# Watermarking-based Intellectual Property Core Protection Scheme

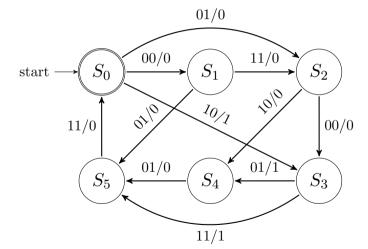
Li-Wei Chen, Shan-Yuan Zheng, Guan-Yu Chen Supervised by C.M. Li

National Taiwan University

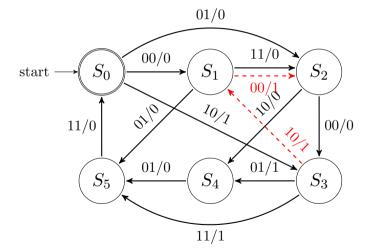
 $June\ 05,\ 2018$ 



# Project Description



# Project Description



3/19

Given the input/output bit string  $b_1b_2\cdots b_n$ , where  $b_i$  is the  $i^{th}$  input/output pair and a the FSM  $(\Sigma, S, s_0, \delta, F)$ , we first compute the maximum length one may go from each  $s \in S$  with the input and output relation specified by  $b_ib_{i+1}\cdots b_n$ .

The unspecified transition will not be taken into consideration, and the maximum length is recorded if there is no path to satisfy the input bit string. We also add a constraint, if the one candidate stops at  $b_j$ , the terminate state for the it must have a unspecified transition for  $b_{j+1}$  to be the maximum length path, expect for when the last input is  $b_n$ .

If their are multiple states that holds the same length, we choose one randomly.

Then we use a greedy strategy, starting from  $b_0$ , we first choose the maximum length state as the first state, then if the maximum path stops at  $b_i$ , we then choose the maximum length state for  $b_{i+2}$  as the second state. Using  $b_j$  as the augmented trasition from the first state to the second state.

A new state is inserted if all the states has zero maximum length and the required input is already specified for all states. Suppose the next input/output pair is  $b_i$ , then we use  $b_i$  as transition to the new state, and  $b_{i+1}$  as the new input/output pair(transition) and continue the algorithm.

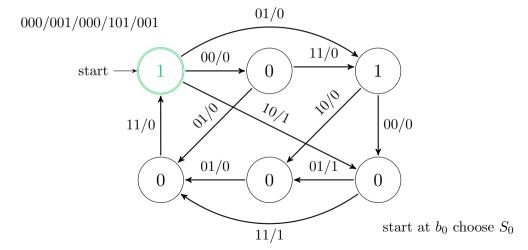
Once a new transition or state is add to the graph, they have no difference from the predefined ones. That is, the algorithm will also take them into consideration.

If the algorithm leads to a dead end, which is, all transitions of the give input  $b_j^i$  is occupied, we push a new state into the graph and restart the algorithm.

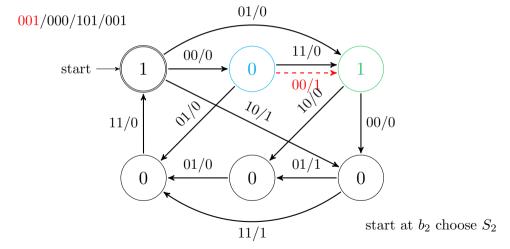
Although this will slow our algorithm a lot for the worst case, the contest input is constraint to be 128 bits, thus it has no influence to the time complexity.

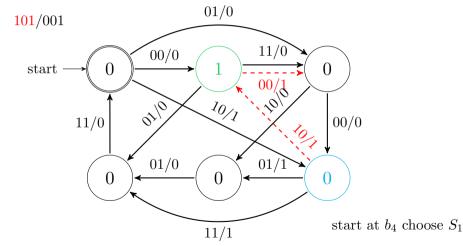
#### CSFSM Detection

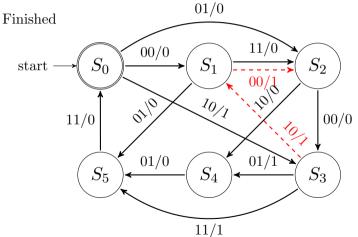
The detection of CSFSM is after the data is loaded and the graph is constructed, we run over each state the check if the out transitions span the whole possible inputs. If yes, the program will report that a CSFSM is detected.



