

FASS SmartPark-IoT - Developer Implementation Spec (PoE)

R&D; and implementation handoff document for the engineering team.

Site: Sabanci University Tuzla Campus - FASS parking lot

Edge HW: Raspberry Pi 4, coverage: all visible slots

Power profile: PoE (see Section 3)

Date: 2026-01-03

Goal: Build a deployable IoT sensing node that publishes per-slot occupancy as event-driven telemetry (MQTT), with reliability, operations monitoring, and remote configuration. ML is optional and must not compromise IoT objectives (bandwidth, uptime, maintainability, privacy).

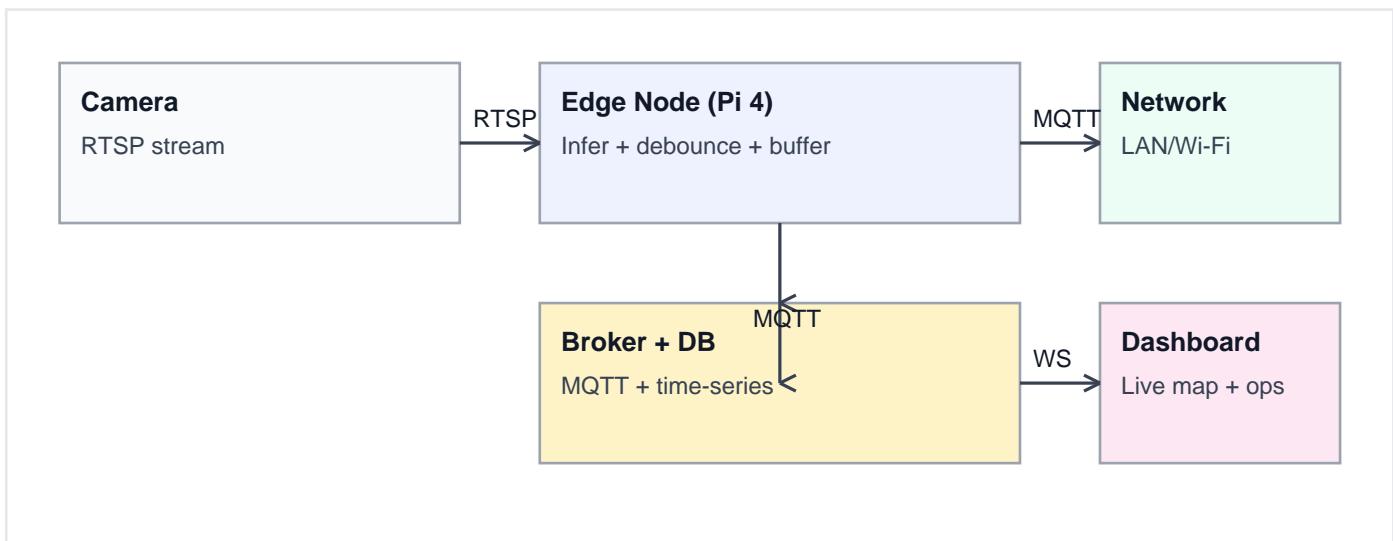
1. Scope and non-scope

Scope is limited to the FASS parking lot. The system must cover all parking slots visible from the selected camera viewpoint.

- In-scope: on-edge sensing pipeline, calibrated slot mapping, MQTT telemetry, buffering/replay, dashboard integration, field deployment.
- Out-of-scope: mobile app, reservations/payment, campus-wide multi-lot rollout (unless time permits), identity/plate tracking.
- Privacy requirement: do not stream or store raw video off-device by default; publish only structured occupancy telemetry.

2. System architecture (IoT-first)

Implement the system as a set of services with clear responsibilities. Prefer robust ops over model complexity.



2.1 Services (edge)

- capture: RTSP ingest, frame timestamping, exposure notes, drop detection.
- calibration: ROI mask + slot polygons loading; optional homography rectification.
- occupancy: per-slot scoring, debounce/hysteresis, UNKNOWN gating, event generation.
- telemetry: MQTT publish, QoS handling, store-and-forward queue, replay.
- health: periodic node metrics (fps/temp/mem/net/buffer depth) + camera stream status.
- config: subscribe to config topic, validate and apply updates safely (rollback support).

