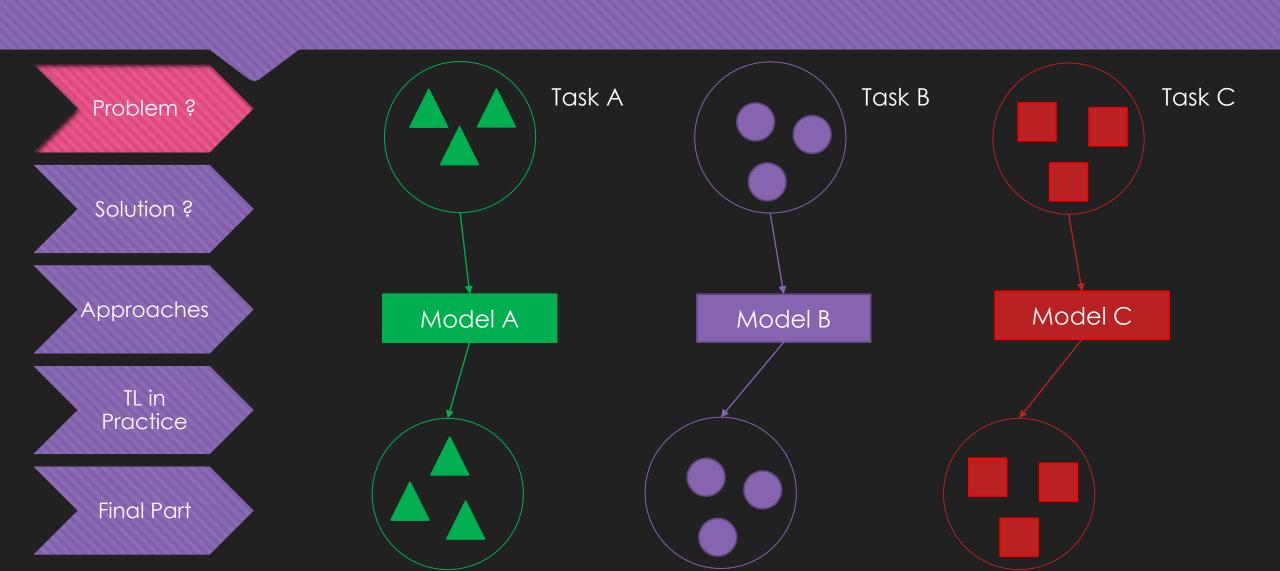
Transfer Learning Theory and it's Applications using Tensorflow & Keras

Babak Badnava PyCon 2018





Traditional ML



Problem Definition!

Problem?

Solution?

Approaches

TL in Practice

- O Complex problems
- O Insufficient labeled data
- O Long training time

Solution?

Problem?

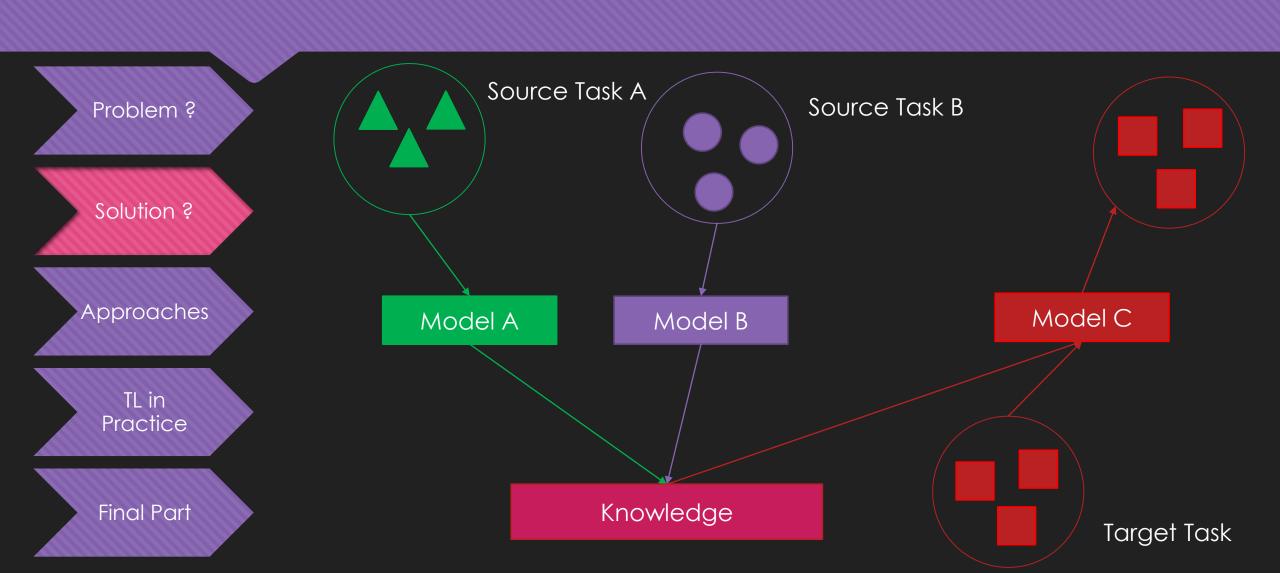
Solution?

