

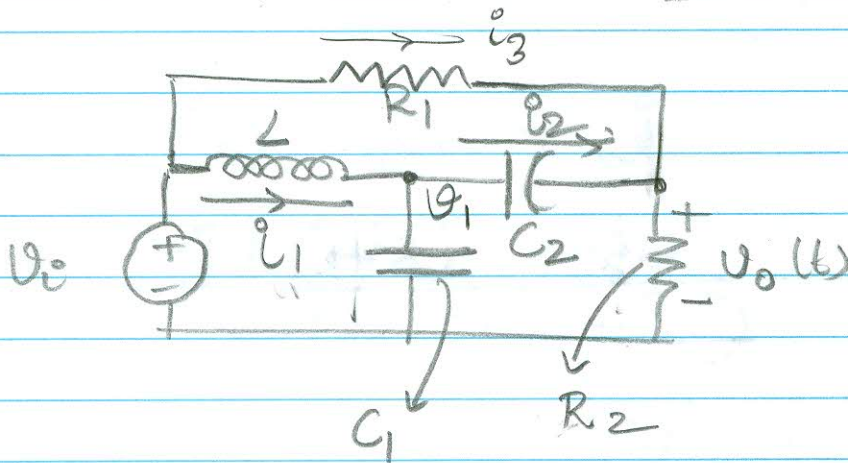
EE128

①

PS2

SOLUTIONS.

1) (a)



$$R_1 = 1\Omega ; R_2 = 1\Omega ; C_1 = 1F ; C_2 = 1F$$

$$L = 1H$$

$$R_1 : V_i(t) - V_o(t) = i_3(t) \quad (1)$$

$$L : V_i(t) - V_1(t) = \frac{di_1}{dt} \quad (2)$$

$$C_1 : i_1(t) - i_2(t) = \frac{dV_1}{dt} \quad (3)$$

$$C_2 : i_2(t) = \frac{dV_1}{dt} - \frac{dV_o}{dt} \quad (4)$$

$$R_2 : V_o(t) = i_2(t) + i_3(t) \quad (5)$$

$$(5) \times (1) \Rightarrow 2i_3(s) = V_i(s) - i_2(s) \quad (6)$$

$$(4) \Rightarrow i_2(s) = sV_1 - sV_o \stackrel{(5)}{=} sV_1 - s(i_2 + i_3) \quad (7)$$

$$(1+s) i_2(s) + s i_3 = sV_1 \quad (7)$$

$$(3) \Rightarrow i_1 - i_2 = sV_1 \stackrel{(7)}{\Rightarrow} (2+s)i_2 + si_3 = i_1 \quad (8)$$

$$(2) \Rightarrow V_i - V_1 = si_1 \Rightarrow sV_i - sV_1 = s^2 i_1 \quad (9)$$

(2)

$$(9) - (s^2+1) \times (8):$$

$$(s^2+1)(2+s) \dot{i}_2 - \dot{i}_2 = sV_i - (s^2+1)s \dot{i}_3.$$

$$\Rightarrow \dot{i}_2 = \frac{sV_i - (s^2+1)s \dot{i}_3}{(s^3+2s^2+s+1)} \quad (10)$$

$$(10) \text{ in } (6) \Rightarrow$$

$$\left[\dot{i}_3 = \frac{(s^3+2s^2+1) V_i}{(s^3+4s^2+s+2)} \right] \quad (11)$$

(b) Phase Variable Form

(i) is of the form

$$\dot{i}_3 = \frac{(s^3+2s^2+1) V_i}{(s^3+4s^2+s+2)}$$

$$\Rightarrow \dot{i}_3 = V_i - \frac{(2s^2+s+1)(V_i)}{(s^3+4s^2+s+2)}$$

Phase variable form for the system:

$$y = \frac{(\beta_2 s^2 + \beta_1 s + \beta_0) u}{(s^3 + \alpha_2 s^2 + \alpha_1 s + \alpha_0)}$$

