

# Ambient Noise Surface-Wave Tomography of the San Francisco Bay Area, Northern California

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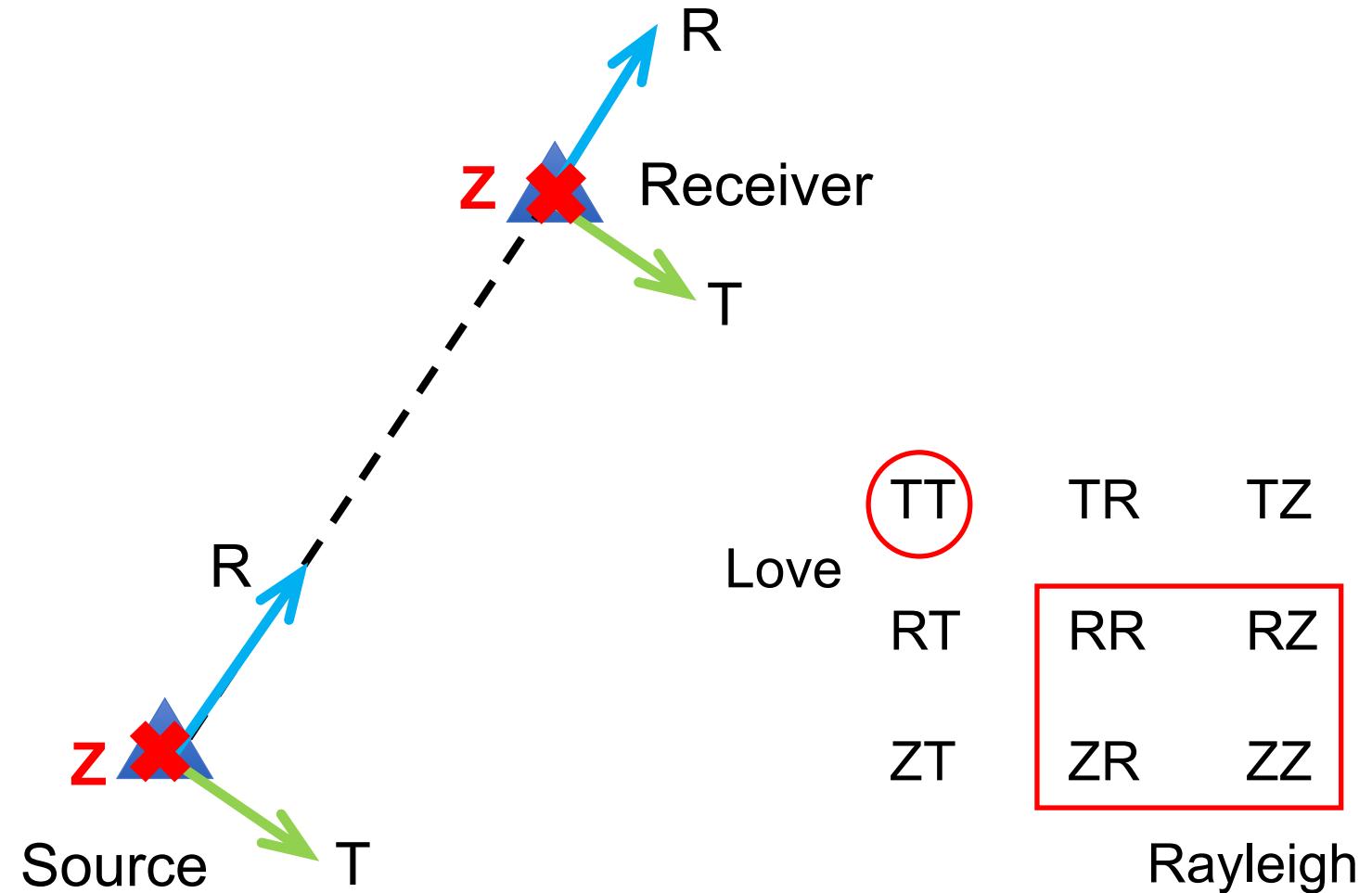
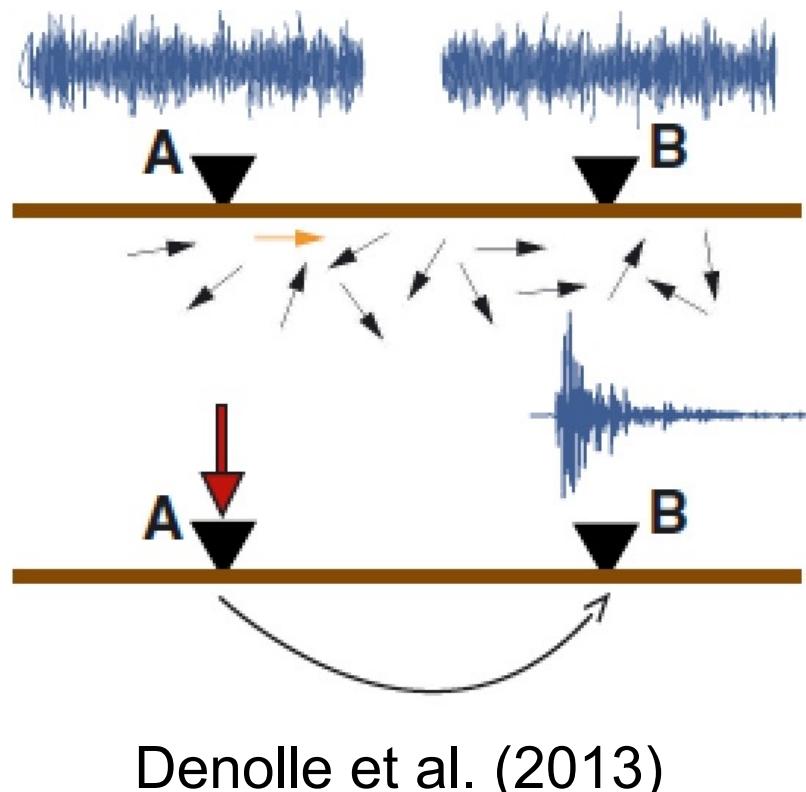
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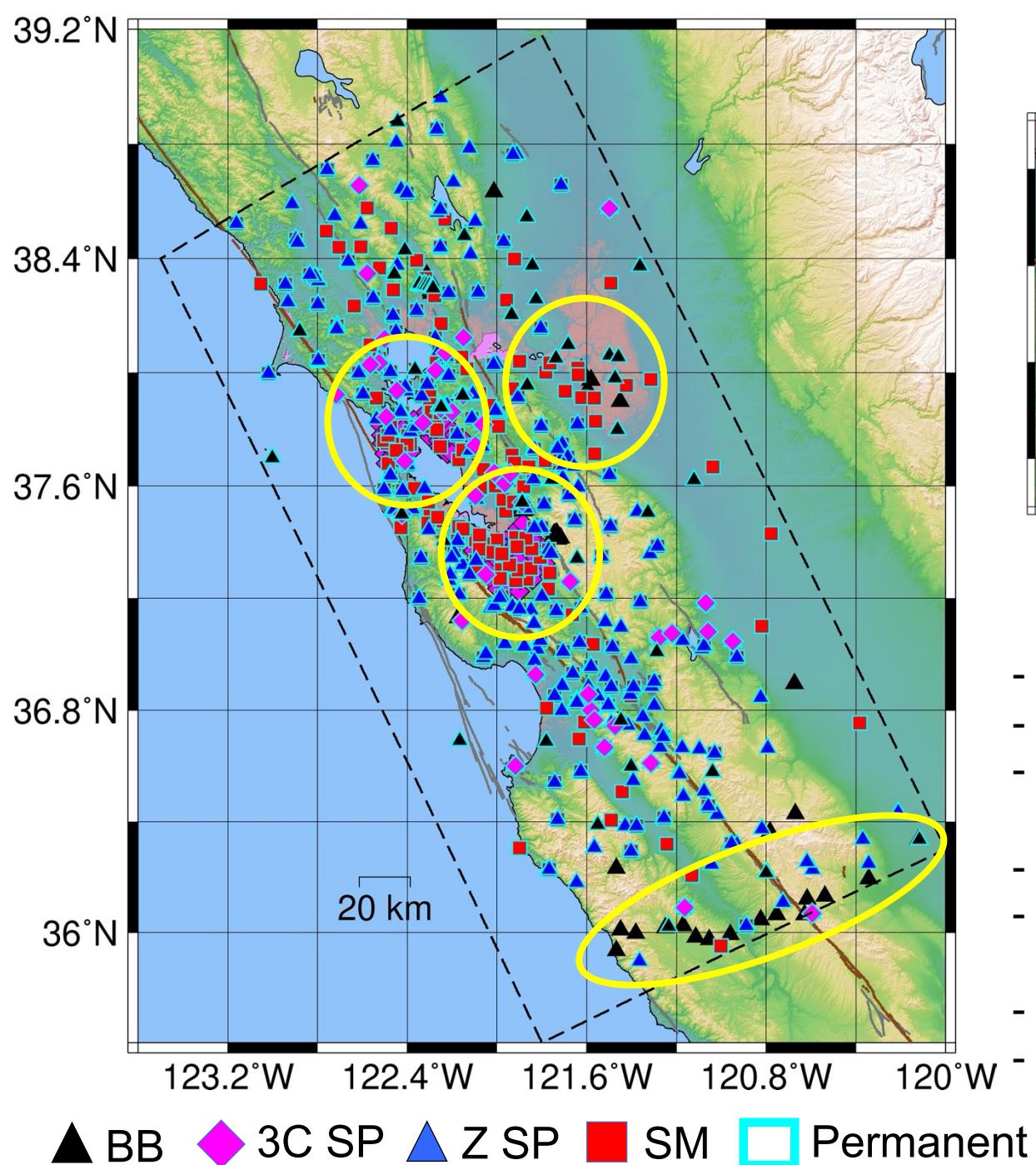
## Acknowledgements:

