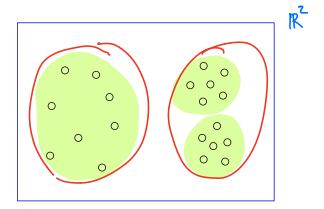
Unsupervised learning

Clustering

DSE 210

Clustering in \mathbb{R}^d



Two common uses of clustering:

- Vector quantization
 Find a finite set of representatives that provides good coverage of a complex, possibly infinite, high-dimensional space.
- Finding meaningful structure in data Finding salient grouping in data.

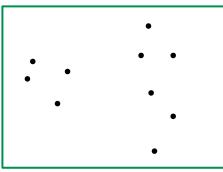
Widely-used clustering methods

- **1** *K*-means and its many variants
- **2** EM for mixtures of Gaussians
- **3** Agglomerative hierarchical clustering

Vector quantization

- Input: Points $x_1, \ldots, x_n \in \mathbb{R}^d$; integer k
- Output: "Centers", or representatives, $\mu_1, \ldots, \mu_k \in \mathbb{R}^d$
- Goal: Minimize average squared distance between points and their nearest representatives:

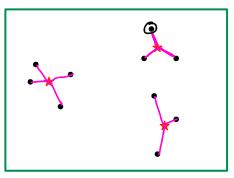
$$\cosh(\mu_1,\ldots,\mu_k) = \sum_{i=1}^n \underbrace{\min_j \|x_i - \mu_j\|^2}_{\text{squared distance}}$$
 from x_i to its closest rep.



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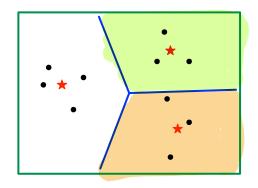
$$cost(\mu_1, ..., \mu_k) = \sum_{i=1}^n \min_j ||x_i - \mu_j||^2$$

K=3



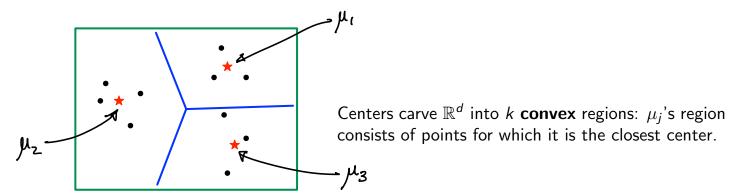
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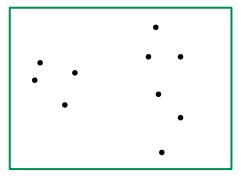


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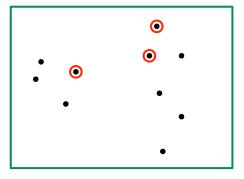
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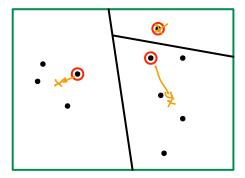
- Initialize centers μ_1, \ldots, μ_k in some manner.
- Repeat until convergence:
 - Assign each point to its closest center.
 - Update each μ_i to the mean of the points assigned to it.



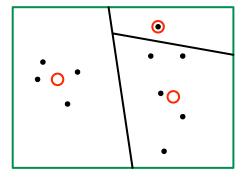
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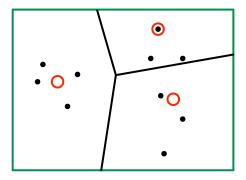
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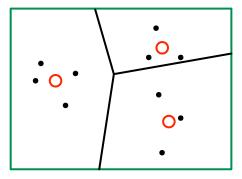
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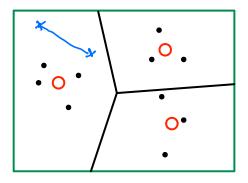


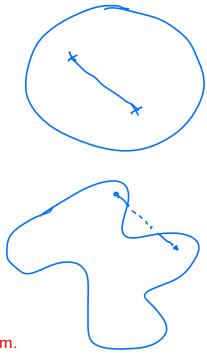
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NP-hard optimization problem. Heuristic: "k-means algorithm".

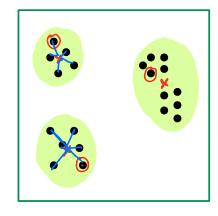
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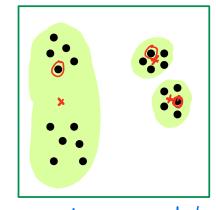


Each iteration reduces the cost \Rightarrow convergence to a local optimum.

Initialization matters



Global optimum: the solution (set of "centers" $\mu_1,...,\mu_k$) with the smallest achievable cost.