(3)

$$\left. \begin{aligned} \tilde{A} &= \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -\alpha_0 & -\alpha_1 & -\alpha_2 \end{bmatrix} ; \tilde{B} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \\ \tilde{C} &= [\beta_0 \quad \beta_1 \quad \beta_2] ; \tilde{D} = 0 \end{aligned} \right\} (12)$$

call $y = \frac{(2s^2 + s + 1)}{(s^3 + 4s^2 + s + 2)} u_i^o - (13)$

Phase variable form for (13):

$$\tilde{A} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -2 & -1 & -4 \end{bmatrix} ; \tilde{B} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

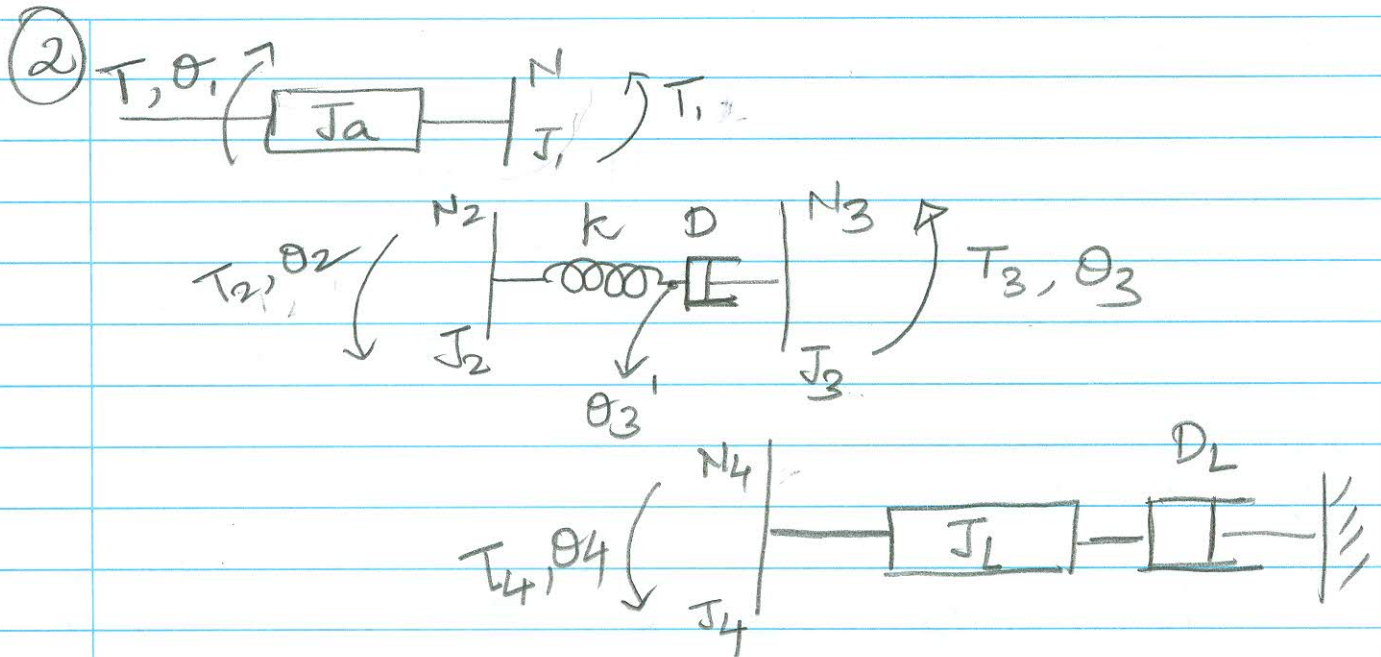
$$\tilde{C} = [1 \quad 1 \quad 2] ; \tilde{D} = 0$$

Phase variable form for (11):