- Waveform data downloaded from NCEDC and IRIS – Networks BK, NC, CE, NP, WR, PB, TA, XL (1998), XL (2000), YU, GS, TO, SB
- Computational resources provided by SAVIO cluster, Berkeley Research Computing, UC Berkeley

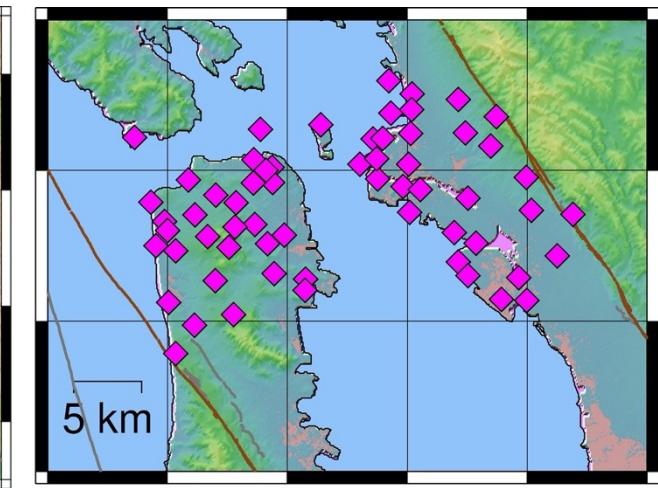
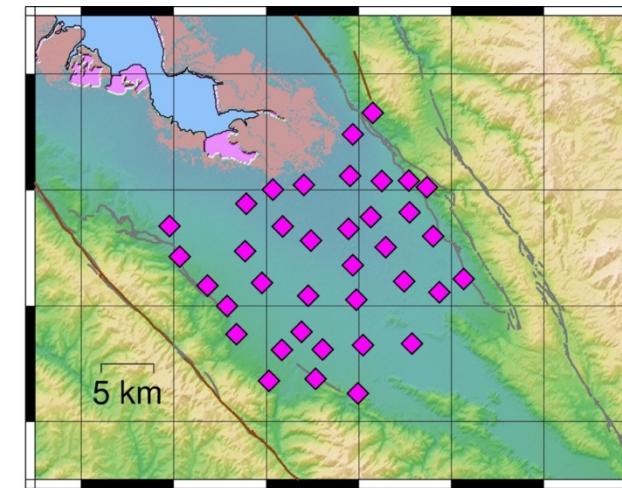
# Surface-wave tomography with multicomponent seismic noise cross-correlations

Cross-correlation of diffused wavefields (ambient noise/coda waves) recorded at 2 sensors converges to the empirical Green's Function between the receivers.





