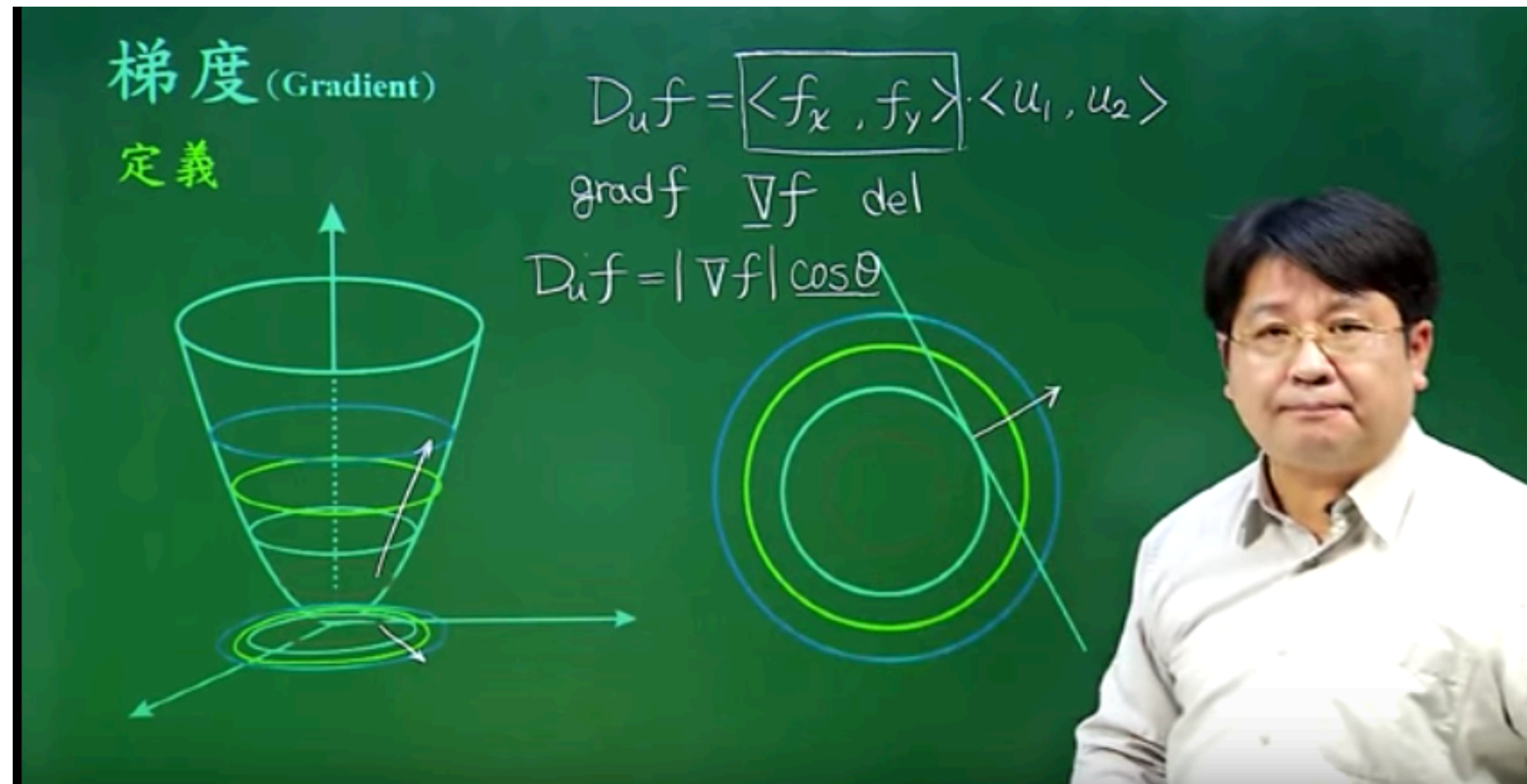


Deep into Neural Network from Gradient Descent

Gradient 梯度



<https://www.youtube.com/watch?v=npkl19rcpdY>

在向量微積分中，純量場的梯度是一個向量場。純量場中某一點的梯度指向在這點純量場增長最快的方向（當然要比較的話必須固定方向的長度），梯度的絕對值是長度為1的方向中函數最大的增加率，也就是說 ∇f 。

