Human Face Generator using GANs

This project implements a Generative Adversarial Network (GAN) to generate realistic human faces. GANs consist of two neural networks, a Generator and a Discriminator, that are trained together to create images that become increasingly realistic over time.

Import Modules

```
import os
import numpy as np
import matplotlib.pyplot as plt
import warnings
from tgdm.notebook import tgdm
from PIL import Image
import tensorflow as tf
from tensorflow import keras
from tensorflow.keras.preprocessing.image import load img,
array to img
from tensorflow.keras.models import Sequential, Model
from tensorflow.keras import layers
from tensorflow.keras.optimizers import Adam
from tensorflow.keras.losses import BinaryCrossentropy
warnings.filterwarnings('ignore')
2024-06-17 17:52:06.825962: E
external/local xla/xla/stream executor/cuda/cuda dnn.cc:9261] Unable
to register cuDNN factory: Attempting to register factory for plugin
cuDNN when one has already been registered
2024-06-17 17:52:06.826071: E
external/local xla/xla/stream executor/cuda/cuda fft.cc:607] Unable to
register cuFFT factory: Attempting to register factory for plugin
cuFFT when one has already been registered
2024-06-17 17:52:06.959981: E
external/local xla/xla/stream executor/cuda/cuda blas.cc:1515] Unable
to register cuBLAS factory: Attempting to register factory for plugin
cuBLAS when one has already been registered
```

Load the files from kaggle 50k-celebrity-faces-imagedataset of 50k human faces

```
BASE_DIR =
'/kaggle/input/50k-celebrity-faces-image-dataset/Celebrity_Faces_Datas
et'
```

```
image_paths = []
for image_name in os.listdir(BASE_DIR):
    image_path = os.path.join(BASE_DIR, image_name)
    image_paths.append(image_path)

len(image_paths)

50000
```

Visualize the Image

```
plt.figure(figsize=(20, 20))
temp_images = image_paths[:49]
index = 1

for image_path in temp_images:
    plt.subplot(7, 7, index)
    img = Image.open(image_path)
    img = img.crop((0, 20, 178, 198))
    img = img.resize((64, 64))
    img = np.array(img)
    plt.imshow(img)
    plt.axis('off')
    index += 1
```



Preprocess Images like loading, croping, normalizing

```
def load_and_preprocess_real_images(image_path, target_size=(64, 64)):
    img = Image.open(image_path)
    img = img.crop((0, 20, 178, 198))
    img = img.resize(target_size)
    img = (np.array(img)-127.5)/127.5
    return img

train_images = [load_and_preprocess_real_images(path) for path in
tqdm(image_paths)]
train_images = np.array(train_images)
```

```
 \label{local_id} $$ \{ $$ model_id": "2e153a9d949b47b28d1826d6943b4b79", "version_major": 2, "version_minor": 0 \} $$
```

Define Constants for Model Configuration

- 1. **LATENT_DIM**: This constant defines the dimensionality of the latent space, which is set to 200. The latent space is typically used in generative models like GANs (Generative Adversarial Networks)
- 2. **WEIGHT_INIT**: This constant specifies the weight initialization method for the neural network layers. Here, the weights are initialized using a normal distribution with a mean of 0.0 and a standard deviation of 0.02. This type of initialization is often used to stabilize the training of deep neural networks.
- 3. **CHANNELS**: This constant defines the number of channels in the input data. For example, in the case of RGB images, the number of channels is 3

```
LATENT_DIM = 200
WEIGHT_INIT = keras.initializers.RandomNormal(mean=0.0, stddev=0.02)
CHANNELS = 3
```

Define the Generator Model

This section defines a generator model using the **Sequential** API from Keras. The model is designed to generate images from random noise.

```
model = Sequential(name='generator1')
model.add(layers.Dense(8 * 8 * 512, input_dim=LATENT_DIM))
model.add(layers.ReLU())
model.add(layers.Reshape((8, 8, 512)))
model.add(layers.Conv2DTranspose(256, (4, 4), strides=(2, 2), padding='same', kernel_initializer=WEIGHT_INIT))
model.add(layers.ReLU())
model.add(layers.Conv2DTranspose(128, (4, 4), strides=(2, 2), padding='same', kernel_initializer=WEIGHT_INIT))
model.add(layers.ReLU())
model.add(layers.Conv2DTranspose(64, (4, 4), strides=(2, 2), padding='same', kernel_initializer=WEIGHT_INIT))
model.add(layers.ReLU())
model.add(layers.ReLU())
model.add(layers.Conv2D(CHANNELS, (4, 4), padding='same',
```

```
activation='tanh'))
generator1 = model
generator1.summary()
Model: "generator1"
Layer (type)
                                Output Shape
Param #
dense (Dense)
                                 (None, 32768)
6,586,368
 re_lu (ReLU)
                                 (None, 32768)
reshape (Reshape)
                                 (None, 8, 8, 512)
0 |
 conv2d transpose
                                 (None, 16, 16, 256)
2,097,408
 (Conv2DTranspose)
 re_lu_1 (ReLU)
                                 | (None, 16, 16, 256) |
0 |
 conv2d transpose 1
                                 (None, 32, 32, 128)
524,416
 (Conv2DTranspose)
 re_lu_2 (ReLU)
                                 (None, 32, 32, 128)
0 |
conv2d_transpose_2
                                 (None, 64, 64, 64)
131,136
 (Conv2DTranspose)
```

Define the Discriminator Model

This section defines a discriminator model using the **Sequential** API from Keras. The model is designed to classify images as real or fake.

```
model = Sequential(name='discriminator1')
input shape = (64, 64, 3)
alpha = 0.2
model.add(layers.Conv2D(64, (4, 4), strides=(2, 2), padding='same',
input shape=input shape))
model.add(layers.BatchNormalization())
model.add(layers.LeakyReLU(alpha=alpha))
model.add(layers.Conv2D(128, (4, 4), strides=(2, 2), padding='same',
input shape=input shape))
model.add(layers.BatchNormalization())
model.add(layers.LeakyReLU(alpha=alpha))
model.add(layers.Conv2D(128, (4, 4), strides=(2, 2), padding='same',
input shape=input shape))
model.add(layers.BatchNormalization())
model.add(layers.LeakyReLU(alpha=alpha))
model.add(layers.Flatten())
model.add(layers.Dropout(0.3))
model.add(layers.Dense(1, activation='sigmoid'))
discriminator1 = model
discriminator1.summary()
Model: "discriminator1"
```

