

Note: $\Pi(t) = u(t + \frac{1}{2}) - u(t - \frac{1}{2})$, and $comb(t) = \sum_{n=-\infty}^{\infty} \delta(t - n)$.

Problem 1 LTI Properties (20 pts)

[7.5 pts] a. Classify the following systems, with input $x(t)$ and output $y(t)$. In each column, write “yes”, “no”, or “?” if the property is not decidable with the given information. (+0.5 for correct, 0 for blank, -0.5 for incorrect).

System	Causal	Linear	Time-invariant
a. $y(t) = x(t) \cos(2\pi t)$			
b. $y(t) = x(t) * u(t - 2)$			
c. $y(t) = 3x(t + 1) + 1$			
d. $y(t) = \int_{-\infty}^{\infty} x(\tau)x(t - \tau)d\tau$			
e. $y(t) = x(t) - \frac{1}{2} \frac{dx(t)}{dt}$			

[6 pts] b. Two of the systems above (a,b,c,d,e) are not BIBO stable. Note below which systems are not BIBO stable, and then find a bounded input $x(t)$ which gives rise to an unbounded output $y(t)$ for each of these systems.

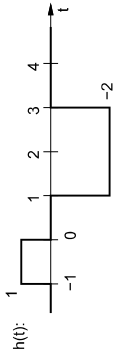
System 1:

Bounded input $x(t) =$ _____

System 2:

Bounded input $x(t) =$ _____

[6.5 pts] c. An LTI system has impulse response $h(t)$ as shown below:



Given input $x(t) = u(t + 1)$. Sketch the output $y(t)$ on the grid below, noting key times and amplitudes.

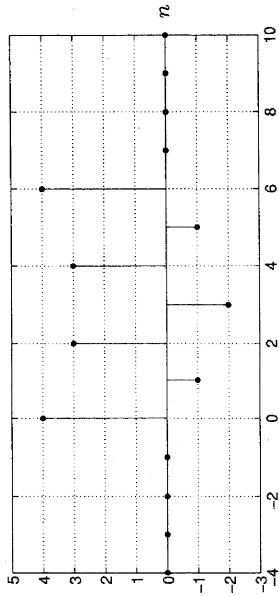
2. (20 pts) Consider an LTI system (with input $x[n]$ and output $y[n]$) defined by the difference equation:

$$y[n] = -0.25x[n] + 0.5x[n-1] - 0.25x[n-2]$$

- Determine if this system is causal and/or stable.
- Determine the frequency response $H(e^{j\omega})$ and sketch its magnitude $|H(e^{j\omega})|$ as a function of ω . Determine the type of filter (low pass, highpass, bandpass, or bandstop) realized by this system.
- Determine whether this system is linear phase.
- Draw a block diagram implementing this system with delay, summation, and multiplication blocks.

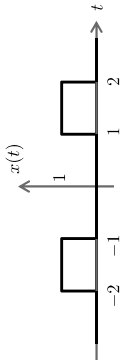
Given the sequence $x[n]$ depicted below, determine the following:

- $X(e^{j0})$
- $X(e^{j\pi})$
- $\int_{-\pi}^{\pi} X(e^{j\omega}) d\omega$
- $\int_{-\pi}^{\pi} |X(e^{j\omega})|^2 d\omega$



7

3. a) (18 points) Determine the Fourier transform of the continuous-time signal $x(t)$ depicted below:



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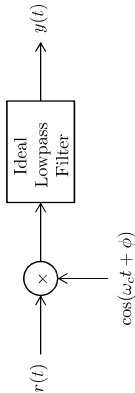
- b) (8 points) Sketch the phase plot for $X(j\omega)$.

4. (20 points)

3. Let $s(t)$ be a real-valued signal for which $S(j\omega) = 0$ when $|\omega| > \omega_c$. Amplitude modulation is performed to produce the signal:

$$r(t) = s(t) \cos(\omega_c t)$$

and the demodulation scheme below is applied to $r(t)$ at the receiver. The constant ϕ represents a phase error that arises when the modulator and demodulator are not synchronized. Determine $y(t)$ assuming that the ideal lowpass filter has a cutoff frequency of ω_c and a passband gain of 2. Your answer should depend only on $s(t)$ and ϕ .