梯度- 維基百科，自由的百科全書 - Wikipedia

<https://zh.wikipedia.org/zh-tw/梯度>

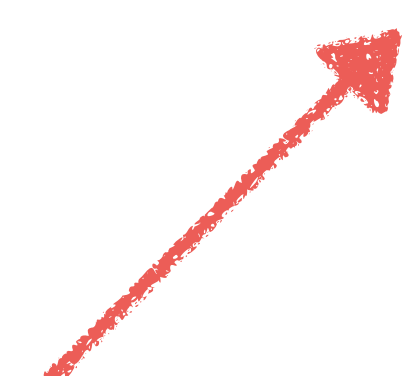
$$f = x^2 + y^2$$

$$\text{grad} = \langle 2x, 2y \rangle$$

* 分別對 x, y 偏微

* *example:*

when in point $\langle 1, 2 \rangle$

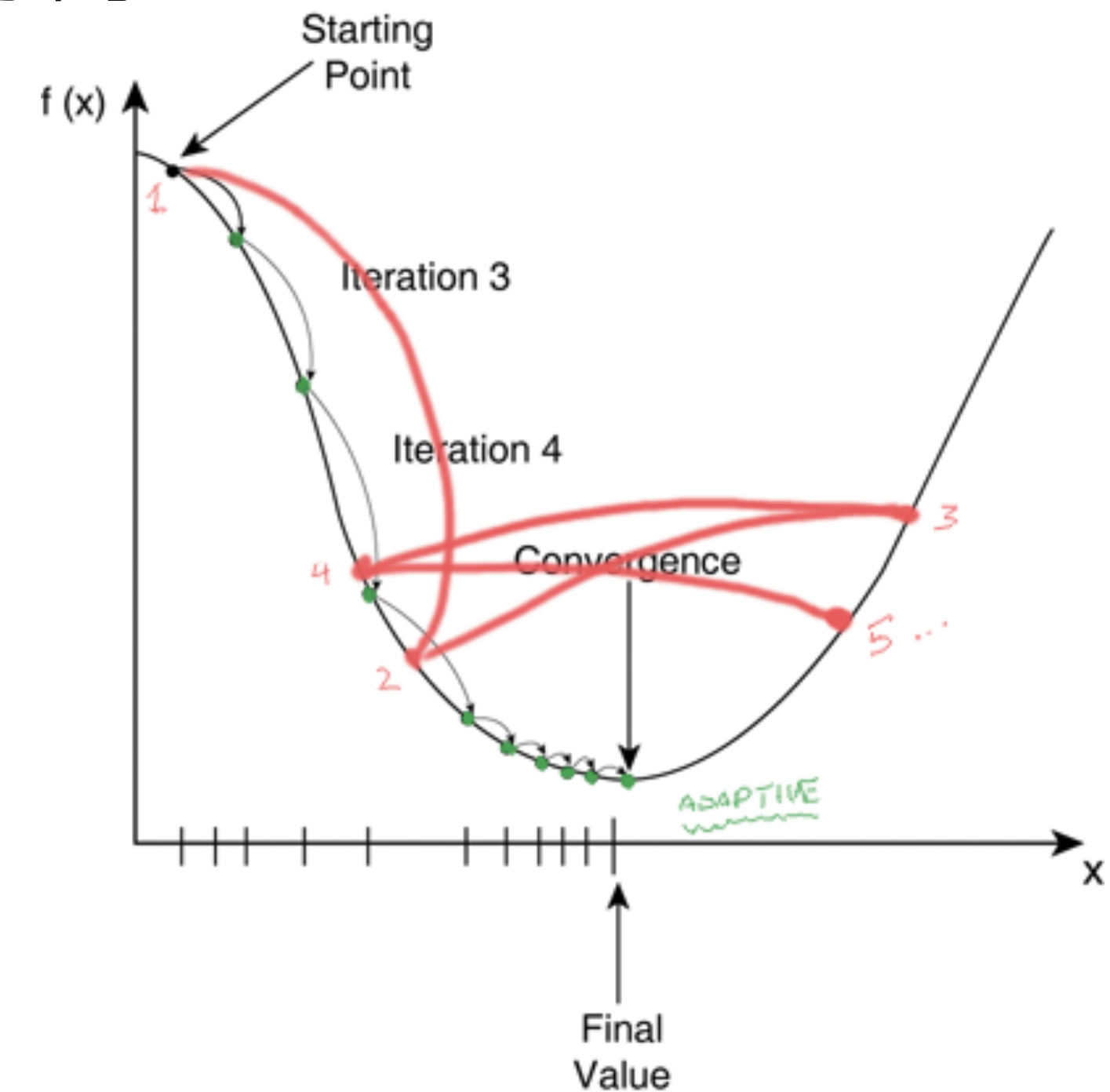


then grad = vector $\langle 2, 4 \rangle$

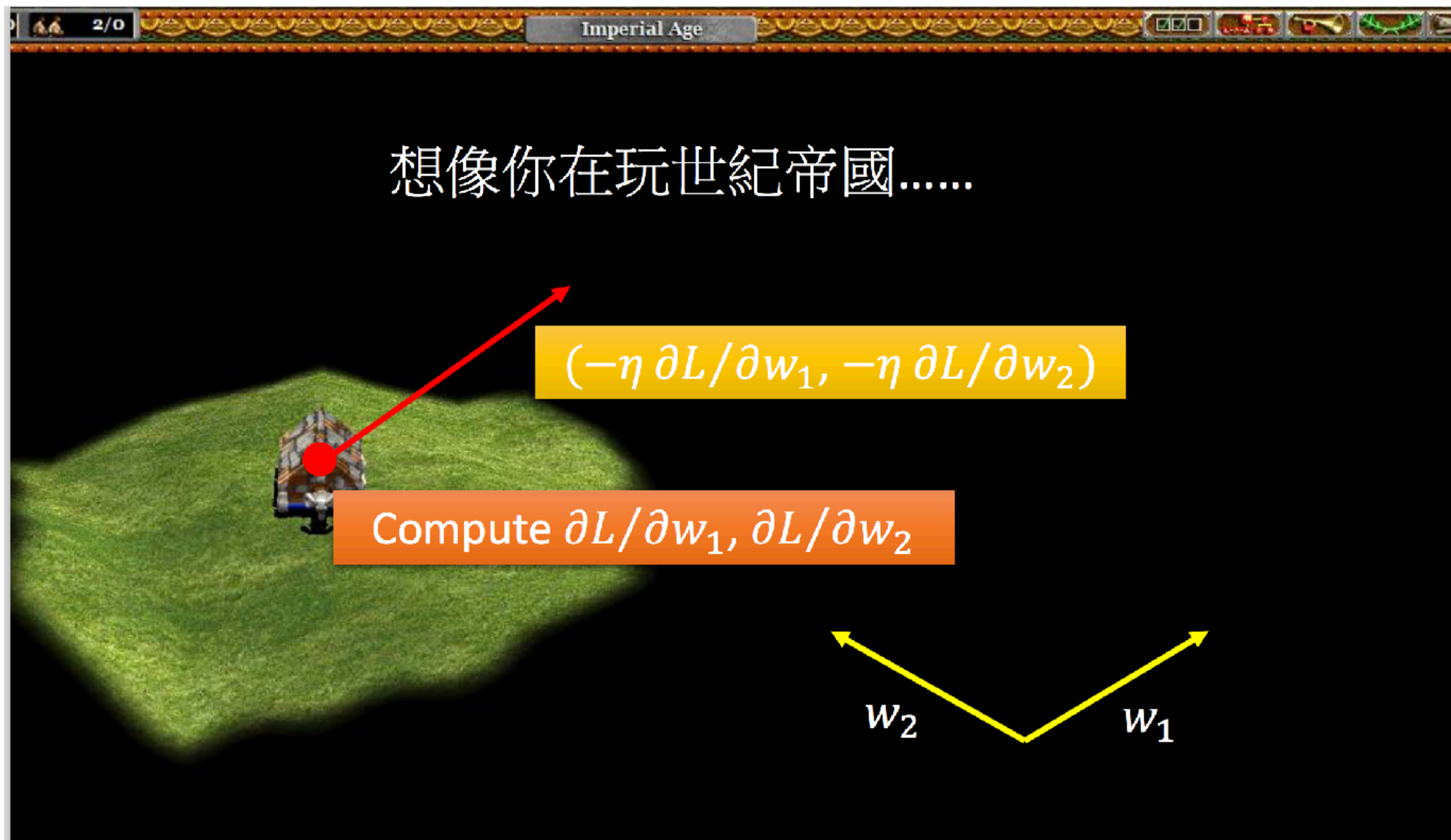
就是在點(1, 2)時，在 $\langle 2, 4 \rangle$ 的方向
坡度最陡（最難爬的方向）

Gradient Descent 梯度下降法

- 所以在X, Y點時, gradient的相反方向就是最好下降的方向
- 但跳太大步可能會跳到坑洞的另一方
- 跳太小步又很孱種(太慢了！)
- 跳的大小程度就是learning rate
- 每次都跳一樣大、越跳越小等等就是策略
- AdamOptimizer就是一種策略
- 每次前進前要用多少資料描繪當時可能的地形(1 vs mini-batch)



往當時下坡度最大的方向跳的程度
→



對方程式做Gradient Descent

$$\text{MSE}(\mathbf{X} h_{\theta}) = \frac{1}{m} \sum_{i=1}^m (\theta^T \cdot \mathbf{x}^{(i)} - y^{(i)})^2$$

..... $\rightarrow w_1 \cdot x^{(i)}_1 + w_2 \cdot x^{(i)}_2 + \dots w_j \cdot x^{(i)}_j + \dots$

$$\frac{\partial}{\partial \theta_j} \text{MSE}(\theta) = \frac{2}{m} \sum_{i=1}^m (\theta^T \cdot \mathbf{x}^{(i)} - y^{(i)}) x_j^{(i)}$$

$$\nabla_{\theta} \text{MSE}(\theta) = \begin{pmatrix} \frac{\partial}{\partial \theta_0} \text{MSE}(\theta) \\ \frac{\partial}{\partial \theta_1} \text{MSE}(\theta) \\ \vdots \\ \frac{\partial}{\partial \theta_n} \text{MSE}(\theta) \end{pmatrix} = \frac{2}{m} \mathbf{X}^T \cdot (\mathbf{X} \cdot \theta - \mathbf{y})$$

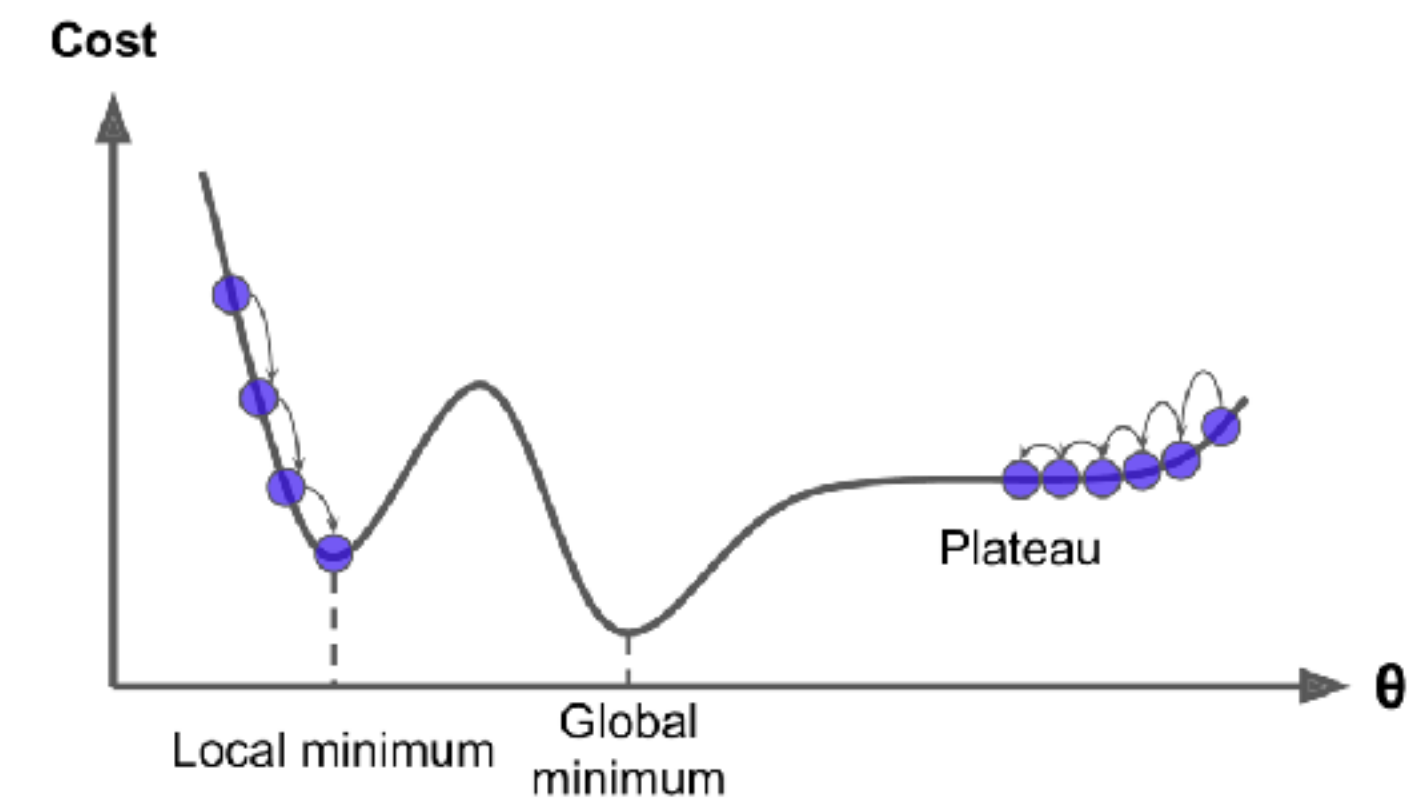


Figure 4-5. Gradient Descent pitfalls

$$\theta^{(\text{next step})} = \theta - \eta \nabla_{\theta} \text{MSE}(\theta)$$

$$X = \begin{bmatrix} [1, 2, 1] \\ [2, 3, 1] \end{bmatrix}$$

(2, 3)

$$\theta = \begin{bmatrix} [0.5] \\ [0.75] \\ [0.25] \end{bmatrix}$$

(3, 1)

$$y = \begin{bmatrix} [4] \\ [6] \end{bmatrix}$$

(2, 1)

$$X \cdot \theta = \begin{bmatrix} [2.25] \\ [3.5] \end{bmatrix}$$

$$\text{MSE}(X h_{\theta}) = \frac{1}{m} \sum_{i=1}^m (\theta^T \cdot x^{(i)} - y^{(i)})^2$$

$$X \cdot \theta - y = \text{error} = \begin{bmatrix} [-1.75] \\ [-2.5] \end{bmatrix}$$

$$\nabla J = \left(\frac{2}{m} \sum_{i=1}^m \left(\underbrace{x^{(i)} \cdot w}_{y_{\text{pred}}} - y \right) x^{(i)} \right)$$

error (都-様)

$$= \frac{2}{m} \begin{bmatrix} [-1.75 \times 1 + -2.5 \times 2] \\ [-1.75 \times 2 + -2.5 \times 3] \\ [-1.75 \times 1 + -2.5 \times 1] \end{bmatrix}$$