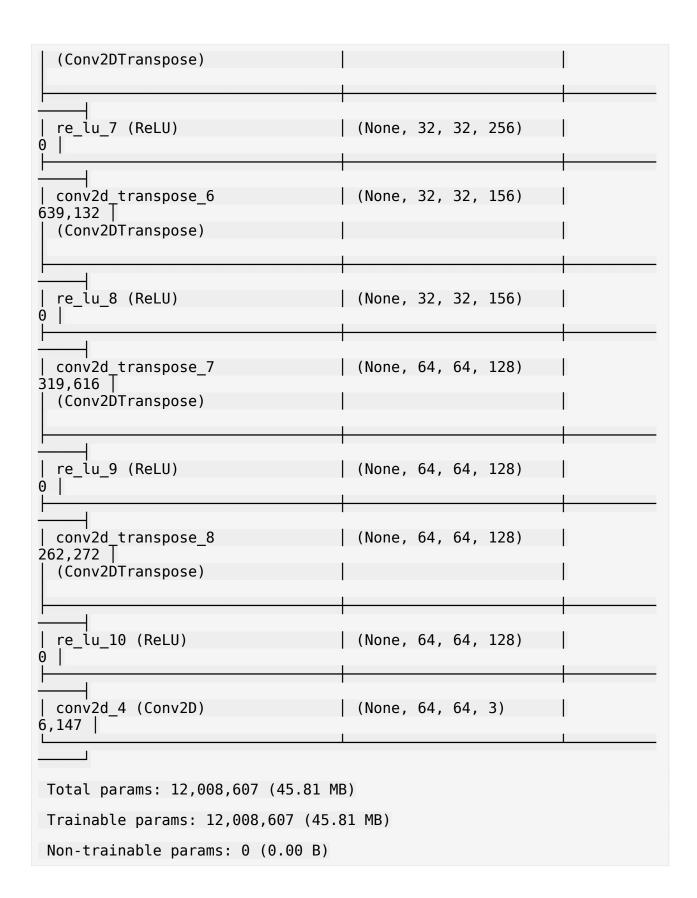
Layer (type) Param #	Output Shape
conv2d_1 (Conv2D) 3,136	(None, 32, 32, 64)
batch_normalization 256 (BatchNormalization)	(None, 32, 32, 64)
	(None, 32, 32, 64)
conv2d_2 (Conv2D)	(None, 16, 16, 128)
batch_normalization_1 512 (BatchNormalization)	(None, 16, 16, 128)
	(None, 16, 16, 128)
conv2d_3 (Conv2D) 262,272	(None, 8, 8, 128)
batch_normalization_2 512 (BatchNormalization)	(None, 8, 8, 128)
leaky_re_lu_2 (LeakyReLU)	(None, 8, 8, 128)
flatten (Flatten)	(None, 8192)

Define the Second Generator Model

This section defines a second generator model using the **Sequential** API from Keras. The model is designed to generate images from random noise, with additional convolutional layers compared to the first generator.

```
model = Sequential(name='generator2')
model.add(layers.Dense(8 * 8 * 512, input_dim=LATENT_DIM))
model.add(layers.ReLU())
model.add(layers.Reshape((8, 8, 512)))
model.add(layers.Conv2DTranspose(256, (4, 4), strides=(2, 2),
padding='same', kernel initializer=WEIGHT INIT))
model.add(layers.ReLU())
model.add(layers.Conv2DTranspose(256, (4, 4), strides=(1, 1),
padding='same', kernel initializer=WEIGHT INIT))
model.add(layers.ReLU())
model.add(layers.Conv2DTranspose(256, (4, 4), strides=(2, 2),
padding='same', kernel_initializer=WEIGHT_INIT))
model.add(layers.ReLU())
model.add(layers.Conv2DTranspose(156, (4, 4), strides=(1,1),
padding='same', kernel initializer=WEIGHT INIT))
model.add(layers.ReLU())
model.add(layers.Conv2DTranspose(128, (4, 4), strides=(2, 2),
padding='same', kernel initializer=WEIGHT INIT))
model.add(layers.ReLU())
model.add(layers.Conv2DTranspose(128, (4, 4), strides=(1, 1),
padding='same', kernel initializer=WEIGHT INIT))
```

```
model.add(layers.ReLU())
model.add(layers.Conv2D(CHANNELS, (4, 4), padding='same',
activation='tanh'))
generator2 = model
generator2.summary()
Model: "generator2"
                                  Output Shape
Layer (type)
Param #
                                 (None, 32768)
 dense 2 (Dense)
6,586,368
  re_lu_4 (ReLU)
                                  (None, 32768)
0
 reshape_1 (Reshape)
                                 (None, 8, 8, 512)
                                  (None, 16, 16, 256)
 conv2d transpose 3
2,097,408
 (Conv2DTranspose)
 re_lu_5 (ReLU)
                                 (None, 16, 16, 256)
 conv2d_transpose_4
                                  (None, 16, 16, 256)
1,048,832
 (Conv2DTranspose)
 re_lu_6 (ReLU)
                                 (None, 16, 16, 256)
conv2d_transpose_5
                                 (None, 32, 32, 256)
1,048,83\overline{2}
```