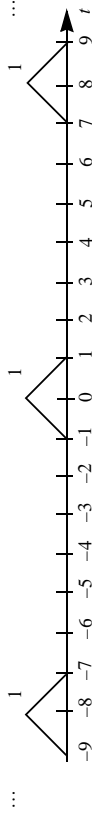


5 20

Problem 1 (10 points) Fourier Series

10

[10 pts.] a) $x(t)$ is a periodic function as shown:



$$x(t) \text{ can be represented as a Fourier Series } x(t) = \sum_{k=-\infty}^{\infty} X_k e^{jk\omega_0 t}.$$

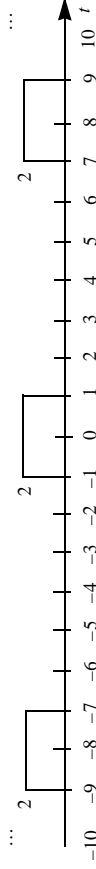
Find ω_0 and X_k .

$$\omega_0 =$$

$$X_k =$$

4

[10 pts.] b) $a(t)$ is a periodic function as shown:



$$a(t) \text{ can be represented as a Fourier Series } (t) = \sum_{k=-\infty}^{\infty} \frac{2 \sin(k\pi/4)}{k\pi} e^{j\frac{k\pi}{4}t}.$$

What is the time average power in $a(t)$?
What is the time average power at the fundamental frequency in $a(t)$?

5

Problem 2 (cont.)

10

[10 pts.] c) Consider a system whose behavior is specified by the differential equation

$$\frac{d^2 y(t)}{dt^2} + 2 \frac{dy(t)}{dt} + y(t) = \frac{d^2 x(t)}{dt^2} + \frac{\pi^2}{16} x(t)$$

with input $x(t)$ and output $y(t)$.

If the input to the system is the periodic function $a(t)$ from part b) above, express the output as a

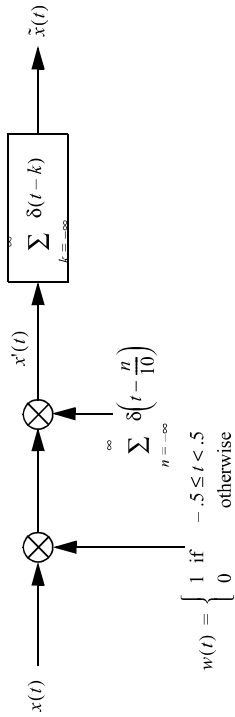
Fourier Series $b(t) = \sum_{k=-\infty}^{\infty} b_k e^{j\frac{k\pi}{4}t}$. Find b_k .

$$b_k =$$

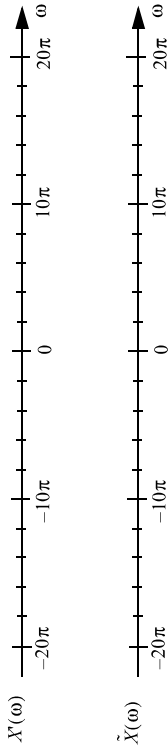
Bonus (2 pts.) (only applicable if you got b_k right): What is the time average power at the fundamental frequency in $b(t)$?

6 20
Problem 7 (30 points)

A system is described by the following block diagram:



16 30 pts.] a) Let $x(t) = \cos 4\pi t$. Sketch $X(\omega)$ and $\tilde{X}(\omega)$, labelling peak magnitude, zero crossing(s), and spacing. (Hint: $X^*(\omega)$ and $\tilde{X}(\omega)$ should be real.)



4 30 pts.] b) What is the relationship between $\tilde{X}(\omega)$ and the 10 point DFT of $x[n] = X[k]$ (where $x[n] = x(0)...x(9)$)? Explain why. (What is the effect of not shifting the window $w(t)$ by $T/2$?)