Machine Learning

(機器學習)

Lecture 11: Support Vector Machine (2)

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Roadmap

- 1 When Can Machines Learn?
- 2 Why Can Machines Learn?
- 3 How Can Machines Learn?
- 4 How Can Machines Learn Better?
- 5 Embedding Numerous Features: Kernel Models

Lecture 11: Support Vector Machine (2)

- Kernel Trick
- Polynomial Kernel
- Gaussian Kernel
- Comparison of Kernels
- Motivation and Primal Problem
- Dual Problem
- Messages behind Soft-Margin SVM
- Soft-Margin SVM as Regularized Model

Dual SVM Revisited

goal: SVM without dependence on \tilde{d}

half-way done:

$$\begin{split} \min_{\boldsymbol{\alpha}} & \quad \frac{1}{2}\boldsymbol{\alpha}^T \mathbf{Q}_{\mathrm{D}}\boldsymbol{\alpha} - \mathbf{1}^T \boldsymbol{\alpha} \\ \text{subject to} & \quad \mathbf{y}^T \boldsymbol{\alpha} = \mathbf{0}; \\ & \quad \alpha_n \geq 0, \text{for } n = 1, 2, \dots, N \end{split}$$

- $q_{n,m} = y_n y_m \mathbf{z}_n^T \mathbf{z}_m$: inner product in $\mathbb{R}^{\tilde{d}}$
- need: $\mathbf{z}_{n}^{\mathsf{T}}\mathbf{z}_{m} = \mathbf{\Phi}(\mathbf{x}_{n})^{\mathsf{T}}\mathbf{\Phi}(\mathbf{x}_{m})$ calculated faster than $O(\tilde{\boldsymbol{\sigma}})$

can we do so?

Fast Inner Product for Φ_2

2nd order polynomial transform

$$\mathbf{\Phi}_{2}(\mathbf{x}) = (1, x_{1}, x_{2}, \dots, x_{d}, x_{1}^{2}, x_{1}x_{2}, \dots, x_{1}x_{d}, x_{2}x_{1}, x_{2}^{2}, \dots, x_{2}x_{d}, \dots, x_{d}^{2})$$

—include both $x_1x_2 \& x_2x_1$ for 'simplicity':-)

$$\Phi_{2}(\mathbf{x})^{T}\Phi_{2}(\mathbf{x}') = 1 + \sum_{i=1}^{d} x_{i}x'_{i} + \sum_{i=1}^{d} \sum_{j=1}^{d} x_{i}x'_{j}x'_{j}x'_{j}$$

$$= 1 + \sum_{i=1}^{d} x_{i}x'_{i} + \sum_{i=1}^{d} x_{i}x'_{i} \sum_{j=1}^{d} x_{j}x'_{j}$$

$$= 1 + \mathbf{x}^{T}\mathbf{x}' + (\mathbf{x}^{T}\mathbf{x}')(\mathbf{x}^{T}\mathbf{x}')$$

for Φ_2 , transform + inner product can be carefully done in O(d) instead of $O(d^2)$

Kernel: Transform + Inner Product

transform
$$\Phi \iff$$
 kernel function: $K_{\Phi}(\mathbf{x}, \mathbf{x}') \equiv \Phi(\mathbf{x})^T \Phi(\mathbf{x}')$
 $\Phi_2 \iff K_{\Phi_2}(\mathbf{x}, \mathbf{x}') = 1 + (\mathbf{x}^T \mathbf{x}') + (\mathbf{x}^T \mathbf{x}')^2$

- quadratic coefficient $q_{n,m} = y_n y_m \mathbf{z}_n^T \mathbf{z}_m = y_n y_m K(\mathbf{x}_n, \mathbf{x}_m)$
- optimal bias b? from SV (\mathbf{x}_s, y_s) ,

$$b = y_s - \mathbf{w}^T \mathbf{z}_s = y_s - \left(\sum_{n=1}^N \alpha_n y_n \mathbf{z}_n \right)^T \mathbf{z}_s = y_s - \sum_{n=1}^N \alpha_n y_n \left(K(\mathbf{x}_n, \mathbf{x}_s) \right)^T$$

optimal hypothesis g_{SVM}: for test input x,

$$g_{\text{SVM}}(\mathbf{x}) = \text{sign}\left(\mathbf{w}^{\mathsf{T}}\mathbf{\Phi}(\mathbf{x}) + b\right) = \text{sign}\left(\sum_{n=1}^{N} \alpha_n y_n \mathcal{K}(\mathbf{x}_n, \mathbf{x}) + b\right)$$