## Data



- 2007- Sacramento Delta Array (Fletcher & Erdem 2017)
- 2006-07 TA stations
- 2011-12 Few USGS BB stations at Poverty Ridge and Mission peak (Hartzell et al. 2014, 2017)
- 2014 Napa aftershock deployment
- 2014-15 Central California Seismic Experiment (Jiang et al. 2018)
- Accelerometers
- New permanent BB + SP stations

▲ BB    ♦ 3C SP    ▲ Z SP    ■ SM    □ Permanent

## Surface-wave tomography workflow

Rayleigh and Love waves from cross-correlations

AFTAN (Bensen et al. 2007) analysis to get group velocity dispersion measurements ~5-16 s

Invert group velocity measurements for 2D group velocity maps ~10 km spacing

Invert group velocity dispersion at each XY point to get  $V_s(\text{depth})$   
Herrmann (2013)

Combine  $V_s$ -depth at all XY points to get 3D  $V_s$  model

Use 3D  $V_s$  model to get reference phase velocity dispersion measurements ~3-16 s

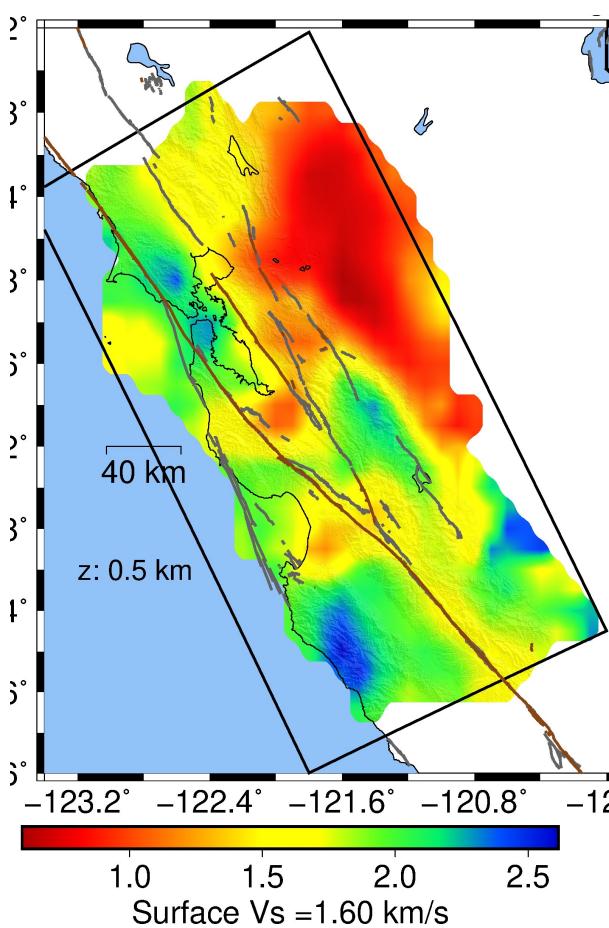
Invert phase velocity measurements for 2D phase velocity maps at ~10 km spacing  
2D Fast marching method  
Rawlinson & Sambridge (2000)  
Damping/smoothing

Invert phase velocity dispersion at each XY point to get  $V_s(\text{depth})$   
Herrmann (2013)

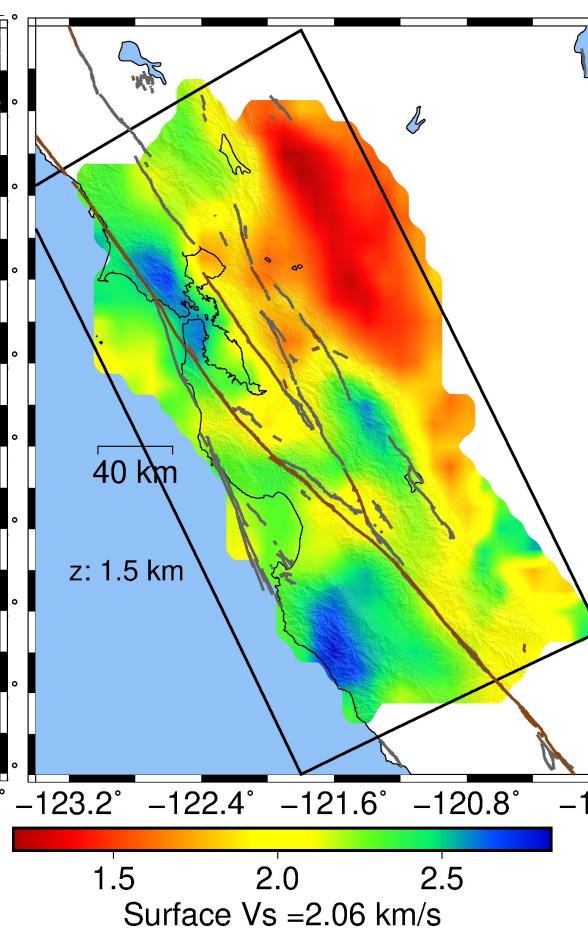
Combine  $V_s$ -depth at all XY points to get 3D  $V_s$  model (~10 km spacing, ~20 layers, min thickness ~ 1 km)