Note $i_2^o = u_i^o - y$

$$\Rightarrow \boxed{\begin{aligned} A &= \tilde{A} ; B = \tilde{B} \\ C &= -\tilde{C} ; D = \tilde{D} + 1 = 1 \end{aligned}}$$

(4)



From Diagram :

$$T - T_1 = (J_a + J_1) \ddot{\theta}_1 \quad \text{--- (1)}$$

$$\frac{\theta_2}{\theta_1} = \frac{N_1}{N_2} \quad ; \quad \frac{T_2}{T_1} = \frac{N_2}{N_1} \quad \text{--- (2)}$$

$$T_2 = J_2 \ddot{\theta}_2 + k(\theta_2 - \theta_3') \quad \text{--- (3)}$$

$$k(\theta_2 - \theta_3') = D(\dot{\theta}_3 - \dot{\theta}_3') \quad \text{--- (4)}$$

$$D(\dot{\theta}_3' - \dot{\theta}_3) - T_3 = J_3 \ddot{\theta}_3 \quad \text{--- (5)}$$

$$\frac{\theta_3}{\theta_4} = \frac{N_4}{N_3} \quad ; \quad \frac{T_4}{T_3} = \frac{N_4}{N_3} \quad \text{--- (6)}$$

$$T_4 = (J_4 + J_L) \ddot{\theta}_4 + D_L \dot{\theta}_4 \quad \text{--- (7)}$$

(5)

Combining ①, ②, ③ :

$$\left(J_0 + J_1 + J_2 \frac{N_1^2}{N_2^2} \right) \ddot{\theta}_1 + \frac{k N_1^2}{N_2^2} \left(\theta_1 - \frac{N_2}{N_1} \theta_3' \right)$$

$$= T - (8)$$

$$(2) \& (4) \Rightarrow$$

$$k \frac{N_1}{N_2} \left(\theta - \frac{N_2}{N_1} \theta_3' \right) = D (\ddot{\theta}_3' - \ddot{\theta}_3)$$

(9)

$$(5), (6), (7) \Rightarrow$$

$$\left(J_3 + (J_4 + J_L) \frac{N_3^2}{N_4^2} \right) \ddot{\theta}_3 + \left(D + D_L \frac{N_3^2}{N_4^2} \right) \ddot{\theta}_3$$

$$= D \ddot{\theta}_3' - (10)$$

$$(10) \Rightarrow \theta_3'(s) = \frac{\left[\left(J_3 + (J_4 + J_L) \frac{N_3^2}{N_4^2} \right) s^2 + \left(D + D_L \frac{N_3^2}{N_4^2} \right) \right]}{D} \theta_3$$

$$\text{Set } J' = J_3 + (J_4 + J_L) \frac{N_3^2}{N_4^2} ; D' = D + D_L \frac{N_3^2}{N_4^2}$$

$$\Rightarrow \theta_3'(s) = (J' s^2 + D') \theta_3 / D$$

$$(9) \Rightarrow (k + Ds) \theta_3' - Ds \theta_3 = \frac{k N_1}{N_2} \theta_1 - (11)$$

Substituting $\theta_3'(s)$ above (11)

(6)

$$\theta_3(s)$$

$$= \frac{(k D N_1 / N_2) \theta_1(s)}{[D J' s^2 + (k J' + D D_L N_3^2 / N_4^2) s + k D]}$$

$$\Rightarrow \theta_3' = \frac{(J' s + D') k N_1 / N_2 \theta_1}{(D J' s^2 + (k J' + D D_L N_3^2 / N_4^2) s + k D)}$$

$$\text{Call } J'' = J_0 + J_1 + J_2 \frac{N_1^2}{N_2^2}$$

then (8) \Rightarrow .

$$(J'' s^2 \theta_1 + \frac{k N_1^2}{N_2^2} \theta_1 - \frac{k N_1}{N_2} \theta_3'(s)) = T.$$

