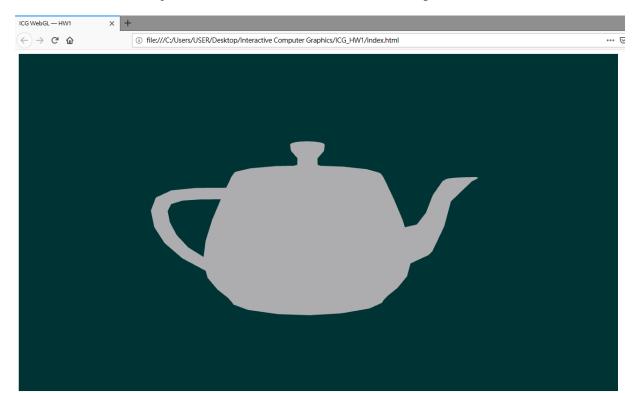
# ICG 2020 Spring Homework1 Guidance 2020/03/31

網媒所碩二 周家宇

#### **Environment Setup**

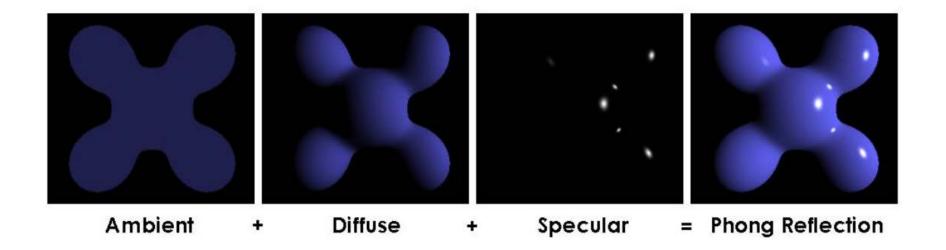
- Download sample code from course website
- ► Follow steps in HW1\_Guide.pdf file



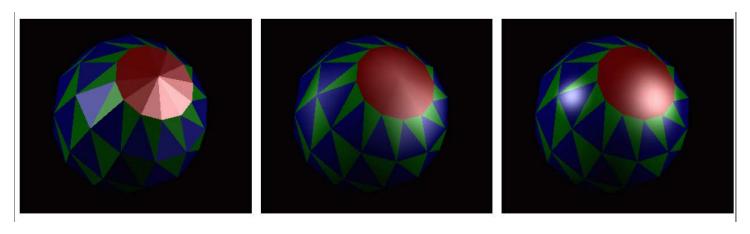
#### Requirements (Due to 2020/05/12)

- Implement Flat, Gouraud, and Phong shading with Phong reflection model in shaders.
- ► Enable multiple transformations (four fundamental transformations) on objects in a scene. You are free to use those provided model files and arrange them to form the scene on your own style.
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- Bonus: Special effects on shading / lighting / animation, ...

#### Phong Reflection Model

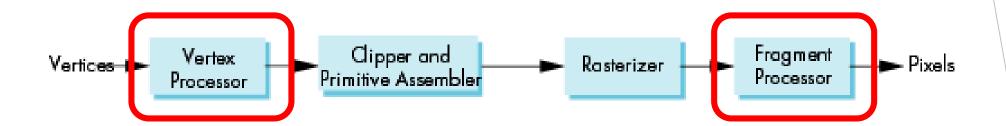


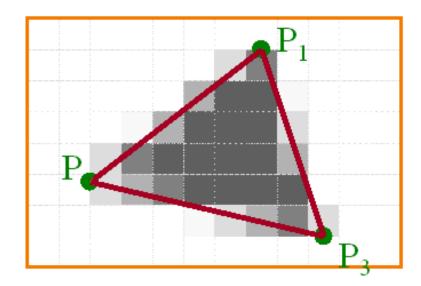
#### Shading



- ► Flat Shading: Constant normal on the whole surface
- Gouraud Shading: Different vertex normal, interpolated vertex color on a fragment
- Phong Shading: Different vertex normal, interpolated vertex normal on a fragment