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kernel trick: plug in **efficient kernel function** to avoid dependence on \tilde{d}

Kernel Hard-Margin SVM Algorithm

- 1 $q_{n,m} = y_n y_m K(\mathbf{x}_n, \mathbf{x}_m); \mathbf{p} = -\mathbf{1}_N; (A, \mathbf{c})$ for equ./bound constraints

3
$$b \leftarrow \left(y_s - \sum_{\text{SV indices } n} \alpha_n y_n K(\mathbf{x}_n, \mathbf{x}_s) \right) \text{ with SV } (\mathbf{x}_s, y_s)$$

4 return SVs and their α_n as well as b such that for new \mathbf{x} ,

$$g_{\text{SVM}}(\mathbf{x}) = \text{sign}\left(\sum_{\text{SV indices } n} \alpha_n \mathbf{y}_n K(\mathbf{x}_n, \mathbf{x}) + b\right)$$

- (1): time complexity $O(N^2)$ · (kernel evaluation)
- (2): QP with N variables and N+1 constraints
- (3) & (4): time complexity O(#SV) · (kernel evaluation)

kernel SVM:

use computational shortcut to avoid \tilde{d} & predict with SV only

Questions?

General Poly-2 Kernel

$$\begin{aligned} & \boldsymbol{\Phi}_{\mathbf{2}}(\mathbf{x}) = (1, x_1, \dots, x_d, x_1^2, \dots, x_d^2) & \Leftrightarrow & \mathcal{K}_{\boldsymbol{\Phi}_{\mathbf{2}}}(\mathbf{x}, \mathbf{x}') = 1 + \mathbf{x}^T \mathbf{x}' + (\mathbf{x}^T \mathbf{x}')^2 \\ & \boldsymbol{\Phi}_{\mathbf{2}}(\mathbf{x}) = (1, \sqrt{2}x_1, \dots, \sqrt{2}x_d, x_1^2, \dots, x_d^2) & \Leftrightarrow & \mathcal{K}_{\mathbf{2}}(\mathbf{x}, \mathbf{x}') = 1 + 2\mathbf{x}^T \mathbf{x}' + (\mathbf{x}^T \mathbf{x}')^2 \end{aligned}$$

$$\Phi_2(\mathbf{x}) = (1, \sqrt{2\gamma}x_1, \dots, \sqrt{2\gamma}x_d, \gamma x_1^2, \dots, \gamma x_d^2)$$

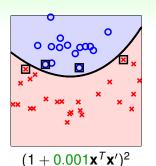
$$\Leftrightarrow \mathcal{K}_2(\mathbf{x}, \mathbf{x}') = 1 + \frac{2\gamma}{2}\mathbf{x}^T\mathbf{x}' + \gamma^2(\mathbf{x}^T\mathbf{x}')^2$$

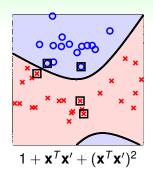
$$K_2(\mathbf{x}, \mathbf{x}') = (1 + \gamma \mathbf{x}^T \mathbf{x}')^2$$
 with $\gamma > 0$

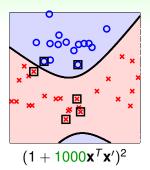
- K₂: somewhat 'easier' to calculate than K_{Φ2}
- Φ₂ and Φ₂: equivalent power,
 different inner product ⇒ different geometry

K2 commonly used

Poly-2 Kernels in Action







- g_{SVM} different, SVs different
 —'hard' to say which is better before learning
- change of kernel ⇔ change of margin definition

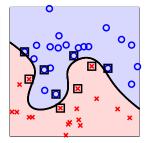
need selecting K, just like selecting Φ

General Polynomial Kernel

$$\begin{array}{lcl} \mathcal{K}_{\mathbf{2}}(\mathbf{x},\mathbf{x}') &=& (\zeta + \gamma \mathbf{x}^T \mathbf{x}')^2 \text{ with } \gamma > 0, \zeta \geq 0 \\ \mathcal{K}_{\mathbf{3}}(\mathbf{x},\mathbf{x}') &=& (\zeta + \gamma \mathbf{x}^T \mathbf{x}')^3 \text{ with } \gamma > 0, \zeta \geq 0 \\ & \vdots \\ \mathcal{K}_{\mathbf{Q}}(\mathbf{x},\mathbf{x}') &=& (\zeta + \gamma \mathbf{x}^T \mathbf{x}')^{\mathbf{Q}} \text{ with } \gamma > 0, \zeta \geq 0 \end{array}$$