# This study

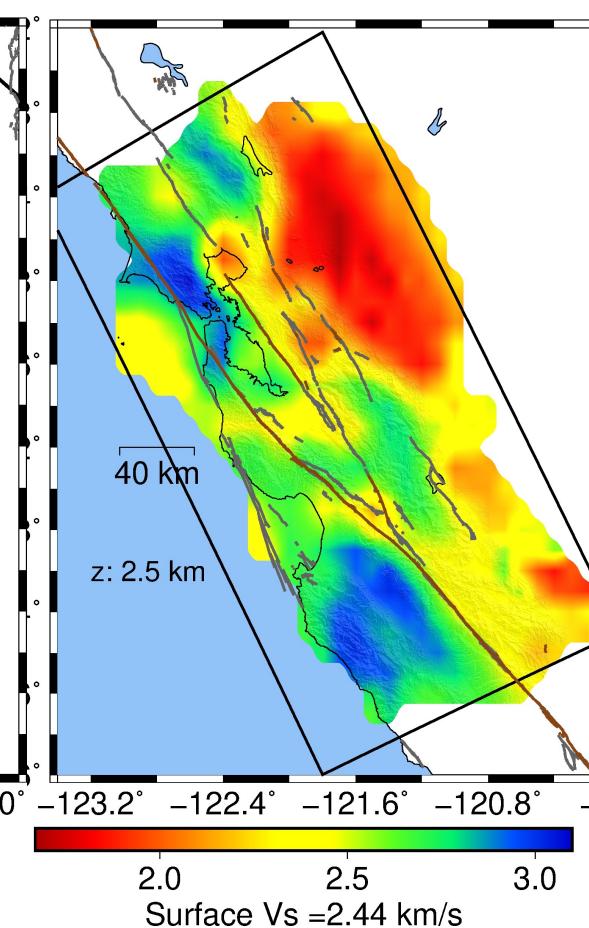
Depth 0.5 km



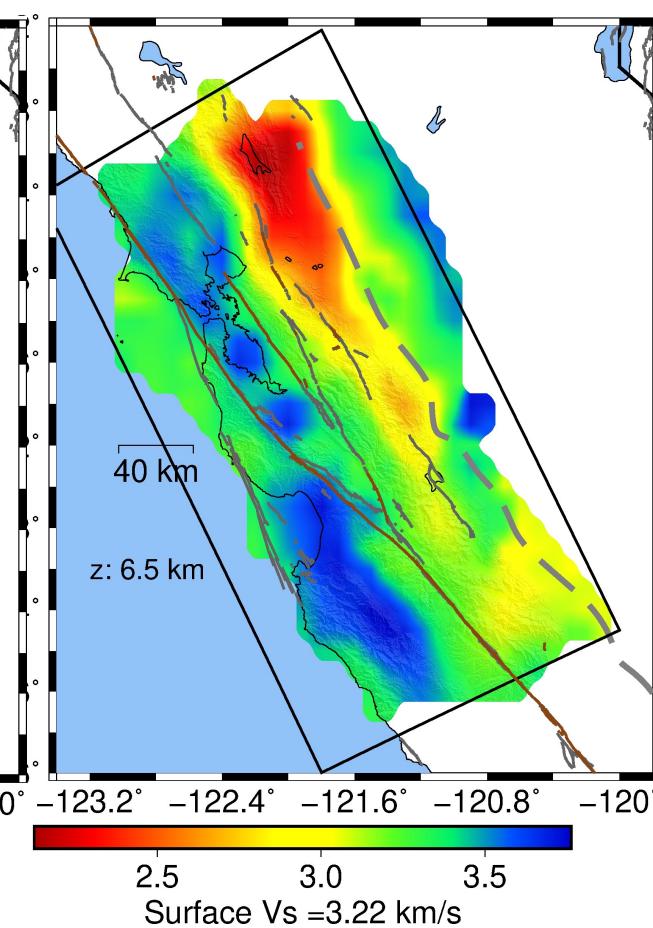
Depth 1.5 km



Depth 2.5 km



Depth 6.5 km



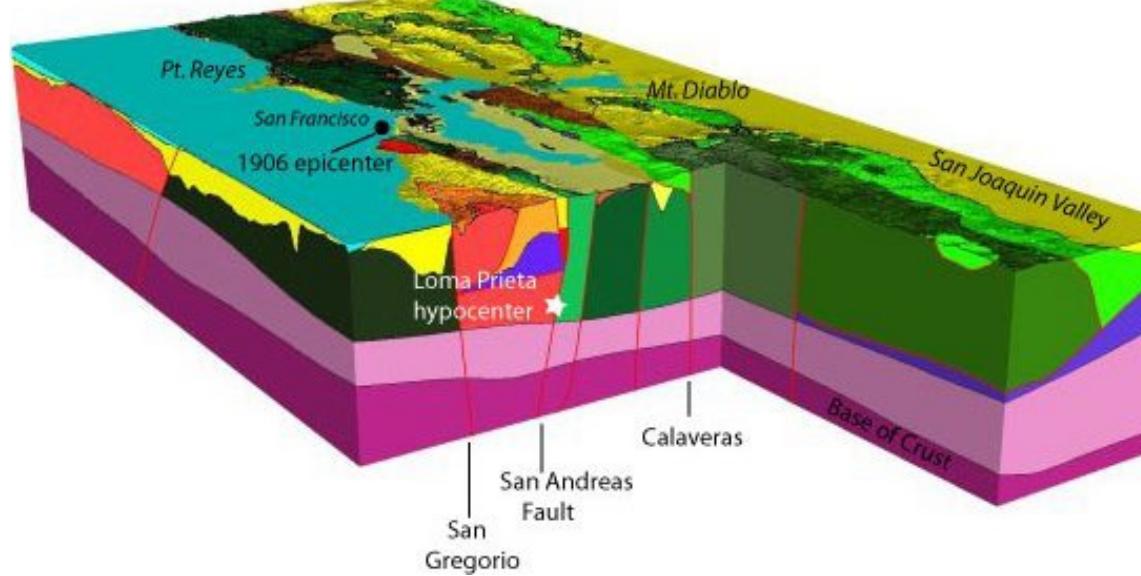
Sedimentary basins

Velocity contrast across  
faults

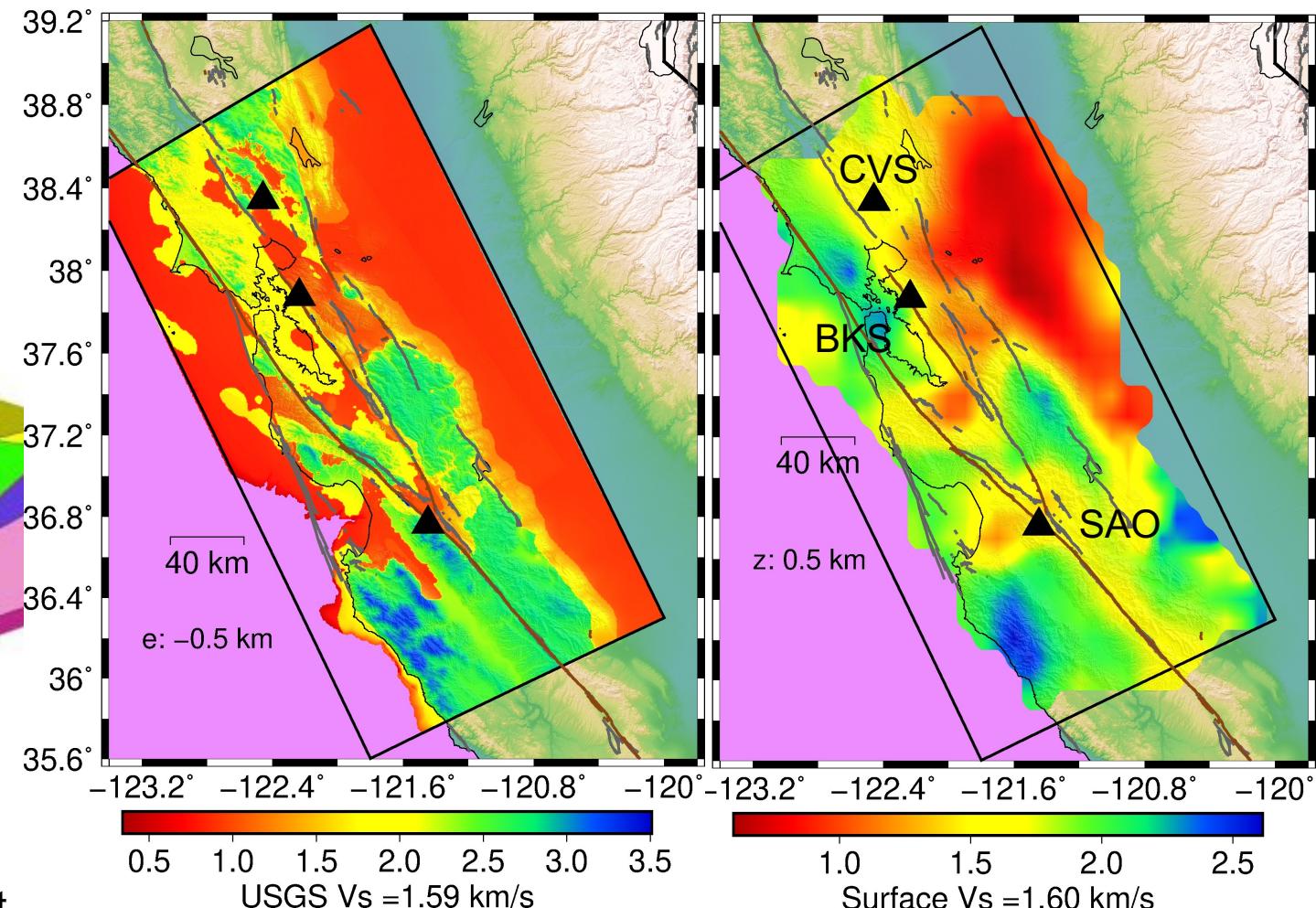
Crystalline basement  
contour from  
Wentworth et al. (1995)

