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Assignment 3, CPSC 406, February 7

Late Days:

Taken: 1, during the weekend.  
Submitted: Saturday, Feb-08.

Colloborations:

Shikhar Nandi, 51931153: Help with Questions 1,2 and 3.

Libraries

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In [200]: using Plots
using LinearAlgebra
using Printf
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Question 1:

a:

i

$f(x_1, x_2) = 2x_2^3 - 6x_2^2 + 3x_1^2x_2.$   
 $\nabla f(x_1) = 6x_1x_2$   
 $\nabla f(x_2) = 6x_2^2 - 12x_2 + 3x_1^2$   
 $\therefore \text{Let } \nabla f(x) = \begin{bmatrix} 6x_1x_2 \\ 6x_2^2 - 12x_2 + 3x_1^2 \end{bmatrix} = 0.$   
When  $\nabla f(x_1) = 6x_1x_2 = 0 \Rightarrow x_1 = 0$  And/Or  $x_2 = 0.$

**Case 1:**  $x_1 = 0$   
 $6x_2^2 = 12x_2 \Rightarrow x_2 = 2$

**Case 2:**  $x_2 = 0$   
 $3x_1^2 = 0 \Rightarrow x_1 = 0$

**Case 3:**  $x_1 = 0 \cap x_2 = 0$   
Default Case

Hence, the two stationary points are: **(0,0) and (0,2).**

ii

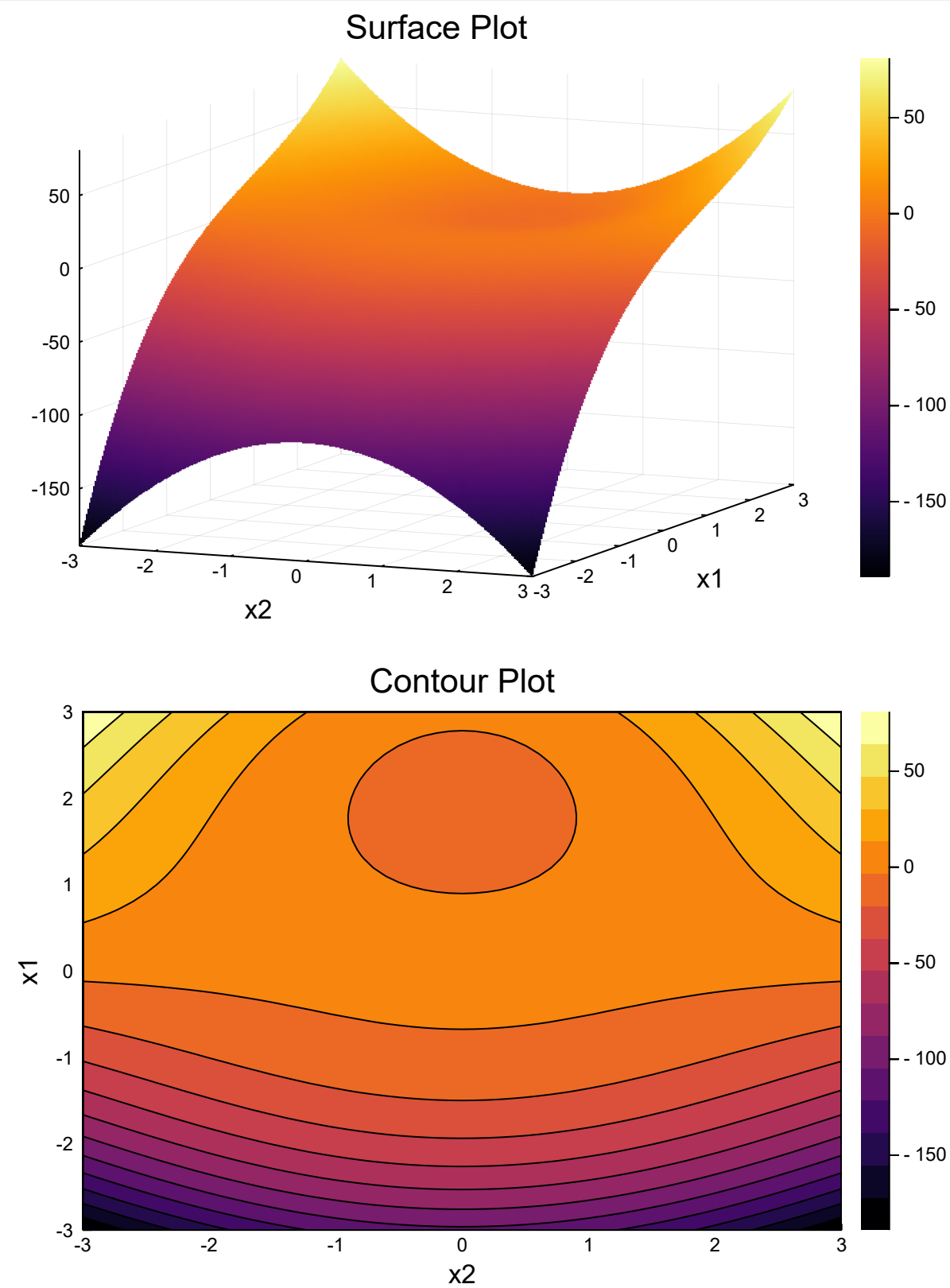
From above, we can deduce that:  
 $\nabla^2 f(x_1) = \begin{bmatrix} 6x_2 & 6x_1 \\ 6x_1 & 12x_2 - 12 \end{bmatrix}$   
Discriminant of  $\nabla^2 f(x_1 : 0, x_2 : 0) = \begin{bmatrix} 0 & 0 \\ 0 & -12 \end{bmatrix}$  [1] is 0.  
Discriminant of  $\nabla^2 f(x_1 : 0, x_2 : 2) = \begin{bmatrix} 12 & 0 \\ 0 & 12 \end{bmatrix}$  [2] is 144.