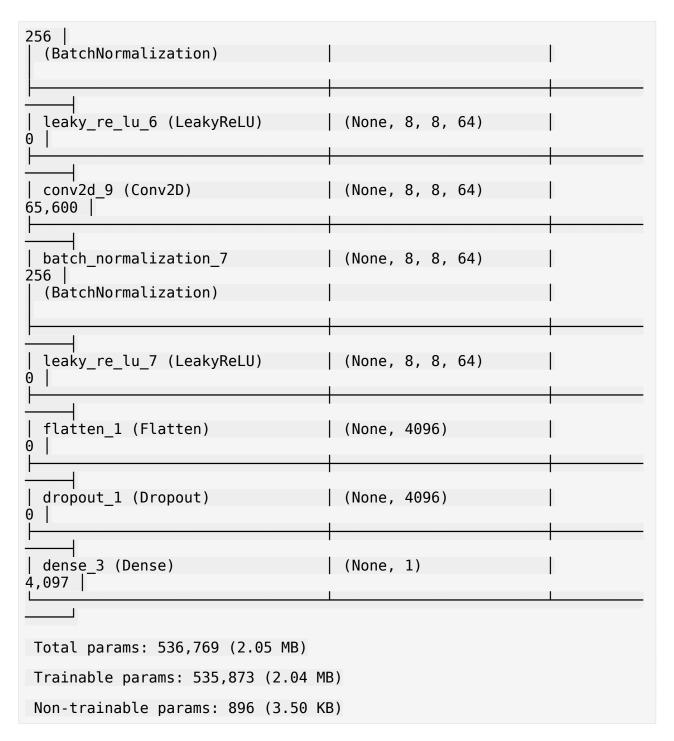


Define the Second Discriminator Model

This section defines a second discriminator model using the **Sequential** API from Keras. The model is designed to classify images as real or fake, with additional convolutional layers compared to the first discriminator.

```
model = Sequential(name='discriminator2')
input shape = (64, 64, 3)
alpha = 0.2
model.add(layers.Conv2D(128, (4, 4), strides=(2, 2), padding='same',
input shape=input shape))
model.add(layers.BatchNormalization())
model.add(layers.LeakyReLU(alpha=alpha))
model.add(layers.Conv2D(128, (4, 4), strides=(2, 2), padding='same',
input shape=input shape))
model.add(layers.BatchNormalization())
model.add(layers.LeakyReLU(alpha=alpha))
model.add(layers.Conv2D(64, (4, 4), strides=(1, 1), padding='same',
input shape=input shape))
model.add(layers.BatchNormalization())
model.add(layers.LeakyReLU(alpha=alpha))
model.add(layers.Conv2D(64, (4, 4), strides=(2, 2), padding='same',
input shape=input shape))
model.add(layers.BatchNormalization())
model.add(layers.LeakyReLU(alpha=alpha))
model.add(layers.Conv2D(64, (4, 4), strides=(1, 1), padding='same',
input shape=input shape))
model.add(layers.BatchNormalization())
model.add(layers.LeakyReLU(alpha=alpha))
model.add(lavers.Flatten())
model.add(layers.Dropout(0.3))
model.add(layers.Dense(1, activation='sigmoid'))
discriminator2 = model
discriminator2.summary()
Model: "discriminator2"
                                  Output Shape
Layer (type)
Param # |
```

1	<u> </u>
conv2d_5 (Conv2D) 6,272	(None, 32, 32, 128)
batch_normalization_3 512 (BatchNormalization)	(None, 32, 32, 128)
leaky_re_lu_3 (LeakyReLU)	(None, 32, 32, 128)
conv2d_6 (Conv2D) 262,272	(None, 16, 16, 128)
batch_normalization_4 512 (BatchNormalization)	(None, 16, 16, 128)
leaky_re_lu_4 (LeakyReLU)	(None, 16, 16, 128)
conv2d_7 (Conv2D) 131,136	(None, 16, 16, 64)
batch_normalization_5 256 (BatchNormalization)	(None, 16, 16, 64)
leaky_re_lu_5 (LeakyReLU)	(None, 16, 16, 64)
conv2d_8 (Conv2D) 65,600	(None, 8, 8, 64)
batch_normalization_6	(None, 8, 8, 64)



Define the DCGAN Model Class

This class implements a DCGAN model, including generator and discriminator models, custom training steps, and loss tracking. It supports compilation with optimizers and a loss function, and uses gradient tapes for backpropagation during training

```
class DCGAN(keras.Model):
    def init (self, generator, discriminator, latent dim):
        super().__init__()
        self.generator = generator
        self.discriminator = discriminator
        self.latent dim = latent dim
        self.g loss metric = keras.metrics.Mean(name='g loss')
        self.d loss metric = keras.metrics.Mean(name='d loss')
    @property
    def metrics(self):
        return [self.g_loss metric, self.d loss metric]
    def compile(self, g optimizer, d optimizer, loss fn):
        super(DCGAN, self).compile()
        self.g optimizer = g optimizer
        self.d optimizer = d optimizer
        self.loss fn = loss fn
    def train step(self, real images):
        batch size = tf.shape(real images)[0]
        random noise = tf.random.normal(shape=(batch size,
self.latent dim))
        with tf.GradientTape() as tape:
            pred real = self.discriminator(real images, training=True)
            real labels = tf.ones((batch size, 1))
            d loss real = self.loss fn(real labels, pred real)
            fake images = self.generator(random noise)
            pred fake = self.discriminator(fake images, training=True)
            fake_labels = tf.zeros((batch_size, 1))
            d_loss_fake = self.loss_fn(fake_labels, pred fake)
            d loss = d loss real + d loss fake
        gradients = tape.gradient(d loss,
self.discriminator.trainable variables)
        self.d optimizer.apply gradients(zip(gradients,
```

```
self.discriminator.trainable variables))
        labels = tf.ones((batch size, 1))
        with tf.GradientTape() as tape:
            fake images = self.generator(random noise, training=True)
            pred fake = self.discriminator(fake images, training=True)
            g loss = self.loss fn(labels, pred fake)
        gradients = tape.gradient(g loss,
self.generator.trainable variables)
        self.g_optimizer.apply_gradients(zip(gradients,
self.generator.trainable variables))
        self.d loss metric.update state(d loss)
        self.g loss metric.update state(g loss)
        return {'d loss': self.d loss metric.result(), 'g loss':
self.g loss metric.result()}
```

Define the DCGAN Monitor Callback

This callback monitors the training process of the DCGAN model, saving generated images and tracking loss values. It generates images at the end of each epoch and plots the discriminator and generator losses at the end of training.

```
class DCGANMonitor(keras.callbacks.Callback):
    def __init__(self, num_imgs=25, latent_dim=200):
        self.num_imgs = num_imgs
        self.latent_dim = latent_dim

    self.noise = tf.random.normal([25, latent_dim])
    self.d_losses = []
    self.g_losses = []
    self.d_losses_all=[]
    self.g_losses_all=[]
    self.total_loss = []
```

```
def on_epoch_end(self, epoch, logs=None):
        g img = self.model.generator(self.noise)
        g \text{ img} = (g \text{ img} * 127.5) + 127.5
        g img.numpy()
        self.d losses.append(logs['d loss'])
        self.g losses.append(logs['g loss'])
        self.total loss.append(logs['d loss']+logs['g loss'])
        if (epoch)%10 == 0:
            fig = plt.figure(figsize=(8, 8))
            for i in range(25):
                plt.subplot(5, 5, i+1)
                img = array_to_img(g_img[i])
                plt.imshow(img)
                plt.axis('off')
            plt.show()
    def on train end(self, logs=None):
        plt.figure(figsize=(10, 5))
        plt.plot(self.d losses, label='Discriminator Loss')
        plt.plot(self.g losses, label='Generator Loss')
        plt.xlabel('Epochs')
        plt.ylabel('Loss')
        plt.legend()
        plt.title('Discriminator and Generator Losses')
        plt.show()
        print(f"minimum value of d loss = {min(self.d losses)} for
epoch {self.d losses.index(min(self.d losses))}
        print(f"minimum value of g loss = {min(self.g losses)} for
       {self.g losses.index(min(self.g losses))}
epoch
        print(f"minimum value of total = {min(self.total loss)} for
epoch {self.total loss.index(min(self.total loss))}
        self.model.generator.save('generator final.h5')
```