- embeds Φ_Q specially with parameters (γ, ζ)
- allows computing large-margin polynomial classification without dependence on d

SVM + Polynomial Kernel: Polynomial SVM

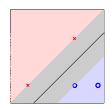


10-th order polynomial with margin 0.1

Special Case: Linear Kernel

$$\begin{aligned} \mathcal{K}_{1}(\mathbf{x}, \mathbf{x}') &= (0 + 1 \cdot \mathbf{x}^{T} \mathbf{x}')^{1} \\ &\vdots \\ \mathcal{K}_{\mathbf{Q}}(\mathbf{x}, \mathbf{x}') &= (\zeta + \gamma \mathbf{x}^{T} \mathbf{x}')^{\mathbf{Q}} \text{ with } \gamma > 0, \zeta \geq 0 \end{aligned}$$

- K₁: just usual inner product, called linear kernel
- 'even easier': can be solved (often in primal form) efficiently



linear first, remember? :-)

Questions?

Kernel of Infinite Dimensional Transform

infinite dimensional $\Phi(\mathbf{x})$? Yes, if $K(\mathbf{x}, \mathbf{x}')$ efficiently computable!

when
$$\mathbf{x} = (x)$$
, $K(x, x') = \exp(-(x - x')^2)$
 $= \exp(-(x)^2)\exp(-(x')^2)\exp(2xx')$
 $\stackrel{\text{Taylor}}{=} \exp(-(x)^2)\exp(-(x')^2)\left(\sum_{i=0}^{\infty}\frac{(2xx')^i}{i!}\right)$
 $= \sum_{i=0}^{\infty}\left(\exp(-(x)^2)\exp(-(x')^2)\sqrt{\frac{2^i}{i!}}\sqrt{\frac{2^i}{i!}}(x)^i(x')^i\right)$
 $= \Phi(x)^T\Phi(x')$
with infinite dimensional $\Phi(x) = \exp(-x^2) \cdot \left(1, \sqrt{\frac{2}{1!}}x, \sqrt{\frac{2^2}{2!}}x^2, ...\right)$

more generally, **Gaussian kernel**
$$K(\mathbf{x}, \mathbf{x}') = \exp(-\gamma ||\mathbf{x} - \mathbf{x}'||^2)$$
 with $\gamma > 0$

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Hypothesis of Gaussian SVM

Gaussian kernel $K(\mathbf{x}, \mathbf{x}') = \exp(-\gamma ||\mathbf{x} - \mathbf{x}'||^2)$

$$\begin{split} g_{\text{SVM}}(\mathbf{x}) &= & \operatorname{sign}\left(\sum_{\text{SV}} \alpha_{n} y_{n} K(\mathbf{x}_{n}, \mathbf{x}) + b\right) \\ &= & \operatorname{sign}\left(\sum_{\text{SV}} \alpha_{n} y_{n} \exp\left(-\gamma \|\mathbf{x} - \mathbf{x}_{n}\|^{2}\right) + b\right) \end{split}$$

- linear combination of Gaussians centered at SVs xn
- also called Radial Basis Function (RBF) kernel

Gaussian SVM:

find α_n to combine Gaussians centered at \mathbf{x}_n & achieve large margin in infinite-dim. space

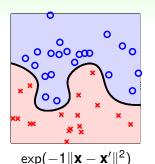
Support Vector Mechanism

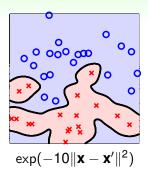
	large-margin hyperplanes higher-order transforms with kernel trick
#	not many
boundary	sophisticated

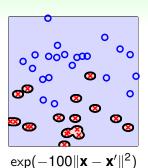
- transformed vector $\mathbf{z} = \mathbf{\Phi}(\mathbf{x}) \Longrightarrow$ efficient kernel $K(\mathbf{x}, \mathbf{x}')$
- store optimal $\mathbf{w} \Longrightarrow$ store a few SVs and α_n

new possibility by Gaussian SVM: infinite-dimensional linear classification, with generalization 'guarded by' large-margin:-)

Gaussian SVM in Action





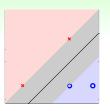


- large $\gamma \Longrightarrow$ sharp Gaussians \Longrightarrow 'overfit'?
- warning: SVM can still overfit :-(

Gaussian SVM: need careful selection of γ

Questions?