#### Rendering Pipeline





#### Graphics API & Shader Language

Graphics API	Shader Language
OpenGL / WebGL	GLSL (OpenGL Shading Language)
DirectX	HLSL (High Level Shading Language)
Vulkan	SPIR-V

#### Shader (GLSL)

#### Shader Data (1/2)

```
<script id="vertexShader" type="vertex">
       attribute vec3 aVertexPosition;
36
       attribute vec3 aFrontColor;
38
       uniform mat4 uMVMatrix;
       uniform mat4 uPMatrix;
40
41
       varying vec4 fragcolor;
43
       void main(void) {
            fragcolor = vec4(aFrontColor.rgb, 1.0);
            gl_Position = uPMatrix * uMVMatrix * vec4(aVertexPosition, 1.0);
46
   </script>
```

#### Shader Data (2/2)

#### **SHADER DATA**

"Per-object constant"

#### **Uniform**

= Shared Constant

Vertex Data = ANYTHING YOU WANT!

Example?

Positions...

Normals...

Colors...

**Texture Coordinates...** 

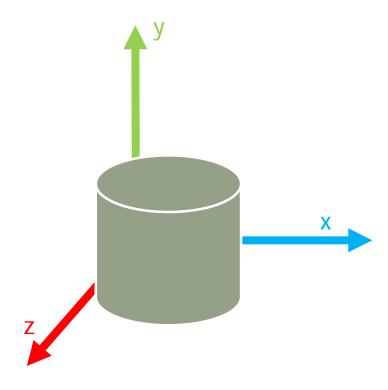
#### **Load Models**

▶ 已經將大部分課程網的 tri 模型轉成 json 檔

#### Example Csie.json

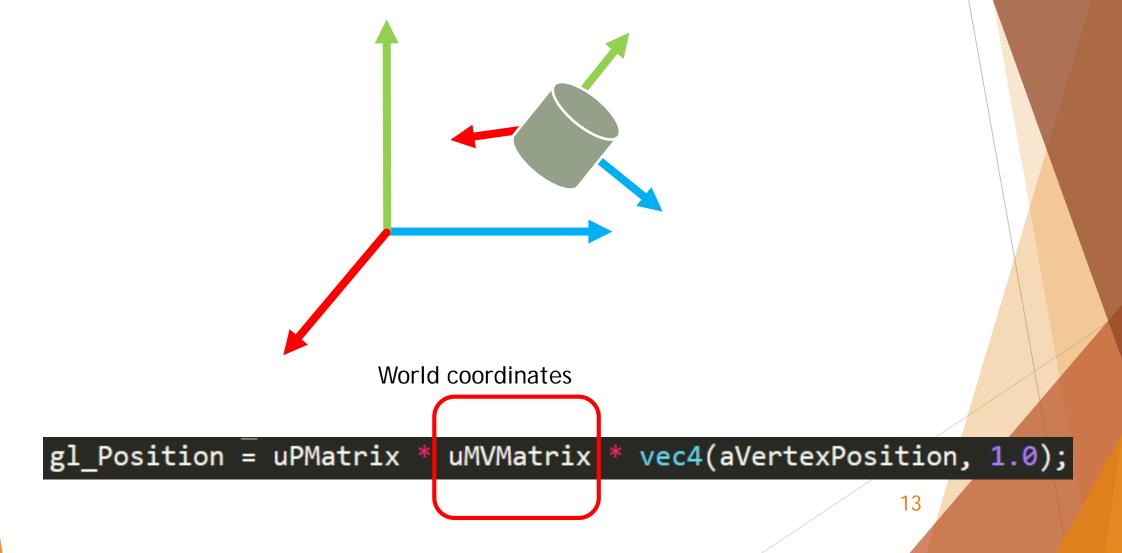
```
1 {
2     "vertexPositions" : [0.85,0.6471428571428571,0.0571428
3     "vertexNormals" : [0.000000,1.0000000,0.0000000,0.0000000
4     "vertexFrontcolors" : [1.0,1.0,1.0,1.0,1.0,1.0,1.0,1.0,1.0
5     "vertexBackcolors" : [0.9803921568627451,0.0,0.0,0.980
6 }
```

