

Homework Assignment 009 (2020)

Matrix and Vector Algebra

Create a Win application project named as < student ID><your name>Ass009. Remember to rename your Form1.cs file to having a meaningful class name. The form class is used as a user interface to test the functionalities of your matrix and vector class.

Define a utility class (namely, e.g., MatrixAndVector) for operations of matrix and vector algebra. Provide the following functions:

static public string VectorString(double[] vector): returns a string for displaying the vector.

static public string MatrixString(double[,] matrix): returns a string for displaying the matrix, rows are separated with escape character `\n`.

static public double[] ToVector(string vectorString): returns a double array from a string, where elements are separated with blank space character.

static public double[,] ToMatrix(string matrixString): returns a two dimensional array from a string where rows of the matrix are separated with the escape character `\n`.

static public double[,] ToMatrix(string[] rowStrings): returns a two dimensional array from an array of string, where each string is a row vector with elements separated with blank space characters.

static public double Norm(double[] vector): calculates the norm of a given vector.

static public double[] Addition(double[] v1, double[] v2): returns the addition of two vectors

static public double[] Subtraction(double[] v1, double[] v2): calculates the subtraction of two vectors.

static public double InnerProduct(double[] v1, double[] v2): calculates the inner product of two vectors.

static public double[] UnitVector(double[] vector): returns the unit vector of a given vector.

static public double[,] Addition(double[,] m1, double[,] m2): calculates the addition of two matrices in the same dimension.

static public double[,] Subtraction(double[,] m1, double[,] m2):

calculates the subtraction of two matrices in the same dimension.

static public double[,] Multiplication(double[,] m1, double[,] m2): calculates the product of two matrices that share the same inner dimension. For example

$$A_{(m \times n)} \cdot B_{(n \times p)} = C_{(m \times p)}. \text{ Mathematically, } C_{(m \times p)} = [c_{i,j}]_{(m \times p)} \quad c_{i,j} = \sum_{k=1}^n a_{i,k} \cdot b_{k,j}, i=1,2,\dots,m; j=1,2,\dots,p.$$

static public double[,] TransposedMatrix(double[,] matrix): returns the transpose matrix from a given matrix.

static public double Determinant(double[,] matrix): calculates the determinant (行列式) of a square matrix. (The dimension should be smaller or equal to 3, for now.)

static public double[] MatrixTimeVector (double[,] matrix, double[] columnVector): returns the resulting vector from a multiplication of a matrix and a (column) vector. Note that the column dimension of the matrix must be equal to the dimension of the

vector. Mathematically, $A_{(m \times n)} \cdot \mathbf{v}_{(n \times 1)} = \mathbf{u}_{(m \times 1)}$; $A_{(m \times n)} = [a_{i,j}]_{(m \times n)}$; $\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$, $\mathbf{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_m \end{bmatrix}$, and then

$$u_i = \sum_{k=1}^n a_{i,k} \cdot v_k, i=1,2,\dots,m$$

static public double[] VectorTimeMatrix(double[] rowVector, double[,] matrix): returns the resulting vector of a multiplication of a (row) vector and a matrix. Note that the row dimension of the matrix must be equal to the dimension of the vector.

Mathematically, $\mathbf{v}_{(1 \times m)} A_{(m \times n)} = \mathbf{u}_{(1 \times n)}$; $A_{(m \times n)} = [a_{i,j}]_{(m \times n)}$; $\mathbf{v} = [v_1 v_2 \dots v_m]$, $\mathbf{u} = [u_1 u_2 \dots u_n]$, and then

$$u_j = \sum_{i=1}^m v_i \cdot a_{i,j}, j=1,2,\dots,n$$

In your form class, provide input UIs, command UIs, and display UIs for the user to specify values of vectors and matrices to test each function of your vector & matrix class. To facilitate the functionality test, you can define data fields of vectors and matrices and hard code them in your form class.