$$= \begin{bmatrix} [-6.95] \\ [-11] \\ [-4.25] \end{bmatrix}$$

\Rightarrow if η (learning rate) = 0.01

$$\theta_2 \leftarrow \theta_1 - 0.01 \times \nabla J$$

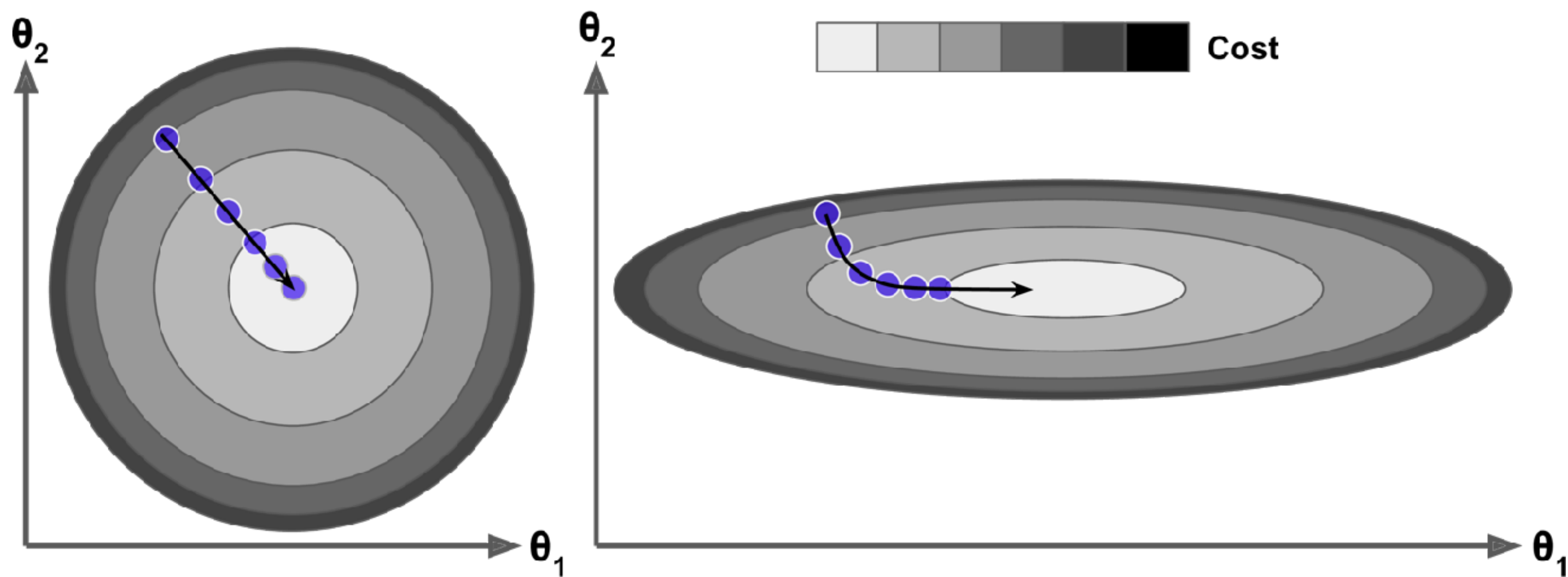
$$= \begin{bmatrix} [0.5] \\ [0.75] \\ [0.25] \end{bmatrix} - 0.01 \begin{bmatrix} [-6.95] \\ [-11] \\ [-4.25] \end{bmatrix} = \begin{bmatrix} [0.5695] \\ [0.86] \\ [0.2925] \end{bmatrix}$$

$$\theta^{(\text{next step})} = \theta - \eta \nabla_{\theta} \text{MSE}(\theta)$$

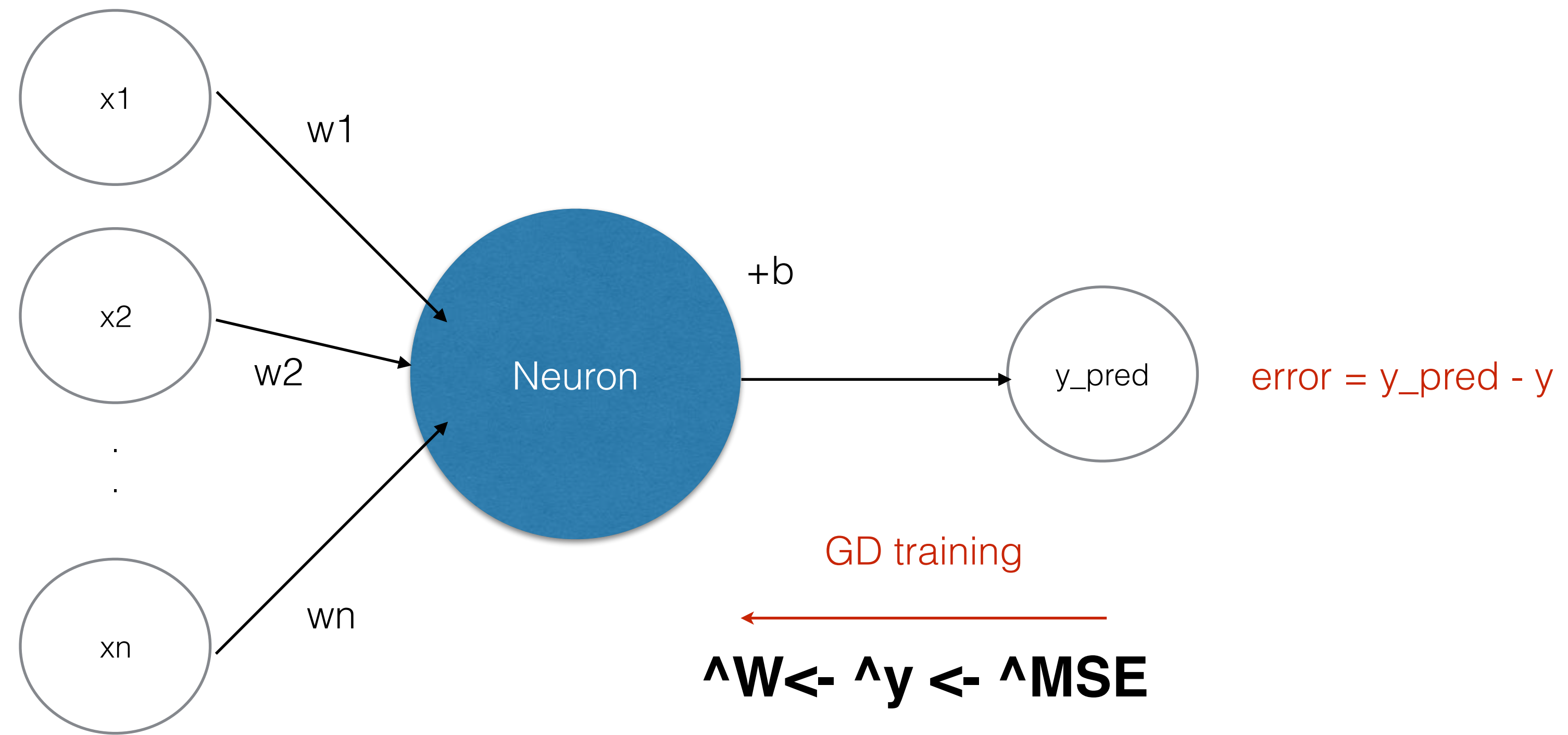
$\theta_{\text{next step}} \rightarrow \dots$

$$\frac{\partial}{\partial \theta_j} \text{MSE}(\theta) = \frac{2}{m} \sum_{i=1}^m (\theta^T \cdot x^{(i)} - y^{(i)}) x_j^{(i)}$$

做Gradient Descent前, 要scaled features!