# Comparison of synthetic waveforms and empirical fundamental mode surface-wave Green's functions derived from ambient noise

USGS Bay Area Model 8.3.0  
Geologic/seismic model



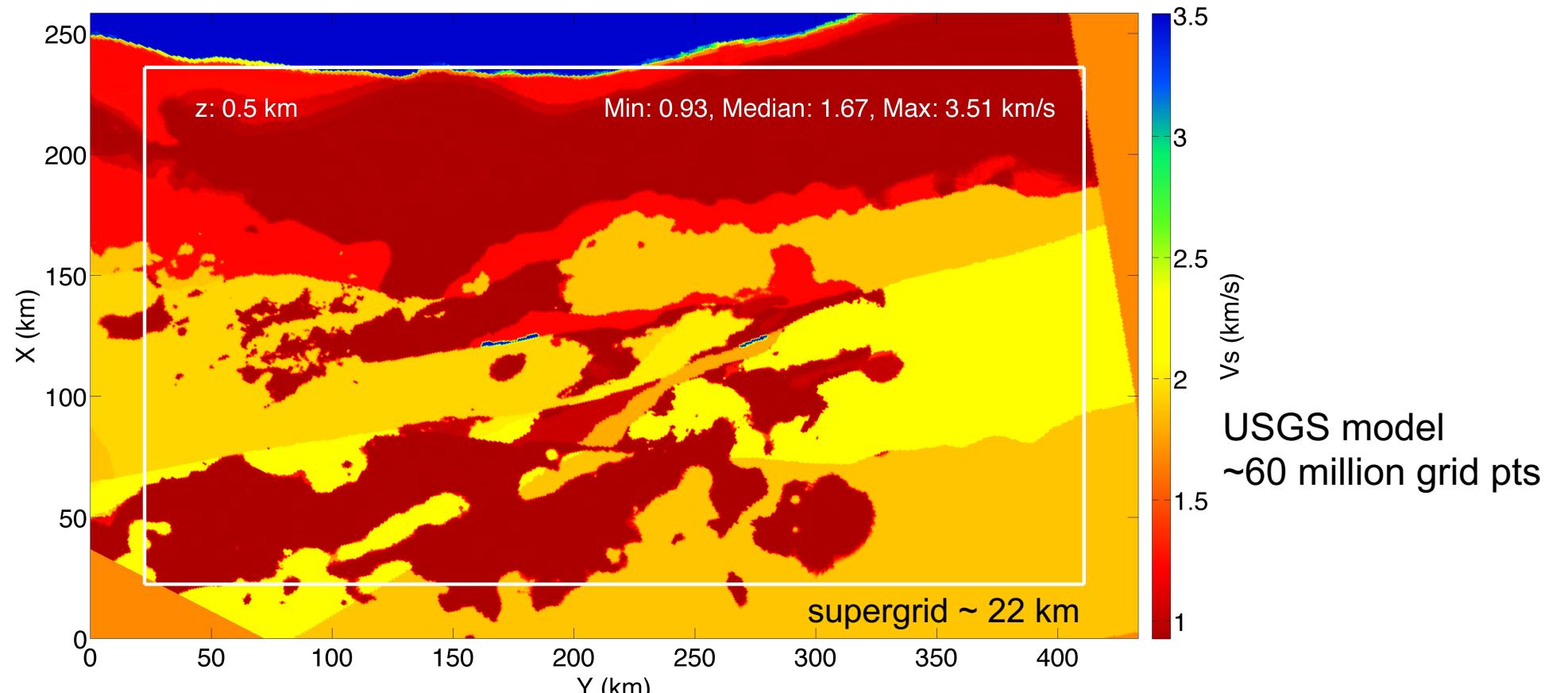
Jachens et al. (2006), Brocher (2005, 2008),  
Aagaard et al. (2008, 2010);  
updated following Rodgers et al. (2008), Thurber et  
al. (2009), Kim et al. (2010)



Topography pushed down,  
Minimum Vs~0.5 km/s imposed  
Model queried at dx~800 m