Approaches

TL in Practice

- OAssumptions?
 - ORelated data for different task
 - OPreviously learned tasks
- OSolution ?
 - OUse them

Transfer Learning framework



Transfer Learning and Neural Networks

Problem?

Solution?

Approaches

TL in Practice

Final Part

OPre-trained models

OTrains with large dataset

OUse for specific task

OFixed feature extractor

OAutoencoders

OFreezing pre-trained model

OFine-tuning

Pre-trained models on ImageNet in Keras

Problem? O Xception OVGG16 Solution? OVGG19 OResNet50 Approaches OInceptionV3 TL in Practice Final Part https://keras.io/applications/

ResNet50 for specific task

Problem?

Solution?

Approaches

TL in Practice

```
from keras.applications.resnet50 import ResNet50
from keras.preprocessing import image
from keras.applications.resnet50 import preprocess_input, decode_predictions
import numpy as np

model = ResNet50(weights='imagenet')
img_path = 'elephant.jpg'
img = image.load_img(img_path, target_size=(224, 224))
x = image.img_to_array(img)
x = np.expand_dims(x, axis=0)
x = preprocess_input(x)

preds = model.predict(x)
```

Extract features with VGG16

Problem?

Solution?

Approaches

TL in Practice

```
from keras.applications.vgg16 import VGG16
from keras.preprocessing import image
from keras.applications.vgg16 import preprocess_input
import numpy as np

model = VGG16(weights='imagenet', include_top=False)

img_path = 'elephant.jpg'
img = image.load_img(img_path, target_size=(224, 224))
x = image.img_to_array(img)
x = np.expand_dims(x, axis=0)
x = preprocess_input(x)

features = model.predict(x)
```

Extract features from an intermediate layer with VGG19

Problem?

Solution?

Approaches

TL in Practice

```
from keras.applications.vgg19 import VGG19
from keras.preprocessing import image
from keras.applications.vgg19 import preprocess_input
from keras.models import Model
import numpy as np
base model = VGG19(weights='imagenet')
model = Model(inputs=base_model.input, outputs=base_model.get_layer('block4_pool').output)
img path = 'elephant.jpg'
img = image.load_img(img_path, target_size=(224, 224))
x = image.img_to_array(img)
x = np.expand_dims(x, axis=0)
x = preprocess input(x)
block4_pool_features = model.predict(x)
```

Fine-tune InceptionV3 on a new set of classes

Problem?

Solution?

Approaches

TL in Practice

```
from keras.applications.inception v3 import InceptionV3
from keras.preprocessing import image
from keras.models import Model
from keras.layers import Dense, GlobalAveragePooling2D
from keras import backend as K
# create the base pre-trained model
base model = InceptionV3(weights='imagenet', include top=False)
# add a global spatial average pooling layer
x = base model.output
x = GlobalAveragePooling2D()(x)
# let's add a fully-connected layer
x = Dense(1024, activation='relu')(x)
# and a logistic layer -- let's say we have 200 classes
predictions = Dense(200, activation='softmax')(x)
model = Model(inputs=base model.input, outputs=predictions)
```

Fine-tune InceptionV3 on a new set of classes(2)

Problem?

Solution?

