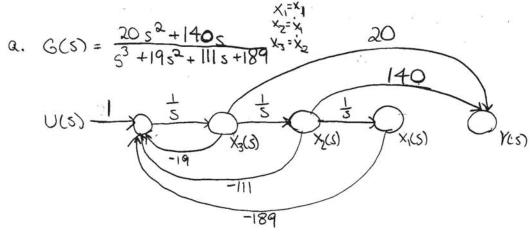
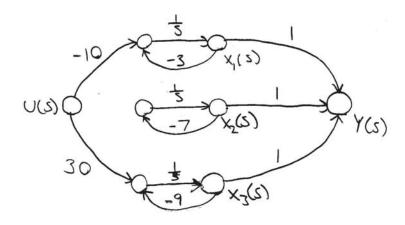
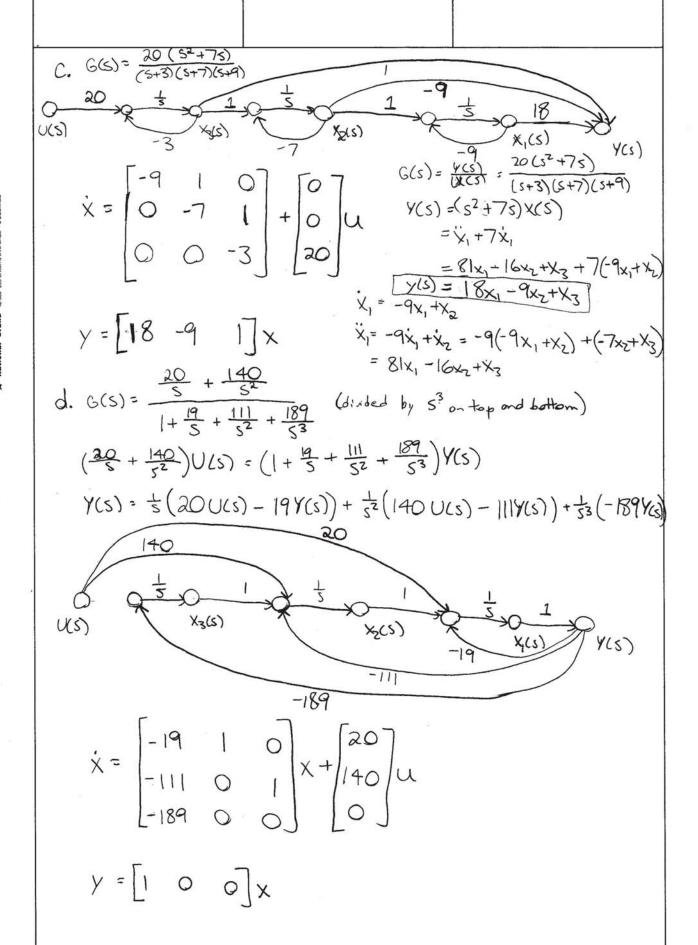
1.
$$G(s) = \frac{20 s(s+7)}{(s+3)(s+7)(s+9)} = \frac{Y(s)}{U(s)}$$



$$\dot{X} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -189 & -111 & -19 \end{bmatrix} \times + \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix} u$$

b.
$$G(s) = \frac{20 s(s+7)}{(s+3)(s+7)(s+9)} = \frac{-10}{s+3} + \frac{0}{s+7} + \frac{30}{s+9}$$





Prob 2 stools. Gr(8) = 20 (8+2) 8(8+5)(1+7). G(8) = 202+40 8(82+128+35). (83+128+358 え = W 40 20 0 n. Signal Graph: 20. 1/5 /5.

OS.j. 2 10.1. + ln 10 = & 11/1-52 (n10)² = (T1²+(1n10)²) & 2 => 22 = (h10)2/(T12+(1010)2) ٤ 2 0.6 Wn z => P1,2 = - & wn & wn \1-82 -2 生。2.66 Pg = 10 (Re (P, 2)) Choose - 20. Characteristic polynomial: (s-P1)(8-P2)(8-P3)

$$= (s+2+j^{2}\cdot66)(s+2-j^{2}\cdot66)(s+20)$$

$$= s^{3}+24s+91\cdot08s+221\cdot51-0$$

$$(a_{2}) (a_{1}) (a_{0})$$
Let $u = -kn^{2} - [k, k_{2} k_{3}] \begin{bmatrix} x_{1} \\ n_{2} \\ x_{3} \end{bmatrix}$

$$\Rightarrow A-Bk = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -k_{1}-k_{2}\cdot35-12 \\ -k_{3} \end{bmatrix}$$

$$\Rightarrow \text{ character letic Polynomial:}$$

$$s^{3}+(12+k_{3})s^{2}+(k_{2}+35)s+k_{1}-2$$
equalizing ① and ② we get
$$[k_{1}=221\cdot51, k_{2}=56\cdot08, k_{3}=12]$$