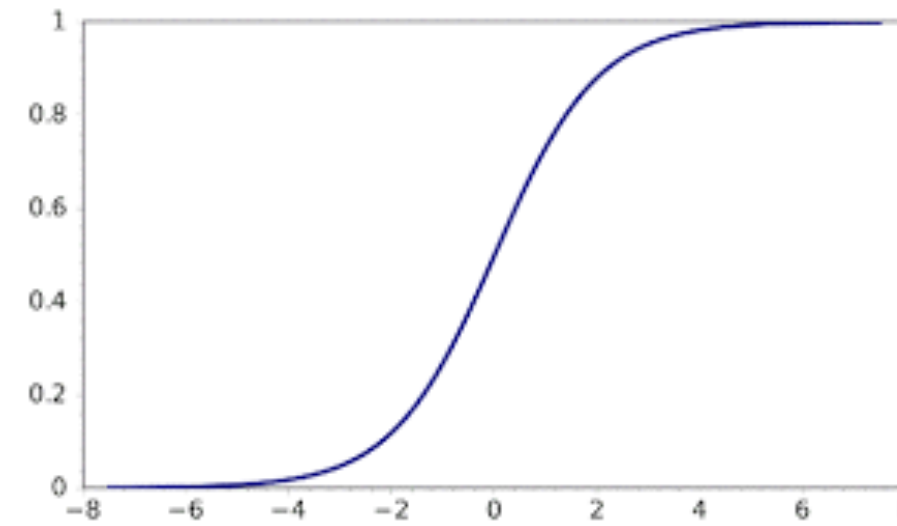
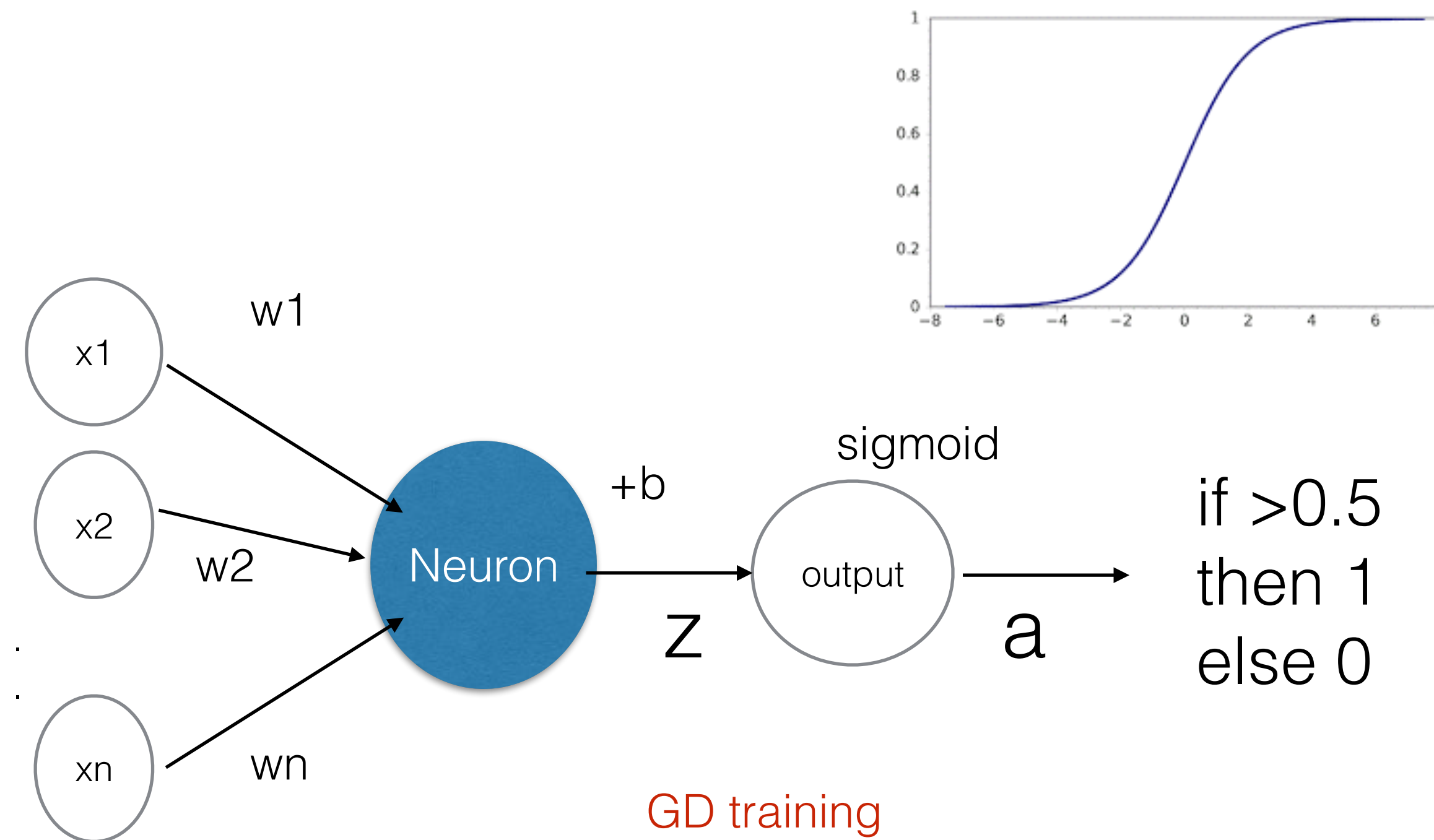


練習1: Linear Regression



最小化MSE訓練出W

Logistic Regression



$$H = - \sum_i (p_i \cdot \log_2(q_i))$$

$$\begin{aligned} -5 \cdot 5 &= -25 \\ -4 \cdot 6 &= -24 \\ -3 \cdot 7 &= -21 \end{aligned}$$

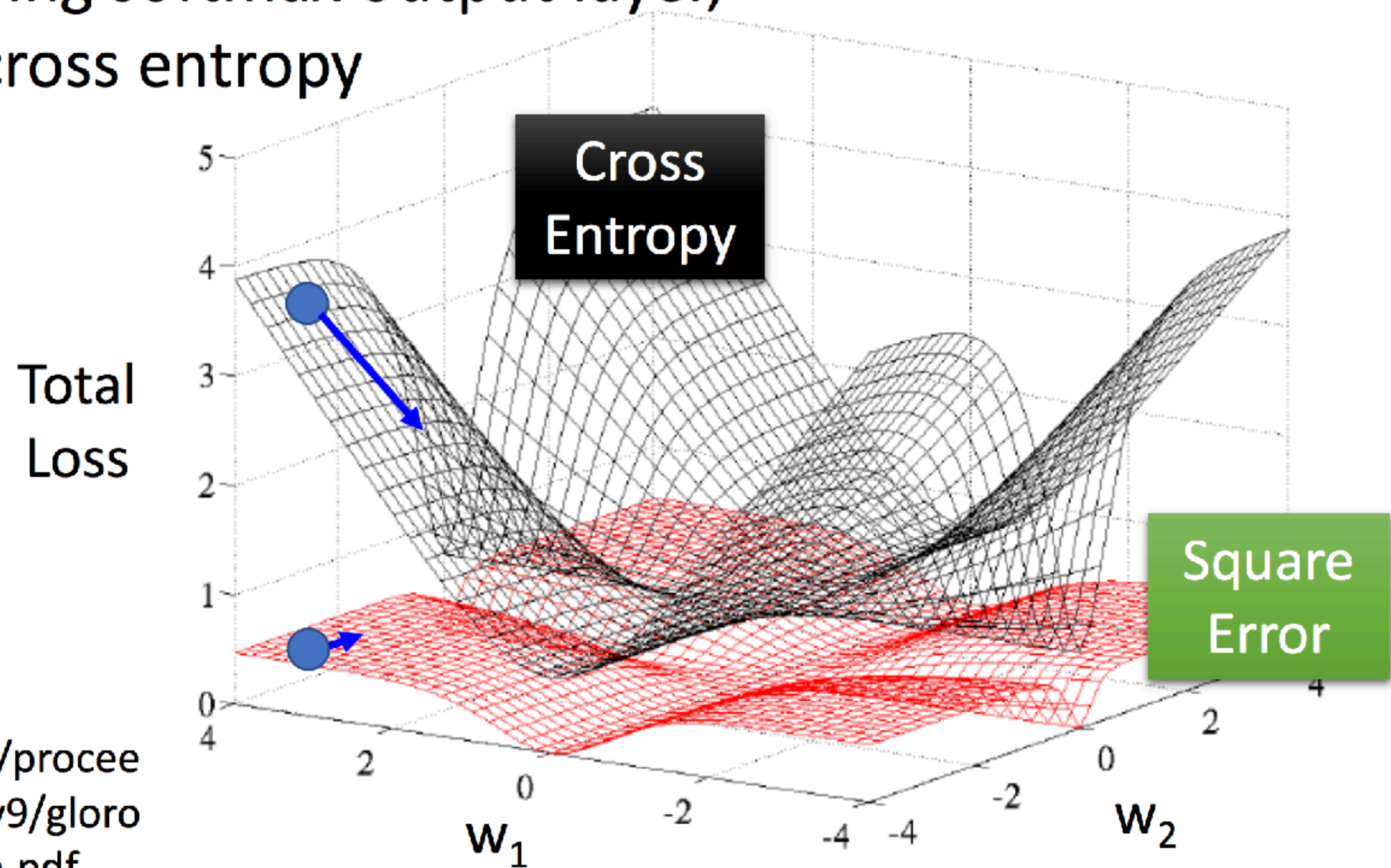
$$J(\theta) = -\frac{1}{m} \sum_{i=1}^m [y^{(i)} \log(\hat{p}^{(i)}) + (1 - y^{(i)}) \log(1 - \hat{p}^{(i)})]$$

$$\hat{W} \leftarrow \hat{z} \leftarrow \hat{a}(\text{sigmoid 斜率}) \leftarrow \hat{\text{loss}}$$