Linear Kernel: Cons and Pros



$$K(\mathbf{x}, \mathbf{x}') = \mathbf{x}^T \mathbf{x}'$$

Cons

restricted—not <u>alwavs separable?!</u>

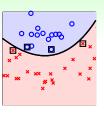


Pros

- safe—linear first, remember? :-)
- fast—with special QP solver in primal
- very explainable—w and SVs say something

linear kernel: an important basic tool

Polynomial Kernel: Cons and Pros



$$K(\mathbf{x}, \mathbf{x}') = (\zeta + \gamma \mathbf{x}^T \mathbf{x}')^Q$$

Cons

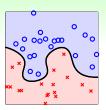
- numerical difficulty for large Q
 - $|\zeta + \gamma \mathbf{x}^T \mathbf{x}'| < 1$: $K \to 0$
 - $|\zeta + \gamma \mathbf{x}^T \mathbf{x}'| > 1$: $K \to \text{big}$
- three parameters (γ, ζ, Q) —more difficult to select

Pros

- less restricted than linear
- strong physical control
 —'knows' degree Q

polynomial kernel: perhaps small-Q only—sometimes efficiently done by linear on $\Phi_Q(\mathbf{x})$

Gaussian Kernel: Cons and Pros



$$K(\mathbf{x}, \mathbf{x}') = \exp(-\gamma \|\mathbf{x} - \mathbf{x}'\|^2)$$

Cons

- mysterious—no w
- slower than linear
- too powerful?!



Pros

- more powerful than linear/poly.
- bounded—less numerical difficulty than poly.
- one parameter only—easier to select than poly.

Gaussian kernel: one of most popular but shall be used with care

Other Valid Kernels

- kernel represents special similarity: $\Phi(\mathbf{x})^T \Phi(\mathbf{x}')$
- any similarity ⇒ valid kernel? not really
- necessary & sufficient conditions for valid kernel:
 Mercer's condition
 - symmetric
 - let $k_{ij} = K(\mathbf{x}_i, \mathbf{x}_i)$, the matrix K

$$= \begin{bmatrix} \mathbf{\Phi}(\mathbf{x}_1)^T \mathbf{\Phi}(\mathbf{x}_1) & \mathbf{\Phi}(\mathbf{x}_1)^T \mathbf{\Phi}(\mathbf{x}_2) & \dots & \mathbf{\Phi}(\mathbf{x}_1)^T \mathbf{\Phi}(\mathbf{x}_N) \\ \mathbf{\Phi}(\mathbf{x}_2)^T \mathbf{\Phi}(\mathbf{x}_1) & \mathbf{\Phi}(\mathbf{x}_2)^T \mathbf{\Phi}(\mathbf{x}_2) & \dots & \mathbf{\Phi}(\mathbf{x}_2)^T \mathbf{\Phi}(\mathbf{x}_N) \\ & \dots & & \dots & \dots \\ \mathbf{\Phi}(\mathbf{x}_N)^T \mathbf{\Phi}(\mathbf{x}_1) & \mathbf{\Phi}(\mathbf{x}_N)^T \mathbf{\Phi}(\mathbf{x}_2) & \dots & \mathbf{\Phi}(\mathbf{x}_N)^T \mathbf{\Phi}(\mathbf{x}_N) \end{bmatrix}$$

$$= \begin{bmatrix} \mathbf{z}_1 & \mathbf{z}_2 & \dots & \mathbf{z}_N \end{bmatrix}^T \begin{bmatrix} \mathbf{z}_1 & \mathbf{z}_2 & \dots & \mathbf{z}_N \end{bmatrix}$$

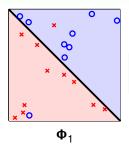
$$= \mathbf{Z} \mathbf{Z}^T \text{ must always be positive semi-definite}$$

define your own kernel: possible, but hard

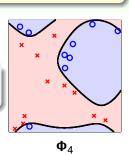
Questions?