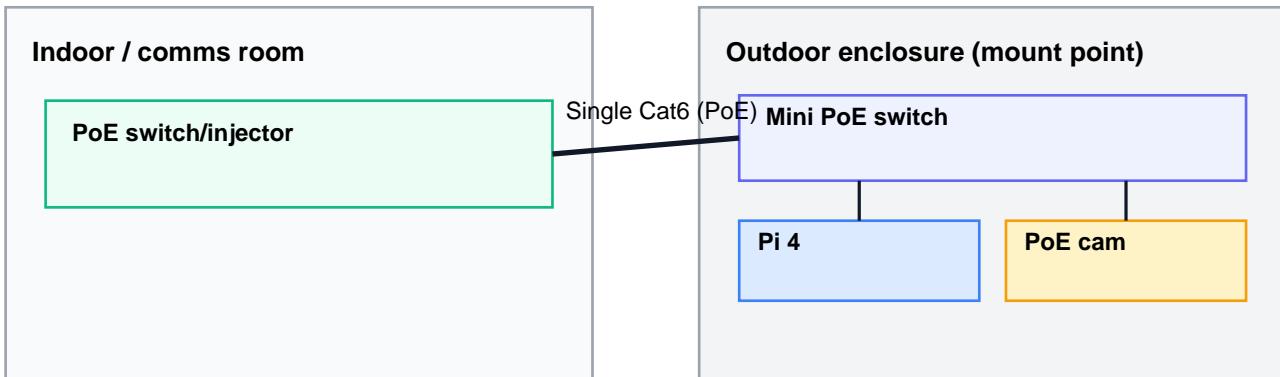
2.2 Server components

- MQTT broker with ACL (per-node credentials).
- DB for events and telemetry (time-series DB preferred).
- Dashboard: live lot state, history, ops panel, basic alerts (node offline, buffer growing).

3. Power and wiring plan

Follow the wiring diagram and safety/robustness notes. This is the main divergence between the PoE and AC versions.

PoE Wiring



3.1 PoE acceptance criteria

- Single Cat6 run to enclosure is preferred (power+data).
- Pi and camera powered via PoE for 8+ hours with no brownouts.
- Outdoor-rated cable, drip loop, strain relief, and enclosure sealing verified.
- Ethernet surge protection and grounding documented (if permitted).

4. Interfaces and data contracts (must implement)

MQTT is the primary interface between edge and server. Keep payloads stable; version artifacts.

Topic	QoS	Direction	Publish rate	Required fields
su/parking/fass/slot/<slot_id>/state	1	Edge->Broker	On change	slot_id, occupied unknown, confidence, ts_utc, dwc
su/parking/fass/summary	0	Edge->Broker	Every 5-10 s	free_count, occupied_count, unknown_count, ts_utc
su/parking/fass/node_health	0	Edge->Broker	Every 10-30 s	uptime_s, fps, cpu_temp_c, mem_mb, dropped_frames
su/parking/fass/config	1	Broker->Edge	On demand	publish_period_s, debounce_s, enter_thr, exit_thr, r

4.1 JSON payload rules

- Include ts_utc in ISO-8601 UTC for all messages.
- Include roi_version and model_version in state and summary.
- State events are only published on transitions after debounce confirms stability.
- Unknown is a valid state when confidence is below threshold; avoid forced guesses.

5. Calibration artifacts and tooling

- roi_mask.png: binary mask of parking region.
- fass_slots_v1.json: polygons for all visible slots (slot_id + list of points).
- homography_v1.json: optional, recommended if camera is angled.
- overlay_check tool: shows live video with ROI/slot overlays to validate calibration.

5.1 Slot polygon JSON schema (example)

```
{ "roi_version": "v1", "image_size": [1920, 1080], "slots": [ { "slot_id": "FASS_001", "poly": [[x1,y1],[x2,y2],[x3,y3],[x4,y4]]}, ... ] }
```

6. Occupancy engine (IoT behavior)

Implement debouncing and hysteresis as the default behavior. This is required for stable IoT sensing.