Subs for $\theta_3'(s)$ we get

$$\theta_1(s) = \frac{[D J' s^2 + (k J' + D D_L \frac{N_3^2}{N_4^2}) s + k D] T}{[D J' J'' s^4 + (D D_L \frac{N_3^2}{N_4^2} + k J') J'' s^3 + k (D' J'' + \frac{N_1^2}{N_2^2} D J') s^2 + k D D_L \frac{N_1^2 N_3^2}{N_2^2 N_4^2} s]}$$

Using the parameter values

$$J' = 2 ; D' = 3 ; J'' = 9/4.$$

⑦

$$\Rightarrow \theta_1 = \frac{(4s^2 + 10s + 12)}{[9s^4 + \frac{45}{2}s^3 + 31s + 2s]} T$$

⑥ For the system:

$$\theta_1 = \frac{[\beta_3 s^3 + \beta_2 s^2 + \beta_1 s + \beta_0]}{[s^4 + \alpha_3 s^3 + \alpha_2 s^2 + \alpha_1 s + \alpha_0]} T$$

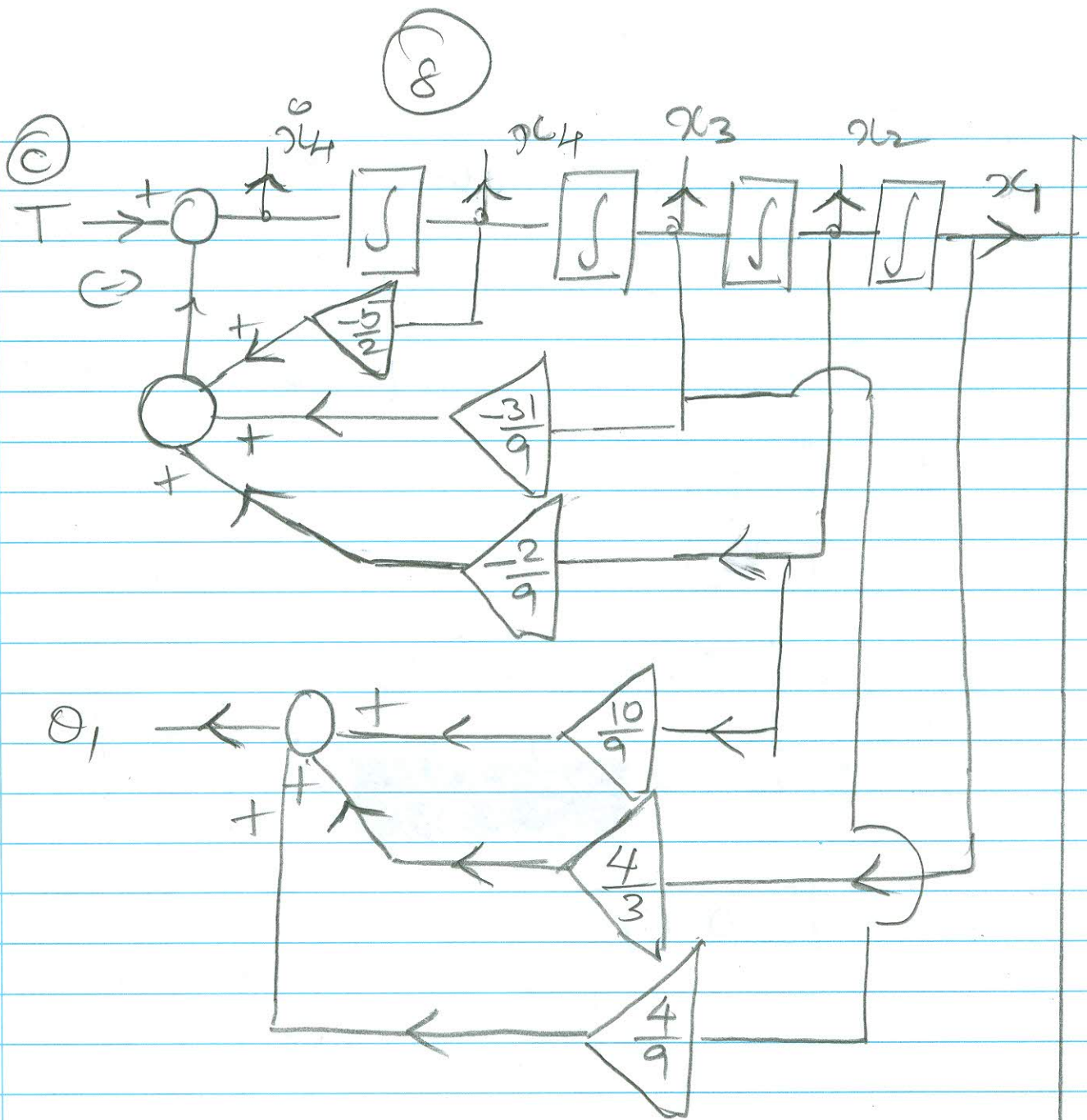
$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -\alpha_0 & -\alpha_1 & -\alpha_2 & -\alpha_3 \end{bmatrix} ; B = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