9/19

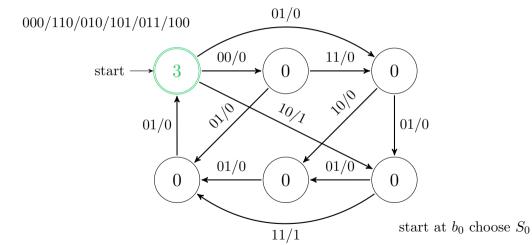


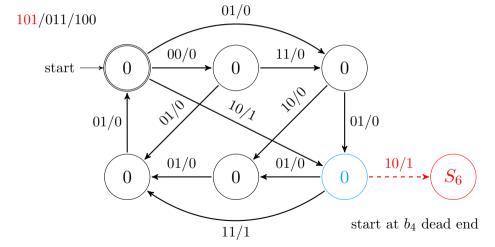


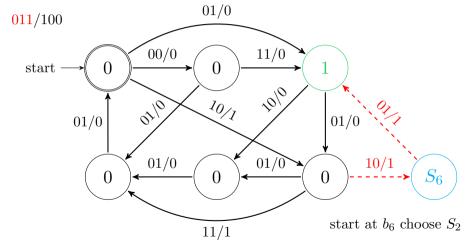


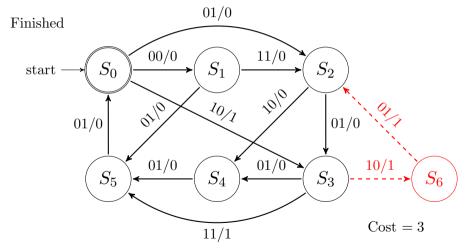
Cost = 2











#### Pseudocode

```
Algorithm 1 Watermark Part 1
1: G: Input FSM, (\Sigma, S, s_0, \delta, F)
2: b^i: Input bit string
3: b^o: Output bit string
4: j = 0, maxlen = 0, start = null, dest = null
5: while i \neq b^i.lenath - 1 do
       for each s in G.S.do
           m, d, j = \text{FindMaxLength}(s, b^i, b^o, j)
           if m \geq maxlen and d \neq null then
8:
              maxlen = m
g.
              dest = d
10.
           end if
11:
       end for
12:
```

```
Algorithm 2 Watermark Part 2
       if dest \neq null then
13:
14:
           AddTransition(start, dest, b_i^i, b_i^o)
15:
       else
           dest = SearchFreeTransition(G, b_i^i)
16:
           if dest \neq null then
17:
               AddNewState(dest, b_i^i, G)
18:
           else
19.
               RandomAddState(G)
20:
21:
               break
           end if
22:
23:
       end if
24:
       i = i + 1
25 end while
26: if i \neq b^i.lenath - 1 then
       Watermark(G, b^i, b^o)
28: end if
29: \mathbf{return}\ G
```

### Pseudocode

#### Algorithm 3 SearchFreeTransition

```
    G: Input FSM
    b<sup>i</sup><sub>j</sub>: Input bit string
    dest = null
    for each s in G.S do
    if b<sup>i</sup><sub>j</sub> ∉ s.outedges then
    dest = s
    break
```

9: end for

10: return dest

#### Algorithm 4 FindMaxLength

```
1: s: Input start state
```

- 2:  $b^i$ : Input bit string
- 3: b°: Output bit string
- 4: j: Current position of the bit string
- 5: tmp = j, d = null
- 6: while  $s.next(b_i^i) \neq null$  and  $j \neq b^i.length 1$  do
- $s', o = s.next(b_j^i)$
- 8: if  $o = b_i^o$  then
- 9: s = s'
- 10: d = s'
- 11: j = j + 1
- 12: end if
- 13: end while
- 14: if  $b_{i+1}^i \not\in s'$ . freetransitions then
- 15:  $\mathbf{return} \ 0, \ null, \ tmp$
- 16: **end if**
- 17: **return** j tmp, d, tmp



# Progress and Difficulties

We are still building the parser, dealing with the kiss format and loading into the C++ class to construct the graph. Some teamates start to implement the algorithm. The difficuties are that it's hard to work parallelly, one working on the algorithm needs to tell what data structure hw needs to the one works with the parser, and the situation changes dynamically.

We think we need a universal coding structure first, we should define all the functions and data structures we need to implement the algorithm, including the return and input types. Then, filling up the whole will be much more efficient for multiple workers.