detection.

1. Direct detection type: One sensor transmits and receives signals to measure the distance.

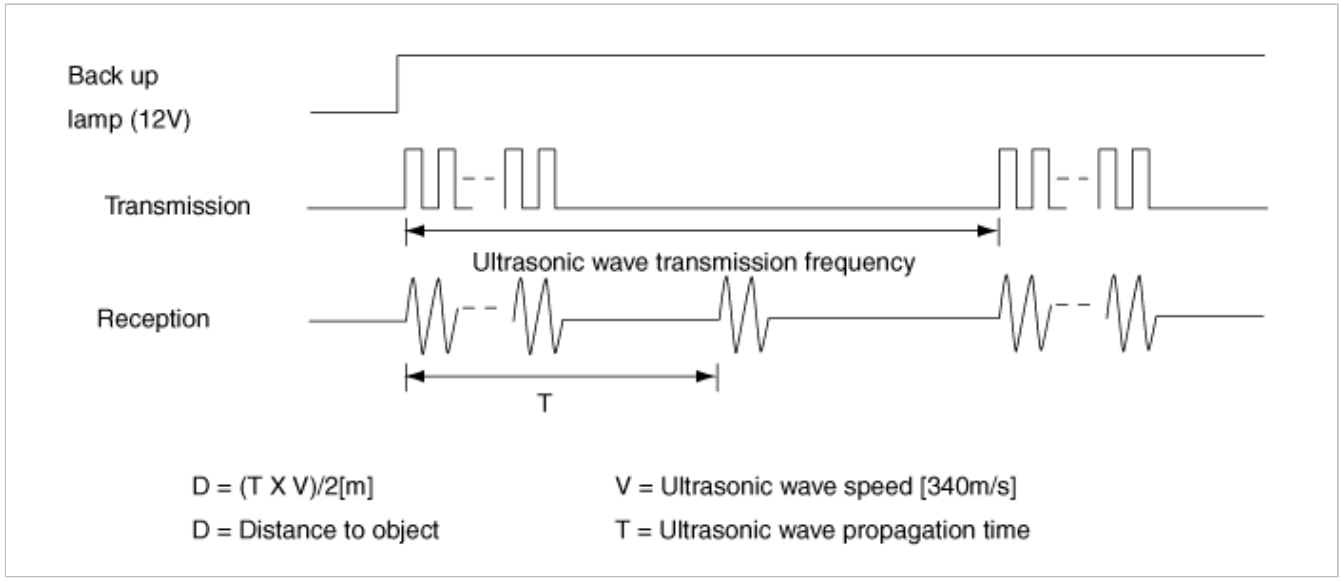


2. Indirect detection type: One sensor transmits signals and the other sensor receives the signals to measure the distance.



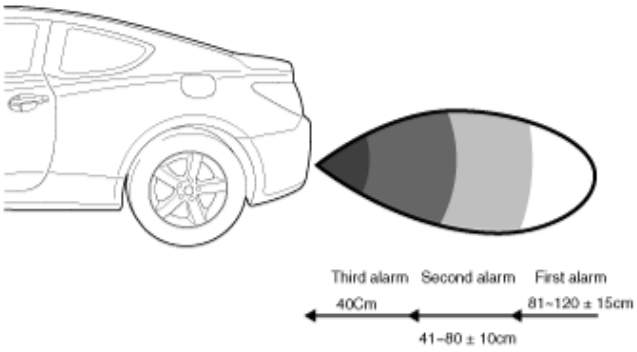
Measurement Principle

Back warning system (BWS) is a complementary device for reversing. BWS detects objects behind vehicle and provides the driver with buzzer alarm finding objects in a certain area, using ultrasonic wave propagation speed and time.
The propagation speed formula of ultrasonic wave in air is following :
v=331.5 + 0.6t (m/s)
v=ultrasonic wave propagation speed
t=ambient temperature
The basic principle of distance measurement using ultrasonic wave is :



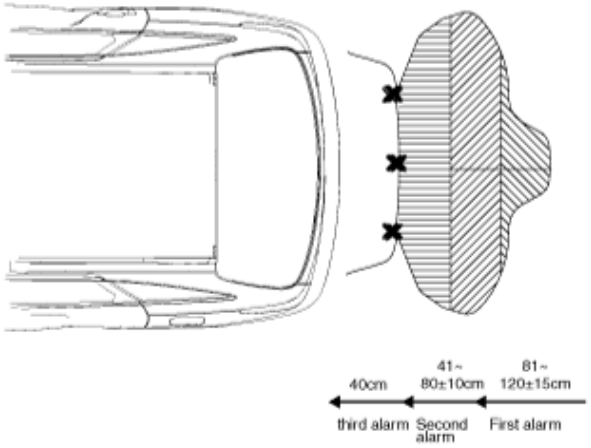
Sensor Detection Range

[Vertical range]