Local optimum but not global optimum

Initializing the *k***-means algorithm**

Typical practice: choose k data points at random as the initial centers.

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Another common trick: start with extra centers, then prune later.

A particularly good initializer: k-means++ (2006)

- Pick a data point x at random as the first center
- Let $C = \{x\}$ (centers chosen so far)
- Repeat until desired number of centers is attained:
 - Pick a data point x at random from the following distribution:

$$\Pr(x) \propto \operatorname{dist}(x, C)^2$$

where
$$dist(x, C) = min_{z \in C} ||x - z||$$

• Add *x* to *C*





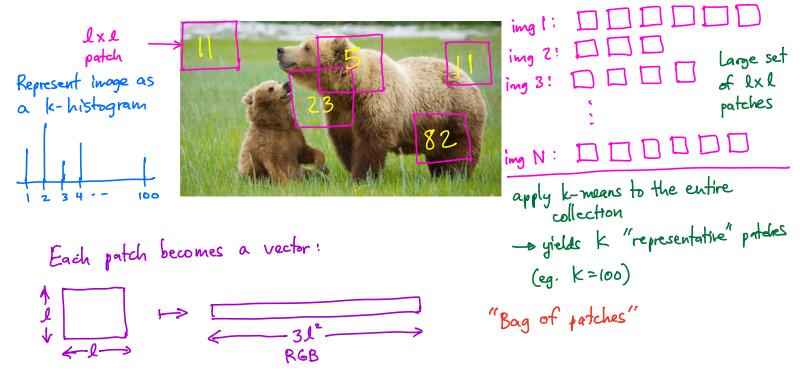
Two common uses of clustering

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Representing images using *k*-means codewords

Vector quantization example

How to represent a collection of images as fixed-length vectors?



Representing images using *k*-means codewords

How to represent a collection of images as fixed-length vectors?



- Take all $\ell \times \ell$ patches in all images. Extract features for each.
- Run *k*-means on this entire collection to get *k* centers.
- Now associate any image patch with its nearest center.
- Represent an image by a histogram over $\{1, 2, ..., k\}$.

Looking for natural groups in data

"Animals with attributes" data set

- 50 animals: antelope, grizzly bear, beaver, dalmatian, tiger, ...
- 85 attributes: longneck, tail, walks, swims, nocturnal, forager, desert, bush, plains, ...
- Each animal gets a score (0-100) along each attribute
- 50 data points in \mathbb{R}^{85}

Apply k-means with k = 10 and look at grouping obtained.

Two different solutions starting from random initializations

- zebra
- 2 spider monkey, gorilla, chimpanzee
- 3 tiger, leopard, wolf, bobcat, lion
- 4 hippopotamus, elephant, rhinoceros
- **5** killer whale, blue whale, humpback whale, seal, walrus, dolphin
- 6 giant panda
- 7 skunk, mole, hamster, squirrel, rabbit, bat, rat, weasel, mouse, raccoon
- **3** antelope, horse, moose, ox, sheep, giraffe, buffalo, deer, pig, cow
- 9 beaver, otter
- grizzly bear, dalmatian, persian cat, german shepherd, siamese cat, fox, chihuahua, polar bear, collie

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- beaver, skunk, mole, squirrel, bat, rat, weasel, mouse, raccoon
- 8 antelope, horse, moose, ox, sheep, giraffe, deer, cow
- hamster, rabbit
- n grizzly bear, polar bear

Streaming and online computation

Streaming computation: for data sets too large to fit in memory.

- Make one pass (or maybe a few passes) through the data.
- On each pass:
 - See data points one at a time, in order.
 - Update models/parameters along the way.
- There is only enough space to store a tiny fraction of the data, or a perhaps short summary.

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Online computation: an even more lightweight setup, for data that is continuously being collected.

- Initialize a model.
- Repeat forever:
 - See a new data point.
 - Update model if need be.

Example: sequential *k*-means

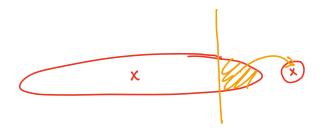
- 1) Set the centers μ_1, \ldots, μ_k to the first k data points
- 2 Set their counts to $n_1 = n_2 = \cdots = n_k = 1$
- 3 Repeat, possibly forever:
 - Get next data point x
 - Let μ_i be the center closest to x
 - Update μ_i and n_i :

$$\mu_j = \frac{n_j \mu_j + x}{n_j + 1}$$
 and $n_j = n_j + 1$
average x

K-means: the good and the bad

The good:

- Fast and easy.
- Effective in quantization.