#### World transform



Model coordinates

#### World transform



## World transform Camera coordinates gl\_Position = uPMatrix uMVMatrix \* vec4(aVertexPosition, 1.0); 14

#### **Transformations**

- ► Fundamental Transformations:
  - ► Translation · Scale · Rotation · Shear
  - Order of matrix multiplication may affect final result
- ► Homogeneous Coordinates

Matrix x Vertex (in this order !!) = TransformedVertex

$$\begin{bmatrix} a & b & c & d \\ e & f & g & h \\ i & j & k & l \\ m & n & o & p \end{bmatrix} \times \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = \begin{bmatrix} ax + by + cz + dw \\ ex + fy + gz + hw \\ ix + jy + kz + lw \\ mx + ny + oz + pw \end{bmatrix}$$

#### **Translation**

These are the most simple tranformation matrices to understand. A translation matrix look like this:

$$\begin{bmatrix} 1 & 0 & 0 & X \\ 0 & 1 & 0 & Y \\ 0 & 0 & 1 & Z \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

where X,Y,Z are the values that you want to add to your position.

So if we want to translate the vector (10,10,10,1) of 10 units in the X direction, we get :

$$\begin{bmatrix} 1 & 0 & 0 & 10 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} * \begin{bmatrix} 10 \\ 10 \\ 10 \\ 1 \end{bmatrix} = \begin{bmatrix} 1*10+0*10+0*10+0*1 \\ 0*10+1*10+0*10+0*1 \\ 0*10+0*10+0*10+1*1 \end{bmatrix} = \begin{bmatrix} 10+0+0+10 \\ 0+10+0+0 \\ 0+0+10+0 \\ 0+0+0+1 \end{bmatrix} = \begin{bmatrix} 20 \\ 10 \\ 10 \\ 1 \end{bmatrix}$$

#### Scale

$$\begin{bmatrix} x & 0 & 0 & 0 \\ 0 & y & 0 & 0 \\ 0 & 0 & z & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

So if you want to scale a vector (position or direction, it doesn't matter) by 2.0 in all directions :

$$\begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = \begin{bmatrix} 2*x+0*y+0*z+0*w \\ 0*x+2*y+0*z+0*w \\ 0*x+0*y+2*z+0*w \\ 0*x+0*y+0*z+1*w \end{bmatrix} = \begin{bmatrix} 2*x+0+0+0 \\ 0+2*y+0+0 \\ 0+0+2*z+0 \\ 0+0+0+1*w \end{bmatrix} = \begin{bmatrix} 2*x \\ 2*y \\ 0*z \\ w \end{bmatrix}$$

#### Rotate

$$R_x(\theta) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & -\sin \theta \\ 0 & \sin \theta & \cos \theta \end{bmatrix}$$

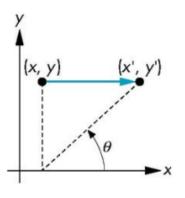
$$R_y(\theta) = \begin{bmatrix} \cos \theta & 0 & \sin \theta \\ 0 & 1 & 0 \\ -\sin \theta & 0 & \cos \theta \end{bmatrix}$$

$$R_z(\theta) = \begin{bmatrix} \cos \theta & -\sin \theta & 0\\ \sin \theta & \cos \theta & 0\\ 0 & 0 & 1 \end{bmatrix}$$

#### Shear

#### Consider simple shear along *x* axis

$$\mathbf{H}(\mathbf{\theta}) = \begin{bmatrix} 1 & \cot \theta & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



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#### Result Example





#### Reference

- https://webglfundamentals.org/
- http://learningwebgl.com/blog/?page\_id=1217
- https://learnopengl.com/

#### **TA Hours**

- ▶ 周家宇 (CSIE R505)
  - r07944038@csie.ntu.edu.tw
  - ► Thursday 14:00 ~ 16:00
- ▶ 李建德 (CSIE R506)
  - r08922180@ntu.edu.tw
  - ► Tuesday 15:00 ~ 17:00

### Q&A