$$C = [\beta_0 \ \beta_1 \ \beta_2 \ \beta_3] ; D = 0$$

\Rightarrow

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & -\frac{2}{9} & -\frac{31}{9} & -\frac{5}{2} \end{bmatrix} ; B = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

$$C = \left[\frac{4}{3} \ \frac{10}{9} \ \frac{4}{9} \ 0 \right] ; D = 0$$



9.

3 @ For the given system:

$$C = [1 \ 0 \ 0] ; A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -3 & -6 & -5 \end{bmatrix}$$

$$B = \begin{bmatrix} 0 \\ 0 \\ 4 \end{bmatrix}$$

$$G(s) = C(sI - A)^{-1}B$$

$$= [1 \ 0 \ 0] (sI - A)^{-1} \begin{bmatrix} 0 \\ 0 \\ 4 \end{bmatrix}$$

$$= [1 \ 0 \ 0] \begin{bmatrix} s & -1 & 0 \\ 0 & s & -1 \\ 3 & 6 & s+5 \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 0 \\ 4 \end{bmatrix}$$

$$= [1 \ 0 \ 0] \begin{bmatrix} s^2+5s+6 & s+5 & 1 \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 4 \end{bmatrix}$$

these values don't contribute

$$[s^3 + 5s^2 + 6s + 3]$$

$$= \frac{4}{[s^3 + 5s^2 + 6s + 3]}$$

(10)

$$\textcircled{b} \quad C = [-3 \quad -9 \quad -7]$$

$$A = \begin{bmatrix} -6 & -12 & -9 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}; \quad B = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}; \quad D = 1.$$

$$\frac{Y(s)}{U(s)} = C(sE - A)^{-1}B + D.$$

$$= [-3 \quad -9 \quad -7] \begin{bmatrix} s+6 & 12 & 9 \\ -1 & s & 0 \\ 0 & -1 & s \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + 1$$

$$= [-3 \quad -9 \quad -7] \begin{bmatrix} s^2 & 0 & 0 \\ s & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + 1.$$

$$[s^3 + 6s^2 + 12s + 9].$$

$$= \boxed{\frac{-3s^2 - 9s - 7}{[s^3 + 6s^2 + 12s + 9]} + 1}$$

$$= \boxed{\frac{s^3 + 3s^2 + 3s + 2}{s^3 + 6s^2 + 12s + 9}}$$

④

①

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}; \quad \vec{y} = \begin{bmatrix} x_2 \\ \beta(x_3 + kx_1) \\ -\frac{\alpha}{x_4^2} u \\ \beta x_1^2 \end{bmatrix} = f(\vec{x}, u)$$

$$\delta \vec{y} = \frac{\partial f(\vec{x}, u)}{\partial \vec{x}} \delta \vec{x} + \frac{\partial f(\vec{x}, u)}{\partial u} \delta u$$