DCGAN Initialization

The dcgan and dcgan2 model is initialized with generator1 and generator2 for image generation, discriminator1 and discriminator2 for image classification respectively, and a latent dimension of LATENT_DIM for random noise input.

```
dcgan = DCGAN(generator=generator1, discriminator=discriminator1,
latent_dim=LATENT_DIM)
```

```
dcgan2 = DCGAN(generator=generator2, discriminator=discriminator2,
latent_dim=LATENT_DIM)
```

Compile DCGAN Model

The dcgan model is compiled with Adam optimizers for the generator and discriminator (G_LR and D_LR learning rates, beta 1=0.5) and BinaryCrossentropy loss function.

```
D_LR = 0.0001
G_LR = 0.0003
dcgan.compile(g_optimizer=Adam(learning_rate=G_LR, beta_1=0.5),
d_optimizer=Adam(learning_rate=D_LR, beta_1=0.5),
loss_fn=BinaryCrossentropy())

D_LR = 0.0001
G_LR = 0.0003
dcgan2.compile(g_optimizer=Adam(learning_rate=G_LR, beta_1=0.5),
d_optimizer=Adam(learning_rate=D_LR, beta_1=0.5),
loss_fn=BinaryCrossentropy())
```

Train DCGAN Model

The dcgan model is trained for N_EPOCHS epochs using train_images data, with DCGANMonitor callback to visualize generated images and monitor losses during training.

```
N EPOCHS = 50
dcgan.fit(train images, epochs=N EPOCHS,
callbacks=[DCGANMonitor(DCGAN)])
Epoch 1/50
                       ----- 47s 30ms/step - d loss: 2.3296 -
   5/1563 -
g loss: 0.6535
WARNING: All log messages before absl::InitializeLog() is called are
written to STDERR
I0000 00:00:1718647148.171929 74 device compiler.h:186] Compiled
cluster using XLA! This line is logged at most once for the lifetime
of the process.
W0000 00:00:1718647148.194784
                                  74 graph launch.cc:671] Fallback to
op-by-op mode because memset node breaks graph update
                             - 0s 37ms/step - d loss: 1.8600 - g loss:
1563/1563 -
2.4383
```



1563/1563 ————— 77s 38ms/step - d_loss: 1.8596 - g_loss: 2.4383 Epoch 2/50

1563/1563 — 45s 29ms/step - d_loss: 1.1241 -

g_loss: 1.4399

Epoch 3/50

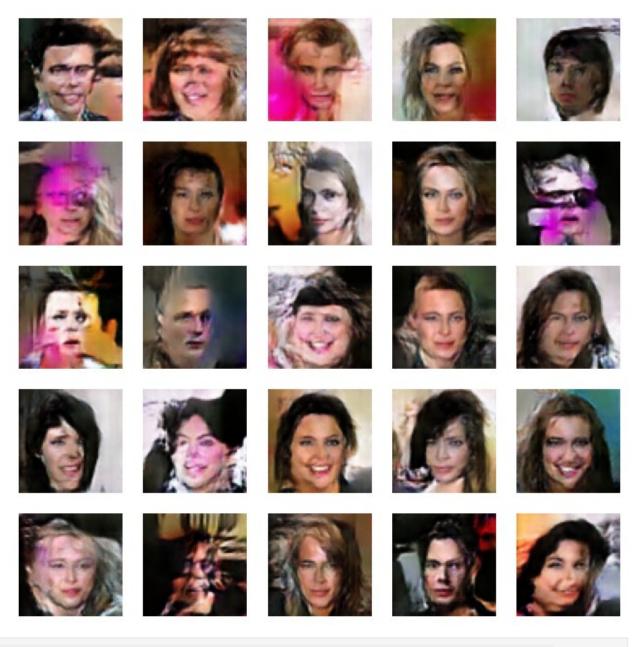
1563/1563 45s 29ms/step - d_loss: 1.2715 -

g_loss: 1.2816 Epoch 4/50

1563/1563 ———— 45s 29ms/step - d_loss: 1.4415 -

g_loss: 0.9326 Epoch 5/50

```
- 45s 29ms/step - d_loss: 1.4390 -
1563/1563 —
g loss: 0.8252
Epoch 6/50
                              - 46s 29ms/step - d loss: 1.4216 -
1563/1563 —
g loss: 0.7985
Epoch 7/50
1563/1563 -
                              - 45s 29ms/step - d loss: 1.4193 -
g loss: 0.7708
Epoch 8/50
                              - 45s 29ms/step - d loss: 1.4158 -
1563/1563 -
g_loss: 0.7562
Epoch 9/50
1563/1563 -
                              - 45s 29ms/step - d_loss: 1.4110 -
g loss: 0.7468
Epoch 10/50
1563/1563 -
                              - 45s 29ms/step - d_loss: 1.4062 -
g loss: 0.7456
Epoch 11/50
                              - 0s 29ms/step - d_loss: 1.4037 - g_loss:
1561/1563 -
0.7402
```



1563/1563 45s 29ms/step - d_loss: 1.4010 -

g_loss: 0.7371 Epoch 13/50

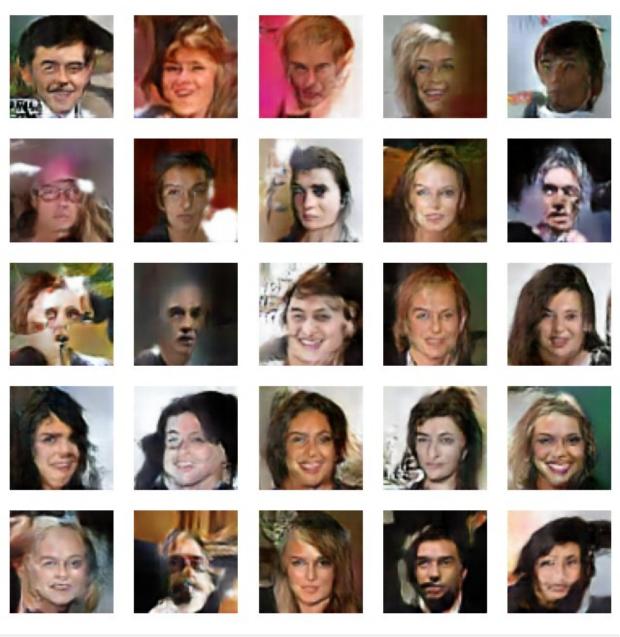
1563/1563 45s 29ms/step - d_loss: 1.3999 -