Approaches

TL in Practice

```
for layer in base model.layers:
    layer.trainable = False
model.compile(optimizer='rmsprop', loss='categorical crossentropy')
model.fit generator(...)
for layer in model.layers[:249]:
   layer.trainable = False
for layer in model.layers[249:]:
   layer.trainable = True
from keras.optimizers import SGD
model.compile(optimizer=SGD(lr=0.0001, momentum=0.9), loss='categorical crossentropy')
model.fit generator(...)
```

TensorFlow-Slim

Problem?

Olightweight high-level API of TensorFlow

Solution?

OMany pre-trained models such as:

Approaches

Olnception

TL in Practice OResNet V1 50

OResNet V1 101

OVGG 16

Final Part

https://github.com/tensorflow/models/tree/master/research/slim

Pre-trained models

Problem?

Solution?

Approaches

TL in Practice

```
import tensorflow as tf
import tensorflow.contrib.slim.nets as nets
slim = tf.contrib.slim
vgg = nets.vgg
train log dir = ...
if not tf.gfile.Exists(train log dir):
 tf.gfile.MakeDirs(train log dir)
with tf.Graph().as default():
 # Set up the data Loading:
 images, labels = ...
 # Define the model:
  predictions = vgg.vgg 16(images, is training=True)
 # Specify the loss function:
 slim.losses.softmax_cross_entropy(predictions, labels)
 total loss = slim.losses.get total loss()
 tf.summary.scalar('losses/total loss', total loss)
 # Specify the optimization scheme:
 optimizer = tf.train.GradientDescentOptimizer(learning rate=.001)
 train tensor = slim.learning.create_train_op(total_loss, optimizer)
 # Actually runs training.
 slim.learning.train(train tensor, train log dir)
```

Transfer a specific layer

Problem?

Solution?

Approaches

TL in Practice

```
import tensorflow as tf

exclude = ['InceptionResnetV2/Logits', 'InceptionResnetV2/AuxLogits']
variables_to_restore = tf.contrib.slim.get_variables_to_restore(exclude = exclude)
saver = tf.train.Saver(variables_to_restore)
checkpoint_file = './inception_resnet_v2_2016_08_30.ckpt'
saver.restore(sess, checkpoint_file)
```

Freeze a layer

Problem?

Solution?

Approaches

TL in Practice

```
def dense_layer(self, input, out_dim, name, func=tf.nn.relu):
    in_dim = input.get_shape().as_list()[-1]
    d = 1.0 / np.sqrt(in_dim)
    with tf.variable_scope(name):
        w_init = tf.random_uniform_initializer(-d, d)
        b_init = tf.random_uniform_initializer(-d, d)
        w = tf.get_variable('w', dtype=tf.float32, shape=[in_dim, out_dim], initializer=w_init, trainable=False)
        b = tf.get_variable('b', shape=[out_dim], initializer=b_init, trainable=False)

        output = tf.matmul(input, w) + b
        if func is not None:
            output = func(output)

        return output
```

Freeze a layer

Problem?

Solution?

Approaches

TL in Practice

```
def conv2d layer(self, input, filter size, out dim, name, strides, func=tf.nn.relu):
        in_dim = input.get_shape().as_list()[-1]
        d = 1.0 / np.sqrt(filter size * filter size * in dim)
        with tf.variable scope(name):
            w init = tf.random uniform initializer(-d, d)
            b init = tf.random uniform initializer(-d, d)
            w = tf.get variable('w',
                                shape=[filter_size, filter_size, in_dim, out_dim],
                                dtype=tf.float32,
                                initializer=w init, trainable=False)
            b = tf.get_variable('b', shape=[out_dim], initializer=b_init, trainable=False)
            output = tf.nn.conv2d(input, w, strides=strides, padding='SAME') + b
            if func is not None:
                output = func(output)
        return output
```

Applications

Problem?

Solution?

Approaches

TL in Practice

- OLearning from simulations
 - OAutonomous cars
 - **O**Robotics
- OAdapting to new domains
- OSemi supervised learning

When and which?

Problem?

Solution?

Approaches

TL in Practice

	Similar dataset	Different dataset
Small dataset	Highest level features + classifier	Lower level features + classifier
Large dataset	Fine tune	Fine tune

Thanks for attention.

Questions?