最小化Cross Entropy訓練出W

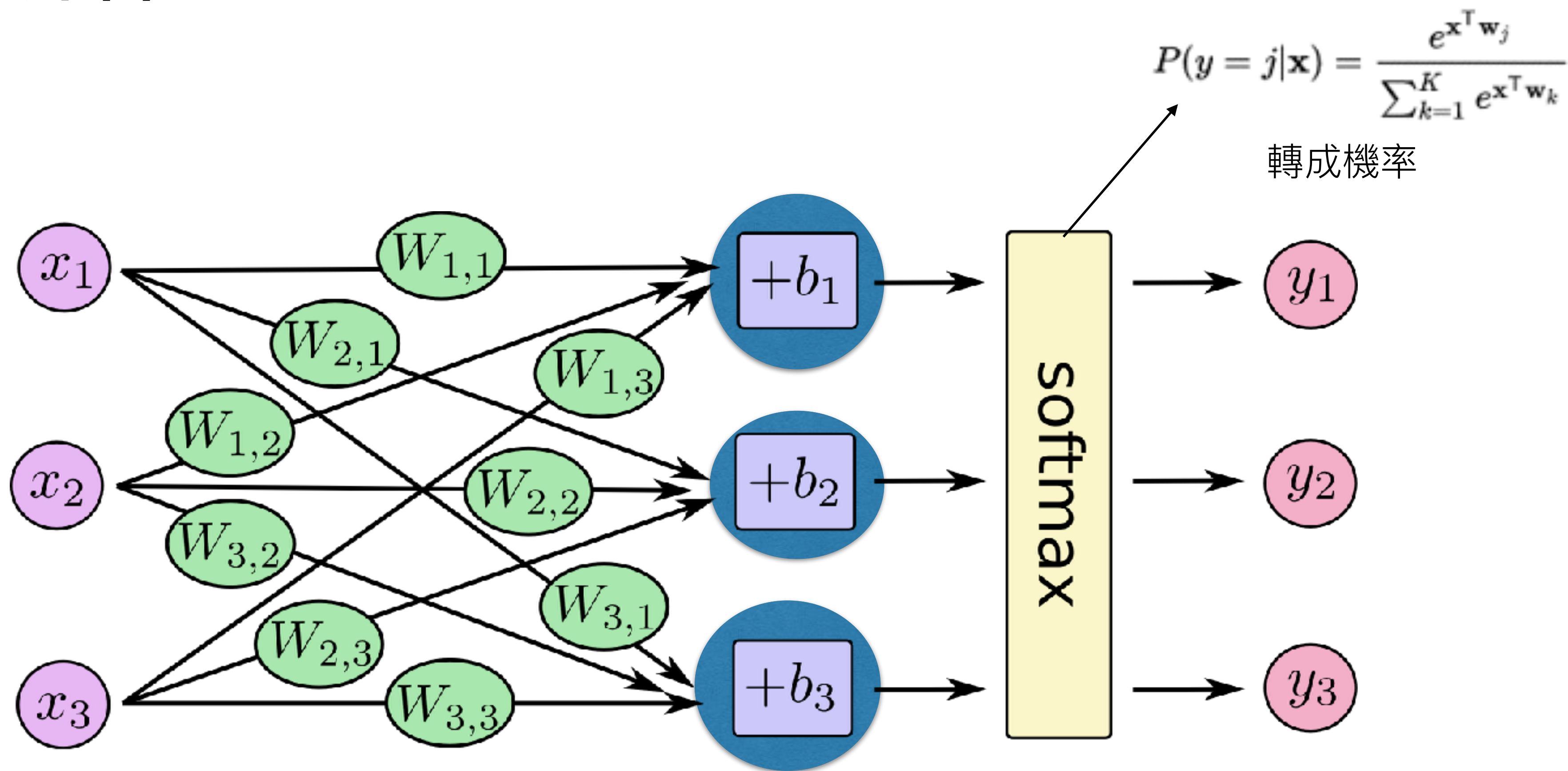
Choosing Proper Loss

When using softmax output layer,
choose cross entropy



<http://jmlr.org/proceedings/papers/v9/glorot10a/glorot10a.pdf>

練習2: Softmax classification



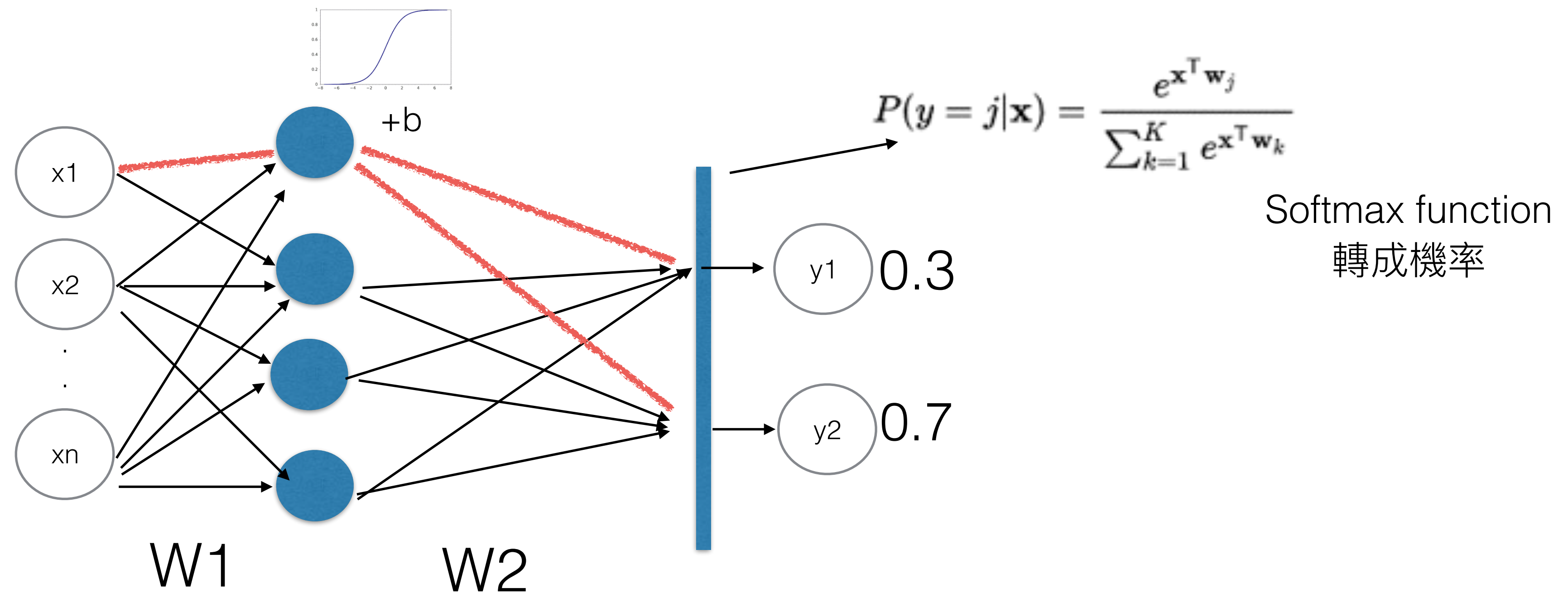
$$loss = - \sum_i \sum_c y_{c_i} \cdot \log(y_predicted_{c_i})$$

最小化Cross Entropy訓練出W

Neural Network

GD training

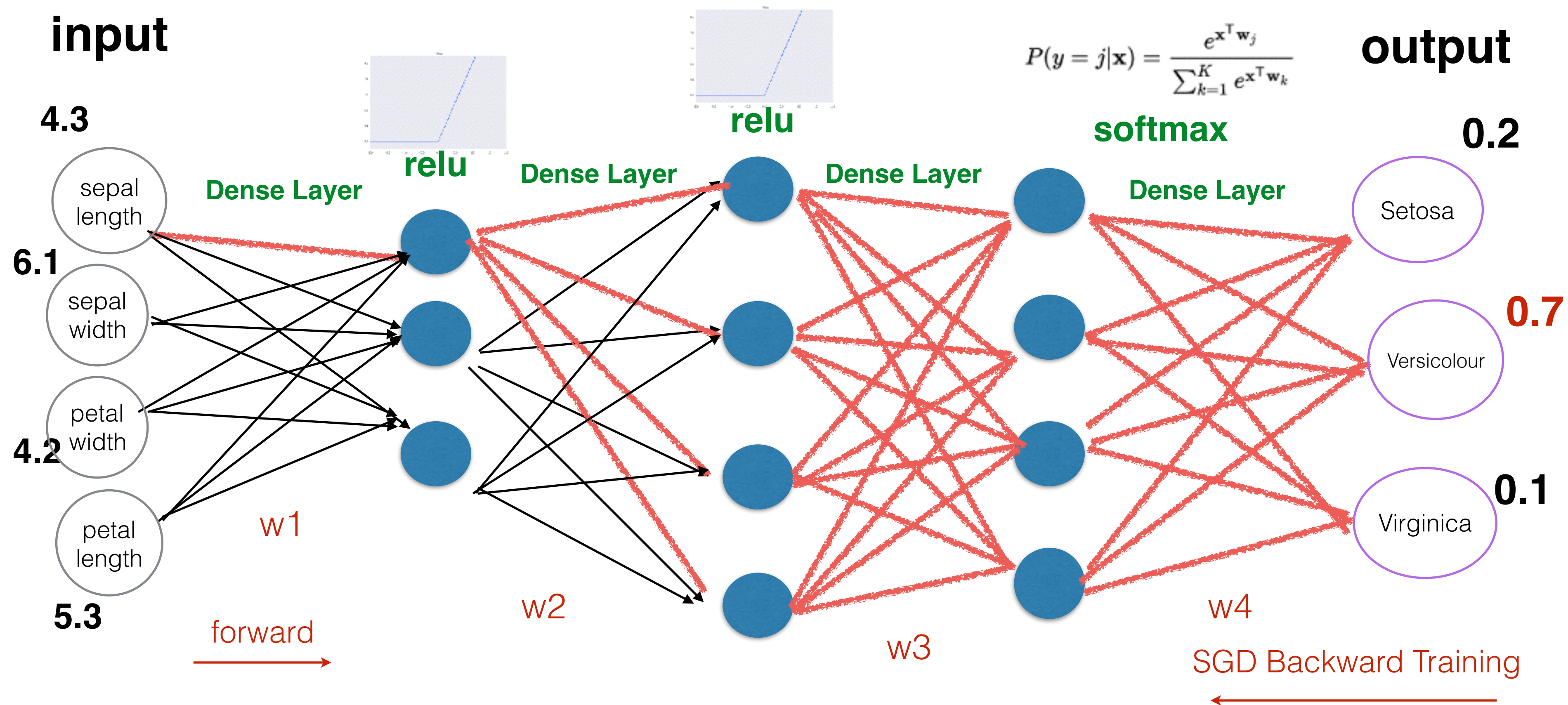
$$\hat{z} \leftarrow \hat{a} \leftarrow \hat{w}_{21} + \hat{w}_{22} \leftarrow \hat{C}$$