g_loss: 0.7364 Epoch 14/50

1563/1563 45s 29ms/step - d_loss: 1.3965 -

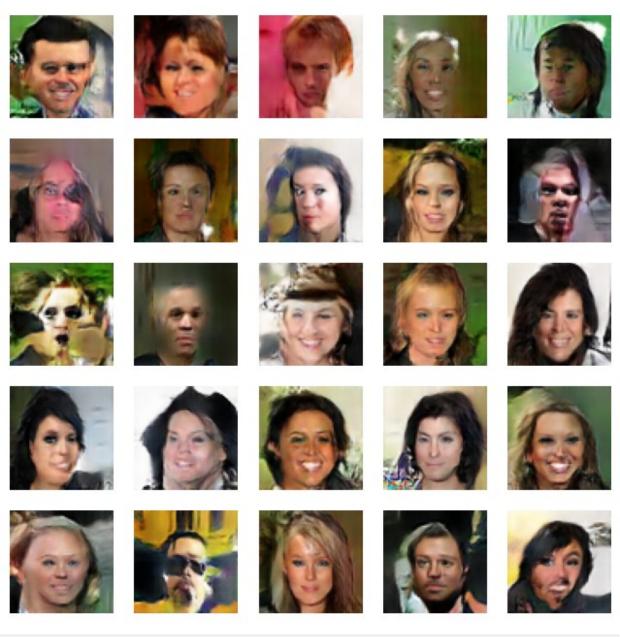
g_loss: 0.7374 Epoch 15/50

```
- 45s 29ms/step - d_loss: 1.3976 -
1563/1563 —
g loss: 0.7364
Epoch 16/50
                              - 45s 29ms/step - d loss: 1.3937 -
1563/1563 —
g loss: 0.7403
Epoch 17/50
1563/1563 -
                              - 45s 29ms/step - d loss: 1.3905 -
g loss: 0.7423
Epoch 18/50
                              - 82s 29ms/step - d loss: 1.3885 -
1563/1563 —
g_loss: 0.7414
Epoch 19/50
1563/1563 -
                              - 45s 29ms/step - d_loss: 1.3894 -
g loss: 0.7411
Epoch 20/50
1563/1563 -
                              - 45s 29ms/step - d_loss: 1.3848 -
g loss: 0.7481
Epoch 21/50
                              • Os 29ms/step - d loss: 1.3855 - g loss:
1561/1563 -
0.7456
```



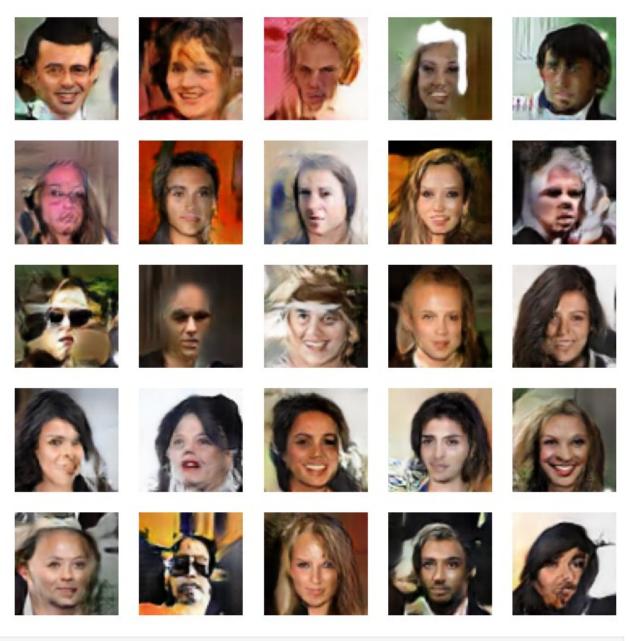
46s 30ms/step - d_loss: 1.3855 -1563/1563 — g_loss: 0.7456 Epoch 22/50 - 45s 29ms/step - d_loss: 1.3820 -1563/1563 g_loss: 0.7492 Epoch 23/50 - 45s 29ms/step - d_loss: 1.3791 -1563/1563 g loss: 0.7533 Epoch 24/50 **-** 45s 29ms/step - d_loss: 1.3767 -1563/1563 g_loss: 0.7556 Epoch 25/50

```
- 45s 29ms/step - d_loss: 1.3739 -
1563/1563 —
g loss: 0.7585
Epoch 26/50
                              - 45s 29ms/step - d loss: 1.3741 -
1563/1563 —
g loss: 0.7647
Epoch 27/50
1563/1563 -
                              - 45s 29ms/step - d loss: 1.3668 -
g loss: 0.7732
Epoch 28/50
                              - 45s 29ms/step - d loss: 1.3625 -
1563/1563 —
g_loss: 0.7830
Epoch 29/50
1563/1563 -
                              - 45s 29ms/step - d_loss: 1.3586 -
g loss: 0.7864
Epoch 30/50
1563/1563 -
                              - 45s 29ms/step - d_loss: 1.3543 -
g loss: 0.7996
Epoch 31/50
                              • Os 29ms/step - d loss: 1.3478 - g loss:
1561/1563 -
0.8095
```



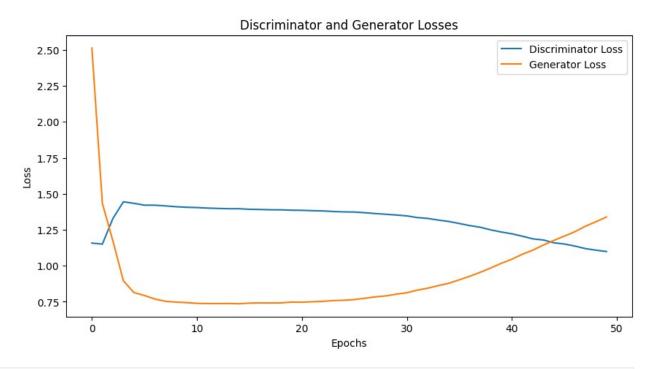
46s 29ms/step - d_loss: 1.3478 -1563/1563 — g_loss: 0.8095 Epoch 32/50 - 45s 29ms/step - d_loss: 1.3360 -1563/1563 g_loss: 0.8264 Epoch 33/50 - 45s 29ms/step - d_loss: 1.3291 -1563/1563 g loss: 0.8415 Epoch 34/50 **-** 45s 29ms/step - d_loss: 1.3205 -1563/1563 g_loss: 0.8585 Epoch 35/50

```
- 45s 29ms/step - d_loss: 1.3070 -
1563/1563 —
g loss: 0.8756
Epoch 36/50
                              - 45s 29ms/step - d loss: 1.2975 -
1563/1563 —
g loss: 0.8965
Epoch 37/50
1563/1563 -
                              - 45s 29ms/step - d loss: 1.2818 -
g loss: 0.9226
Epoch 38/50
                              - 45s 29ms/step - d loss: 1.2720 -
1563/1563 —
g loss: 0.9516
Epoch 39/50
1563/1563 -
                              - 45s 29ms/step - d_loss: 1.2509 -
g loss: 0.9812
Epoch 40/50
1563/1563 -
                              - 82s 29ms/step - d_loss: 1.2326 -
g loss: 1.0126
Epoch 41/50
                              - 0s 29ms/step - d_loss: 1.2168 - g_loss:
1561/1563 -
1.0437
```



