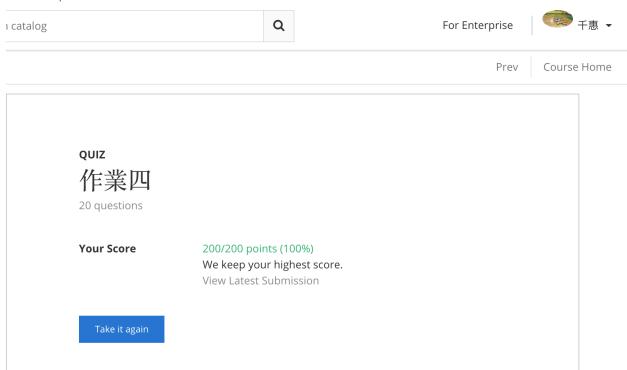
# Homework #4

Instructor: Hsuan-Tien Lin

資工三 B04902009 蕭千惠 17<sup>th</sup> January, 2018

### Problem 1

Score: 200 / 200



## Problem 2

$$E_{aug}(\mathbf{w}) = E_{in}(\mathbf{w}) + \frac{\lambda}{N} \mathbf{w}^{T} \mathbf{w}$$

$$\Rightarrow \nabla E_{aug}(\mathbf{w}) = \nabla E_{in}(\mathbf{w}) + \frac{2\lambda}{N} \mathbf{w}$$

$$\mathbf{w}(t+1) \leftarrow \mathbf{w}(t) - \eta \nabla E_{aug}(w)$$

$$\Rightarrow \mathbf{w}(t+1) \leftarrow \mathbf{w}(t) - \eta (\nabla E_{in}(\mathbf{w}) + \frac{2\lambda}{N} \mathbf{w})$$

$$\Rightarrow \mathbf{w}(t+1) \leftarrow (1 - \frac{2\eta\lambda}{N}) \mathbf{w}(t) - \eta \nabla E_{in}(\mathbf{w}(t))$$

### Problem 3

$$E_{aug}(\mathbf{w}) = E_{in}(\mathbf{w}) + \frac{\lambda}{N} \mathbf{w}^T \mathbf{w}$$

$$\|\mathbf{w}_{reg}(\lambda)\|^2 = \mathbf{w}^T \mathbf{w} = C$$

When 
$$\lambda = 0, \mathbf{w}_{reg}(\lambda) = \mathbf{w}_{lin} \Rightarrow \sqrt{C} = ||\mathbf{w}_{reg}(\lambda)|| = ||\mathbf{w}_{lin}||$$

Larger  $\lambda \Leftrightarrow \text{prefer shorter } \mathbf{w} \Leftrightarrow \text{effectively smaller } C$ 

$$\Rightarrow$$
 For any  $\lambda > 0, \sqrt{C} = \|\mathbf{w}_{reg}(\lambda)\| \le \|\mathbf{w}_{lin}\|$ 

## Problem 4

$$E_{loocv} = \frac{1}{3}(e_1 + e_2 + e_3)$$

1. Model: constant  $h_0(x) = b_0$ 

$$g_1^- = \frac{1}{2}$$
  $g_2^- = 0$   $g_3^- = \frac{1}{2}$ 

$$e_1 = err(g_1^-(-1), 0) = err(\frac{1}{2}, 0) = (\frac{1}{2})^2 = \frac{1}{4}$$

$$e_2 = err(g_2^-(-1), 1) = err(0, 1) = 1$$

$$e_3 = err(g_3^-(-1), 0) = err(\frac{1}{2}, 0) = (\frac{1}{2})^2 = \frac{1}{4}$$

$$\Rightarrow E_{loocv}(h_0) = \frac{1}{3}(\frac{1}{4} + 1 + \frac{1}{4}) = \frac{1}{2}$$

2. Model: linear  $h_1(x) = a_1 x + b_1$ 

$$g_1^- = \frac{1}{\rho - 1}x - \frac{1}{\rho - 1}$$
  $g_2^- = 0$   $g_3^- = \frac{1}{\rho + 1}x + \frac{1}{\rho + 1}$ 

$$g_2^- = 0$$
  $g_3^- =$ 

$$e_1 = err(g_1^-(-1), 0) = err(\frac{2}{\rho - 1}, 0) = (\frac{2}{\rho - 1})^2$$