3.
$$\dot{X} = A \times = \begin{bmatrix} \dot{X}_1 \\ \dot{X}_2 \\ \dot{X}_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -24 & -26 & -9 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix} \qquad \dot{X}_0(+=0) = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$X_o(+=0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$det(2I-A) = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} - \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

$$= \begin{bmatrix} 2 & -1 & 0 \\ 0 & 2 & -1 \\ 24 & 26 & 2+9 \end{bmatrix}$$

$$= 2^{3} + 92^{2} + 262 + 24$$

$$2 = -2 - 3 - 4$$

Find eigenvectors:

$$\frac{2=-2}{AV_1=2V_1}$$

$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -24 & -26 & -9 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = -2 \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$$

$$v_2 = -2v_1$$

$$v_3 = -2v_2$$

$$-24v_1 - 26v_2 - 9v_3 = -2v_2$$

$$2 = -2$$
 $\Rightarrow \bigvee_{1} = \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix}$

$$\lambda_{2} = -3 \implies V_{2} = \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{3} \\ 1 \end{bmatrix}$$

$$\lambda_{3} = -4 \implies V_{3} = \begin{bmatrix} \frac{1}{16} \\ -\frac{1}{4} \\ 1 \end{bmatrix}$$

$$V_1 = \frac{1}{4}V_3$$
 $V_2 = -\frac{1}{2}V_3$
 $V_2 = -\frac{1}{2}V_3$
 $V_3 = -\frac{1}{2}V_3$
 $V_4 = -\frac{1}{2}V_3$
 $V_5 = -\frac{1}{2}V_5$
 $V_7 = \frac{1}{4}V_7$

$$\lambda_3 = -4 \implies V_3 = \begin{bmatrix} \frac{1}{16} \\ -\frac{1}{4} \\ 1 \end{bmatrix}$$

$$\rho^{-1} = \begin{bmatrix} \frac{1}{4} & \frac{1}{9} & \frac{1}{16} \\ -\frac{1}{2} & -\frac{1}{3} & -\frac{1}{4} \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 24 & 14 & 2 \\ -72 & -54 & -9 \\ 48 & 40 & 8 \end{bmatrix}$$

So:
$$A = P^{-1}AP$$

$$\begin{bmatrix}
-2 & 0 & 0 \\
0 & -3 & 0
\end{bmatrix} = \begin{bmatrix}
24 & 14 & 2 \\
-72 & -54 & -9 \\
48 & 40 & 8
\end{bmatrix} = \begin{bmatrix}
0 & 1 & 0 \\
0 & 0 & 1
\end{bmatrix} = \begin{bmatrix}
4 & 4 & 16 \\
4 & -3 & -4 \\
1 & 1 & 1
\end{bmatrix}$$

$$A = P$$

b.
$$e^{At} = \rho e^{At} \rho^{-1}$$

$$= \begin{bmatrix} \frac{1}{4} & \frac{1}{4} & \frac{1}{16} \\ -\frac{1}{2} & -\frac{1}{3} & -\frac{1}{4} \end{bmatrix} \begin{bmatrix} e^{-2t} & Q & Q \\ Q & e^{-3t} & Q \\ Q & Q & e^{-4t} \end{bmatrix} \begin{bmatrix} 24 & 14 & 2 \\ -72 & -54 & -9 \\ 48 & 4Q & 8 \end{bmatrix}$$

$$= \begin{bmatrix} 6e^{-2t} - 8e^{-3t} + 3e^{-4t} & \frac{7}{2}e^{-2t} - 6e^{-3t} + \frac{5}{2}e^{-4t} & \frac{1}{2}e^{-2t} - e^{-3t} + \frac{1}{2}e^{-4t} \\ -12e^{-2t} + 24e^{-3t} - 12e^{-4t} & -7e^{-2t} + 18e^{-3t} - 10e^{-4t} & -e^{-2t} + 3e^{-3t} - 2e^{-4t} \\ 24e^{-2t} - 72e^{-3t} + 48e^{-4t} & 14e^{-2t} - 54e^{-3t} + 40e^{-4t} & 2e^{-2t} - 9e^{-3t} + 8e^{-4t} \end{bmatrix}$$