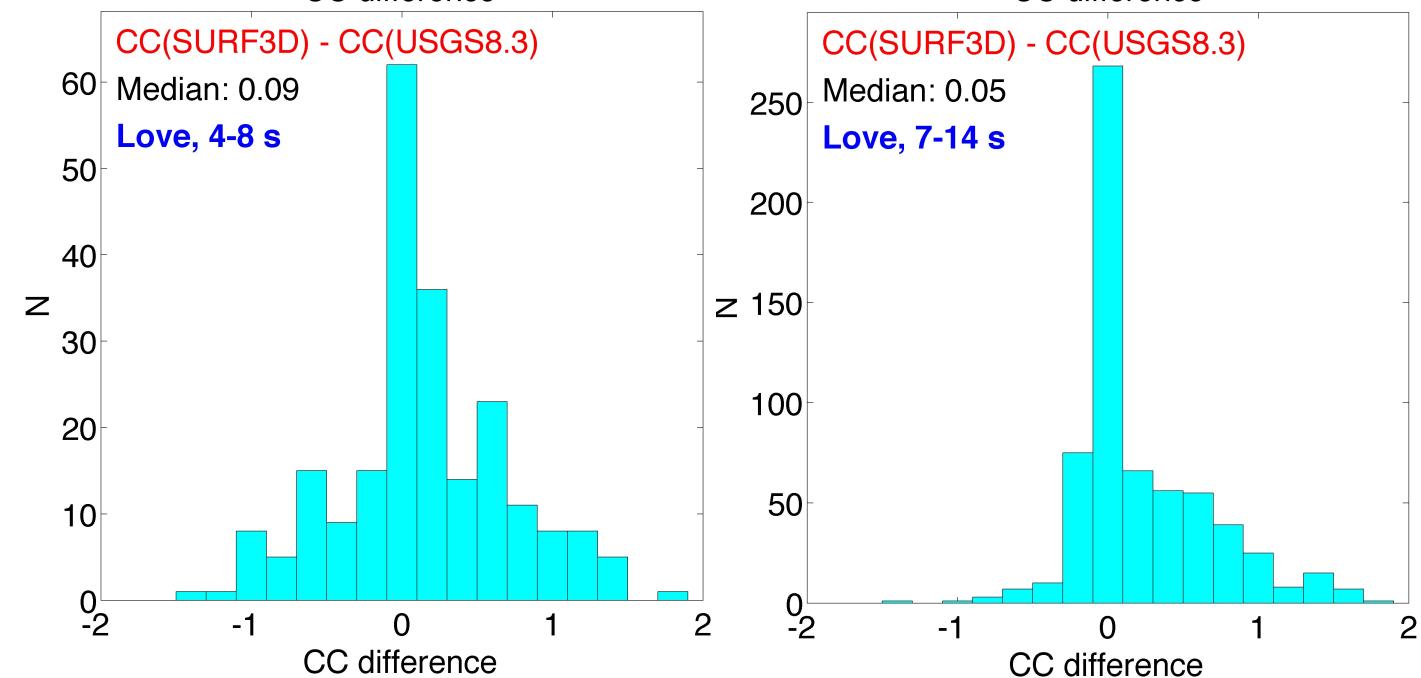
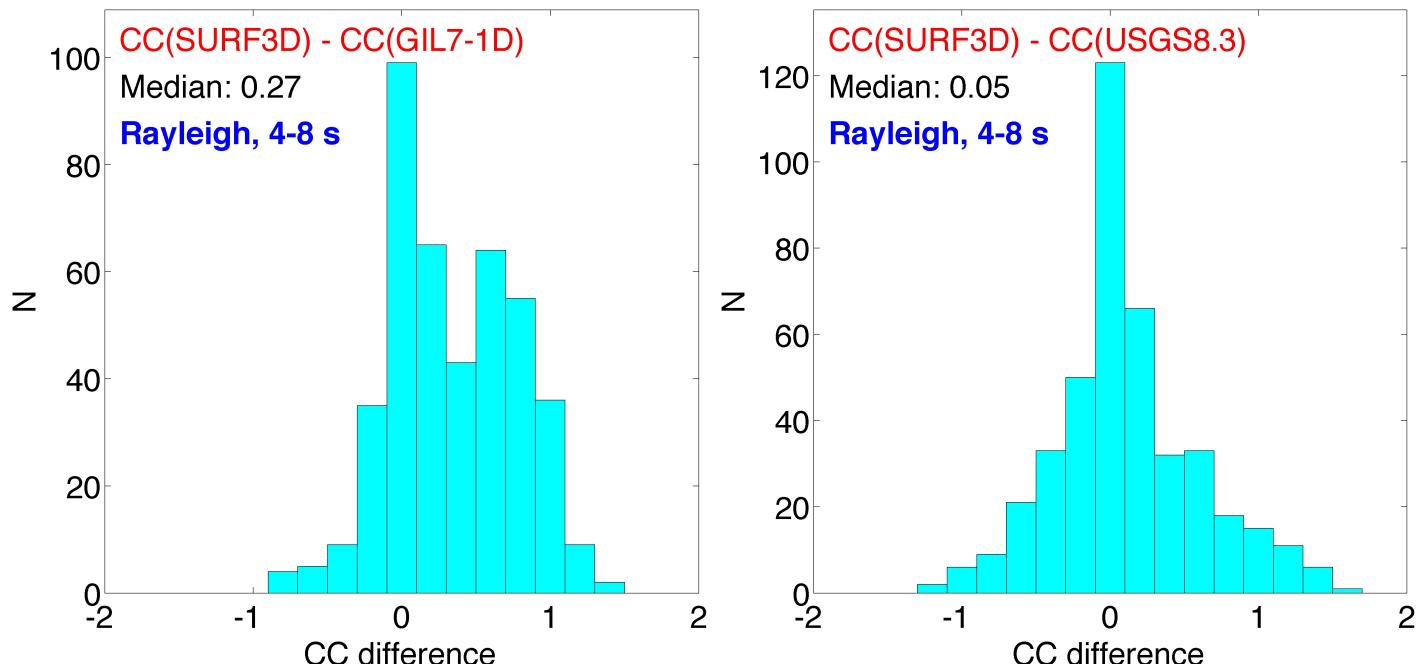
# Comparison of synthetic waveforms and empirical fundamental mode surface-wave Green's functions derived from ambient noise

- Synthetics for the 2 **3D models** calculated using **SW4** (Sjogreen & Petersson 2012; Petersson and Sjogreen, 2017); grid spacing **~87 m** at surface to **~700 m** at depth; **~6.8 grid points per minimum wavelength at ~1.2 s**
- Synthetics for a local 1D model (**GIL7**, Stidham et al. 1999) calculated using **FK integration** (Herrmann 2013)
- Waveforms in 2 passbands for comparison: **~4-8 s** and **~7-14 s**; calculate zero-lag correlation between obs and syn waveforms; select station pairs for which CC exceeds **~0.6** for any one model.