Cons of Hard-Margin SVM

recall: SVM can still overfit :-(



- part of reasons: Φ
- other part: separable



if always insisting on **separable** (⇒ **shatter**), have power to **overfit to noise**

Give Up on Some Examples

want: give up on some noisy examples

min.-error perceptron

$$\min_{b,\mathbf{w}}$$

$$\sum_{n=1}^{N} [y_n \neq \operatorname{sign}(\mathbf{w}^T \mathbf{z}_n + b)]$$

hard-margin SVM

$$\min_{b,\mathbf{w}} \quad \frac{1}{2}\mathbf{w}^T\mathbf{w}$$

 $y_n(\mathbf{w}^T\mathbf{z}_n+b)>1$ for all ns.t.

$$\frac{1}{2}\mathbf{w}^T\mathbf{w}$$

$$\mathbf{w} + \mathbf{C} \cdot \sum_{N}$$

$$\int_{-\infty}^{\infty} [y_n]$$

$$\frac{1}{2}\mathbf{w}^{T}\mathbf{w} + \mathbf{C} \cdot \sum_{n=1}^{N} \left[y_n \neq \operatorname{sign}(\mathbf{w}^{T}\mathbf{z}_n + b) \right]$$

s.t.
$$y_n(\mathbf{w}^T\mathbf{z}_n + b) \ge 1$$
 for correct n

$$y_n(\mathbf{w}^T\mathbf{z}_n + b) \ge -\infty$$
 for incorrect n

C: trade-off of large margin & noise tolerance

Soft-Margin SVM (1/2)

$$\min_{b,\mathbf{w}} \frac{1}{2}\mathbf{w}^{T}\mathbf{w} + \mathbf{C} \cdot \sum_{n=1}^{N} \left[y_{n} \neq \operatorname{sign}(\mathbf{w}^{T}\mathbf{z}_{n} + b) \right]$$
s.t.
$$y_{n}(\mathbf{w}^{T}\mathbf{z}_{n} + b) \geq 1 - \infty \cdot \left[y_{n} \neq \operatorname{sign}(\mathbf{w}^{T}\mathbf{z}_{n} + b) \right]$$

- [·]: non-linear, not QP anymore :-(
 —what about dual? kernel?
- cannot distinguish small error (slightly away from fat boundary)
 or large error (a...w...a...y... from fat boundary)
- record 'margin violation' by ξ_n —linear constraints
- penalize with margin violation instead of error count
 —quadratic objective

soft-margin SVM:
$$\min_{b, \mathbf{w}, \xi} \frac{1}{2} \mathbf{w}^T \mathbf{w} + \mathbf{C} \cdot \sum_{n=1}^{N} \xi_n$$

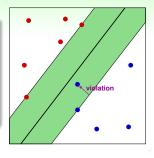
s.t.
$$y_n(\mathbf{w}^T\mathbf{z}_n + b) \ge 1 - \xi_n$$
 and $\xi_n \ge 0$ for all n

Soft-Margin SVM (2/2)

- record 'margin violation' by ξ_n
- penalize with margin violation

$$\min_{b, \mathbf{w}, \boldsymbol{\xi}} \frac{1}{2} \mathbf{w}^T \mathbf{w} + \frac{C}{C} \cdot \sum_{n=1}^{N} \xi_n$$
s.t.
$$y_n(\mathbf{w}^T \mathbf{z}_n + b) \ge 1 - \xi_n \text{ and } \xi_n \ge 0 \text{ for all } n$$

s.t.
$$y_n(\mathbf{w}^T\mathbf{z}_n + b) \ge 1 - \xi_n$$
 and $\xi_n \ge 0$ for all r



- parameter C: trade-off of large margin & margin violation
 - large C: want less margin violation
 - small C: want large margin
- QP of $\tilde{d} + 1 + N$ variables, 2N constraints

next: remove dependence on d by soft-margin SVM primal ⇒ dual?

Questions?