In [1], we can see that the eigenvalues are  $\lambda_1 = 0$  and  $\lambda_2 = -12$ . Thus, the Hessian in [1] is Non-Positive. We also find the Discriminant to be 0, hence, this is a **saddle point**.

In [2], we can see that the eigenvalues are  $\lambda_1 = 12$  and  $\lambda_2 = 12$ . Thus, the Hessian in [2] is Positive. Also, the discriminant at this point is  $> 0$ , so it's a minima. Since the domain of this function is  $R^2$ , therefore this point is a **non-strict local minima**.

iii

```
In [154]: # y = 2*x2^3-6*x2^2+3*(x1^2)*x2;
x1 = range(-3,stop = 3, length = 61);
x2 = range(-3,stop = 3, length = 61);
f(x1,x2) = 2*x2^3-6*x2^2+3*(x1^2)*x2;
surf = surface(x1,x2,f, legend = true,
    title = "Surface Plot", xaxis = "x2", yaxis = "x1");
cont = contour(x1,x2,f, fill = true,
    title = "Contour Plot", xaxis = "x2", yaxis = "x1");
display(plot(surf));
display(plot(cont));
```



From both of the plots we can deduce that at (0, 0) there is no change, and since this is a critical point, we can state that this is a **saddle point**. On the other hand, we can say that at (0, 2) we see a change, and thus we can conclude from the visual depth that this point is a **local minima**.

iv

From everything above, we can state that (0,0) is **not an extrema**, while (0,2) is a **local minima**.

b:

We are given that  $f(x) = \frac{1}{2}x^T Ax + b^T x + c$ ; where  $A \in R^{n \times n}$  is PSD ( $A \geq 0$ ),  $b \in R^n$  and  $c \in R$ .

Firstly, we take the gradient of  $f(x)$   
 $\nabla f(x) = Ax + b^T$ ; and we will show that  $b \in range(A)$ .  
Now, if we set this to 0, we get  $Ax = -b^T$ . Let's say we have  $\tilde{x}$  that solves the equation, such that  $\nabla f(\tilde{x}) = 0$ . We already know that A is PSD,  $\therefore \nabla^2 f(x) = A$  is also a PSD. From both of the aforementioned facts, we can conclude that  $f(x) \geq f(\tilde{x}) > -\infty; \forall x \in R^n$ .

Now, for a more formal proof, let us assume that  $b \notin range(A)$ . We already know that the main function is bounded, and so there must be a  $\tilde{x}$  such that  $f(x) \geq f(\tilde{x}) > -\infty; \forall x \in R^n$ . And since  $\tilde{x}$  is a solution,  $\therefore \nabla f(\tilde{x}) = 0$  and  $\nabla^2 f(\tilde{x})$  is a PSD. When we compute the  $\nabla f(x) = 0$ , we get  $Ax = -b^T$ . But, we already know that there is  $\tilde{x}$  exists, and  $\nabla f(\tilde{x}) = 0$ . Thus we hit a contradiction to our original assumption for this part, that  $b \notin A$ , which makes it impossible to happen.

Thus, now we can finally conclude that  $f$  is bounded below over  $R^n$  iff  $b \in \text{range}(A)$ .