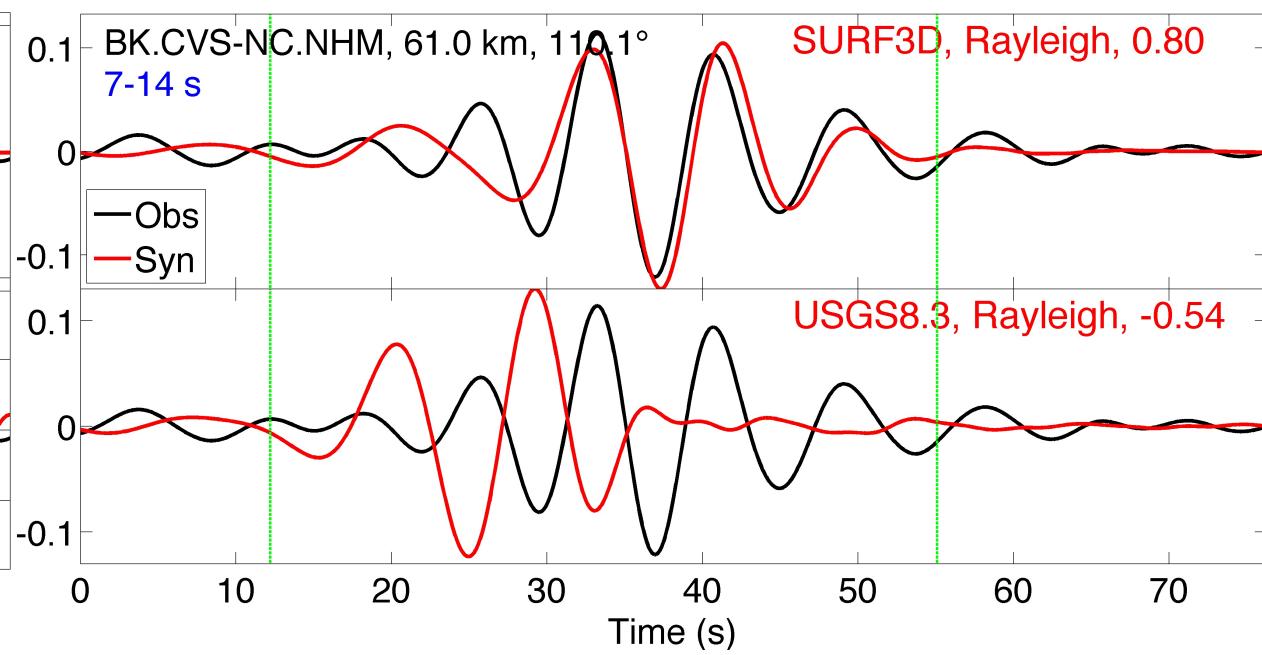
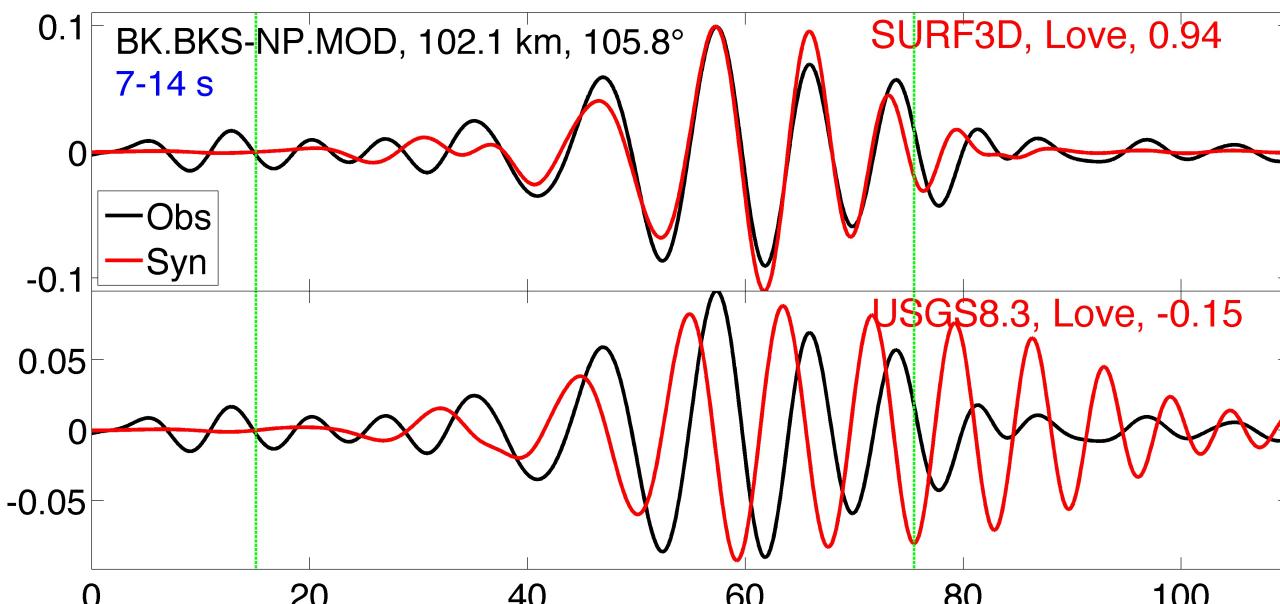


# Comparison of synthetic waveforms and empirical fundamental mode surface-wave Green's functions derived from ambient noise