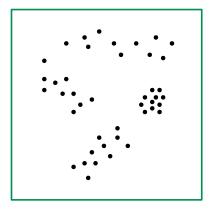


The bad:

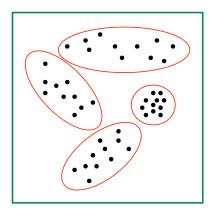
• Geared towards data in which the clusters are spherical, and of roughly the same radius.

Is there is a similarly-simple algorithm in which clusters of more general shape are accommodated?

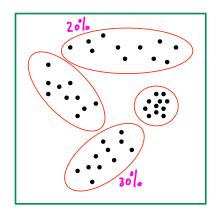
Mixtures of Gaussians



Mixtures of Gaussians



Mixtures of Gaussians



K-means: each cluster only gets a center Now: each cluster gets its own Gaussian distribution

Each of the k clusters is specified by:

- ullet a Gaussian distribution $P_j = \mathcal{N}(\mu_j, \Sigma_j)$
- a mixing weight π_j

Overall distribution over \mathbb{R}^d : a **mixture of Gaussians**

$$Pr(x) = \pi_1 P_1(x) + \cdots + \pi_k P_k(x)$$

The clustering task

We are given data $x_1, \ldots, x_n \in \mathbb{R}^d$.

For any mixture model $\pi_1, \ldots, \pi_k, \ P_1 = N(\mu_1, \Sigma_1), \ldots, P_k = N(\mu_k, \Sigma_k)$,

$$\Pr\left(\text{data} \mid \pi_1 P_1 + \dots + \pi_k P_k\right)$$

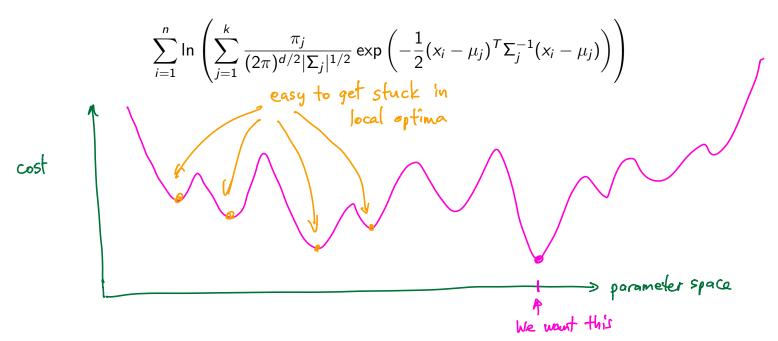
$$= \prod_{i=1}^n \left(\pi_1 P_1(x_i) + \dots + \pi_k P_k(x_i)\right) \quad \text{probability of } X_i \quad \text{under the mixture model}$$

$$= \prod_{i=1}^n \left(\sum_{j=1}^k \frac{\pi_j}{(2\pi)^{d/2} |\Sigma_j|^{1/2}} \exp\left(-\frac{1}{2}(x_i - \mu_j)^T \Sigma_j^{-1}(x_i - \mu_j)\right)\right)$$

Find the maximum-likelihood mixture of Gaussians: parameters $\{\pi_j, \mu_j, \Sigma_j : j = 1 \dots k\}$ maximizing this function.

Optimization surface

Minimize the negative log-likelihood,



The EM algorithm

- 1 Initialize π_1, \ldots, π_k and $P_1 = N(\mu_1, \Sigma_1), \ldots, P_k = N(\mu_k, \Sigma_k)$.
- 2 Repeat until convergence:
 - Assign each point x_i fractionally between the k clusters:

$$w_{ij} = \Pr(\mathsf{cluster}\; j \mid x_i) = \frac{\pi_j P_j(x_i)}{\sum_{\ell} \pi_{\ell} P_{\ell}(x_i)}$$

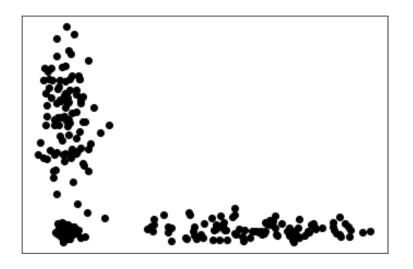
• Update mixing weights, means, and covariances:

$$\pi_{j} = \frac{1}{n} \sum_{i=1}^{n} w_{ij}$$

$$\mu_{j} = \frac{1}{n\pi_{j}} \sum_{i=1}^{n} w_{ij} x_{i}$$

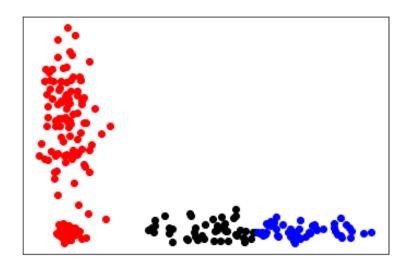
$$\Sigma_{j} = \frac{1}{n\pi_{j}} \sum_{i=1}^{n} w_{ij} (x_{i} - \mu_{j}) (x_{i} - \mu_{j})^{T}$$

Data with 3 clusters, each with 100 points.