最小化Cross Entropy訓練出W2

W1的改變會擴散到W1 -> **Backpropagation**

練習3: Build your neural network

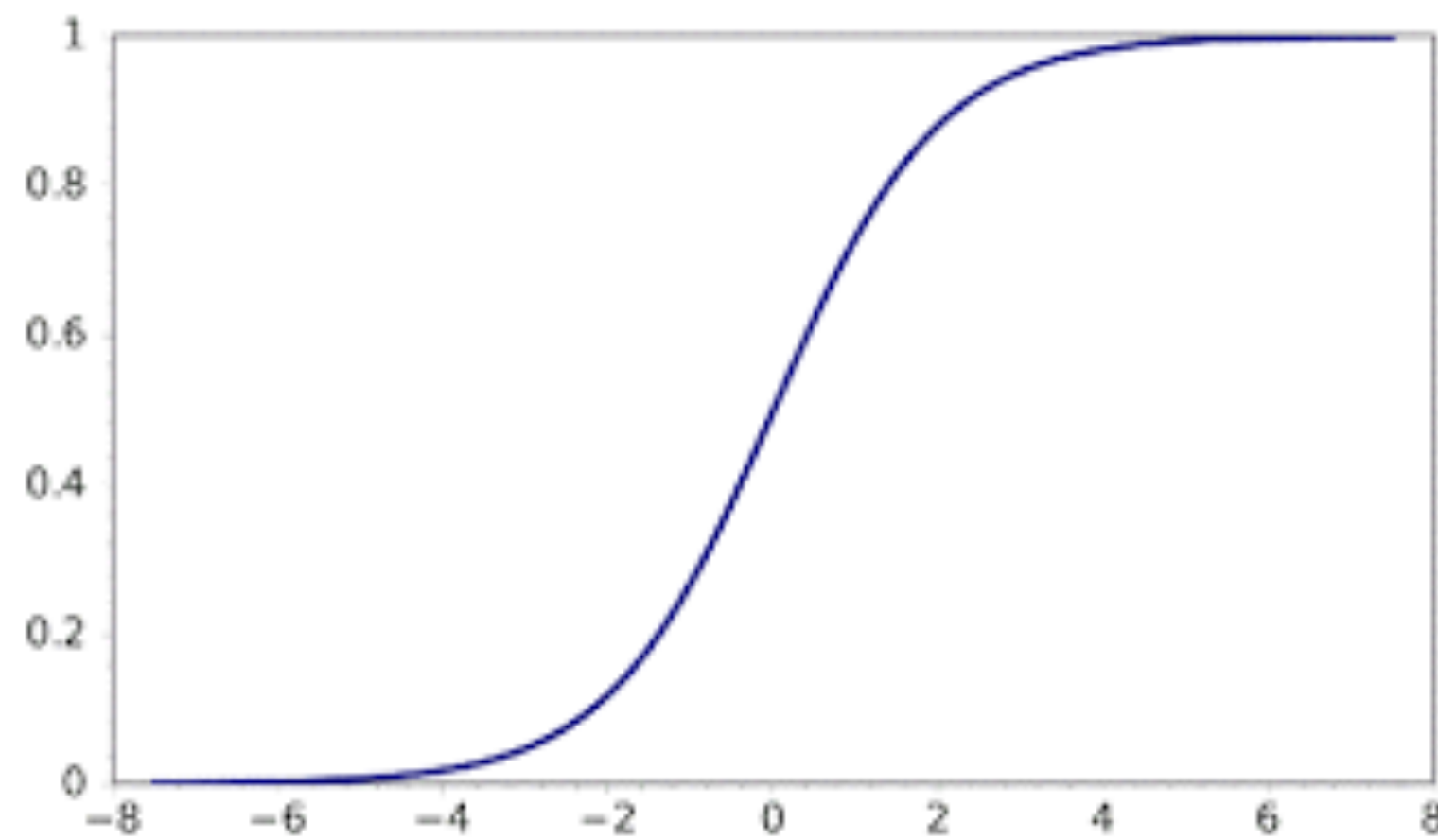


loss function to minimize:
cross entropy

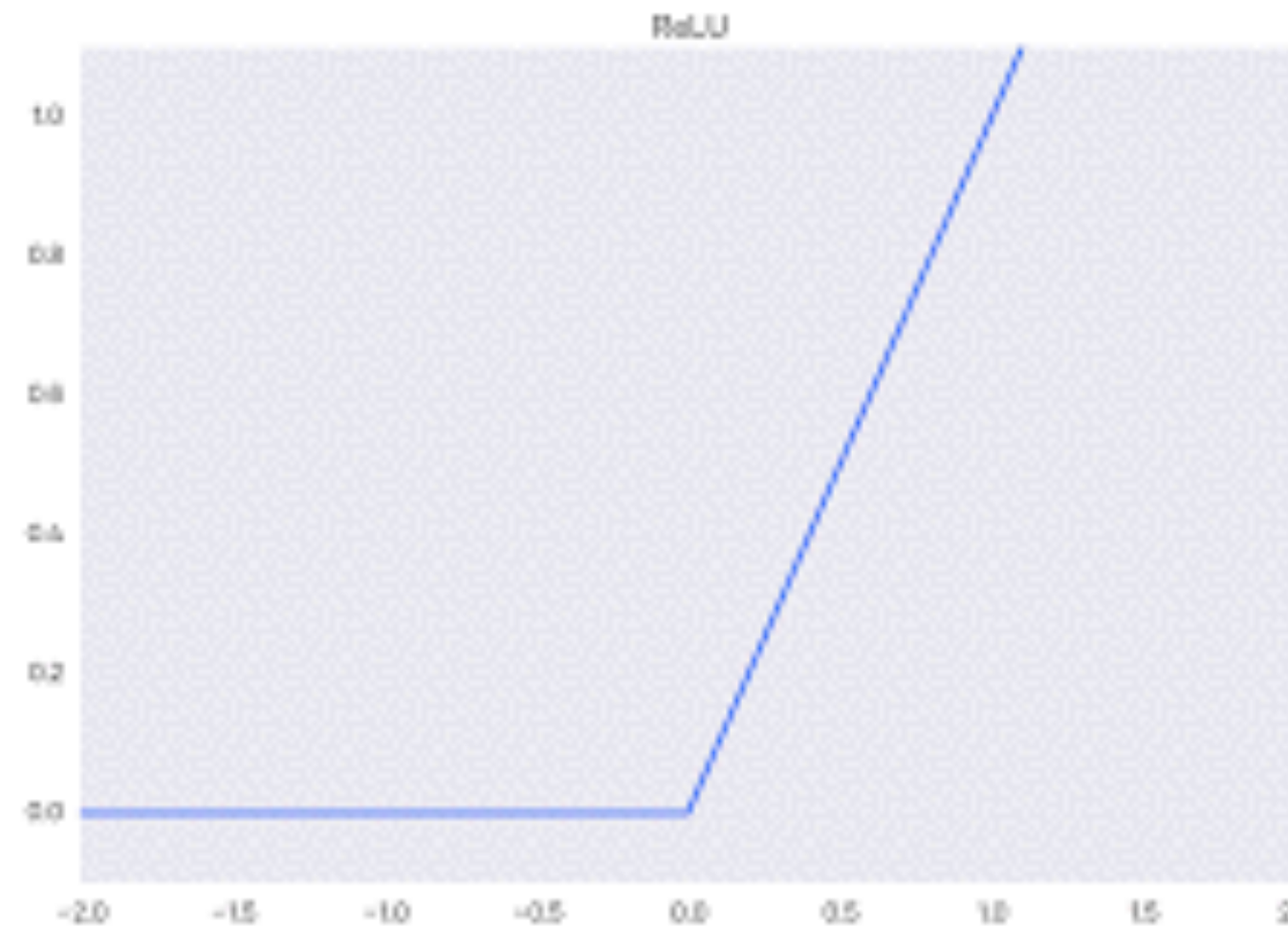
深層網路的BP會層層往後更新

Question

Why from Sigmoid to Relu?