1563/1563 **—** 46s 29ms/step - d_loss: 1.2168 g_loss: 1.0437 Epoch 42/50 - 45s 29ms/step - d_loss: 1.2070 -1563/1563 g_loss: 1.0681 Epoch 43/50 - 45s 29ms/step - d_loss: 1.1841 -1563/1563 g loss: 1.1022 Epoch 44/50 **-** 45s 29ms/step - d_loss: 1.1787 -1563/1563 g_loss: 1.1412 Epoch 45/50

```
1563/1563 -
                              - 45s 29ms/step - d_loss: 1.1627 -
g loss: 1.1679
Epoch 46/50
1563/1563 —
                               45s 29ms/step - d loss: 1.1435 -
g_loss: 1.2033
Epoch 47/50
                               45s 29ms/step - d loss: 1.1371 -
1563/1563 -
g loss: 1.2283
Epoch 48/50
1563/1563 -
                               45s 29ms/step - d loss: 1.1187 -
g loss: 1.2710
Epoch 49/50
1563/1563 -
                               45s 29ms/step - d_loss: 1.1071 -
g loss: 1.2996
Epoch 50/50
1563/1563 -
                               45s 29ms/step - d loss: 1.0970 -
g loss: 1.3307
```



```
minimum value of d_loss = 1.099036693572998 for epoch 49
minimum value of g_loss = 0.7358095645904541 for epoch 14
minimum value of total = 2.130660891532898 for epoch 17

<keras.src.callbacks.history.History at 0x7ac52b5dbeb0>

N_EPOCHS = 50
dcgan2.fit(train_images, epochs=N_EPOCHS,
callbacks=[DCGANMonitor(DCGAN)])
```

Epoch 1/50

2/1563 — 2:23 92ms/step - d_loss: 2.0665 -

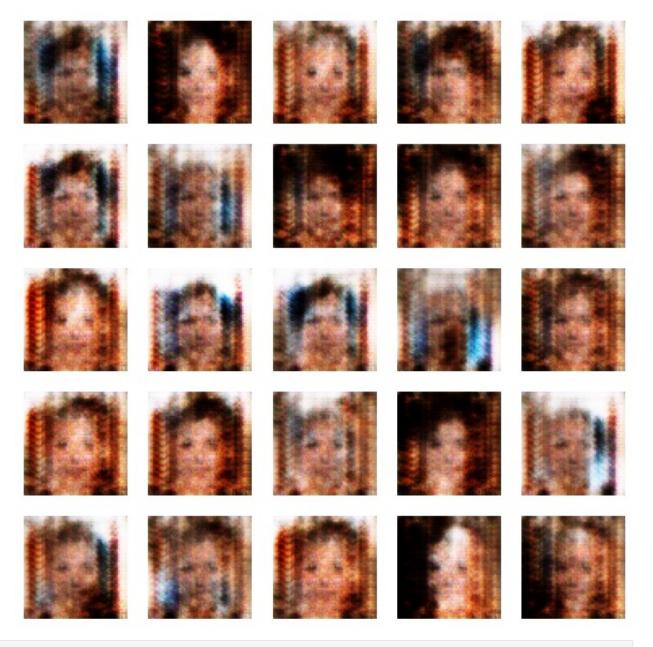
g_loss: 1.0457

W0000 00:00:1718649540.017232 73 graph_launch.cc:671] Fallback to

op-by-op mode because memset node breaks graph update

1563/1563 ———— Os 101ms/step - d_loss: 2.5843 -

g_loss: 1.1827



1563/1563 _____ 188s 102ms/step - d_loss: 2.5838 -

g loss: 1.1827

```
Epoch 2/50
1563/1563 -
                              - 141s 90ms/step - d loss: 1.4487 -
g loss: 0.8069
Epoch 3/50
1563/1563 -
                              - 141s 90ms/step - d loss: 1.4332 -
g loss: 0.7721
Epoch 4/50
1563/1563 -
                              - 141s 90ms/step - d loss: 1.4249 -
g loss: 0.7398
Epoch 5/50
1563/1563 -
                              - 142s 91ms/step - d_loss: 1.4103 -
g_loss: 0.7455
Epoch 6/50
                              - 143s 92ms/step - d loss: 1.4048 -
1563/1563 -
g loss: 0.7436
Epoch 7/50
                              - 143s 92ms/step - d_loss: 1.3998 -
1563/1563 —
g_loss: 0.7422
Epoch 8/50
1563/1563 -
                              - 143s 92ms/step - d loss: 1.3956 -
g loss: 0.7548
Epoch 9/50
1563/1563 —
                              - 144s 92ms/step - d loss: 1.3934 -
g loss: 0.7503
Epoch 10/50
1563/1563 -
                              - 143s 92ms/step - d_loss: 1.3861 -
g loss: 0.7542
Epoch 11/50
                              • Os 92ms/step - d_loss: 1.3916 - g_loss:
1563/1563 -
0.7362
```