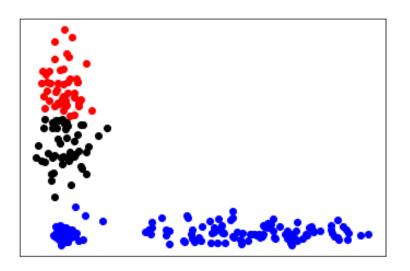
The data set

Data with 3 clusters, each with 100 points.



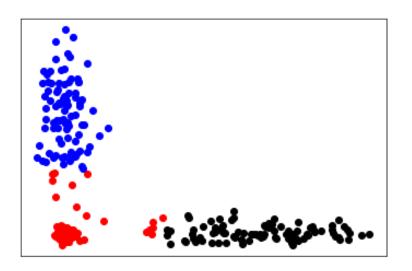
k-means solution 1

Data with 3 clusters, each with 100 points.



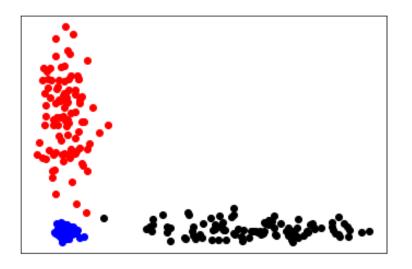
k-means solution 2

Data with 3 clusters, each with 100 points.



k-means solution 3

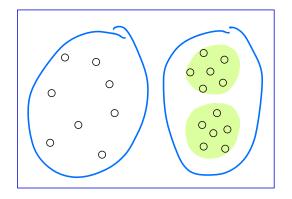
Data with 3 clusters, each with 100 points.



EM for mixture of Gaussians

Hierarchical clustering

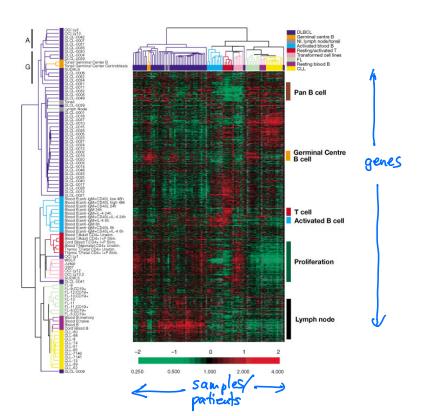
Choosing the number of clusters (k) is difficult.



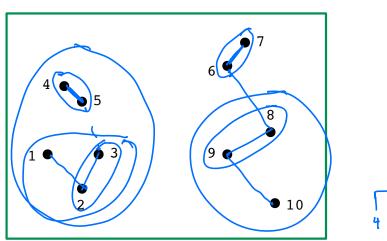
Often: no single right answer, because of multiscale structure.

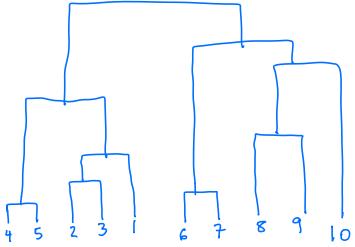
Hierarchical clustering avoids these problems.

Example: gene expression data



The single linkage algorithm





- Start with each point in its own, singleton, cluster
- Repeat until there is just one cluster:
 - Merge the two clusters with the closest pair of points
- Disregard singleton clusters

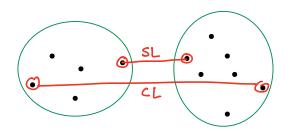
Linkage methods

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How to measure distance between two clusters C and C'?



Single linkage

$$\operatorname{dist}(C,C') = \min_{x \in C, x' \in C'} \|x - x'\|$$

Complete linkage

$$\mathsf{dist}(C,C') = \max_{x \in C, x' \in C'} \|x - x'\|$$

Average linkage

Three commonly-used variants:

1 Average pairwise distance between points in the two clusters

$$dist(C, C') = \frac{1}{|C| \cdot |C'|} \sum_{x \in C} \sum_{x' \in C'} ||x - x'||$$

2 Distance between cluster centers

$$dist(C, C') = ||mean(C) - mean(C')||$$

3 Ward's method: the increase in k-means cost occasioned by merging the two clusters

$$\operatorname{dist}(C,C') = \frac{|C| \cdot |C'|}{|C| + |C'|} \|\operatorname{mean}(C) - \operatorname{mean}(C')\|^2$$