1. Distance tolerance(Messured at the front of sensor)
   81~120cm : ±15cm
   41~80cm : ±10cm
   40cm : ±10Cm
2. Detection tolerance
   At 40cm :45° ± 15°
   At 80cm : 30° ± 15°
   At 120cm : 20° ± 15°
3. At nearer distance than 40cm detection may occur.
4. Measurement condition : Room temperature (20℃), 90mm diameter, 3m length rod.

[Horizontal range]



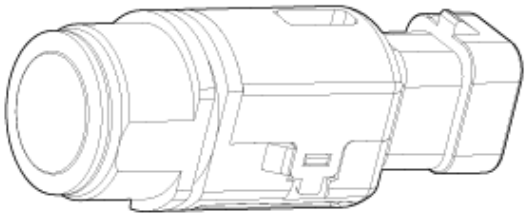
1. Distance tolerance(Messured at the front of sensor)
   81~120cm : ±15cm
   41~80cm : ±10cm
   40cm : ±10cm
2. Detection tolerance
   At 80cm : 90° ± 20°
   At 120cm : 10° ± 20°
3. At nearer distance than 40Cm detection may occur.
4. Measurement condition : Room temperature (20℃), 90mm diameter, 3m length rod.

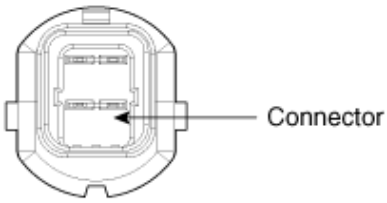
NOTE

1. 14cm (dia.) plastic rod is used for the test target.
2. The test result may differ by a different target object.
3. Detection range may be reduced by dirt accumulated on sensor, and extremely hot or cold weather.
4. The following object may not be detected.
   - Sharp object or thin object like rope.
   - Cotton sponge, snow or other materials absorbing sonic wave.

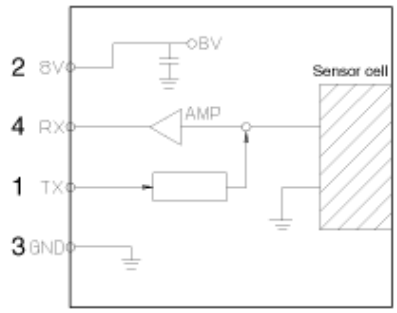
- Smaller objects than 14cm (dia.), 1m length.

Component





Block Diagram



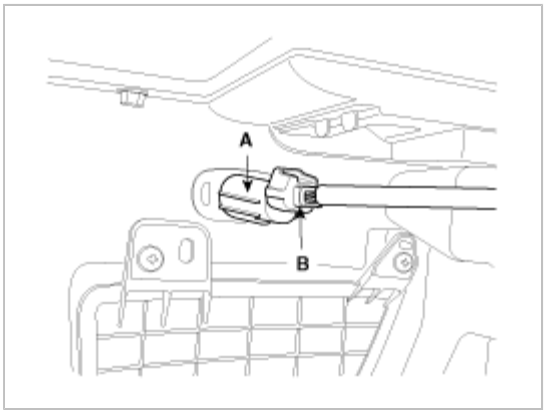
Pin information		
	Pin No.	Signal
	1	TX
	2	8V
	3	GND
	4	RX

Removal

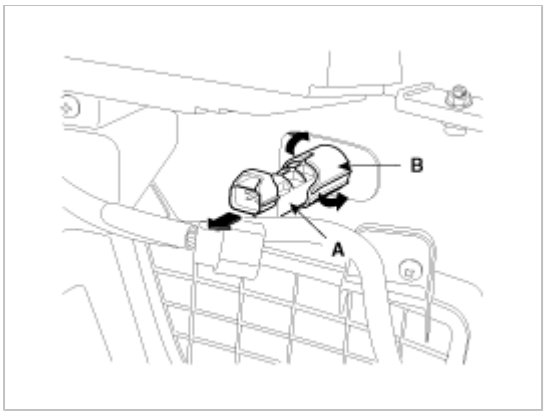
1. [illegible]

2. [illegible]
   [illegible]

3. [illegible]



4. [illegible]



Installation

1. [illegible]

2. [illegible]