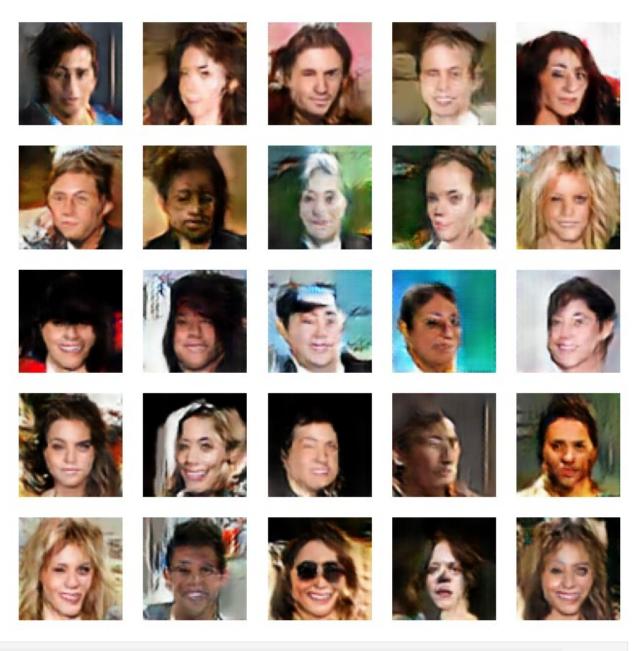
_____ 145s 93ms/step - d_loss: 1.3916 -1563/1563 —— g_loss: 0.7363 Epoch 12/50 - 142s 91ms/step - d_loss: 1.3833 -1563/1563 g_loss: 0.7507 Epoch 13/50 - 143s 91ms/step - d_loss: 1.3911 -1563/1563 g loss: 0.7370 Epoch 14/50 - 142s 91ms/step - d_loss: 1.3918 -1563/1563 g_loss: 0.7308 Epoch 15/50

```
1563/1563 —
                             - 142s 91ms/step - d_loss: 1.3943 -
g loss: 0.7246
Epoch 16/50
                              - 142s 91ms/step - d loss: 1.3808 -
1563/1563 —
g loss: 0.7548
Epoch 17/50
1563/1563 -
                              - 141s 90ms/step - d loss: 1.3867 -
g loss: 0.7374
Epoch 18/50
                              - 141s 91ms/step - d loss: 1.3910 -
1563/1563 —
g_loss: 0.7252
Epoch 19/50
1563/1563 -
                              - 141s 90ms/step - d_loss: 1.3919 -
g loss: 0.7213
Epoch 20/50
1563/1563 -
                              - 141s 90ms/step - d_loss: 1.3894 -
g loss: 0.7271
Epoch 21/50
                              • Os 90ms/step - d loss: 1.3896 - g loss:
1563/1563 -
0.7261
```



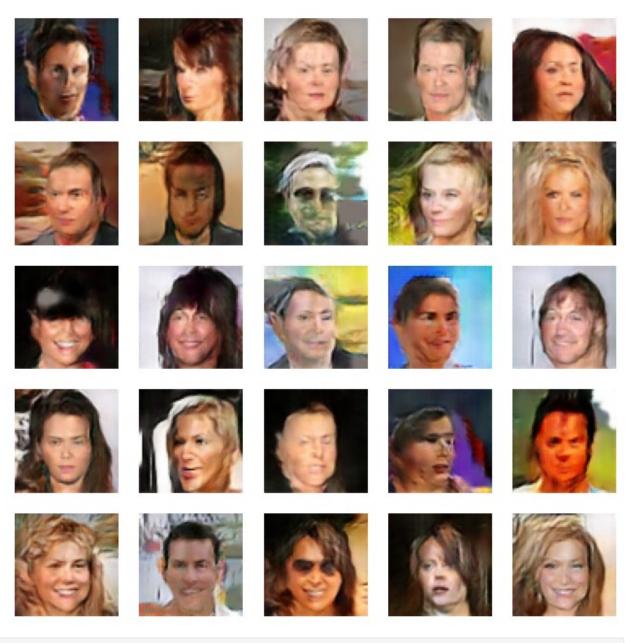
_____ 143s 91ms/step - d_loss: 1.3896 -1563/1563 —— g_loss: 0.7261 Epoch 22/50 - 142s 91ms/step - d_loss: 1.3869 -1563/1563 g_loss: 0.7302 Epoch 23/50 - 141s 90ms/step - d_loss: 1.3851 -1563/1563 g loss: 0.7301 Epoch 24/50 - 141s 90ms/step - d_loss: 1.3729 -1563/1563 g_loss: 0.7591 Epoch 25/50

```
1563/1563 —
                              - 141s 90ms/step - d_loss: 1.3809 -
g loss: 0.7403
Epoch 26/50
                              - 141s 90ms/step - d loss: 1.3809 -
1563/1563 —
g loss: 0.7430
Epoch 27/50
1563/1563 -
                              - 141s 90ms/step - d loss: 1.3756 -
g loss: 0.7530
Epoch 28/50
                              - 141s 90ms/step - d loss: 1.3806 -
1563/1563 —
g loss: 0.7494
Epoch 29/50
1563/1563 -
                              - 141s 90ms/step - d_loss: 1.3592 -
g loss: 0.7848
Epoch 30/50
1563/1563 -
                              - 141s 90ms/step - d_loss: 1.3772 -
g loss: 0.7596
Epoch 31/50
                              • Os 90ms/step - d loss: 1.3643 - g loss:
1563/1563 -
0.7760
```



1563/1563 ——— - 142s 91ms/step - d_loss: 1.3643 g_loss: 0.7760 Epoch 32/50 - 141s 90ms/step - d_loss: 1.3682 -1563/1563 g_loss: 0.7668 Epoch 33/50 - 142s 91ms/step - d_loss: 1.3728 -1563/1563 g loss: 0.7686 Epoch 34/50 - 142s 91ms/step - d_loss: 1.3677 -1563/1563 g_loss: 0.7757 Epoch 35/50

```
1563/1563 —
                             - 141s 90ms/step - d_loss: 1.3633 -
g loss: 0.7754
Epoch 36/50
                              - 142s 91ms/step - d loss: 1.3629 -
1563/1563 —
g loss: 0.7823
Epoch 37/50
1563/1563 -
                              - 141s 90ms/step - d loss: 1.3641 -
g loss: 0.7844
Epoch 38/50
                              - 142s 91ms/step - d loss: 1.3647 -
1563/1563 —
g loss: 0.7857
Epoch 39/50
1563/1563 -
                              - 142s 91ms/step - d_loss: 1.3587 -
g loss: 0.7992
Epoch 40/50
1563/1563 -
                              - 142s 91ms/step - d_loss: 1.3531 -
g loss: 0.8000
Epoch 41/50
1563/1563 -
                              - Os 90ms/step - d loss: 1.3535 - g loss:
0.8073
```