$$e_2 = err(g_2^-(\rho), 1) = err(0, 1) = 1$$

$$e_3 = err(g_3^-(1), 0) = err(\frac{2}{\rho+1}, 0) = (\frac{2}{\rho+1})^2$$

$$\Rightarrow E_{loocv}(h_1) = \frac{1}{3}((\frac{2}{\rho - 1})^2 + 1 + (\frac{2}{\rho + 1})^2)$$

$$E_{loocv}(h_0) = E_{loocv}(h_1)$$

$$\Rightarrow \frac{1}{2} = \frac{1}{3}\left(\left(\frac{2}{\rho - 1}\right)^2 + 1 + \left(\frac{2}{\rho + 1}\right)^2\right)$$

$$\Rightarrow \rho = \sqrt{9 + 4\sqrt{6}}$$

#### Problem 5

$$E_{in}(\mathbf{w}_{lin}) = \min_{\mathbf{w}} \frac{1}{N+K} \left( \sum_{n=1}^{N} (y_n - \mathbf{w}^T \mathbf{x}_n) + \sum_{k=1}^{K} (\tilde{y}_k - \mathbf{w}^T \tilde{\mathbf{x}}_k) \right)$$

$$E_{in}(\mathbf{w}_{lin}) = \min_{\mathbf{w}} \frac{1}{N+K} [(\mathbf{w}^T \mathbf{X}^T \mathbf{X} \mathbf{w} + 2\mathbf{w}^T \mathbf{X}^T \mathbf{y} + \mathbf{y}^T \mathbf{y}) + (\mathbf{w}^T \tilde{\mathbf{X}}^T \tilde{\mathbf{X}} \mathbf{w} + 2\mathbf{w}^T \tilde{\mathbf{X}}^T \tilde{\mathbf{y}} + \tilde{\mathbf{y}}^T \tilde{\mathbf{y}})]$$

$$\Rightarrow \nabla E_{in}(\mathbf{w}_{lin}) = \frac{2}{N+K} (\mathbf{X}^T \mathbf{X} \mathbf{w}_{lin} - \mathbf{X}^T \mathbf{y} + \tilde{\mathbf{X}}^T \tilde{\mathbf{X}} \mathbf{w}_{lin} - \tilde{\mathbf{X}}^T \tilde{\mathbf{y}}) = 0$$

$$\Rightarrow (\mathbf{X}^T \mathbf{X} + \tilde{\mathbf{X}}^T \tilde{\mathbf{X}}) \mathbf{w}_{lin} = \mathbf{X}^T \mathbf{y} + \tilde{\mathbf{X}}^T \tilde{\mathbf{y}}$$

$$\Rightarrow \mathbf{w}_{lin} = (\mathbf{X}^T \mathbf{X} + \tilde{\mathbf{X}}^T \tilde{\mathbf{X}})^{-1} (\mathbf{X}^T \mathbf{y} + \tilde{\mathbf{X}}^T \tilde{\mathbf{y}})$$

### Problem 6

$$\mathbf{w}_{lin} = (\mathbf{X}^T \mathbf{X} + \tilde{\mathbf{X}}^T \tilde{\mathbf{X}})^{-1} (\mathbf{X}^T \mathbf{y} + \tilde{\mathbf{X}}^T \tilde{\mathbf{y}})$$

$$\mathbf{w}_{reg} = \underset{\mathbf{w}}{\operatorname{argmin}} \frac{\lambda}{N} ||\mathbf{w}||^2 + \frac{1}{N} ||\mathbf{X} \mathbf{w} - \mathbf{y}||^2$$

$$\Rightarrow \frac{2\mathbf{w}_{reg}\lambda}{N} + \frac{2}{N} (\mathbf{X}^T \mathbf{X} \mathbf{w}_{reg} - \mathbf{X}^T \mathbf{y}) = 0$$

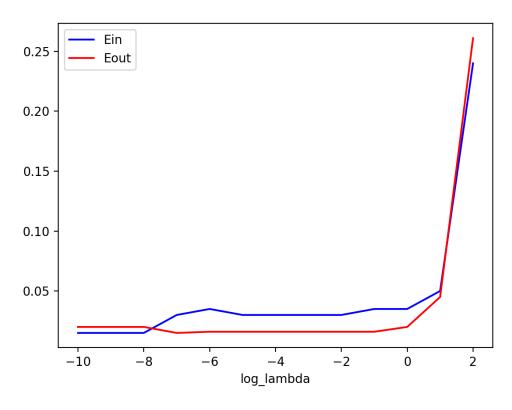
$$\Rightarrow (\lambda \mathbf{I} + \mathbf{X}^T \mathbf{X}) \mathbf{w}_{reg} - \mathbf{X}^T \mathbf{y} = 0$$

$$\Rightarrow \mathbf{w}_{reg} = (\mathbf{X}^T \mathbf{X} + \lambda \mathbf{I})^{-1} \mathbf{X}^T \mathbf{y}$$