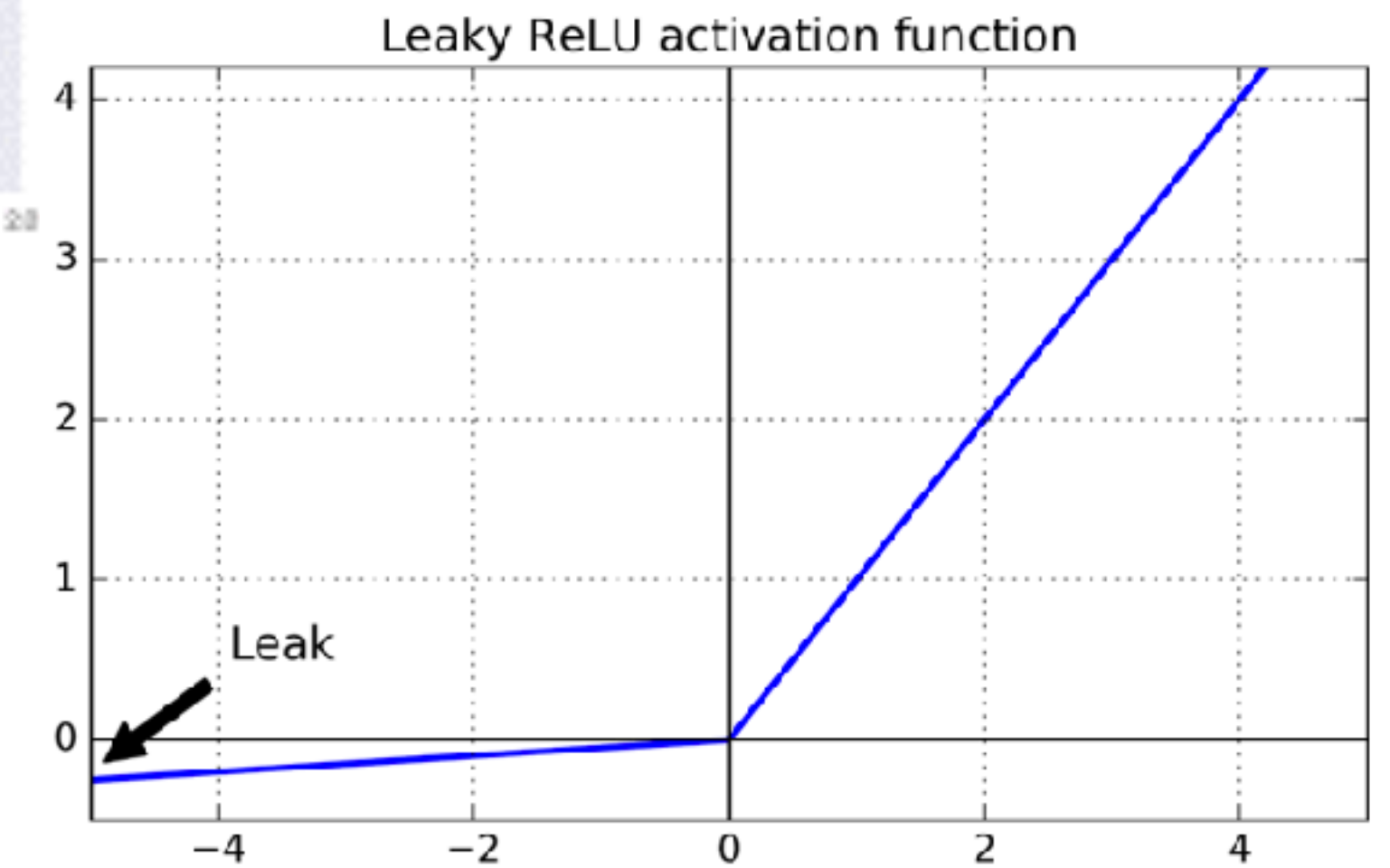
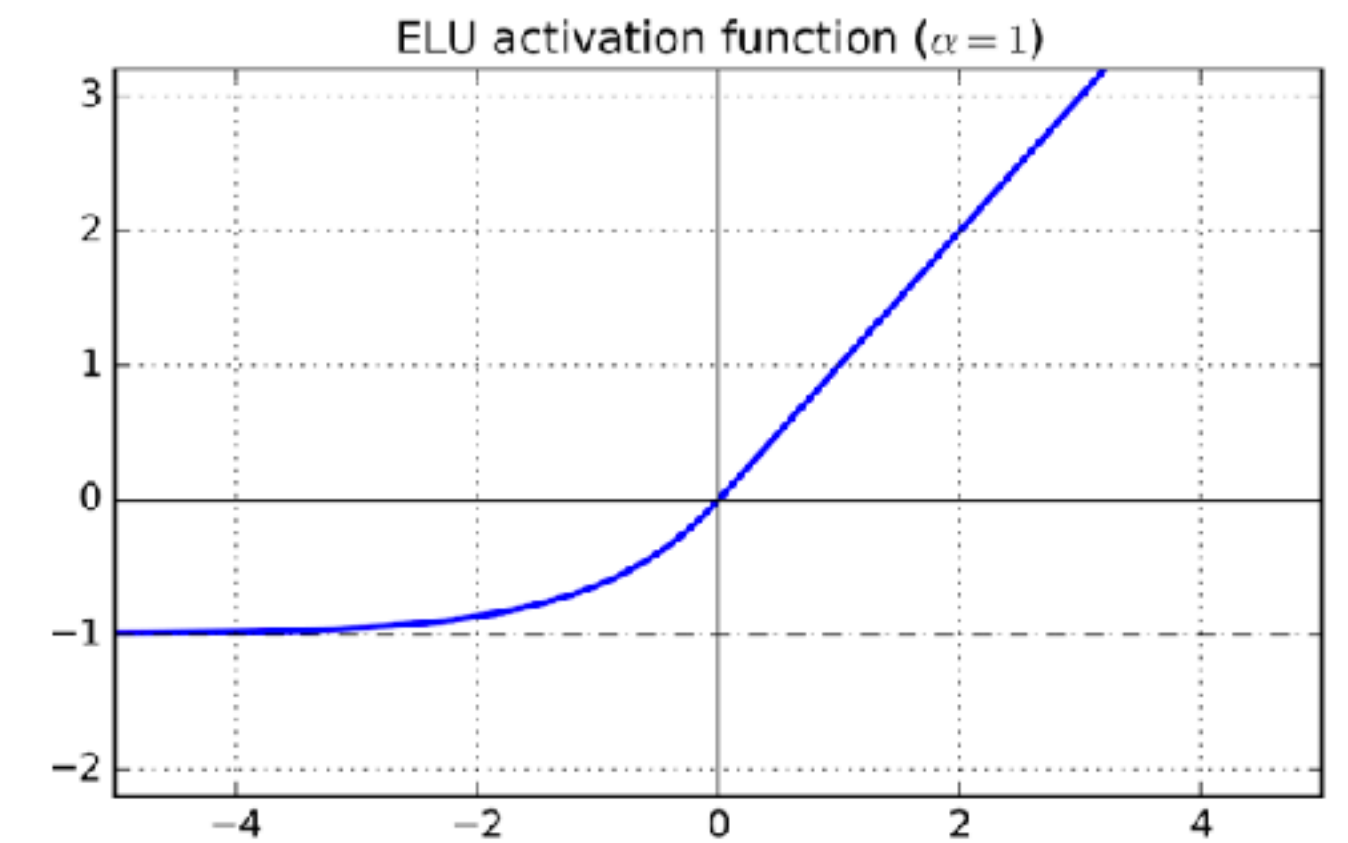


sigmoid



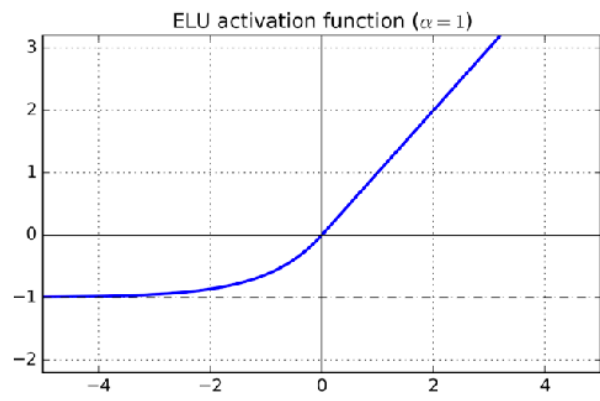
relu

$$\text{ELU}_{\alpha}(z) = \begin{cases} \alpha(\exp(z) - 1) & \text{if } z < 0 \\ z & \text{if } z \geq 0 \end{cases}$$



Ways to improve DNN

$$\text{ELU}_\alpha(z) = \begin{cases} \alpha(\exp(z) - 1) & \text{if } z < 0 \\ z & \text{if } z \geq 0 \end{cases}$$



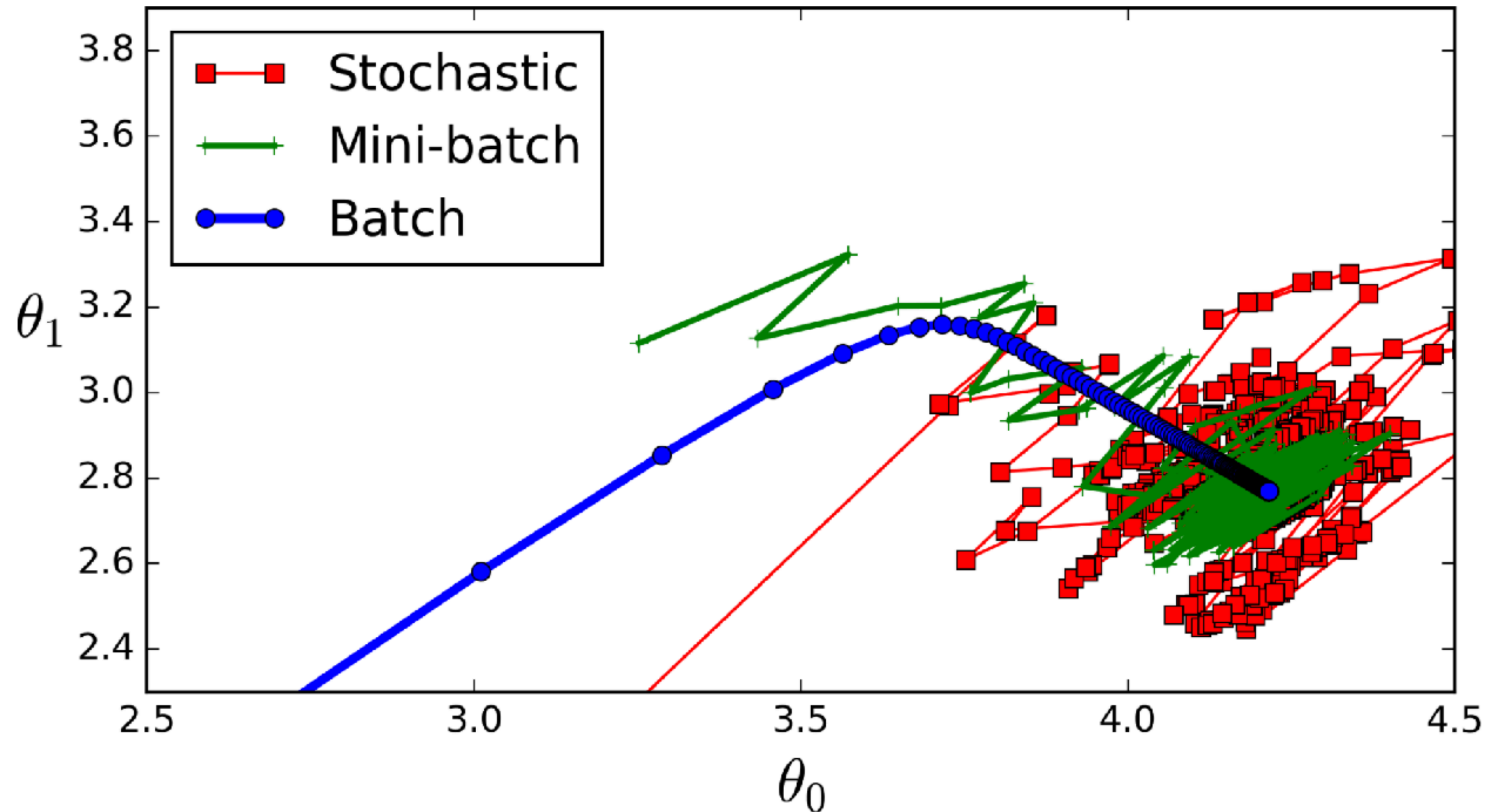
- Weight Initialization - He initialization
- Activation function - ELU
- Normalization - Batch Normalization
- Regularization - Dropout
- Optimizer - Adam
- Check 一天搞懂深度學習