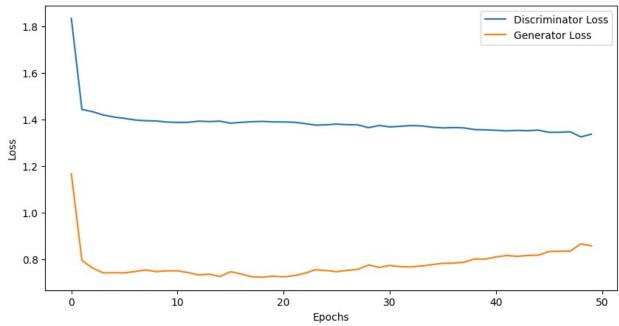
1563/1563 **—** - 143s 91ms/step - d_loss: 1.3535 g_loss: 0.8073 Epoch 42/50 - 141s 90ms/step - d_loss: 1.3478 -1563/1563 g_loss: 0.8172 Epoch 43/50 - 142s 91ms/step - d_loss: 1.3559 -1563/1563 g loss: 0.8068 Epoch 44/50 - 141s 90ms/step - d_loss: 1.3532 -1563/1563 g_loss: 0.8144 Epoch 45/50

```
1563/1563 -
                               - 141s 90ms/step - d loss: 1.3540 -
g loss: 0.8220
Epoch 46/50
1563/1563 —

    141s 90ms/step - d loss: 1.3406 -

g loss: 0.8322
Epoch 47/50
                               141s 90ms/step - d loss: 1.3431 -
1563/1563 -
g loss: 0.8338
Epoch 48/50
1563/1563 -
                               141s 90ms/step - d loss: 1.3480 -
g loss: 0.8351
Epoch 49/50
1563/1563 -
                               141s 91ms/step - d loss: 1.3276 -
g loss: 0.8588
Epoch 50/50
1563/1563 -
                               141s 90ms/step - d loss: 1.3334 -
g loss: 0.8640
```

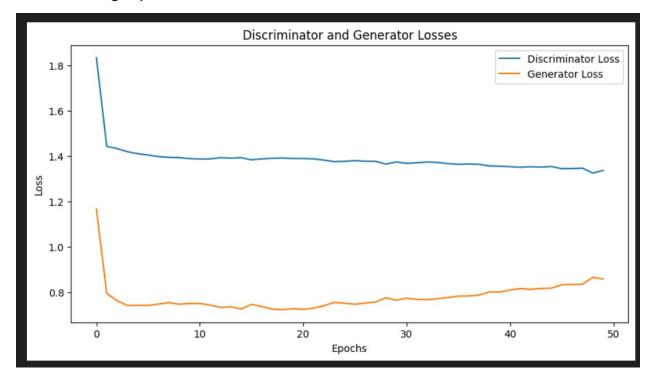




minimum value of d_loss = 1.325143814086914 for epoch 48 minimum value of g_loss = 0.7227808833122253 for epoch 18 minimum value of total = 2.113315999507904 for epoch 20

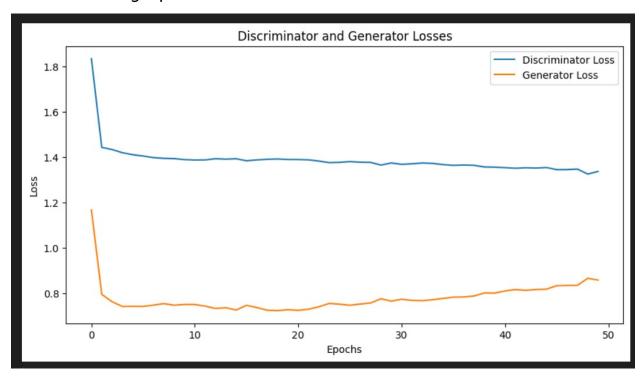
<keras.src.callbacks.history.History at 0x7ac3e0ebbdf0>

First model graph and error



minimum value of d_loss = 1.099036693572998 for epoch 49 minimum value of g_loss = 0.7358095645904541 for epoch 14 minimum value of total = 2.130660891532898 for epoch 17

Second model graph and error

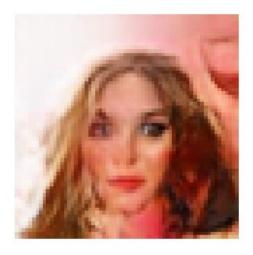


minimum value of d_loss = 1.325143814086914 for epoch 48 minimum value of g_loss = 0.7227808833122253 for epoch 18 minimum value of total = 2.113315999507904 for epoch 20

Generate New Human Faces

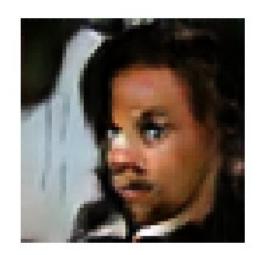
First model image

```
noise = tf.random.normal([1, 200])
fig = plt.figure(figsize=(3, 3))
g_img = dcgan.generator(noise)
g_img = (g_img * 127.5) + 127.5
g_img.numpy()
img = array_to_img(g_img[0])
plt.imshow(img)
plt.axis('off')
plt.show()
```



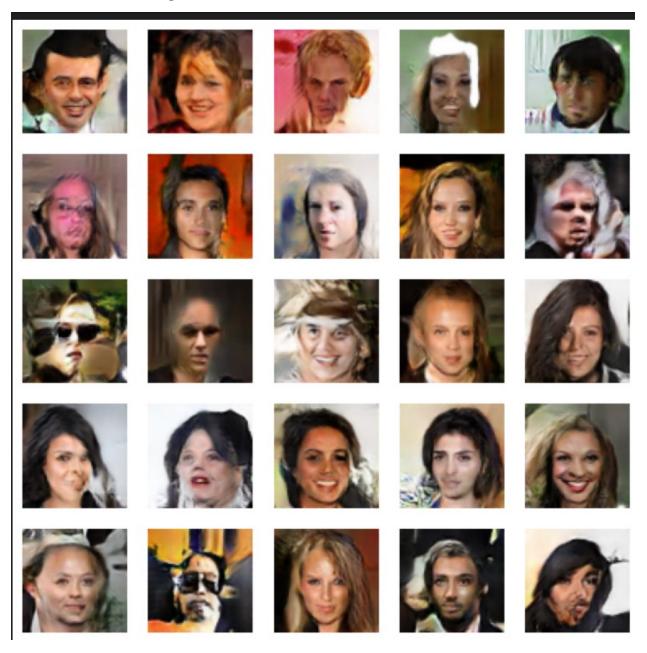
Second model image

```
noise = tf.random.normal([1, 200])
fig = plt.figure(figsize=(3, 3))
g_img = dcgan2.generator(noise)
g_img = (g_img * 127.5) + 127.5
g_img.numpy()
img = array_to_img(g_img[0])
plt.imshow(img)
plt.axis('off')
plt.show()
```



After manually generating outputs by loading the .h5 file into the model, the results were promising and aligned well with our expectations.

First model images



Second model images



The second model's images show slight improvement over the first, as they exhibit less blurriness. Perhaps after 100 or 200 epochs, both models will significantly enhance their image quality.

tilt faces are good in second model

Comment

Despite my efforts, I was unable to reduce the error rate by 5%. However, I did manage to improve it by around 1-2%. Additionally, the image quality appears to have noticeably enhanced. Due to time constraints, I limited training to 50 epochs, as this notebook takes approximately 4 hours to train on a Kaggle GPU.