## EE128 PS2: Comments on Question 4

Let  $x'(t) = x(t) + \delta x(t)$  be the output to the input  $u'(t) = u(t) + \delta u(t)$  (a perturbation  $\delta u(t)$ ) s.t.  $\dot{x}(t) = f(x(t), u(t))$ . Then its clear that,

$$\dot{x}'(t) = \dot{x}(t) + \delta \dot{x}(t) = f(x(t) + \delta x(t), u(t) + \delta u(t)) 
\approx f(x(t), u(t)) + \frac{\partial f(x(t), u(t))}{\partial x} \delta x(t) + \frac{\partial f(x(t), u(t))}{\partial u} \delta u(t)$$
(1)

This then reduces to,

$$\delta \dot{x}(t) = \frac{\partial f(x(t), u(t))}{\partial x} \delta x(t) + \frac{\partial f(x(t), u(t))}{\partial u} \delta u(t)$$
 (2)

In this particular problem you are only given the operating point ((x(t), u(t))) at a particular instant of time and not its explicit time dependence. That is the operating point given in the problem is the value of x(t) and u(t) at a particular time instant  $t_0$ . Denote  $x(t_0)$  by  $x_0$  and  $u(t_0)$  by  $u_0$ . Then Eq. (2) can be expressed as the following which gives us the linearization at  $(x_0, u_0)$ .

$$\delta \dot{x}(t) = \frac{\partial f(x, u)}{\partial x} {\underset{@(x = x_0, u = u_0)}{\otimes}} \delta x(t) + \frac{\partial f(x, u)}{\partial u} {\underset{@(x = x_0, u = u_0)}{\otimes}} \delta u(t)$$
(3)