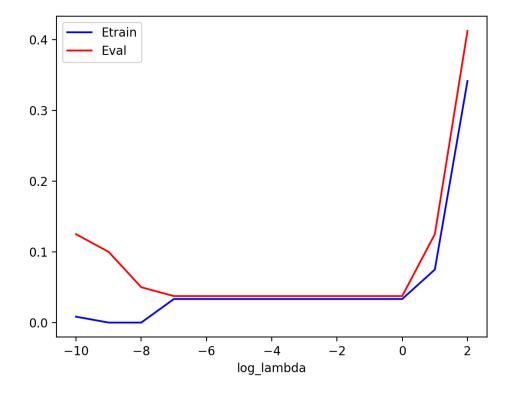
$$\mathbf{w}_{lin} = \mathbf{w}_{reg}$$

$$\Rightarrow \tilde{\mathbf{X}} = \sqrt{\lambda} \mathbf{I}, \tilde{\mathbf{v}} = 0$$

# Problem 7



# Problem 8



## Problem 9(Bonus)

(a)

1. Algorithm  $\mathcal{A}_{majority}$   $\begin{cases} g = +1 \text{ when the majority class is positive} \\ g = -1 \text{ when the majority class is negative} \end{cases}$   $E_{loocv}(\mathcal{A}_{majority}) = \frac{1}{2252} \sum_{i=1}^{2252} e_i = \frac{1}{2252} \sum_{i=1}^{2252} err(g_i^-, y_i)$   $\begin{cases} x_i > 0 \Rightarrow g_i^- = -1, & y_i = +1 \Rightarrow e_i = 1 \\ x_i < 0 \Rightarrow g_i^- = +1, & y_i = -1 \Rightarrow e_i = 1 \end{cases}$   $\Rightarrow E_{loocv}(\mathcal{A}_{majority}) = \frac{1}{2252} \sum_{i=1}^{2252} 1 = 1$ 

2. Algorithm  $\mathcal{A}_{minority}$ 

Let 
$$g \in \mathcal{A}_{minority}$$
, 
$$\begin{cases} g = +1 \text{ when the minority class is positive} \\ g = -1 \text{ when the minority class is negative} \end{cases}$$

$$E_{loocv}(\mathcal{A}_{minority}) = \frac{1}{2252} \sum_{i=1}^{2252} e_i = \frac{1}{2252} \sum_{i=1}^{2252} err(g_i^-, y_i)$$

$$\begin{cases} x_i > 0 \Rightarrow g_i^- = +1, \ y_i = +1 \Rightarrow e_i = 0 \\ x_i < 0 \Rightarrow g_i^- = -1, \ y_i = -1 \Rightarrow e_i = 0 \end{cases}$$

$$\Rightarrow E_{loocv}(\mathcal{A}_{minority}) = \frac{1}{2252} \sum_{i=1}^{2252} 0 = 0$$

 $\Rightarrow \mathcal{A}_{minority}$  algorithm should be chosen if we use  $E_{loocv}$  for algorithm selection.

(b)

Let  $g \in \mathcal{A}_{average}$  predicts the average value within the data set that it sees.

$$E_{loocv}(\mathcal{A}_{average}) = \frac{1}{N} \sum_{i=1}^{N} e_{i} = \frac{1}{N} \sum_{i=1}^{N} err(g_{i}^{-}, y_{i})$$

$$\forall x_{i}, \begin{cases} y_{i} = x_{i} \\ g_{i}^{-} = \frac{N\bar{x} - x_{i}}{N - 1} \end{cases}$$

$$\Rightarrow err(g_{i}^{-}, y_{i}) = (x_{i} - \frac{N\bar{x} - x_{i}}{N - 1})^{2} = (\frac{N}{N - 1}(x_{i} - \bar{x}))^{2}$$

$$\Rightarrow E_{loocv}(\mathcal{A}_{average}) = \frac{N^{2}}{(N - 1)^{2}} \sum_{i=1}^{N} \frac{(x_{i} - \bar{x})}{N} = \frac{N^{2}}{(N - 1)^{2}} \sum_{i=1}^{N} \frac{(y_{i} - \bar{y})}{N} = \frac{N^{2}}{(N - 1)^{2}} \text{Var} \left[ \{y_{n}\}_{n=1}^{N} \right]$$