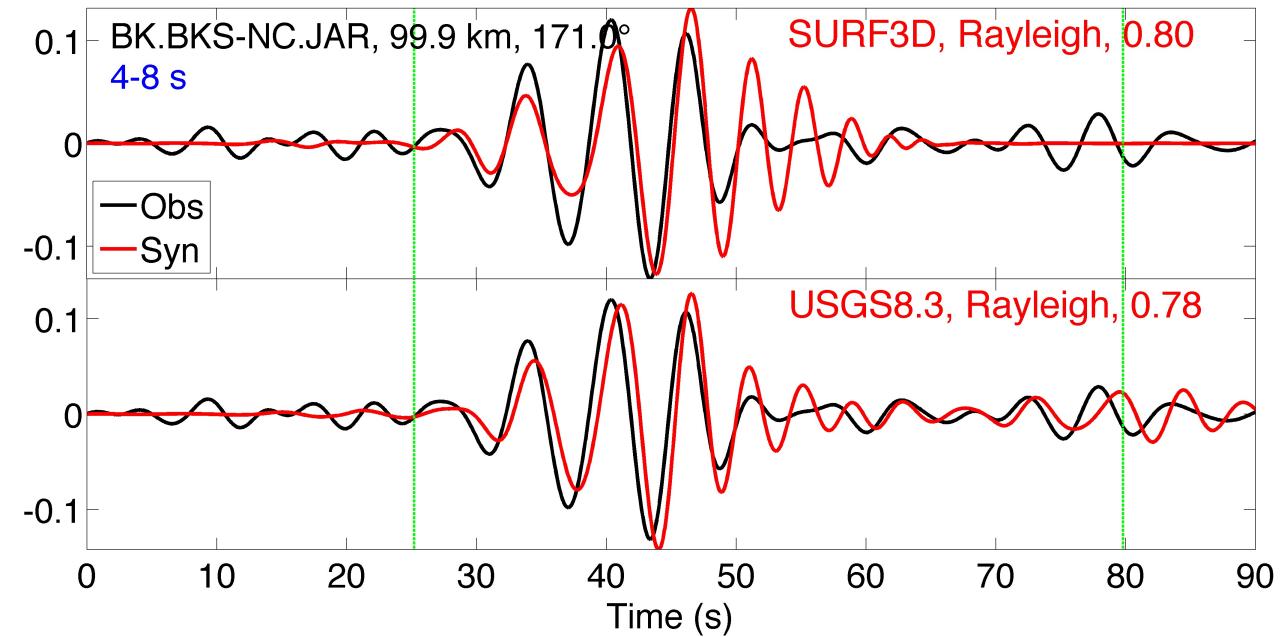
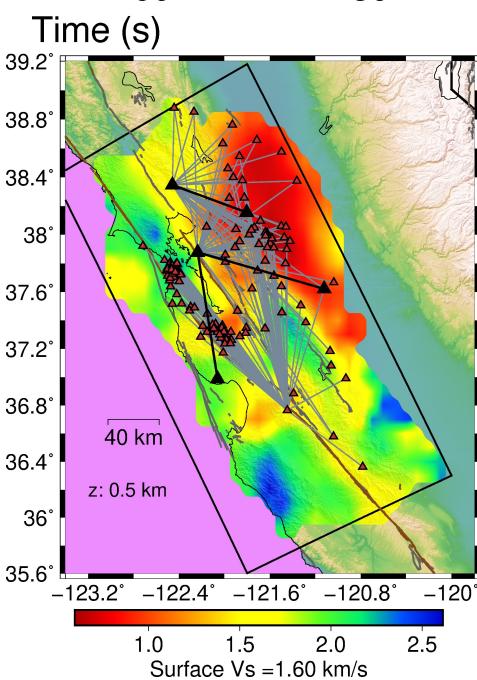
Our surface-wave model fits similar or slightly better than USGS model; largest difference for long-period Love waves



# Comparison of synthetic waveforms and empirical fundamental mode surface-wave Green's functions derived from ambient noise

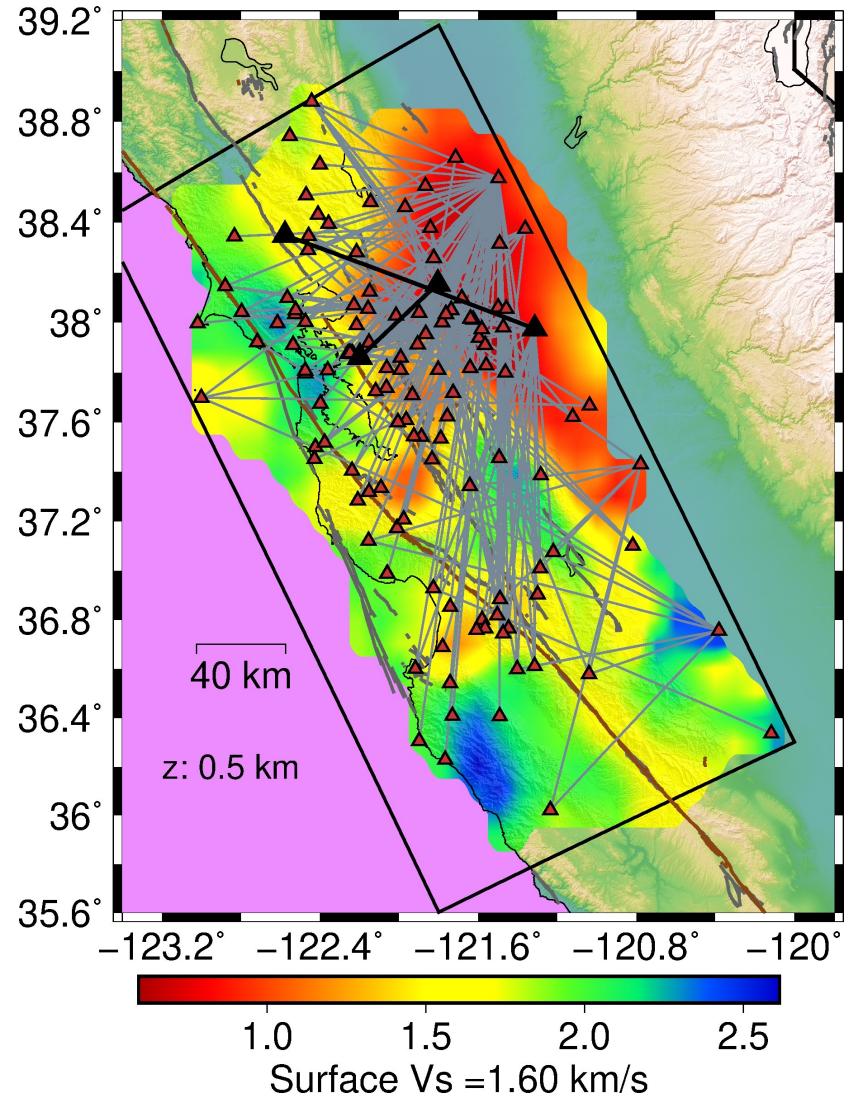


The paths with the largest differences are over sedimentary basins, particularly the Sacramento-San Joaquin delta



Identified paths with prograde elliptical particle motion in the radial-vertical components: 1<sup>st</sup> higher mode Rayleigh wave (~200 pairs)

Work in progress: direct and joint inversion of fundamental mode and first higher mode Rayleigh wave phase arrival times



## Future Work/Possibilities/Limitations/Issues

- Surface-wave tomography at these periods using ambient noise only accounts for **long-wavelength structure**. How to incorporate long-wavelength structures from the inverted model into the current USGS model ? Alternatively, if the USGS model is used as an initial model in the inversion, how to best preserve short-wavelength structure in the inversion ?
- Surface-wave tomography software used in this study does not account for **topography**.
- Once we have the final model, we will compare synthetic waveforms and noise cross-correlations for more paths for the two models.
- Incorporate **body-wave travel times** from earthquakes and active source experiments in a joint inversion.
- Incorporate **Rayleigh wave ellipticity and teleseismic receiver functions** in the joint inversion for shallower and deeper structure respectively
- Compare earthquake waveforms and synthetics for the two models
  - need a set of reference earthquakes with reference locations and moment tensors (from Rodgers et al., Kim et al., recent events)