- Per-slot score in [0,1].
- Enter threshold != exit threshold (hysteresis).
- Debounce: require state to hold for K seconds before transition.
- Emit dwell_s in events (time spent in previous state).
- Confidence gating: if score is between thresholds or noisy, set state UNKNOWN.

6.1 Minimal baseline (no-ML) must exist

- Background difference within ROI + threshold features.
- Used for regression tests and as fallback if model fails.

7. Reliability and operations (must-have)

- Store-and-forward queue (SQLite): append on publish failure; replay on reconnect; dedupe on (slot_id, transition_ts).
- Systemd services with Restart=always; log rotation.
- Heartbeat metric and alert when node is offline > 30 s.
- Camera reconnect strategy; expose stream_up boolean in health telemetry.

7.1 Test cases (engineer must run)

- Network outage test: pull uplink for 2 minutes; verify no lost transitions and correct replay ordering.
- Camera outage test: stop RTSP stream; verify reconnect behavior; health shows stream_down.
- Thermal soak: run 1 hour; ensure fps stable and no throttling.

8. Milestones and deliverables

- D1: Site survey + mount plan + sample clip from final viewpoint.
- D2: Calibration v1 (all visible slots) + live overlay validation.
- D3: Edge pipeline stable for 60 min + local overlay + basic metrics.
- D4: MQTT telemetry live (state + summary + health) + server storage.
- D5: Dashboard live map + history + ops panel.
- D6: Reliability features + outage tests + evaluation report.

9. Implementation backlog (epics)

Epic	Key tasks	Acceptance criteria (done means)
E0.5 PoE power integration	Site PoE topology (single run + mini switch); PoE splitter and PoE power protection	Power delivery to edge nodes; PoE splitting; PoE power protection; Edge node temperature
E0 Site survey & mount	Choose mount point; confirm FOV covers all visible slots; sample captures taken at various angles; camera calibration done	Site survey done; mount plan done; camera calibration done
E1 Calibration artifacts	Create roi_mask; label all slot polygons; export fass_vision_v1	Calibration artifacts removed; ROI versioned; JUnit tests pass
E2 Edge capture pipeline	RTSP ingest; frame timestamping (UTC); exposure control; frame shift detection; caps reported	Edge capture pipeline functional; performance; frame shift detection; caps reported; fps within spec

E3 Occupancy engine ROI crop/rectify; occupancy score; debounce + hysteresis to trigger events	Network latency measured between edge and server
E4 Telemetry & schema	MQTT client; topics; JSON payloads; QoS selection; Broker message delivery events summary, health; messages in backlog
E5 Reliability & ops	Store-and-forward queue (SQLite); replay; heartbeat; Network watchdog tested over loss of network connection; health monitoring
E6 Dashboard	Live map view (slot colors); free/occupied counts; Show series; state; keep history; latest queries; indicates node health
E7 Security hardening	MQTT auth + ACL; TLS if feasible; SSH key-only; New wallet; User publish/subscribe; credentials stored safely; min password length

10. Repository and dev environment

Prefer Python for rapid iteration on Pi. Containerize server if possible (Docker Compose).

```
repo/
  edge/ services/ (capture.py, occupancy.py, telemetry.py, health.py, config.py)
  calibration/ (fass_slots_v1.json, roi_mask.png, homography_v1.json)
  tests/ (schema tests, replay tests)
  systemd/ (unit files)
  server/ compose.yaml (mqtt broker, db, dashboard)
  mqtt/ (acl, users)
  dashboard/ docs/
```

10.1 Suggested technologies

- Edge: Python 3.11+, OpenCV, paho-mqtt, SQLite, psutil.
- Server: Mosquitto (MQTT), InfluxDB or Postgres, Grafana or a minimal web dashboard.
- Transport: MQTT with QoS 1 for events, QoS 0 for summaries/health.

11. Definition of Done (project acceptance)

- All visible slots are mapped and reported with stable state (no flicker) under normal daytime conditions.
- Event-driven telemetry reduces bandwidth (no raw video off-device; state events only on changes).
- Reliability: network outage test passes with buffered replay and no lost events.
- Ops: dashboard shows node health; node restarts on failure automatically.
- Power: PoE node + camera sustained for 8+ hours on one PoE run.