Lagrange Dual

primal:
$$\min_{b, \mathbf{w}, \xi} \frac{1}{2} \mathbf{w}^T \mathbf{w} + C \cdot \sum_{n=1}^{N} \xi_n$$

s.t. $y_n(\mathbf{w}^T\mathbf{z}_n + b) \ge 1 - \xi_n$ and $\xi_n \ge 0$ for all n

Lagrange function with Lagrange multipliers α_n and β_n

$$\mathcal{L}(b, \mathbf{w}, \boldsymbol{\xi}, \boldsymbol{\alpha}, \boldsymbol{\beta}) = \frac{1}{2} \mathbf{w}^{\mathsf{T}} \mathbf{w} + C \cdot \sum_{n=1}^{N} \xi_{n} + \sum_{n=1}^{N} \alpha_{n} \cdot (1 - \xi_{n} - y_{n}(\mathbf{w}^{\mathsf{T}} \mathbf{z}_{n} + b)) + \sum_{n=1}^{N} \beta_{n} \cdot (-\xi_{n})$$

want: Lagrange dual

$$\max_{\substack{\alpha_n \geq 0, \ \beta_n \geq 0}} \left(\min_{\substack{b, \mathbf{w}, \boldsymbol{\xi}}} \mathcal{L}(b, \mathbf{w}, \boldsymbol{\xi}, \boldsymbol{\alpha}, \boldsymbol{\beta}) \right)$$

Simplify ξ_n and β_n

$$\max_{\alpha_n \ge 0, \ \beta_n \ge 0} \quad \left(\min_{b, \mathbf{w}, \xi} \quad \frac{1}{2} \mathbf{w}^T \mathbf{w} + C \cdot \sum_{n=1}^{N} \xi_n + \sum_{n=1}^{N} \alpha_n \cdot \left(1 - \xi_n - y_n(\mathbf{w}^T \mathbf{z}_n + b) \right) + \sum_{n=1}^{N} \beta_n \cdot (-\xi_n) \right)$$

- $\frac{\partial \mathcal{L}}{\partial \mathcal{E}_n} = 0 = C \alpha_n \beta_n$
- no loss of optimality if solving with implicit constraint $\beta_n = C \alpha_n$ and explicit constraint $0 \le \alpha_n \le C$: β_n removed

ξ can also be removed :-), like how we removed b

$$\max_{0 \leq \alpha_n \leq C, \ \beta_n = C - \alpha_n} \left(\min_{b, \mathbf{w}, \xi} \frac{1}{2} \mathbf{w}^T \mathbf{w} + \sum_{n=1}^N \alpha_n (1 - y_n (\mathbf{w}^T \mathbf{z}_n + b)) + \sum_{n=1}^N (C - \alpha_n - \beta_n) \cdot \xi_n \right)$$

Other Simplifications

$$\max_{0 \leq \alpha_n \leq C, \ \beta_n = C - \alpha_n} \left(\min_{b, \mathbf{w}} \frac{1}{2} \mathbf{w}^T \mathbf{w} + \sum_{n=1}^N \alpha_n (1 - y_n (\mathbf{w}^T \mathbf{z}_n + b)) \right)$$

familiar? :-)

- inner problem same as hard-margin SVM
- $\frac{\partial \mathcal{L}}{\partial b} = 0$: no loss of optimality if solving with constraint $\sum_{n=1}^{N} \alpha_n y_n = 0$
- $\frac{\partial \mathcal{L}}{\partial w_i} = 0$: no loss of optimality if solving with constraint $\mathbf{W} = \sum_{n=1}^{N} \alpha_n y_n \mathbf{Z}_n$

standard dual can be derived using the same steps as Lecture 10

Standard Soft-Margin SVM Dual

$$\begin{aligned} & \underset{\boldsymbol{\alpha}}{\min} & & \frac{1}{2} \sum_{n=1}^{N} \sum_{m=1}^{N} \alpha_{n} \alpha_{m} y_{n} y_{m} \mathbf{z}_{n}^{T} \mathbf{z}_{m} - \sum_{n=1}^{N} \alpha_{n} \\ & \text{subject to} & & \sum_{n=1}^{N} y_{n} \alpha_{n} = 0; \\ & & 0 \leq \alpha_{n} \leq C, \text{for } n = 1, 2, \dots, N; \\ & \text{implicitly} & & \mathbf{w} = \sum_{n=1}^{N} \alpha_{n} y_{n} \mathbf{z}_{n}; \\ & & \beta_{n} = C - \alpha_{n}, \text{for } n = 1, 2, \dots, N \end{aligned}$$

—only difference to hard-margin: upper bound on α_n

another (convex) \overline{QP} , with N variables & 2N + 1 constraints

Questions?