$$\frac{\partial f}{\partial \vec{x}} = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \frac{\partial f_1}{\partial x_3} & \frac{\partial f_1}{\partial x_4} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} & \frac{\partial f_2}{\partial x_3} & \frac{\partial f_2}{\partial x_4} \\ \frac{\partial f_3}{\partial x_1} & \frac{\partial f_3}{\partial x_2} & \frac{\partial f_3}{\partial x_3} & \frac{\partial f_3}{\partial x_4} \\ \frac{\partial f_4}{\partial x_1} & \frac{\partial f_4}{\partial x_2} & \frac{\partial f_4}{\partial x_3} & \frac{\partial f_4}{\partial x_4} \end{bmatrix} \bigg|_{\substack{x_1=1, x_2=1 \\ x_3=1, x_4=2 \\ u=0}}$$

$$= \begin{bmatrix} 0 & 1 & 0 & 0 \\ \beta k & 0 & \beta & 0 \\ 0 & 0 & 0 & 0 \\ 2\beta & 0 & 0 & 0 \end{bmatrix}$$

12

$$B = \begin{bmatrix} \frac{\partial f_1}{\partial u} \\ \frac{\partial f_2}{\partial u} \\ \frac{\partial f_3}{\partial u} \\ \frac{\partial f_4}{\partial u} \end{bmatrix}$$

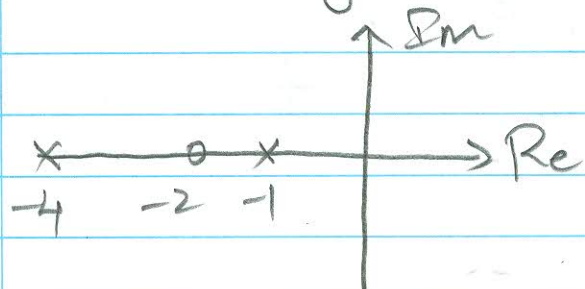
@ $x_1=1, x_2=1, x_3=1, x_4=2, u=0$

$$= \begin{bmatrix} 0 \\ 0 \\ -\frac{2}{4} \\ 0 \end{bmatrix}$$

⑤ a) $y_1(s) = \frac{s+2}{(s+1)(s+4)} \left(\frac{1}{s} \right) = H(s)u(s)$

↑ step.

P-Z Diagram:



Response:

$$P_1 = -1, P_2 = -4$$

$$\lim_{t \rightarrow \infty} y_1(t) = \frac{1}{2}$$

$$\Rightarrow y_1(t) = \frac{1}{2} - A_1 e^{-t} - B_1 e^{-4t}$$

(13)

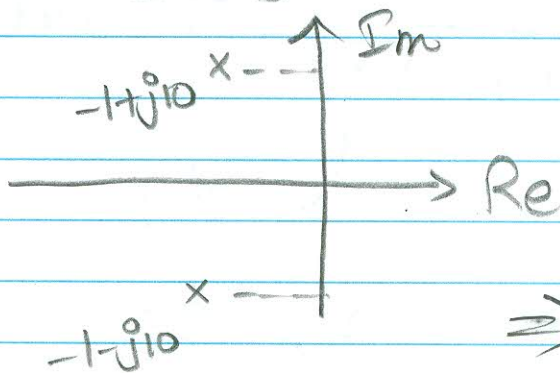
$$\textcircled{b} \quad H(s) = \left(\frac{101}{s^2 + 2s + 101} \right)$$

$$H_2(s) = \left(\frac{101}{s^2 + 2s + 101} \right) \left(\frac{1}{s} \right) = Y_2(s)$$

Zeros: no zeros (zeros at ∞)

Poles: $P_{1,2} = \frac{-2 \pm \sqrt{-400}}{2}$
 $= -1 \pm j10$

P-Z diagram:



Response:

$$\lim_{t \rightarrow \infty} y_2(t) = \lim_{s \rightarrow 0} s Y_2(s) = 1$$

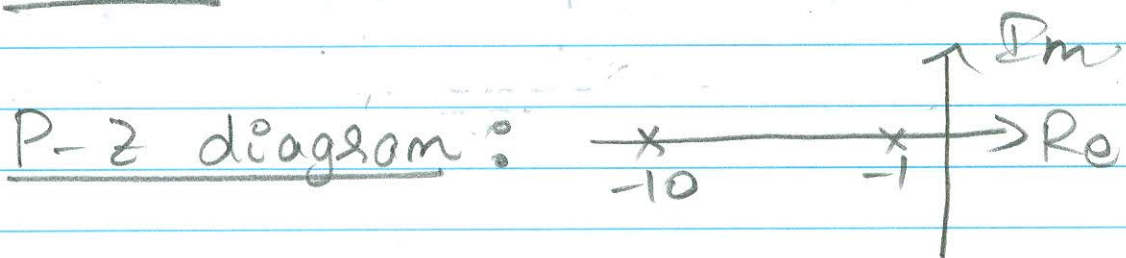
$$\Rightarrow y_2(t) = 1 - e^{-t} [A_2 \cos(10t) + B_2 \sin(10t)]$$

(14)

(c) $y_3(s) = \frac{10}{(s+1)(s+10)} \cdot \frac{1}{s} \quad \Bigg| \quad H(s) = \frac{10}{(s+1)(s+10)}$

Poles : $P_1 = -1, P_2 = -10$.

Zeros : Zeros at ∞

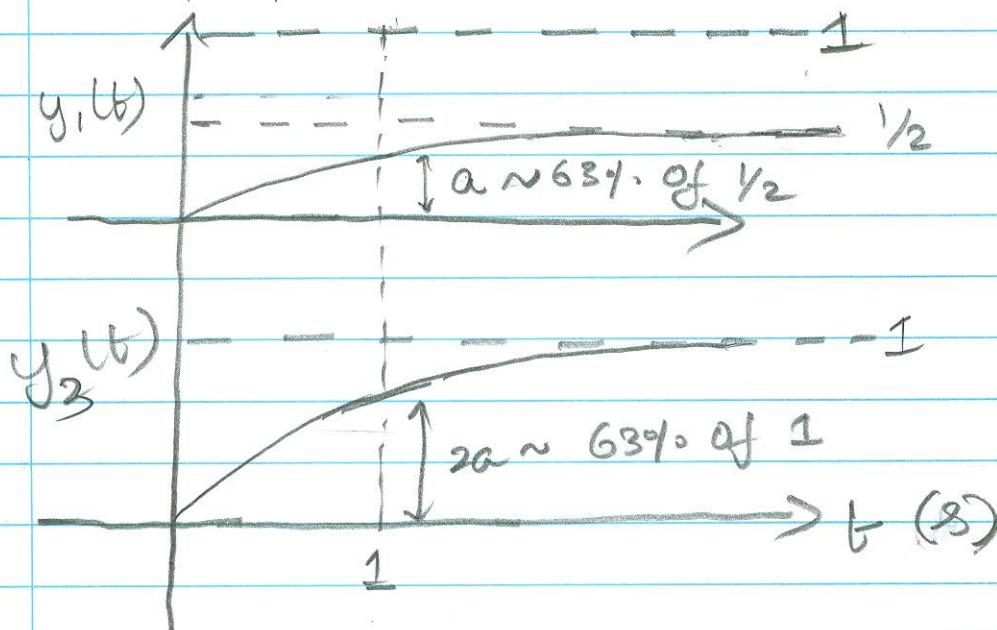


Response :

$$\lim_{t \rightarrow \infty} y_3(t) = \lim_{s \rightarrow 0} s y_3(s) = (1)$$

$$\Rightarrow \boxed{y_3(t) = 1 - A_3 e^{-t} - B_3 e^{-10t}}$$

Response Plot :



15

