


# Baaqer Farhat

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 baaqerfarhat

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## Summary

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Passionate about robotics engineering, with a track record of leadership in international competitions and prestigious awards. Particularly interested in robots/manufacturing, controls, EVs, and mechatronics.

## EDUCATION

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**California Institute of Technology**

*EE / Robotics Engineering with minor in Control Systems and Dynamics*

**Pasadena, CA**

*Sept 2023 - Present*

## SKILLS

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|-----------------------------|---------------------------|---------------------------------|
| ○ CUDA/Pytorch              | ○ Isaac Sim/Lab           | ○ ROS1 and ROS2                 |
| ○ 3-D printing              | ○ PID/MPC/LQR             | ○ Soldering / Quick Prototyping |
| ○ Solidworks/Fusion/Onshape | ○ Wiring/Electronics      | ○ PLC Programming               |
| ○ Robot Arms (FANUC)        | ○ Microcontrollers        | ○ CNC Machining                 |
| ○ Altium/KiCAD: PCBs        | ○ Python/Java Programming | ○ Communication/Leadership      |

## HIGHLIGHTED COURSE WORK

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| ○ <b>ME/EE/CS 133:</b> Kinematics and Dynamics        | ○ <b>CS 1/2:</b> Python and Java Programming |
| ○ <b>ME 169:</b> Mobile Robot Localization/Navigation | ○ <b>EE 150:</b> Deep Learning               |
| ○ <b>ME 13:</b> Prototyping (Solidworks and CNC)      | ○ <b>Android App Development:</b> Java       |
| ○ <b>EE 13/23:</b> Electronic Systems Prototyping     | ○ <b>EE 44/55:</b> Advanced Circuit Analysis |
| ○ <b>Altium Training:</b> Caltech Racing (FSAE) Team  | ○ <b>CS 156:</b> Machine Learning            |

## Internships and Awards

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- **Reserach Intern in Autonomous Robotics Lab at Caltech (Summer 2025):** Developing a closed-loop VIO pipeline for a spacecraft simulator, using a multimodal Transformer to perform real-time fault detection and identification.
- **Avalon Robotics Engineering Internship (Spring 2024):** Worked on autonomous manufacturing through mechatronics projects and FANUC Robot arm
- **CPS Office of Computer Science Robotics Summer Internship (Summer 2023):** Group leader for building and programming a mecanum robot chassis
- **Morningstar Summer Internship (Summer 2022):** Front-End Developer on Institutional products team
- **United by STEM: One Team, Two Continents (Fall 2023):** Robotics mentoring in South Africa
- **FIRST Robotics:** Deans List Award (Midwest): First place in State for student leaders
- **2x FTC Chicago City Championship (robotics):** B est FTC team in City
- **FTC Chicago City Control Award :** M ost advanced robot design
- FRC Midwest Regional Judge Award and Inspire Award

## Projects

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- Publishing paper for Fault Detection and Identification in Spacecraft Simulator Lab
- ROS2 Autonomous Robot Explorer and Navigator
- ROS2 Fly Swatter Robot Arm
- Developed a Micro-Stompy Humanoid Robot from scratch as part of a startup initiative with K-scale, designed for a low-cost humanoid and ReelSteel-inspired boxing competition.
- RFID Invetory System for autonomous manufacturing
- Automatic Coolent/water Pump for CNC automation through PLC NEXTEngineer
- Multipurpose probe (Designed Schematic, PCB, and Assembled)
- PID Self Balancing Robot (built + optimized with simulations)
- FTC Cone Delivery Robot: Odometry localization
- International Robotics Mentor Through One Team, Two Continents Project