For example:

```
double[] vector1 = { -2, 2, 1, -1 };
double[] vector2 = { 1, 2, 3, 4 };
double[,] matrix1 = { { 1, 2, 3, 4 }, { 4, 3, 2, 1 }, { -1, 2, 3, 0 }, { 1, -1, -2, 3 } };
double[,] matrix2 = { { 4, 1, 3, -1 }, { -2, 3, -1, 4 }, { 3, 2, -3,
```

```

1 }, { 2, 3, -1, 2 } };

double[,] matrix3 = { { 1, 0, -1, 2 }, { 3, -1, -2, 0 }, { 2, 1, 4,
3 } };

void initializeUserInterfaces()
{ } // Set value properties of controls from all vectors and matrices
void updateV1()
{ } // Set Vector1 from controls. Called before using V1.
void updateV2()
{ } // Set Vector2 from controls. Called before using V2.
void updateM1()
{ } // Set Matrix1 from controls. Called before using M1.
void updateM2()
{ } // Set Matrix2 from controls. Called before using M2.
void updateM3()
{ } // Set Matrix3 from controls. Called before using M3.

```

Snapshot of a sample application:

The application window, titled "Vector and Matrix Demo", displays the following data:

Control	Value
Vector 1	-2.00 2.00 1.00 -1.00
Vector 2	1.00 2.00 3.00 4.00
Matrix 1	1.00 2.00 3.00 4.00 4.00 3.00 2.00 1.00 -1.00 2.00 3.00 0.00 1.00 -1.00 -2.00 3.00
Matrix 2	4.00 1.00 3.00 -1.00 -2.00 3.00 -1.00 4.00 3.00 2.00 -3.00 1.00 2.00 3.00 -1.00 2.00
Matrix 3	1.00 0.00 -1.00 2.00 3.00 -1.00 -2.00 0.00 2.00 1.00 4.00 3.00

Computation Results:

- Norm of v1: 3.16227766016838
- Determinant of M1: 180
- Unit vector of v1: -0.63 0.63 0.32 -0.32
- Transpose of m3: 1.00 3.00 2.00 0.00 -1.00 1.00 -1.00 -2.00 4.00 2.00 0.00 3.00
- v1 + v2: -1.00 4.00 4.00 3.00
- M1*v1: 1.00 -1.00 9.00 -9.00
- M1*M2: 17.00 25.00 -12.00 18.00 18.00 20.00 2.00 12.00 1.00 11.00 -14.00 12.00 6.00 3.00 7.00 -1.00

Operation Buttons:

- Norm of V1
- Determinant of M1
- Unit Vector of V1
- Transpose of M3
- V1 + V2
- M1 + M2
- V1 - V2
- M1 x M2** (highlighted)
- V1 . V2
- M2 x M3
- V1 X V2
- M1 * V1
- V1 * M1

Appendix: Determinant

The determinant of a matrix of arbitrary size can be defined by the Leibniz formula or the Laplace formula. The Leibniz formula for the determinant of an $n \times n$ matrix A is

$$\det(A) = \sum_{\sigma \in S_n} \left(\operatorname{sgn}(\sigma) \prod_{i=1}^n a_{i, \sigma_i} \right)$$

Here the sum is computed over all permutations σ of the set $\{1, 2, \dots, n\}$. A permutation is a function that reorders this set of integers. The value in the i th position after the reordering σ is denoted by σ_i . For example, for $n = 3$, the original sequence 1, 2, 3 might be reordered to $\sigma = [2, 3, 1]$, with $\sigma_1 = 2$, $\sigma_2 = 3$, and $\sigma_3 = 1$. The set of all such permutations (also known as the symmetric group on n elements) is denoted by S_n . For each permutation σ , $\operatorname{sgn}(\sigma)$ denotes the signature of σ , a value that is $+1$ whenever the reordering given by σ can be achieved by successively interchanging two entries an even number of times, and -1 whenever it can be achieved by an odd number of such interchanges.

2x2 matrices:

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$

3x3 matrices:

$$\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = a \begin{vmatrix} e & f \\ h & i \end{vmatrix} - b \begin{vmatrix} d & f \\ g & i \end{vmatrix} + c \begin{vmatrix} d & e \\ g & h \end{vmatrix} = aei + bfg + cdh - ceg - bdi - afh$$

4x4 matrices:

$$\begin{vmatrix} a & b & c & d \\ e & f & g & h \\ i & j & k & l \\ m & n & o & p \end{vmatrix} = a \begin{vmatrix} f & g & h \\ j & k & l \\ n & o & p \end{vmatrix} - b \begin{vmatrix} e & g & h \\ i & k & l \\ m & o & p \end{vmatrix} + c \begin{vmatrix} e & f & h \\ i & j & l \\ m & n & p \end{vmatrix} - d \begin{vmatrix} e & f & g \\ i & j & k \\ m & n & o \end{vmatrix}$$