## Question 2:

$A \in R^{m \times n}$  and  $B \in R^{m \times n}$

$$\text{Let } A = \begin{bmatrix} A_{1,1} & A_{1,2} & \dots & A_{1,n} \\ A_{2,1} & A_{2,2} & \dots & A_{2,n} \\ \vdots & \vdots & \dots & \vdots \\ A_{m,1} & A_{m,2} & \dots & A_{m,n} \end{bmatrix}. \text{ Let } B = \begin{bmatrix} B_{1,1} & B_{1,2} & \dots & B_{1,n} \\ B_{2,1} & B_{2,2} & \dots & B_{2,n} \\ \vdots & \vdots & \dots & \vdots \\ B_{m,1} & B_{m,2} & \dots & B_{m,n} \end{bmatrix}$$

$$\therefore A^T = \begin{bmatrix} A_{1,1} & A_{2,1} & \dots & A_{m,1} \\ A_{1,2} & A_{2,2} & \dots & A_{m,2} \\ \vdots & \vdots & \dots & \vdots \\ A_{1,n} & A_{2,n} & \dots & A_{m,n} \end{bmatrix}$$

$$\begin{aligned} (A^T B)_{1,1} &= A_{1,1} B_{1,1} + A_{2,1} B_{2,1} + \dots + A_{m,1} B_{m,1} \\ (A^T B)_{2,2} &= A_{1,2} B_{1,2} + A_{2,2} B_{2,2} + \dots + A_{m,2} B_{m,2} \\ &\vdots \\ (A^T B)_{n,n} &= A_{1,n} B_{1,n} + A_{2,n} B_{2,n} + \dots + A_{m,n} B_{m,n} \end{aligned}$$

$$\therefore \text{ We see that } \text{tr}(A^T B) = \sum_{i,j} A_{ij} B_{ij}.$$

```
In [202]: m = 100;
n = 50;
A = randn(m,n);
B = randn(m,n);
@time tr(A'*B);

@time function rhs()
    s = 0;
    for i in 1:m
        for j in 1:n
            s += A[i,j]*B[i,j];
        end
    end
    return s;
end;
@printf("LHS = %f \n",tr(A'*B));
@printf("RHS = %f",rhs());
```

```
0.000042 seconds (8 allocations: 19.828 KiB)
0.000034 seconds (20 allocations: 1.845 KiB)
LHS = -13.460622
RHS = -13.460622
```

Above, I used Random Matrices of size  $100 \times 50$  to calculate the time and storage complexities of two sides of the equation. Computationally, they take around the same time, albeit, RHS is a bit faster and takes less storage space. So, RHS seems to be a superior formula.

## Question 3:

**a**

We are given that  $A$  is a diagonal matrix. Now, let us assume that  $A \geq 0$ . Stating what's given along with our assumption, we can write  $x^T A x$  as  $\lambda_1 x_1^2 + \lambda_2 x_2^2 + \dots + \lambda_n x_n^2$  for a vector  $\{x_1, x_2, \dots, x_n\}$ .  $A$  is a diagonal matrix, so the diagonal values are the eigenvalues.

Since, we are assuming  $A \geq 0$ ,  $x^T A x \geq 0$  has to be true.  
 $\therefore \lambda_1 x_1^2 + \lambda_2 x_2^2 + \dots + \lambda_n x_n^2 \geq 0 \Rightarrow \lambda_i \geq 0, \forall i \in \{1, \dots, n\}$  which confirms that for  $A \geq 0$  iff  $A_{ii} \geq 0$ . In similar way we can prove for  $A > 0$ .

If we assume that  $A > 0$ , then  $x^T A x > 0$  has to be true.  
 $\therefore \lambda_1 x_1^2 + \lambda_2 x_2^2 + \dots + \lambda_n x_n^2 > 0 \Rightarrow \lambda_i > 0, \forall i \in \{1, \dots, n\}$  which confirms that for  $A > 0$  iff  $A_{ii} > 0$ .

**b**

We are given

$$A = \begin{bmatrix} A^{(1)} & 0 & \dots & 0 \\ 0 & A^{(2)} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & A^{(l)} \end{bmatrix}$$

Similar to part (a), we can conclude that since  $A$  is a diagonal matrix, and if we are given that  $A \succeq 0$  or  $A \succ 0$ , then the eigenvalues of  $A$  are non-negative. And, also since  $A$  is a diagonal matrix, the determinant of  $A$  is the total product of each block  $A^{(k)}$ , where  $k \in \{1, \dots, l\}$ . Thus, for  $A \succeq 0$  or  $A \succ 0$  to be true,  $A^{(k)} \succeq 0$  or  $A^{(k)} \succ 0$  has to be true, which we could also see is parallel to what we conclude in part (a).