Activation function	Uniform distribution [-r, r]	Normal distribution
Logistic	$r = \sqrt{\frac{6}{n_{\text{inputs}} + n_{\text{outputs}}}}$	$\sigma = \sqrt{\frac{2}{n_{\text{inputs}} + n_{\text{outputs}}}}$
Hyperbolic tangent	$r = 4\sqrt{\frac{6}{n_{\text{inputs}} + n_{\text{outputs}}}}$	$\sigma = 4\sqrt{\frac{2}{n_{\text{inputs}} + n_{\text{outputs}}}}$
ReLU (and its variants)	$r = \sqrt{2}\sqrt{\frac{6}{n_{\text{inputs}} + n_{\text{outputs}}}}$	$\sigma = \sqrt{2}\sqrt{\frac{2}{n_{\text{inputs}} + n_{\text{outputs}}}}$

Equation 11-3. Batch Normalization algorithm

1. $\mu_B = \frac{1}{m_B} \sum_{i=1}^{m_B} \mathbf{x}^{(i)}$
2. $\sigma_B^2 = \frac{1}{m_B} \sum_{i=1}^{m_B} (\mathbf{x}^{(i)} - \mu_B)^2$
3. $\mathbf{\hat{x}}^{(i)} = \frac{\mathbf{x}^{(i)} - \mu_B}{\sqrt{\sigma_B^2 + \epsilon}}$
4. $\mathbf{z}^{(i)} = \gamma \mathbf{\hat{x}}^{(i)} + \beta$

Why using mini-batch?



Too many matrix multiplication

layer

$$\begin{array}{c}
 \begin{bmatrix} y_1 \end{bmatrix} \\
 \begin{bmatrix} y_1 \end{bmatrix} \\
 \begin{bmatrix} y_1 \end{bmatrix} \\
 \vdots \\
 \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}
 \end{array}
 = \text{softmax} \left(
 \begin{array}{c}
 \begin{bmatrix} W_{1,1} & W_{1,2} & W_{1,3} \end{bmatrix} \begin{bmatrix} x_1 \end{bmatrix} + \begin{bmatrix} b_1 \end{bmatrix} \\
 \begin{bmatrix} W_{1,1} & W_{1,2} & W_{1,3} \end{bmatrix} \begin{bmatrix} x_1 \end{bmatrix} + \begin{bmatrix} b_1 \end{bmatrix} \\
 \begin{bmatrix} W_{1,1} & W_{1,2} & W_{1,3} \end{bmatrix} \begin{bmatrix} x_1 \end{bmatrix} + \begin{bmatrix} b_1 \end{bmatrix} \\
 \vdots \\
 \begin{bmatrix} W_{3,1} & W_{3,2} & W_{3,3} \end{bmatrix} \begin{bmatrix} x_3 \end{bmatrix} + \begin{bmatrix} b_3 \end{bmatrix}
 \end{array}
 \right)$$

What is your question?

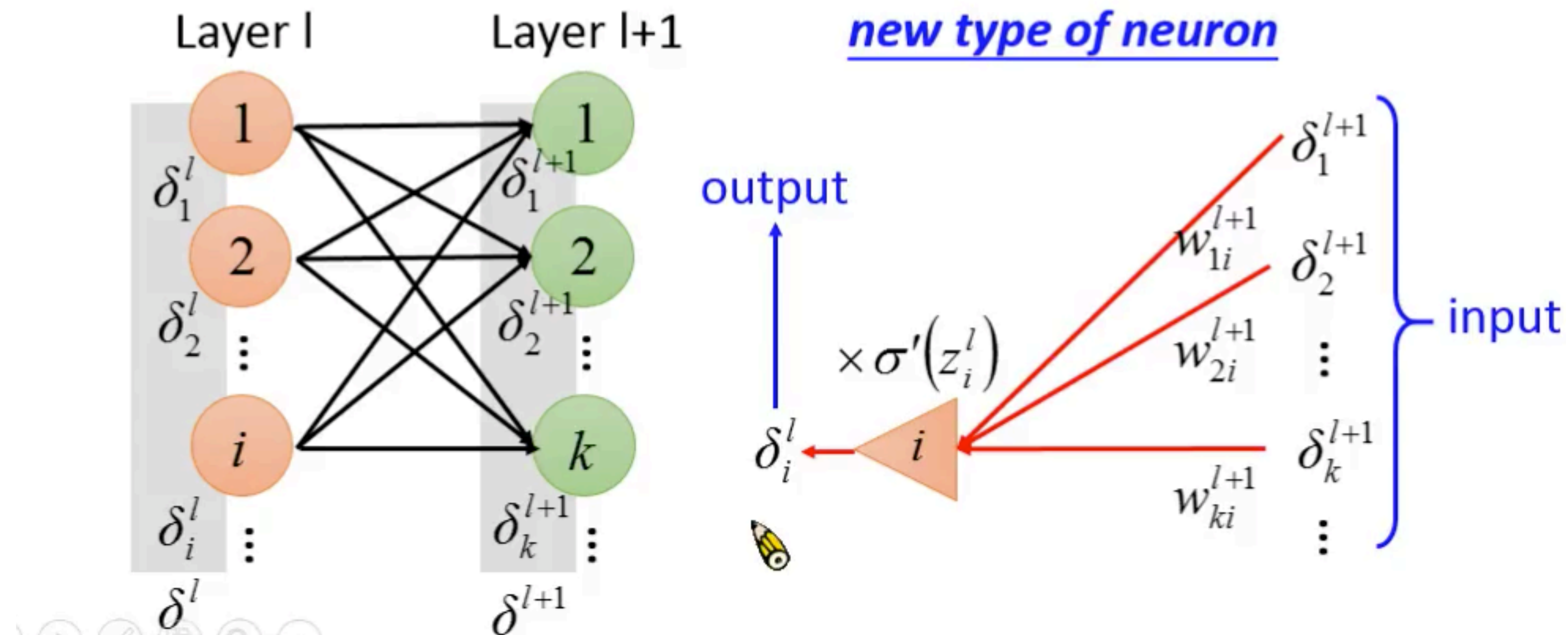
Others

Backpropagation

$\partial C^r / \partial w_{ij}^l$ - Second Term

$$\frac{\partial C^r}{\partial w_{ij}^l} = \frac{\partial z_i^l}{\partial w_{ij}^l} \boxed{\frac{\partial C^r}{\partial z_i^l}} \rightarrow \delta_i^l$$

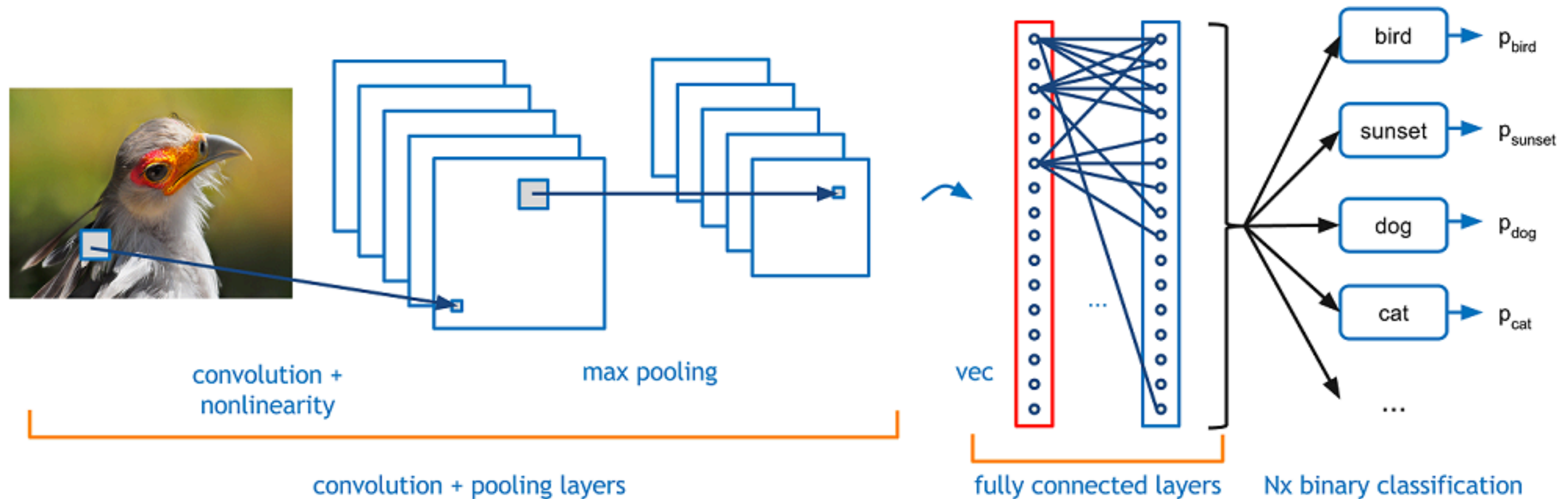
$$\delta_i^l = \sigma'(z_i^l) \sum_k w_{ki}^{l+1} \delta_k^{l+1}$$



Homework

- Try classify mnist with Keras
- Check the tensorflow tutorials - <https://www.tensorflow.org/tutorials/mnist/beginners/>
- Check the tensorflow template (in templates folder)
- Check CNN concept - <https://www.youtube.com/watch?v=JiN9p5vWHDY>

Next time!



Convolution Neural Network