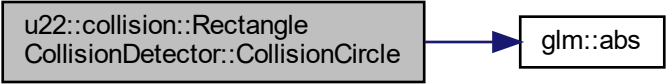


u22::collision::Rectangle
CollisionDetector::CollisionCircle



```
graph LR; A["u22::collision::Rectangle  
CollisionDetector::CollisionCircle"] --> B["glm::abs"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains two lines of text: 'u22::collision::Rectangle' and 'CollisionDetector::CollisionCircle'. The right box is white and contains the text 'glm::abs'. A dark blue arrow points from the right side of the gray box to the left side of the white box.

glm::abs