$$X(t) = e^{At}X_0 + \int_0^t Be^{A(t-t)}u(t) dt$$
 $B = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
 $S_0:$
 $X(t) = e^{At}X_0$

$$x(t) = e^{At} x_e$$

$$= e^{At} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$X(t) = \begin{bmatrix} \frac{13}{2}e^{-2t} - 9e^{-3t} + \frac{7}{2}e^{-1t} \\ -13e^{-2t} + 27e^{-3t} - 14e^{-4t} \\ 26e^{-2t} - 81e^{-3t} + 56e^{-1t} \end{bmatrix}$$

5.
$$\dot{x} = \begin{bmatrix} 1 & -2 \\ -1 & 1 \end{bmatrix} x + \begin{bmatrix} k_1 \\ k_2 \end{bmatrix} u(t)$$

For which values of k, and kz is system completely controllable?

$$C_{M} = \begin{bmatrix} B & AB \end{bmatrix} = \begin{bmatrix} k_{1} & k_{1} - 2k_{2} \\ k_{2} & -k_{1} + k_{2} \end{bmatrix}$$

Full rank unless:

System controllable Yk, kz such that |k, | # 12 |k2 |

Prolo 4 starte G(8) = s (s+3) (s+1). (s3+10s2+21-s+0) ao 20, 9, 2-21, az 2-10. , B= -10 001 Let Lz => A-LC 2 0 -21-L2 0 1 -10-63 Desired pole locations. &= 0.4 , wn = 75 => P1,2 = -30+168.74.

	$=> P_3 = -300.$
	Desired Characteristic Polynomial:
	(8-P1) (8-P2) (8-P3)
	$= 8^3 + 3608^2 + 23625.193 + 1687556.28$
	L2
	D: 13+(10+L3)52+(21+L2)8+L1
•	Dogodd Characteristes ashing al
	achieved by setting is
	L by equating coefficients of 1) and 2]

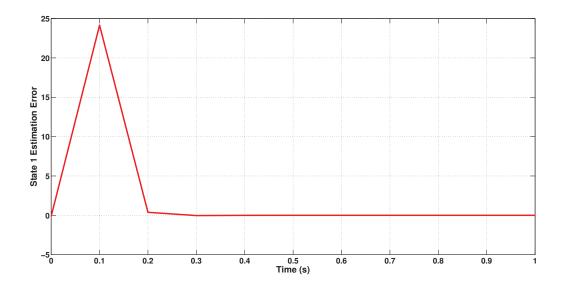


Figure 1: State 1 Estimation Error

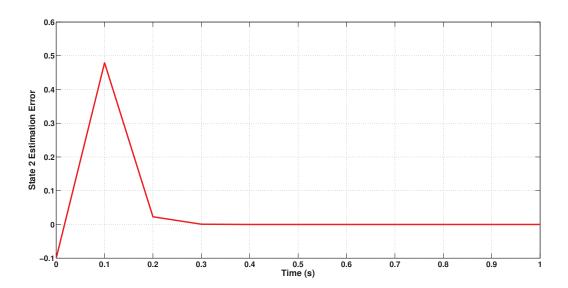


Figure 2: State 2 Estimation Error

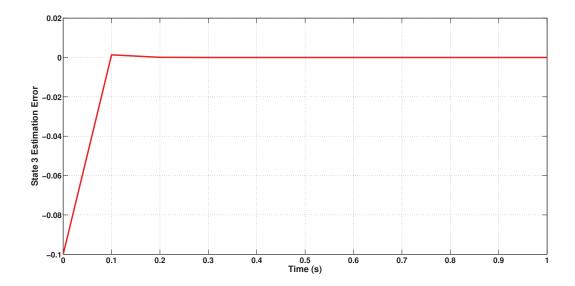


Figure 3: State 3 Estimation Error

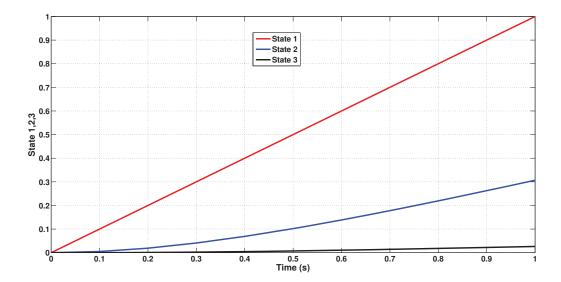


Figure 4: State Response