Kernel Soft-Margin SVM

Kernel Soft-Margin **SVM** Algorithm

- $\mathbf{0} \quad \mathbf{q}_{n,m} = \mathbf{y}_n \mathbf{y}_m K(\mathbf{x}_n, \mathbf{x}_m); \mathbf{p} = -\mathbf{1}_N; (A, \mathbf{c}) \text{ for } \mathbf{q}_n$ equ./lower-bound/upper-bound constraints
- 6 b ←?
- return SVs and their α_n as well as b such that for new **x**,

$$g_{\text{SVM}}(\mathbf{x}) = \operatorname{sign}\left(\sum_{\substack{\text{SV indices } n}} \alpha_n \mathbf{y}_n K(\mathbf{x}_n, \mathbf{x}) + b\right)$$

- almost the same as hard-margin
- more flexible than hard-margin -primal/dual always solvable

remaining question: step (3)?

Solving for *b*

hard-margin SVM

complementary slackness:

$$\alpha_n(1-y_n(\mathbf{w}^T\mathbf{z}_n+b))=0$$

• SV $(\alpha_s > 0)$ $\Rightarrow b = y_s - \mathbf{w}^T \mathbf{z}_s$

soft-margin SVM

complementary slackness:

$$\frac{\alpha_n(1-\xi_n-y_n(\mathbf{w}^T\mathbf{z}_n+b))=0}{(C-\alpha_n)\xi_n=0}$$

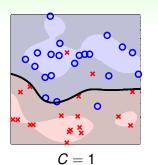
- SV $(\alpha_s > 0)$ $\Rightarrow b = y_s - y_s \xi_s - \mathbf{w}^T \mathbf{z}_s$
- free $(\alpha_s < C)$ $\Rightarrow \xi_s = 0$

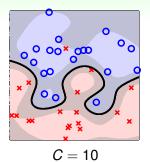
solve unique b with free SV (\mathbf{x}_s, y_s) :

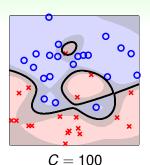
$$b = y_s - \sum_{\substack{\text{SV indices } n}} \alpha_n y_n K(\mathbf{x}_n, \mathbf{x}_s)$$

—range of *b* otherwise

Soft-Margin Gaussian SVM in Action







- large $C \Longrightarrow$ less noise tolerance \Longrightarrow 'overfit'?
- warning: SVM can still overfit :-(

soft-margin Gaussian SVM: need careful selection of (γ, C)

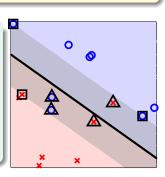
Physical Meaning of α_n

complementary slackness:

$$\alpha_n(1-\xi_n-y_n(\mathbf{w}^T\mathbf{z}_n+b))=0$$

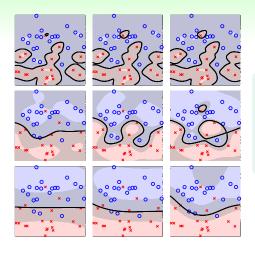
$$(C-\alpha_n)\xi_n=0$$

- non SV $(0 = \alpha_n)$: $\xi_n = 0$, 'away from'/on fat boundary
- \Box free SV (0 < α_n < C): ξ_n = 0, on fat boundary, locates b
- \triangle bounded SV ($\alpha_n = C$): $\xi_n = \text{violation amount}$, 'violate'/on fat boundary



 α_n can be used for **data analysis**

Practical Need: Model Selection



- complicated even for (C, γ) of Gaussian SVM
- more combinations if including other kernels or parameters

how to select? validation:-)

Questions?

Wrap-Up

Hard-Margin Primal

$$\min_{b,\mathbf{w}} \quad \frac{1}{2}\mathbf{w}^T\mathbf{w}$$

s.t.
$$y_n(\mathbf{w}^T\mathbf{z}_n + b) > 1$$

Soft-Margin Primal

$$\min_{b,\mathbf{w},\boldsymbol{\xi}} \qquad \frac{1}{2}\mathbf{w}^T\mathbf{w} + \frac{C}{C}\sum_{n=1}^{N} \xi_n$$

s.t.
$$y_n(\mathbf{w}^T\mathbf{z}_n + b) \ge 1 - \xi_n, \xi_n \ge 0$$

Hard-Margin Dual

$$\begin{aligned} \min_{\alpha} & \quad \frac{1}{2} \alpha^T Q \alpha - \mathbf{1}^T \alpha \\ \text{s.t.} & \quad \mathbf{y}^T \alpha = 0 \end{aligned}$$

