Deep Learning for Computer Vision HW1 Report

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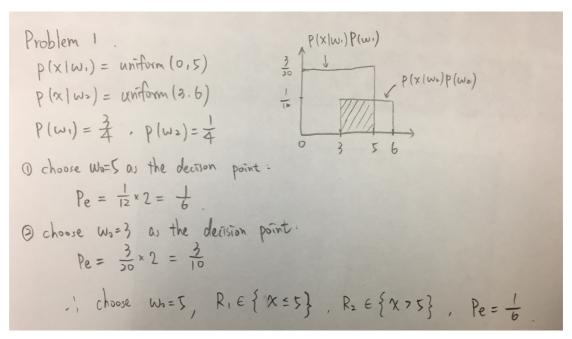
Problem 1 Bayes Decision Rule

For a 2-class problem based on an observable \mathbf{x} , in order to determine the decision region, by the decision rule mentioned in class, we have:

$$\omega^* = \operatorname*{argmax}_{i} P(\omega_i | x)$$

Meanwhile, we should minimize the error rate $P_e = \min \left(P(\omega_1|x), P(\omega_2|x) \right)$,

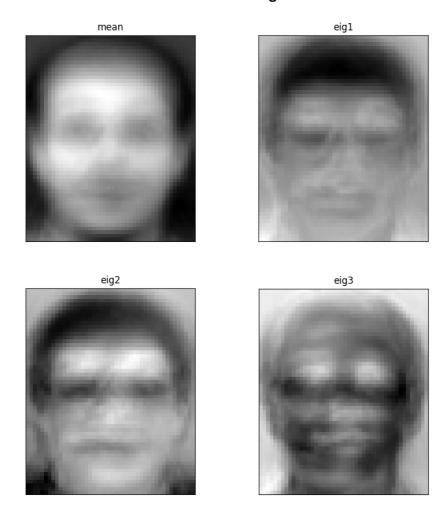
where
$$P(\omega_i|x) = \frac{P(x|\omega_i) \cdot P(\omega_i)}{P(x)}$$



$$P_e = \frac{1}{6}$$

Problem 2 PCA and KNN Classification

(a) Plot the mean face and the first three eigenfaces



(b) Plot the reconstructed images, with the corresponding MSE values.



n = 50, MSE = 213.263227244



n = 100, MSE = 81.9517802869



n = 239, MSE = 2.89831416384e-27



(c) Apply k-nearest neighbors classifier to recognize test set images, determine the best k and n values by 3-fold cross-validation. k = 1, 3, 5 and n = 3, 50, 159
 3-fold cross validation, validation set as first (1,2), (3,4), (5,6) pic of each class.
 (1,2):

```
k=1, n= 3, score=0.56250
k=1, n= 50, score=0.92500
k=1, n=159, score=0.92500
k=3, n= 3, score=0.46250
k=3, n= 50, score=0.82500
k=3, n=159, score=0.82500
k=5, n= 3, score=0.38750
k=5, n= 50, score=0.72500
k=5, n=159, score=0.72500
```

(3,4):

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k=1, n= 3, score=0.71250
k=1, n= 50, score=0.92500
k=1, n=159, score=0.93750
k=3, n= 3, score=0.61250
k=3, n= 50, score=0.86250
k=3, n=159, score=0.88750
k=5, n= 3, score=0.52500
k=5, n= 50, score=0.80000
k=5, n=159, score=0.78750
```

(5,6):

```
k=1, n= 3, score=0.76250
k=1, n= 50, score=0.92500
k=1, n=159, score=0.93750
k=3, n= 3, score=0.62500
k=3, n= 50, score=0.87500
k=3, n=159, score=0.88750
k=5, n= 3, score=0.65000
k=5, n= 50, score=0.76250
k=5, n=159, score=0.75000
```

As the results shown, (k=1, n=159) is the best choice for the three cases. So, we choose hyperparameters k=1, n=159 to test on the testing set Recognition rate on testing set : 0.94375

Problem 3 Determine the first eigenvector

Using the Power Iteration method!

```
Problem 3.

Let A be the dxd symmetric matrix. Assume v_1, v_2, \dots, v_d are the associated eigenvectors, which are linearly independent and form a basis for \mathbb{R}^d. Then we choose an initial approximate x_0, we know that x_0 = c_1v_1 + c_2v_2 + \dots + c_d v_d. c_1.c_2 and are constants, c_1 \neq 0.

Next, create a sequence \{x_k\} in the rule of x_{k+1} = \frac{A \times h}{\|A \times h\|}.

x_1 = Ax_0 = c_1(Av_1) + c_2(Av_2) + \dots + c_d(Av_d)
x_2 = Ax_1 = A^2x_2

x_3 = Ax_4 = A^2x_4

x_4 = A^2x_4

x_5 = A^3x_6 = \lambda_1^3 \left[c_1v_1 + c_2\left(\frac{\lambda_2}{\lambda_1}\right)^k v_2 + \dots + c_d\left(\frac{\lambda_d}{\lambda_d}\right)^k v_d\right]

For each y_1 = x_1 + x_2 = x_1.

For each y_2 = x_1 + x_2 = x_1 + x_3 = x_4 + x_4 = x_4
```

Reference:

https://en.wikipedia.org/wiki/Power_iteration

http://zoro.ee.ncku.edu.tw/na/res/09-power_method.pdf

https://ccjou.wordpress.com/2010/11/02/power-遞迴法/

http://ergodic.ugr.es/cphys/LECCIONES/FORTRAN/power_method.pdf