$0 < \alpha_n$

Soft-Margin Dual

$$\min_{\alpha} \qquad \frac{1}{2} \alpha^T Q \alpha - \boldsymbol{1}^T \alpha$$

s.t.
$$\mathbf{y}^T \alpha = 0$$

$$0 \le \alpha_n \le C$$

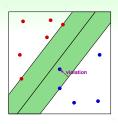
soft-margin preferred in practice; linear: LIBLINEAR: non-linear: LIBSVM

Slack Variables ξ_n

- record 'margin violation' by ξ_n
- penalize with margin violation

$$\min_{b, \mathbf{w}, \boldsymbol{\xi}} \qquad \frac{1}{2} \mathbf{w}^T \mathbf{w} + \frac{\mathbf{C}}{\mathbf{C}} \cdot \sum_{n=1}^{N} \xi_n$$

s.t.
$$y_n(\mathbf{w}^T\mathbf{z}_n + b) \ge 1 - \xi_n$$
 and $\xi_n \ge 0$ for all n



on any
$$(b, \mathbf{w})$$
, $\xi_n = \mathbf{margin\ violation} = \max(1 - y_n(\mathbf{w}^T\mathbf{z}_n + b), 0)$

- (\mathbf{x}_n, y_n) violating margin: $\xi_n = 1 y_n(\mathbf{w}^T \mathbf{z}_n + b)$
- $(\mathbf{x}_n, \mathbf{y}_n)$ not violating margin: $\xi_n = 0$

'unconstrained' form of soft-margin SVM:

$$\min_{b,\mathbf{w}} \frac{1}{2}\mathbf{w}^T\mathbf{w} + \frac{C}{C}\sum_{n=1}^{N} \max(1 - y_n(\mathbf{w}^T\mathbf{z}_n + b), 0)$$

Unconstrained Form

$$\min_{b,\mathbf{w}} \frac{1}{2}\mathbf{w}^T\mathbf{w} + \frac{C}{C}\sum_{n=1}^{N} \max(1 - y_n(\mathbf{w}^T\mathbf{z}_n + b), 0)$$

$$min \qquad \frac{1}{2} \mathbf{w}^T \mathbf{w} + \mathbf{C} \sum \widehat{err}$$

just L2 regularization

min
$$\frac{\lambda}{N} \mathbf{w}^T \mathbf{w} + \frac{1}{N} \sum \text{err}$$

with shorter w, another parameter, and special err

why not solve this? :-)

- not QP, no (?) kernel trick
- max(·, 0) not differentiable, harder to solve

SVM as Regularized Model

	minimize	constraint
regularization by constraint	E _{in}	$\mathbf{w}^T\mathbf{w} \leq \frac{\mathbf{C}}{\mathbf{C}}$
hard-margin SVM	$\mathbf{w}^T\mathbf{w}$	$E_{\text{in}} = 0$ [and more]
L2 regularization	$\frac{\lambda}{N}\mathbf{w}^T\mathbf{w} + E_{in}$	
soft-margin SVM	$\frac{1}{2}\mathbf{w}^T\mathbf{w} + \frac{\mathbf{C}}{N}\widehat{E_{\text{in}}}$	

large margin \iff fewer hyperplanes \iff L2 regularization of short ${\bf w}$

$$\text{soft margin} \Longleftrightarrow \text{special } \widehat{\text{err}}$$

larger \mathcal{C} or $\mathcal{C} \iff$ smaller $\lambda \iff$ less regularization

viewing SVM as regularized model:

allows extending/connecting to other learning models

Questions?

Summary Embedding Numerous Features: Kernel Models

Lecture 11: Support Vector Machine (2)

- Kernel Trick
 kernel as shortcut of transform + inner product
- Polynomial Kernel embeds specially-scaled polynomial transform
- Gaussian Kernel embeds infinite dimensional transform
- Comparison of Kernels
 linear for efficiency or Gaussian for power
- Motivation and Primal Problem add margin violations ξ_n
- Dual Problem upper-bound α_n by C
- Messages behind Soft-Margin SVM bounded/free SVs for data analysis
- Soft-Margin SVM as Regularized Model
 L2-regularization with hinge error measure